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This is going to be a, hopefully, complete tutorial on configuring endstops on 3D printers build on Ramps 1.4 (http://reprap.org/wiki/RAMPS_1.4) using Marlin firmware (<https://github.com/MarlinFirmware/Marlin>).

I am going to use Pronterface/Printrun (<http://www.pronterface.com/>) host program to connect to my printer and issue terminal commands (G-codes (<http://reprap.org/wiki/Gcodes>)). That sounded very hairy, but it is just a simple program with a graphical interface.

Even though I'm going to use Ramps 1.4 (http://reprap.org/wiki/RAMPS_1.4) and Marlin firmware (<https://github.com/MarlinFirmware/Marlin>), this tutorial will most likely be usefull for most setups. We are going to use the newest Arduino IDE (<https://www.arduino.cc/en/Main/Software>) to edit the Marlin firmware.

3D Printer Buyer's Guide

For Professional and Production Applications



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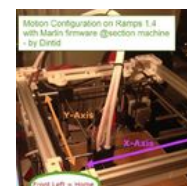
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Configuring endstops often boils down to being methodical in finding faults, which is why it is causing so many problems for many people, as many hope they can, and try to, just plug in the printer and hope it works. Which it rarely does.

If it doesn't Work it can be tempting to do something rash in hope of a quick fix, which in turn tends to compound the issues and make it much worse.

Common symptoms of faulty endstops are motors/axes which refuses to move, move in the wrong direction or move a tad this and then that way.

In short: setting up endstops correctly is not just recommended, but is mandatory before beginning to configure movement, including homing -settings for the Axes.

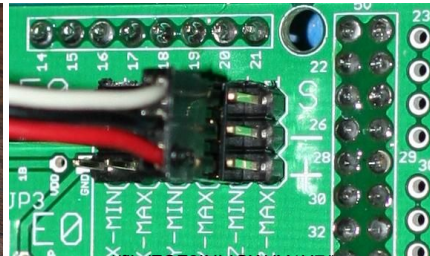
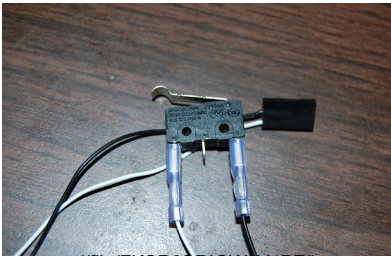
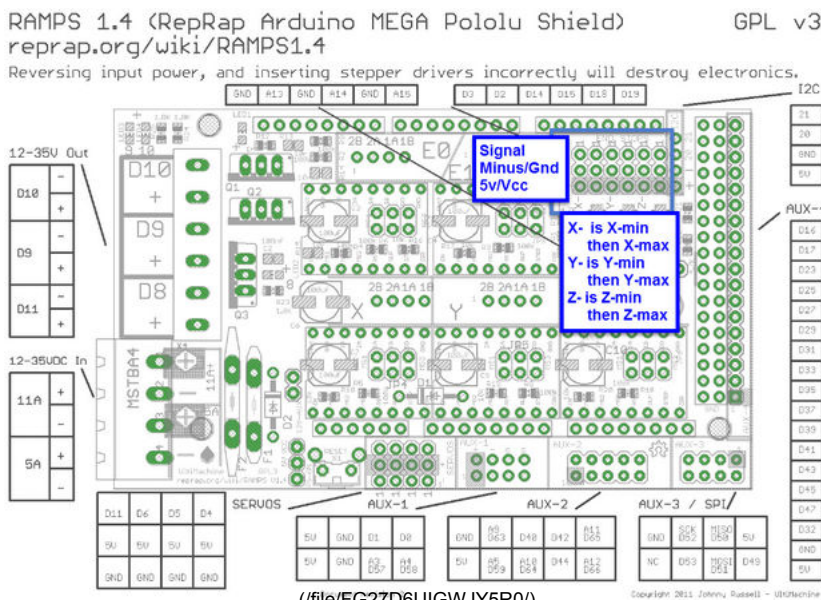
In this tutorial we are going to:

1. Explorer physical endstop pin-layout
(<http://reprap.org/mediawiki/images/c/ca/Arduinomega1-4connectors.png>) on Ramps 1.4 (http://reprap.org/wiki/RAMPS_1.4) board.
 1. Connect 2 and 3 pin endstops.
2. Get endstop status and configure Marlin firmware
([@section homing](https://github.com/MarlinFirmware/Marlin) using Pronterface (<http://www.pronterface.com/>) and the newest Arduino IDE (<https://www.arduino.cc/en/Main/Software>)
3. All done. Ready for motion configuration.



IMG_5665.MOV (/files/orig/FVL/NGWI/IGWJYF89/FVLNGWIIGWJYF89.mov)

Step 1: Endstop pin-layout on Ramps 1.4



Our first task is to identify the pins we are going to use on our Ramps 1.4 board.

Endstop pin-layout

When looking at the Ramps 1.4 board with the power-plugs facing left, the endstop-pins are located in the upper right corner as shown in the image.

From left to right we have X-min, X-max, Y-min, Y-max, Z-min, Z-max

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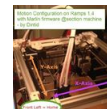
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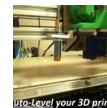
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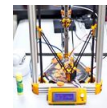
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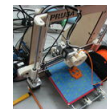
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by SteveRoy

The top most pins are *Signal* pins, the middle pins are *ground* and the lower pins are *5v/Vcc*.

Connecting Endstops

If we use a simple limit-switch as our endstop, shown on an image here, which only uses 2 wires, we are going to connect them to the *Signal* and *Ground* pin. It does not matter in which order they are connected. Signal and Ground are the 2 top-most pins.

The limit-switch has 3 legs where 1 is for signal and the other 2 are labeled *NC* and *NO*, which means *Normally Closed* and *Normally Open*, respectively.

Choosing NC or NO

I prefer using *NC* which Means a current is running through it all the time. When depressing the arm on the switch the circuit is broken and it triggers a response. It also means a fault is registered if a wire breaks, a connector comes loose, or something similar.

If you use *NO* the Circuit is closed, a current runs through it, when the arm is depressed. This means that no alarm is triggered if a wire or connector comes.

Some years ago *NO* was the norm as it wasn't as sensitive to noise and Thus did not make false positive (triggering the endstop) due to noise from motors.

The Electronics now, even on cheap Ramps 1.4 has improved a lot and the noise should not be an issue any more, so I'll recommend using the *NC* pin.

3-pin endstops

More advanced endstops which have LEDS or other Electronics Integrated use 3 wires. One for signal, ground and 5v/vcc.

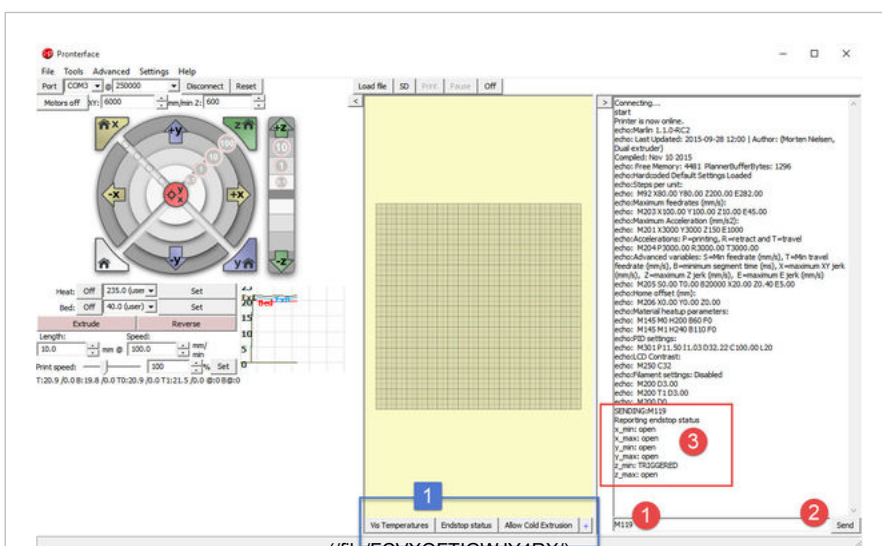
When connecting these kinds of endstops it is vitally important that the wires are correctly connected. The Signal and Ground becomes important, as opposed to the 2-wire switches, as you risk shorting out the Electronics if you connect the signal to gnd and gnd to signal, while also using the 5v/vcc pin.

Testing wires

When you have soldered the two wires to your endstop, you should test for continuity on the wires using a Multimeter. If you do not have one, I'll recommend you go buy one. A cheap one will do.

If you use more advanced endstops like IR sensors or similar, you should test it according to the manufacturers documentation.

Step 2: Endstop status using Pronterface and setup Marlin in Arduino





Now we have successfully connected our endstop and it is time to setup our firmware.

Using Pronterface

Fire up Pronterface (<http://www.pronterface.com/>) and connect to your printer.

You can see in the middle of the program, marked by a blue Square, I have added some custom bottoms for actions I use a lot like getting Endstop status (http://reprap.org/wiki/G-code#M119:_Get_Endstop_Status), allowing Cold Extrusion (http://reprap.org/wiki/G-code#M302:_Allow_cold_extrudes) and Vis Temperature (http://reprap.org/wiki/G-code#M105:_Get_Extruder_Temperature) on Extruder (Vis = show in Danish).

You do not have to create any button, but it is a nice tool. Just click the +, type in some text and the Gcode you want to use. The code for Get Endstop Status (http://reprap.org/wiki/G-code#M119:_Get_Endstop_Status) is **M119**

Commands can also just be written in the input box in lower right corner, see image, and executed by pressing enter or send.

Using M119 command

First make sure no endstops are triggered. Move the Axes if necessary. It makes it much easier to do this if all endstops has the same status. When all is ready you issue the **M119** command.

After issueing the command you will most likely see some endstops with the status of OPEN and some with the status TRIGGERED

The ones with the OPEN status are most likely configured correctly, while the other endstops are either defective, activated by your axes or the firmware needs to be corrected.

Fault finding/verifying

Now that we have our status we check to see that all the endstop with *OPEN* status are working correctly. You do that by manually activating them one by one while issue in the M119 command. If the status does not change when activated it is most likely due to bad pin-wiring on Ramps, but it can also be the firmware.

If you have any endstops not behaving you turn off the printer, unplug the USB and Check the pin-connection. Correct as necessary.

Also check for continuity again, using a multimeter.

Make a list of the endstops which shows the status as TRIGGERED when not triggered, or just keep pronterface open to see the output.

Configuring Marlin firmware in Arduino IDE

Open the Configuration.h file/sketch/tab and scroll Down to the *@section homing* - around line 330 or so.

Make sure you do not have 2 // in front of #define ENDSTOPPULLUPS. If you have, then remove them, upload the firmware to your printer and redo the tests we just did in Pronterface.

Note: remember you have to disconnect in Pronterface before uploading firmware or you will get an error in Arduino IDE

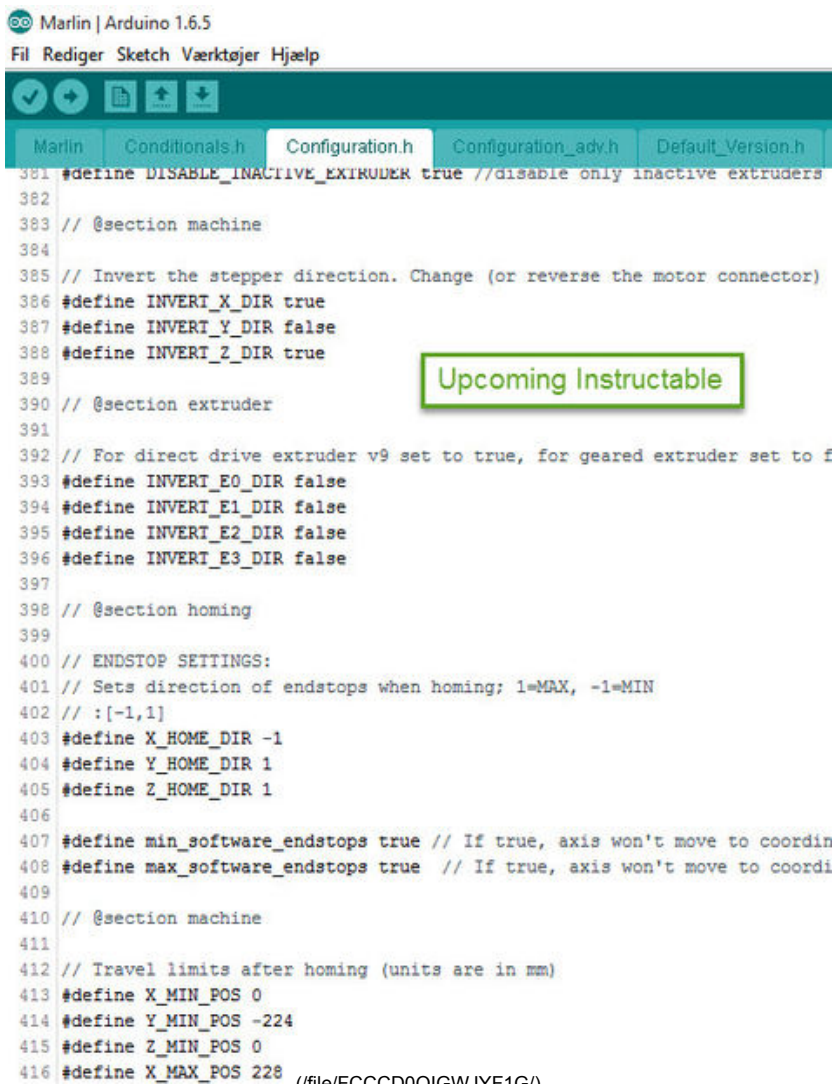
Now go Down a few line to *"// Mechanical endstop with COM to ground and NC..."* and change the value from *false* to *true* or the other way, see image, for the endstops outputting TRIGGERED when not triggered.

```
// The pullups are needed if you directly connect a mechanical endswitch b
etween the signal and ground pins.
const bool X_MIN_ENDSTOP_INVERTING = false; // set to true to invert...
const bool Y_MIN_ENDSTOP_INVERTING = true; // set to true to invert...
const bool Z_MIN_ENDSTOP_INVERTING = false; // set to true to invert...
const bool X_MAX_ENDSTOP_INVERTING = true; // set to true to invert...
const bool Y_MAX_ENDSTOP_INVERTING = false; // set to true to invert..
const bool Z_MAX_ENDSTOP_INVERTING = false; // set to true to invert...
//#define DISABLE_MAX_ENDSTOPS
//#define DISABLE_MIN_ENDSTOPS
```

Upload the firmware and redo the test in Pronterface.

I changed my Z-min to true from false and it now displays correctly in Pronterface - see image.

Step 3: All done. Ready for motion configuration



```
Marlin | Arduino 1.6.5
Fil Rediger Sketch Værktøjer Hjælp

Marlin Configuration.h Configuration_adv.h Default_Version.h

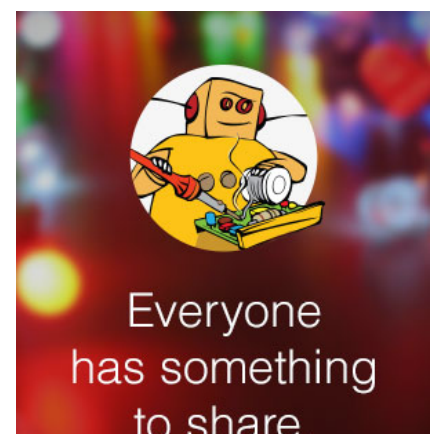
381 #define DISABLE_INACTIVE_EXTRUDER true //disable only inactive extruders
382
383 // @section machine
384
385 // Invert the stepper direction. Change (or reverse the motor connector)
386 #define INVERT_X_DIR true
387 #define INVERT_Y_DIR false
388 #define INVERT_Z_DIR true
389
390 // @section extruder
391
392 // For direct drive extruder v9 set to true, for geared extruder set to f
393 #define INVERT_E0_DIR false
394 #define INVERT_E1_DIR false
395 #define INVERT_E2_DIR false
396 #define INVERT_E3_DIR false
397
398 // @section homing
399
400 // ENDSTOP SETTINGS:
401 // Sets direction of endstops when homing; 1=MAX, -1=MIN
402 // :[-1,1]
403 #define X_HOME_DIR -1
404 #define Y_HOME_DIR 1
405 #define Z_HOME_DIR 1
406
407 #define min_software_endstops true // If true, axis won't move to coordin
408 #define max_software_endstops true // If true, axis won't move to coordi
409
410 // @section machine
411
412 // Travel limits after homing (units are in mm)
413 #define X_MIN_POS 0
414 #define Y_MIN_POS -224
415 #define Z_MIN_POS 0
416 #define X_MAX_POS 228 //16/ECCDD001GW1V51G)
```

Congratulate yourself as you have just setup one of the most important features of your printer.

You actually don't need to use endstops, but when you do, you really need to have them configured correctly before you can move on and setup the motion of your printer.

I am going to make an Instructable on setting up the movement direction of the axes, homing direction and configuration of Travel limits after homing.

Update: you can find it here: Motion Configuration on Ramps 1.4 with Marlin firmware @section machine (<http://www.instructables.com/id/Motion-Configuration-on-Ramps-14-with-Marlin-firmware/>)



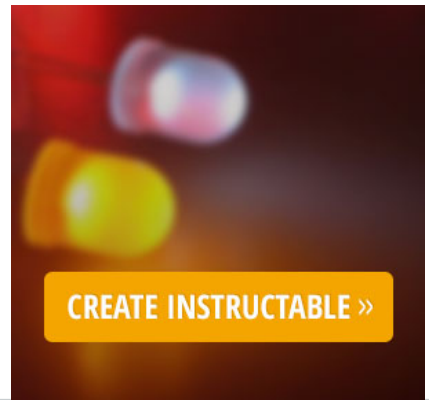


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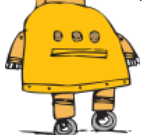
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