Homework 10

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1. We begin by writing an expression for $B_k = 0$, which gives us a waveform of:

$$x_0(t) = \cos\left(\frac{2\pi Nt}{T}\right), \quad t \in [(k-1)T, kT]$$

We then write, for $B_k = 1$:

$$x_0(t) = -\sin\left(\frac{2\pi Nt}{T}\right), \quad t \in [(k-1)T, kT]$$

We know that, given that f_o is a multiple of 1/T, we know a full N cycles will be transmitted. We may observe that the sample space of X consists of 8 waveforms, as a result of the transmission of 3 bits (which means 2^3 possible combinations. These are given by:

$$x_{o}(t), \quad t \in [0, 3T]$$

$$x_{o}(t), \quad t \in [0, 2T] \quad \text{and} \quad x_{1}(t), \quad t \in [2T, 3T]$$

$$x_{o}(t), \quad t \in [0, T] \cup [2T, 3T] \quad \text{and} \quad x_{1}(t), \quad t \in [T, 2T]$$

$$x_{o}(t), \quad t \in [T, 3T] \quad \text{and} \quad x_{1}(t), \quad t \in [0, T]$$

$$x_{o}(t), \quad t \in [0, T] \quad \text{and} \quad x_{1}(t), \quad t \in [T, 3T]$$

$$x_{o}(t), \quad t \in [T, 2T] \quad \text{and} \quad x_{1}(t), \quad t \in [0, T] \cup [2T, 3T]$$

$$x_{o}(t), \quad t \in [2T, 3T] \quad \text{and} \quad x_{1}(t), \quad t \in [0, 2T]$$

$$x_{1}(t), \quad t \in [0, 3T]$$

Accordingly, we find that the elements correspond to $(B_1, B_2, B - 3)$ as:

$$X_k(t) \to \begin{cases} 1, & (0,0,0) \\ 2, & (0,0,1) \\ 3, & (0,1,0) \\ 4, & (1,0,0) \\ 5, & (0,1,1) \\ 6, & (1,0,1) \\ 7, & (1,1,0) \\ 8, & (1,1,1) \end{cases}$$

To plot, we need to assume a value of N. Let us take this such that N=T to simplify the functions. We proceed to plot each corresponding figure:

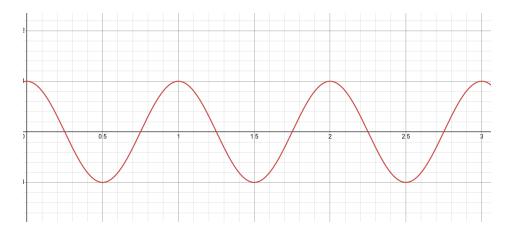


Figure 1: Plot for $(B_1, B_2, B_3) = (0, 0, 0)$

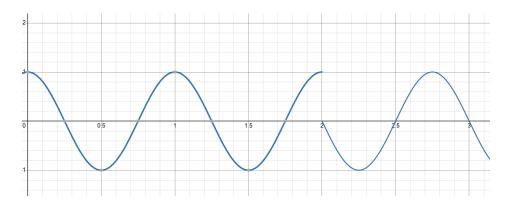


Figure 2: Plot for $(B_1, B_2, B_3) = (0, 0, 1)$

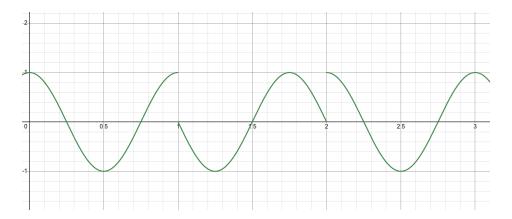


Figure 3: Plot for $(B_1, B_2, B_3) = (0, 1, 0)$

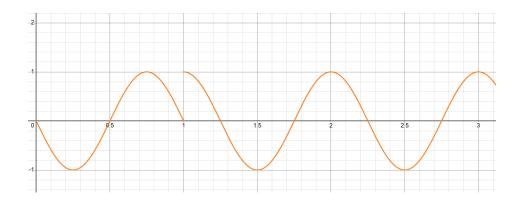


Figure 4: Plot for $(B_1, B_2, B_3) = (1, 0, 0)$

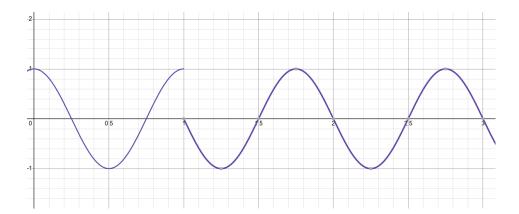


Figure 5: Plot for $(B_1, B_2, B_3) = (0, 1, 1)$

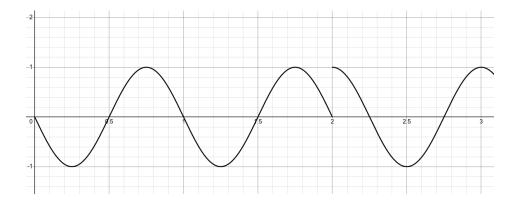


Figure 6: Plot for $(B_1, B_2, B_3) = (1, 1, 0)$

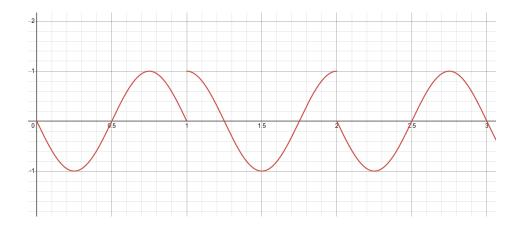


Figure 7: Plot for $(B_1, B_2, B_3) = (1, 0, 1)$

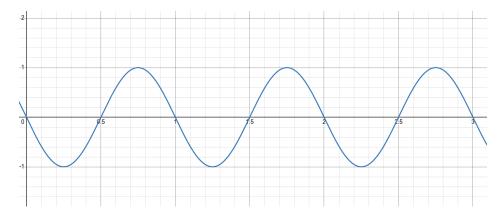


Figure 8: Plot for $(B_1, B_2, B_3) = (1, 1, 1)$

2. (a) Taking $t \to 100/3 [\mu s]$, we obtain:

$$s_1 = 5\cos(10^4\pi(100/3)\cdot 10^{-6})$$

$$s_1 = 5\cos(\pi/3)$$
$$s_1 = 2.5$$

We can then find $Y_1(t)$ by tacking on the noise term to get:

$$Y_1(t) \to N(2.5, 1)$$

Which means that this gives a normal distribution with a mean of 2.5 and standard deviation of 1.

(b) Similarly, we take $t \to 100 [\mu s]$ to get:

$$s_2 = 5\cos(10^4\pi 200 \cdot 10^{-6})$$

 $s_2 = 5\cos(2\pi)$
 $s_2 = 5$

This gives us:

$$Y_2(t) \rightarrow N(5,1)$$

Or a normal distribution with mean 5 and standard deviation 1.

(c) Given that s(t) is static, we know that the covariance depends solely on the noise. This gives us:

$$Cov(Y_1, Y_2) = Cov(N_1, N_2)$$

Since N_1 and N_2 are normal functions independent of each other, we find:

$$Cov(Y_1, Y_2) = Cov(N_1, N_2) = 0$$

Which means that Y_1 and Y_2 are independent

(d) Summing the two distributions and averaging their means and standard deviations, we find:

$$E\left[\frac{Y_1 + Y_2}{2}\right] = \frac{1}{2}(5 + 2.5)$$
$$E\left[\frac{Y_1 + Y_2}{2}\right] = 3.75$$

And then:

$$\sigma_{(Y_1+Y_2)/2} = \left(\frac{1}{2}\right)^2 (1+1)$$

$$\sigma_{(Y_1+Y_2)/2} = .5$$

Thus, we get:

$$\frac{Y_1(t) + Y_2(t)}{2} \to N(3.75, .5)$$

A normal distribution, with a mean of 3.75 and standard deviation of .5

4. (a) We know that the mean of X(t) may be expressed as:

$$\mu_X = E[X(t)] = E[A_o \cos(\omega_o t + \theta)]$$

Given that this is over a uniform function from $-\pi$ to π , we find:

$$\mu_X = 0$$

We proceed to find the autocorrelation function as:

$$\mathcal{R}_{XX}(t,\tau) = E[X(t)X(t+\tau)]$$

We expand to get:

$$\mathcal{R}_{XX}(t,\tau) = E[A_o^2 \cos(\omega_o t + \theta) \cos(\omega_o (t + \tau) + \theta)]$$

Applying our cosine properties gives us:

$$\mathcal{R}_{XX}(t,\tau) = E\left[\frac{A_o^2}{2}(\cos(\omega_o \tau) + \cos(2\omega_o t + \omega_o \tau))\right]$$

This simplifies to:

$$\mathcal{R}_{XX}(t,\tau) = \frac{A_o^2}{2}\cos(\omega_o \tau)$$

As such, since the autocorrelation depends on the time difference, and the mean is constant, we may conclude that this is a wide-sense stationary process

(b) We may write the mean as:

$$\mu_y = E[V + X(t)] = E[V] + E[X(t)]$$

This gives us:

$$\mu_y = \mu_V$$

We then write the autocorrelation function as:

$$\mathcal{R}_{YY}(t,\tau) = E[Y(t)Y(t+\tau)]$$

Expanding gives us:

$$\mathcal{R}_{YY}(t,\tau) = E[(V+X(t))(V+X(t+\tau))]$$

$$\mathcal{R}_{YY}(t,\tau) = E[V^2 + VX(t+\tau) + VX(t) + X(t)X(t+\tau)]$$

We then simplify to:

$$\mathcal{R}_{YY}(t,\tau) = E[V^2 + X(t)X(t+\tau)]$$

$$\mathcal{R}_{YY}(t,\tau) = E[V^2] + E[X(t)X(t+\tau)]$$

$$\mathcal{R}_{YY}(t,\tau) = \sigma_V^2 + \frac{A_o^2}{2}\cos(\omega_o\tau)$$

Since the mean is constant due to its independence from θ , and the autocorrelation depends on the time difference, this is a wide-sense stationary function

- 5. (a) From the fact that $C(\tau) \neq C(-\tau)$, we may observe that this is <u>not a valid</u> autocovariance function for a WSS random process
 - (b) Although the given function is even, it does not satisfy the positive-definite requirement. That is, is does not follow:

$$\sum_{i=1}^{n} \sum_{j=1}^{n} c_i c_j \mathcal{R}_x(\tau_i, \tau_j) \ge 0$$

If we take $\tau_1 = -1$ and $\tau_2 = -2$, then we get:

$$-c_1^2 - 2c_2^2$$

We observe that this is less than zero, and, therefore, this is <u>not a valid</u> autocovariance function for a WSS random process

(c) The function is even and non-negative for all of τ, and it is positive definite. Therefore, we conclude that this is a valid autocovariance function for a WSS random process. Note: we may verify that it is positive definite by showing that the sum would yield:

$$c_i c_j \to \frac{1}{|\tau_1|} \frac{1}{|\tau_2|}$$

Which must be positive.

- (d) We may observe that the function is even, non-negative for all of τ , and is positive definite. Therefore, we conclude that this is a valid autocovariance function for a WSS random process
- 6. (a) We may observe that X(t) is not periodic, since the autocorrelation function does not contain a periodic term

(b) The function is not periodic, so we use the autocorrelation. We want to take $\tau \to \infty$; however, since τ is bounded, in this case, we take $\tau \to 6$:

$$E[X] = 3 - \frac{1}{2}(6)$$
$$E[X] = 0$$

(c) We may write the expected power as:

$$E[X^2(t)] = \mathcal{R}_{XX}(0)$$

This gives us:

$$E[X^{2}(t)] = 3 - \frac{1}{2}(0)$$
$$E[X^{2}(t)] = 3$$

(d) We can express this using the value of the uniform distribution to get:

$$P[X(t=1) > 1] = \int_{1}^{3} \frac{1}{3 - (-3)} dx$$

$$P[X(t=1) > 1] = \int_{1}^{3} \frac{1}{6} dx$$

$$P[X(t=1) > 1] = \frac{x}{6} \Big|_{1}^{3}$$

$$P[X(t=1) > 1] = \frac{3 - 1}{6}$$

$$P[X(t=1) > 1] = \frac{1}{3}$$

(e) We can break this up to write:

$$E[(X(1) + X(2) + X(3))^{2}] = E[X^{2}(1)] + E[X^{2}(2)] + EX^{2}(3)] + 2E[X(1)X(2)] + 2E[X(2)X(3)] + 2E[X(1)X(3)]$$

This is equivalent to:

$$E[(X(1) + X(2) + X(3))^{2}] = 3\mathcal{R}_{XX}(0) + 4\mathcal{R}_{XX}(1) + 2\mathcal{R}_{XX}(2)$$

We evaluate to get:

$$E[(X(1) + X(2) + X(3))^{2}] = 3[3] + 4\left[\frac{5}{2}\right] + 2[2]$$

$$E[(X(1) + X(2) + X(3))^{2}] = 23$$

(f) Expanding, we get:

$$E[Y] = 2E[X] + 3$$
$$E[Y] = 3$$

We can then find:

$$\mathcal{R}_{YY}(t) = E[(2X(t) + 3)(2X(t + \tau) + 3)]$$

We expand this to get:

$$\mathcal{R}_{YY}(t) = 4E[X(t)2X(t+\tau)] + 6E[X(t+\tau)] + 6E[X(t)] + 9$$
$$\mathcal{R}_{YY}(t) = 4\mathcal{R}_{XX}(t) + 9$$

7. (a) We may begin by computing the autocovariance as:

$$C_{XX}(n,k) = Cov(X_n, X_k)$$

But because all X_n are i.i.d, we get:

$$C_{XX}(n,k) = \begin{cases} \operatorname{Var}(X_n), & n = k \\ 0, & n \neq k \end{cases}$$

We then compute the autocorrelation as:

$$R_{XX}(n,k) = E[X_n X_k]$$

Because of independence, we write:

$$R_{XX}(n,k) = E[X_n]E[X_k]$$

Accordingly, we get:

$$R_{XX}(n,k) = \begin{cases} p, & n = k \\ p^2, & n \neq k \end{cases}$$

(b) Since the distributions X_n are i.i.d, we may obtain the probability as simply the sum of individual probabilites. Since the probability of each is the same, we get:

$$\boxed{E[Y_n] = np}$$

Similarly, we can sum the variances by writing:

$$Var(Y_n) = nVar(X_n)$$

$$\boxed{\operatorname{Var}(Y_n) = np(1-p)}$$

- (c) We may observe that each X_n represents a Bernoulli trial. accordingly, since Y_n is the sum of Bernoulli trials, it represents a Binomial distribution such that $Y_n = \text{Binom}(n, p)$
- (d) We know that, to be a wide-sense stationary process, two conditions must be met:
 - i. $E[Y_n]$ is constant
 - ii. $Cov(Y_n, Y_k)$ is dependent solely on the difference |n-k|

From (b), we see that $E[Y_n] = np$ is not constant, and, therefore, the process is not wide-sense stationary.

(e) We begin by writing:

$$C_{YY}(n,k) = Cov(Y_n, Y_k)$$

This gives us:

$$C_{YY}(n,k) = \sum_{i=1}^{n} \sum_{j=1}^{k} \operatorname{Cov}(X_i, X_j)$$

Given the independence of the distributions, we see that only diagonal terms remain, which means that the only non-zero covariances occur when:

$$i = j \to \operatorname{Cov}(X_i, X_j) = p(1 - p)$$

Therefore, we rewrite the above to get:

$$C_{YY}(n,k) = \sum_{i=1}^{\min(n,k)} p(1-p)$$

As such, we finally get:

$$C_{YY}(n,k) = \min(n,k)p(1-p)$$

8. (a) Given that X and Y are wide sense stationary processes, we may write:

$$V(t) = 2X(t) + Y(t) \to E[V] = 2E[X] + E[Y]$$
$$\mathcal{R}_V(t,\tau) = E[\bar{V}(t)V(t+\tau)]$$

We expand this to get:

$$\mathcal{R}_{V}(t,\tau) = E[(2X(t) + Y(t))(2X(t+\tau) + Y(t+\tau))]$$

$$\mathcal{R}_{V}(t,\tau) = E[(2X(t)2X(t+\tau) + Y(t)Y(t+\tau)) + 2X(t)Y(t+\tau) + 2Y(t)X(t+\tau)]$$

And thus we conclude:

$$\mathcal{R}_{V}(t,\tau) \neq \mathcal{R}_{X}(t,\tau) + \mathcal{R}_{Y}(t,\tau)$$

Therefore, it is not wide sense stationary

(b) Similar to the above, we write:

$$E[W] = E[XY]$$

Since Y and X are independent, we get:

$$E[W] = E[X]E[Y] = \mu_X \mu_Y$$

We then write:

$$\mathcal{R}_W(t,\tau) = E[\bar{W}(t)W(t+\tau)]$$

We expand:

$$\mathcal{R}_W(t,\tau) = E[X(t)Y(t)X(t+\tau)Y(t+\tau)]$$

Once again, because X and Y are independent, we get:

$$\mathcal{R}_W(t,\tau) = E[X(t)X(t+\tau)][EY(t)Y(t+\tau)] = \mathcal{R}_X(t,\tau)\mathcal{R}_Y(t,\tau)$$

And, therefore, W is independent and wide sense stationary

9. We begin by writing the autocorrelation as:

$$\mathcal{R}_{WW}(t,\tau) = E[W(t)W(t+\tau)]$$

We expand to get:

$$\mathcal{R}_{WW}(t,\tau) = E[(X\cos(10^8\pi t) + Y\sin(10^8\pi t))(X\cos(10^8\pi (t+\tau)) + Y\sin(10^8\pi (t+\tau)))]$$

Since X and Y are uncorrelated, we know that any expectation value involving both will cancel, so we simplify to:

$$\mathcal{R}_{WW}(t,\tau) = E[X^2 \cos(10^8 \pi t) \cos(10^8 \pi (t+\tau)) + Y^2 \sin(10^8 \pi t) \sin(10^8 \pi (t+\tau))]$$

We use the identity that $\cos(x+y) = \cos(x)\cos(y) - \sin(x)\sin(y)$ to get:

$$\mathcal{R}_{WW}(t,\tau) = E[X^2 \cos(10^8 \pi \tau) \cos(10^8 \pi t) + Y^2 \cos(10^8 \pi \tau) \sin(10^8 \pi t)]$$

Since X and Y both have mean 0 and variance σ^2 , we find that, as long as t and $t + \tau$ are within the range of integration:

$$\mathcal{R}_{WW}(t,\tau) = \sigma^2 \cos(10^8 \pi (t-\tau))$$

Otherwise, it is zero.

Accordingly, we observe that the process W(t) is wide sense stationary, since the mean is zero and the autocorrelation only depends on the time difference, $t-\tau$

We can find the autocovariance as:

$$C_{WW}(t,\tau) = R_{WW}(t,\tau) - E[W(t)]E[W(t+\tau)]$$

Since we know the terms that go to zero, we find:

$$C_{WW}(t,\tau) = R_{WW}(t,\tau)$$

$$C_{WW}(t,\tau) = \sigma^2 \cos(10^8 \pi (t-\tau))$$

We use the autocovariance to find:

$$C_{WW}(0,.001) = \sigma^2 \cos(-10^8 \pi \cdot 10^{-3})$$

 $C_{WW}(0,.001) = \sigma^2 \cos(-10^5 \pi)$

This simplifies to:

$$C_{WW}(0,.001) = \sigma^2$$

We can find the mean signal power by taking $\mathcal{R}_{WW}(0)$:

$$E[W^{2}(t)] = \sigma^{2} \cos (0)$$
$$E[W^{2}(t)] = \sigma^{2}$$

Since the mean is zero, nothing is subtracted from the power, which gives us a variance of:

$$\boxed{\operatorname{Var}(W(t)) = \sigma^2}$$

10. We are given that the weather on each day is normally distributed with $E[W] = 20[^{\circ}C]$ and $\sigma = 5[^{\circ}C]$. Let us then express the two day-averaged distribution as:

$$W_n = \frac{2X_n + X_{n-1}}{3}$$
 and $W_{n+1} = \frac{2X_{n+1} + X_n}{3}$

We find the Covariance between daily "steps" to get:

$$Cov(W_n, W_{n+1}) = Cov\left(\frac{2X_n + X_{n-1}}{3}, \frac{2X_{n+1} + X_n}{3}\right)$$

We can break this apart to get:

$$Cov(W_n, W_{n+1}) = \frac{1}{9} \left[2Cov(X_n, X_n) + 4Cov(X_n, X_{n+1}) + 2Cov(X_{n-1}, X_{n+1}) + Cov(X_{n-1}, X_n) \right]$$

$$Cov(W_n, W_{n+1}) = \frac{1}{9} \left[2Var(X_n) \right]$$

$$Cov(W_n, W_{n+1}) = \frac{50}{9} \left[{}^{\circ}C^2 \right]$$

Thus, since the covariance is not zero, the W_n distributions are not independent, and, therefore it is not an i.i.d random sequence.

12. (a) We may begin by constructing our distribution by using the formula for a Poisson distribution for each individual train line:

$$P[n] = \frac{(\lambda T)e^{-\lambda T}}{n!}$$

We combine the individual PMFs to get a general one for train arrivals as:

$$\lambda = \lambda_R + \lambda_G + \lambda_B$$

Entering the given information, we write:

$$\lambda = .1 + .05 + .15$$
$$\lambda = .3[\min^{-1}]$$

Accordingly, we find the quantity of trains in an hour as:

$$\lambda T = 60(.03)$$

 $\lambda T = 18[\text{trains/hour}]$

Applying this to our Poisson distribution formula, we find:

$$P_N[n] = Poisson(18) = \frac{(18)^n e^{-18}}{n!}$$

(b) We want to find the conditional PMF, which we can do by constructing a binomial distribution

$$P[R|N = 10] = {10 \choose R} \left(\frac{.1}{.3}\right)^R \left(1 - \frac{.1}{.3}\right)^{10-R}$$

We simplify to find:

$$P[R|N=10] = {10 \choose R} \left(\frac{1}{3}\right)^R \left(\frac{2}{3}\right)^{10-R}$$

As such, we see that this follows a binomial distribution with n = 10 and p = 1/3