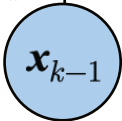


prior factor



$$\mathbf{x}_{k-1} - \bar{\mathbf{x}}_{k-1}$$



motion factor

$$\mathbf{x}_k - \mathbf{f}(\mathbf{x}_{k-1}, \mathbf{u}_k)$$



observation factor



$$\mathbf{z}_k - \mathbf{h}(\mathbf{x}_k)$$

