

# Dynare Tutorial

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# Calibrated Characteristic Equations with Level Variables

$$\frac{1}{c} = \beta E \left[ \frac{1}{c'} (1 + r') \right]$$

$$\frac{A}{1 - h} = \frac{w}{c}$$

$$a' = (1 + r)a + wh - c$$

$$r = \alpha z \left( \frac{K}{L} \right)^{\alpha-1} - \delta$$

$$w = (1 - \alpha)z \left( \frac{K}{L} \right)^{\alpha}$$

$$\log z' = \rho \log z + \epsilon', \quad \epsilon \sim N(0, \sigma_{\epsilon}^2)$$

$$a = K, \quad h = L$$

# Preamble Block (level variables)

```
// preamble: declare variables and parameters

var prod cons invst cap labor irate wage asst hour z;
varexo eps;
parameters bta delta alpha A rho sigeps;

// set parameter values

bta = 0.99;
delta = 0.025;
alpha = 0.36;
A = 1.723;
rho = 0.95;
sigeps = 0.007;
```

# Model Block (level variables)

```
// specify model equations

model;
1/cons = bta * 1/cons(+1) * (1 + irate(+1));
A*cons/(1-hour) = wage;
asst = wage*hour + (1+irate)*asst(-1) - cons;
cap = asst(-1);
labor = hour;
irate = alpha * z(-1) * (cap/labor)^(alpha-1) - delta;
wage = (1-alpha) * z(-1) * (cap/labor)^alpha;
prod = z(-1) * cap^alpha * labor^(1-alpha);
invst = wage*hour + (irate+delta)*asst(-1) - cons;
log(z) = rho*log(z(-1)) + eps;
end;
```

# Steady State Block (level variables)

```
// set initial values of endogenous variables

initval;
prod = 1.2;
cons = 0.9;
invst = 0.3;
cap = 12;
labor = 0.33;
irate = 0.01;
wage = 2.4;
asst = 12;
hour = 0.33;
z = 1;
end;

// compute steady state

steady;
```

# Shocks + Computation

```
// specify shocks

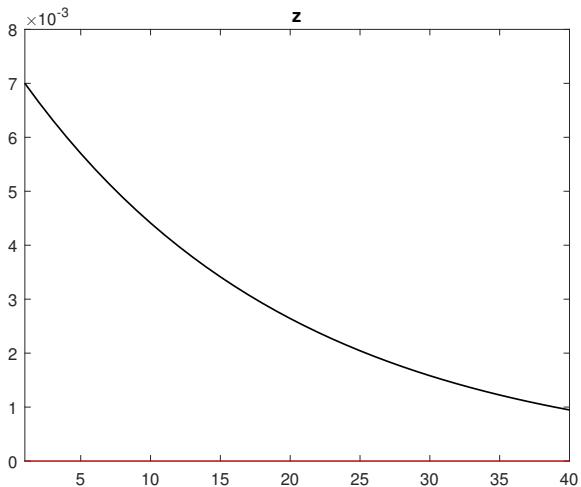
shocks;
var eps = sigeps^2;
end;

// compute solution

stoch_simul(order=1, hp_filter=1600,
             periods=40000, drop = 1000, irf = 80);
```

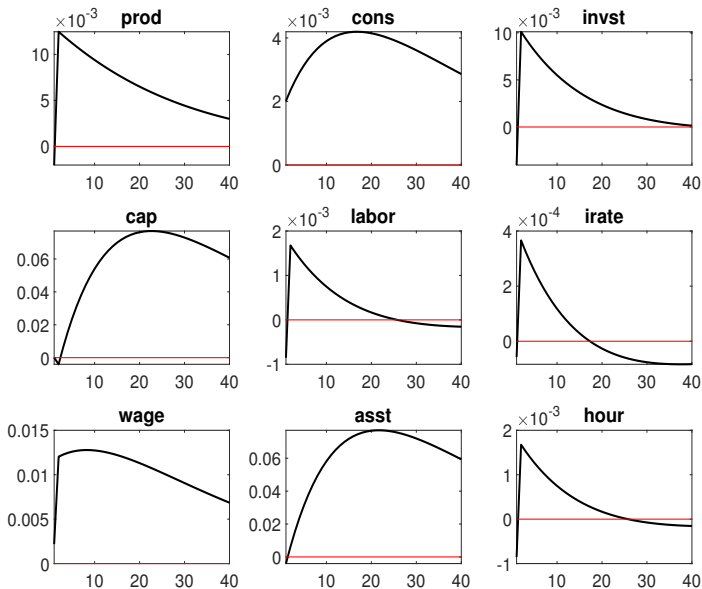
See Matlab Outputs

# Technology Shock

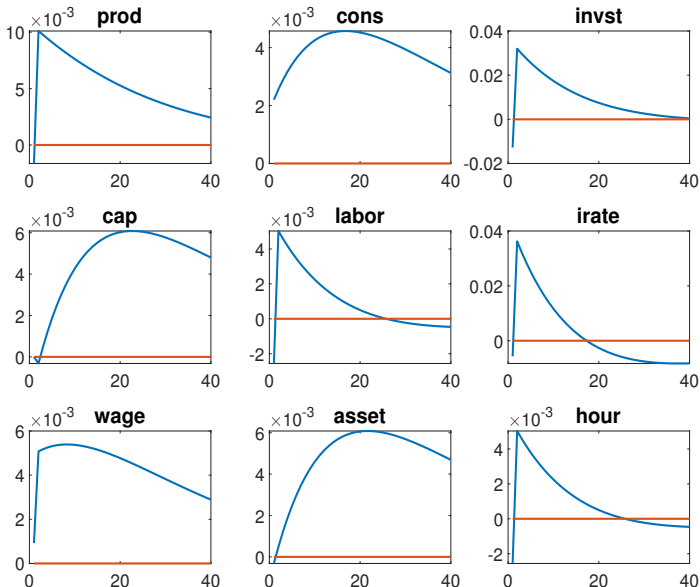




# Impulse Responses to Technology Shock



# Impulse Responses in % Dev. from Steady State



# Social Planner's Problem

The benevolent social planner maximizes the consumer's life-time utility given the resource constraints:

$$\begin{aligned} V(K, z) &= \max_{C, L} \left\{ u(C, L) + \beta E[V(K', z')|z] \right\} \\ \text{s.t. } K' &= F(z, K, L) + (1 - \delta)K - c \\ z' &= g(z, \epsilon) \end{aligned} \quad (1)$$

- The social planner's allocation is identical to that from the competitive equilibrium.
- By definition, the planner's solution is Pareto efficient.
- One can set  $w = F_L(K, K, z)$  and  $r = F_K(F, L, z) - \delta$  to construct a competitive equilibrium from the social planner's allocation.

# Calibrated Characteristic Equations (Planner)

$$\frac{1}{C} = \beta E \left[ \frac{1}{C'} \left( 1 - \delta + \alpha z \left( \frac{K}{L} \right)^{\alpha-1} \right) \right]$$

$$\frac{AC}{1-L} = (1-\alpha)z \left( \frac{K}{L} \right)^{\alpha}$$

$$K' = zK^{\alpha}L^{1-\alpha} + (1-\delta)K - C$$

$$\log z' = \rho \log z + \epsilon', \quad \epsilon \sim N(0, \sigma_{\epsilon}^2)$$

# Preamble (Planner economy)

```
// preamble: declare variables and parameters

var prod cons invst cap labor irate wage z;
varexo eps;
parameters bta delta alpha A rho sigeps;

// set parameter values

bta = 0.99;
delta = 0.025;
alpha = 0.36;
A = 1.723;
rho = 0.95;
sigeps = 0.007;
```

# Model (planner economy)

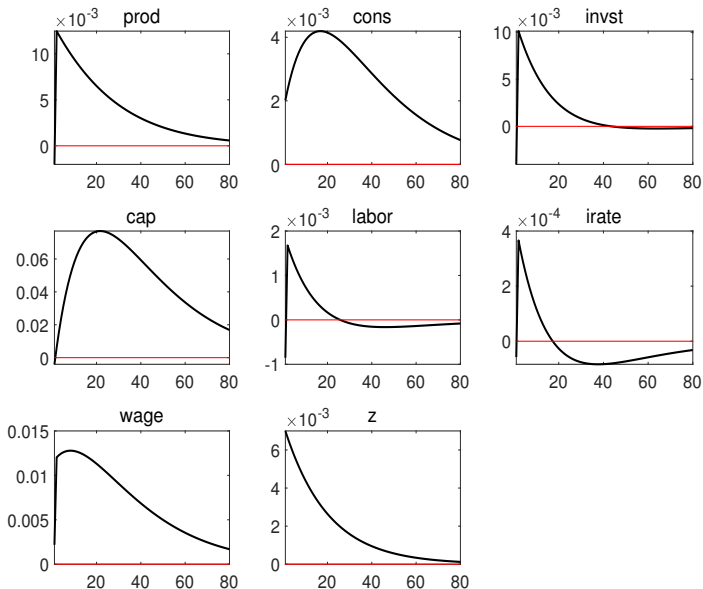
```
// specify model equations

model;
1/cons = bta * 1/cons(+1) * (1 + irate(+1));
A*cons/(1-labor) = wage;
prod = z(-1) * cap(-1)^alpha * labor^(1-alpha);
cap = prod + (1-delta)*cap(-1) - cons;
invst = cap - (1-delta)*cap(-1);
log(z) = rho*log(z(-1)) + eps;
irate = alpha * z(-1) * (cap(-1)/labor)^(alpha-1) - delta;
wage = (1-alpha) * z(-1) * (cap(-1)/labor)^alpha;
end;
```

# Dynare Results: planner economy

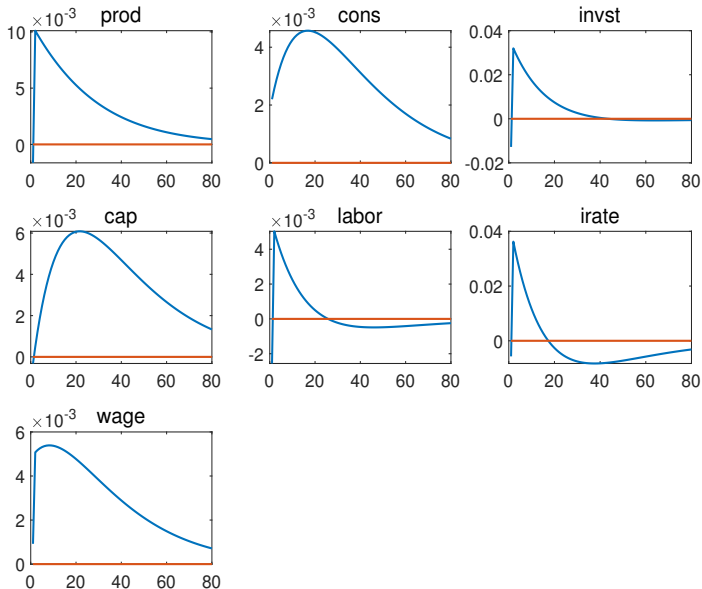
See Matlab Outputs

# Impulse Responses (planner economy)





# Imp. Resp. in $\% \Delta$ from S.S. (planner economy)



# Log-Linearized Characteristic Equations

$$0 = E \left[ \hat{c}_t - \hat{c}_{t+1} + \frac{\bar{r}}{1 + \bar{r}} \hat{r}_{t+1} \right]$$

$$\hat{h}_t = \frac{1 - \bar{h}}{\bar{h}} (\hat{w}_t - \hat{c}_t)$$

$$\hat{c}_t = \phi_a (\hat{r}_t + \hat{a}_t) + (1 - \phi_a) (\hat{w}_t + \hat{h}_t) + \left( \frac{1}{\bar{r}} \right) \phi_a (\hat{a}_t - \hat{a}_{t+1})$$

$$\hat{r}_t = \left( \frac{\bar{r} + \delta}{\bar{r}} \right) \left( \hat{z}_t + (\alpha - 1) (\hat{K}_t - \hat{L}_t) \right)$$

$$\hat{w}_t = \hat{z}_t + \alpha (\hat{K}_t - \hat{L}_t)$$

$$\hat{z}_{t+1} = \rho \hat{z}_t + \epsilon_{t+1}$$

$$\hat{a}_t = \hat{K}_t, \quad \hat{h}_t = \hat{L}_t$$

# Preamble Block (log deviation variables)

```
// preamble: declare variables and parameters

var prod cons invst cap labor irate wage asst hour z;
varexo eps;
parameters bta delta alpha A rho sigeps phi_a;
parameters prod_bar cons_bar invst_bar cap_bar labor_bar irate_bar hour_bar;

// set parameter values

bta = 0.99;
delta = 0.025;
alpha = 0.36;
A = 1.723;
rho = 0.95;
sigeps = 0.007;
```

# Preamble Block (log deviation variables)

```
// steady state values

labor_bar = 0.33;
hour_bar = labor_bar;
irate_bar = 1/bta - 1;
k_bar = (alpha/(irate_bar+delta))^(1/(1-alpha));
cap_bar = k_bar*labor_bar;
prod_bar = k_bar^alpha*labor_bar;
invst_bar = delta*cap_bar;
cons_bar = prod_bar - invst_bar;
phi_a = irate_bar*cap_bar/cons_bar;
```

# Model Block (log deviation variables)

```
// specify model equations

model;
0 = cons - cons(+1) + irate_bar/(1+irate_bar) * irate(+1);
hour = (1-hour_bar)/hour_bar * (wage - cons);
cons = phi_a*(irate + asst(-1)) + (1-phi_a)*(wage+hour)
      + (1/irate_bar)*phi_a*(asst(-1) - asst);
irate = (irate_bar+delta)/irate_bar * (z(-1)
      + (alpha-1)*(cap - labor));
wage = z(-1) + alpha*(cap - labor);
cap = asst(-1);
labor = hour;
z = rho*z(-1) + eps;
prod = z(-1) + alpha*cap + (1-alpha)*labor;
invst_bar*invst = prod_bar*prod - cons_bar*cons;
end;
```

# Steady State Block (log deviation variables)

```
// set initial values of endogenous variables

initval;
prod = 0.0;
cons = 0.0;
invst = 0.0;
cap = 0.0;
labor = 0.0;
irate = 0.01;
wage = 0.0;
asst = 0.0;
hour = 0.0;
z = 0;
end;

// compute steady state

steady;
```

```
// specify shocks

shocks;
var eps = sigeps^2;
end;

// compute solution

stoch_simul(hp_filter=1600, periods=40000, drop = 1000, irf = 80);
//stoch_simul(hp_filter=1600);
```

# Dynare Results: Log-linearized economy

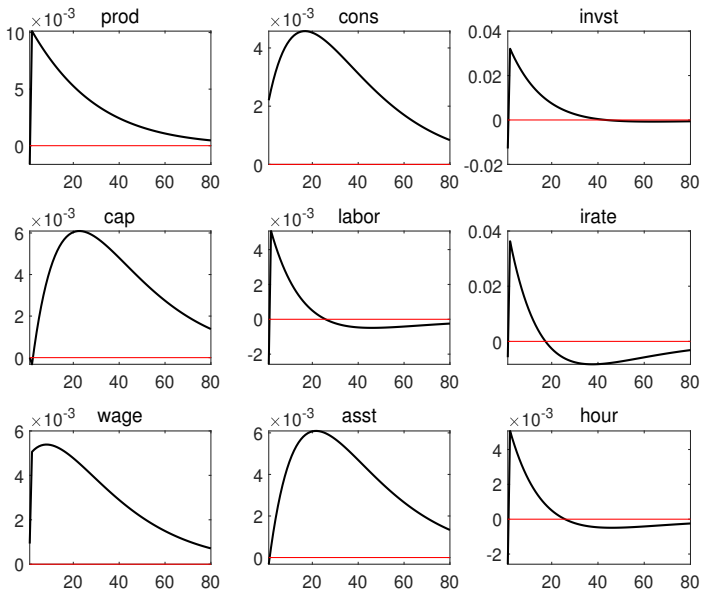
- Dynare computes and simulates
  - steady state values
  - coefficients of the system of log-linearized equations as functions of state variables and a shock.
  - theoretical or simulated moments
    - standard deviations
    - cross-correlations
    - autocorrelations
  - time-series of variables with random shocks
  - impulse responses functions



# Dynare Results: Log-linearized economy

See Matlab Outputs

# Impulse Responses (log-linearized system)



# A Variation: CRRA Utility

- The preferences of the worker/consumer has changed as follows:

$$\max_{\{c_t, l_t\}_{t=0}^{\infty}} E_0 \sum_{t=0}^{\infty} \beta^t \left\{ \frac{c_t^{1-\sigma} - 1}{1-\sigma} - B \frac{h_t^{1+1/\gamma} - 1}{1+1/\gamma} \right\},$$

- All other elements (production technology, productivity shock process and etc.) are the same as those in the standard DSGE model.

# A Variation: CRRA Utility

- Write down the characteristic equations and log-linearize them around the steady state.
- Write the Dynare codes to simulate the equilibrium with level variables.
- Write the Dynare codes to simulate the equilibrium with log-deviation variables.

# Dynare: Deterministic Model

Dynare can solve for the deterministic model to simulate the effects of

- (Un)anticipated changes in productivity
- (Un)anticipated shifts in parameters, which can be interpreted as changes in policies.

# Preamble Block (Deterministic Model)

```
// preamble: declare variables and parameters

var prod cons invst cap labor irate wage asst hour;
varexo z;
parameters bta delta alpha A;

// set parameter values

bta = 0.99;
delta = 0.025;
alpha = 0.36;
A = 1.723;
```

# Model Block (Deterministic Model)

```
// specify model equations

model;
1/cons = bta * 1/cons(+1) * (1 + irate(+1));
A*cons/(1-hour) = wage;
asst = wage*hour + (1+irate)*asst(-1) - cons;
cap = asst(-1);
labor = hour;
irate = alpha * z(-1) * (cap/labor)^(alpha-1) - delta;
wage = (1-alpha) * z(-1) * (cap/labor)^alpha;
prod = z(-1) * cap^alpha * labor^(1-alpha);
invst = prod - cons;
end;
```

# Steady State Block (Deterministic Model)

```
// set initial values of endogenous variables
// and compute steady state

initval;
prod = 1.2;
cons = 0.9;
invst = 0.3;
cap = 12;
labor = 0.33;
irate = 0.01;
wage = 2.4;
asst = 12;
hour = 0.33;
z = 1;
end;
steady;
```



# Temporary Technology Shocks (Deterministic Model)

```
// specify deterministic shocks

shocks;

var z;
periods 1:8;
values 0;

end;
```

# Permanent Technology Shocks (Deterministic Model)

```
// set a permanent technology shock and compute the corresponding
// steady state regarded as the terminal values of endog. variables

endval;
prod = 1.2;
cons = 0.9;
invst = 0.3;
cap = 12;
labor = 0.33;
irate = 0.01;
wage = 2.4;
asst = 12;
hour = 0.33;
z = 1.1;
end;
steady;
```

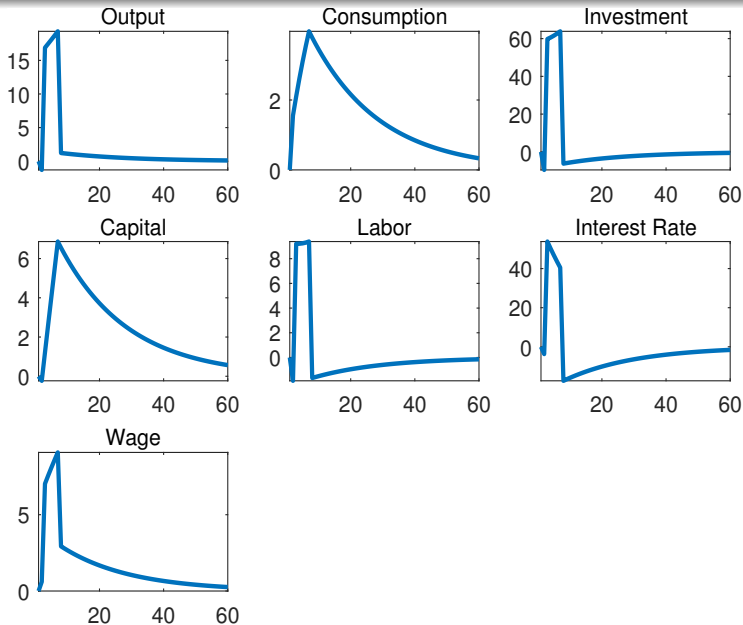
# Computation (Deterministic Model)

```
// compute solution  
  
simul(periods=2000);
```

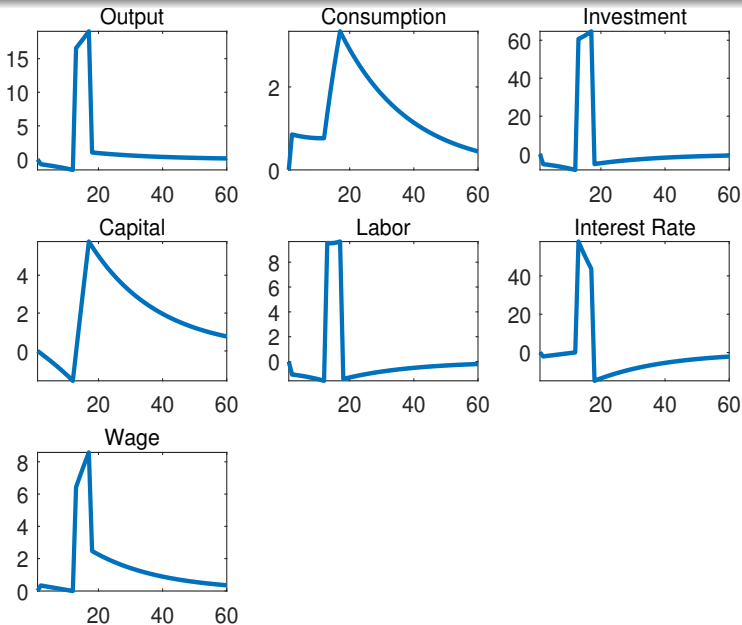
# Dynare Results for a Deterministic Model

- Computes the steady state of endogenous variables
- Simulates the transitions of endogenous variables to
  - a temporary technology shock
  - an anticipated temporary technology shock
  - a permanent technology shock
  - an anticipated permanent technology shock

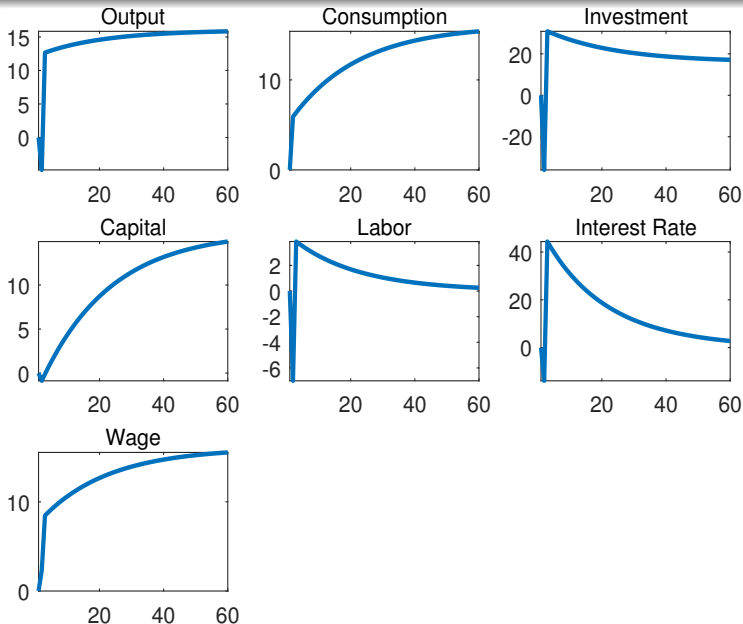
# An Unanticipated Temporary Technology Shock



# An Anticipated Temporary Technology Shock



# An Unanticipated Permanent Technology Shock



# An Anticipated Permanent Technology Shock

