

ISTANBUL TECHNICAL UNIVERSITY
COMPUTER ENGINEERING DEPARTMENT

BLG 212E
MICROPROCESSOR SYSTEMS
TERM PROJECT

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GROUP NO : G7

GROUP MEMBERS:

150150104 : Ece Nur ŞEN

150150109 : Dilara İnan

150150015 : İdil Sezgin

070170450 : Muhammed Enes Deniz

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FRONT COVER

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1 INTRODUCTION

In this project, we created an assembly program that takes data set and performs operation on data with given instruction set. Our instructions consist of adding an element to linked list, removing element from linked list and transforming linked list to array. In order to create this program, we have worked with Arm Cortex M0+ processor and we used Keil uVision IDE as integrated development environment. Since we didn't own an Arm Cortex M0+ processor, we tested our program with the simulator of Keil uVision. We arranged our processors clock frequency as 8 MHz. Our program creates a SysTick interrupt every 827 microseconds. Whenever an systick interrupt occurs, SysTick_Handler is called. In SysTick_Handler, a new data and its relative flag are read from given in_data array and in_data_flag array. According to its flag, data is sent to a function which might be Insert, Remove and LinkedList2Arr. If an error occurs, the error code and required inputs are sent to WriteErrorLog function. Errors are saved to memory. End of the the SysTick_Handler, we check whether the whether we read every data in in_data array or not. If every data is read, we stopped the systick timer and the program terminates.

2 MATERIALS AND METHODS

2.1 SysTick_Handler

SysTick_Handler function is called when systick counter reached to 0. Firstly, the in_data and its relative in_data_flag is read from the memory. Data represent the value, whereas the flag represent with function this value will be send. If flag is equal to 0, value is sent to Remove function. If flag is equal to 1, value is sent to insert function. If flag is equal to 2, LinkedList2Arr function is called without input. After functions returns with error code; tick count, error code, operation -which is flag- and value -which is data- is sent to WriteErrorLog. Error code that is sent could be 0, which represents no error occurred during execution of function. Afterwards, TICK_COUNT will be incremented. We check, whether we reach the end of in_data array or not. If we reached the end of input data array, SysTick_Stop function is called. Finally, SysTick_Handler returns to main loop.

2.2 SysTick_Init

Systick_Init function sets the System Tick Timer registers, start the timer and update the program status register. To conduct these operations firstly we have to calculate the reload value with the given clock frequency: 8 Mhz and Period Of the System Tick Timer

Interrupt: 827 microseconds.

$$\begin{aligned}Period &= (1 + ReloadValue)/F_{cpu} \\827 * 10^{-6} &= (1 + ReloadValue)/8 * 10^6 \\827 * 8 &= (1 + ReloadValue) \\6616 &= (1 + ReloadValue) \\ReloadValue &= 6615\end{aligned}$$

After loading the reload value, we set the enable, clock and interrupt flags as 1. We update the program status register content as 1 to start the timer.

2.3 SysTick_Stop

SysTick_Stop function stops the System Tick Timer. First we take the address of systick control and status register then we load zero value to this address. It makes countflag = 0, clksource = 0, tickint = 0 and enable = 0. Then we clear the interrupt flag. After that we take the address of program status to update its value and we give two to program status to say that all data operations are finished.

2.4 Clear Functions

Clear_ErrorLogs and Clear_Alloc functions work in the same way. Clear_Alloc function uses the starting address and size of the allocation table (AT_MEM), while the Clear_ErrorLog function uses the starting address and size of the error log array (LOG_MEM). After the required values are loaded, a register is initialized to keep the index value. The selected indexes of the arrays are reset, then the index is increased and the loop starts again. The index value is compared with the size of the array, when the index is equal to the size, the function ends.

2.5 Init_GlobVars

Init_GlobVars function initializes the global variables such as TICK_COUNT, FIRST_ELEMENT, INDEX_INPUT_DS, INDEX_ERROR_LOG and PROGRAM_STATUS. Firstly we give zero value to a register, then store the register's value in the global variables.

2.6 Malloc

Malloc function finds and allocates the unused memory node from allocation table. In allocation table there exists 20 words and each word consists from 32 bits. Moreover, each bit points one memory node so in other words in every word there exists 32 memory nodes and in total there exists $20 \times 32 = 640$ space for allocation. To visualize this we have created the allocation table's possible look in figure 1. There exists 20 rows which represents words and 32 columns which represents 32-bit.

1st Word	0. bit	1. bit	2. bit	3. bit	4. bit	5. bit	6. bit	7. bit	25. bit	26. bit	27. bit	28. bit	29. bit	30. bit	31. bit
2nd Word	0. bit	1. bit	2. bit	3. bit	4. bit	5. bit	6. bit	7. bit	25. bit	26. bit	27. bit	28. bit	29. bit	30. bit	31. bit
3rd Word	0. bit	1. bit	2. bit	3. bit	4. bit	5. bit	6. bit	7. bit	25. bit	26. bit	27. bit	28. bit	29. bit	30. bit	31. bit
4th Word	0. bit	1. bit	2. bit	3. bit	4. bit	5. bit	6. bit	7. bit	25. bit	26. bit	27. bit	28. bit	29. bit	30. bit	31. bit
5th Word	0. bit	1. bit	2. bit	3. bit	4. bit	5. bit	6. bit	7. bit	25. bit	26. bit	27. bit	28. bit	29. bit	30. bit	31. bit
6th Word	0. bit	1. bit	2. bit	3. bit	4. bit	5. bit	6. bit	7. bit	25. bit	26. bit	27. bit	28. bit	29. bit	30. bit	31. bit
7th Word	0. bit	1. bit	2. bit	3. bit	4. bit	5. bit	6. bit	7. bit	25. bit	26. bit	27. bit	28. bit	29. bit	30. bit	31. bit
8th Word	0. bit	1. bit	2. bit	3. bit	4. bit	5. bit	6. bit	7. bit	25. bit	26. bit	27. bit	28. bit	29. bit	30. bit	31. bit
9th Word	0. bit	1. bit	2. bit	3. bit	4. bit	5. bit	6. bit	7. bit	25. bit	26. bit	27. bit	28. bit	29. bit	30. bit	31. bit
10th Word	0. bit	1. bit	2. bit	3. bit	4. bit	5. bit	6. bit	7. bit	25. bit	26. bit	27. bit	28. bit	29. bit	30. bit	31. bit
11th Word	0. bit	1. bit	2. bit	3. bit	4. bit	5. bit	6. bit	7. bit	25. bit	26. bit	27. bit	28. bit	29. bit	30. bit	31. bit
12th Word	0. bit	1. bit	2. bit	3. bit	4. bit	5. bit	6. bit	7. bit	25. bit	26. bit	27. bit	28. bit	29. bit	30. bit	31. bit
13th Word	0. bit	1. bit	2. bit	3. bit	4. bit	5. bit	6. bit	7. bit	25. bit	26. bit	27. bit	28. bit	29. bit	30. bit	31. bit
14th Word	0. bit	1. bit	2. bit	3. bit	4. bit	5. bit	6. bit	7. bit	25. bit	26. bit	27. bit	28. bit	29. bit	30. bit	31. bit
15th Word	0. bit	1. bit	2. bit	3. bit	4. bit	5. bit	6. bit	7. bit	25. bit	26. bit	27. bit	28. bit	29. bit	30. bit	31. bit
16th Word	0. bit	1. bit	2. bit	3. bit	4. bit	5. bit	6. bit	7. bit	25. bit	26. bit	27. bit	28. bit	29. bit	30. bit	31. bit
17th Word	0. bit	1. bit	2. bit	3. bit	4. bit	5. bit	6. bit	7. bit	25. bit	26. bit	27. bit	28. bit	29. bit	30. bit	31. bit
18th Word	0. bit	1. bit	2. bit	3. bit	4. bit	5. bit	6. bit	7. bit	25. bit	26. bit	27. bit	28. bit	29. bit	30. bit	31. bit
19th Word	0. bit	1. bit	2. bit	3. bit	4. bit	5. bit	6. bit	7. bit	25. bit	26. bit	27. bit	28. bit	29. bit	30. bit	31. bit
20th Word	0. bit	1. bit	2. bit	3. bit	4. bit	5. bit	6. bit	7. bit	25. bit	26. bit	27. bit	28. bit	29. bit	30. bit	31. bit

Figure 1: Allocation Table

From starting the least significant bit of each word we traverse to whole table and when we come up to empty memory node which is denoted by 0 bit we allocate that space for the next element by doing two operation: Firstly we have set the found 0 bit as 1 and then returning its address. To return the node address we have to make a conversion for finding the node's place in data area which is used for the linked list. Similarly to visualize the data area we have created the table in figure 2. There exists again 20 rows to make visual alignment with allocation table and 32 cell(column) with each cell of it consist by 8 byte area this 8 byte is divided as following: 4 byte for value, 4 byte for next value's address.

2.8 Insert

Insert function adds the given value to linked list. If there exists another element with same value in the linked list, the given value will not be added to linked list and function returns error code 2. If the linked list is full, value will not be added to linked list and function will return with error code 1. The flow of function is as follow: Function firstly checks whether the linked list is empty or not. If the linked list is empty, function will branch to "InsertFirst" subroutine. If linked list is not empty, function will check whether the given value is smaller than first element of the linked list or not. Linked list is sorted in ascending order. If the given value is smaller than first element of the linked list, function will branch to "InsertFirst" subroutine. Otherwise, the loop phase of Insert function will begin. In the loop, function will firstly check whether the given value is equal to pointed element of linked list. If the values are equal, function will return with error code 2. Otherwise, function will check whether the pointed element of linked list is the last element of the list or not. If it is the last element, function will branch to "InsertMid" subroutine to insert given value to end of linked list. If the pointed element isn't the last element, pointer of linked list will be incremented and will show the next element. If the newly pointed element is larger than given value, function will branch to "InsertMid" subroutine. If not, the loop will continue. In "InsertFirst" subroutine, function will firstly call Malloc function to allocate memory for new value. If Malloc function returns with error, Insert function will return with error code 1, meaning the memory is full. If Malloc returns with address, given value will be saved to address. First element will be configured to show new address and pointer of the new element will point to old first element. Insert function will return with error code 0, insertion successful. Only difference between "InsertMid" and "InsertFirst" subroutines is that the given value will not be added as a first element in the linked list. Therefore, the given value will connected to previous element and current element of the linked list.

2.9 Remove

Remove function searches for the given value in the linked list. If the linked list is empty the function returns with error code 3. If the given value is not found the function returns with error code 4. Then if there is no error, it means given value is found. When the value is found, the function controls is the element at the beginning of the linked list or not. Because if the given value is the first element, the function have to change to the address of FIRST_ELEMENT pointer. If not the function gives the previous elements next pointer to the next element. Then the function calls free function to clear corresponding bits of the element from the allocation table. Lastly the functions returns 0 as success

code.

2.10 LinkedList2Arr

LinkedList2Arr function first clears the content of the AREA_MEM because we will write the elements of the linked list to this array. The function checks if the linked list is empty or not. If the linked list empty then the function returns with error code 5. If not the function iterates every element one by one and stores their values in the array. At the end, the function returns 0 as success code.

2.11 WriteErrorLog

WriteErrorLog function takes four arguments. First, the argument in the R1 register (error code) is checked. If this value is zero, the function is terminated directly because the function operates with non-zero error codes. After this step, the starting address and index value of the error log array are loaded. The current address of the array is determined by adding the index value to the starting address. If this address is not equal to _LOG_MEM then array is not full. Arguments are written to the corresponding addresses sequentially. Then the GetNow function is called to get the 32-bit timestamp value. The return value is taken from the R0 register and written to the last place. The index value is incremented and the function is terminated.

2.12 GetNow

GetNow function calculates the working time of System Tick Timer using the TICK_COUNT variable and System Tick Timer Current Value Register.

TICK_COUNT holds the number of interrupts so far. We can simply multiply TICK_COUNT with period. In our case an interrupt occurs every 827 microseconds. R0 register temporarily holds the result of this multiplication. After, to find the value of the System Tick Timer current register, its address is loaded into register R3 (0xE000E018). The value obtained is not yet correct because the clock counts from reload value to zero. So we need to subtract received value from reload value to find actual current value. To convert this value to microseconds, the formula we use to find the reload value is used.

$$Period = (1 + ReloadValue)/FCPU$$

$$CurrentTime(seconds) = (1 + CurrentValue)/8 * 10^6 \quad (2)$$

$$CurrentTime(microseconds) = (1 + CurrentValue)/8 \quad (3)$$

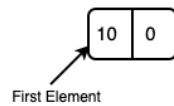
Finally current time obtained in microseconds added to R0 and function ends.

3 RESULTS

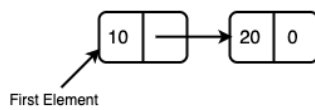
3.1 Given Test Case

In Figure 3 you can see a schema for the given test case.

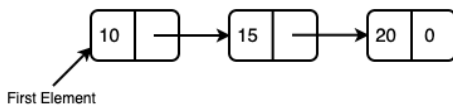
► **counter = 0** Operation: Insert 10 Add element to the beginning of linked list



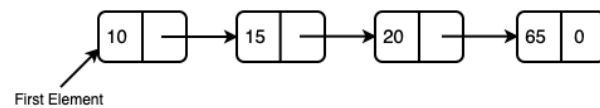
► **counter = 1** Operation: Insert 20 Add element to the end of linked list



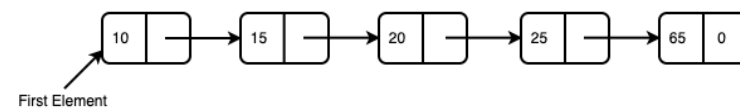
► **counter = 2** Operation: Insert 15 Add element to middle of linked list



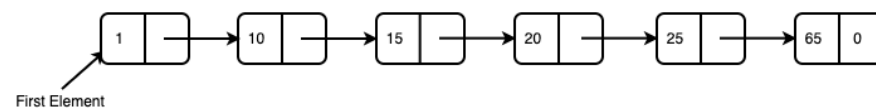
► **counter = 3** Operation: Insert 65 Add element to the end of linked list



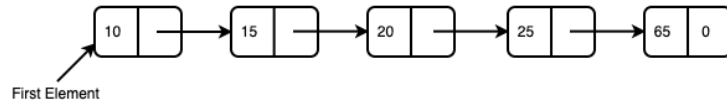
► **counter = 4** Operation: Insert 25 Add element to middle of linked list



► **counter = 5** Operation: Insert 1 Add element to the beginning of linked list



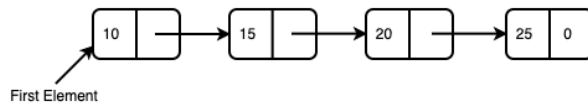
► **counter = 6** Operation: Remove 1 Remove element from the beginning of linked list



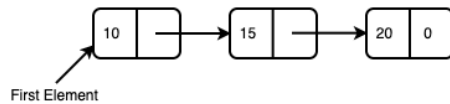
► **counter = 7** Operation: Remove 12 Remove non existing element

Return: Error code 4

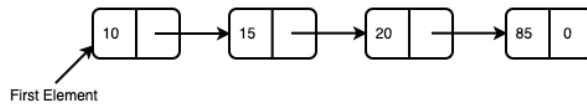
► **counter = 8** Operation: Remove 65 Remove element from the end of linked list



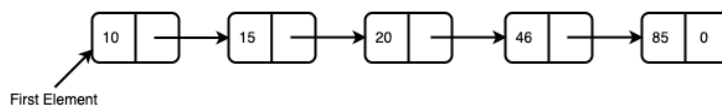
► **counter = 9** Operation: Remove 25 Remove element from the end of linked list



► **counter = 10** Operation: Insert 85 Add element to the end of linked list



► **counter = 11** Operation: Insert 46 Add element to middle of linked list



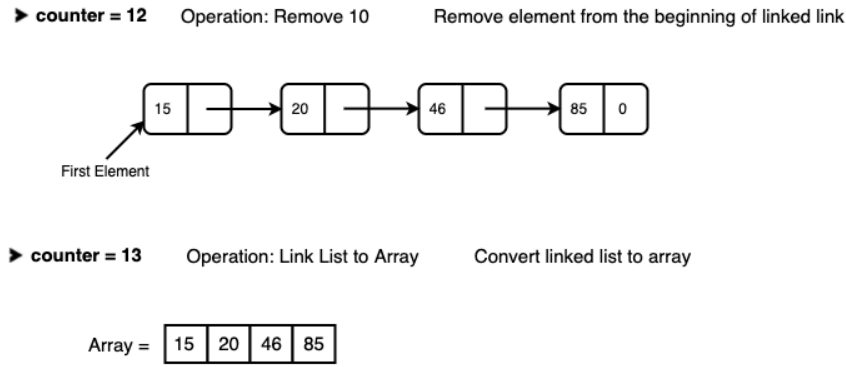


Figure 3: Result of given test case

When we run the given test case we had one error which is deletion of 12. Figure 4 shows the error log of given test case. In the first four digit of error log if 1C which is 28 in decimal. It means the index of 12 is 7. Then the next two digits shows 04 which is the error code. Next two digit is 00 which is operation. Next eight digit shows 12 which is input. And last 8 digits shows that the current System Tick Timer working time in microseconds.

Address:	0x20000A54
0x20000A54:	1C 00 04 00 12 00 00 00 B3 16 00 00 00 00 00 00 00 00 00 00 00 00

Figure 4: Error log of given test case

3.2 Our Test Case

We created a new test case to try all operations and other errors. Our IN_DATA elements are: 0x00, 0x04, 0x18, 0x09, 0x07, 0x10, 0x13, 0x07, 0x09, 0x18, 0x00 and our IN_DATA_FLAG elements are 0x02, 0x00, 0x01, 0x01, 0x01, 0x00, 0x01, 0x00, 0x01, 0x00, 0x02. When we run the program with our test case, in first element we had error code 5 which is converting empty linked list to array. In second element we had error code 3 which is remove element when linked list is empty. In sixth element we had error code 4 which is remove element when the element is not in the linked list. Lastly, in ninth element we had error code 2 which is insert the duplicated value. You can see the error_log array in the Figure 5.

Memory 1	
Address:	0x20000A54
0x20000A54:	00 00 05 02 00 00 00 00 91 02 00 00 04 00 03 00 04 00 00 00 4B 03 00 00 14 00 04 00 10 00 00 00 3B 10 00 00
0x20000A9F:	00 00

- Memory organization: In our aspect the memory organization is one of the hardest part of the project and we have work on this problem together. To ease our understanding we have create visualization for the memory tables. Employing lots of our work power on the debugging process has created a workload for us.
- In insert and remove functions, adding or removing element from linked list differs when the element is first element of the linked list. Thus, while writing this functions, we had to keep that difference in mind.

The project was covering nearly all subjects discussed in the fall term. During our progress, we have embodied most of the concepts we have learned and able to gain some basic fundamentals on assembly programming. Since we could not physically gather and come together we have experienced some communication problems yet we have accomplished to overcome them.

5 CONCLUSION

Implementing a sorted set linked list is a complicated process even with a higher level programming language. We faced many difficulties such as lack of registers, incorrect LR values, pointer usage and variety of errors. The most challenging part was that mistakes in a function could only be noticed when other functions gave unreasonable errors. At first, we had difficulties returning from functions because we lost correct LR values constantly. To overcome this, we tried to return from nested functions with B, but it turned out that this is not the correct way. At the end, we learned the correct way to return functions. After completing the code, with the help of the test cases we prepared, we fixed the errors that we could not predict at first and successfully completed the project.