

# YOLOv11n-Segmentation Model

It focuses on detecting **blue color changes (dots)** within a **pink patch** using **YOLOv11n-seg** for instance segmentation. The objective is to localize blue dot-like irregularities inside circular pink regions, useful for real-time monitoring of chemical changes or reactions on paper.

## Dataset Details

### Manual Dataset Preparation

- **Pink Paper:** Circular patches were manually cut from pink-coloured paper.
- **Dot Creation:** Blue watercolour droplets were placed within the pink circles, resulting in **irregular-shaped blue marks**.
- **Photography Setup:** Images were captured on a **plain background under varying lighting conditions** to ensure **diversity and robustness** in the dataset. This helps the model generalize better across different real-world scenarios.

### Annotation

- **Tool Used:** Roboflow
- **Project Type:** Instance Segmentation
- **Annotation Method:** Smart Polygon Tool (per-pixel blue dot region inside pink patch)
- **Dataset Split**

Set	Count	Percentage
Train Set	159	88%
Valid Set	15	8%
Test Set	7	4%

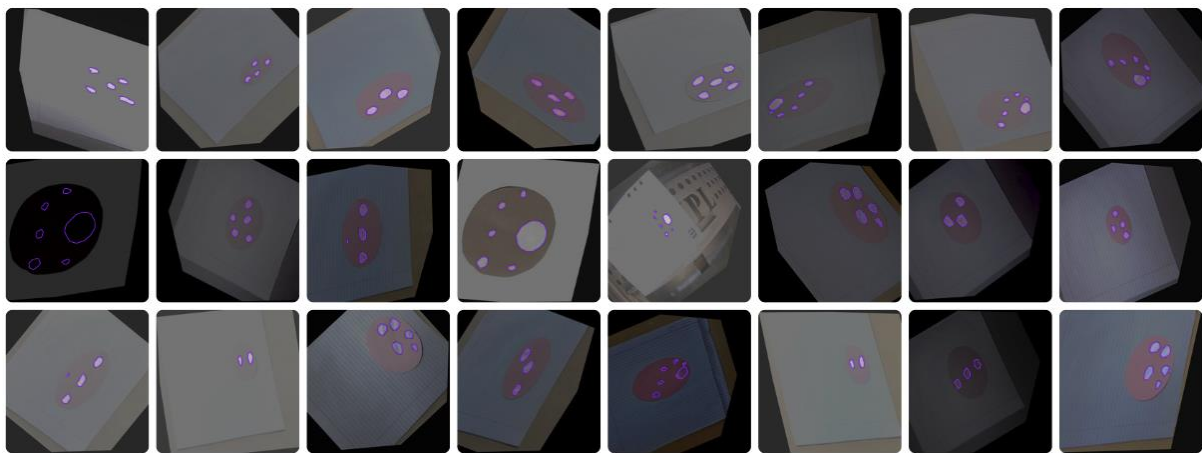
**Preprocessing:** The preprocessing steps included Auto-Orient, which was successfully applied, and Resize, where all images were stretched to 640×640 pixels, preserving non-uniform aspect ratios.

### Augmentations

Each training image generates **3 outputs** via augmentation:

Augmentation Type	Range
Rotation	$\pm 45^\circ$
Shear	$\pm 13^\circ$ Horizontal, $\pm 14^\circ$ Vertical
Saturation	-55% to +55%
Brightness	-36% to +36%
Exposure	-27% to +27%

These augmentations ensure the model learns to generalize across various lighting, orientation, and color shift conditions.



**Model & Training Setup**

**Command Used:** `yolo segment train data=data.yaml model=yolo11n-seg.yaml pretrained=yolo11n-seg.pt epochs=100 imgsz=1024 batch=32`

**Configuration**

Setting	Value
Model	yolo11n-seg.yaml (2.84M params)
Pretrained	yolo11n-seg.pt
Epochs	100
Image Size	1024
Batch Size	32
Device	GPU (CUDA)
Augmentations Enabled	

**Training Results Summary**

Metric	Value
Box mAP@0.5	0.985
Segmentation mAP@0.5	0.971
Segmentation mAP@0.5:0.95	0.712

- Loss steadily decreased.
- Accuracy peaked in last 10 epochs.
- Best model saved as runs/segment/train/weights/best.pt.

**Final Outputs**

Output File / Folder	Description
train_batch*.jpg	Sample predictions during training
results.csv	Epoch-wise logs
confusion_matrix.png, F1_curve.png, PR_curve.png	Evaluation metrics
best.pt / last.pt	Trained weights

## MODEL INFERENCE

The **MAIN.py** Python script utilizes a **YOLOv11 segmentation model** to detect **blue dots** inside pink paper regions in both **images and videos**. It supports dynamic annotation visualization and saves the output with detected masks.

### Features

- Accepts both **image** and **video** file inputs.
- Supports **YOLOv11 segmentation** format with `retina_masks=True` for fine-grained instance masks.
- Automatically saves **annotated output** images or videos.
- Displays real-time detection results during video processing.

### Dependencies

- ultralytics (YOLOv11)
- OpenCV (cv2)
- os for path and file checks

### Working Mechanism

#### 1. Model Loading:

Loads the pretrained YOLOv11n segmentation model from: **train/weights/best.pt**

#### 2. Image Processing:

- Performs inference.
- Applies **segmentation masks** (without bounding boxes).
- Saves and displays the annotated output image.

#### 3. Video Processing:

- Reads video frame-by-frame.
- Runs YOLOv11 segmentation on each frame.
- Applies mask overlays and writes annotated frames to an output .avi file.
- Allows early exit with the 'q' key.

### Example Output

- output\_detected.jpg — for image input
- output\_detected.avi — for video input