## Chapter 7: Supervised Hebbian Learning

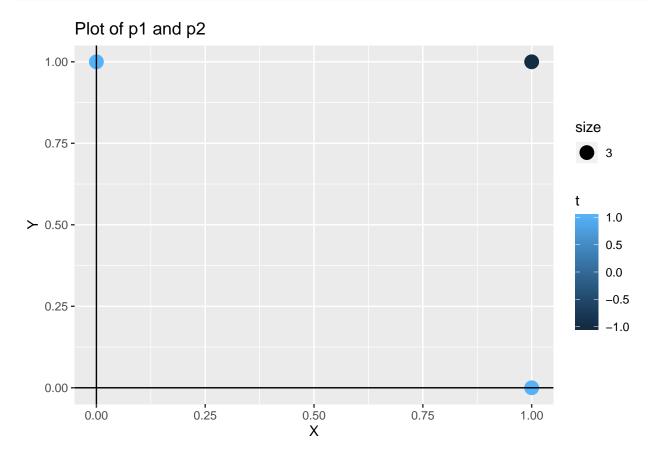
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## E7.6

1

We can see from the plot below of the three input vectors colored by their expected  $t_i$  value, no linear discriminator centered about the origin can classify these two groups. Therefore, a y-intercept, bias, is needed to classify these two groups.

```
library(ggplot2)
data = data.frame(v1=c(1, 1, 0), v2=c(0, 1, 1), t=c(1, -1, 1))
ggplot(data=data, aes(x=v1, y=v2, color=t)) + geom_point(aes(size = 3))+xlab("X")+
   ylab("Y")+ggtitle("Plot of p1 and p2")+geom_hline(yintercept=0)+
   geom_vline(xintercept=0)
```



 $\mathbf{2}$ 

We can include bias into our calculations of the pseudoinverse rule by use of augmented vectors, i.e., including it as an extra term. Now,  $p_1^t = [1, 0, 1]$ ,  $p_2^t = [1, 1, 1]$ , and  $p_3^t = [0, 1, 1]$ .

```
T = matrix(c(1, -1, 1), ncol=3)
p1 = matrix(c(1, 0, 1), ncol=1)
p2 = matrix(c(1, 1, 1), ncol=1)
p3 = matrix(c(0, 1, 1), ncol=1)
P = matrix(c(p1, p2, p3), ncol=3)
P
```

```
## [,1] [,2] [,3]
## [1,] 1 1 0
## [2,] 0 1 1
## [3,] 1 1 1
```

Now, we can use the pseudoinverse rule  $W = TP^+$ ; however, because the number of rows for P is less than the number of columns, before augmenting,  $P^+ = P^t(PP^t)^{-1}$ 

Then,  $P^+$  becomes:

```
pseudo = t(P)%*%solve(P%*%t(P))
pseudo
```

```
## [,1] [,2] [,3]
## [1,] 0 -1.000000e+00 1
## [2,] 1 1.000000e+00 -1
## [3,] -1 2.220446e-16 1
```

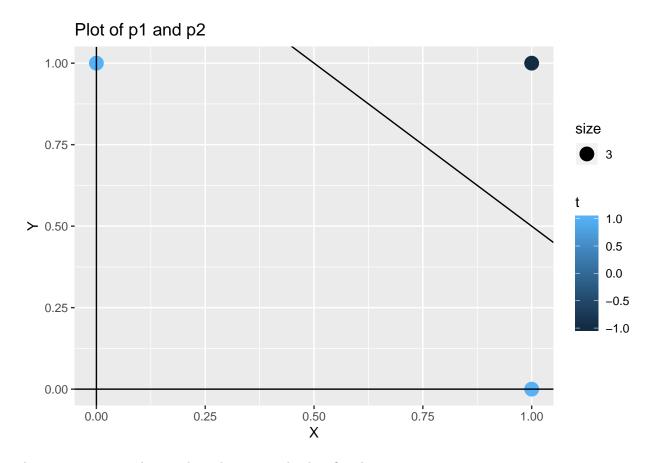
Now our weight matrix can be calculated:

```
W=T%*%(pseudo)
W
```

```
## [,1] [,2] [,3]
## [1,] -2 -2 3
```

From these we get the following decision boundary:  $-2p_1 - 2p_2 + 3 = 0$ , from Wp + b = 0. Therefore,  $p_2 = \frac{3}{2} - p_1$ .

```
ggplot(data=data, aes(x=v1, y=v2, color=t)) + geom_point(aes(size = 3))+xlab("X")+
   ylab("Y")+ggtitle("Plot of p1 and p2")+geom_hline(yintercept=0)+
   geom_vline(xintercept=0)+geom_abline(intercept=1.5, slope=-1)
```



As one can see, our decision boundary correctly classifies the two groups.

## Side Note

## [1,]

-2

I find it interesting how this question makes us use the pseudoinverse rule to design the network when the augmented P matrix is square and independent, therefore  $P^{-1}$  exists. If one were to use  $W = TP^{-1}$  instead to train the weights:

```
W=T%*%solve(P)
W
## [,1] [,2] [,3]
```

Which is the same as created from the pseudoinverse rule, therefore the same boundary will be created.