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# 1.0 Objectives

This report aims to explore the design and implementation of an arbitrary sequence counter using J-K and D flip-flops. The focus includes analyzing ICs, presenting state transition tables, deriving K-maps, equations, and circuit diagrams for flip-flops.

The main objectives are:

1. ICs: Compare and select suitable chips for counters.
2. Flip-Flops: Analyze J-K and D types, provide tables, K-maps, equations.
3. Circuit Design: Illustrate J-K and D flip-flop setups in counter.

# 2.0 Components

1. IC 74LS76AP
2. Trainer Board
3. Clock Pulse
4. Logisim Software

# 3.0 Theory

## 3.1 Sequence Recognition

Sequence recognition in digital logic refers to the process of identifying and detecting specific patterns or sequences of binary values within a stream of digital data. It involves designing circuits or systems that can determine whether a given sequence of bits exists in the incoming data stream.

## 3.2 Arbitrary Sequence

An arbitrary sequence refers to a sequence of elements, often numbers or symbols, that does not follow a predictable or regular pattern. In other words, the sequence is not governed by a specific rule or formula that generates its elements. Instead, the elements in an arbitrary sequence appear to be selected or arranged in a seemingly random or unstructured manner.

## 3.3 JK Flip Flop

A JK flip-flop is a type of digital circuit component or flip-flop that can store one bit of binary information. It is a sequential logic device, which means it has an internal state that changes based on the inputs and clock signals it receives. JK flip-flops are widely used in digital electronics for various purposes, such as memory storage, control circuits, and counter circuits.

## 4.0 Problem/Design Solve Procedure

### 4.0.1 Arbitrary sequence counter J-K flip-flop "2->3->1->4->6->0->2->so on"

Q(t)	Q(t+1)	J	K
0	0	0	x
0	1	1	x
1	0	x	1
1	1	x	0

J-K Excitation Table

State Table for Arbitrary sequence "2->3->1->4->6->0->2->"

Present State			Next State			Input					
$Q_{2(n)}$	$Q_{1(n)}$	$Q_{0(n)}$	$Q_{2(n+1)}$	$Q_{1(n+1)}$	$Q_{0(n+1)}$	$J_2$	$K_2$	$J_1$	$K_1$	$J_0$	$K_0$
0	0	0	0	1	0	0	x	1	x	0	x
0	0	1	1	0	0	1	x	0	x	x	1
0	1	0	0	1	1	0	x	x	0	1	x
0	1	1	0	0	1	0	x	x	1	x	0
1	0	0	1	1	0	x	0	1	x	0	x
1	0	1	0	0	0	x	1	0	x	x	1
1	1	0	0	0	0	x	1	x	1	0	x
1	1	1	0	0	0	x	1	x	1	x	1

## 4.0.2 K-Map and Equations

$J_2 :$

$Q_2 \backslash Q_1 Q_0$	$Q_1' Q_0'$ 00	$Q_1' Q_0$ 01	$Q_1 Q_0$ 11	$Q_1 Q_0'$ 10
$Q_2' 0$		1		
$Q_2 1$	X	X	X	X

$J_2 = Q_0 \cdot Q_1'$

$K_2 :$

$Q_2 \backslash Q_1 Q_0$	$Q_1' Q_0'$ 00	$Q_1' Q_0$ 01	$Q_1 Q_0$ 11	$Q_1 Q_0'$ 10
$Q_2' 0$	X	X	X	X
$Q_2 1$		1	1	1

$K_2 = Q_0 + Q_1$

$J_1 :$

$Q_1 \backslash Q_2 Q_0$	$Q_2' Q_0'$ 00	$Q_2' Q_0$ 01	$Q_2 Q_0$ 11	$Q_2 Q_0'$ 10
$Q_1' 0$	1		X	X
$Q_1 1$	1		X	X

$J_1 = Q_0'$

$K_1 :$

$Q_1 \backslash Q_2 Q_0$	$Q_2' Q_0'$ 00	$Q_2' Q_0$ 01	$Q_2 Q_0$ 11	$Q_2 Q_0'$ 10
$Q_1' 0$	X	X	1	
$Q_1 1$	X	X	1	1

$K_1 = Q_2 + Q_0$

$J_0 :$

$Q_0 \backslash Q_2 Q_1$	$Q_2' Q_1'$ 00	$Q_2' Q_1$ 01	$Q_2 Q_1$ 11	$Q_2 Q_1'$ 10
$Q_0' 0$		X	X	1
$Q_0 1$		X	X	

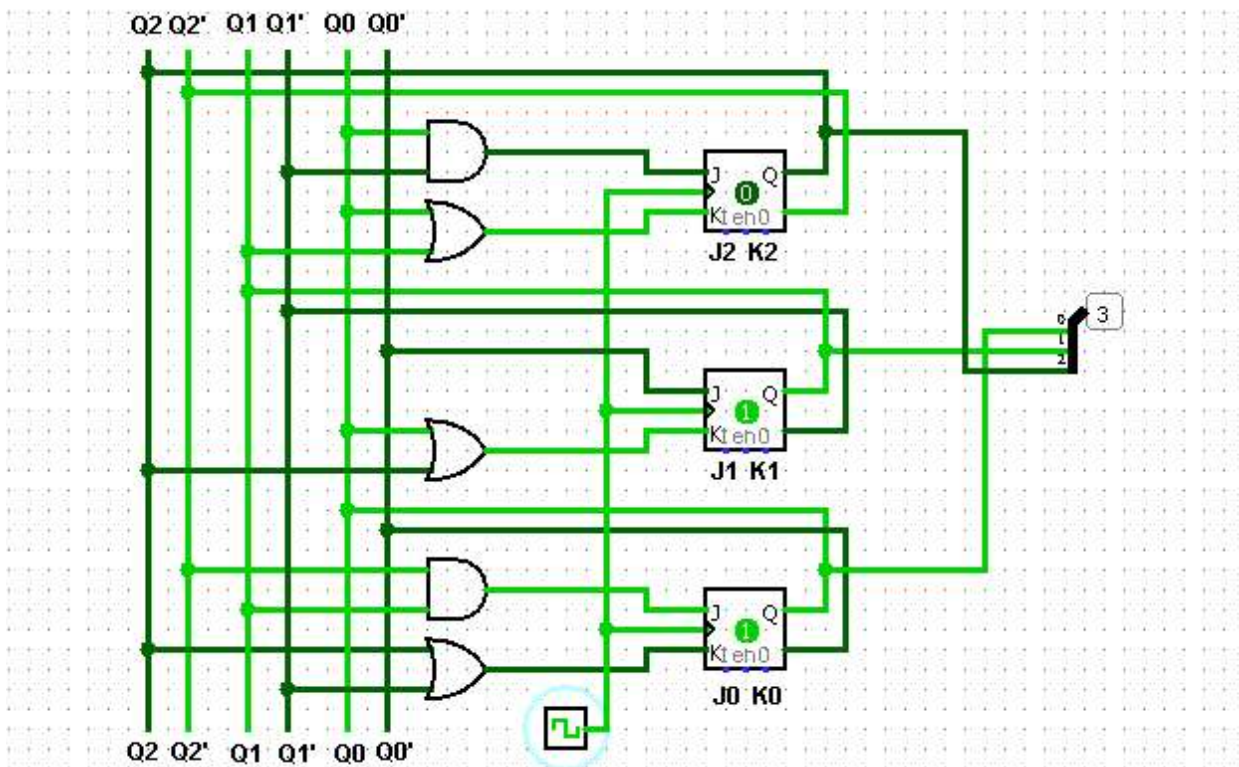
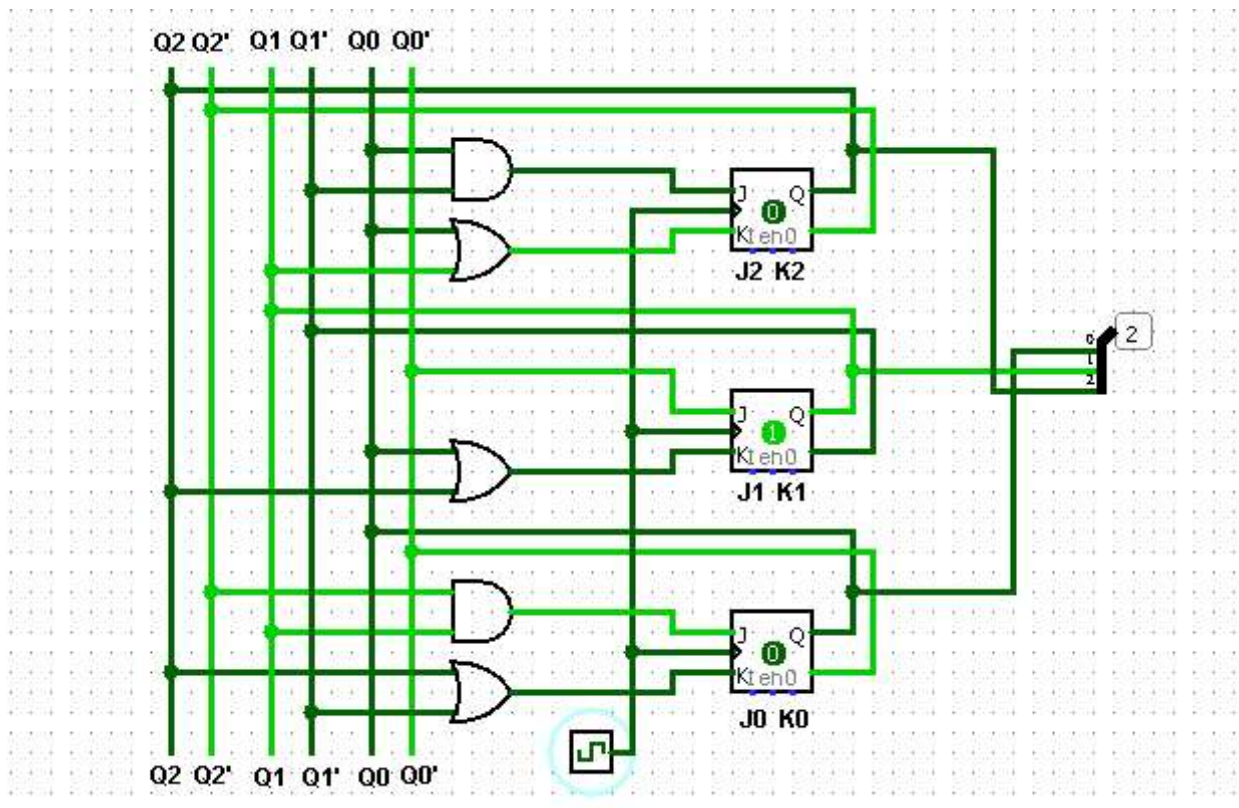
$J_0 = Q_2' Q_1$

$K_0 :$

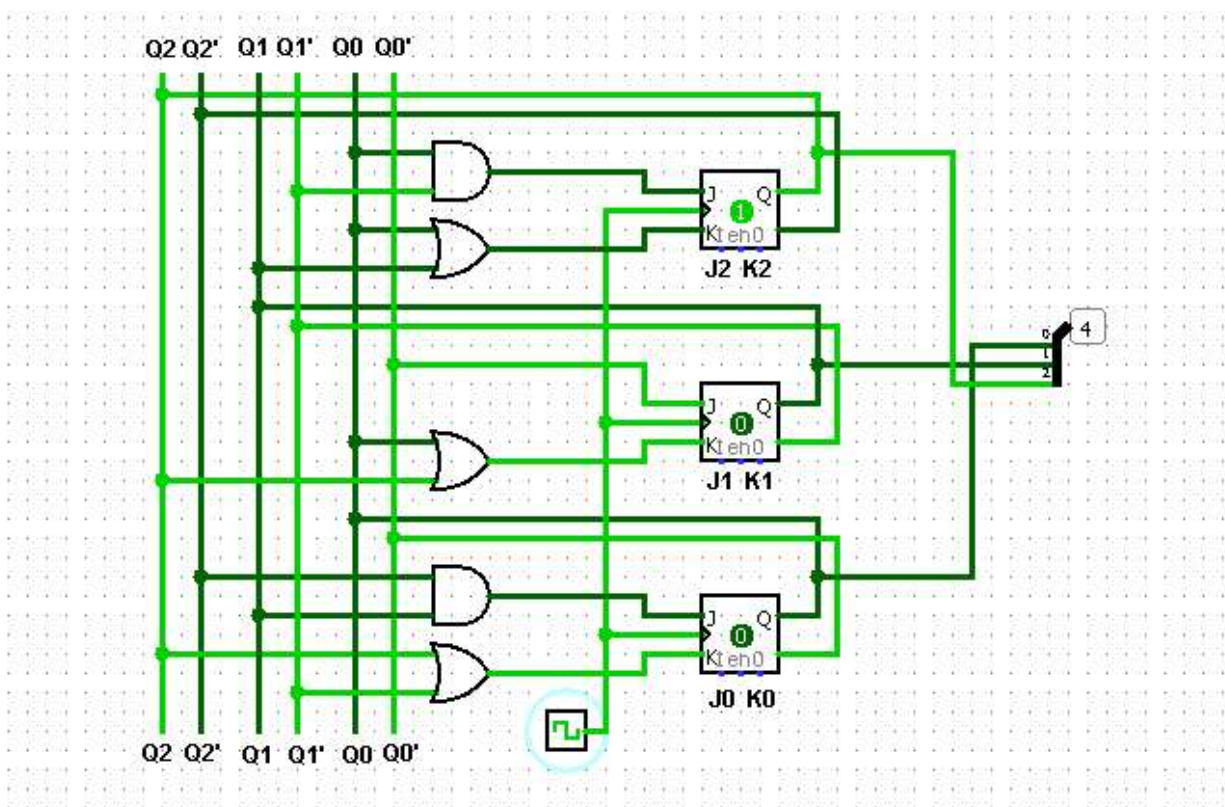
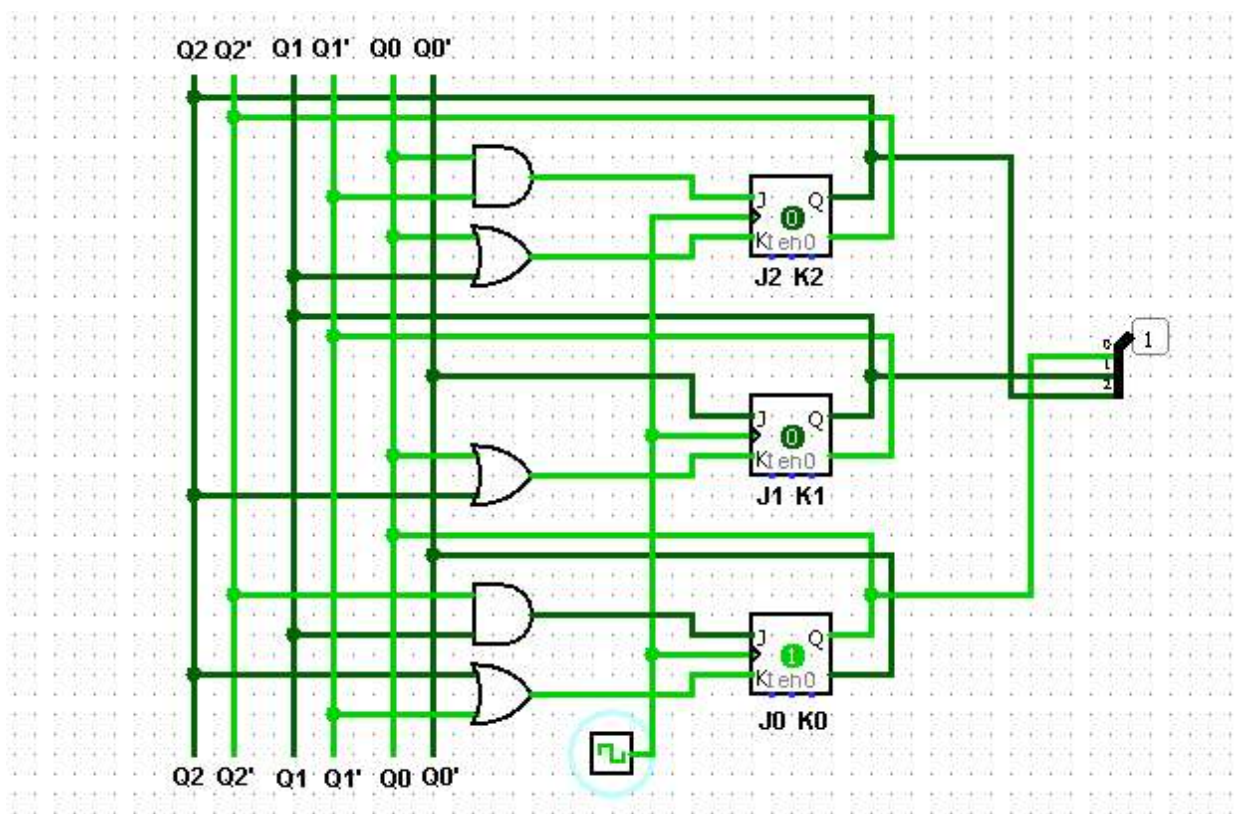
$Q_0 \backslash Q_2 Q_1$	$Q_2' Q_1'$ 00	$Q_2' Q_1$ 01	$Q_2 Q_1$ 11	$Q_2 Q_1'$ 10
$Q_0' 0$	X	1		X
$Q_0 1$	X	1	1	X

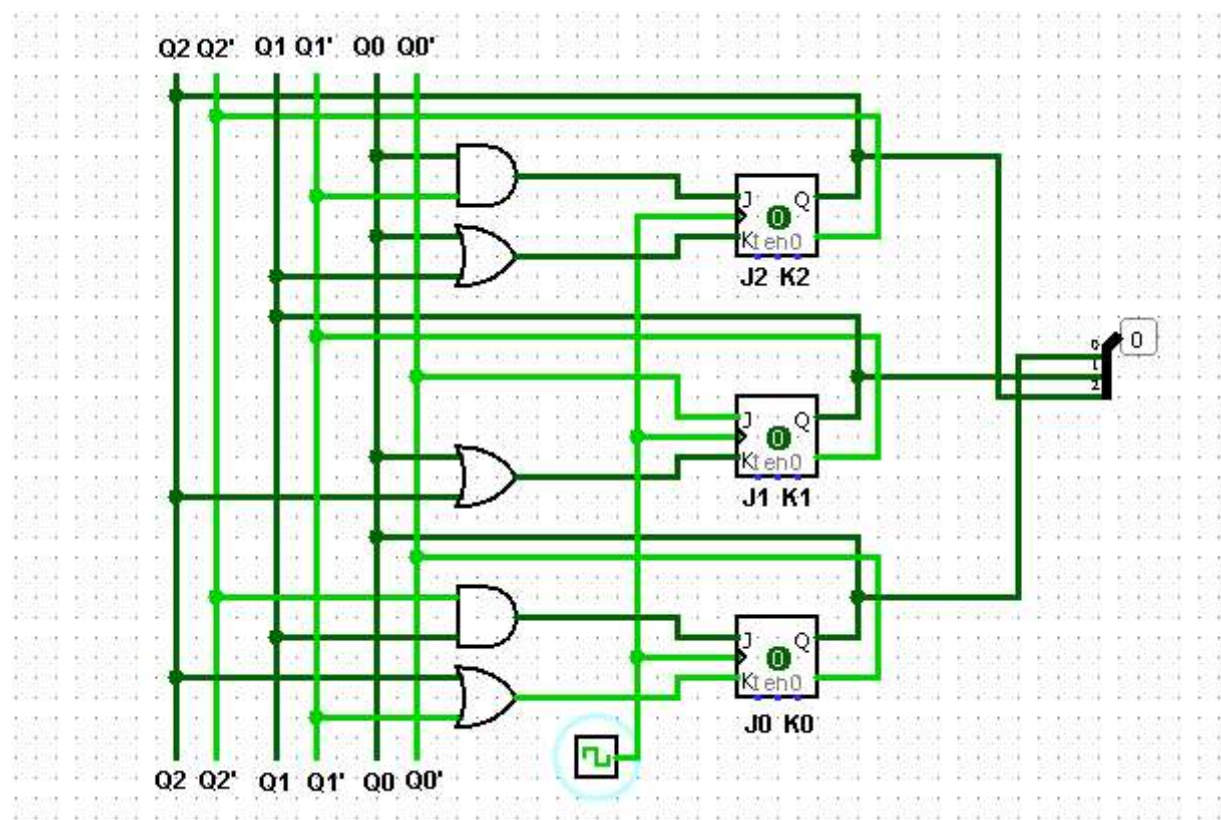
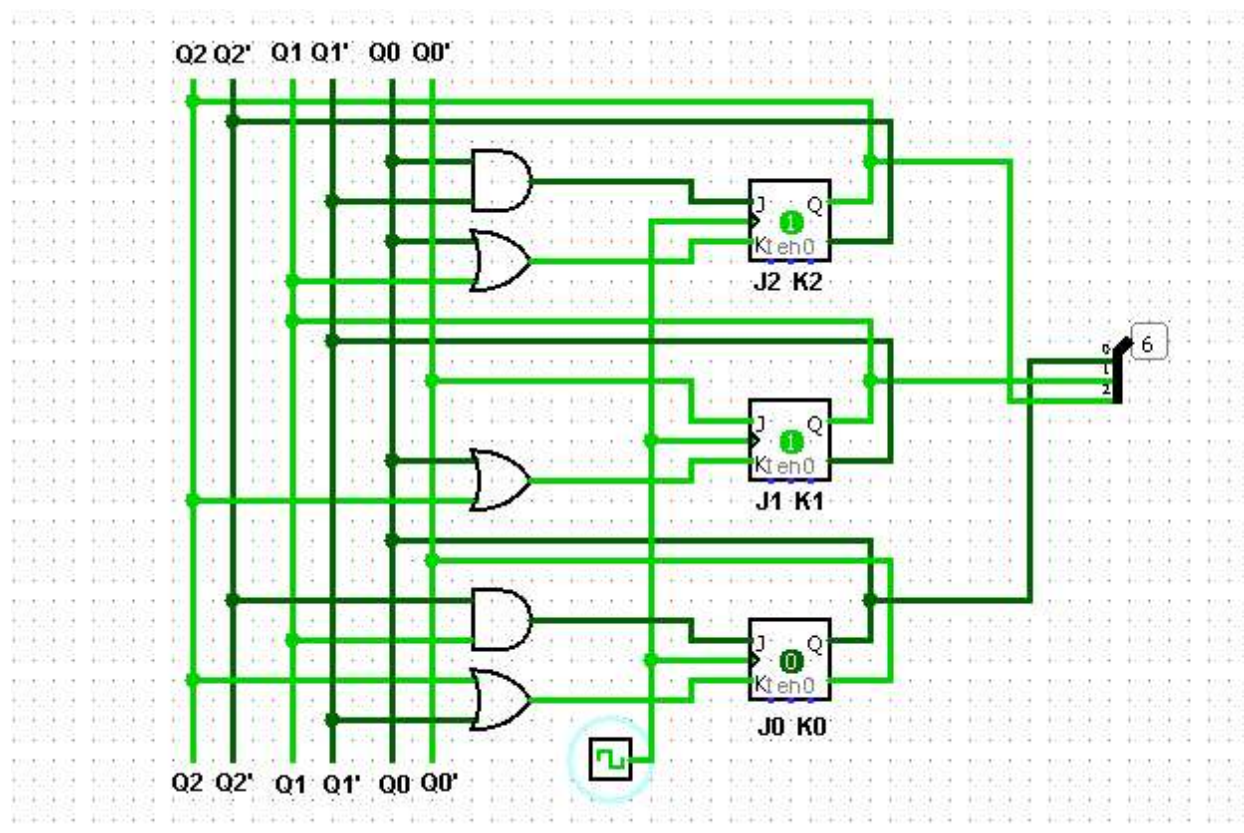
$K_0 = Q_2 + Q_1'$

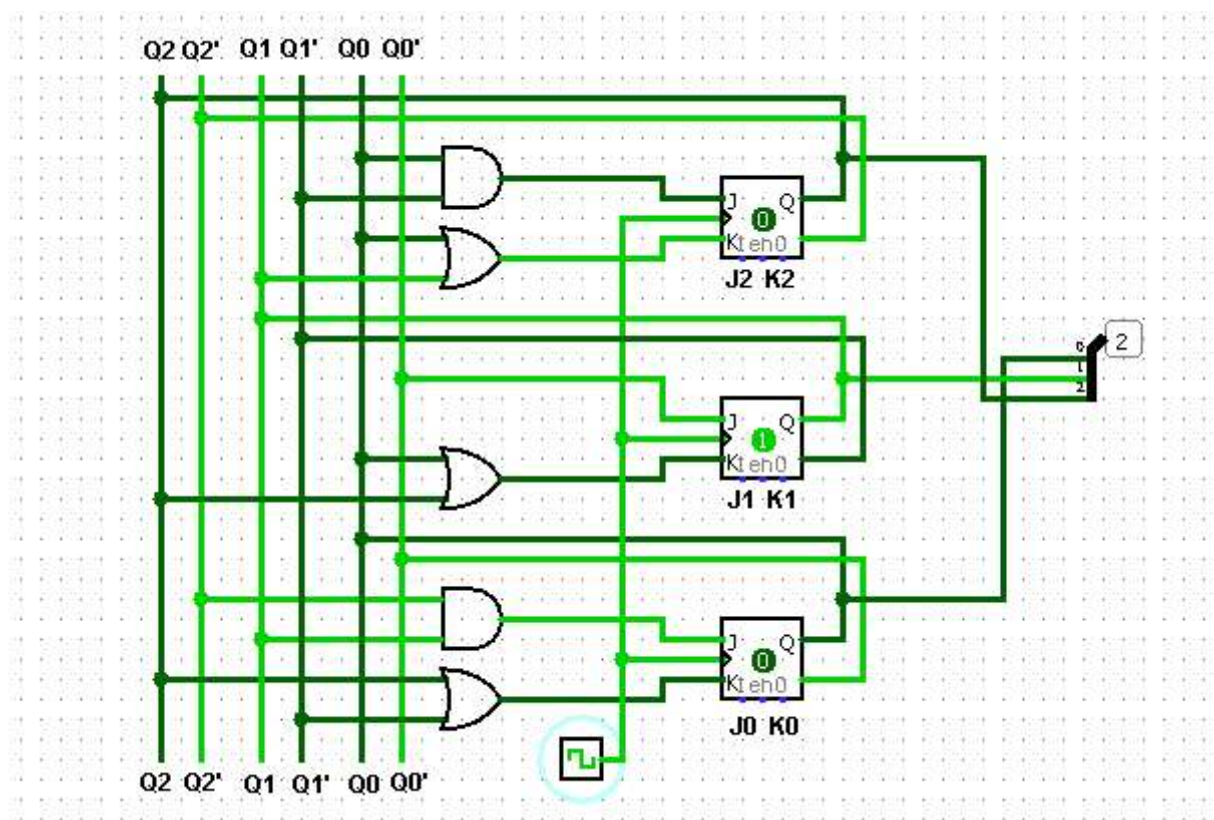
### 4.0.3 Circuit Diagrams











## 5.0 Discussion

The term "arbitrary sequence" refers to a sequence of elements that does not follow a specific predetermined pattern or rule. While arbitrary sequences may lack predictability and regularity, they can have several potential benefits and applications.

**The JK flip-flop offers several benefits and advantages** that make it a valuable component in digital circuit design and sequential logic:

1. **Versatility:** JK flip-flops are versatile with toggle functionality for counting, memory storage, and state machines.
2. **Frequency Division:** Used in counters for dividing frequencies or counting pulses.
3. **Memory:** Stores binary data, aiding in memory elements.
4. **State Machines:** Essential for finite state machine designs.
5. **Synchronous Operation:** Synchronized actions with clock signals.
6. **Compact Design:** Single flip-flop handles set and reset functions.
7. **Educational Tool:** Aids in teaching digital logic and sequential circuits.
8. **Control Circuits:** Supports timing-sensitive control systems.