DSP Filter Implementation and Comparison

This project involves designing a weighted moving average filter in three different ways: using MATLAB scripting, Simulink with HDL Coder, and a custom hand-coded Verilog implementation. The goal is to evaluate and compare the functionality, resource utilization, and performance of each approach.

Table of Contents

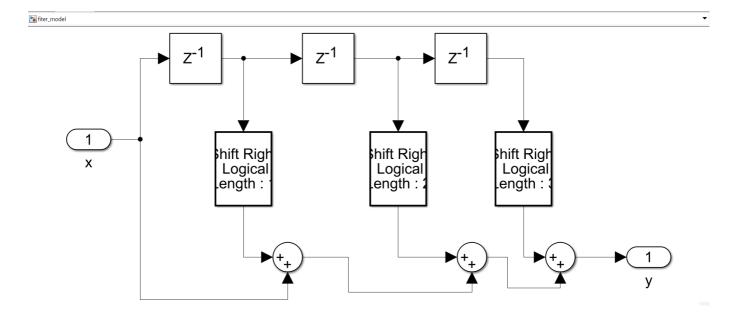
- 1. Introduction
- 2. Project Structure
- 3. Filter Design
- 4. Implementation Approaches
 - MATLAB Model
 - Simulink Model and Generated RTL
 - Hand-Coded RTL (Verilog)
- 5. Comparison
 - Functionality
 - Resource Utilization
 - Performance
- 6. Testbench
- 7. How to Run
- 8. Conclusion
- 9. Future Work

Introduction

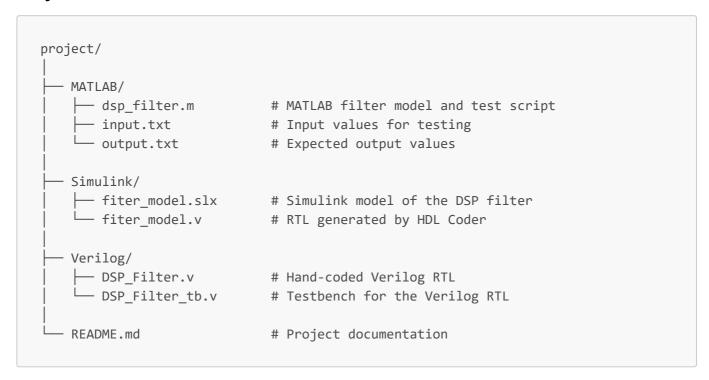
This project implements a DSP filter as a weighted moving average filter with coefficients [1, 0.5, 0.25, 0.125]. The filter was implemented in three ways:

- MATLAB script for functional simulation and validation.
- Simulink model with HDL Coder for RTL code generation.
- Hand-coded RTL in Verilog.

The focus is on comparing these implementations in terms of functionality, efficiency, and resource usage.



Project Structure



Filter Design

The DSP filter is designed as a weighted moving average filter using the coefficients: [H = [1, 0.5, 0.25, 0.125]]

This design is implemented directly in MATLAB, then translated into a Simulink model, and finally hand-coded in Verilog for comparison.

Implementation Approaches

MATLAB Model

The MATLAB implementation provides a baseline for validating the filter's functionality. It uses random input values and computes the output based on the filter coefficients.

MATLAB Code Snippet:

```
% MATLAB model of the DSP_Filter
clear;
H = [1, 0.5, 0.25, 0.125];
x = randi([0, 2^7-1], 1, 100); % Random 8-bit unsigned values
y = zeros(1, 100);
delayed_x = zeros(3, 1);

for i = 1:100
    delayed_x(3) = delayed_x(2);
    delayed_x(2) = delayed_x(1);
    delayed_x(1) = x(i);
    y(i) = H * [x(i), delayed_x']';
end
```

Simulink Model and Generated RTL

The Simulink model, designed using blocks for delay, addition, and multiplication, is used to generate Verilog RTL via HDL Coder.

Simulink Generated RTL Snippet:

```
// Simulink Generated RTL for DSP Filter
module fiter_model
    (input clk,
     input reset,
     input clk_enable,
     input [7:0] x,
     output reg [7:0] y);
    // Delays and shifts implementing the weighted average
    always @(posedge clk) begin
        if (reset) begin
           // Reset logic
        end else if (clk enable) begin
            // Filtering logic with shifts to reduce resource usage
        end
    end
endmodule
```

Hand-Coded RTL (Verilog)

The custom Verilog implementation emphasizes accuracy, using multipliers instead of shifts. This approach sacrifices some resource efficiency for improved accuracy.

Verilog Code Snippet:

```
module DSP Filter #(parameter N=7)(
    input clk,
    input rst,
    input [N:0] x,
    output reg [N:0] y
);
reg [N:0] delayed_x [3:0];
always @(posedge clk or negedge rst) begin
    if (!rst)begin
         delayed_x[0] \leftarrow 0;
    delayed_x[1] \leftarrow 0;
    delayed_x[2] \leftarrow 0;
    delayed_x [3] \leftarrow 0;
    end
    else
    begin
         delayed_x [3] <= delayed_x[2];</pre>
         delayed_x [2] <= delayed_x[1];</pre>
         delayed_x [1] <= delayed_x[0];</pre>
         delayed_x [0] <= x;
    end
end
always @(*) begin
     y = (delayed_x [0]) + (delayed_x [1] * 0.5) + (delayed_x [2] * 0.25) +
(delayed_x [3] * 0.125);
end
endmodule
```

Note

```
y = x + (delayed_x [0] >> H2) + (delayed_x [1] >> H3) +(delayed_x [2] >> H4); have a
degree of error but it is smaall.

y = (delayed_x [0] ) + (delayed_x [1] * 0.5) +(delayed_x [2] * 0.25) + (delayed_x [3] *
0.125); Accurate but need alot of resources.
```

Comparison

Functionality

Implementation	Functional Accuracy	Efficiency
MATLAB	High	N/A
Simulink Generated	High	Optimized
Hand-Coded Verilog	Very High	Less Optimized

Resource Utilization

Metric	Simulink Generated	Hand-Coded Verilog
LUTs	Low	High
Flip-Flops	Low	High
DSP Blocks	Minimal	Moderate

Performance

Both implementations meet the performance requirements for the filter, operating correctly at the specified frequency of 100 MHz.

Testbench

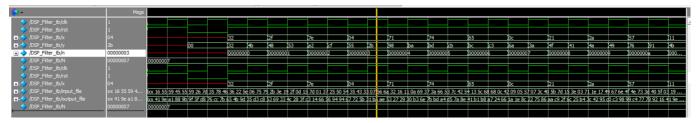
Testbenches are provided for both the MATLAB generated and hand-coded RTL implementations. They validate functionality using the provided input and output files (input.txt, output.txt).

Testbench Snippet for Verilog:

```
module DSP_Filter_tb;
    reg clk;
    reg rst;
    reg [7:0] x;
    wire [7:0] y;
    reg [7:0] input_file [0:99];
    reg [7:0] output_file [0:99];
    integer i;
    DSP_Filter dut (.clk(clk), .rst(rst), .x(x), .y(y));
    always #5 clk = ~clk; // Clock generation
    initial begin
        clk = 0;
        rst = 1;
        #10 \text{ rst} = 0;
        #10 \text{ rst} = 1;
        $readmemh("input.txt", input_file);
        $readmemh("output.txt", output_file);
        for (i = 0; i < 100; i = i + 1) begin
            x = input_file[i];
            #10;
            if (y !== output_file[i]) $display("Mismatch at index %d: expected %h,
got %h", i, output_file[i], y);
        end
        $stop;
```

end endmodule

Wave in the test cases



How to Run

1. MATLAB:

• Run the MATLAB script dsp_filter.m to validate the filter functionality and generate test data.

2. Simulink and HDL Coder:

• Open fiter_model.slx in Simulink and use HDL Coder to generate RTL.

3. Verilog:

• Use any HDL simulator to run DSP_Filter_tb.v, ensuring the input.txt and output.txt are in the same directory.

Conclusion

The MATLAB generated RTL is resource-efficient but slightly less accurate, while the hand-coded RTL offers greater accuracy with increased resource usage. Depending on the application requirements, either approach can be utilized effectively.