

List of Physical Constants

Name	Symbol	Value
Gravitational Acceleration	g	9.81 m/s ²
Mass of Earth	M_e	5.97×10^{24} kg
Boltzmann constant	$k_B = R / N_A$	1.381×10^{-23} J/K
Avogadro's number	N_A	6.02×10^{23} molecules/mol
Universal gas constant	R	8.314 J/mol K
Absolute zero	0 K	– 273.15°C
Pressure conversion	1 bar	10^5 N/m ² (or Pa)
	1 atm	1.01×10^5 Pa
Mass of electron	m_e	9.11×10^{-31} kg
Mass of proton	m_p	1.673×10^{-27} kg
Mass of neutron	m_n	1.675×10^{-27} kg
Speed of light in vacuum	c	3×10^8 m/s
Permeability of vacuum	μ_0	$4\pi \times 10^{-7}$ T·m/A
Permittivity of vacuum	$\epsilon_0 = 1/(\mu_0 c^2)$	8.854×10^{-12} C ² /(N·m ²)
Coulomb constant	$k = 1/(4\pi\epsilon_0)$	8.99×10^9 N·m ² /C ²
Magnitude of electron charge	$ e $	1.6×10^{-19} C
Gravitational constant	G	6.67×10^{-11} N·m ² /kg ²
Electron volt	1 eV	1.6×10^{-19} J

List of Formulae

Part 1: Mechanics

Linear Motion

$$\vec{v}_{avg} = \frac{\Delta \vec{r}}{\Delta t} = \frac{\vec{r}_f - \vec{r}_i}{t_f - t_i}, \quad \vec{v} \equiv \lim_{\Delta t \rightarrow 0} \frac{\Delta \vec{r}}{\Delta t} = \frac{d\vec{r}}{dt}, \quad v = \frac{dx}{dt}$$

$$\vec{a}_{avg} = \frac{\Delta \vec{v}}{\Delta t} = \frac{\vec{v}_f - \vec{v}_i}{t_f - t_i}, \quad \vec{a} \equiv \lim_{\Delta t \rightarrow 0} \frac{\Delta \vec{v}}{\Delta t} = \frac{d\vec{v}}{dt} = \frac{d^2 \vec{r}}{dt^2}, \quad a = \frac{dv}{dt}$$

$$v_f = v_i + at, \quad x_f = x_i + \frac{1}{2}(v_i + v_f)t, \quad v_f^2 = v_i^2 + 2a(x_f - x_i), \quad x_f = x_i + v_i t + \frac{1}{2}at^2$$

$$y = (\tan \theta_i)x - \left(\frac{g}{2v_i^2 \cos^2 \theta_i} \right) x^2, \quad h = \frac{v_i^2 \sin^2 \theta_i}{2g}, \quad R = \frac{v_i^2 \sin 2\theta_i}{g}$$

$$\Sigma \vec{F} = \frac{d\vec{p}}{dt} = m\vec{a}, \quad F_t = v \frac{dm}{dt}, \quad \vec{p} = m\vec{v}, \quad f_k = \mu_k N, \quad f_s \leq \mu_s N, \quad v = \frac{mg}{b} (1 - e^{-\frac{b}{m}t})$$

$$\vec{I} = \int_{t_i}^{t_f} \vec{F} dt = \Delta \vec{p} = \vec{p}_f - \vec{p}_i, \quad \vec{I} = \vec{F}_{avg} \Delta t$$

$$W = \int_{x_i}^{x_f} \vec{F} \cdot d\vec{x} = \Delta KE \quad W = \vec{F} \cdot \vec{r} = |\vec{F}| |\vec{r}| \cos \phi = \Delta KE, \quad P = \frac{dW}{dt} = \vec{F} \cdot \vec{v}$$

$$KE = \frac{1}{2}mv^2, \quad PE_E = \frac{1}{2}k(\Delta x)^2, \quad PE_G = mgh$$

$$m_1 v_{1i} + m_2 v_{2i} = m_1 v_{1f} + m_2 v_{2f}, \quad v_{1i} - v_{2i} = -(v_{1f} - v_{2f})$$

$$\vec{r}_{CM} = \frac{1}{M} \sum_i m_i \vec{r}_i, \quad x_{CM} = \frac{1}{M} \sum_i m_i x_i, \quad y_{CM} = \frac{1}{M} \sum_i m_i y_i, \quad z_{CM} = \frac{1}{M} \sum_i m_i z_i$$

Rotational Motion

$$a_c = \frac{v^2}{r} = r\omega^2, \quad a_t = \frac{d|\vec{v}|}{dt}$$

$$s = r\theta, \quad \omega = \frac{d\theta}{dt} = \frac{v}{r}, \quad \alpha = \frac{d\omega}{dt} = \frac{a}{r},$$

Gravitation

$$F = \frac{GM_1 M_2}{r^2} \quad U = -\frac{GM_1 M_2}{r}$$

$$g = \frac{GM}{r^2} \quad V = -\frac{GM}{r}$$

$$\omega_f = \omega_i + \alpha t, \quad \theta_f = \theta_i + \frac{1}{2}(\omega_i + \omega_f)t, \quad \omega_f^2 = \omega_i^2 + 2\alpha(\theta_f - \theta_i), \quad \theta_f = \theta_i + \omega_i t + \frac{1}{2}\alpha t^2$$

$$I = \sum_i r_i^2 m_i, \quad I = \int r^2 dm, \quad I_0 = I_{CM} + MD^2, \quad I_z = I_x + I_y$$

$$\tau = \vec{r} \times \vec{F} = |\vec{F}| |\vec{r}| \sin \phi, \quad \Sigma \tau = \frac{dL}{dt} = I\alpha, \quad KE_r = \frac{1}{2}I\omega^2, \quad L = \vec{r} \times \vec{p} = |\vec{p}| |\vec{r}| \sin \phi = I\omega$$

List of moments of inertia

Thin cylindrical shell	$I_{CM} = MR^2$
Hollow cylinder	$I_{CM} = \frac{1}{2}M(R_1^2 + R_2^2)$
Solid cylinder or disc	$I_{CM} = \frac{1}{2}MR^2$
Rectangular plate	$I_{CM} = \frac{1}{12}M(a^2 + b^2)$
Long thin rod with rotation axis through centre	$I_{CM} = \frac{1}{12}ML^2$
Long thin rod with rotation axis through end	$I = \frac{1}{3}ML^2$
Thin spherical shell	$I_{CM} = \frac{2}{3}MR^2$
Solid sphere	$I_{CM} = \frac{2}{5}MR^2$

Part 2: Thermal Physics

$$\Delta L = \alpha L_i \Delta T, \quad \Delta A = 2\alpha A_i \Delta T, \quad \Delta V = \beta V_i \Delta T$$

$$T = \frac{P(T) - P(0)}{P(100) - P(0)} \times 100, \quad T = 273.16 \text{ K} \lim_{P_{tr} \rightarrow 0} \frac{P}{P_{tr}}$$

$$PV = nRT, \quad PV^\gamma = \text{constant}, \quad TV^{\gamma-1} = \text{constant}, \quad \gamma = \frac{c_p}{c_v}, \quad c_p - c_v = R, \quad k_B = \frac{R}{N_A}$$

$$KE_{total} = \frac{1}{2} M \overline{v^2} = \frac{3}{2} nRT = \frac{3}{2} N k_B T, \quad E_{int} = \frac{3}{2} nRT$$

$$Q = mc\Delta T, \quad Q = ml, \quad Q = nC_v \Delta T, \quad Q = nC_p \Delta T, \quad Q = \Delta E_{int} + W$$

$$W = \int_{V_i}^{V_f} P dV, \quad W = p(V_f - V_i), \quad W = nRT \ln \frac{V_f}{V_i}, \quad W = \frac{1}{1-\gamma} (p_f V_f - p_i V_i)$$

$$\eta = \frac{W_{out}}{Q_H} = 1 - \frac{Q_C}{Q_H}$$

Part 3: Electricity and Magnetism

$$\vec{A} \cdot \vec{B} \equiv |A||B| \cos \theta; \quad \vec{A} \times \vec{B} \equiv |A||B| \sin \theta \hat{n}$$

$$\vec{F} = q\vec{E} \quad |F| = \frac{|Qq|}{4\pi\epsilon_0 r^2} \quad |E| = \frac{|Q|}{4\pi\epsilon_0 r^2} \quad \Phi_E = \oint \vec{E} \cdot d\vec{A} = \frac{Q_{in}}{\epsilon_0}$$

$$U = qV \quad U = \frac{Qq}{4\pi\epsilon_0 r} \quad V = \frac{Q}{4\pi\epsilon_0 r} \quad E_r = -\frac{dV}{dr}$$

$$Q = C\Delta V \quad U = \frac{1}{2} C (\Delta V)^2 \quad u_E = \frac{1}{2} \epsilon_0 E^2 \quad \vec{\tau} = \vec{p} \times \vec{E};$$

$$C = \frac{\epsilon_0 A}{d} \quad U = -\vec{p} \cdot \vec{E}$$

$$I = \frac{dQ}{dt} \quad J = \frac{I}{A} = nqv_d \quad J = \sigma E \quad V = IR; \quad R = \rho \frac{L}{A}; \quad \rho = \frac{1}{\sigma}$$

$$\mathcal{E} = IR + Ir \quad q(t) = Q(1 - e^{-\frac{t}{RC}}) \quad q(t) = Q_0 e^{-\frac{t}{RC}} \quad \sum_{\text{junction}} I = 0; \quad \sum_{\text{closed loop}} \Delta V = 0$$

$$I(t) = \frac{\mathcal{E}}{R} e^{-\frac{t}{RC}} \quad P = IV = I^2 R = \frac{V^2}{R}$$

$$\vec{F} = q\vec{v} \times \vec{B} \quad \vec{B} = \frac{\mu_0}{4\pi} \int \frac{I d\vec{s} \times \hat{r}}{r^2} \quad \oint \vec{B} \cdot d\vec{s} = \mu_0 I \quad B = \frac{\mu_0 I}{2\pi r}; B = \mu_0 nI; B = \frac{\mu_0 NI}{2r}$$

$$\vec{F} = I\vec{L} \times \vec{B} \quad \vec{F} = I \int_a^b d\vec{s} \times \vec{B} \quad \Phi_B = \oint \vec{B} \cdot d\vec{A} = 0 \quad u_B = \frac{1}{2\mu_0} B^2$$

$$\begin{aligned}
\vec{F} &= q\vec{E} + q\vec{v} \times \vec{B} & \vec{\tau} &= \vec{\mu} \times \vec{B}; U = -\vec{\mu} \cdot \vec{B} \\
\mathcal{E} &= -N \frac{d\Phi_B}{dt} & \Phi_B &= \int \vec{B} \cdot d\vec{A} & \mathcal{E} &= Blv \cos \theta & \oint \vec{E} \cdot d\vec{s} &= -\frac{d\Phi_B}{dt} \\
\mathcal{E} &= -L \frac{dI}{dt} & L &= \frac{N\Phi_B}{I}; U = \frac{1}{2}LI^2 & \mathcal{E}_2 &= -M_{12} \frac{dI_1}{dt} & M_{12} &= \frac{N_2\Phi_{12}}{I_1} = M_{21} = \frac{N_1\Phi_{21}}{I_2} \\
I(t) &= \frac{\mathcal{E}}{R} e^{-\frac{R}{L}t} & I(t) &= \frac{\mathcal{E}}{R} (1 - e^{-\frac{R}{L}t}) & Q &= Q_{max} e^{-\frac{R}{2L}t} \cos \omega_d t & \omega_d &= \sqrt{\frac{1}{LC} - (\frac{R}{2L})^2} \\
I_{rms} &= \frac{I_{max}}{\sqrt{2}} & P_{avg} &= I_{rms}^2 R
\end{aligned}$$

Part 4: Mathematics

Algebra

$$a^m \times a^n = a^{m+n} \quad (a^m)^n = a^{mn} \quad x_{1,2} = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a} \text{ where } ax^2 + bx + c = 0$$

Trigonometric Identities

$$\begin{aligned}
\tan A &= \sin A / \cos A & \sec A &= 1 / \cos A & \operatorname{cosec} A &= 1 / \sin A & \cot A &= \cos A / \sin A = 1 / \tan A \\
\sin^2 A + \cos^2 A &= 1 & \sec^2 A &= 1 + \tan^2 A & \operatorname{cosec}^2 A &= 1 + \cot^2 A
\end{aligned}$$

$$\frac{a}{\sin \alpha} = \frac{b}{\sin \beta} = \frac{c}{\sin \gamma} \quad \& \quad c^2 = a^2 + b^2 - 2ab \cos \gamma \quad \text{where } \alpha + \beta + \gamma = 180^\circ$$

Derivatives / Integrals (An arbitrary constant should be added to each integral)

$$\begin{aligned}
\frac{d}{dx}(ax^n) &= anx^{n-1} & \frac{d}{dx}(e^{ax}) &= ae^{ax} \\
\frac{d}{dx}(\sin kx) &= k \cos kx & \frac{d}{dx}(\cos kx) &= -k \sin kx & \frac{d}{dx}(\tan kx) &= k \sec^2 kx \\
\int x^n dx &= \frac{x^{n+1}}{n+1} \quad (n \neq -1) & \int \frac{dx}{x} &= \ln x & \int \frac{dx}{a+x} &= \ln(a+x) & \int \frac{xdx}{a+x} &= x - a \ln(a+x) \\
\int \frac{dx}{\sqrt{x^2 \pm a^2}} &= \ln \left(x + \sqrt{x^2 \pm a^2} \right) & \int \frac{xdx}{\sqrt{x^2 \pm a^2}} &= \sqrt{x^2 \pm a^2} \\
\int \frac{dx}{(x^2 \pm a^2)^{3/2}} &= \frac{\pm x}{a^2 \sqrt{x^2 \pm a^2}} & \int \frac{xdx}{(x^2 \pm a^2)^{3/2}} &= \frac{-1}{\sqrt{x^2 \pm a^2}}
\end{aligned}$$