# 1 Treatment of Neumann boundary conditions

### Simple approach

The simple approach here is to take a one-sided finite difference approximation: Here, the one-sided differ-

$$\frac{\partial T}{\partial x} = F(y)$$

$$\frac{T_{imax,j} - T_{imax-1,j}}{\Delta x} = F(y_j)$$

ence has been used such that information relies only on the interior of the domain.

#### Second-order approach

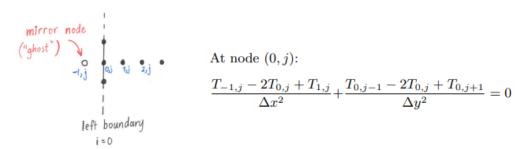
Can you write a second order accurate method for this boundary? What is the form of this and the related error term? *Hint:* can use method of undetermined coefficients, or derive through a Taylor expansion.

## 1.1 Symmetry boundary conditions

This is a special type of Neumann boundary condition in which the derivative with respect to the normal of the domain boundary is 0,

$$\frac{\partial T}{\partial \mathbf{n}} = 0.$$

Example for Laplace equation:



Find expression for ghost value  $T_{-1}$  using symmetry boundary condition:

$$\frac{\partial T}{\partial n} = 0 \quad \rightarrow \quad \frac{T_{1,j} - T_{-1,j}}{2\Delta x} \approx 0 \quad \rightarrow \quad T_{-1,j} = T_{i,j}$$

Finally giving:

$$\frac{2T_{1,j} - 2T_{0,j}}{\Delta x^2} + \frac{T_{0,j-1} - 2T_{0,j} + T_{0,j+1}}{\Delta y^2} = 0$$

## 2 Discretisation error

In solving the Laplace (or Poisson) equations, we have been using second order central differences to determine both the second derivative with respect to x and y. For some discretisation,  $(\delta x, \delta y)$  the corresponding error terms are,

$$\varepsilon_{xx} = \frac{\delta x^2}{12} \frac{\partial^4 f}{\partial x^4} (\xi_i, y_j), \quad \text{with } x_{i-1} \le \xi_i \le x_{i+1}$$

$$\varepsilon_{yy} = \frac{\delta y^2}{12} \frac{\partial^4 f}{\partial y^4} (x_i, \eta_j), \quad \text{with } y_{j-1} \le \eta_i \le y_{j+1}$$

Here it can be seen that the global error is  $O(\delta x^2 + \delta y^2)$ , namely a second order scheme.

#### Boundary influence

What happens when we use a first order one-sided difference for our boundary in this second order scheme? It turns out that 'in-general' one can use a boundary discretisation that is one order less than the interior scheme without having a significant impact on the global order of accuracy.

# 3 Applying finite difference to real world problems

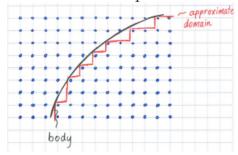
#### 3.1 Verification

Before we can trust our code, we first have to verify that it is solving what we wanted it to solve. The best way to do this is to compare our error and how this converges in comparison to an analytical solution. Namely, for the Laplace equation we have been looking at, we know our scheme is second order, so with mesh refinement we should approach an analytical solution accordingly.

## 3.2 Grid generation

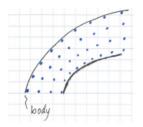
If only life was lived on a square grid.... To cater for this we can either use an embedded or body-conforming approach, It turns out that elliptic PDEs can be used for grid generation themselves. So by solving a pre-

Embedded technique



- finite-difference method is relatively easy to formulate
- accuracy may be poor due to approximate representation

Body-conforming approach



- finite-difference method is more complex: transformation from physical domain to computational domain is required
- there are sophisticated grid generation techniques to build good quality body-fitted meshes on complex geometries

determined PDE, we can determine the location for our grid points.

## Structured grid generation

Here we will look at two classes of methods:

- algebraic grid generation (e.g. transfinite interpolations)
- PDE-based grid generation (e.g. elliptic grid generation)

The use of a PDE solution comes with a number of benefits including the determination of grid locations based solely on the boundary specification and the smoothness of the resulting mesh.