

## **Multi-material upgrade on any printer: BUILD GUIDE**

The aim of this project is to popularize multi-material 3d printing by making a more reliable, cheaper, and hopefully better multi-material upgrade based on the MMU2 from Prusa. There is still a lot of work to do but this is prototype that works well enough to be considered as viable.

### **Before you attempt to build this:**

This guide is currently meant for more advanced user, comfortable with Marlin configuration and with a bit of programming experience. The models may still need work and are not final. You will need to do a lot of tuning before you get everything going, parts modification may be required, and you will almost certainly need to do some troubleshooting. If you think this is too much for you do not worry, I will be releasing a tutorial that goes way more in depth and should be easier to follow, the models shown and provided in this video will be tested on multiple printers and the risk of something not working will be reduced by a lot. If you are still reading this and want to build this for yourself, I highly recommend you join the discord server. There is a help channel in there specifically to answer any questions or issues you have while building the MMU.

There are also a few things to now before deciding to build this upgrade. I don't take any responsibility regarding your actions, this is still a prototype and requires heavy modifications of your printer which is a risk that you should be willing to take if attempting this build.

There will also be improvements that may require extra parts, you should be easily able to transition from this version to the newer ones, but this will add extra costs.

Lastly, this is not perfect, and your printer may not work as well as before so you should make sure that you can afford having your printer out of commission and keep a copy of the firmware for single filament on hand (you will work on it later in this guide) so that you can transition back to the original state in order to print improved parts or to fix models that may not be working correctly.

### **Parts required**

All the following links may be affiliate links (mostly the amazon ones) and I may earn money if a purchase is made using those links. All the profit will go directly back in this project. The price mentioned is only to give you an idea as they may fluctuate. The ones mentioned are the lowest ones I could find including shipping to NA at the date of writing this.

Products in green are the ones that I consider as necessary to buy specifically for this build and in red the ones that you may need to buy but that come in big packs and that you will most likely use(let's say that you need only 15 screws for this build and we are not going to count the 700 screws in the pack in the final price)and that you probably already have like M3 bolts and nuts. The red items will be allocated a very small budget but won't be included completely in the final price calculations.

Part name	Picture	Links	Pcs in pack	Pcs needed	Price \$
608 ball bearings		<a href="https://amzn.to/35gdeBc">https://amzn.to/35gdeBc</a> <a href="https://amzn.to/3olusVk">https://amzn.to/3olusVk</a> <a href="https://amzn.to/3hQoNny">https://amzn.to/3hQoNny</a> <a href="https://aliexpi.com/Ep3X">https://aliexpi.com/Ep3X</a>	20 20 10 10	6	5.17 \$
Heated inserts M3		<a href="https://amzn.to/3pVMlou">https://amzn.to/3pVMlou</a> <a href="https://amzn.to/3bfT7qr">https://amzn.to/3bfT7qr</a> (better choice)	20 420	4	10\$
M3 and M2 bolts and nuts		<a href="https://amzn.to/35dwXSc">https://amzn.to/35dwXSc</a>	700	≈20	20\$
PTFE tubing PC4-M10 PC4-M6		<a href="https://amzn.to/3nBpF0Z">https://amzn.to/3nBpF0Z</a>  this kit includes everything you will need and is the best value	4m 8 pcs 8 pcs	2m 6 pcs 5pcs	10\$
5mm to 5mm coupler		<a href="https://amzn.to/35pzHf7">https://amzn.to/35pzHf7</a> <a href="https://amzn.to/3otoqSL">https://amzn.to/3otoqSL</a>	2 2	1	7\$
Metal rod 5mmx80m m(a little longer won't cause any problems)		<a href="https://amzn.to/2JYjWEt">https://amzn.to/2JYjWEt</a> <a href="https://amzn.to/2JYjWEt">https://amzn.to/2JYjWEt</a>	5 2	2 2	12\$
MK8 gears with filament groove		<a href="https://amzn.to/3noCCuF">https://amzn.to/3noCCuF</a>	5	5	8\$

Nema 17 stepper motor		<a href="https://amzn.to/3osSZbb">https://amzn.to/3osSZbb</a>	1	1	14\$
Endstops		<a href="https://amzn.to/3hWqekq">https://amzn.to/3hWqekq</a>	10	1	8
Idler spring		<a href="https://shop.prusa3d.com/en/spare-parts/599-idler-spring.html">https://shop.prusa3d.com/en/spare-parts/599-idler-spring.html</a> <a href="https://www.voxelfactory.com/collections/original-prusa-i3-mk2-mk2s-parts/products/replacement-tension-spring-for-prusa-i3-mk2s-or-mk3">https://www.voxelfactory.com/collections/original-prusa-i3-mk2-mk2s-parts/products/replacement-tension-spring-for-prusa-i3-mk2s-or-mk3</a>	1	2	4-8\$
Total:					78\$

## Prebuild checks

Before trying to build this upgrade, you should have a fully working printer, with a compatible mainboard (check below), with Marlin configured properly for a single extruder. You should get the Marlin source code from my GitHub repo: <https://github.com/PierreMasselot1/MMU2-on-any-printer> (I will create a proper fork in the future and create a pull request so that we may have this upgrade in the actual official release of Marlin, but in order to do that I need to be at a more final and stable stage of development). Once you have Marlin configured for your printer before upgrading to the MMU keep a copy in a known location so that you can easily transition back to stock if the upgrade were to fail. After that, download the latest version of PrusaSlicer and follow this guide (<https://www.youtube.com/watch?v=Wz2Soog4HkQ&t=245s>) on how to set everything up for your printer in a single extruder mode. Once all of that is done download the latest files from my GitHub and start printing them using the methods and settings mentioned below. Check that you also have all the components and tools required.

## Motherboard compatibility

Your motherboard will need to have 5 dedicated stepper motor control (and in case of a dual Z make sure that your printer is using a splitter internally, meaning that you have 6 motor plugs available or use a splitter for your Z axis : <https://amzn.to/35fcFaS> or <https://amzn.to/2L60ard> ).

Once you have checked that your motherboard supports enough motor controls make sure that you have a way to access to at least two I/O pins: one for the endstop and one for the magnetic rotary encoder (will most likely be an AS5600 in I2C mode) that I am working on. You should also have some access to VCC and ground but even if there are no extra dedicated pins you could easily use one from any of the endstops. You will also need to make sure that you have access to 3.3V (or be ready to convert 5 to 3.3) but as I said your endstops may already have this available. If you have endstop pins for X,Y and Z max you should be good to go.

We are currently working with Paul Lewis to replace/ give the option to have a servo motor controlling the idler instead of a servo motor. This means that we will eventually need only 4 stepper motor control and a servo port (you will need a single free pin and some ways to get your servo connected to vcc and ground).

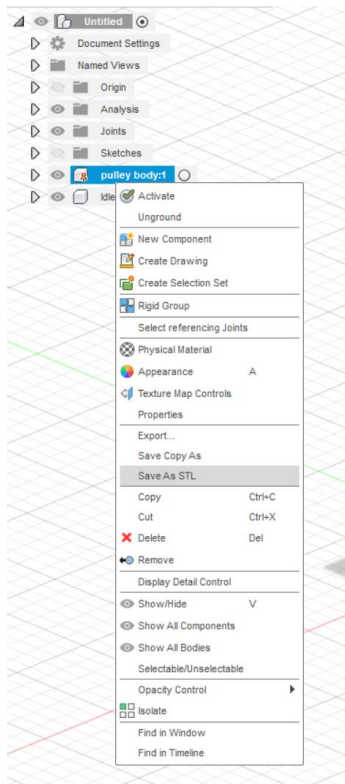
Mother board with extra endstops connector and easily accessible expansion pins will be the easiest to work with since less tweaking will have to be done to the Pins file of your specific board. If by any chance you were to modify something to fit your setup and think that it could be useful to other people, make sure to let me know and maybe do a pull request.

## Printing

Since we are currently working on the 3d files constantly, you will need to download the original files from GitHub and then convert them into an stl file in order to be able to print them.

### Idler body, pulley body and merger:

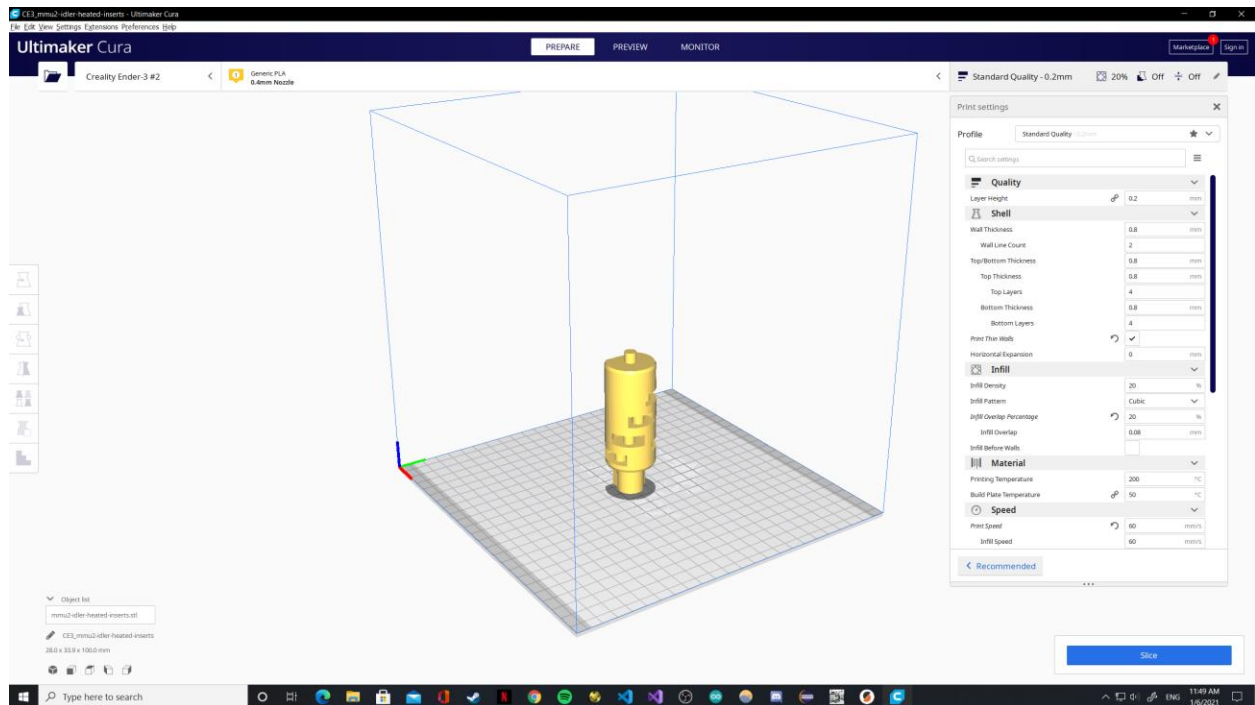
All of those files +**the idler** are in the F3D folder insider the parts folder. In order to convert them to stl you will need to download fusion 360(<https://www.autodesk.ca/en/products/fusion-360/personal> ) after doing all of the setup you will have to open each file, select the object you want to print by right clicking on it and using save as STL



The idler body and the pulley body are both in the same file and the merger is in a separate file. Once you have all of them converted to stl they are easy to print, they do not require any support and you can print them at a 0.2 mm layer height and 0.1mm layer height for the merger. Infill should be at least 20%.

## Idler

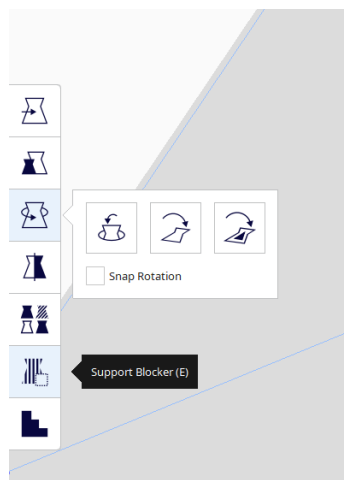
This model prints vertically as shown below:



Once the model is on the build plate you will need to use supports only touching build plate and add a support blocker in the center of the idler.

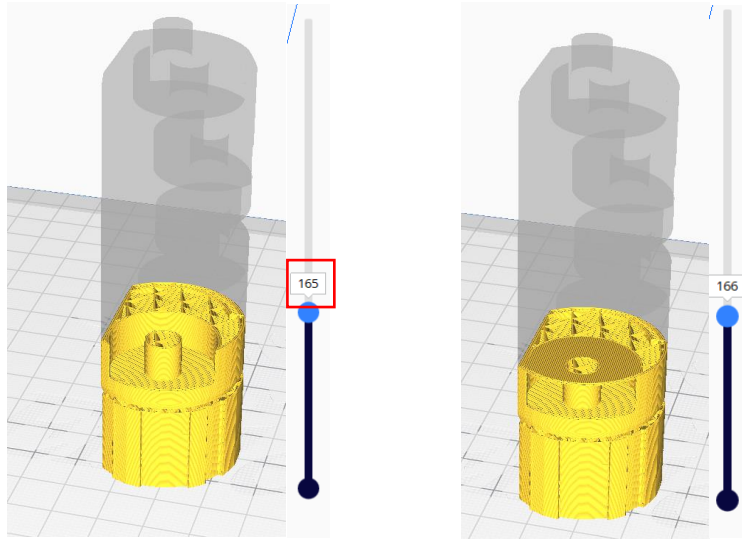


All of the settings that I am using can easily be found inside other slicers (PrusaSlicer shown below)



once you have selected support blocker you will need to click once at the center of the idler so that no support is printed inside the motor shaft mount. Slice the model using the layer height that you want to use (I personally used 0.2mm)

go into preview mode and use the slider to mark the last layer before closing the bearing enclosure as shown below

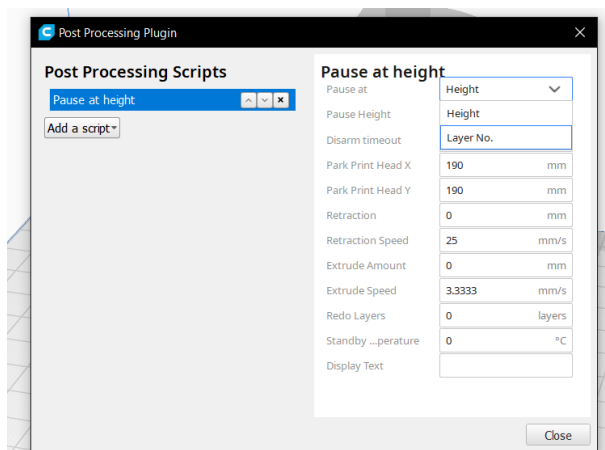


Use the arrow up and down to go up layer by layer.

Mark down this layer height for each bearing, you should have 5 values for the 5 bearings.

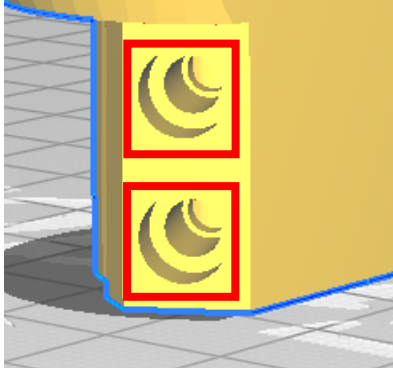
You then have to add a pause at layer line script for each of those values in cura go to extensions-> post processing-> modify gcode->add a script->pause at height.

From the drop-down menu select pause at layer No and change the pause layer to the first value that you took. Repeat with each value.



Reslice your model one last time and start the print, your printer should pause before closing a bearing enclosure and insert the 608 ball bearings before resuming the print.

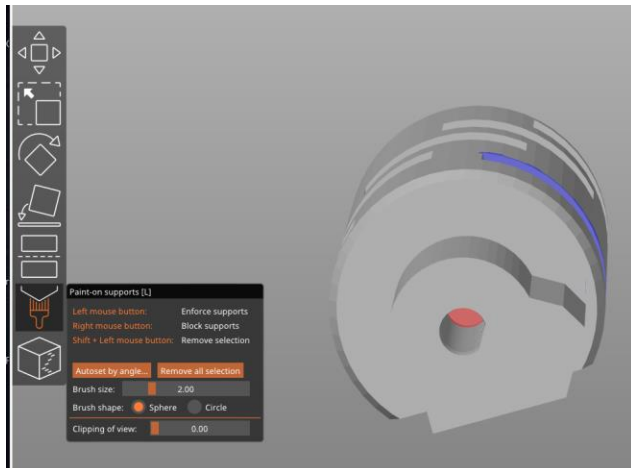
Once the print is completely done make sure that your bearings can spin freely and insert the heated inserts/embedded nuts into your print (heated inserts position and demo below)



You are now done with the idler.

### For PrusaSlicer

Use paint on supports to support the endstop slot and support blockers to prevent any supports from blocking the motor shaft.

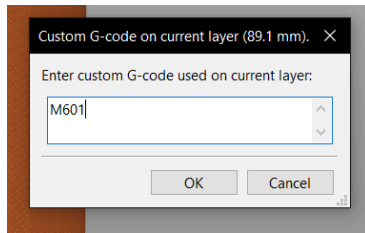


### Layer pause



Right click on the orange plus icon and insert pause print Gcode





The merger may require a bit of post processing since any stringing and print defects that happened inside the tube may jam the filament. First try to insert your ptfe tube in each dedicated slot and then put a filament through. If holes themselves seem to be tight for the filament you most likely have problems with horizontal expansion, so I recommend that you make use of the help channel on discord. If there seems to be a point where the filament gets jammed then make sure that your ptfe tube is cut straight and properly inserted, if it is the case try to put a bit of pressure on the filament or use a hard object to remove the jam. If there is some slight friction this is normal, and it will get better and better and the merger wears out.

### **Assembly:**

Assembly is relatively easy.

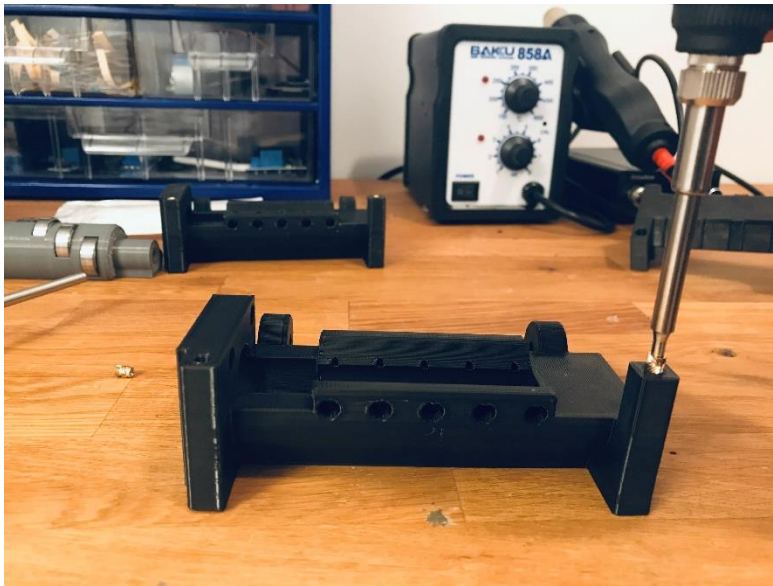
The first thing is to assemble the merger and check that it works properly as mentioned previously. It uses only PC4 M10 pneumatic couplers that you should be able to screw in by hand. You may need a bit more force for the end, but it should not take too much force otherwise you could strip the connectors and have to reprint the model.



You can now set the merger aside.



You will then need to setup your motor. Connect the motor and one of the 5mm metal rod. If you are using a flexible coupler, make sure that the two ends are touching to reduce flex to a maximum. Slide all the extruder gears onto the rod but do not tighten them too much yet: the screws used are really small and can be damaged easily and you will need to be further in assembly in order to align the gears properly.



The next parts that will need work are the pulley body and the idler. They both need heated inserts.

[idler picture todo still not reprinted]

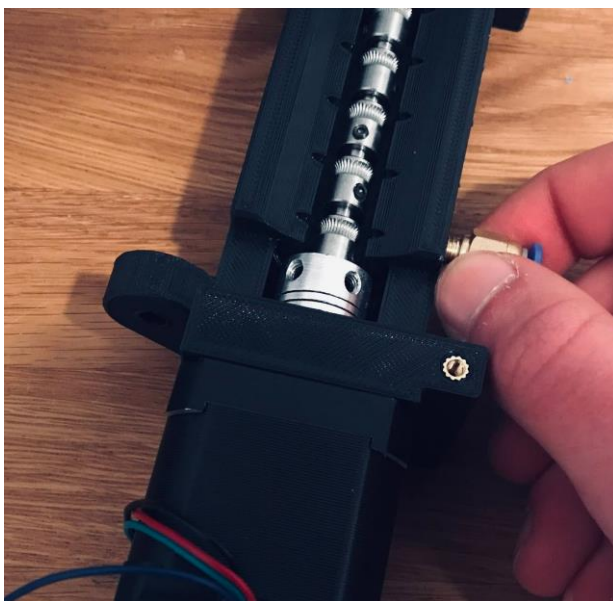
If you are not familiar with heated inserts here is a guide:

<https://hackaday.com/2019/02/28/threading-3d-printed-parts-how-to-use-heat-set-inserts/>

They are not that difficult to use just make sure to not heat up your part for too long.



You can then insert the motor and shaft assembly. Secure the motor using M3\*8 screws, if they don't align with the motor (by about 1mm) checkout the latest update of this model since the previous one didn't have the correct spacing (with a bit of work even that one worked just not perfectly). You can now align each of the gears with the filament slot corresponding and properly tighten them.



Attach each PC4-M6 couplers to the output of the MMU.



You then have to wire up the endstop for idler body, which you will then secure using M2\*12 screws and nuts. It should be facing inward towards the center of the idler



Place a bearing on the end of the idler and pass it through the motor hole of the idler body. You will then be able to press fit it in the dedicated slot.

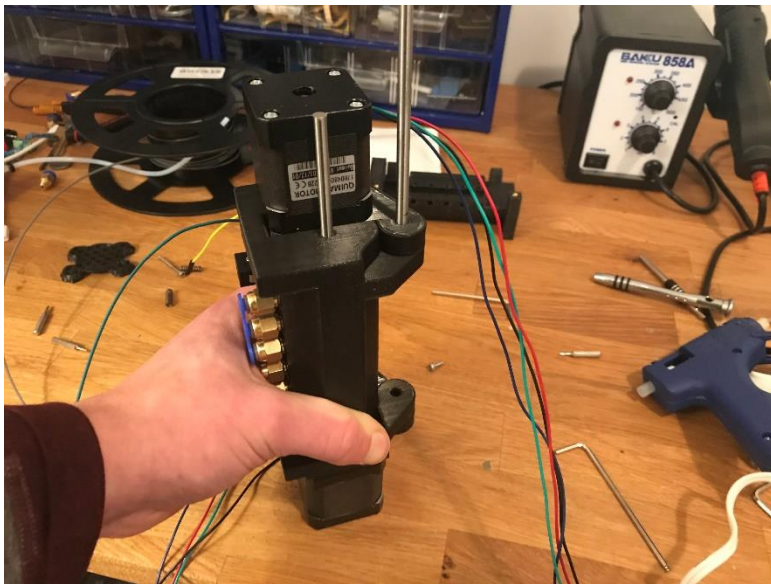




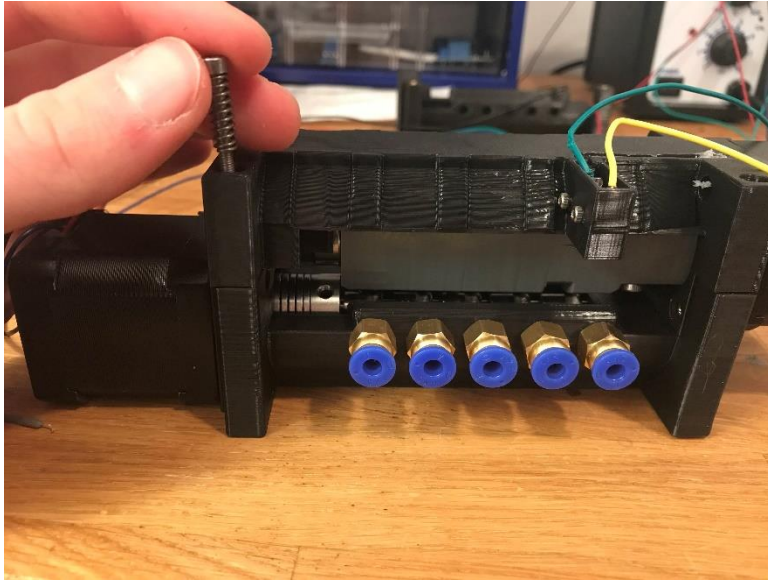
After this is done check that the idler can properly rotate and triggers the endstop properly.



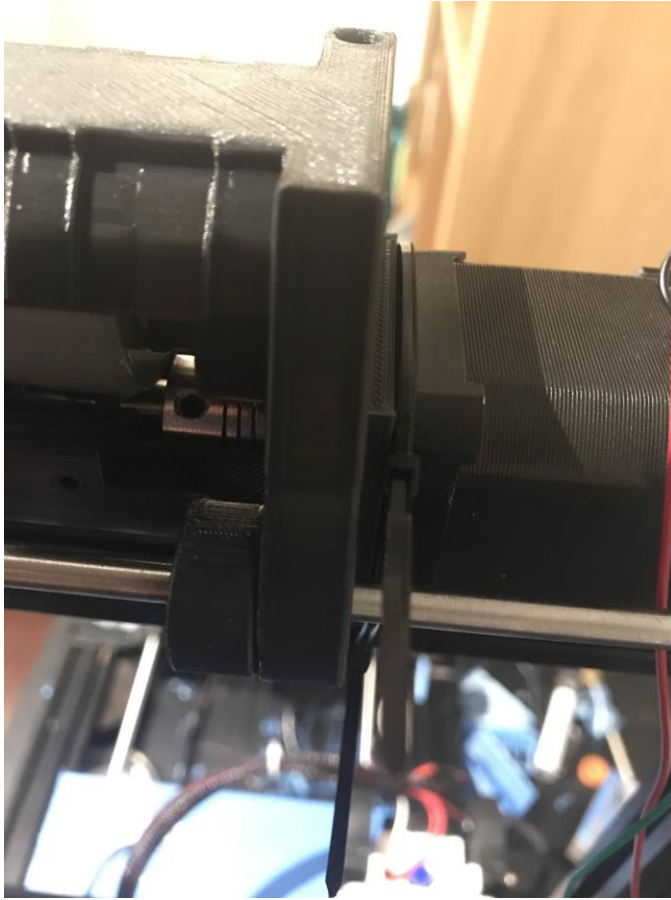
Assemble the idler body and pulley body as shown and insert the remaining metal rod through the dedicated holes.



The amount of force required to insert the rods may vary depending on your print settings but I still need feedback regarding clearances so if you have a well calibrated printer let me know whether the clearances are right or whether I need to increase them.



You can now insert the spring and the screws: M3x(from 25 mm up to 35 mm) in order to tension the idler. For now idler tension will be made through trial and error but a good indicator is when you are able to open idler slightly and that the springs push it back in a closed position. I will add visual indicators in a later model as well as find other springs.



You will then need to mount the MMU to your printer. A mount for aluminum extrusions will be designed shortly but you will have to improvise for now, either design your own or use zip ties.

You can then connect the merger to the nozzle. Try to have about 5 cm of space in between so that the filament changes can be as fast as possible but not below 4 cm so that the ptfе tube bend isn't too hard (potentially causing issues).

You can then connect each of the merger inputs to the MMU outputs making sure that the ptfе tubing is long enough to reach the extremities of the axis.

You are now done with the building process.



## Marlin configuration

This needs to be done **after** you have successfully configured Marlin for a single extruder setup (You may have seen that in the configuration file there is a default of 3 extruders, but this should not cause any problems when setting up your printer for a single nozzle. If it does you can switch it back to one but remember that you need to switch it back to 3 when configuring for the multi-material upgrade).

```
//MMU clone using two stepper motors, one for the filament selection
#define MMU_CLONE
#if ENABLED(MMU_CLONE)
  #define BOWDEN_TUBE //enable when working with the MMU as a bowden
  //#define DIRECT_DRIVE //enable to work in a direct drive setup

  #define MMU_EXTRUDER_PIN 0//define the MMU extruder motor pin
  #define MMU_IDLER_PIN 1 //define the extruder pin that the idler i
  #if ENABLED(DIRECT_DRIVE)
    #define EXTRUDER_PIN 2//define the extruder pin that the actual
  #endif
  #define ROTARY_ENCODER //rotary encoder for filament sensor
  #ifndef ROTARY_ENCODER
    #define ROTARY_ENCODER_PIN1 1//dummy value so that the compiler
    #define ROTARY_ENCODER_PIN2 1//dummy value so that the compiler
  #endif

  #define BOWDEN_TUBE_LENGTH 40//bowden tube length from the merger
#endif
```

This build guide is only for a bowden style setup but as you can see we will soon have support for direct drive. The Bowden tube length will vary depending on your setup but you should try to have it as short as possible since it will directly impact the filament change time

```

*/
#define PREVENT_COLD_EXTRUSION
#define EXTRUDE_MINTEMP 170

/**
 * Prevent a single extrusion longer than EXTRUDE_MAXLENGTH.
 * Note: For Bowden Extruders make this large enough to allow load/unload.
 */
#define PREVENT_LENGTHY_EXTRUDE
#define EXTRUDE_MAXLENGTH 200
//

```

Remember to set your extrude\_maxlength higher than your bowden tube length

```

642 // Specify here all the endstop connectors that are connected to any
643 // Almost all printers will be using one per axis. Probes will use one
644 // extra connectors. Leave undefined any used for non-endstop and no
645 #define USE_XMIN_PLUG
646 #define USE_YMIN_PLUG
647 #define USE_ZMIN_PLUG
648 #define USE_XMAX_PLUG
649 // #define USE_YMAX_PLUG
650 // #define USE_ZMAX_PLUG

```

You should then enable XMAX plug (uncomment it by removing the //) since this is what we are going to be using to home the idler. If your board does not have an XMAX endstop you can find a free IO pin and connect your endstop to that, but you will need to configure an XMAX endstop inside your board's pins file similarly to what is shown below. If you need help with that step reach out to me on the discord server.

```

#define X_MAX_PIN PE15 // E0

```

You may also need to invert the endstop logic depending on your board. If the idler doesn't home (considers the endstop as always triggered) this may be the problem. Usually this will be like your other endstops.

```

682 #define X_MAX_ENDSTOP_INVERTING true // Set to true to invert the logic

```

You will also need to define driver type for each motor

```

702  */
703  #define X_DRIVER_TYPE  A4988
704  #define Y_DRIVER_TYPE  A4988
705  #define Z_DRIVER_TYPE  A4988
706  //#define X2_DRIVER_TYPE A4988
707  //#define Y2_DRIVER_TYPE A4988
708  //#define Z2_DRIVER_TYPE A4988
709  //#define Z3_DRIVER_TYPE A4988
710  //#define Z4_DRIVER_TYPE A4988
711  #define E0_DRIVER_TYPE A4988
712  #define E1_DRIVER_TYPE A4988
713  #define E2_DRIVER_TYPE A4988
714  //#define E3_DRIVER_TYPE A4988
715  //#define E4_DRIVER_TYPE A4988
716  //#define E5_DRIVER_TYPE A4988
717  //#define E6_DRIVER_TYPE A4988
718  //#define E7_DRIVER_TYPE A4988
719

```

Similarly to your XYZ axis you can change the direction of the extruder stepper in order to match the expected behavior. If when homing the idler goes in the opposite direction you would change E1 dir to false(Or E x if you have setup custom extruder pins)

```

1117  // For direct drive extruder v9 set to true, for geared extruder set to false
1118  #define INVERT_E0_DIR true
1119  #define INVERT_E1_DIR true
1120  #define INVERT_E2_DIR true
1121  #define INVERT_E3_DIR false
1122  #define INVERT_E4_DIR false
1123  #define INVERT_E5_DIR false
1124  #define INVERT_E6_DIR false
1125  #define INVERT_E7_DIR false
1126

```

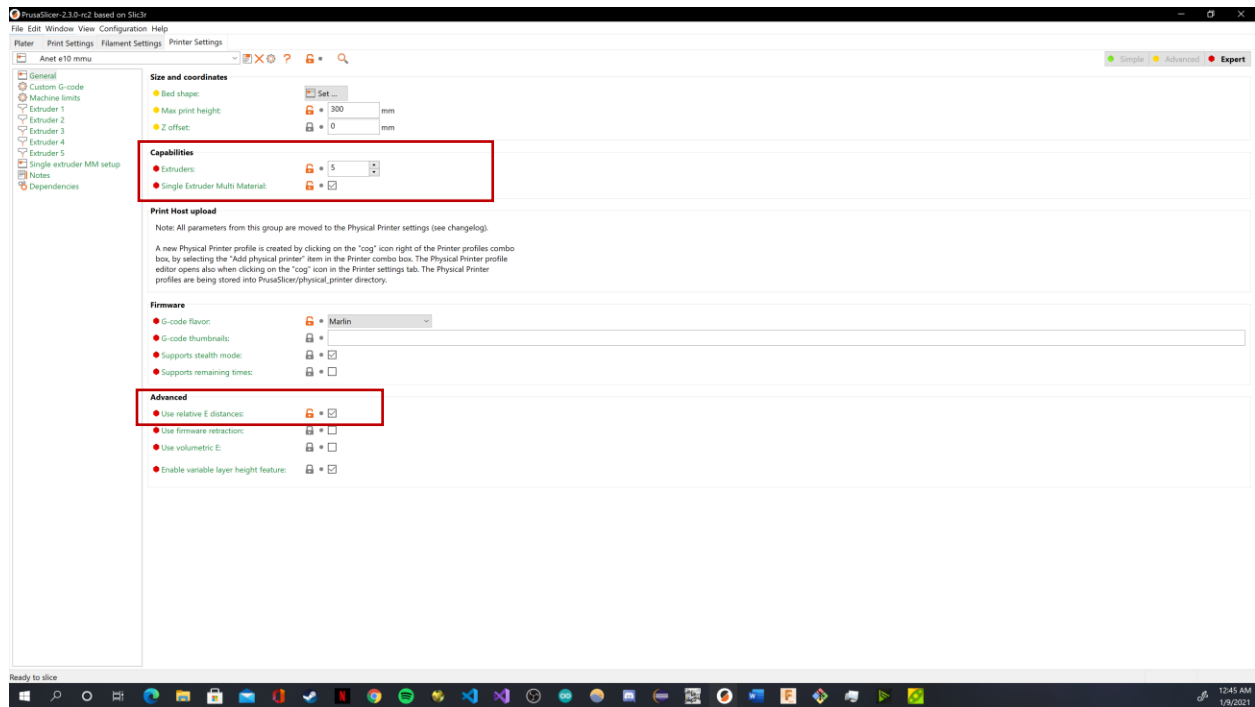
You are now done with the software modifications.

### Slicer settings.

You will now need to configure the slicer in order to adapt it to your printer.

You can use the same slicer profile that you were using or create a new one (recommended)

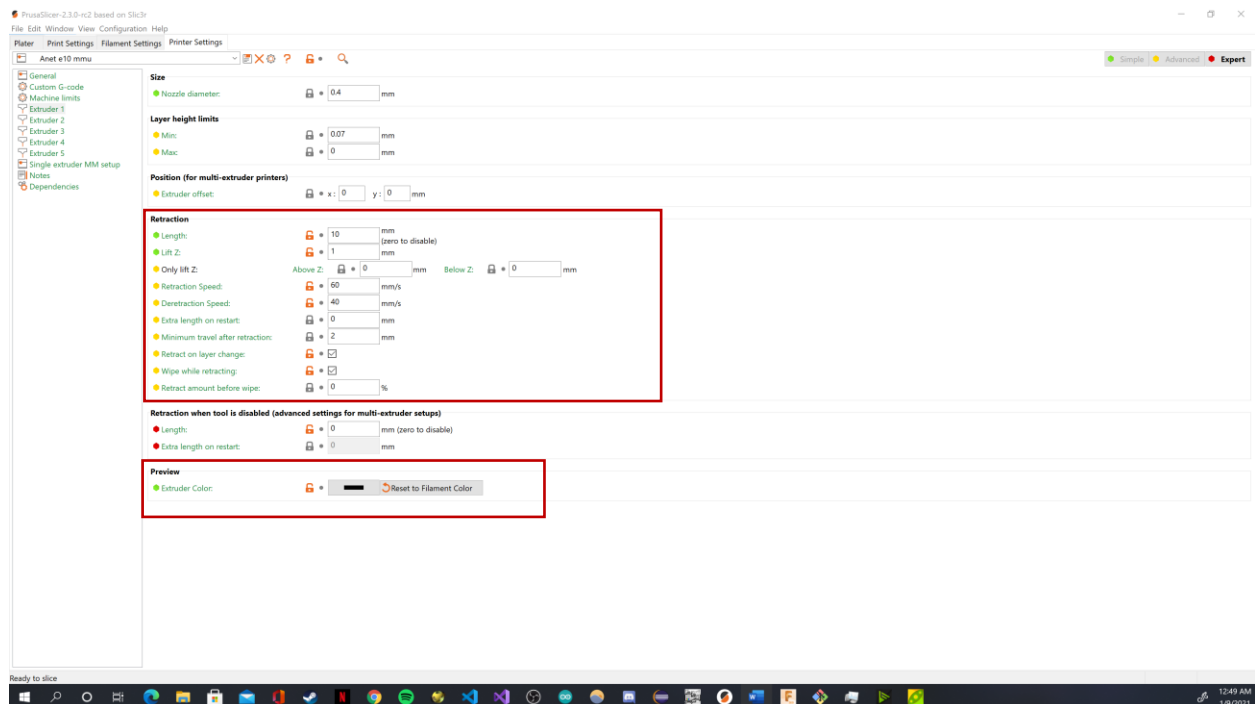
The first thing you will need to do is change the number of extruders to 3, in the printer settings tab and to check the single extruder multi material



You also need to use relative E distance

You should now have 5 extruders to work with.

In there you can change retraction settings (choose a setting similar to what you were using before) and also select the extruder color: extremely useful for multi-color prints.

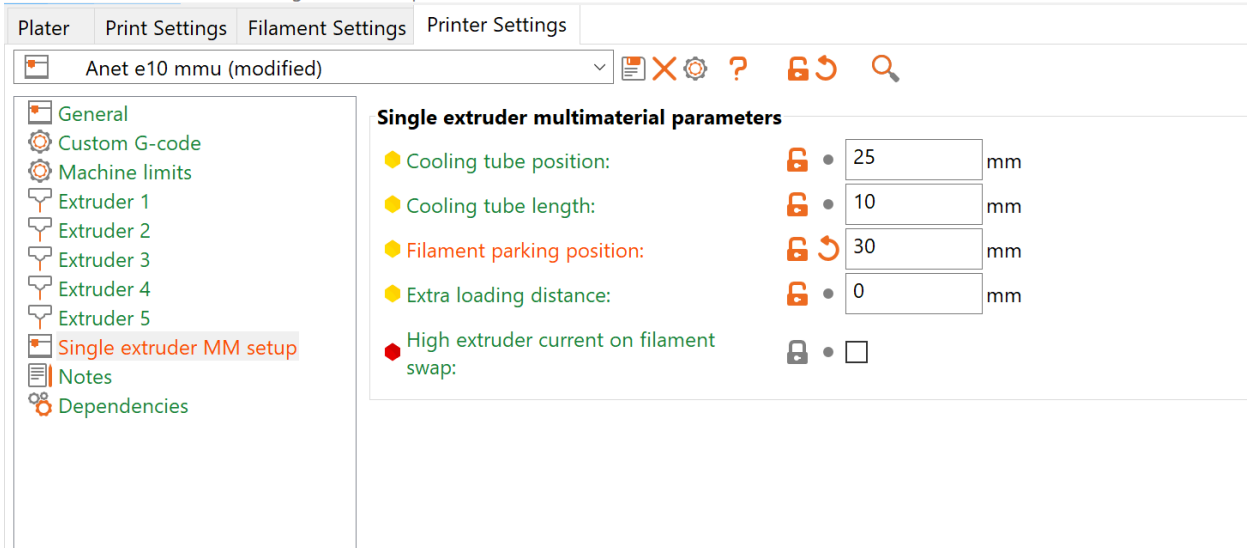


Now go to the single extruder multimaterial parameters(Single extruder MM setup)

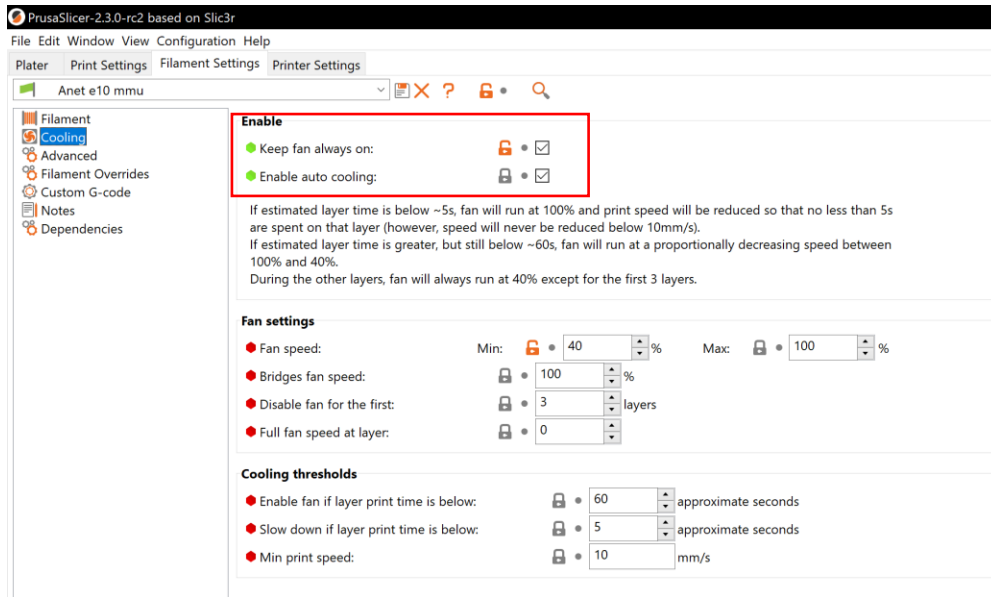
You will have four things to adjust. First off, the cooling tube position. In order to find it simply measure from your nozzle to the middle of the cooling block on your extruder. The cooling tube length will vary depending on your extruder but 10mm seems to be a good value for most extruders. The filament parking position should be the cooling tube position+ (the cooling tube length/2) since we are handling the unloading and reloading in Marlin (may not be as necessary right now but when working with less capable boards will enable us to make some really interesting stuff... more info on that later) the extra loading distance should be at 0 and be tweaked if you find that it doesn't start extruding exactly when restarting (this is irrelevant when using a wipe tower).

PrusaSlicer-2.3.0-rc2 based on Slic3r

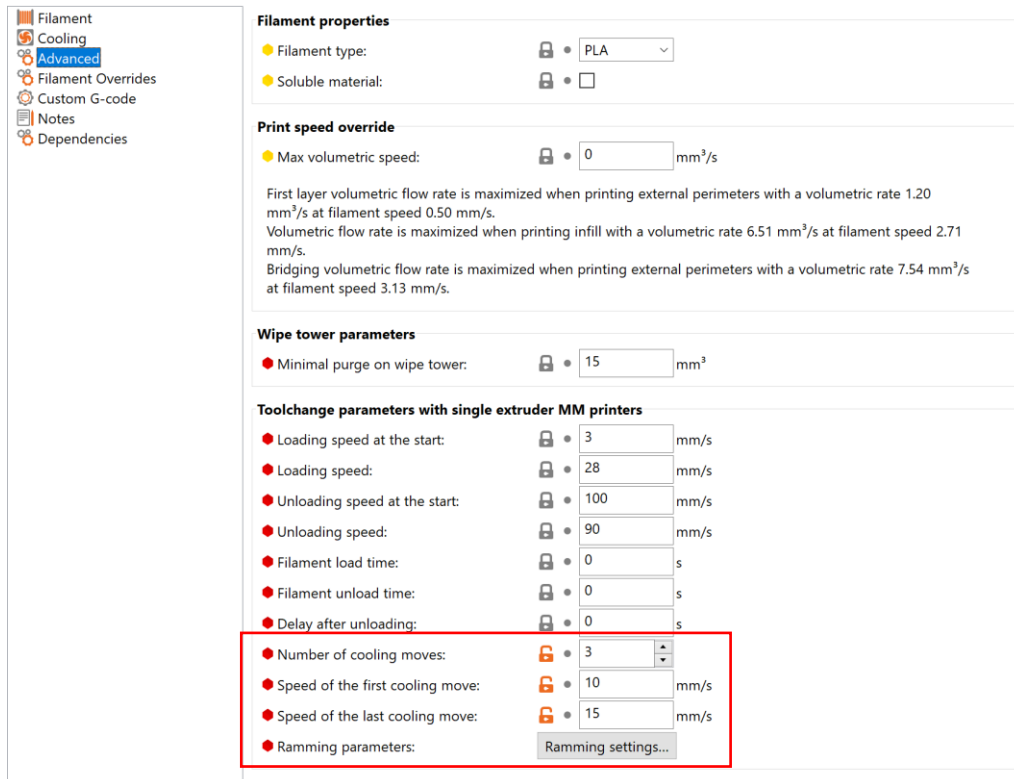
File Edit Window View Configuration Help



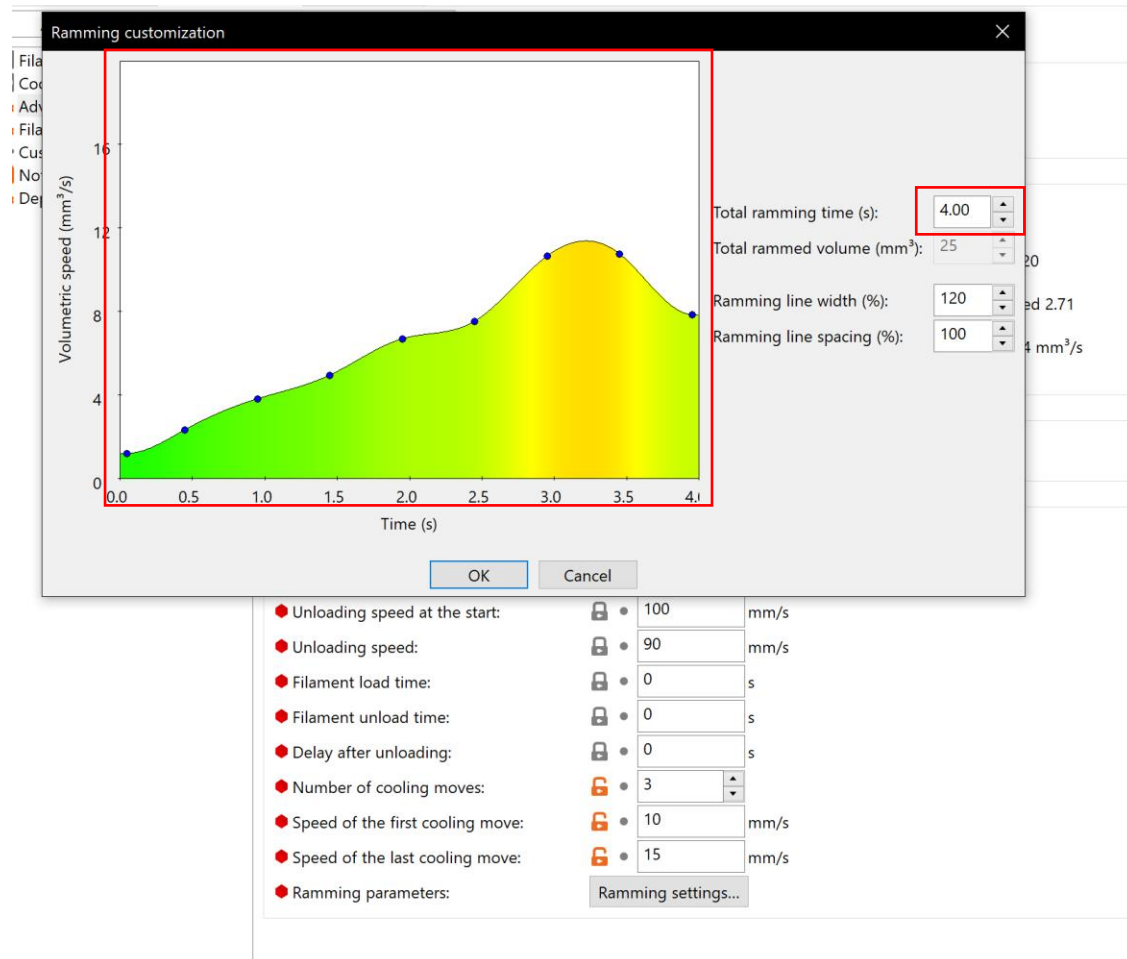
You will then go in filament settings and make sure that you have keep fan always on turned on since it will stop when doing tool changes and not turn on for small patch of color.



Then go in advanced and change 4 things. The number of cooling moves: too low and it will jam and too high and it will take a huge amount of time. 3 seems to work well for me, the speed of the cooling move can also be adjusted but it doesn't matter much, a little faster will speed up a filament change

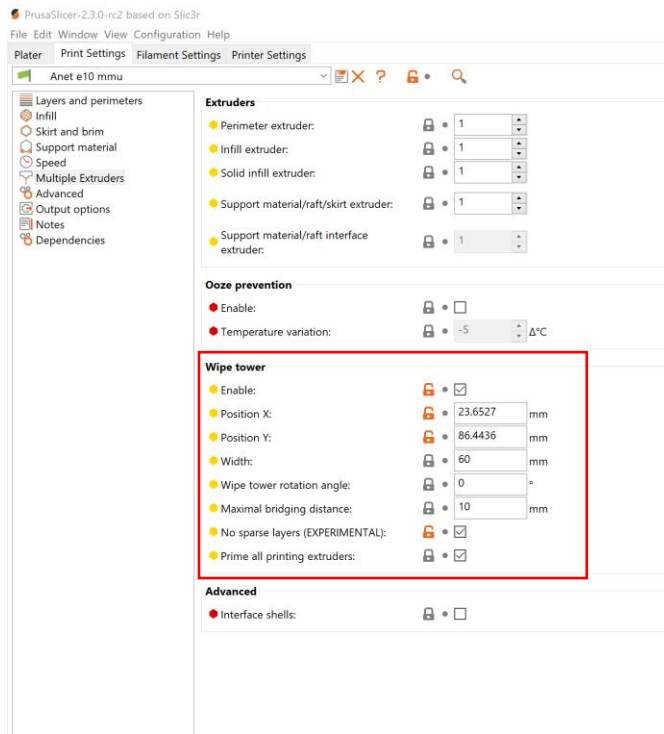


The last thing in there that you will need to adjust is the ramming setting. The default one seems to work but with a bit of tweaking you can get a way cleaner filament tip the following picture is an example of what I am running but you will need to do a bit of experimenting on your side.



You just need to click on ramming settings to get access to these controls.

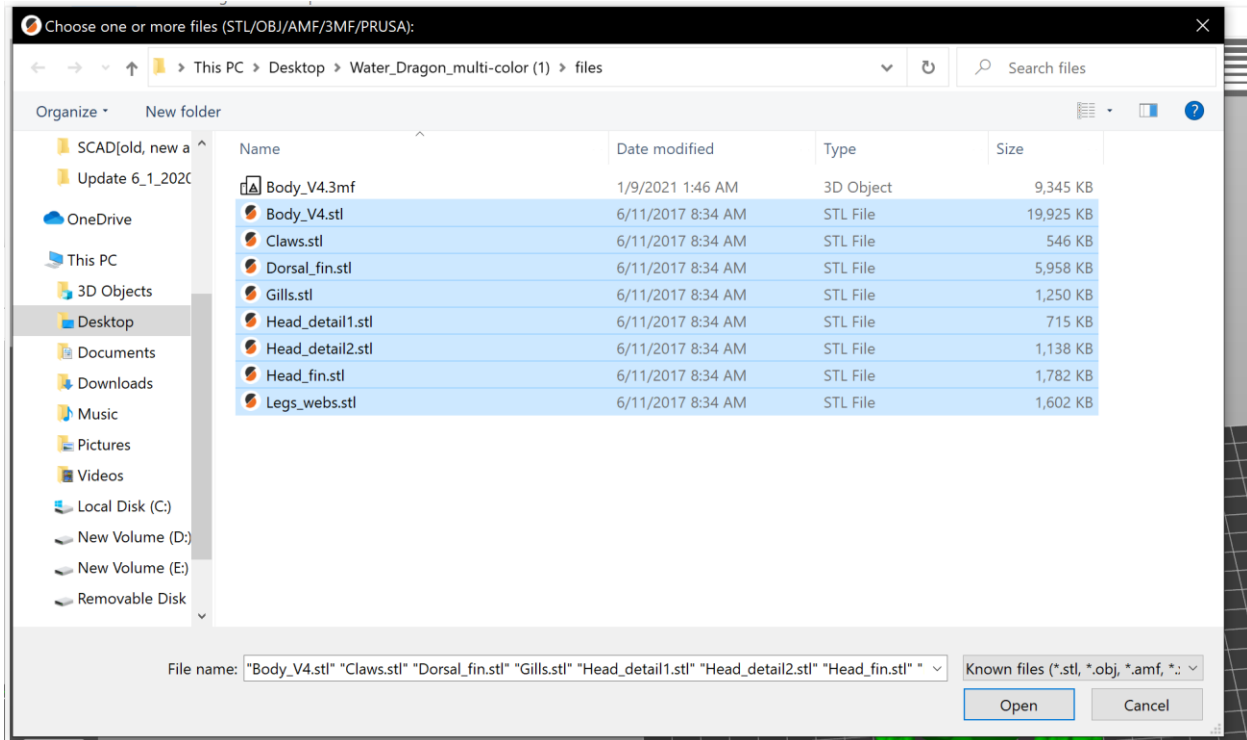
In print settings make sure that you have the wipe tower enabled inside of the Multiple extruder tab and prime all printing extruders enabled as well.



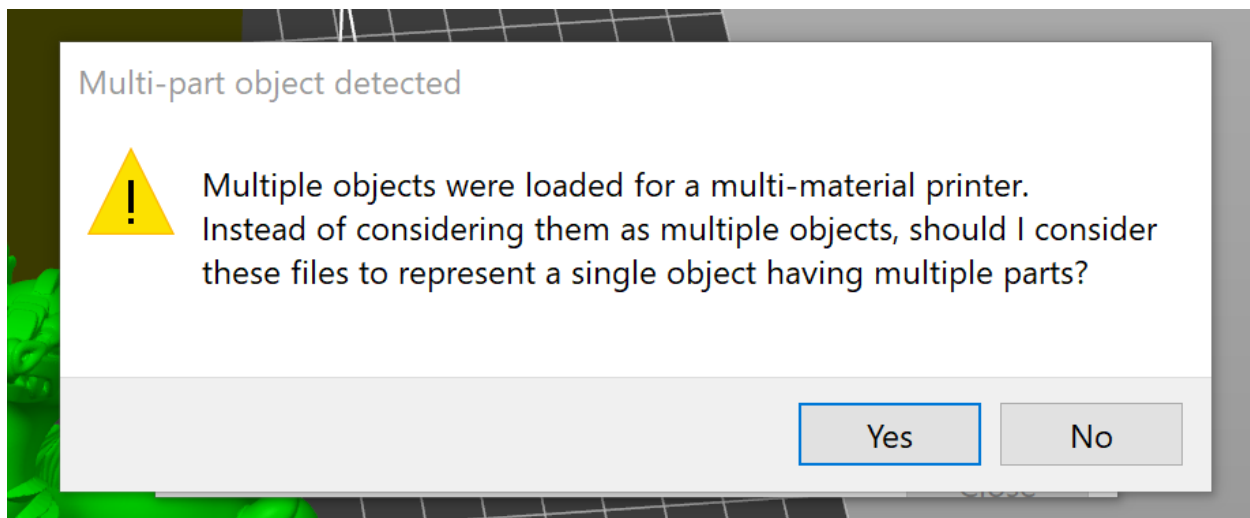
You are now done with slicer settings.

To print you will just need to import a multicolor model. Launch prusa slicer, open all the parts of your model at the same time.





Click open



Hit yes

You will then be able to select different extruders on the right hand side of your screen. Happy printing!

If you have any problems make sure to message me on discord so that I can both help you and improve the documentation.

