



Introduction to the V-REP robot simulator

Exercise #1 (14:15-16:00, 27/Feb/2018) in CAB G11

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- Introduction of V-REP scene
 - Model browser
 - Scene hierarchy (Lua child script)
- MATLAB remote APIs
 - Obtaining robot pose and sensor measurements and sending control inputs.
- Material can be found from http://www.asl.ethz.ch/education/lectures/autonomous_mobile_robots/spring-2018.html
- You can build your own algorithms based on this.

V-REP scene

