UNIT 4: VIRTUAL MEMORY MANAGEMENT AND FILE MANAGEMENT

1. Demand Paging

• Definition:

A technique where pages are only loaded into memory **when they are needed**, rather than loading the entire process at once.

• How It Works:

- o Initially, no pages are loaded.
- o On a page fault, the OS loads the required page from disk to RAM.
- o Reduces memory usage and allows more processes to fit in memory.

Advantages:

- o Less I/O.
- o Faster program startup.
- o Efficient memory usage.

Disadvantages:

- o Page faults can cause delays.
- o If used poorly, can lead to **thrashing**.

2. Copy-On-Write (COW)

• Definition:

A resource-management strategy where multiple processes share the same memory page until one needs to modify it.

How It Works:

- o Commonly used during fork() in UNIX-like OSes.
- o Parent and child share memory.
- On a write attempt, the OS copies the page, and each process gets its own version.

• Benefits:

- o Saves memory when pages are not modified.
- o Improves performance by avoiding unnecessary copying.

• Use Cases:

- o Process creation.
- o Virtual memory optimization.
- o Forking in multiprocessing environments.

3. Page Replacement

• Definition:

When memory is full and a page fault occurs, the OS must **replace** a page in memory with a new one from disk.

Common Algorithms:

- o **FIFO** (**First-In**, **First-Out**): Oldest page is replaced.
- o LRU (Least Recently Used): Page not used for the longest time is replaced.
- o **Optimal:** Replaces the page that will not be used for the longest time (theoretical, used for benchmarking).
- Clock Algorithm (Second-Chance): Cycles through pages to find a suitable one to replace.

• Page Fault Rate:

- o Important to minimize.
- o Affected by algorithm choice and number of allocated frames.

4. Allocation of Frames

• Definition:

Refers to how many frames (physical memory pages) are allocated to each process.

Types of Allocation:

- o **Equal Allocation:** Each process gets the same number of frames.
- o **Proportional Allocation:** Based on the size or priority of processes.
- o **Priority-Based Allocation:** High-priority processes get more frames.

• Global vs. Local Allocation:

- o Global Replacement: Process can take frames from other processes.
- o **Local Replacement:** Process can only replace its own pages.

• Minimum Number of Frames:

Determined by hardware and the instruction set architecture (e.g., how many pages a single instruction can touch).

1. Thrashing

• Definition:

Thrashing occurs when a system spends more time swapping pages in and out of memory than executing actual processes, due to frequent page faults.

Causes:

- o High degree of multiprogramming.
- o Insufficient frames allocated to processes.
- o Processes exceeding their working sets (the set of pages they actively use).

• Symptoms:

- o High page-fault rate.
- o Low CPU utilization.
- Very slow performance.

Solutions:

- Reduce degree of multiprogramming (kill or suspend some processes).
- Use working set model: Allocate enough frames to each process based on its actual usage.
- Page fault frequency (PFF) control: Monitor and adjust based on acceptable page fault rates.
- Use smarter page replacement algorithms (like LRU instead of FIFO).

2. Memory-Mapped Files

• Definition:

A technique that maps a file or a portion of a file into the **virtual memory address space** of a process.

• How It Works:

- o File contents appear in memory; the OS handles loading and saving transparently.
- No need for explicit read/write system calls; memory access (load/store) is used instead.
- o Page faults are used to load file contents into memory as needed (lazy loading).

Advantages:

- o Efficient I/O for large files.
- o Simplifies file access (especially in shared memory scenarios).
- o Shared memory between processes is easy (via shared file mappings).

Use Cases:

- Databases and multimedia applications.
- o Shared memory IPC (Inter-Process Communication).
- o Fast file access in operating systems and language runtimes.

3. Allocating Kernel Memory

• Definition:

Refers to how memory is allocated **within the kernel space** for various kernel activities and data structures.

• Requirements:

- Memory should be allocated quickly and must be **non-pageable** (always resident in RAM).
- Must handle various allocation sizes (small for structures like process control blocks; large for buffers).

• Allocation Methods:

1. Buddy System:

- Allocates memory in power-of-2 sized blocks.
- Fast coalescing and splitting.
- Used for larger memory requests.

2. Slab Allocator:

- Efficient for allocating memory for objects of the same size (e.g., file descriptors, inodes).
- Reduces fragmentation.
- Uses caches (slabs) of pre-initialized objects.

• Fragmentation Issues:

- o **Internal Fragmentation:** Memory allocated but not used.
- External Fragmentation: Free memory is in small pieces scattered across memory.

• Kernel Memory Zones (in Linux):

- o **ZONE_DMA:** For devices needing memory below a certain address.
- o **ZONE_NORMAL:** Regular memory.

o **ZONE_HIGHMEM:** Memory not permanently mapped into the kernel space.

1. Other Considerations (in Memory Management)

These are additional memory management concerns not covered by primary mechanisms like paging or segmentation.

Key Points:

• TLB (Translation Lookaside Buffer):

- o Cache used to store recent virtual-to-physical address translations.
- o Speeds up memory access in paged systems.

• Fragmentation:

- o **Internal Fragmentation:** Wasted space within allocated memory blocks.
- o **External Fragmentation:** Free memory exists but is scattered.

Swapping:

o Moving entire processes in and out of memory to disk (less common today).

• NUMA (Non-Uniform Memory Access):

 Memory access time varies depending on which processor accesses which part of memory.

Memory Protection:

- o Ensures that processes cannot access each other's memory.
- Implemented through hardware support like base-limit registers or page tables with protection bits.

2. Storage Management

• Definition:

Refers to the efficient organization, storage, and retrieval of data on secondary storage devices like **hard disks** or **SSDs**.

Key Responsibilities:

• Block Management:

- Data on disk is stored in fixed-size blocks.
- o Free blocks must be tracked (free lists, bitmaps).

• Space Allocation Methods:

- o Contiguous: Fast but causes fragmentation.
- o **Linked Allocation:** Easy to grow, but slow to access.
- o **Indexed Allocation:** Uses an index block to locate all data blocks.

• Free Space Management:

o Techniques include bitmaps, free lists, and grouping of free blocks.

• Caching and Buffering:

o Improve performance by keeping frequently used data in faster memory (RAM).

• I/O Scheduling:

 Algorithms like FCFS, SSTF, SCAN, and LOOK optimize disk head movement to minimize latency.

3. File Concepts

• Definition:

A file is a logical container for storing related data (e.g., text, images, executables).

File Attributes:

- Name
- Type
- Size
- Location
- Protection (permissions)
- Time and date of creation/modification/access

File Operations:

- Create
- Read/Write
- Delete
- Seek (move file pointer)
- Open/Close

File Types:

- Regular files (text, binary)
- Directories
- Special files (device files, pipes, sockets)

4. Access Methods

• Definition:

Refers to how data in a file is read/written by programs.

Types:

1. Sequential Access:

- o Data is accessed in a linear, one-after-the-other fashion.
- o Most common (e.g., reading a text file).
- o Simple but not flexible.

2. Direct (Random) Access:

- o Data is accessed by specifying its location (offset).
- Useful for databases and indexing.
- o Requires fixed-length records or block-based structure.

3. Indexed Access:

- o Uses an index (like in a book) to locate blocks or records.
- Supports fast lookup and updates.
- o Common in modern file systems and databases.

1. Directory Structure

Definition:

A directory is a container that holds file entries. It organizes files hierarchically and allows efficient management and access.

Common Directory Structures:

1. Single-Level Directory:

- o All files are in one directory.
- o Easy to implement but causes name conflicts.

2. Two-Level Directory:

- Each user has their own directory.
- o Prevents name conflicts but limits grouping flexibility.

3. Tree-Structured Directory:

- o Hierarchical structure (like Windows/Linux).
- o Allows file grouping and subdirectories.
- Supports absolute and relative paths.

4. Acyclic Graph Directory:

- o Files/directories can have multiple parents using links.
- o Allows shared files but needs loop prevention.

5. General Graph Directory:

- o Like acyclic, but allows cycles.
- Needs garbage collection to handle deleted files.

2. File System Mounting

• Definition:

The process of making a file system accessible by attaching it to the main file system hierarchy.

Key Concepts:

• Mount Point:

A directory where the new file system appears (e.g., /mnt/usb in Linux).

• Mount Table:

Keeps track of all mounted file systems.

• Unmounting:

Detaching the file system to prevent data corruption or loss.

• Verification:

Before mounting, the OS verifies file system integrity and compatibility.

3. File Sharing

• Definition:

Allows multiple users or processes to access the same file, either concurrently or over time.

Mechanisms:

- User IDs and Groups:
 - o File permissions are managed based on ownership.
- Shared File Pointers:
 - o Allows processes to share the same pointer (useful in multiprocessing).
- Remote File Sharing:
 - o Using protocols like NFS (Network File System) or SMB/CIFS (Windows).
- Concurrency Control:
 - Locks (advisory/mandatory) are used to prevent race conditions and inconsistencies.

4. Protection

• Definition:

Ensures that only authorized users can access or modify files.

Common Techniques:

- Access Control Lists (ACLs):
 - o Lists permissions for each user or group.
- Unix File Permissions:
 - o Three sets: owner, group, others.
 - o Permissions: read (r), write (w), execute (x).
- Capabilities:
 - o Tokens or keys that grant specific access rights.
- Encryption:
 - o Files can be encrypted to protect content even if accessed.
- User Authentication:
 - o Ensures access is granted only to verified users.

5. Implementing a File System

• Overview:

Involves creating structures on disk that support file and directory management.

Core Components:

• Boot Control Block:

o Contains info to boot the system from the disk (if bootable).

• Superblock (or File System Control Block):

o Stores file system type, size, and metadata like inode count, block size, etc.

• Inode (Index Node):

 Metadata structure in Unix-like systems. Contains info like permissions, timestamps, and block pointers.

• Directory Structure:

Stores mappings between filenames and inodes.

• File Allocation Table (FAT):

o Used in FAT file systems (DOS/Windows). Points to the next block of the file.

Journaling:

o Helps recover from crashes by logging metadata updates before applying them.

6. File System Structure

• Physical Layout on Disk:

Components:

1. Boot Block:

o Contains bootloader code.

2. Superblock:

o Key metadata about the file system.

3. Inode Table:

List of inodes for all files.

4. Data Blocks:

Actual contents of files.

5. Free Space Management:

o Bitmaps or lists of unused blocks.

Allocation Strategies:

• Contiguous Allocation:

o Fast access, but prone to fragmentation.

• Linked Allocation:

o Each block contains a pointer to the next. No fragmentation but slower access.

• Indexed Allocation:

• Uses index blocks to store all block addresses.

1. File System Structure Implementation

• Definition:

The way the operating system organizes files and directories on **secondary storage** (like HDDs or SSDs).

Key Components on Disk:

1. Boot Block:

o Contains OS loader (if disk is bootable).

2. Superblock (File System Control Block):

o Holds metadata about the file system: total size, block size, number of inodes, etc.

3. Inode Table / FAT Table:

• Stores information about individual files (metadata like size, owner, permissions, and data block pointers).

4. Directory Structure:

o Maps file names to inodes or file descriptors.

5. Data Blocks:

o Where the actual contents of files are stored.

6. Free Space Map:

o Keeps track of which blocks are free and available for use.

2. Directory Implementation

• Goal:

Efficiently map file names to inode numbers or file descriptors and support fast lookups, creation, and deletion.

Two Common Methods:

1. Linear List:

- o Directory is a simple list of file entries.
- Easy to implement but **slow for large directories** (O(n) lookup).

2. Hash Table:

- Hashes file names to entries.
- \circ Much faster lookup (O(1) on average).
- o Requires extra memory and hash collision handling.

Directory Entry Contains:

- File name
- File type
- Inode number (or pointer to metadata)
- Possibly timestamps and size

3. Allocation Methods

How the file system allocates **disk blocks** to files.

1. Contiguous Allocation:

- Files stored in sequential blocks.
- Fast access (especially for sequential reads).
- Drawbacks:
 - o External fragmentation.
 - o File size must be known in advance.

2. Linked Allocation:

- Each file block contains a pointer to the next block.
- No fragmentation.
- Drawbacks:
 - o Random access is slow (O(n)).
 - o Extra space used for pointers.

3. Indexed Allocation:

- Uses a special index block that contains all the pointers to the file's blocks.
- Supports direct access and large files.
- **Example:** Inodes in UNIX/Linux.
- Drawbacks:
 - o Index block can be limited in size unless multi-level indexing is used.

4. Free Space Management

How the OS keeps track of which blocks are free and available for new data.

Common Techniques:

1. Bit Map (Bit Vector):

- \circ 1 = block used, 0 = block free.
- Very compact, easy to check contiguous space.
- o Can be slow to find large free blocks.

2. Free List:

- Linked list of free blocks.
- o Simple to implement, fast for allocating single blocks.
- o Not efficient for allocating contiguous blocks.

3. **Grouping:**

- o Stores addresses of free blocks in groups.
- o Improves space utilization and reduces search time.

4. Counting:

- Keeps track of free blocks in runs (e.g., start block + count).
- o Good for systems with long runs of free space.

5. Efficiency and Performance

The goal is to optimize speed, minimize overhead, and make effective use of storage.

Techniques to Improve Performance:

• Buffer Cache (Disk Cache):

- Frequently accessed disk blocks are kept in memory.
- Reduces I/O access times.

Read-Ahead:

o Predict and preload blocks into memory before they are requested.

• Write-Back vs. Write-Through:

- o Write-back: Writes are cached, improving performance but less safe.
- o Write-through: Writes go directly to disk, safer but slower.

• Clustering:

o Group blocks together to reduce seek time.

• Defragmentation:

o Rearranges blocks on disk to reduce fragmentation and improve access speed.

• Block Size Tuning:

- o Small blocks reduce internal fragmentation but may increase overhead.
- o Large blocks are more efficient for large files but waste space for small files.

1. What is Recovery?

• Definition:

Recovery is the process of **restoring a consistent state** of the system after a failure. It's especially important for **file systems**, **databases**, and **transactional systems**.

• Objective:

- Ensure data integrity and consistency.
- Resume normal operation after:
 - System crash
 - Power failure
 - Disk failure
 - File corruption

2. Types of Failures

1. System Crash (Volatile Memory Loss):

- o OS crashes or power outage.
- o Main memory (RAM) contents are lost.
- Disk content remains intact.

2. Disk Failure:

- Physical disk damage or data corruption.
- o Can result in permanent data loss.

3. Software Errors:

o Bugs or improper shutdowns may corrupt the file system or metadata.

4. Transaction Failures:

o Interruptions in multi-step operations (common in databases).

3. Recovery Techniques

A. Consistency Checking (fsck, chkdsk):

- Utility scans the file system and repairs inconsistencies.
- Example:
 - o In UNIX/Linux: fsck
 - o In Windows: chkdsk

B. Backups:

- Periodic copying of files or entire file systems to secondary storage.
- Allows manual or automatic restoration.

C. Journaling (Log-Based Recovery):

- Used in **journaling file systems** (e.g., ext3/ext4, NTFS).
- All metadata updates are first written to a **journal** (**log**).
- In case of a crash:
 - o The journal is replayed to recover the correct state.
- Two phases:
- 1. Write-Ahead Logging (WAL): Log before writing to disk.
- 2. **Commit or Abort:** Apply changes only if the transaction is complete.

D. Shadow Paging:

- Used in databases and advanced file systems.
- A copy (shadow) of the original page is made before modification.
- If failure occurs, original remains safe.

4. Steps in Recovery Process

1. **Detection of Failure:**

o Through system logs, crash reports, or inconsistency flags.

2. Analysis:

o Determine the state before the crash (via logs or snapshots).

3. Restore Consistency:

- o Apply recovery tools (like journaling replay or fsck).
- o Restore files from backup if needed.

4. Validation:

o Ensure recovered file system is working and consistent.

5. File System Specific Recovery Support

File System	Recovery Feature
ext3/ext4	Journaling (metadata or full)
NTFS	Journaling and Transaction Logs
XFS	Metadata journaling
ZFS	Copy-on-write & checksums
FAT32	No built-in recovery (requires chkdsk)

6. Best Practices for Recovery

- Use **journaling file systems** to reduce recovery time.
- Keep **regular backups** (incremental & full).
- Use **UPS systems** to prevent data loss from power failures.
- Automate periodic file system checks.