

<b>flint neill</b>	Client / Project	Job No.	Sub. Ref.	No. 1/2
SUBJECT Frequency response from state-space eqns.		Date 03/11/16	Prep. by LHY	Check. by

## FREQUENCY RESPONSE (FROM STATE-SPACE EQNS)

State-space equations:

$$\begin{bmatrix} \dot{\underline{y}} \\ \underline{y} \end{bmatrix} = \begin{bmatrix} 0 & \underline{I} \\ -\underline{M}^{-1}\underline{K} & -\underline{M}^{-1}\underline{C} \end{bmatrix} \begin{bmatrix} \underline{y} \\ \dot{\underline{y}} \end{bmatrix} + \begin{bmatrix} 0 \\ -\underline{M}^{-1} \end{bmatrix} \underline{F}(t)$$

$$\text{ie } \underset{\substack{\uparrow \\ (2N \times 1)}}{\dot{\underline{x}}(t)} = \underset{\substack{\uparrow \\ (2N \times 2N)}}{[\underline{A}]} \underset{\substack{\uparrow \\ (2N \times 1)}}{\underline{x}(t)} + \underset{\substack{\uparrow \\ (2N \times N)}}{[\underline{B}]} \underset{\substack{\uparrow \\ (N \times 1)}}{\underline{F}(t)}$$

These are  
"state-space  
equations"  
that define  
the problem

$$\text{Also: } \underset{\substack{\uparrow \\ (N_0 \times 1)}}{\underline{y}_0(t)} = \underset{\substack{\uparrow \\ (N_0 \times 2N)}}{[\underline{C}]} \underset{\substack{\uparrow \\ (2N \times 1)}}{\underline{x}(t)} + \underset{\substack{\uparrow \\ (N_0 \times N)}}{[\underline{D}]} \underset{\substack{\uparrow \\ (N \times 1)}}{\underline{F}(t)}$$

Note  $\underline{y}_0 \neq \underline{y}$ . This is  
the output vector  
( $N_0 \times 1$ )

Frequency response is defined as follows:

$$\underset{\substack{\uparrow \\ \text{Laplace} \\ \text{(or Fourier)} \\ \text{transform} \\ \text{of } \underline{y}_0(t)}}{\underline{y}_0(s)} = [\underline{G}(s)] \underset{\substack{\uparrow \\ \text{Laplace (or Fourier)} \\ \text{transform of } \underline{F}(t)}}{\underline{F}(s)}$$

Laplace      Fourier  
 $s \Leftrightarrow j\omega$

$$\text{Dimensions: } (N_0 \times 1) = (N_0 \times N) \cdot (N \times 1).$$

ie  $[\underline{G}(s)]$  is a  $(N_0 \times N)$  matrix, mapping inputs (force)  
to outputs.

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Properties of Laplace transform:

$$\mathcal{L}(\underline{\dot{y}}(t)) = s \underline{y}(s)$$

$$\mathcal{L}(\underline{\ddot{y}}(t)) = s \underline{\dot{y}}(s) \quad (= s^2 \underline{y}(s))$$

Laplace transform of state equations:

$$\left. \begin{aligned} \mathcal{L}(\underline{\dot{x}}(t)) &= [A_c] \underline{x}(s) + [B] \underline{F}(s) \\ \mathcal{L}(\underline{y}_o(t)) &= [C] \underline{x}(s) + [D] \underline{F}(s) \end{aligned} \right\}$$

$$\left. \begin{aligned} s \underline{x}(s) &= [A_c] \underline{x}(s) + [B] \underline{F}(s) \\ \underline{y}_o(s) &= [C] \underline{x}(s) + [D] \underline{F}(s) \end{aligned} \right\}$$

$$\Rightarrow (s \overset{\text{Identity matrix}}{[I]} - [A_c]) \underline{x}(s) = [B] \underline{F}(s)$$

$$\Rightarrow \underline{x}(s) = (s [I] - [A_c])^{-1} [B] \underline{F}(s)$$

$$\Rightarrow \underline{y}_o(s) = ([C] (s [I] - [A_c])^{-1} [B] + [D]) \underline{F}(s)$$

$$\Rightarrow [G(s)] = [C] (s [I] - [A_c])^{-1} [B] + [D]$$

Defines  $[G(s)]$  in terms of state-space matrices  $A, B, C, D$ .

Let  $s = j\omega$   <sup>$\nwarrow$  Fi</sup>; this gives frequency response  $[G(\omega)]$  (which is complex)

$$[G(\omega)] = [C] (j\omega [I] - [A_c])^{-1} [B] + [D]$$