## وَمَا أُوتِيثُمْ مِنَ الْعِلْمِ إِلَّا قَلِيلًا Dr. Hesham Omran Ain Shams University – Master Micro LLC

# Analog IC Design – Cadence Tools & SA Lab 05

Simple vs Wide Swing (Low Compliance) Cascode Current Mirror

# **Intended Learning Objectives**

In this lab you will:

- Explore current mirror sizing trade-offs using Sizing Assistant (SA).
- Design and simulate low-voltage and simple current mirrors.
- Compare low-voltage and simple current mirrors.
- Learn how to use hierarchical design.

NOTE: To get access to the Sizing Assistant please register at <a href="https://adt.master-micro.com/">https://adt.master-micro.com/</a> and create a support ticket from your dashboard. Verified instructors may also request access to an editable MS Word version of the lab and the lab model answer.

NOTE: The values and charts used in the lab document assume the provided 180 nm educational device models and 1.8 V supply. Other models/technologies can be used by applying reasonable adjustments to the lab values.

# Part 1: Exploring Sizing Tradeoffs Using SA

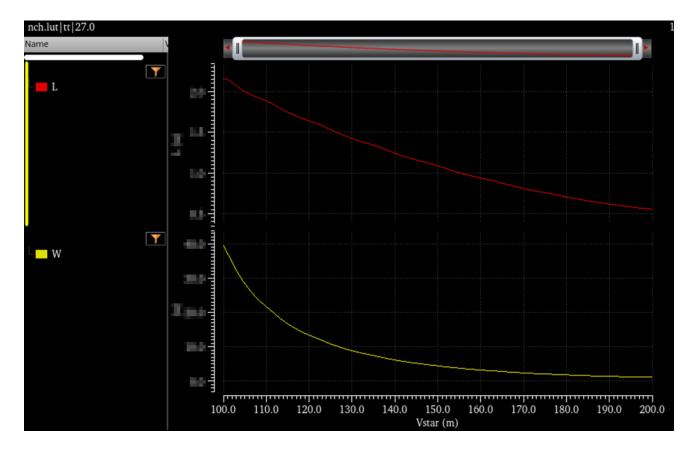
1) We want to design a simple current mirror with the following specs.

Parameter	
Input Current	10μΑ
Output Current	20μΑ
% Change in Current for $\Delta V_{out} = 1V$	< 10%
Current direction (source/sink)	Sink

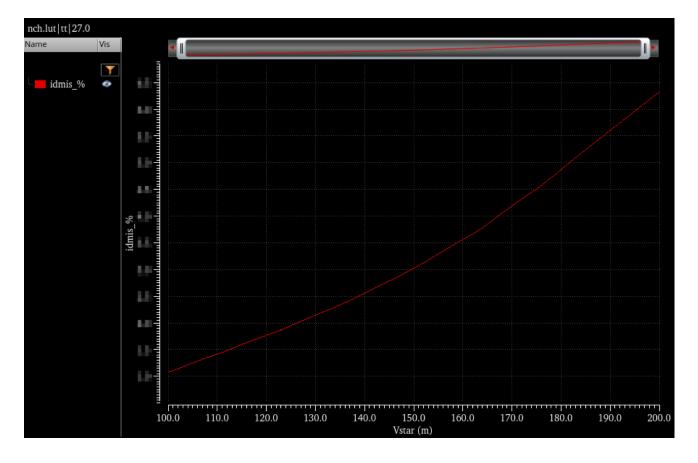
#### Answer the following:

- 2) The % Change in current translates to a spec on the  $\lambda=1/V_A$  of the device. How much is the required  $\lambda$ ?
- 3) Sinking current means which device type? NMOS or PMOS?
- 4) The higher the  $g_m/I_D$  (the lower the  $V^*$ ) the higher the headroom (the available swing), but the larger the area. Examine this trade-off using SA as shown below. Report L and W vs Vstar.





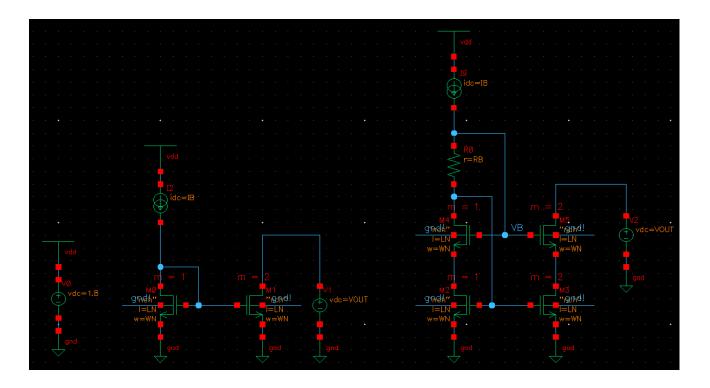
- 5) Another related tradeoff is the random mismatch, which is inversely proportional to the device area. Assume Pelgrom's coefficient for  $V_{TH}$  random mismatch is  $5mV \cdot \mu m$ . Plot the % rms (standard deviation, i.e., sigma) change in current vs Vstar using this expression in SA: idmis\_% = 5m/sqrt(W\*L\*1e12)\*gm/ID\*100
  - → ADT Hint: If the LUT contains mismatch data, we can directly use the parameter idmis in SA to get the standard deviation of the current random variations. The mismatch data can be added to any LUT using ADT by using an appropriate Monte Carlo mismatch model file.



- 6) Pick a bias point (Vstar) that gives idmis < 3%. Determine W and L. We will use these sizing parameters for the cascode current mirror as well.
- 7) Can we do the previous design trade-offs exploration sweeps using a standard SPICE simulator, i.e., sweep Vstar at a constant  $\lambda$ ? Why?

# Part 2: Current Mirror Simulation

- 1) Create a new schematic. Construct the circuit shown below. or using the toolbar.
  - → Cadence Hint: You can add labels (names) to nets (wires) using the hotkey "l" and create ports using the hotkey "p".
  - → Cadence Hint: You can put the circuit under test in a schematic, create a symbol, then create a new schematic for the testbench. For design variables (e.g., WN and LN), you can use pPar("VariableName"), which passes the variable to the upper level of hierarchy. The variables will appear when you instantiate the cell in the upper level schematic.
- 2) The current mirror takes input current IB and generates output current = 2\*IB (note the multiplier setting in the output branch).
- 3) Instead of using a wide-swing bias transistor (a magic battery) to generate RB, we use a resistor in series with the input branch.
- 4) Unless otherwise stated, set VOUT = VDD/2, VMIS1 = VMIS2 = 0.



### 1. Design and OP (Operating Point) Analysis

1) Assume we want to set a 50mV saturation margin for M2 and M3, i.e.,  $V_{DS2} \approx V_{DS3} \approx V^* + 50mV$ . Ignore the body effect and **calculate** a rough value for RB.

Hint: 
$$R_B = \frac{V_{GS4} + V_{DS2} - V_{GS2}}{I_B} \approx \frac{V_{DS2}}{I_B}$$

Hint: The purpose of rough analysis is not to reach a final design point, but to calculate a value that makes sense and can be used to determine a reasonable range for a simulator sweep.

- 2) Perform DC sweep (not parametric sweep) for RB. Choose a reasonable sweep range given the rough value computed in the previous step. **Report**  $V_{DS3}$  vs  $R_B$ . **Choose**  $R_B$  to satisfy the 50mV saturation margin requirement. Is the selected  $R_B$  value larger or smaller than the rough analytical value? Why?
  - → Cadence Hint: The DC sweep is performed in a simulator inner loop, so it is very fast and takes small disk space. The parametric sweep is an outer loop repetitive calling of the simulator, so it is much slower and takes much larger disk space.
- 3) Simulate the OP point. Report a snapshot clearly showing the following parameters.
  - → Cadence Hint: You can use Info Balloons (View -> Info Balloons) to show the device parameters. Use (View -> Annotations -> Setup) to customize the Info Balloons.
  - → Cadence Hint: You can add expressions to the Info Balloons, e.g., Vstar = 2/(gm/ID).

ID	
VGS	
VDS	
VTH	
VDSAT	
Vstar = 2/(gm/ID)	
gm/ID	
GM	
GDS	
GMB	
Region	

4) Do all transistors operate in saturation?

### 2. DC Sweep ( $I_{out}$ vs VOUT)

- 1) Perform DC sweep (not parametric sweep) using VOUT = 0:10m:VDD. Report  $I_{out}$  vs VOUT for the two CMs overlaid in the same plot.
  - o Comment on the difference between the two circuits.
  - From the plot, find an estimate for the compliance voltage of each current mirror.
  - $\circ$   $I_{out}$  of the simple CM is exactly equal to IB\*2 at a specific value of VOUT. Why?
- 2) For the simple current mirror, calculate the percent change in  $I_{out}$  when VOUT changes from 0.5V to 1.5V (i.e., 1V change). Compare the result to the value expected from Part 1.
- 3) Report the percent of error in  $I_{out}$  vs VOUT (ideal  $I_{out}$  should be IB\*2) for the two CMs in the current mirror operating region (VOUT  $\approx V^*$ to VDD) overlaid in the same plot.
  - Comment on the difference between the two circuits.
- 4) Report Rout vs VOUT (take the inverse of the derivative of  $I_{out}$  plot) for the two CMs in the current mirror operating region (VOUT  $\approx V^*$ to VDD) overlaid in the same plot. Use log scale on the y-axis. Add a cursor at VOUT = VDD/2.
  - o Comment on the difference between the two circuits.
  - Does Rout change with VOUT? Why?
  - → Cadence Hint: Rout can be also simulated using AC analysis. The value we used here should be the same as the AC analysis result at low frequencies.
- 5) Analytically calculate Rout of both circuits at VOUT = VDD/2. Compare with simulation results in a table.

### 3. Mismatch

**NOTE:** Practically, we study the mismatch using Monte Carlo simulation. However, since the educational device model we are using does not include a mismatch model, we will manually add mismatch in the circuit.

- 1) Set VMIS1 = 5m/sqrt(W\*L) and VMIS2 = 0. This models the standard deviation of the mismatch in  $V_{TH}$  for the current mirror devices. Run OP simulation. Find the percent change in  $I_{out}$ .
- 2) Analytically calculate the percent change and compare it to the simulation result. Hint: The voltage change at the gate can be considered as a small signal. Thus, the change in the current can be calculated using the  $G_m$  of the circuit. In this case, the circuit can be considered as a cascode amplifier.
- 3) Set VMIS1 = 0 and VMIS2 = 5m/sqrt(W\*L). This models the standard deviation of the mismatch in  $V_{TH}$  for the cascode devices. Run OP simulation. Find the percent change in  $I_{out}$ .
- 4) Analytically calculate the percent change and compare it to the simulation result. Hint: The voltage change at the gate can be considered as a small signal. Thus, the change in the current can be calculated using the  $G_m$  of the circuit. In this case, the circuit can be considered as a **degenerated** common source amplifier.
- 5) Which mismatch contribution is more pronounced? Why?
- 6) Which design decision is better: setting the same W and L for the mirror and cascode devices? Or using larger W and L for the current mirror devices? Why?

# **Lab Summary**

### In Part 1 you learned:

- How to use SA to examine current mirror design trade-offs.
- How to design a simple current mirror.

### In Part 2 you learned:

- How to design a wide swing (low-voltage) current mirror.
- How the behavior of a simple current mirror changes with the output voltage.
- How the behavior of a low-voltage current mirror changes with the output voltage.

# Acknowledgements