SPINAR:: CHEAT SHEET



What is spINAR?

The R package spINAR was developed to simulate, estimate and bootstrap integer autoregressive (INAR) models.

Installation

Development version

- > devtools::install_github("MFaymon/spINAR")
 > library(spINAR)
- Tutorial for spINAR

See Readme file in Github repository MFaymon/spINAR or

> help(package = "spINAR")

Arguments

- x: data
- n: sample size
- p: model order
- alpha: INAR coefficient(s)
- *pmf*: probability mass function of the innovation distribution
- prerun: number of additional observations
- type: estimation type (moment- or maximum likelihood-based)
- distr: parametric family of distributions (Poisson, geometric or negative binomial)
- B: number of bootstrap replicates
- setting: semiparametric or parametric
- *M*: upper limit for innovations
- level: level of confidence intervals
- progress: true or false whether progress bar is wanted
- *penal1* : L1 penalization parameter
- penal2: L2 penalization parameter
- validation: true or false whether validation is wanted
- over: indicates whether validation over penal1, penal2 or both
- init1: initial penal1 value
- init2: initial penal2 value
- folds: number of folds in validation

Functions

Simulation of INAR(p) data

spinar_sim() simulates INAR data for given sample size, model order, model coefficient(s) and pmf of the innovation distribution **Output:** simulated INAR data x

spinar sim(n, p, alpha, pmf, prerun)

Syntax

Semiparametric estimation of INAR(p) model

spinar_est() estimates semiparametrically an INAR model of given order p on given data

spinar_est(x, p)

Output: estimated model parameters: alpha and pmf

Parametric estimation of INAR(p) model

spinar_est_param() estimates parametrically (moment- or ML-based) and INAR model of given order p on given data for a given parametric family of distribution (Poi, Geo or NB)

Output: estimated model parameters: alpha and parameter(s) of input distribution

spinar_est_param(x, p, type, distr)

Bootstrapping INAR(p) data

spinar_boot() performs the (semi)parametric INAR bootstrap procedure for given data, model order, number of replications for a given parametric family of distribution (Poi, Geo or NB) and estimation method

Output: bootstrap observations, bootstrap estimated parameters (alpha and pmf or innovation parameters) and bootstrap confidence intervals

spinar_boot(x, p, B, setting, type, distr, M, level, progress)

Penalized semiparametric estimation of INAR(p) model

spinar_penal() estimates semiparametrically and penalized an INAR model of given order and given the penalization parameters on given dataOutput: penalized estimated parameters: alpha, pmf

spinar_penal(x, p, penal1, penal2)

spinar_penal_val() estimates semiparametrically and penalized an INAR model of given order and given the penalization parameter(s) on given data and allows for validation of both or only one penalization parameter

Output: penalized estimated parameters alpha, pmf and validated penalization parameter(s)

spinar_penal_val(x, p, validation, penal1, penal2, over, folds, init1, init2, progress)