```matlab
%Assess Centroid Data
addpath('data');
filename = 'data/centroidData_1hz_60sec_ambient_vacuum.xlsx';
mu_budget_urad = 0.31; %urad
sigma_budget_urad = 16.4; %urad
f_ir_mm = 125; %ir camera focal length
w_pxl_ir_mm = 12.5e-3; %ir camera pixel pitch

data = xlsread(filename);
tx_a = data(:,1);
tx_sigma = data(:,2);
tx_x = data(:,3);
tx_y = data(:,4);
tx_res = data(:,5);
bcn_a = data(:,6);
bcn_sigma = data(:,7);
bcn_x = data(:,8);
bcn_y = data(:,9);
bcn_res = data(:,10);

err_x_pxl = tx_x - bcn_x;
err_y_pxl = tx_y - bcn_y;
err_x_urad = err_x_pxl*w_pxl_ir_mm/f_ir_mm*1e6;
err_y_urad = err_y_pxl*w_pxl_ir_mm/f_ir_mm*1e6;

figure;
subplot(2,1,1);
plot(1:length(err_x_pxl), err_x_pxl);
ylabel('X Err (pixels)');
subplot(2,1,2);
plot(1:length(err_y_pxl), err_y_pxl);
ylabel('Y Err (pixels)');
xlabel('Data Point Number');
figure;
subplot(1,2,1);
histogram(err_x_urad);
xlabel('X Err (urad)');
subplot(1,2,2);
histogram(err_y_urad);
xlabel('Y Err (urad)');

err_x_mean = mean(err_x_urad);
err_x_std = std(err_x_urad);
err_y_mean = mean(err_y_urad);
err_y_std = std(err_y_urad);
disp(['Ptg Budget CBE - Err Stats (urad): mu_max
 = ', num2str(mu_budget_urad), ', sigma_max = ',
 num2str(sigma_budget_urad)]);
disp(['PAT Test - X Err Stats (urad): mu_x = ',
 num2str(err_x_mean), ', sigma_x = ', num2str(err_x_std)]);
disp(['PAT Test - Y Err Stats (urad): mu_y = ',
 num2str(err_y_mean), ', sigma_y = ', num2str(err_y_std)]);
```
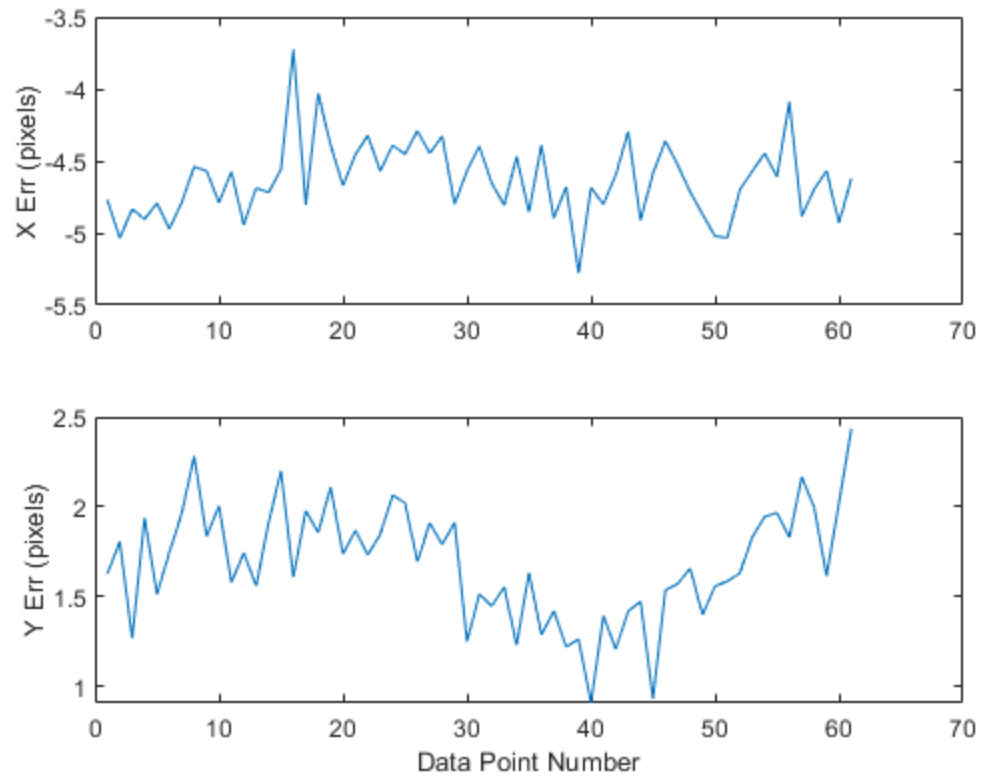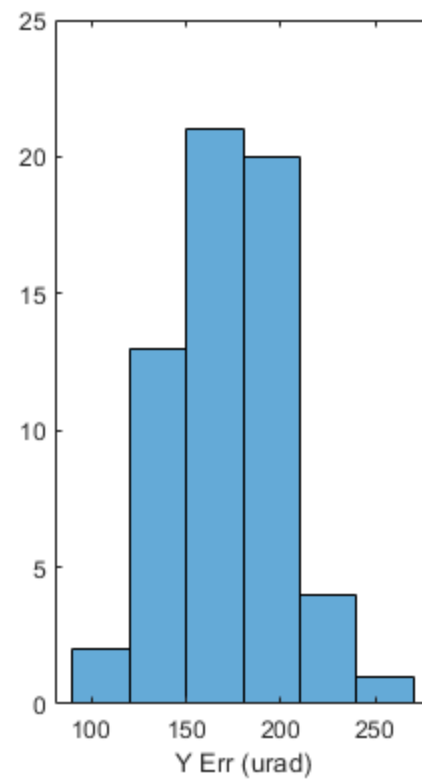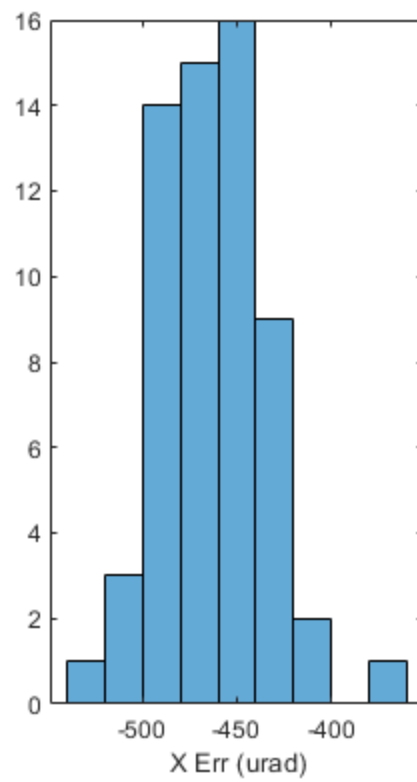
*Ptg Budget CBE - Err Stats (urad): mu_max = 0.31, sigma_max = 16.4*
*PAT Test - X Err Stats (urad): mu_x = -463.3993, sigma_x = 26.719*
*PAT Test - Y Err Stats (urad): mu_y = 168.8938, sigma_y = 31.6027*

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