

# Microgrid Controller Hardware-in-the-Loop Demonstration Platform

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**Homeland  
Security**

Science and Technology



**MIT Lincoln Laboratory**



U.S. DEPARTMENT OF  
**ENERGY**

Electricity Delivery  
& Energy Reliability

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# How Do We Accelerate Microgrid Deployment?

## Reduce Integration Time, Cost, & Risk



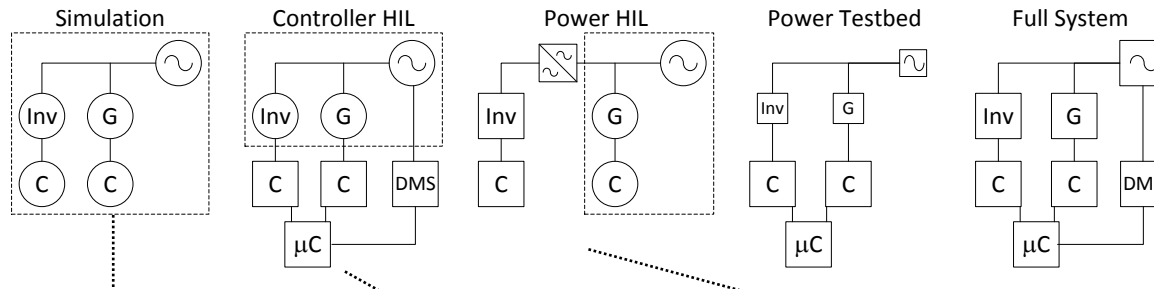
- **High NRE for each project**
  - One vendor's microgrid controller quote: \$1M starting price
- **“Vaporware”**
  - No standard list of functions or performance criteria
  - Difficult to validate marketing claims
- **Risk of damage to expensive equipment**
  - One utility-deployed microgrid: 1 year of controls testing, damaged a 750 kW transformer, required significant engineering staff support
- **Interconnection behavior unknowable to utility engineers**
  - Controls are implemented in proprietary software
  - Microgrids are a system of systems: Exhibit emergent behavior
- **No standards verification**
  - IEEE P2030.7 and P2030.8 standards are on the horizon



# Microgrid Controller Hardware-in-the-Loop (HIL) Testbed



## Types of Controller Testbeds



### Legend

- G generator
- Inv battery or solar inverter
- C device controller
- μC microgrid controller
- DMS distribution management system controller
- power grid
- high-bandwidth AC-AC converter
- simulation or emulation boundary
- hardware
- virtual (simulated or emulated)

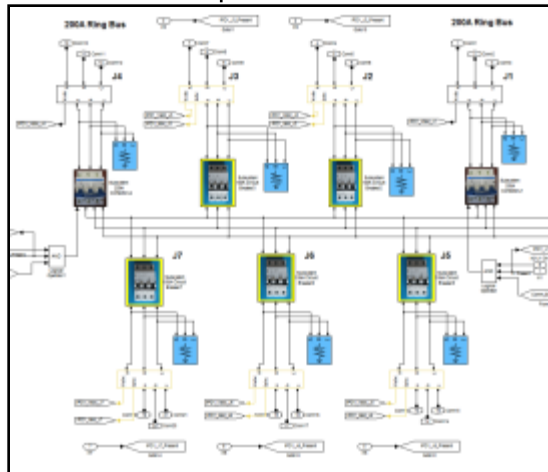


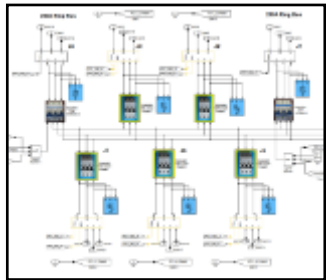
Image: Florida State Univ. CAPS



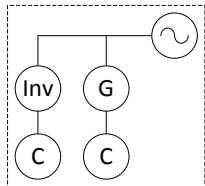
# Power Simulation: Flight Simulator Analogy



Matlab SimPowerSystems  
simulation (not real-time)



Simulation

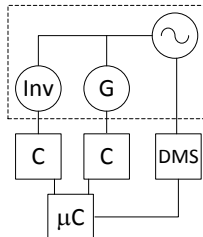


Actual device and microgrid  
controller with real-time simulation



(Microgrid controller HIL)

Controller HIL

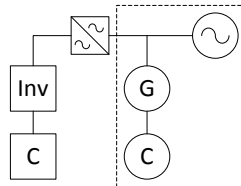


Real-time simulation coupled with  
power electronics testbed

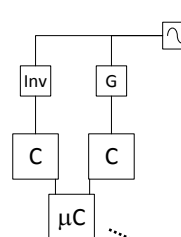


(Florida State CAPS facility)

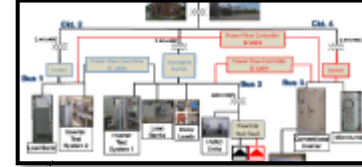
Power HIL



Power Testbed

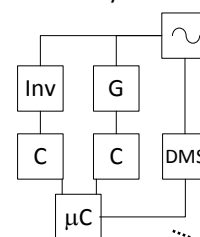


Low-power microgrid testbed



(DECC Microgrid Lab)

Full System



## Legend

- G generator
- Inv battery or solar inverter
- C device controller
- $\mu C$  microgrid controller
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Actual microgrid



(Princeton U. cogen plant)



Slow PC simulation, small  
screen, keyboard/mouse inputs



Actual plane cockpit, advanced  
simulation, wide field-of-view



Moving cockpit, field-of-view  
visualization



Trainer aircraft



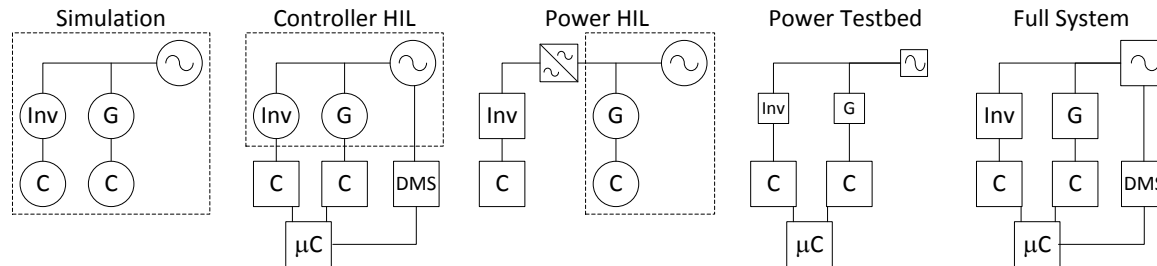
Passenger-carrying aircraft



# Microgrid Controller Hardware-in-the-Loop (HIL) Testbed



## Types of Controller Testbeds



Testbed Cost					
Test Fidelity					
Test Coverage					

### Legend

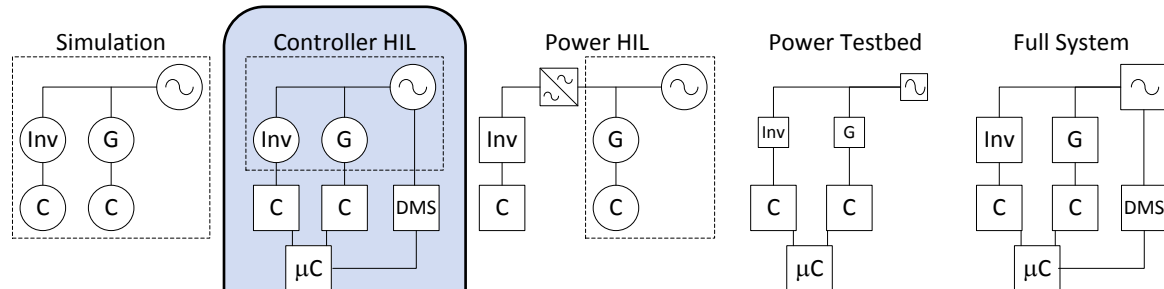
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- DMS distribution management system controller
- ~ power grid
- ~ high-bandwidth AC-AC converter
- - - simulation or emulation boundary
- hardware
- virtual (simulated or emulated)



# Microgrid Controller Hardware-in-the-Loop (HIL) Testbed



## Types of Controller Testbeds



Testbed Cost					
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### Legend

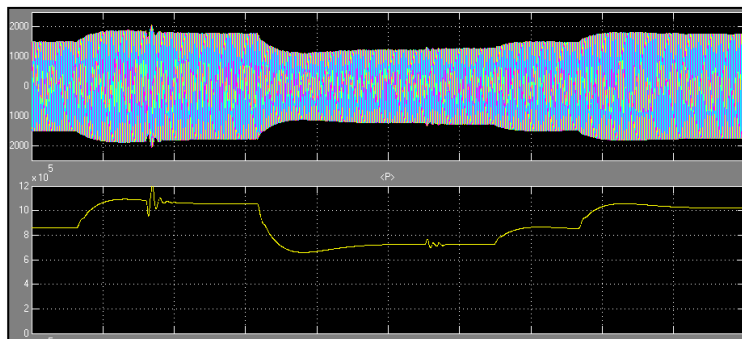
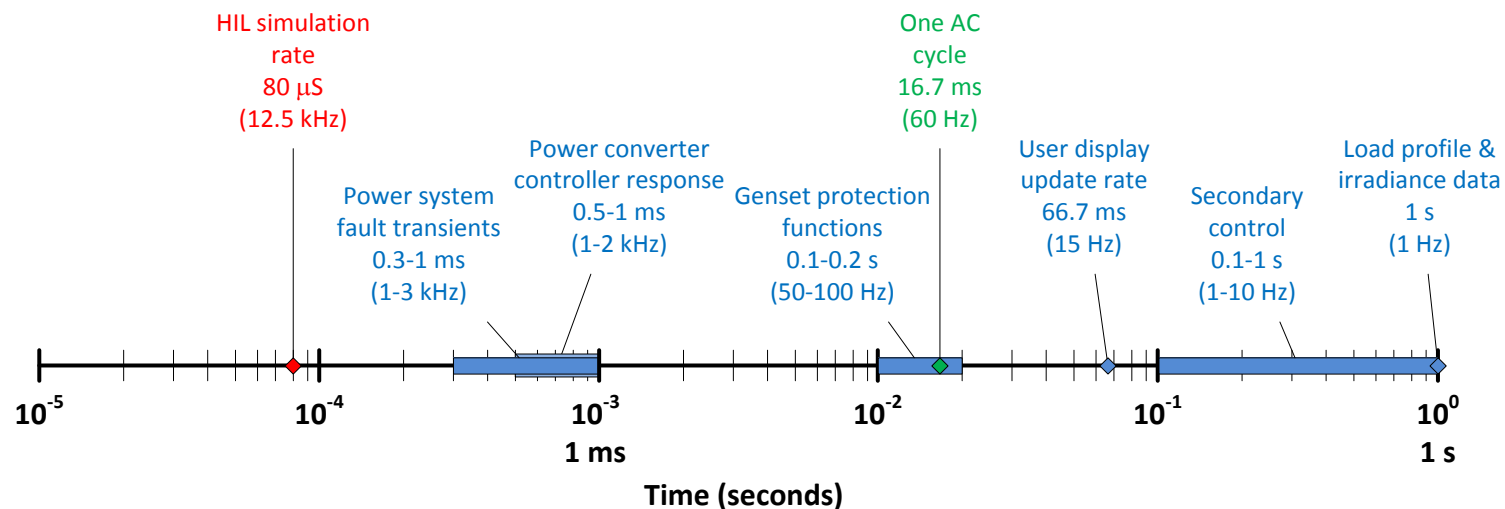
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# High-fidelity Real-time Simulation



- Microgrid controller HIL simulates in real-time at sub-cycle timescales
  - Useful for steady-state, dynamic, and transient analyses





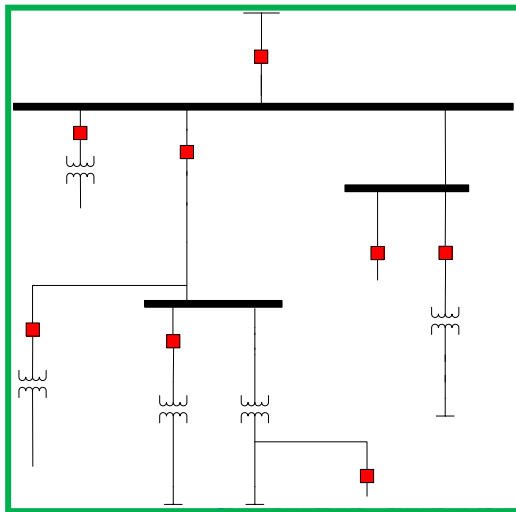


# Construction of Detailed Microgrid Test Feeder Model



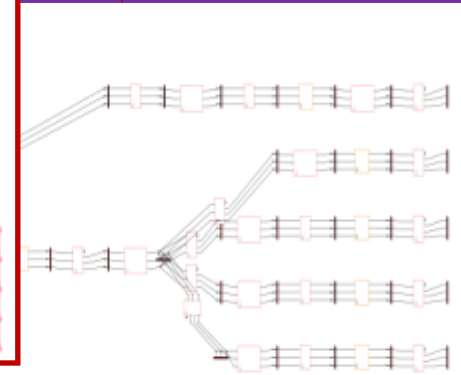
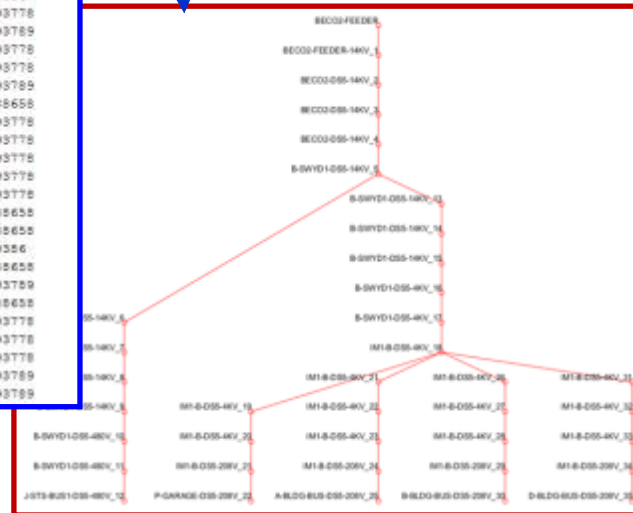
Automated  
with  
scripting

1. One-line diagram
2. Netlist
3. MATLAB data connectivity diagram
4. Simulink model



```
0.12 17.0182 0.93789
0.12 8.5091 0.93789
0.12 17.0182 0.93789
0.12 9.4629 0.9386
0.12 28.3888 0.9386
0.12 18.9259 0.9386
0.12 14.1944 0.9386
0.12 2.5942 0.88658
B 0.12 2.5942 0.88658
C 0.12 9.4629 0.9386
A 0.12 9.2344 0.93778
B 0.12 8.5091 0.93789
A 0.12 36.9375 0.93778
A 0.12 2.7703 0.93778
B 0.12 2.5527 0.93789
C 0.12 2.5942 0.88658
A 0.12 9.2344 0.93778
A 0.12 18.4688 0.93778
A 0.12 18.4688 0.93778
A 0.12 18.4688 0.93778
A 0.12 9.2344 0.93778
A 0.12 2.5942 0.88658
B 0.12 2.5942 0.88658
C 0.12 3.7852 0.9386
A 0.12 2.5942 0.88658
B 0.12 5.1055 0.93789
C 0.12 2.5942 0.88658
A 0.12 18.4688 0.93778
A 0.12 18.4688 0.93778
A 0.12 27.7032 0.93778
B 0.12 17.0182 0.93789
B 0.12 17.0182 0.93789
```

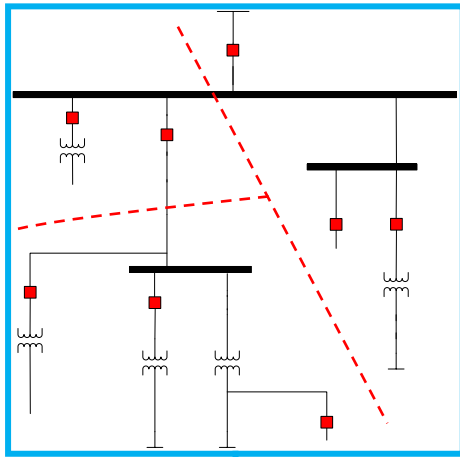
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R2-12-47-1_tn_116 R2-12-47-1_tn_25
R2-12-47-1_tn_117 R2-12-47-1_tn_26
R2-12-47-1_tn_118 R2-12-47-1_tn_27
R2-12-47-1_tn_119 R2-12-47-1_tn_28
R2-12-47-1_tn_120 R2-12-47-1_tn_29
R2-12-47-1_tn_121 R2-12-47-1_tn_30
R2-12-47-1_tn_122 R2-12-47-1_tn_31
R2-12-47-1_tn_123 R2-12-47-1_tn_32
R2-12-47-1_tn_124 R2-12-47-1_tn_33
```



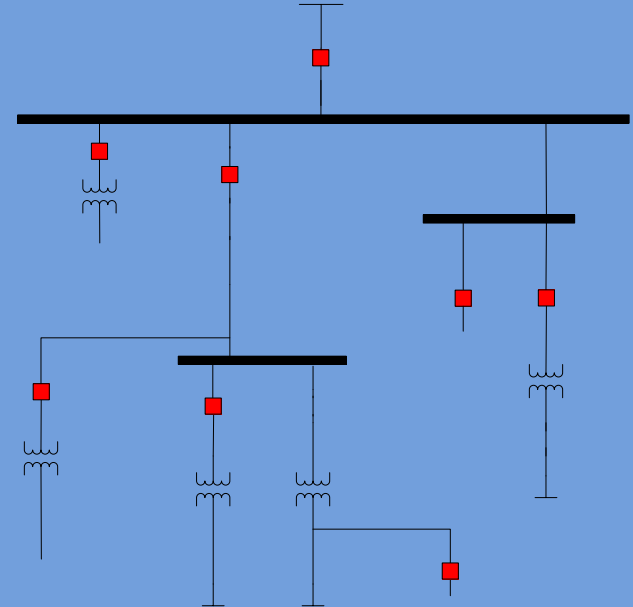




# Elements of the Microgrid Controller HIL Platform



## Hardware-in-the-Loop Simulator



Simulated Microgrid Feeder

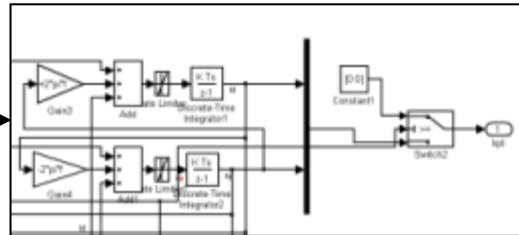
**Load the feeder model into the HIL simulator “target”**



# Elements of the Microgrid Controller HIL Platform



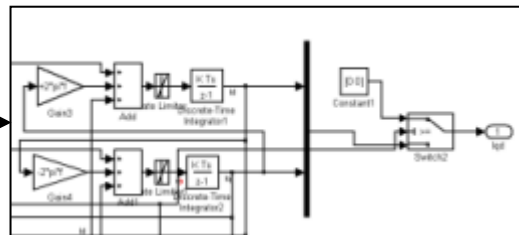
Solar Inverter



Power Electronics Model



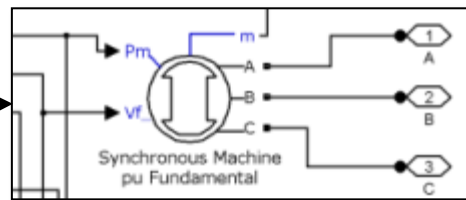
Bidirectional Power Converter



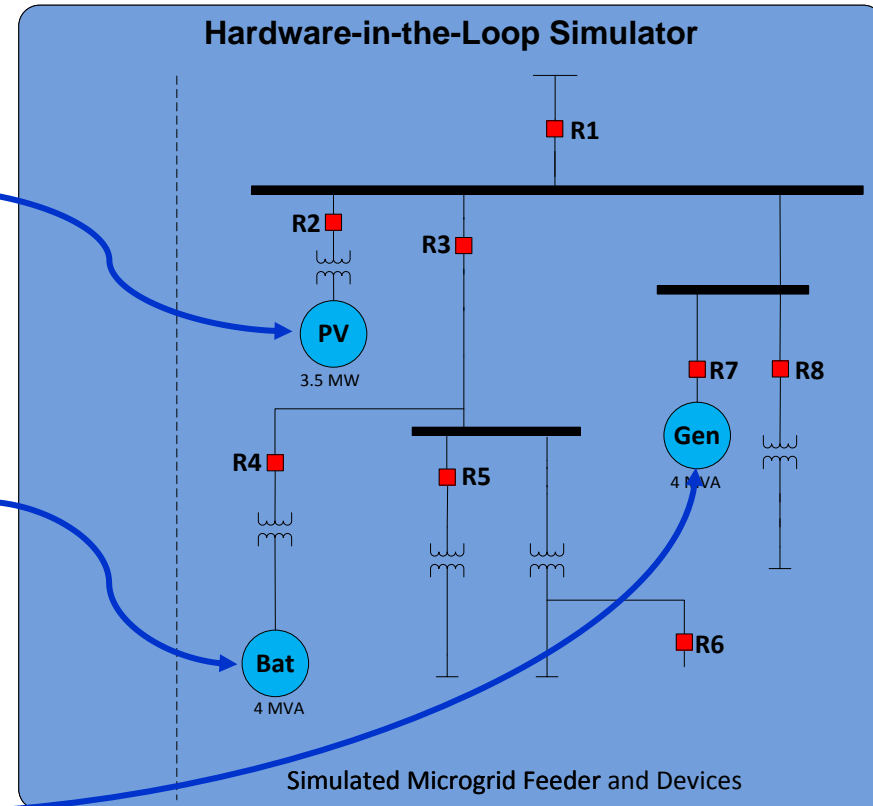
Power Electronics Model



Genset



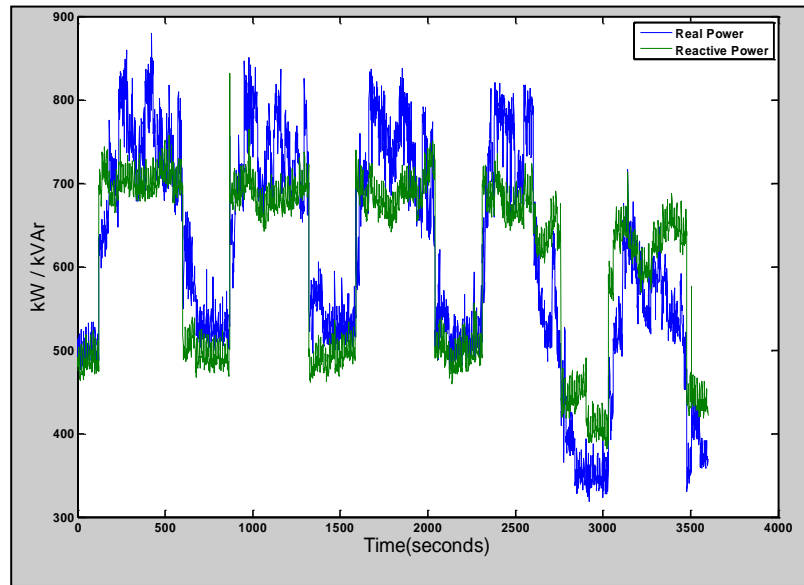
Machine Model



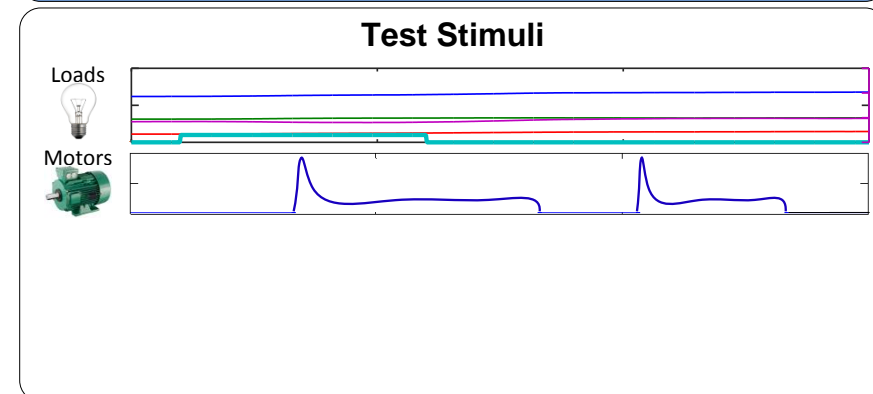
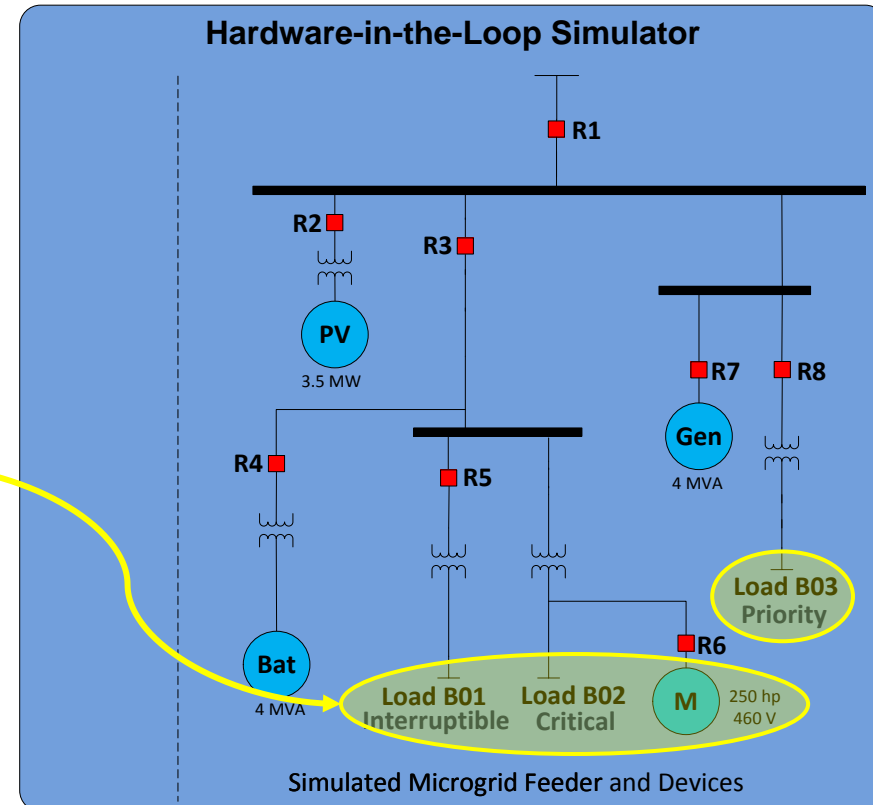
Create detailed models of the DER devices



# Elements of the Microgrid Controller HIL Platform

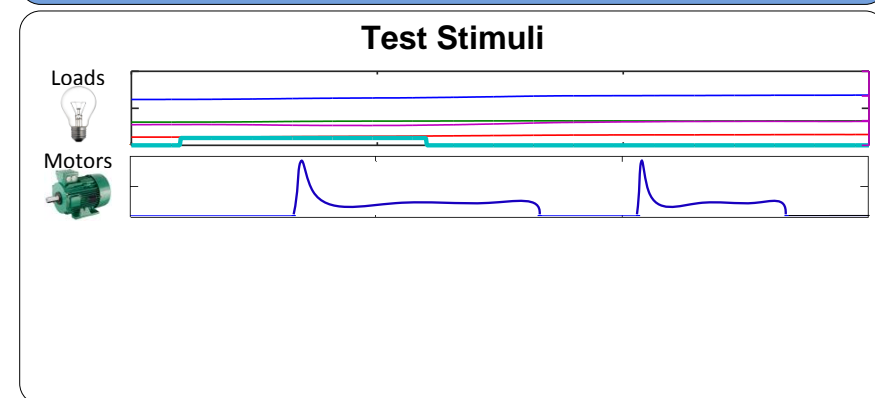
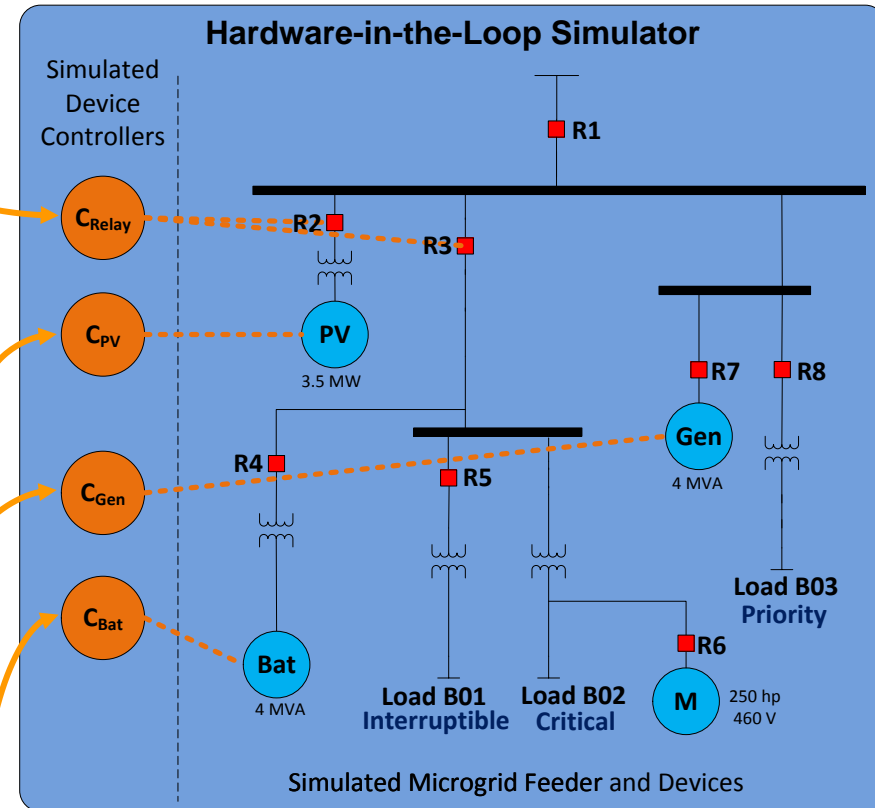
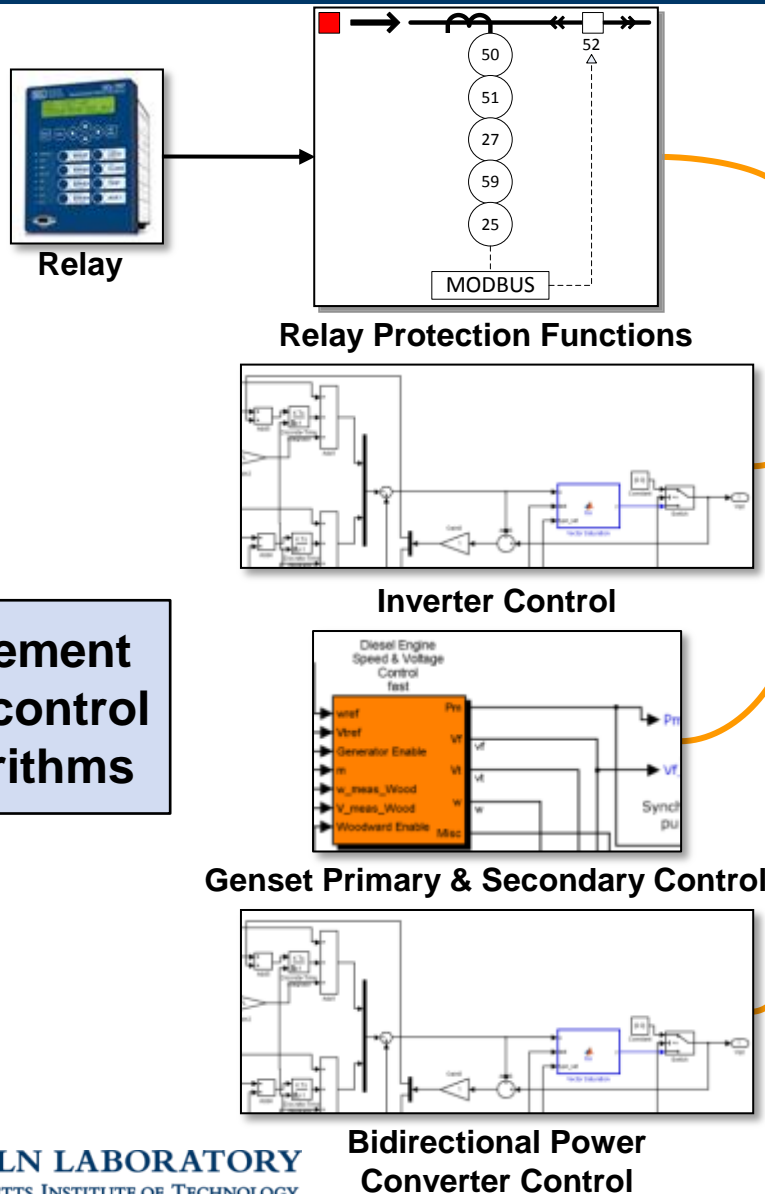


Add load profiles and assign load priorities



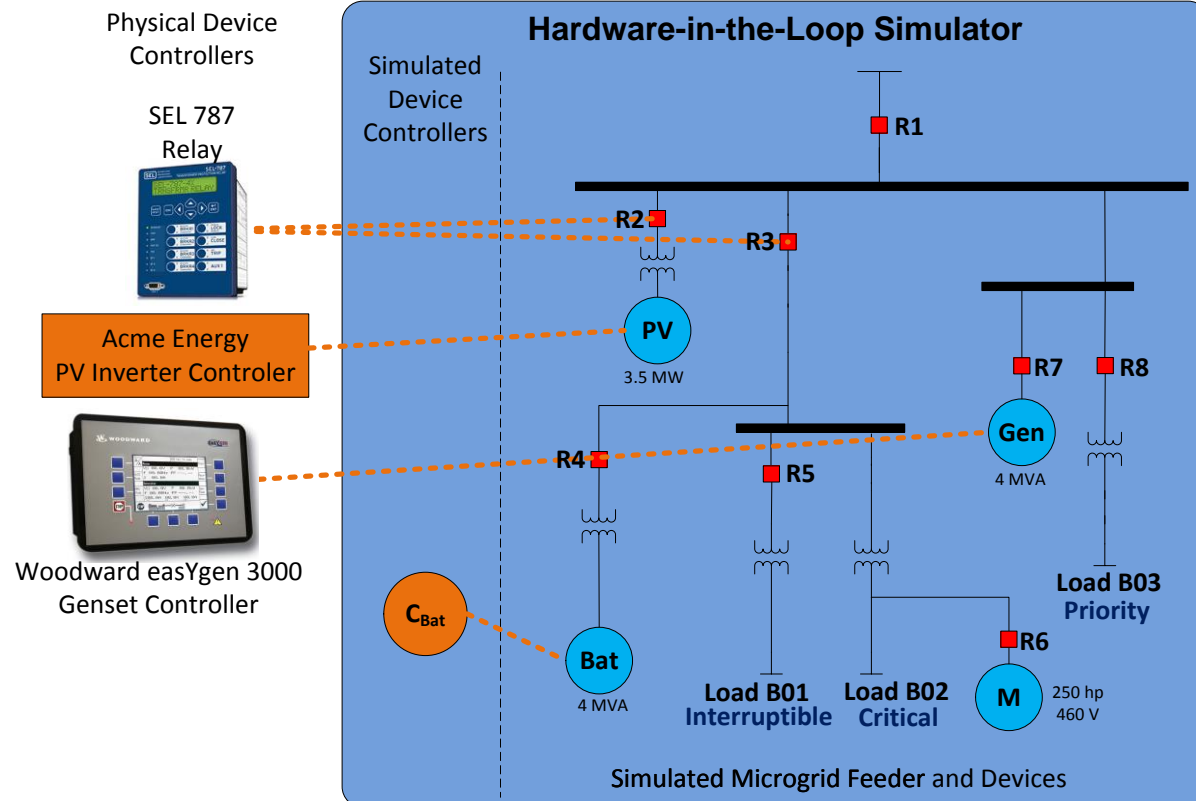


# Elements of the Microgrid Controller HIL Platform

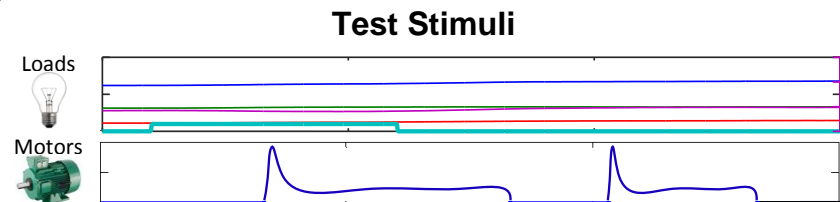




# Elements of the Microgrid Controller HIL Platform

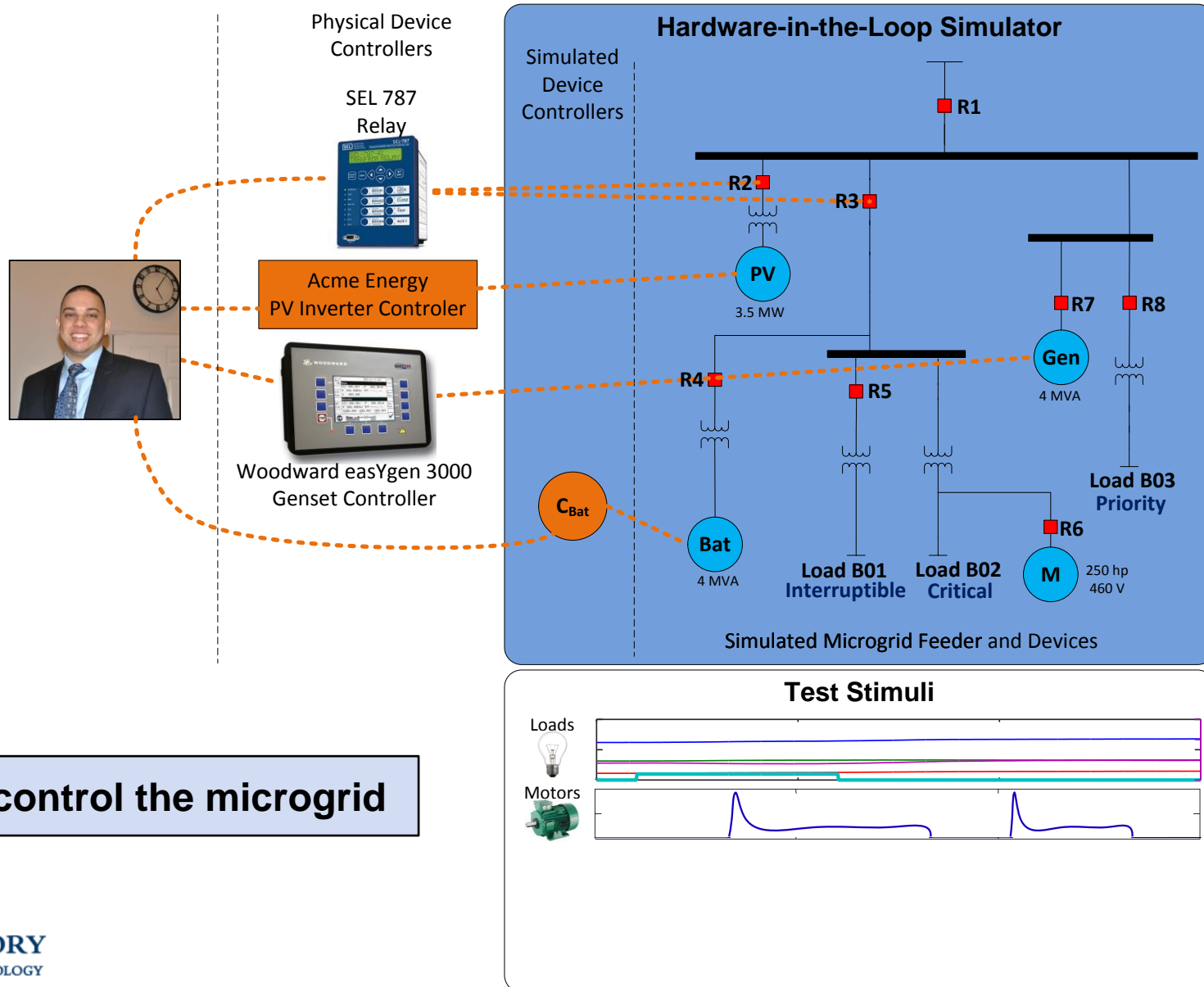


**Replace simulated device controllers with vendors' commercial device controllers**



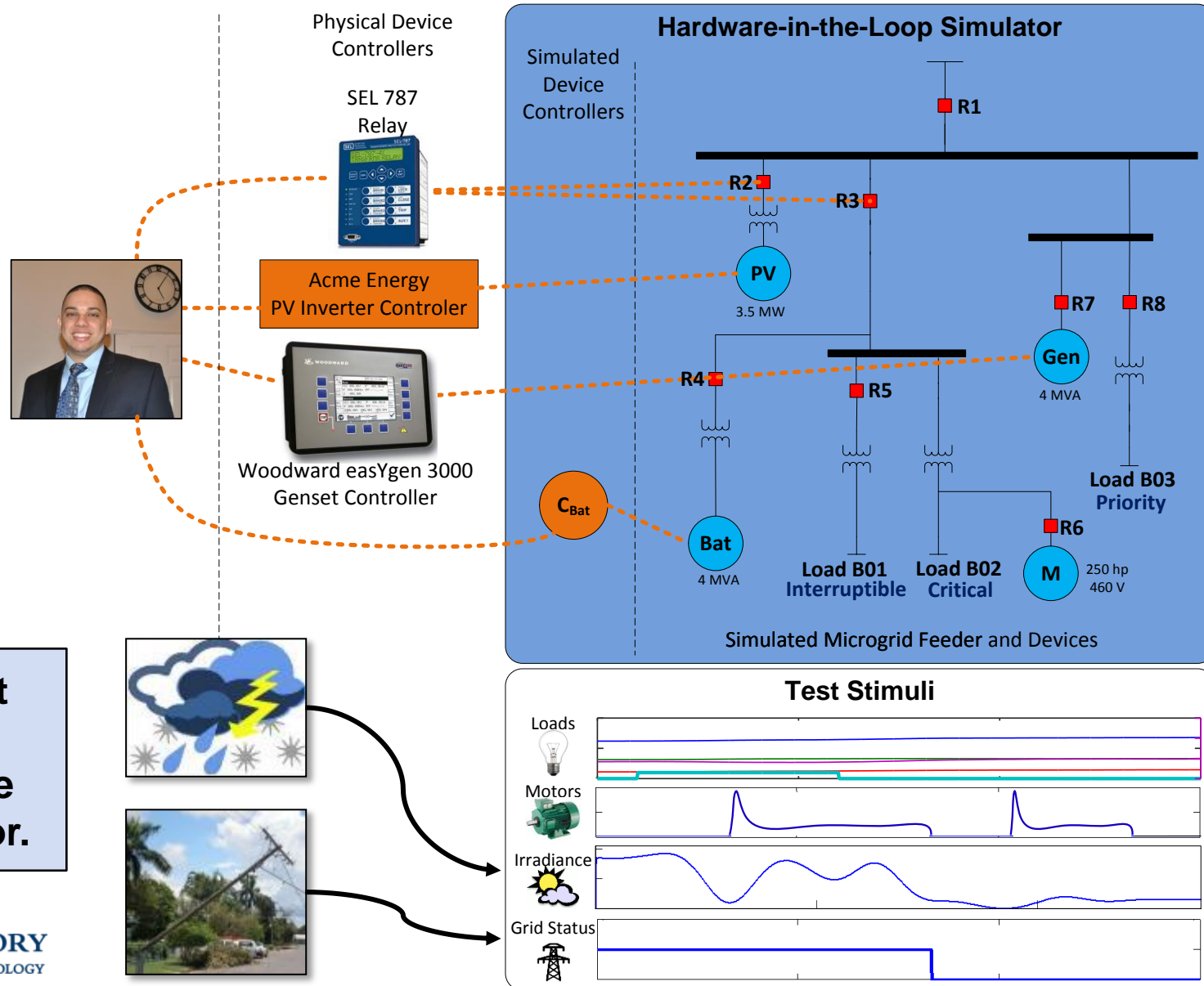


# Elements of the Microgrid Controller HIL Platform





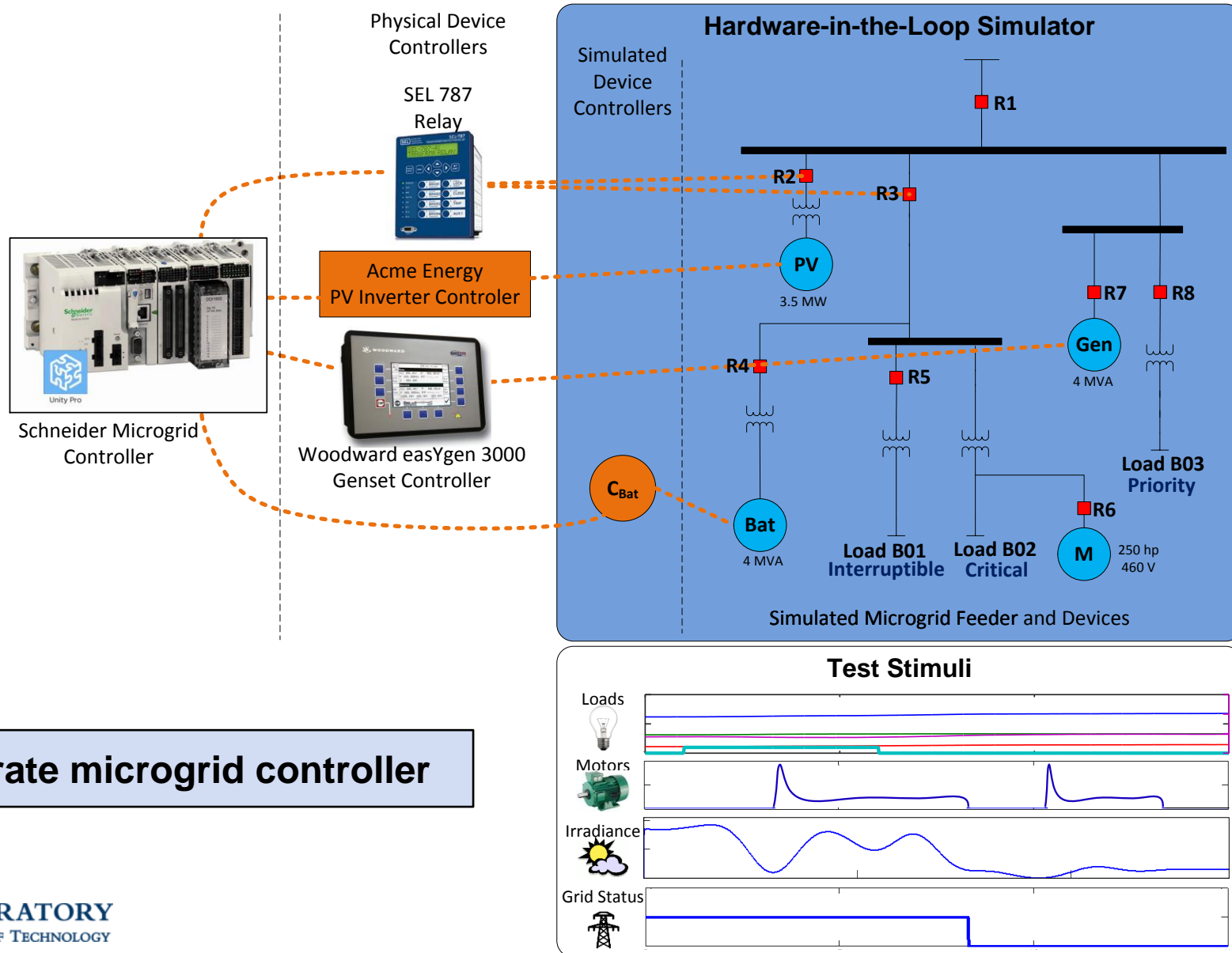
# Elements of the Microgrid Controller HIL Platform







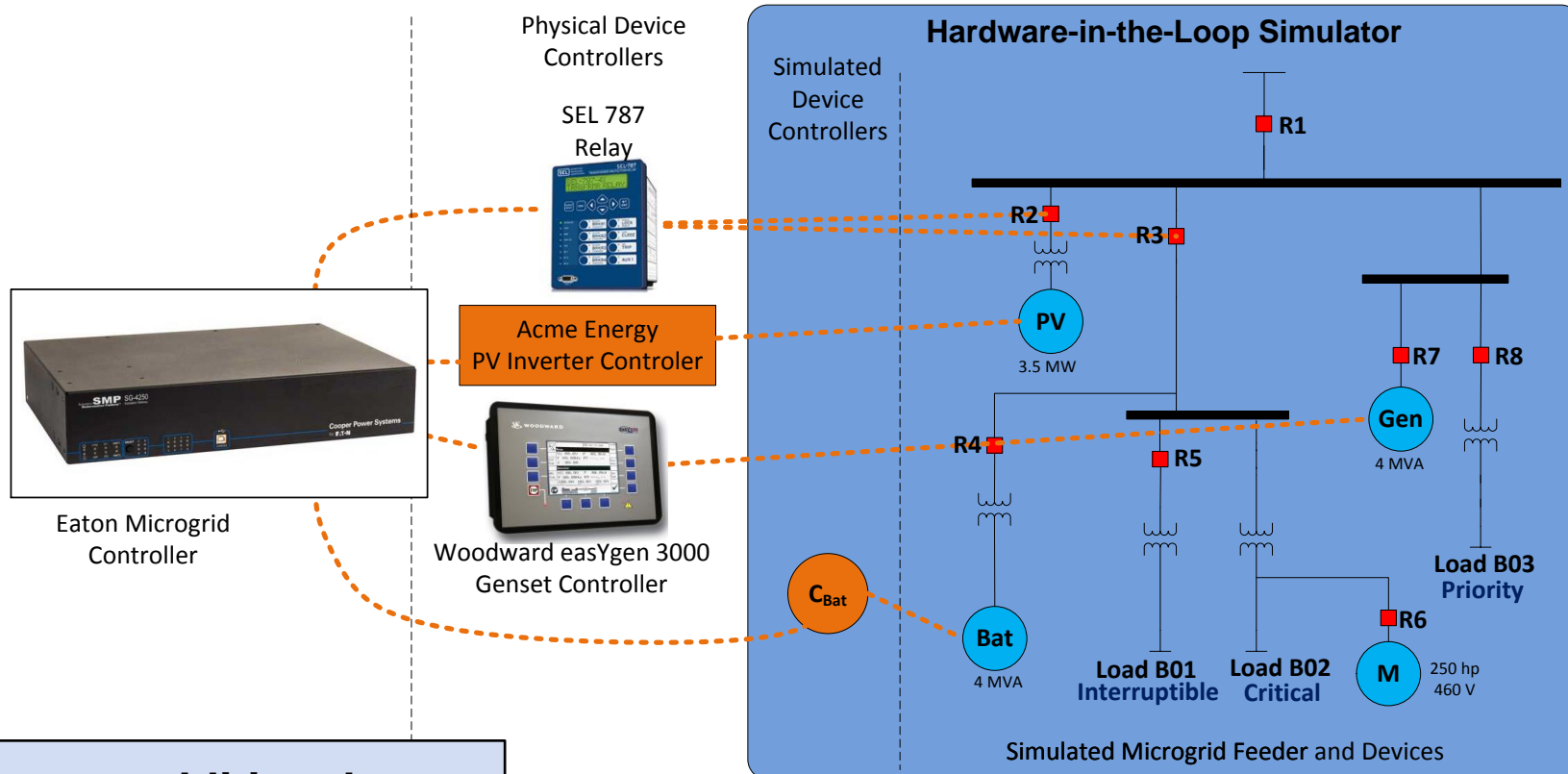
# Elements of the Microgrid Controller HIL Platform



**Integrate microgrid controller**



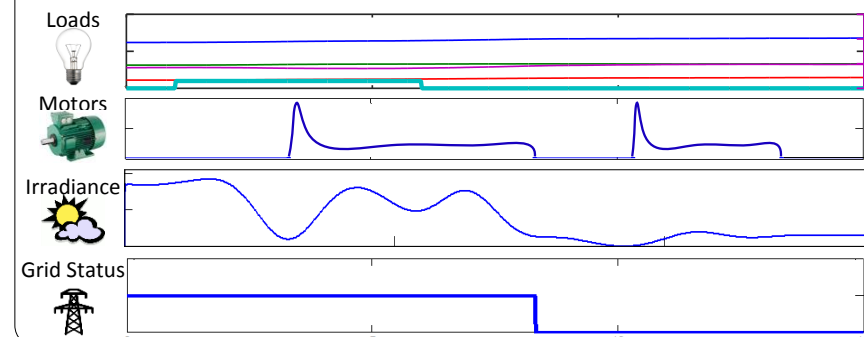
# Elements of the Microgrid Controller HIL Platform

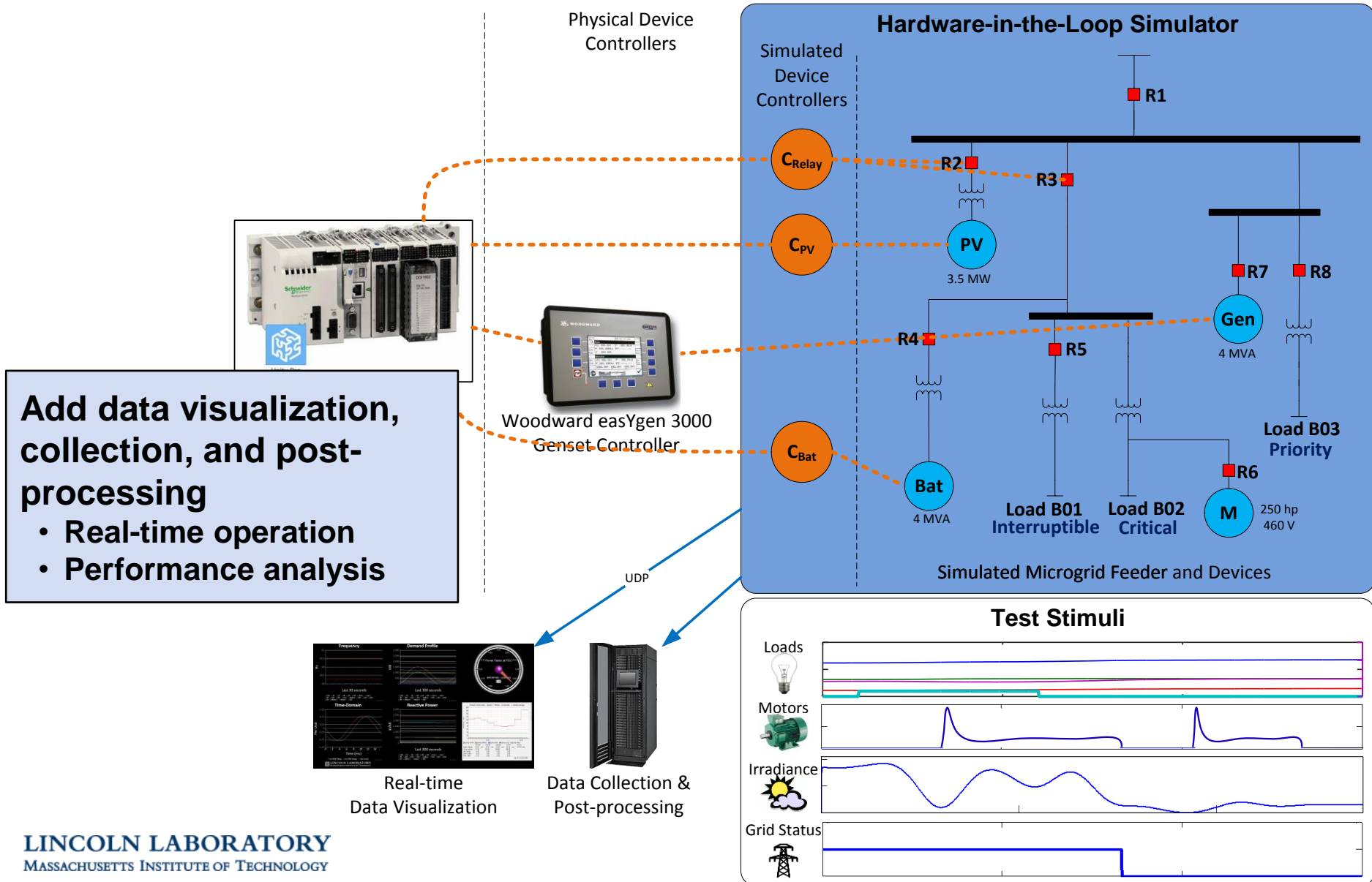


**Integrate additional microgrid controllers**

- Vendor capability demonstration
- Performance comparison

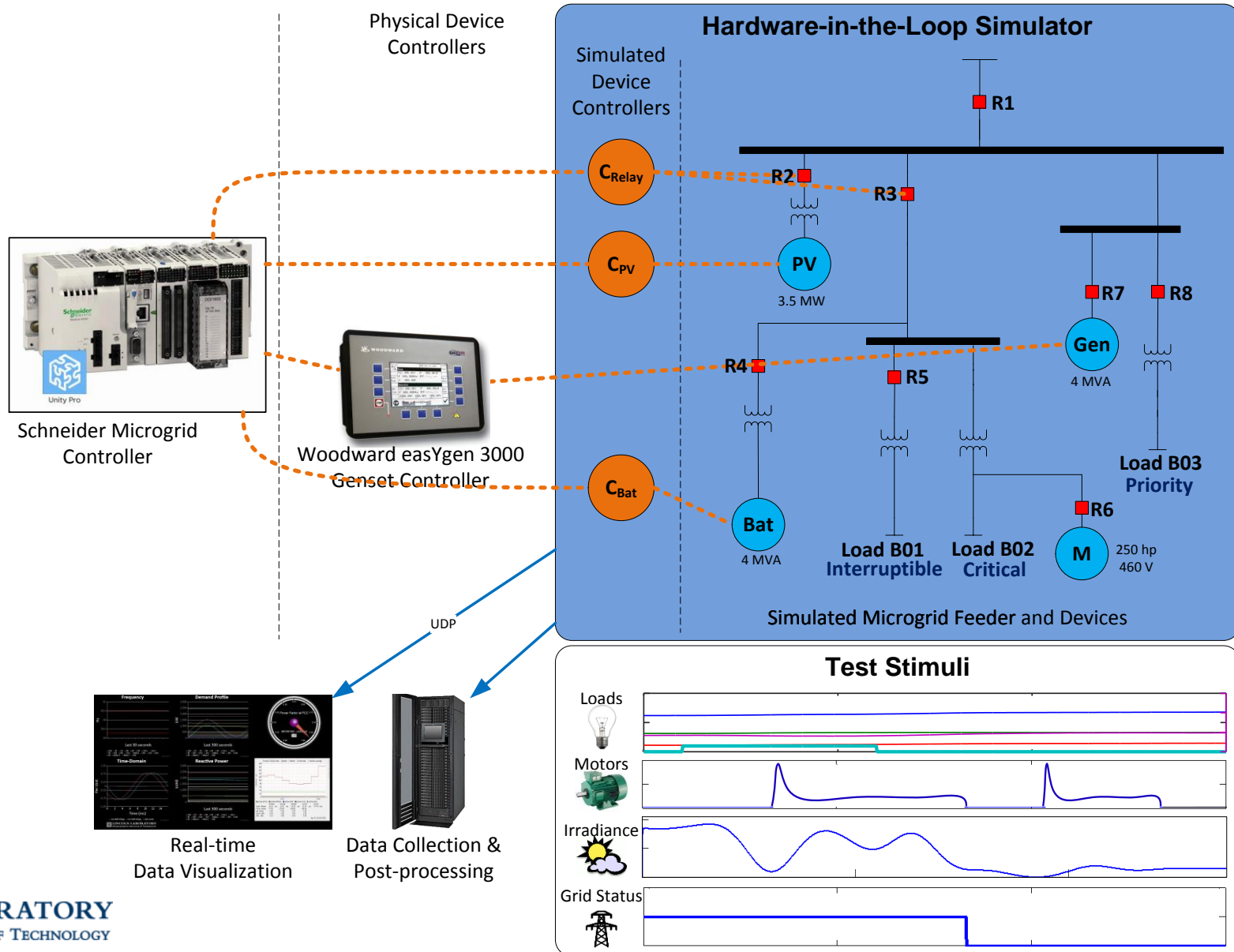
## Test Stimuli





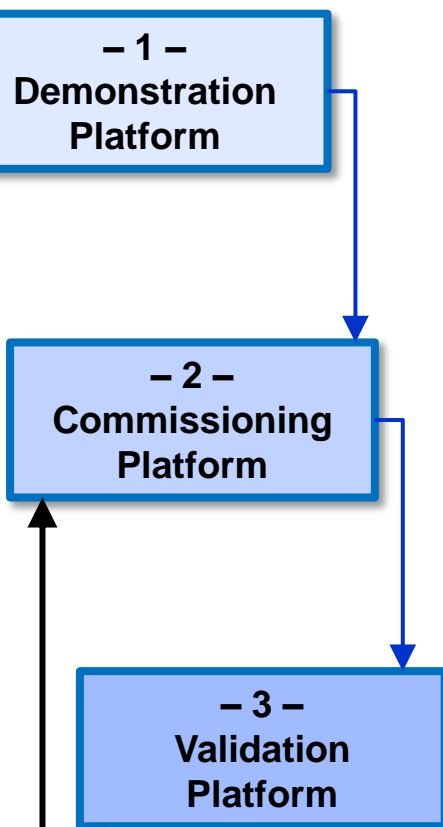


# Microgrid Controller HIL Platform





# Vision for the Microgrid Controller HIL Platform



- Cost-effective evaluation of commercial microgrid controllers
- Side-by-side comparison of commercial products
- *Demonstrations at Massachusetts Microgrid Controls Symposium*
- Commission a microgrid before putting any steel in the ground
- Exercise the actual device controllers; test edge conditions
- Technical risk reduction and confidence building for the utility
- *Commission Boston microgrid project*
- Develop standard test feeders and test profiles
- *Test against IEEE P2030.8 standard and utility requirements*

Open Source HIL Project



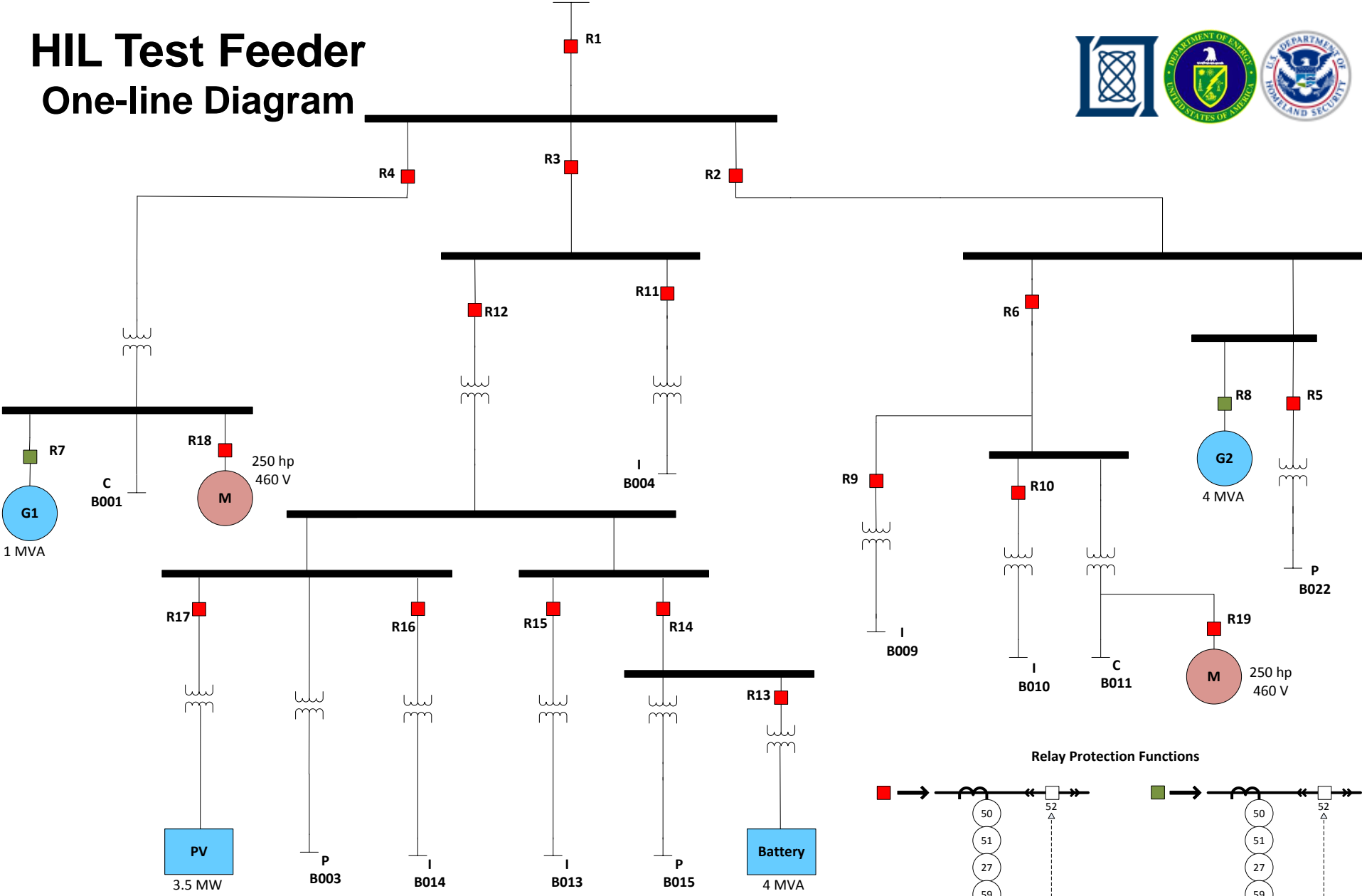
# Outline



- Introduction to Controller Hardware-in-the-Loop
- ➔ • Orientation to Today's Demonstration
- Way Ahead

# HIL Test Feeder

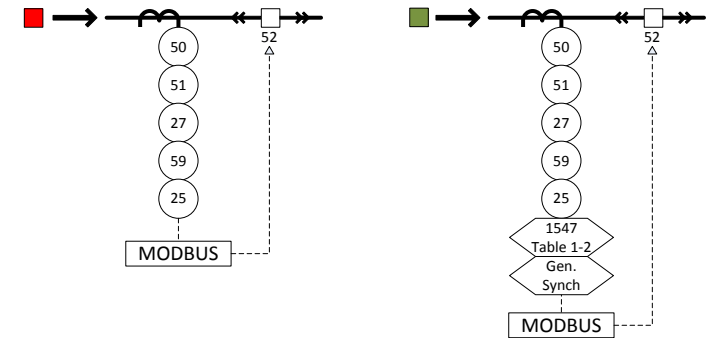
## One-line Diagram



### Legend

- ■ ← Protection, Relay and Monitoring (PRM)
- ← Priority load
- ← Interruptible load
- ← Critical load
- ← Load I.D.

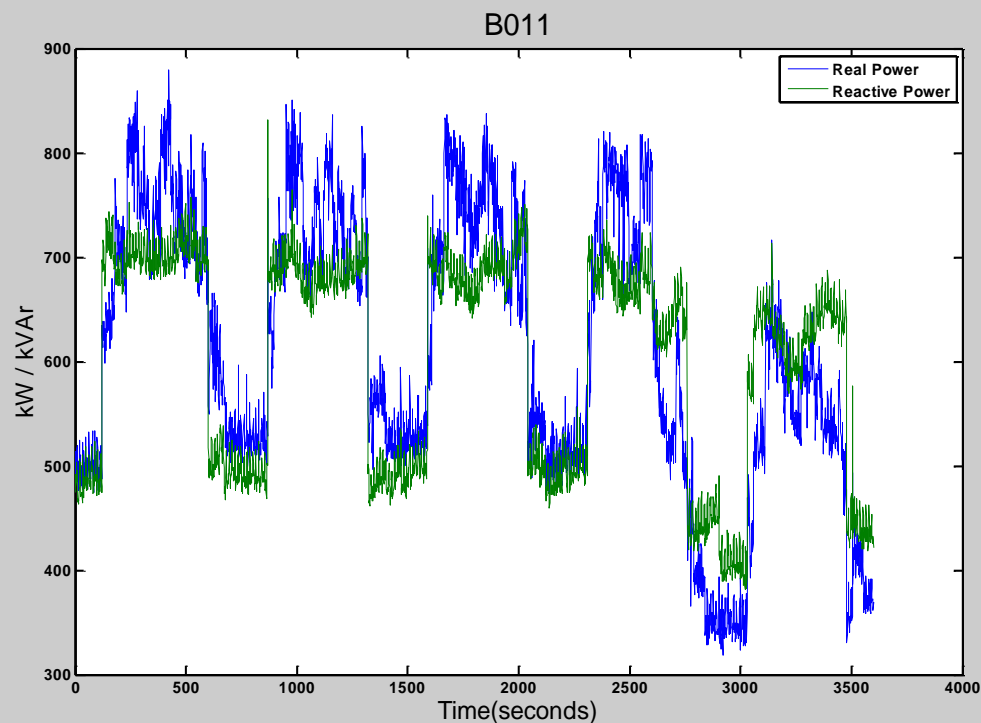
### Relay Protection Functions







# Example Load (B011)



- Peak kW: 879
- Min kW: 319
- Peak kVAR: 832
- Min kVAR: 382
- Nominal Voltage:  
460 V

1 work week compressed into 2 hours



# Microgrid Controller Hardware-in-the-Loop Platform



Firewall and  
Network Switch

Console

Woodward  
easYGen

Interface Box

Monitoring I/O  
Analog & Digital

Opal-RT HIL  
Target

MIT Lincoln Lab  
Windows Server

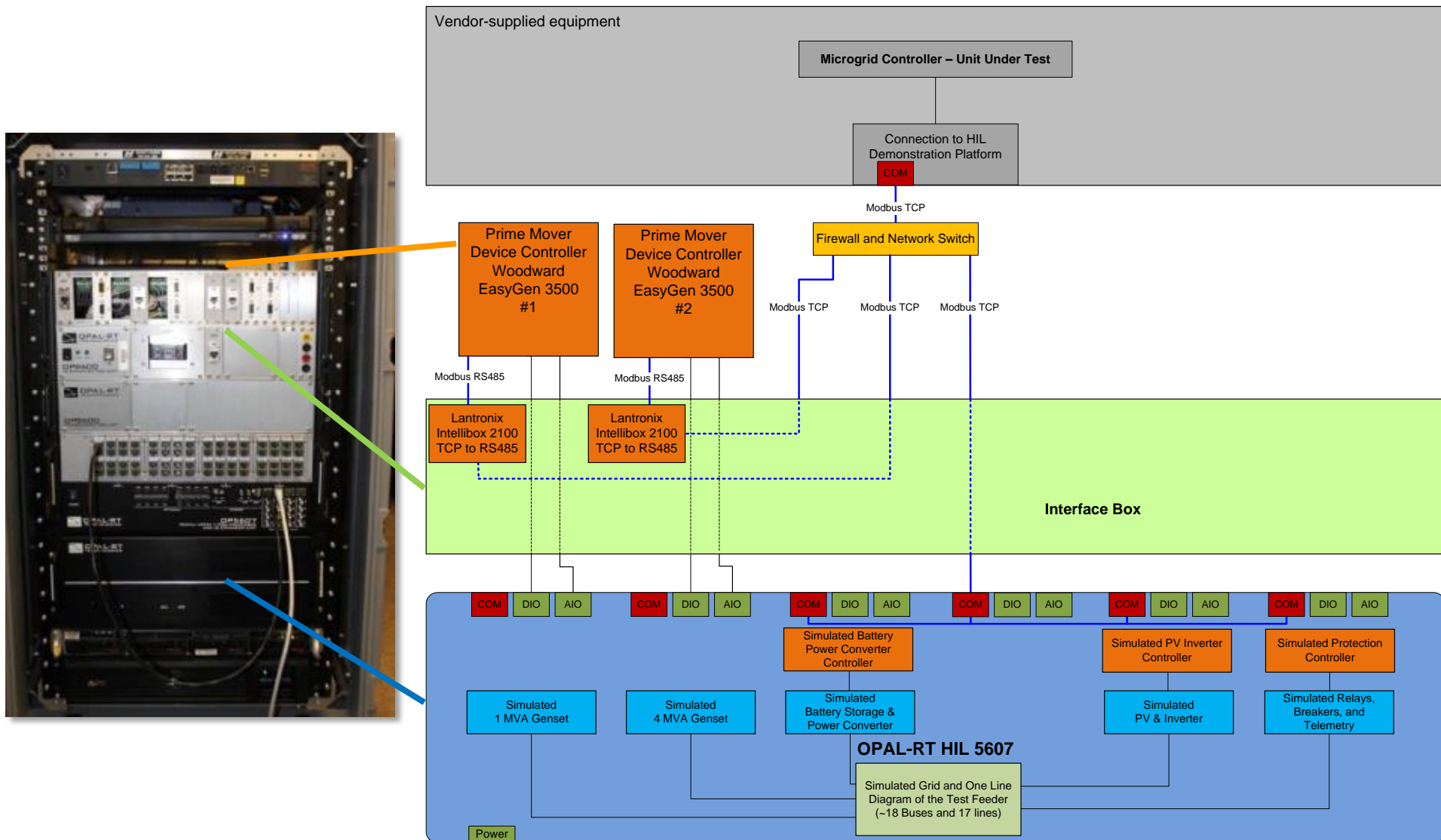
Power Supply



Two integrated  
Woodward easYgen 3000  
genset controllers



# HIL Platform Block Diagram





# Device Address List



Device	IP Address	Notes
1 MVA Genset Controller	192.168.10.35	-
4 MVA Genset Controller	192.168.10.36	-
Storage Controller	192.168.10.40	-
PV Controller	-	No interface
Relay 1	10.10.45.101	Point of Common Coupling
Relay 2	10.10.45.102	Serves & senses sub-panel B021
Relay 3	10.10.45.103	Serves & senses sub-panel B012
Relay 4	10.10.45.104	Serves & senses load B001 + genset1
Relay 5	10.10.45.105	Serves & senses B022
Relay 6	10.10.45.106	Serves & senses loads B009-B011
Relay 7	10.10.45.107	Serves & senses genset 1
Relay 8	10.10.45.108	Serves & senses genset 2
Relay 9	10.10.45.109	Serves & senses load B009
Relay 10	10.10.45.110	Serves & senses load B010
Relay 11	10.10.45.111	Serves & senses load B004
Relay 12	10.10.45.112	-
Relay 13	10.10.45.113	Serves & senses battery
Relay 14	10.10.45.114	Serves & senses load B015 + battery
Relay 15	10.10.45.115	Serves & senses load B013
Relay 16	10.10.45.116	Serves & senses load B014
Relay 17	10.10.45.117	Serves & sense PV
Motor Relays		



# Simulated Battery and PV Systems



- **Four quadrant power source with sub-cycle transient accuracy, modeled in real time**
  - **Boost rectifier average model**
  - **Three phase PLL**
  - **D and Q axis current PIDs respond to power commands**
- **PV MPP tracker**
- **Inverter physical limits monitored by fault controller**

	Battery Rating	PV Rating
AC Power Rating (kVA)	4,000	3,500
Storage (kWh)	500	n/a
Cycle Life	$\infty$	n/a
Voltage (V)	2,400	2,400
Frequency (Hz)	60	60
Ramp Rate	8 MW/s	2.5 MW/min

Battery and PV system ratings and characteristics

Parameter	Units	Notes
Real Power Command	kW	(-) discharge; (+) charge
Reactive Power Command	kVAR	(+) capacitive; (-) inductive
Modbus Enable	0/1	1 to indicate active Modbus connection.
Fault Status		Phase A Over Current Phase B Over Current Phase C Over Current DC Link Overvoltage PLL Loss of Sync Vrms out of spec Battery Empty Battery Full
Battery SoC	%	Battery start at 50%
Enable	0/1	Cycle to clear any faults.

Register list for battery system device controller



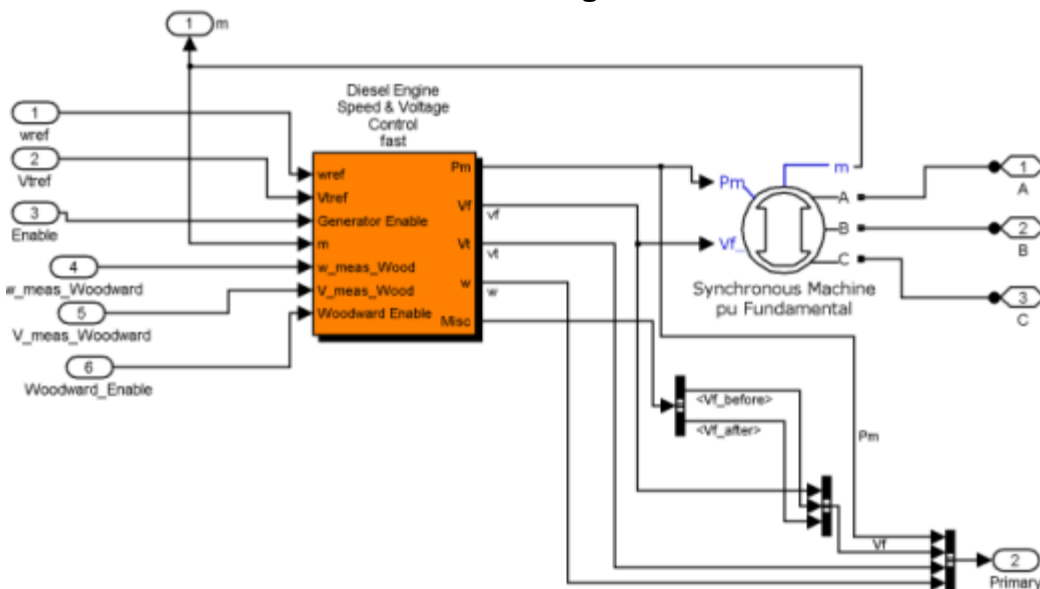


# Simulated Genset Block



	1 MW Genset	4 MW Genset
<b>Manufacturer / Model</b>	CAT C32	CAT C175-20
<b>Rating (kVA)</b>	1,000	4,000
<b>Power Factor</b>	TBD	TBD
<b>Voltage (V)</b>	480	13,800
<b>Frequency (Hz)</b>	60	60
<b>Speed (RPM)</b>	1800	1800
<b>Minimum Output Power</b>	25kW	100kW
<b>Startup Time</b>	<10 sec	<15 sec

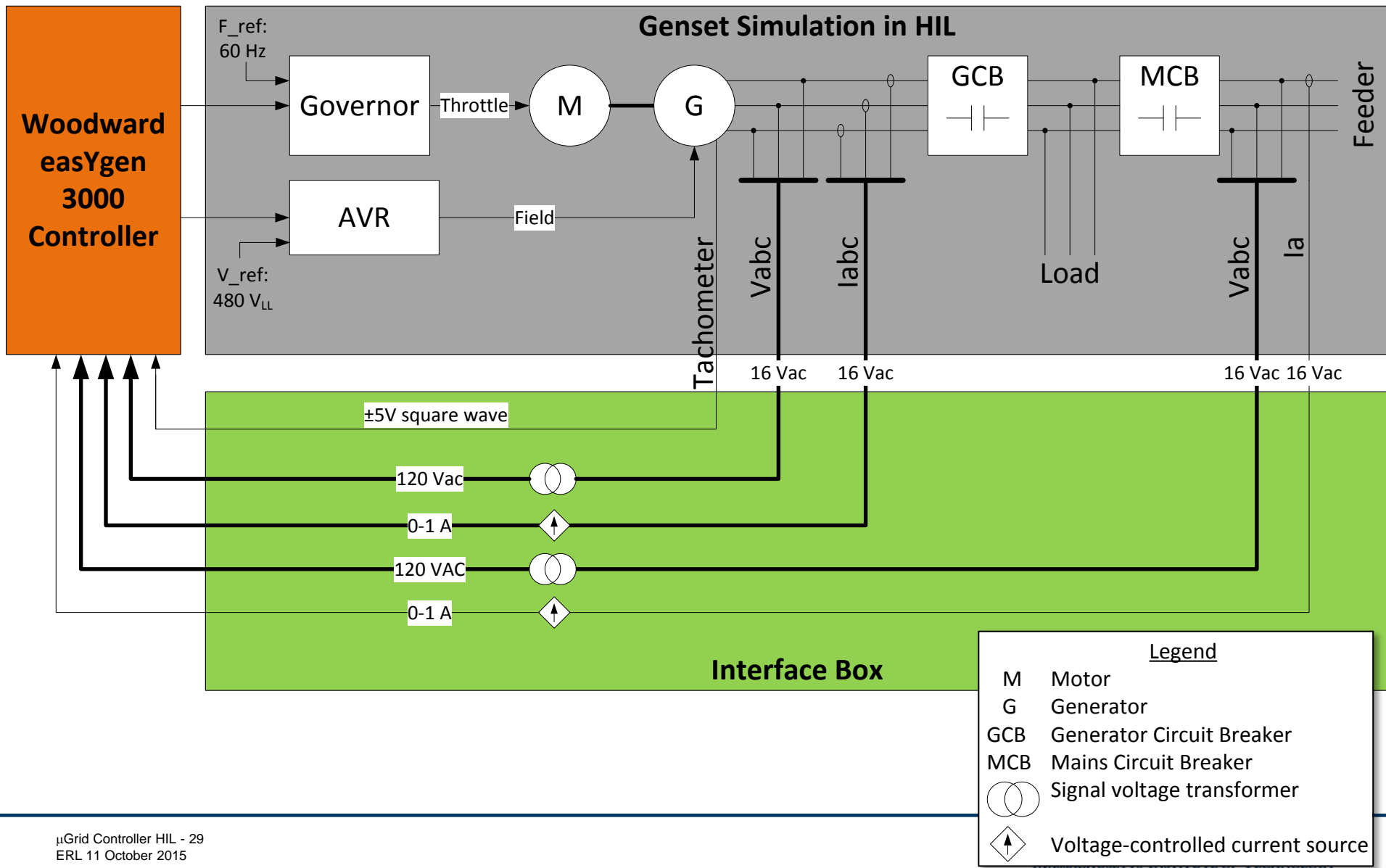
Genset ratings and characteristics



Synchronous Machine, Governor, and AVR Models



# Device Controller Integration: Woodward easYgen 3000







# Simulated Relay: SEL-787 Transformer Protection Relay

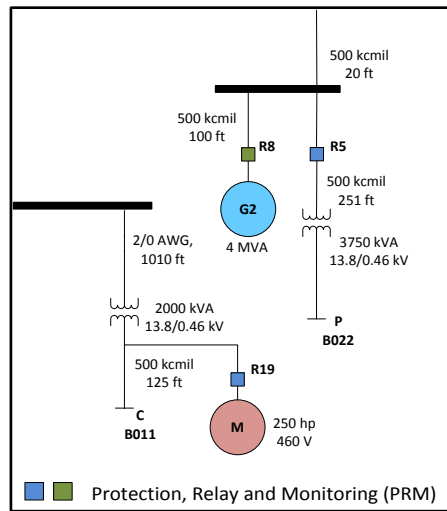
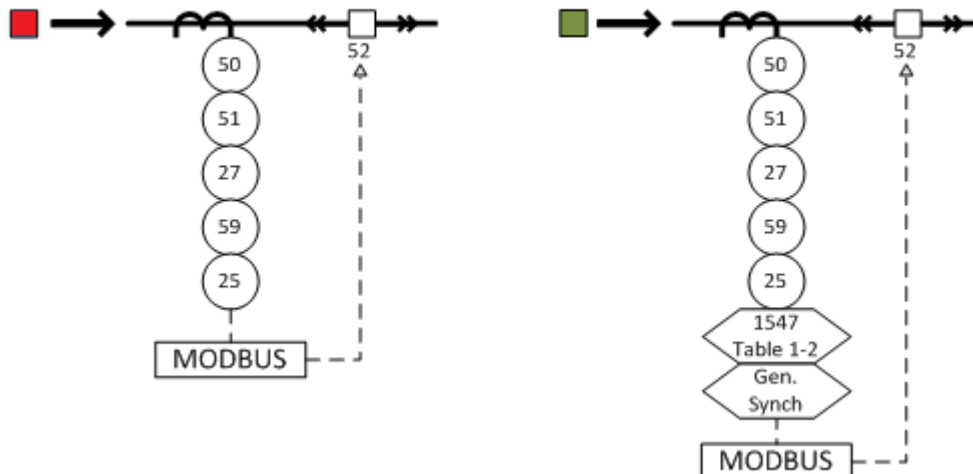


Image: Schweitzer Engineering

## Relay Protection Functions



## Protection Function

ANSI 50	Inst. overcurrent
ANSI 51	Avg. overcurrent
ANSI 27	Undervoltage
ANSI 59	Overvoltage
ANSI 25	Synchronism-check
1547 Tables 1&2	Abnormal V & f
Gen. Synch	Generator synch
ANSI 52	AC Circuit Breaker



# Demonstration against ORNL/EPRI Microgrid Functional Use Cases



Functional Use Case	Description	Demonstration
<b>F-1 Frequency Control</b>	Selection of grid-forming, -feeding, and -supporting energy sources to maintain stability; sub-second control to maintain stable frequency while islanded	The microgrid controller selects from among the two gensets and battery DERs.
<b>F-2 Voltage Control</b>	Regulate voltage at the microgrid point of common coupling	No demo
<b>F-3 Intentional Islanding</b>	Planned disconnect from area electric power system (AEPS)	Islanding will be initiated by the microgrid controller
<b>F-4 Unintentional Islanding</b>	Fast disconnect from AEPS upon large disturbance to provide continuous supply to loads	No demo due to battery and PV inverter controller PLL instability
<b>F-5 Transition from Islanded to Grid-tied</b>	Resynchronize and reconnect to AEPS	Initiated by microgrid controller once generators and grid synchronize



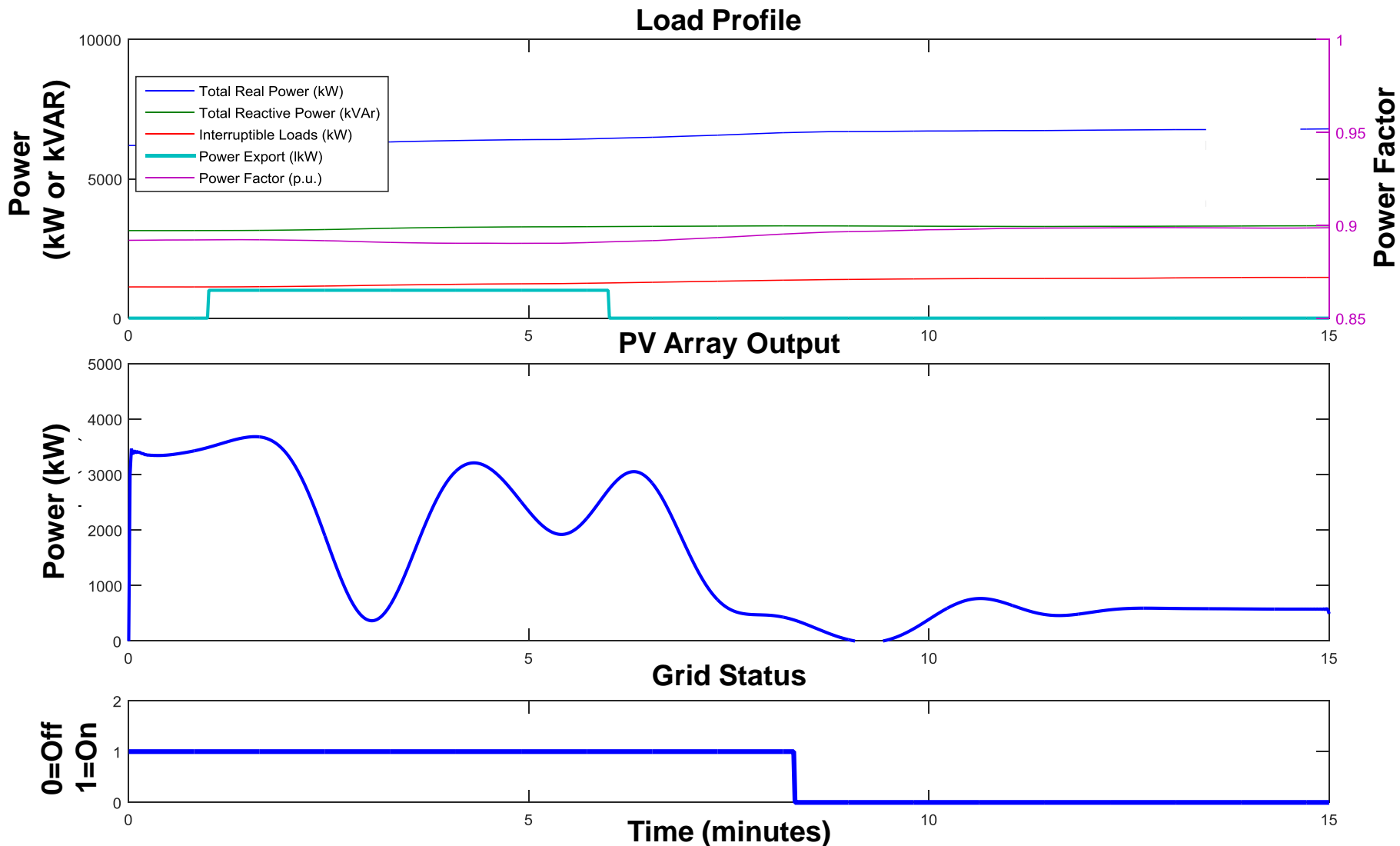
# Demonstration against ORNL/EPRI Microgrid Functional Use Cases (cont.)



Functional Use Case	Description	Demonstration
<b>F-6(a) Energy Management: grid-tied</b>	Coordinate generation, load, & storage dispatch, to participate in utility operation and energy market activities	The microgrid controllers target a power export value for a defined period, and should also shave peak demand.
<b>F-6(b) Energy Management: islanded</b>	Coordinate generation, load, & storage dispatch, to optimize islanded operation (fuel consumption, islanding duration)	Fuel consumption and service of critical and priority loads are measured during islanded operation.
<b>F-7 Microgrid Protection</b>	Configure protection devices for different operating conditions	DER and relay protection are implemented, but are not configurable.
<b>F-8 Ancillary Services: regulation</b>	Provide frequency regulation, generation reserves, reactive power support, and demand response to AEPS	Demand response to hit a target power export value; Reactive power support to maintain unity power factor at PCC
<b>F-9 Microgrid Blackstart</b>	Restore islanded operation after a complete shutdown	Likely limited by present genset control capabilities
<b>F-10 User Interface, Data Collection</b>	Organize, archive, and visualize real-time and non-real-time data	Data collection and visualization performed by MIT-LL, not $\mu$ C



# 15-minute Demonstration Sequence

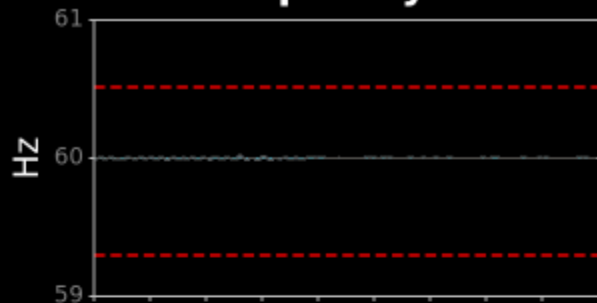




# Heads-up Display (screen 1)



## Frequency

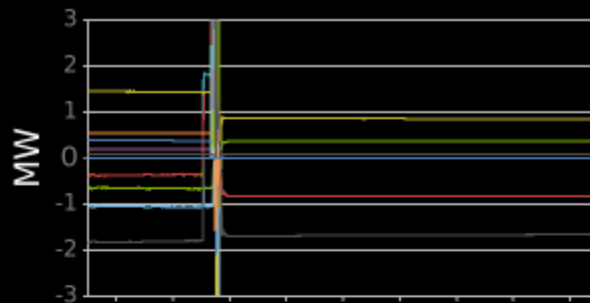


Last 30 seconds

Grid R2 R3 R4 R5 R6 Gen 1  
Gen 2 R9 R10 R11 R12 Battery  
R14 R15 R16 PV Motor 1 Motor 2  
R20

CanvasJS.com

## Real Power

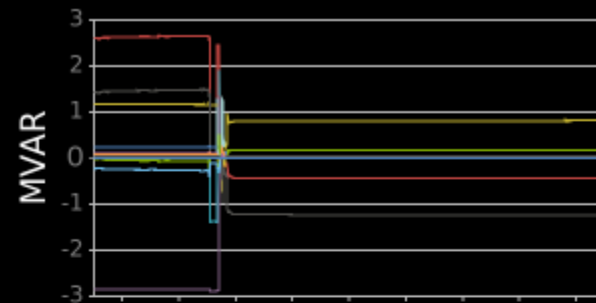


Last 300 seconds

Grid R2 R3 R4 R5 R6 Gen 1  
Gen 2 R9 R10 R11 R12 Battery  
R14 R15 R16 PV Motor 1 Motor 2  
R20

CanvasJS.com

## Reactive Power

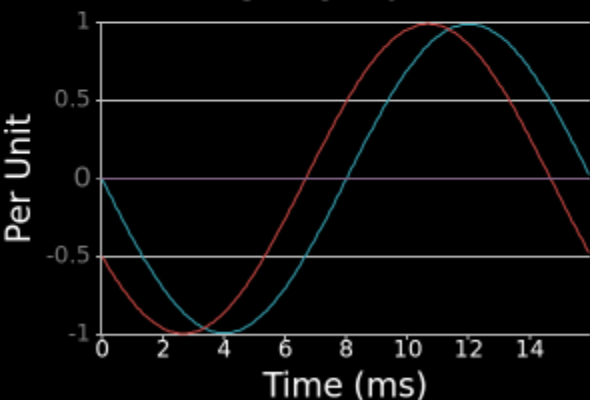


Last 300 seconds

Grid R2 R3 R4 R5 R6 Gen 1  
Gen 2 R9 R10 R11 R12 Battery  
R14 R15 R16 PV Motor 1 Motor 2  
R20

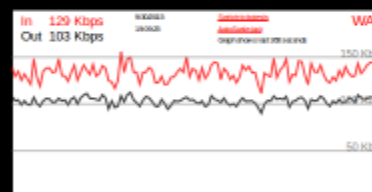
CanvasJS.com

## Time-Domain



Gen 4MW Voltage Gen 1MW Voltage  
Batt current

CanvasJS.com

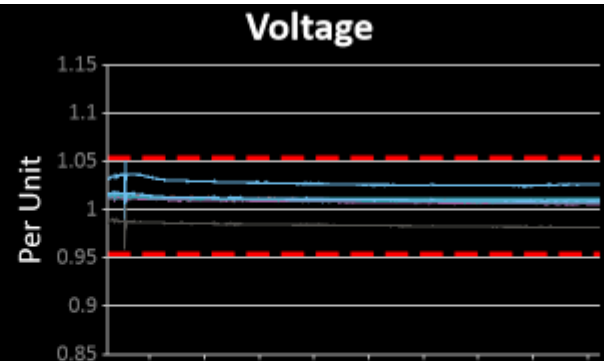


Host IP	Bandwidth In	Bandwidth Out
10.10.45.17	84.54k Bps/sec	105.18k Bps/sec
10.10.45.103	11.31k Bps/sec	7.88k Bps/sec
10.10.45.110	11.31k Bps/sec	7.88k Bps/sec
10.10.45.116	11.31k Bps/sec	7.88k Bps/sec
10.10.45.106	9.91k Bps/sec	6.96k Bps/sec
10.10.45.102	8.28k Bps/sec	3.03k Bps/sec
10.10.45.115	8.28k Bps/sec	3.03k Bps/sec
10.10.45.105	8.16k Bps/sec	4.88k Bps/sec
10.10.45.108	8.16k Bps/sec	4.88k Bps/sec
10.10.45.101	6.18k Bps/sec	7.88k Bps/sec



The diagram illustrates a complex power distribution network. Key components include:

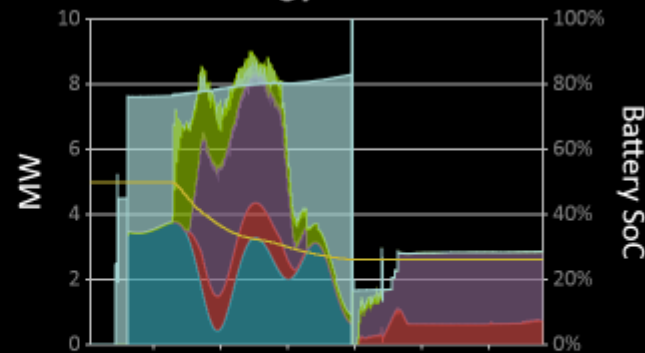
- High Voltage Section:** A 13.8 kV busbar at the top, fed by a 13.8 kV line. It branches into three main paths.
- Medium Voltage Section:** Includes a 460 V busbar (left) and a 4160 V busbar (center). The 460 V busbar serves a 1 MVA generator (G1) and a 250 hp motor. The 4160 V busbar acts as a central hub connecting to multiple other buses.
- Low Voltage Section:** Consists of numerous buses labeled B001 through B015, each with associated breakers (R1-R19) and protective devices. These are further connected to specific loads like a 3.5 MW source and a 4 MVA transformer.



Last 300 seconds



## Energy Sources



15 Minutes





# Anonymized Results of Demonstration Runs



## Energy Consumption

	Grid-tied			Islanded
	Fuel Used (gal.)	Energy Imported (kWh)	Energy Exported (kWh)	Fuel Used (gal.)
Sequence 1	5.9	311	13	4.9
Sequence 2				
Sequence 3				

## Load-not-Served (kWh) while Islanded Voltage Profile (sec exceeding $\pm 5\%$ )

	Critical	Priority	Inter.		Grid-tied	Islanded
Sequence 1	79	466	143	Sequence 1	0	3.6
Sequence 2				Sequence 2		
Sequence 3				Sequence 3		





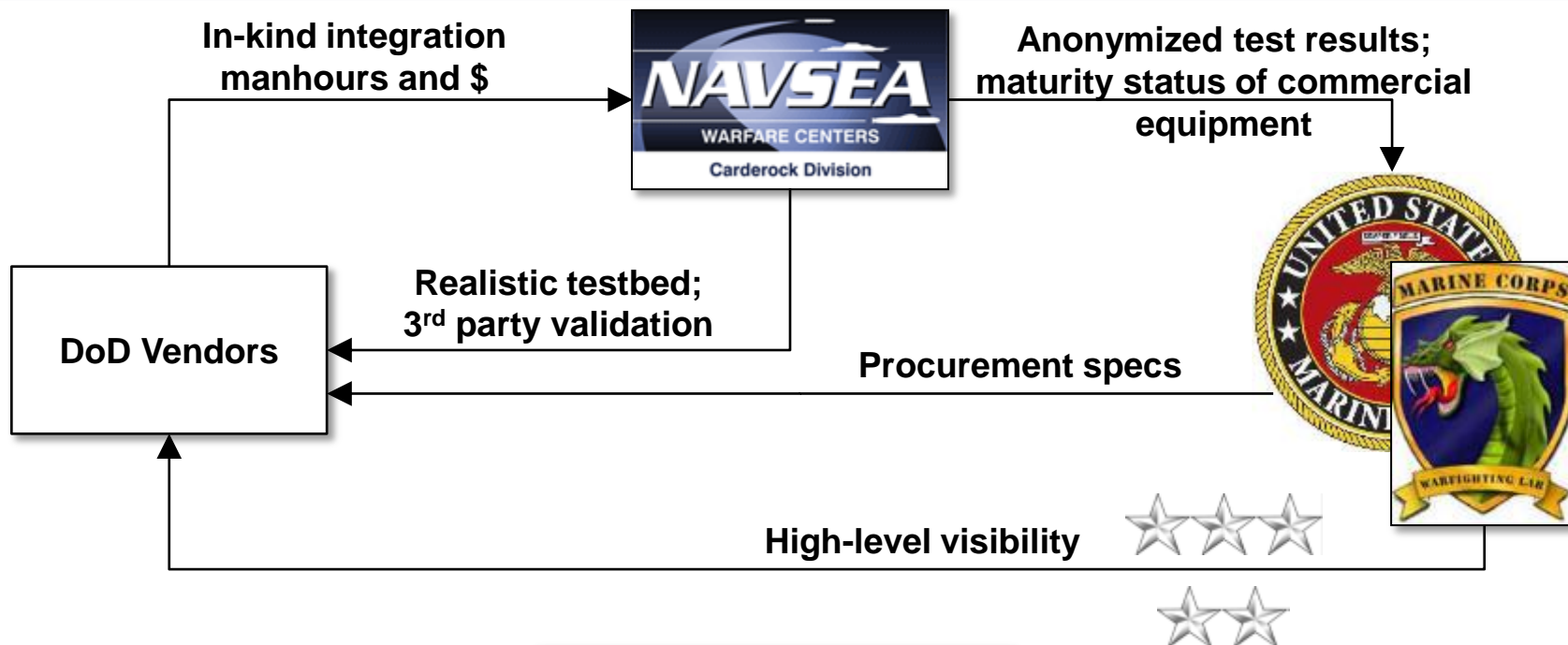
# Outline



- Introduction to Controller Hardware-in-the-Loop
- Orientation to Today's Demonstration
- ➔ • Way Ahead



# USMC ExFOB Example



ExFOB 2013 – Twentynine Palms

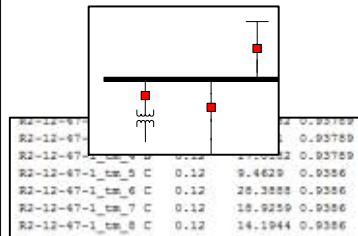


# Elements of the Open Source HIL Repository



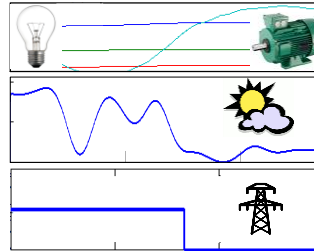
## Microgrid Test Repository

### Microgrid Test Feeders



Netlists

### Standard Test Stimuli



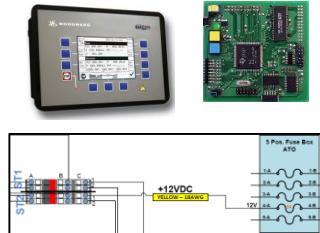
Load profiles, irradiance profiles, grid outages, faults

### Post-processing Scripts for Test Results



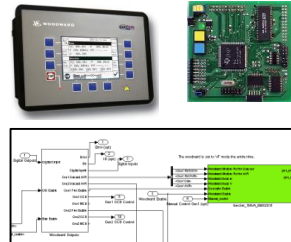
## Controller-in-the-Loop Repository

### Interface Circuitry for Device Controllers

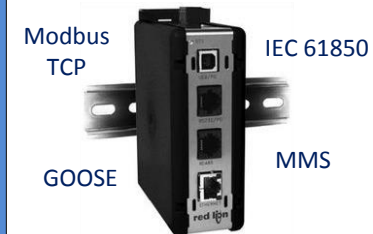


Circuit schematics, bills of material

### Interface Code for Device Controllers

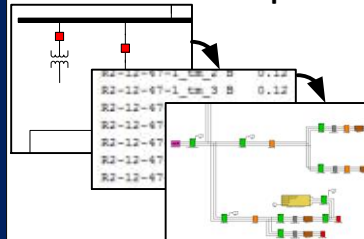


### Communications Interface Translation Code



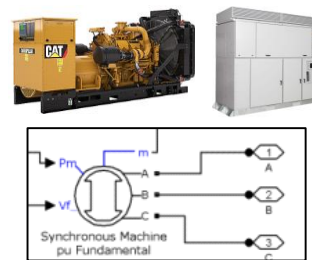
## HIL Platform Repository

### HIL Target Platform Conversion Scripts



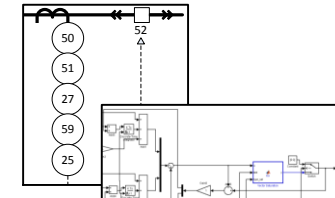
Targets: OPAL-RT, Typhoon HIL, RTDS, NI, and others

### Validated Device Models



Motor-generators, power converters / inverters, and relays

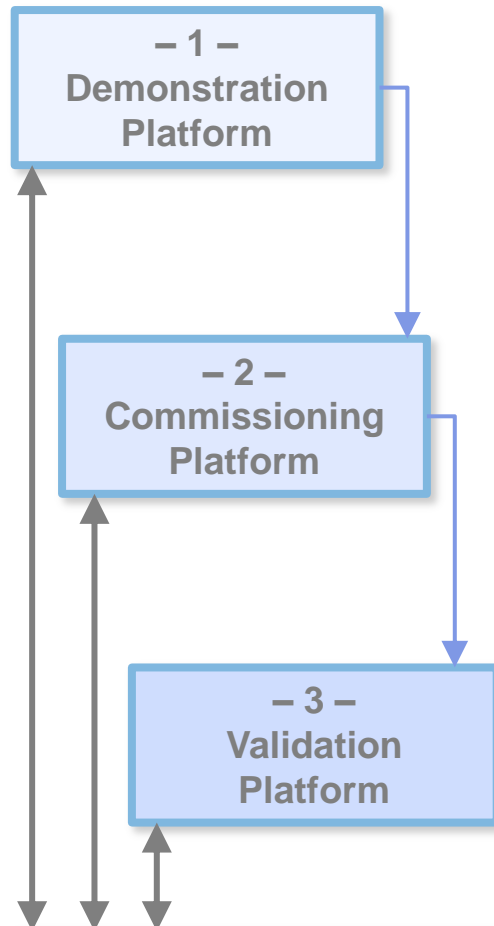
### Validated Device Controller Software



Genset controllers, power converter controllers, relay protection functions



# Vision for Microgrid HIL Open-source Repository



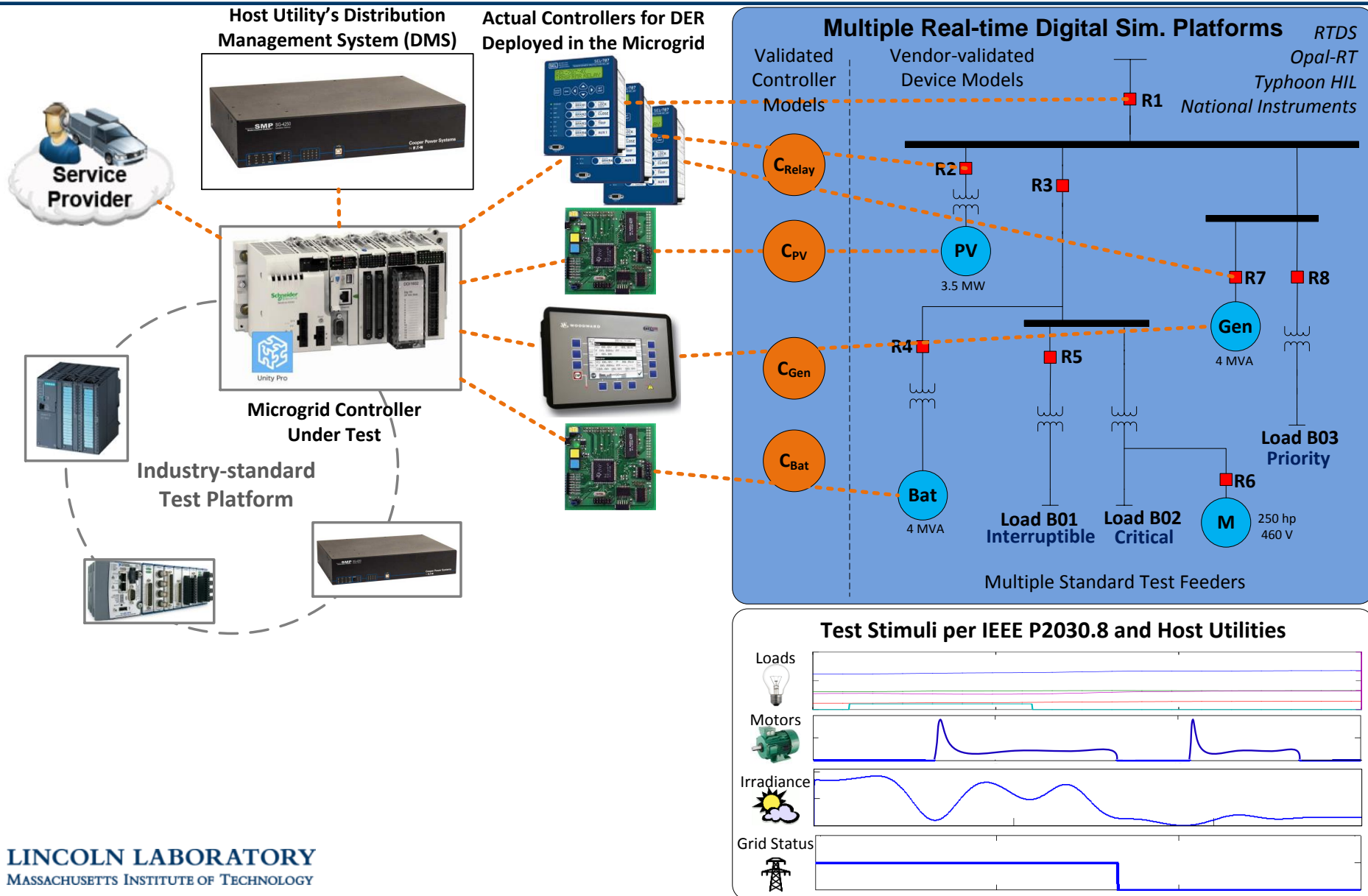
- **Goals:**
  - Accelerate and reduce risk of microgrid deployment
    - Enable software development and integration work to be 95% done at the start of commissioning, not 50%
  - Enable rapid proof-of-concepts to reduce utility engineers' perceived risk
- **Agnostic to real-time simulation platform**
  - NI, OPAL-RT, RTDS, Typhoon, or any other target
- **Validated DER device models provided by vendors**
- **Standard test benches**
  - Reference microgrid feeders
  - Test scripts / test stimuli
  - Post-processing software for compliance verification

**Interested in participating? Contact MIT-LL.**

**Open Source HIL Project**



# Vision for Eventual HIL Capabilities





# Acknowledgements



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**Division 4 – Homeland Protection**  
**Division 5 – Cyber Security**  
**Division 6 – Communications**  
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**Michael Starke, ORNL**  
**Tom Steber, Schneider**  
**Brad Swing, City of Boston**





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# October 1 Massachusetts Microgrid Controls Symposium

