

What is the relation between quadratic form, Hessian, precision matrix, Mahalanobis distance and optimization?

1 Gradient of Linear Function

Consider a linear function of the form

$$f(w) = a^T w,$$

where a and w are length- d vectors. We can derive the gradient in matrix notation as follows:

1. **Convert to summation notation:**

$$f(w) = \sum_{j=1}^d a_j w_j,$$

where a_j is element j of a and w_j is element j of w .

2. **Take the partial derivative with respect to a generic element k :**

$$\frac{\partial}{\partial w_k} \left[\sum_{j=1}^d a_j w_j \right] = a_k.$$

3. **Assemble the partial derivatives into a vector:**

$$\nabla f(w) = \begin{bmatrix} \frac{\partial}{\partial w_1} \\ \frac{\partial}{\partial w_2} \\ \vdots \\ \frac{\partial}{\partial w_d} \end{bmatrix} = \begin{bmatrix} a_1 \\ a_2 \\ \vdots \\ a_d \end{bmatrix}$$

4. **Convert to matrix notation:**

$$\nabla f(w) = \begin{bmatrix} a_1 \\ a_2 \\ \vdots \\ a_d \end{bmatrix} = a.$$

So our final result is that

$$\nabla f(w) = a.$$

This generalizes the scalar case where $\frac{d}{dw}[\alpha w] = \alpha$. We can also consider general linear functions of the form

$$f(w) = a^T w + \beta,$$

for a scalar β . But in this case we still have $\nabla f(w) = a$ since the y-intercept β does not depend on w .

2 Gradient of Quadratic Function

Consider a quadratic function of the form

$$f(w) = w^T A w,$$

where w is a length- d vector and A is a d by d matrix. We can derive the gradient in matrix notation as follows

1. **Convert to summation notation:**

$$f(w) = w^T \underbrace{\begin{bmatrix} \sum_{j=1}^d a_{1j} w_j \\ \sum_{j=1}^d a_{2j} w_j \\ \vdots \\ \sum_{j=1}^d a_{dj} w_j \end{bmatrix}}_{Aw} = \sum_{i=1}^d \sum_{j=1}^d w_i a_{ij} w_j.$$

where a_{ij} is the element in row i and column j of A . To help with computing the partial derivatives, it helps to re-write it in the form

$$f(w) = \sum_{i=1}^d \sum_{j=1}^d w_i a_{ij} w_j = \sum_{i=1}^d (a_{ii} w_i^2 + \sum_{j \neq i} w_i a_{ij} w_j).$$

2. **Take the partial derivative with respect to a generic element k :**

$$\frac{\partial}{\partial w_k} \left[\sum_{i=1}^d (a_{ii} w_i^2 + \sum_{j \neq i} w_i a_{ij} w_j) \right] = 2a_{kk} w_k + \sum_{j \neq k} w_j a_{jk} + \sum_{j \neq k} a_{kj} w_j.$$

The first term comes from the a_{kk} term that is quadratic in w_k , while the two sums come from the terms that are linear in w_k . We can move one $a_{kk} w_k$ into each of the sums to simplify this to

$$\frac{\partial}{\partial w_k} \left[\sum_{i=1}^d (a_{ii} w_i^2 + \sum_{j \neq i} w_i a_{ij} w_j) \right] = \sum_{j=1}^d w_j a_{jk} + \sum_{j=1}^d a_{kj} w_j.$$

3. **Assemble the partial derivatives into a vector:**

$$\nabla f(w) = \begin{bmatrix} \frac{\partial}{\partial w_1} \\ \frac{\partial}{\partial w_2} \\ \vdots \\ \frac{\partial}{\partial w_d} \end{bmatrix} = \begin{bmatrix} \sum_{j=1}^d w_j a_{j1} + \sum_{j=1}^d a_{1j} w_j \\ \sum_{j=1}^d w_j a_{j2} + \sum_{j=1}^d a_{2j} w_j \\ \vdots \\ \sum_{j=1}^d w_j a_{jd} + \sum_{j=1}^d a_{dj} w_j \end{bmatrix} = \begin{bmatrix} \sum_{j=1}^d w_j a_{j1} \\ \sum_{j=1}^d w_j a_{j2} \\ \vdots \\ \sum_{j=1}^d w_j a_{jd} \end{bmatrix} + \begin{bmatrix} \sum_{j=1}^d a_{1j} w_j \\ \sum_{j=1}^d a_{2j} w_j \\ \vdots \\ \sum_{j=1}^d a_{dj} w_j \end{bmatrix}$$

4. **Convert to matrix notation:**

$$\nabla f(w) = \begin{bmatrix} \sum_{j=1}^d w_j a_{j1} \\ \sum_{j=1}^d w_j a_{j2} \\ \vdots \\ \sum_{j=1}^d w_j a_{jd} \end{bmatrix} + \begin{bmatrix} \sum_{j=1}^d a_{1j} w_j \\ \sum_{j=1}^d a_{2j} w_j \\ \vdots \\ \sum_{j=1}^d a_{dj} w_j \end{bmatrix} = A^T w + A w = (A^T + A) w.$$

So our final result is that

$$\nabla f(w) = (A^T + A)w.$$

Note that if A is symmetric ($A^T = A$) then we have $(A^T + A) = (A + A) = 2A$ so we have

$$\nabla f(w) = 2Aw.$$

This generalizes the scalar case where $\frac{d}{dw}[\alpha w^2] = 2\alpha w$. We can also consider general quadratic functions of the form

$$f(w) = \frac{1}{2}w^T Aw + b^T w + \gamma.$$

Using the above results we have

$$\nabla f(w) = \frac{1}{2}(A^T + A)w + b,$$

and if A is symmetric then

$$\nabla f(w) = Aw + b.$$

3 Hessian of Linear Function

For a linear function of the form,

$$f(w) = a^T w,$$

we show above the partial derivatives are given by

$$\frac{\partial f}{\partial w_k} = a_k.$$

Since these first partial derivatives don't depend on any w_k , the second partial derivatives are thus given by

$$\frac{\partial^2 f}{\partial w_k \partial w_{k'}} = 0,$$

which means that the Hessian matrix is the zero matrix,

$$\nabla^2 f(w) = \begin{bmatrix} \frac{\partial}{\partial w_1} \frac{\partial}{\partial w_1} f(w) & \frac{\partial}{\partial w_1} \frac{\partial}{\partial w_2} f(w) & \cdots & \frac{\partial}{\partial w_1} \frac{\partial}{\partial w_d} f(w) \\ \frac{\partial}{\partial w_2} \frac{\partial}{\partial w_1} f(w) & \frac{\partial}{\partial w_2} \frac{\partial}{\partial w_2} f(w) & \cdots & \frac{\partial}{\partial w_2} \frac{\partial}{\partial w_d} f(w) \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial}{\partial w_d} \frac{\partial}{\partial w_1} f(w) & \frac{\partial}{\partial w_d} \frac{\partial}{\partial w_2} f(w) & \cdots & \frac{\partial}{\partial w_d} \frac{\partial}{\partial w_d} f(w) \end{bmatrix} = \begin{bmatrix} 0 & 0 & \cdots & 0 \\ 0 & 0 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & 0 \end{bmatrix},$$

and using 0 to denote the zero matrix we have

$$\nabla^2 f(w) = 0.$$

4 Hessian of Quadratic Function

For a quadratic function of the form,

$$f(w) = w^T Aw,$$

we show above the partial derivatives are given by linear functions,

$$\frac{\partial f}{\partial w_k} = \sum_{j=1}^d w_j a_{jk} + \sum_{j=1}^d a_{kj} w_j.$$

The second partial derivatives are thus constant functions of the form

$$\frac{\partial^2 f}{\partial w_k \partial w_{k'}} = a_{k'k} + a_{kk'},$$

which means that the Hessian matrix has a simple form

$$\nabla^2 f(w) = \begin{bmatrix} \frac{\partial}{\partial w_1} \frac{\partial}{\partial w_1} f(w) & \frac{\partial}{\partial w_1} \frac{\partial}{\partial w_2} f(w) & \cdots & \frac{\partial}{\partial w_1} \frac{\partial}{\partial w_d} f(w) \\ \frac{\partial}{\partial w_2} \frac{\partial}{\partial w_1} f(w) & \frac{\partial}{\partial w_2} \frac{\partial}{\partial w_2} f(w) & \cdots & \frac{\partial}{\partial w_2} \frac{\partial}{\partial w_d} f(w) \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial}{\partial w_d} \frac{\partial}{\partial w_1} f(w) & \frac{\partial}{\partial w_d} \frac{\partial}{\partial w_2} f(w) & \cdots & \frac{\partial}{\partial w_d} \frac{\partial}{\partial w_d} f(w) \end{bmatrix} = \begin{bmatrix} a_{11} + a_{11} & a_{21} + a_{12} & \cdots & a_{d1} + a_{1d} \\ a_{12} + a_{21} & a_{22} + a_{22} & \cdots & a_{d2} + a_{2d} \\ \vdots & \vdots & \ddots & \vdots \\ a_{1d} + a_{d1} & a_{2d} + a_{d2} & \cdots & a_{dd} + a_{dd} \end{bmatrix}.$$

This gives a result of

$$\nabla^2 f(w) = A + A^T,$$

and if A is symmetric this simplifies to

$$\nabla^2 f(w) = 2A.$$

5 Example of Least Squares

The least squares objective function has the form

$$f(w) = \frac{1}{2} \|Xw - y\|^2,$$

which can be written as

$$f(w) = \frac{1}{2} w^T \underbrace{X^T X}_A w - w^T \underbrace{X^T y}_b + \underbrace{\frac{1}{2} y^T y}_\gamma.$$

By using that $X^T X$ is symmetric and using the results above we have that

$$\nabla f(w) = X^T Xw - X^T y,$$

and that

$$\nabla^2 f(w) = X^T X.$$