

# MECH3750 PBL Content Summary

## Week 8

Content:

- Hyperbolic PDEs
  - Wave equation

Upcoming assessment:

- Problem Sheet 8 (due before Week 9 PBL session, after mid-sem break)

Tutors: Nathan Di Vaira, Alex Muirhead, William Snell, Tristan Samson, Nicholas Maurer, Jakob Ivanhoe, Robert Watt

# 1 Hyperbolic PDEs

This week in lectures we looked at the 2nd type of PDEs, hyperbolic. Hyperbolic PDEs can be first order (the convection equation),

$$\frac{\partial u}{\partial t} + v \frac{\partial u}{\partial x} = 0,$$

or 2nd order (the wave equation),

$$\frac{\partial^2 u}{\partial t^2} = c^2 \frac{\partial^2 u}{\partial x^2}.$$

The wave equation is the standard form of hyperbolic PDEs. In PBL *Question 1* you should obtain this equation. For oscillations (of a vibrating string), the constant  $c^2$  is replaced by  $F/\rho A$  (PBL *Question 2*).

## 1.1 Numerical Solution to Wave Equation

So how do we solve the wave equation using finite differences? 2nd order central differences are typically used for both the temporal and spatial derivatives,

$$\frac{u_j^{m-1} - 2u_j^m + u_j^{m+1}}{(\Delta t)^2} = c^2 \left( \frac{u_{j-1}^m - 2u_j^m + u_{j+1}^m}{(\Delta x)^2} \right),$$

However, it can be seen that this approximation depends on the previous time step ( $m-1$ ), which is a problem at the first time step. To deal with this, we apply a three-point central difference approximation to the first derivative of the initial condition,  $U_1(x)$ , such that the update equation for the first time step uses  $U_1(x)$ ,

$$u_j^1 = \frac{\sigma^2}{2} u_{j-1}^0 + (1 - \sigma^2) u_j^0 + \frac{\sigma^2}{2} u_{j+1}^0 + \Delta t U_1(x),$$

recognising that the  $u^0$  terms are simply the initial condition for displacement,  $U_0(x)$ . The general update equation for all subsequent steps is then,

$$u_j^{m+1} = \sigma^2 u_{j-1}^m + (2 - 2\sigma^2) u_j^m + \sigma^2 u_{j+1}^m - u_j^{m-1},$$

where  $\sigma = c \frac{\Delta t}{\Delta x}$ .

Similar to the diffusion equation last week, these update equations can be written in matrix form (refer to lecture notes).

## 1.2 Boundary conditions

To deal with boundaries in the wave equation, it is easiest to directly apply them at each time step. Common boundary conditions are fixed ends (Dirichlet),

$$u_0^{m+1} = u_0^m = 0; u_N^{m+1} = u_N^m = 0.$$

or specifying a zero-gradient (Neumann). By taking a 2nd order forward difference at the boundary nodes, the update for the zero-gradient condition can be obtained,

$$u_0^{m+1} = \frac{4u_1^{m+1} - u_2^{m+1}}{3}; u_{N-1}^{m+1} = \frac{4u_{N-2}^{m+1} - u_{N-3}^{m+1}}{3}.$$

Note, however, that both Dirichlet and Neumann boundaries can be non-zero and/or vary with time.