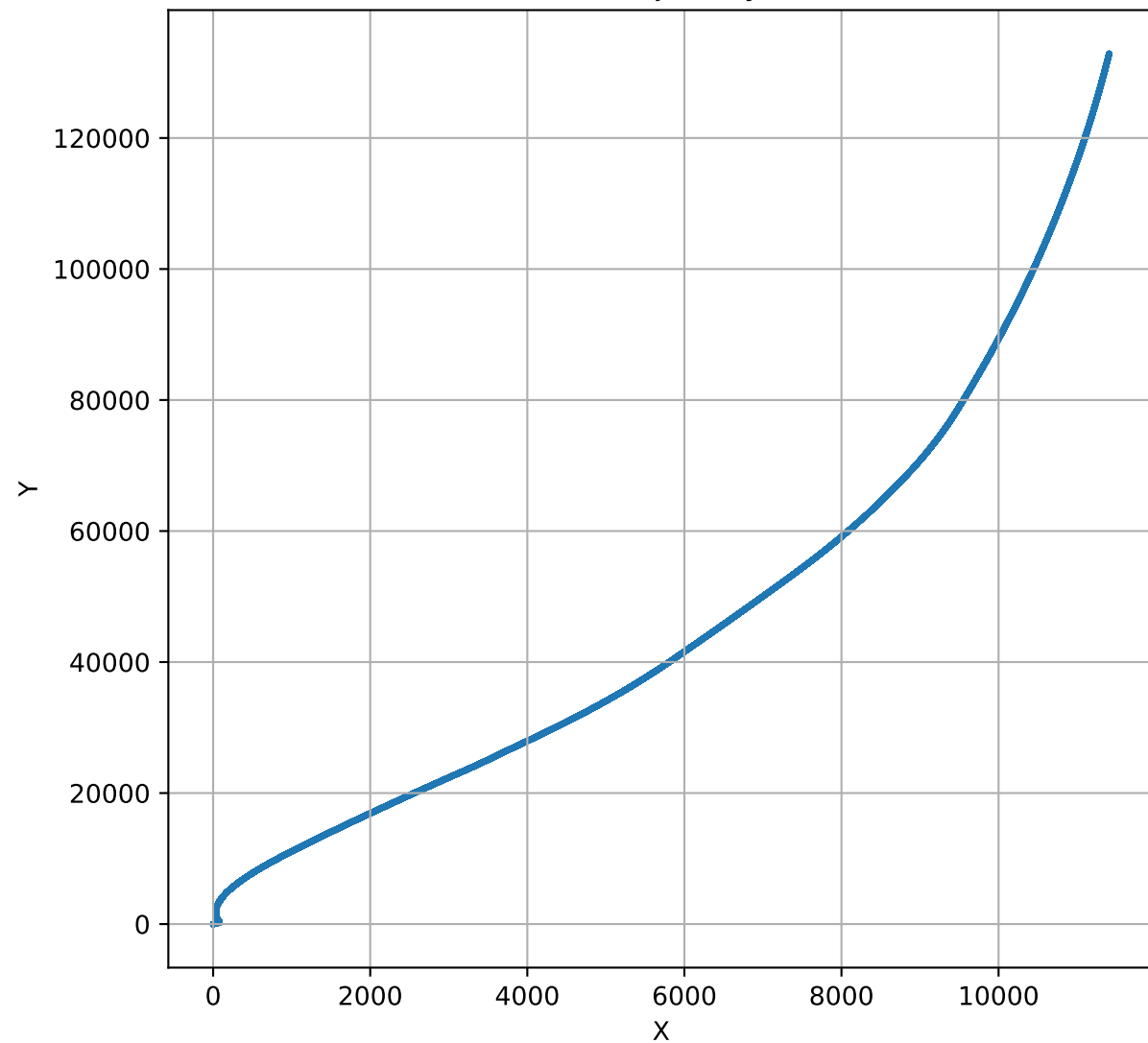


2D trajectory



q

