# MICHAEL A. BICK

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### **EDUCATION**

Bachelors of Science: Mechanical Engineering Georgia Institute of Technology, Atlanta, GA Aug 2016 - June 2020

**GPA** 

Robotics Minor

Studied abroad at Georgia Tech Lorraine in Metz, France

#### Work Experience

June 2016 - Aug 2018

# UCLA Recreation | Lead Sailing Coordinator

- Coordinated the daily plan and goals for 20 co-workers
- Responsible for safety of UCLA sailors on and off the water
- Taught sailors with skill levels ranging from beginner to advanced
- Advanced from instructor to lead coordinator

#### ACADEMIC LEADERSHIP PROJECTS

Aug 2018 - April 2019

#### GTRI Agricultural Robotics | Undergraduate Researcher

- Researched, integrated, and programmed stereo depth and SLAM LIDAR units for brachiating robot
- Processed color and depth video using openCV to identify a thin cable in harsh environmental conditions
- Implemented ROS (Robot Operating System) to record, communicate, and log robot and sensor state
- Developing a standalone cable-pose sensor for feedback controls of a robot and flexible cable system

Aug 2016 - April 2017

# Robojackets | Team Member

- Lead design of a 3lb combat robot including CAD and Design for Manufacture
- Performed Finite Element Analysis on weapon subsystem to prevent catastrophic and fatigue failure
- Manufactured robotic components using precision machinery including CNC mills, lathes, and waterjets
- Created autonomous path planning and motion profile algorithm using MATLAB

Aug 2016 - April 2017

#### GT Motorsports | POWERTRAIN TEAM MEMBER

- Simulated engine dynamics to increase efficiency and low-end torque by lowering power-band
- Designed improved camshaft to match optimal lift profile

Aug 2011 - Jun 2016

#### MilkenKnights FRC Team | TEAM CAPTAIN

- Used Lean and Six Sigma principles to streamline manufacturing and assembly process
- Managed 60 students in rapid prototyping, designing, and manufacturing a robot in six weeks
- $\bullet$  Created top-down Solidworks models of transmissions, manipulators, and complex linkages
- Implemented position PID, velocity PID, vision tracking, motion profiles, and path following
- Trained students in CAD and operating precision machinery including a mill, lathe, and CNC router

Aug 2016 - Dec 2016

# 3D Printing Design Project

- Surface modeled an X-Wing, designed to be SLS printed to minimize part count and ease assembly
- Performed Geometric Dimensioning and Tolerancing to ensure functionality
- Created manufacturing drawings, assembly diagrams, and sections views for a technical report
- Final print is used as an example of excellent modeling technique and novel usage of SLS 3D printing

#### Creative Decisions and Design Competition

- Utilized CAD and laser cutting techniques to enable rapid prototyping, ideation, and manufacturing
- Wrote technical project reports outlining design process, decisions, and future improvements
- Presented our machine, design decisions, and process to a panel of qualified judges
- Programmed a NI myRio to execute a system of automated tasks using LabView

#### TECHNICAL SKILLS

- CAD Solidworks (8 years), Autodesk Inventor (9 years), Master Model, Top-down Design, Parametric Design, Surface Modeling, 2D & 3D Manufacturing/Installation Drawings, Geometric Design & Tolerancing, Design for Manufacture (DFM), Design for Assembly (DFA), Finite Element Analysis (FEA)
- Fabrication G-Code, CNC Mill, Manual Mill, Manual Lathe, Laser Cutter, Waterjet, 3D Printer, Selective Laser Sintering (SLS), Drill Press, Bandsaw, Soldering Iron
- Programming MATLAB, Java, Python, Git, Bash, Robot Operating System (ROS), OpenCV, LabView, Android, LATEX
- Mechatronics NI cRio/myRio/roboRio, Arduino, Servo Motors, Intel Realsense Stereo Camera, SLAM LIDAR, Sonar, Hall Effect, Pneumatic Actuators, Encoders, Solenoids, IR Sensors, Wire Harness
  - **Software** Adobe Illustrator, Linux, Ubuntu, Emacs, Vim, Inkscape, Gimp, Excel, Word, MacOS, Windows
  - Instruments Micrometer, Caliper, Ocilloscope, Multimeter
- Communication Oral Reports, Technical Reports, Documentation, Executive Summaries, Progress Reports, Bill of Materials (BOM)
  - **Planning** House of Quality, Specification Sheet, Morph Chart, Function Tree, Gantt Chart, Evaulation Matrix

# Awards & Honors

Dec 2016	to Present	Georgia Tech Dean's List
Nov 2017	7 th / 60	Georgia Tech ME2110 Design Competition