

Physics 2210 – Exam Two Formulae and Constants

$$\sin(\theta) = \frac{\text{opp}}{\text{hyp}}$$

$$\cos(\theta) = \frac{\text{adj}}{\text{hyp}}$$

$$\tan(\theta) = \frac{\text{opp}}{\text{adj}}$$

$$r = \sqrt{x^2 + y^2 + z^2}$$

$$\vec{A} \cdot \vec{B} = A_x B_x + A_y B_y + A_z B_z$$

$$\vec{A} \cdot \vec{B} = |\vec{A}| |\vec{B}| \cos(\theta)$$

$$\vec{A} \times \vec{B} = -\vec{B} \times \vec{A}$$

$$|\vec{A} \times \vec{B}| = |\vec{A}| |\vec{B}| \sin(\theta)$$

$$\vec{A} \times \vec{B} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ A_x & A_y & A_z \\ B_x & B_y & B_z \end{vmatrix}$$

$$\vec{r} = \vec{r}_0 + \vec{v}_0 t + \frac{1}{2} \vec{a} t^2$$

$$\vec{r} = \vec{r}_0 + \frac{1}{2} (\vec{v}_0 + \vec{v}) t$$

$$\vec{v} = \vec{v}_0 + \vec{a} t$$

$$v^2 = v_0^2 + 2 \vec{a} \cdot (\vec{r} - \vec{r}_0)$$

$$\vec{v} = \frac{d\vec{r}}{dt}$$

$$\vec{a} = \frac{d\vec{v}}{dt}$$

$$\vec{a} = \frac{d^2\vec{r}}{dt^2}$$

$$\Delta \vec{r} = \vec{r}_f - \vec{r}_i$$

$$\vec{v} = \frac{\Delta \vec{r}}{\Delta t}$$

$$\vec{a} = \frac{\Delta \vec{v}}{\Delta t}$$

$$a_r = \frac{v_t^2}{r}$$

$$T = \frac{2\pi r}{v_t}$$

$$As^2 + Bs + C = 0 \rightarrow s = \frac{-B \pm \sqrt{B^2 - 4AC}}{2A}$$

$$\sum \vec{F} = m\vec{a}$$

$$F_{\text{spring}} = -kx$$

$$K = \frac{1}{2} m v^2$$

$$U_{\text{gravity}} = mgy$$

$$U_{\text{spring}} = \frac{1}{2} k x^2$$

$$\Delta K_{\text{NC}} = -f_k \Delta s$$

$$\vec{I} = \Delta \vec{p} = \vec{F} \Delta t$$

$$s = r\theta$$

$$\theta = \theta_0 + \omega_0 t + \frac{1}{2} \alpha t^2$$

$$\theta = \theta_0 + \frac{1}{2} (\omega_0 + \omega) t$$

$$\omega = \omega_0 + \alpha t$$

$$\omega^2 = \omega_0^2 + 2\alpha (\theta - \theta_0)$$

$$I = \sum_{i=1}^n m_i r_i^2$$

$$v_t = r\omega$$

$$a_t = r\alpha$$

$$f_s \leq \mu_s n$$

$$f_k = \mu_k n$$

$$\vec{w} = m\vec{g}$$

$$K_i + U_i + \Delta K_{\text{NC}} = K_f + U_f$$

$$\Delta K + \Delta U = \Delta K_{\text{NC}}$$

$$\vec{p} = m\vec{v}$$

$$\vec{F} = \frac{d\vec{p}}{dt}$$

$$\vec{p}_{\text{total}} = \vec{p}_1 + \vec{p}_2 = \text{constant}$$

$$\Sigma \vec{p}_i = \Sigma \vec{p}_f$$

$$\bar{P} = \frac{\Delta W}{\Delta t}$$

$$P = \frac{dW}{dt} = \vec{F} \cdot \vec{v}$$

$$\Delta \theta = \theta_f - \theta_i$$

$$\bar{\omega} = \frac{\Delta \theta}{\Delta t} = \frac{\theta_f - \theta_i}{t_f - t_i}$$

$$\omega = \frac{d\theta}{dt}$$

$$\bar{\alpha} = \frac{\Delta \omega}{\Delta t} = \frac{\omega_f - \omega_i}{t_f - t_i}$$

$$\alpha = \frac{d\omega}{dt} = \frac{d^2\theta}{dt^2}$$

$$\sum \tau = I\alpha$$

$$\vec{\tau} = \vec{r} \times \vec{F}$$

$$|\vec{\tau}| = |\vec{r}| |\vec{F}| \sin(\theta)$$

$$K_R = \frac{1}{2} I \omega^2$$

$$K = \frac{1}{2} I \omega^2 + \frac{1}{2} m v_{\text{cm}}^2$$

$$v_{\text{cm}} = R\omega$$

$$a_{\text{cm}} = R\alpha$$

$$P = \tau\omega$$

$$W_{\text{net}} = \tau_{\text{net}} \theta = \Delta K_R$$

$$L_i = L_f$$

$$I_i \omega_i = I_f \omega_f$$

$$\vec{\tau} = \frac{d\vec{L}}{dt}$$

$$\vec{L} = \vec{r} \times \vec{p}$$

$$|\vec{L}| = m|v||r| \sin(\phi)$$

$$L = I\omega$$

Physical Constants

$$|\vec{g}| = 9.80 \text{ m/s}^2$$