

Maschinelles Lernen 1 - Assignment 2 Technische Universität Berlin

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WS 2013/2014

1 Gauging the Risk

f = a house will be flooded $\neg f = a$ house won't be flooded x =house stands in a high risk area $\neg x = \text{house stands in a low risk area}$ P(f) = 0.0005 $P(\neg f) = 0.9995$ P(x) = 0.04 $P(\neg x) = 0.96$ P(x|f) = 0.8 $P(\neg x|f) = 0.2$ α_1 = buying insurance $\alpha_2 = \text{not buying insurance}$ $\lambda(\alpha_1|f) = 1100 \in$ $\lambda(\alpha_1|\neg f) = 1100 \in$ $\lambda(\alpha_2|f) = 100000 \in$ $\lambda(\alpha_2|\neg f) = 0 \in$

a)

Bayes' formula is

$$P(A|B) = \frac{P(B|A)P(A)}{P(B)}$$

We want to determine the probability that a house in a high risk area will be flooded, i. e., we want to calculate P(f|x):

$$P(f|x) = \frac{P(x|f)P(f)}{P(x)} = \frac{0.8 \cdot 0.0005}{0.04} = 0.01$$

There is a 1% probability that our house will be flooded next year.

b)

We want to compute how much loss we can expect depending on whether we decide to buy insurance or not. Therefore we compute $R(\alpha_1|x)$ and $R(\alpha_2|x)$:

$$P(\neg f|x) = 1 - P(f|x) = 0.99$$

$$R(\alpha_1|x) = \lambda(\alpha_1|f)P(f|x) + \lambda(\alpha_1|\neg f)P(\neg f|x) = 1100 \in \cdot 0.01 + 1100 \in \cdot 0.99 = 1100 \in$$

$$R(\alpha_2|x) = \lambda(\alpha_2|f)P(f|x) + \lambda(\alpha_2|\neg f)P(\neg f|x) = 100000 \in \cdot 0.01 + 0 \in \cdot 0.99 = 1000 \in$$

Since $R(\alpha_2|x) < R(\alpha_1|x)$ it would be cheaper not to buy an insurance.

c)

We feel that the existing calculation matches this group's common sense.

2 Bounds on the Error

a)

Proof. We have

$$\min[P(\omega_1|x), P(\omega_2)|x)] \stackrel{!}{\leq} 2P(\omega_1|x)P(\omega_2|x)$$

WLOG let $P(\omega_1|x) \leq P(\omega_2|x)$ so that $0 \leq P(\omega_1|x) \leq 0.5$. Then

$$P(\omega_1|x) \le 2P(\omega_1|x)P(\omega_2|x).$$

It holds that $P(\omega_2|x) = 1 - P(\omega_1|x)$ so

$$P(\omega_1|x) \le 2P(\omega_1|x)(1 - P(\omega_1|x))$$

$$\le 2P(\omega_1|x) - 2P(\omega_1|x)^2 \Leftrightarrow$$

$$2P(\omega_1|x)^2 \le P(\omega_1|x)$$

For $P(\omega_1|x) = 0$, the inequality holds. Otherwise we can divide by that term and get

$$P(\omega_1|x) \leq 0.5$$

which is fulfilled because of our assumptions.

b)

Let $P(\omega_1|x) = P(\omega_2|x) = 0.5$. Then

$$P(\text{error}|x) = \min[P(\omega_1|x, P(\omega_2|x)] \stackrel{!}{\leq} \alpha P(\omega_1|x) P(\omega_2|x)$$
$$0.5 \leq 0.25\alpha \Leftrightarrow$$
$$\alpha \geq 2$$

which violates the assumption $\alpha < 2$.

3 Gaussian Densities

a)

Because $P(\text{error}|x) = P(\omega_2|x)$ and the definition of P(error|x) we know that $P(\omega_2|x) \leq P(\omega_1|x)$. Using Bayes' rule, it holds that

$$\frac{P(x|\omega_2)P(\omega_2)}{P(x)} \le \frac{P(x|\omega_1)P(\omega_1)}{P(x)}$$

We reformulate this to

$$\frac{P(x|\omega_2)}{P(x|\omega_1)} \le \frac{P(\omega_1)}{P(\omega_2)}$$

and using the definitions we get

$$\frac{\exp(-(x+\mu)^2/(2\sigma^2))}{\exp(-(x-\mu)^2/(2\sigma^2))} \le \frac{P(\omega_1)}{P(\omega_2)}$$

Applying the logarithm gives

$$\frac{1}{2\sigma^2} \left((x - y)^2 - (x + y)^2 \right) = \frac{1}{2\sigma^2} (-4x\mu) \le \ln \frac{P(\omega_1)}{P(\omega_2)}$$

If we want the relationship between $P(\omega_2|x)$ and the conditional error to hold, then

$$\ln P(\omega_2|x) \le \ln P(\omega_1|x) + \frac{2x\mu}{\sigma^2} \Leftrightarrow$$
$$P(\omega_2|x) \le e^{2x\mu/\sigma^2} P(\omega_1|x)$$

b)

If we furthermore also assume $\mu_2 = -\mu_1$ for a Laplacian distribution, we need to make a differentiation.

- for $x \ge \mu$, condition for $P(\omega_2)$ does not depend on x any more.
- for $x < \mu$, condition for $P(\omega_2)$ does not depend on μ any more.