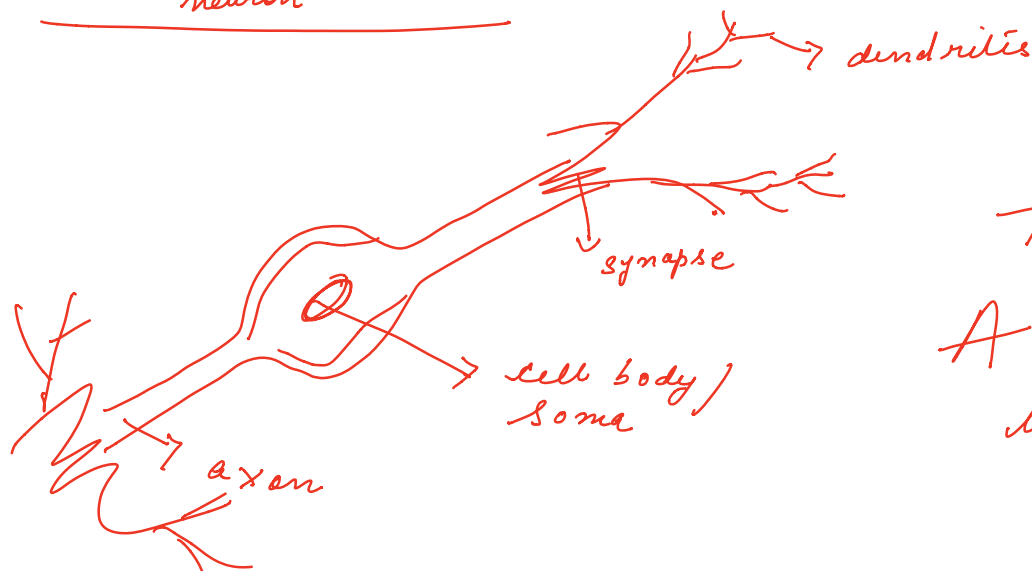


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## Introduction to Neural Networks

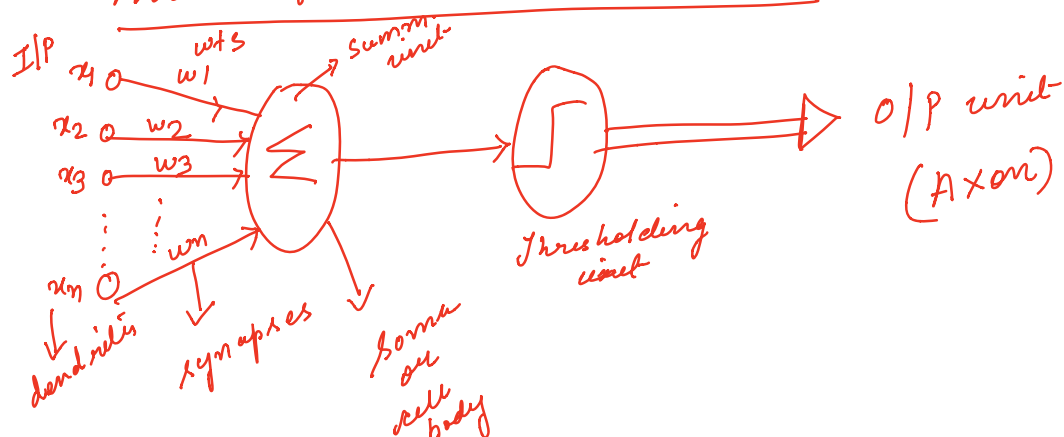
- ✓ Introdn. to NN
- ✓ standard activation functions
- ✓ NN architectures
- ✓ learning paradigms.

### Model of a biological neuron :



A  
A  
A

### Model of an artificial neuron :



$x_1, x_2, \dots, x_n$  are  $n$  inputs to artificial neuron  
 $w_1, w_2, \dots, w_n$  are weights attached to input links

$$I = w_1 x_1 + w_2 x_2 + \dots + w_n x_n$$

$$= \sum_{i=1}^n w_i x_i$$

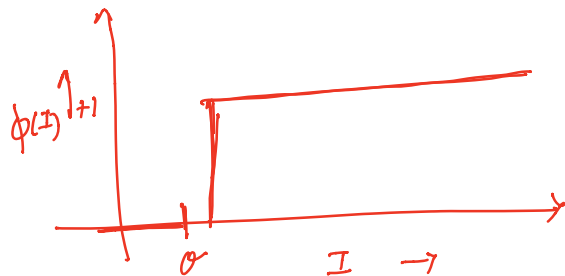
$$\boxed{Y = \phi(I)}$$

To generate the final o/p  $Y$ , the sum is passed to a non-linear filter  $\phi$  which releases the o/p.

Standard activation functions :

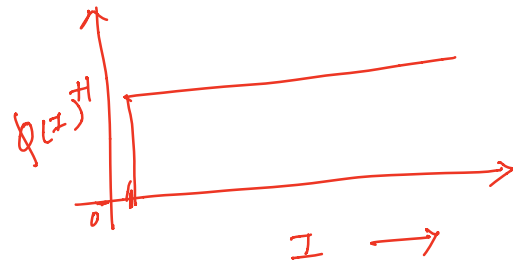
1. Thresholding function :

if  $I > 0$  then  $Y = 1$   
else  $Y = 0$



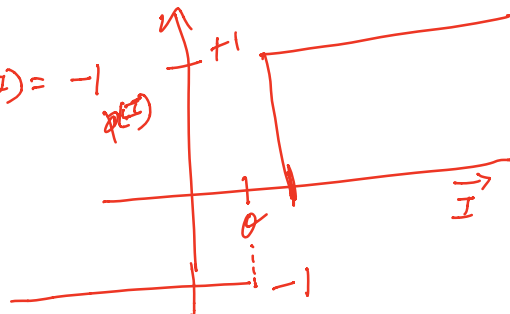
2. Heaviside function :

if  $I > 0$ , then  $\phi(I) = 1$   
else  $\phi(I) = 0$



3. Signum function :

if  $I > 0$  then  $\phi(I) = +1$   
else (if  $I \leq 0$ ) then  $\phi(I) = -1$



v.imp  
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Sigmoidal function :

$$\phi(I) = \frac{1}{1 + e^{-\lambda I}}$$

$\lambda \rightarrow$  sigmoidal gain

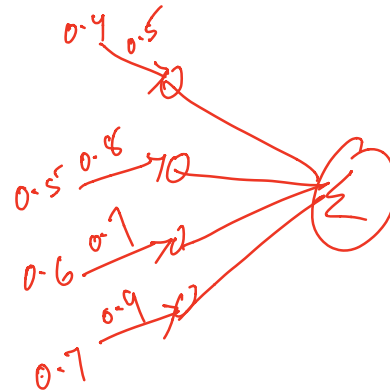
\* sigmoidal functions are differentiable -

57 Hyperbolic tangent function:

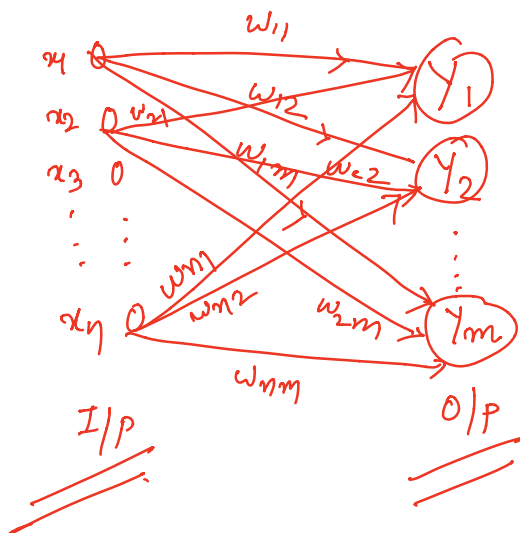
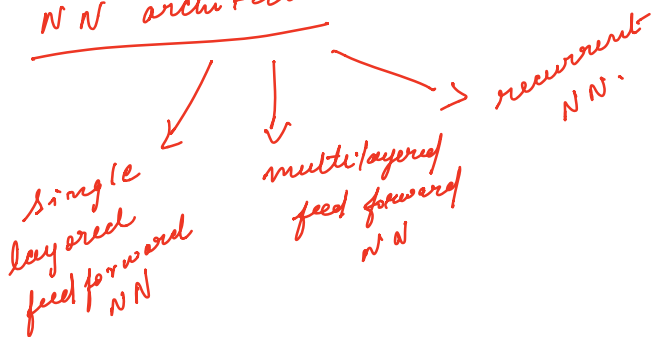
$$\boxed{f(I) = \tanh(I)}$$

which can produce negative o/p values.

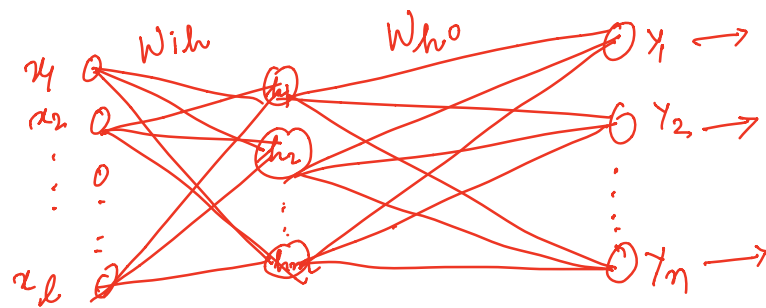
$$\begin{matrix} f_1 & f_2 & f_3 & f_4 \\ \langle 0.4 & 0.5 & 0.6 & 0.7 \rangle \end{matrix}$$



NN architectures:



2) multilayered FFNN :



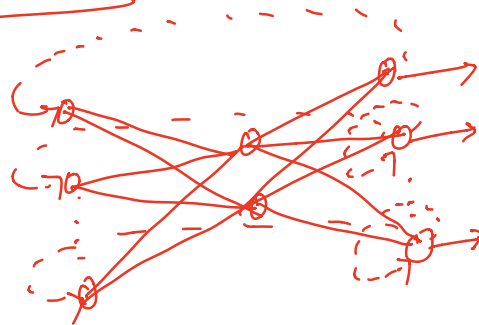
$l \times m \times n$

$c1 \rightarrow \begin{bmatrix} 1 & 0 & 0 \end{bmatrix}$

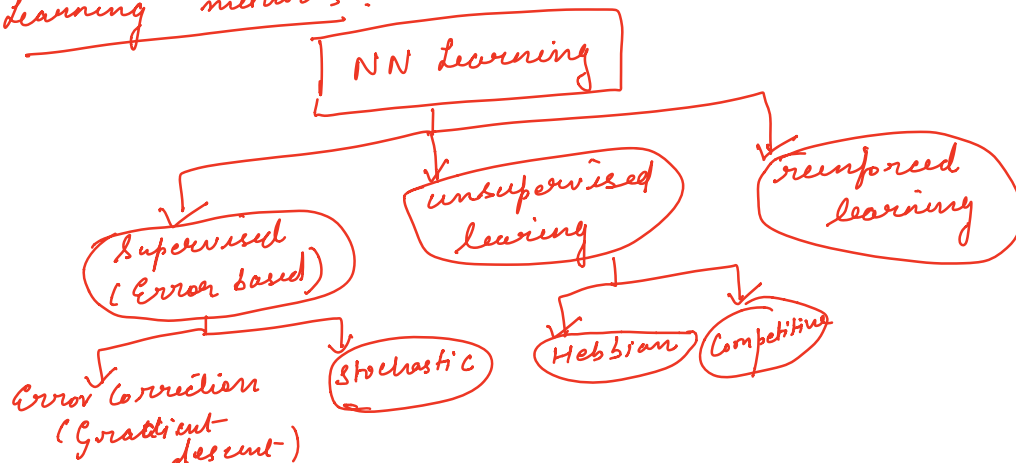
$c2 \rightarrow \begin{bmatrix} 0 & 1 & 0 \end{bmatrix}$

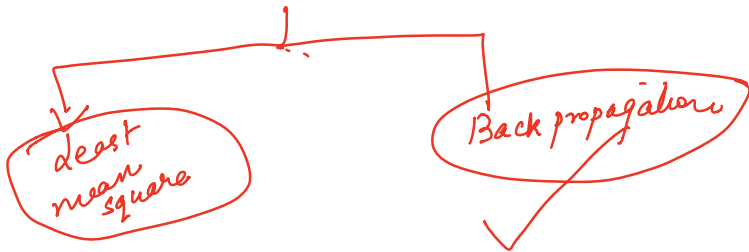
$c3 \rightarrow \begin{bmatrix} 0 & 0 & 1 \end{bmatrix}$

3) Recurrent NN :



Learning methods :





$\langle \text{I/P} \rangle \dots \dots \langle \text{Target} \rangle$   
o/p label

$$\frac{\partial E}{\partial w}$$

$\odot(0) \longleftrightarrow \odot(T)$   
 $(T - 0)^2 = \text{Err}$

