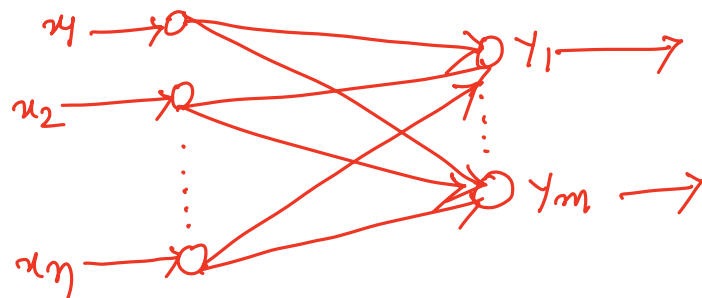


dec-04  
24/08/21

→ Perception model  
→ Adaline model

Perceptron:



- The perceptron is a computational model of the retina of the eye and hence it is named as "perceptron".
- The network comes under single layer feed forward network and are named as simple perceptrons.

Perceptron learning algo:

Step 1: Initialize all wts  $w_0, w_1, \dots, w_n$ .

2: Set the learning rate  $\eta$  s.t.  $0 < \eta < 1$  and threshold  $\theta$ .

3: for each training pair  $s: t$  do steps 4-8.

4: activate the input units  $x_i = s_i$ , for  $i=0, \dots, n$

5: Compute the net input to the output unit

$$y_{in} = \sum_{i=0}^n w_i x_i$$

6. Compute the activation of the o/p unit using the function:

$$y_{out} = \begin{cases} 1 & \text{if } y_{in} > \theta \\ 0 & \text{if } -\theta \leq y_{in} \leq \theta \\ -1 & \text{if } y_{in} < -\theta \end{cases} \checkmark$$

7. If there is an error i.e.  $Y_{out} \neq T$ , then adjust the weight as follows:

$$w_i(\text{new}) = w_i(\text{old}) + \eta \times e \times x_i$$

$$b(\text{new}) = b(\text{old}) + \eta \times e$$

If however, no error has occurred, the wts. are kept unchanged.

8. If there is no error i.e.  $Y_{out} = T$ , for the entire set of training pairs then stop else goto step 2.

$w_1 = 0 + 1 \times 1 \times 1$   
 $0 + 0 \times 1 \times 1$   
 (Assume  $\eta = 0.2$ )

Numerical:

no $x_1$ $x_2$ $x_3$				$Y_{in}$ Net I/P	Net o/p $Y_{out}$	Target	wts. $w_0, w_1, w_2, w_3$
<del>1</del>	<del>1</del>	<del>1</del>	<del>1</del>	0	<del>0</del> ✓	<del>1</del> ✓	<del>0 0 0 0</del>
1	-1	1	1	2	1 ✓	-1 ✓	0 2 0 0
1	1	-1	1	2	0 ✓	-1 ✓	-1 1 1 -1
1	1	1	-1	2	0 ✓	-1 ✓	<del>(-2 0 0 0)</del>

term 01  
 $w_0 = 0 + 1 \times 1 \times 1$   
 $w_1 = 0 + 1 \times 1 \times 1$   
 $w_2 = 0 + 1 \times 1 \times 1$   
 $w_3 = 0 + 1 \times 1 \times 1$

term 02  
 $Err\ 01 = (Y_{out} - T)^2 = 1$   
 $02 = (1 - (-1))^2 = 4$   
 $03 = (1 - (-1))^2 = 4$   
 $04 = (1 - (-1))^2 = 4$

$$M \cdot \text{S.E} = \frac{1 + 4 + 4 + 4}{4}$$

$$= \frac{13}{4}$$

After 1st Epoch:

$$R.M.S.E = \sqrt{13/4} = 1.8$$

$$rmse < 0.01$$

→ The input vectors are allowed to be either binary / or bipolar. However, the o/p must be in bipolar form.

→ The bias wt.  $w_0$  is adjustable but the threshold  $\theta$  used in the activation function is fixed.

Adaline : (Adaptive linear neural element network)

[By Bernard Widrow of Stanford Univ.]

→ Here there is only one o/p neuron and the o/p are bipolar (-1 or +1).

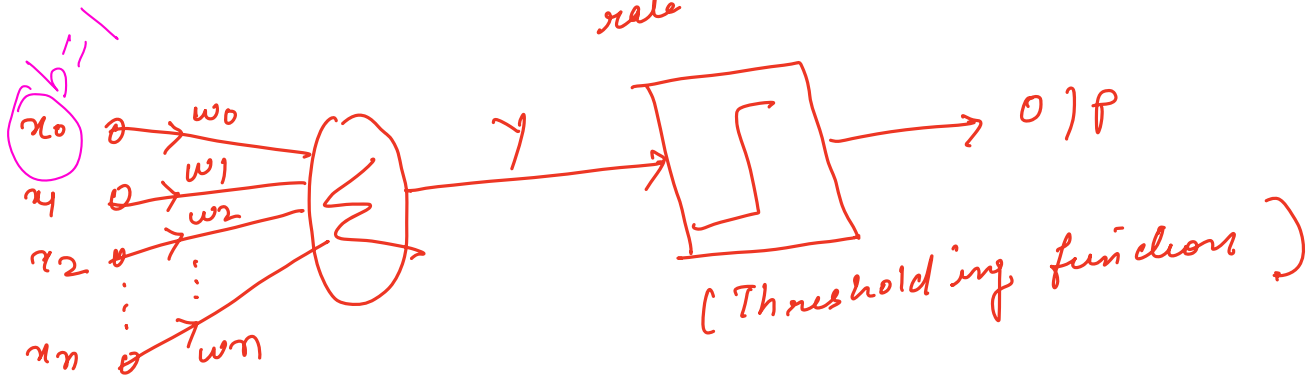
→ The i/p could be binary, bipolar or real valued.

→ If the weighted sum of inputs is greater than or equal to 0, then O/P is +1 else -1.

→ Devised by Andrew Hoff [1960] and the learning algo. is known as Least Mean Square (LMS) or Delta rule :

$$w_i(\text{new}) = w_i(\text{old}) + \alpha (t - y) x_i \rightarrow \text{I/P}$$

$\swarrow$  learning rate       $\swarrow$  Target       $\swarrow$  computed O/P



Adaline Learning algo:

Step 1: Set wt. and bias wt. to some random values but not zero. Set the learning parameter  $\alpha$ .

2: Perform step 3-7 till the stopping criteria is met.

3: Perform step 4-6 for each bipolar training pair  $L: L^-$  :

4: Set activation for i/p unit  $i = 1$  to  $n$   
 $x_i = L_i$

5: Calculate the net i/p to the o/p unit

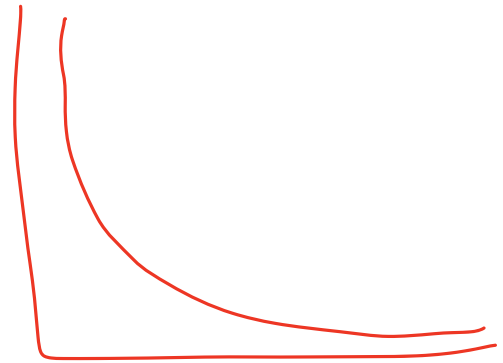
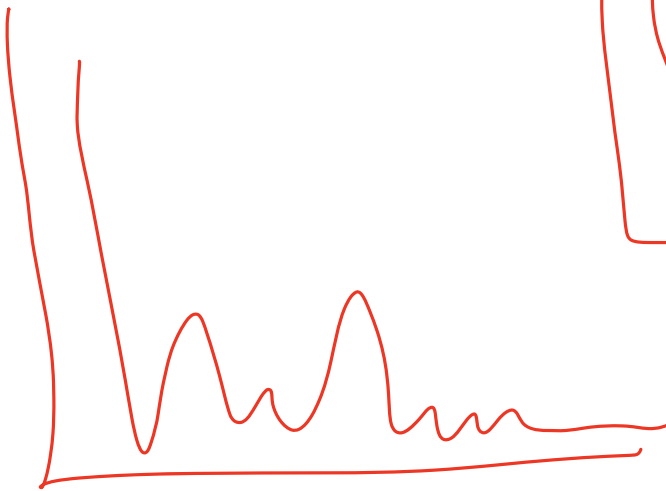
$$y_{in} = b + \sum_{i=1}^n w_i x_i$$

6: update the wt. and bias for  $i=1$  to  $n$

$$w_i(\text{new}) = w_i(\text{old}) + \alpha (t - y_{in}) x_i$$

$$b(\text{new}) = b(\text{old}) + \alpha (t - y_{in})$$

7. If the highest wt. change that occurred during training is smaller than a specified tolerance, then stop the training process else continue.



Stopping criteria

1)  $t \rightarrow w$   
 $t+1 \rightarrow w'$

$w - w' \leq \epsilon$

2

$r_{mse} \leq 0.001$

3

~~Epochs  $\leq 500$~~

OR

OR