

view_frames Result

Recorded at time: 60.175

map

Broadcaster: /gazebo
Average rate: 1012.540 Hz
Most recent transform: 60.213 (-0.038 sec old)
Buffer length: 5.024 sec

base_footprint

Broadcaster: /gazebo
Average rate: 1000.201 Hz
Most recent transform: 60.175 (0.000 sec old)
Buffer length: 4.986 sec

base_link

Broadcaster: /teeterbot/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (60.175 sec old)
Buffer length: 0.000 sec

body_com

Broadcaster: /teeterbot/robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (60.175 sec old)
Buffer length: 0.000 sec

teeterbot__link_0

Broadcaster: /teeterbot/robot_state_publisher
Average rate: 48.185 Hz
Most recent transform: 60.164 (0.011 sec old)
Buffer length: 4.960 sec

left_wheel

Broadcaster: /teeterbot/robot_state_publisher
Average rate: 48.185 Hz
Most recent transform: 60.164 (0.011 sec old)
Buffer length: 4.960 sec

right_wheel