
Summary: Inter-Process Communication (IPC) – Key Insights

I. What Is IPC?

Inter-Process Communication (IPC) allows processes to exchange data or signals. Essential for multitasking systems like **Linux/Unix**, it enables collaboration between:

- Parent-child processes
 - Unrelated processes
 - Processes across machines
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II. Core IPC Mechanisms (Local Systems)

Method	Purpose / Nature	Speed	Use Case Example
1. Pipes	Unidirectional, parent-child process communication	Fast	<code>pipe()</code> with <code>fork()</code>
2. FIFOs	Named pipes for unrelated processes	Moderate	<code>mkfifo()</code> , accessed via filesystem
3. Message Queue	Queue of typed messages between processes	Scalable	<code>msgget()</code> , <code>msgsnd()</code> , <code>msgrcv()</code>
4. Shared Memory	Fastest: directly share memory	Very Fast	<code>shmget()</code> , <code>shmat()</code>
5. Semaphores	Synchronize access to shared resources	Critical	<code>semget()</code> , <code>semop()</code>
6. Signals	Event notifications (lightweight)	Instant	<code>signal(SIGINT, handler)</code>
7. Sockets	IPC over local or remote networks	Flexible	<code>socket()</code> , <code>bind()</code> , <code>connect()</code>
8. Memory-mapped files	File-backed shared memory	Fast	<code>mmap()</code>
9. D-Bus	Desktop services and application messaging	High-level	Systemd, GNOME, KDE

Best Practice:

- Use **Shared Memory + Semaphores** for fast & synchronized large data sharing.
 - Use **Message Queues/Sockets** for asynchronous, flexible communications.
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III. IPC in Distributed Systems

Method	Use Case / Description
TCP/UDP Sockets	Standard networking IPC (e.g., <code>bind()</code> , <code>listen()</code>)
Message Queue Servers	RabbitMQ, Kafka, ZeroMQ for scalable messaging
gRPC (RPC)	Remote function calls over network
Distributed Shared Memory	Used in HPC, e.g., OpenMPI, TreadMarks
File-based IPC (NFS)	Write/read shared files across machines
D-Bus (Extended)	Limited use over networks with TCP backend

🔄 Trade-Off:

- **Sockets/gRPC** = best for real-time, cross-machine process interaction.
 - **Queue servers** = best for message durability, async, and load balancing.
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IV. Low-Level Functions – How IPC Is Built in C

Common Function Groups:

Function	Role
<code>pipe()</code>	Create unnamed pipe
<code>fork()</code>	Spawn child process
<code>read()</code>	Read from pipe/shared memory
<code>write()</code>	Write to pipe/shared memory
<code>mkfifo()</code>	Create named pipe
<code>open()</code>	Open FIFO for read/write
<code>close()</code>	Close descriptor
<code>unlink()</code>	Remove named pipe/file

`popen()` & `pclose()`: High-level abstraction

- `popen("ls", "r")` opens pipe to command output.
- Used like file operations: `fgets()`, `fprintf()`.

V. Code Pattern Summary

- **Pipe + `fork()`:** One-way parent-child communication.
 - **FIFO:** File-based IPC across unrelated processes.
 - **Message Queues:** Use `msgsnd()` and `msgrcv()` for flexible message passing.
 - **Shared Memory:** `shmget()` to allocate, `shmat()` to access.
 - **Semaphores:** Lock critical sections with `sem_wait()` / `sem_post()`.
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VI. Decision Matrix for IPC Choice

Goal	Best IPC Mechanism
High-speed data transfer	Shared Memory + Semaphores
Simple signaling	Signals
Cross-machine communication	Sockets or gRPC
Complex desktop communication	D-Bus
File-backed sharing	Memory-Mapped Files (<code>mmap</code>)

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