



Universidad Nacional de San Agustín de Arequipa

# CodeRats al fallo

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## 1 Contest

## 2 Mathematics

## 3 Data structures

## 4 Numerical

## 5 Number theory

## 6 Combinatorial

## 7 Graph

## 8 Geometry

## 9 Strings

## 10 Various

# Contest (1)

### template.cpp

15 lines

```
#include <bits/stdc++.h>
using namespace std;

#define rep(i, a, b) for(int i = a; i < (b); ++i)
#define all(x) begin(x), end(x)
#define sz(x) (int)(x).size()
typedef long long ll;
typedef pair<int, int> pii;
typedef vector<int> vi;
typedef vector<vi> vvi;

int main() {
    cin.tie(0)->sync_with_stdio(0);
    cin.exceptions(cin.failbit);
}
```

### .bashrc

3 lines

```
alias c='g++ -Wall -Wconversion -Wfatal-errors -g -std=c++17 \
-fsanitize=undefined,address'
xmodmap -e 'clear lock' -e 'keycode 66=less greater' #caps =<
```

### .vimrc

6 lines

```
set cin aw ai is ts=4 sw=4 tm=50 nu noeb bg=dark ru cul
sy on | im jk <esc> | im kj <esc> | no ; :
" Select region and then type :Hash to hash your selection.
" Useful for verifying that there aren't mistypes.
ca Hash w !cpp -dD -P -fpreprocessed \| tr -d '[':space:]' \| md5sum \| cut -c-6
```

### hash.sh

3 lines

```
# Hashes a file, ignoring all whitespace and comments. Use for
# verifying that code was correctly typed.
cpp -dD -P -fpreprocessed | tr -d '[':space:]' | md5sum | cut -c-6
```

### 1 troubleshoot.txt

52 lines

Pre-submit:  
1 Write a few simple test cases if sample is not enough.  
Are time limits close? If so, generate max cases.  
Is the memory usage fine?  
3 Could anything overflow?  
Make sure to submit the right file.

5 Wrong answer:  
Print your solution! Print debug output, as well.  
9 Are you clearing all data structures between test cases?  
Can your algorithm handle the whole range of input?  
Read the full problem statement again.  
11 Do you handle all corner cases correctly?  
Have you understood the problem correctly?  
Any uninitialized variables?  
12 Any overflows?  
Confusing N and M, i and j, etc.?  
18 Are you sure your algorithm works?  
What special cases have you not thought of?  
Are you sure the STL functions you use work as you think?  
23 Add some assertions, maybe resubmit.  
Create some testcases to run your algorithm on.  
Go through the algorithm for a simple case.  
25 Go through this list again.  
Explain your algorithm to a teammate.  
Ask the teammate to look at your code.  
Go for a small walk, e.g. to the toilet.  
Is your output format correct? (including whitespace)  
Rewrite your solution from the start or let a teammate do it.

Runtime error:  
Have you tested all corner cases locally?  
Any uninitialized variables?  
Are you reading or writing outside the range of any vector?  
Any assertions that might fail?  
Any possible division by 0? (mod 0 for example)  
Any possible infinite recursion?  
Invalidated pointers or iterators?  
Are you using too much memory?  
Debug with resubmits (e.g. remapped signals, see Various).

Time limit exceeded:  
Do you have any possible infinite loops?  
What is the complexity of your algorithm?  
Are you copying a lot of unnecessary data? (References)  
How big is the input and output? (consider scanf)  
Avoid vector, map. (use arrays/unordered\_map)  
What do your teammates think about your algorithm?

Memory limit exceeded:  
What is the max amount of memory your algorithm should need?  
Are you clearing all data structures between test cases?

# Mathematics (2)

## 2.1 Equations

$$ax^2 + bx + c = 0 \Rightarrow x = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

The extremum is given by  $x = -b/2a$ .

$$\begin{aligned} ax + by = e &\Rightarrow x = \frac{ed - bf}{ad - bc} \\ cx + dy = f &\Rightarrow y = \frac{af - ec}{ad - bc} \end{aligned}$$

In general, given an equation  $Ax = b$ , the solution to a variable  $x_i$  is given by

$$x_i = \frac{\det A'_i}{\det A}$$

where  $A'_i$  is  $A$  with the  $i$ 'th column replaced by  $b$ .

## 2.2 Recurrences

If  $a_n = c_1 a_{n-1} + \dots + c_k a_{n-k}$ , and  $r_1, \dots, r_k$  are distinct roots of  $x^k - c_1 x^{k-1} - \dots - c_k$ , there are  $d_1, \dots, d_k$  s.t.

$$a_n = d_1 r_1^n + \dots + d_k r_k^n.$$

Non-distinct roots  $r$  become polynomial factors, e.g.  
 $a_n = (d_1 n + d_2) r^n$ .

## 2.3 Trigonometry

$$\sin(v + w) = \sin v \cos w + \cos v \sin w$$

$$\cos(v + w) = \cos v \cos w - \sin v \sin w$$

$$\tan(v + w) = \frac{\tan v + \tan w}{1 - \tan v \tan w}$$

$$\sin v + \sin w = 2 \sin \frac{v+w}{2} \cos \frac{v-w}{2}$$

$$\cos v + \cos w = 2 \cos \frac{v+w}{2} \cos \frac{v-w}{2}$$

$$(V + W) \tan(v - w)/2 = (V - W) \tan(v + w)/2$$

where  $V, W$  are lengths of sides opposite angles  $v, w$ .

$$a \cos x + b \sin x = r \cos(x - \phi)$$

$$a \sin x + b \cos x = r \sin(x + \phi)$$

where  $r = \sqrt{a^2 + b^2}, \phi = \text{atan2}(b, a)$ .

## 2.4 Geometry

### 2.4.1 Triangles

Side lengths:  $a, b, c$

Semiperimeter:  $p = \frac{a+b+c}{2}$

Area:  $A = \sqrt{p(p-a)(p-b)(p-c)}$

Circumradius:  $R = \frac{abc}{4A}$

Inradius:  $r = \frac{A}{p}$

Length of median (divides triangle into two equal-area triangles):  
 $m_a = \frac{1}{2} \sqrt{2b^2 + 2c^2 - a^2}$

# UNSA-CC

Length of bisector (divides angles in two):

$$s_a = \sqrt{bc \left[ 1 - \left( \frac{a}{b+c} \right)^2 \right]}$$

$$\text{Law of sines: } \frac{\sin \alpha}{a} = \frac{\sin \beta}{b} = \frac{\sin \gamma}{c} = \frac{1}{2R}$$

$$\text{Law of cosines: } a^2 = b^2 + c^2 - 2bc \cos \alpha$$

$$\text{Law of tangents: } \frac{a+b}{a-b} = \frac{\tan \frac{\alpha+\beta}{2}}{\tan \frac{\alpha-\beta}{2}}$$

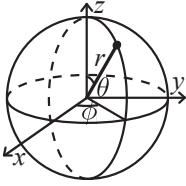
## 2.4.2 Quadrilaterals

With side lengths  $a, b, c, d$ , diagonals  $e, f$ , diagonals angle  $\theta$ , area  $A$  and magic flux  $F = b^2 + d^2 - a^2 - c^2$ :

$$4A = 2ef \cdot \sin \theta = F \tan \theta = \sqrt{4e^2f^2 - F^2}$$

For cyclic quadrilaterals the sum of opposite angles is  $180^\circ$ ,  $ef = ac + bd$ , and  $A = \sqrt{(p-a)(p-b)(p-c)(p-d)}$ .

## 2.4.3 Spherical coordinates



$$\begin{aligned} x &= r \sin \theta \cos \phi & r &= \sqrt{x^2 + y^2 + z^2} \\ y &= r \sin \theta \sin \phi & \theta &= \arccos(z/\sqrt{x^2 + y^2 + z^2}) \\ z &= r \cos \theta & \phi &= \arctan(y/x) \end{aligned}$$

## 2.5 Derivatives/Integrals

$$\frac{d}{dx} \arcsin x = \frac{1}{\sqrt{1-x^2}} \quad \frac{d}{dx} \arccos x = -\frac{1}{\sqrt{1-x^2}}$$

$$\frac{d}{dx} \tan x = 1 + \tan^2 x \quad \frac{d}{dx} \arctan x = \frac{1}{1+x^2}$$

$$\int \tan ax = -\frac{\ln |\cos ax|}{a} \quad \int x \sin ax = \frac{\sin ax - ax \cos ax}{a^2}$$

$$\int e^{-x^2} = \frac{\sqrt{\pi}}{2} \operatorname{erf}(x) \quad \int x e^{ax} dx = \frac{e^{ax}}{a^2} (ax - 1)$$

Integration by parts:

$$\int_a^b f(x)g(x)dx = [F(x)g(x)]_a^b - \int_a^b F(x)g'(x)dx$$

# template .bashrc .vimrc hash troubleshoot

## 2.6 Sums

$$c^a + c^{a+1} + \dots + c^b = \frac{c^{b+1} - c^a}{c - 1}, c \neq 1$$

$$1 + 2 + 3 + \dots + n = \frac{n(n+1)}{2}$$

$$1^2 + 2^2 + 3^2 + \dots + n^2 = \frac{n(2n+1)(n+1)}{6}$$

$$1^3 + 2^3 + 3^3 + \dots + n^3 = \frac{n^2(n+1)^2}{4}$$

$$1^4 + 2^4 + 3^4 + \dots + n^4 = \frac{n(n+1)(2n+1)(3n^2+3n-1)}{30}$$

## 2.7 Series

$$e^x = 1 + x + \frac{x^2}{2!} + \frac{x^3}{3!} + \dots, (-\infty < x < \infty)$$

$$\ln(1+x) = x - \frac{x^2}{2} + \frac{x^3}{3} - \frac{x^4}{4} + \dots, (-1 < x \leq 1)$$

$$\sqrt{1+x} = 1 + \frac{x}{2} - \frac{x^2}{8} + \frac{2x^3}{32} - \frac{5x^4}{128} + \dots, (-1 \leq x \leq 1)$$

$$\sin x = x - \frac{x^3}{3!} + \frac{x^5}{5!} - \frac{x^7}{7!} + \dots, (-\infty < x < \infty)$$

$$\cos x = 1 - \frac{x^2}{2!} + \frac{x^4}{4!} - \frac{x^6}{6!} + \dots, (-\infty < x < \infty)$$

## 2.8 Probability theory

Let  $X$  be a discrete random variable with probability  $p_X(x)$  of assuming the value  $x$ . It will then have an expected value (mean)  $\mu = \mathbb{E}(X) = \sum_x x p_X(x)$  and variance  $\sigma^2 = V(X) = \mathbb{E}(X^2) - (\mathbb{E}(X))^2 = \sum_x (x - \mathbb{E}(X))^2 p_X(x)$  where  $\sigma$  is the standard deviation. If  $X$  is instead continuous it will have a probability density function  $f_X(x)$  and the sums above will instead be integrals with  $p_X(x)$  replaced by  $f_X(x)$ .

Expectation is linear:

$$\mathbb{E}(aX + bY) = a\mathbb{E}(X) + b\mathbb{E}(Y)$$

For independent  $X$  and  $Y$ ,

$$V(aX + bY) = a^2 V(X) + b^2 V(Y).$$

### 2.8.1 Discrete distributions

#### Binomial distribution

The number of successes in  $n$  independent yes/no experiments, each which yields success with probability  $p$  is  $\text{Bin}(n, p)$ ,  $n = 1, 2, \dots$ ,  $0 \leq p \leq 1$ .

$$p(k) = \binom{n}{k} p^k (1-p)^{n-k}$$

$$\mu = np, \sigma^2 = np(1-p)$$

$\text{Bin}(n, p)$  is approximately  $\text{Po}(np)$  for small  $p$ .

## First success distribution

The number of trials needed to get the first success in independent yes/no experiments, each which yields success with probability  $p$  is  $\text{Fs}(p)$ ,  $0 \leq p \leq 1$ .

$$p(k) = p(1-p)^{k-1}, k = 1, 2, \dots$$

$$\mu = \frac{1}{p}, \sigma^2 = \frac{1-p}{p^2}$$

## Poisson distribution

The number of events occurring in a fixed period of time  $t$  if these events occur with a known average rate  $\kappa$  and independently of the time since the last event is  $\text{Po}(\lambda)$ ,  $\lambda = t\kappa$ .

$$p(k) = e^{-\lambda} \frac{\lambda^k}{k!}, k = 0, 1, 2, \dots$$

$$\mu = \lambda, \sigma^2 = \lambda$$

## 2.8.2 Continuous distributions

#### Uniform distribution

If the probability density function is constant between  $a$  and  $b$  and 0 elsewhere it is  $\text{U}(a, b)$ ,  $a < b$ .

$$f(x) = \begin{cases} \frac{1}{b-a} & a < x < b \\ 0 & \text{otherwise} \end{cases}$$

$$\mu = \frac{a+b}{2}, \sigma^2 = \frac{(b-a)^2}{12}$$

#### Exponential distribution

The time between events in a Poisson process is  $\text{Exp}(\lambda)$ ,  $\lambda > 0$ .

$$f(x) = \begin{cases} \lambda e^{-\lambda x} & x \geq 0 \\ 0 & x < 0 \end{cases}$$

$$\mu = \frac{1}{\lambda}, \sigma^2 = \frac{1}{\lambda^2}$$

#### Normal distribution

Most real random values with mean  $\mu$  and variance  $\sigma^2$  are well described by  $\mathcal{N}(\mu, \sigma^2)$ ,  $\sigma > 0$ .

$$f(x) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$$

If  $X_1 \sim \mathcal{N}(\mu_1, \sigma_1^2)$  and  $X_2 \sim \mathcal{N}(\mu_2, \sigma_2^2)$  then

$$aX_1 + bX_2 + c \sim \mathcal{N}(\mu_1 + \mu_2 + c, a^2\sigma_1^2 + b^2\sigma_2^2)$$



```

    p[r+1][c+1] = v[r][c] + p[r][c+1] + p[r+1][c] - p[r][c];
}
T sum(int u, int l, int d, int r) {
    return p[d][r] - p[d][l] - p[u][r] + p[u][l];
}
};
```

## Matrix.h

**Description:** Basic operations on square matrices.**Usage:** Matrix<int, 3> A;

A.d = {{{1,2,3}}, {{4,5,6}}, {{7,8,9}}};

array&lt;int, 3&gt; vec = {1,2,3};

vec = (A^N) \* vec;

6ab5db, 26 lines

```

template<class T, int N> struct Matrix {
    typedef Matrix M;
    array<array<T, N>, N> d{};
    M operator*(const M& m) const {
        M a;
        rep(i,0,N) rep(j,0,N)
            rep(k,0,N) a.d[i][j] += d[i][k]*m.d[k][j];
        return a;
    }
    array<T, N> operator*(const array<T, N>& vec) const {
        array<T, N> ret{};
        rep(i,0,N) rep(j,0,N) ret[i] += d[i][j] * vec[j];
        return ret;
    }
    M operator^(ll p) const {
        assert(p >= 0);
        M a, b(*this);
        rep(i,0,N) a.d[i][i] = 1;
        while (p) {
            if (p&1) a = a*b;
            b = b*b;
            p >>= 1;
        }
        return a;
    }
};
```

## LineContainer.h

**Description:** Container where you can add lines of the form  $kx+m$ , and query maximum values at points  $x$ . Useful for dynamic programming ("convex hull trick").**Time:**  $\mathcal{O}(\log N)$ 

8ec1c7, 30 lines

```

struct Line {
    mutable ll k, m, p;
    bool operator<(const Line& o) const { return k < o.k; }
    bool operator<(ll x) const { return p < x; }
};

struct LineContainer : multiset<Line, less<> {
    // (for doubles, use inf = 1/.0, div(a,b) = a/b)
    static const ll inf = LLONG_MAX;
    ll div(ll a, ll b) { // floored division
        return a / b - ((a ^ b) < 0 && a % b); }
    bool isect(iterator x, iterator y) {
        if (y == end()) return x->p = inf, 0;
        if (x->k == y->k) x->p = x->m > y->m ? inf : -inf;
        else x->p = div(y->m - x->m, x->k - y->k);
        return x->p >= y->p;
    }
    void add(ll k, ll m) {
        auto z = insert({k, m, 0}), y = z++, x = y;
        while (isect(y, z)) z = erase(z);
        if (x != begin() && isect(--x, y)) isect(x, y = erase(y));
        while ((y = x) != begin() && (!--x->p >= y->p))
```

```

            isect(x, erase(y));
        }
        ll query(ll x) {
            assert(!empty());
            auto l = *lower_bound(x);
            return l.k * x + l.m;
        }
};
```

## Treap.h

**Description:** A short self-balancing tree. It acts as a sequential container with log-time splits/joins, and is easy to augment with additional data.**Time:**  $\mathcal{O}(\log N)$ 

1754b4, 53 lines

```

struct Node {
    Node *l = 0, *r = 0;
    int val, y, c = 1;
    Node(int val) : val(val), y(rand()) {}
    void recalc();
};

int cnt(Node* n) { return n ? n->c : 0; }
void Node::recalc() { c = cnt(l) + cnt(r) + 1; }

template<class F> void each(Node* n, F f) {
    if (n) { each(n->l, f); f(n->val); each(n->r, f); }
}

pair<Node*, Node*> split(Node* n, int k) {
    if (!n) return {};
    if (cnt(n->l) >= k) { // "n->val >= k" for lower_bound(k)
        auto [l, R] = split(n->l, k);
        n->l = R;
        n->recalc();
        return {l, n};
    } else {
        auto [L, R] = split(n->r, k - cnt(n->l) - 1); // and just "k"
        n->r = L;
        n->recalc();
        return {n, R};
    }
}

Node* merge(Node* l, Node* r) {
    if (!l) return r;
    if (!r) return l;
    if (l->y > r->y) {
        l->r = merge(l->r, r);
        return l->recalc(), l;
    } else {
        r->l = merge(l, r->l);
        return r->recalc(), r;
    }
}

Node* ins(Node* t, Node* n, int pos) {
    auto [l,r] = split(t, pos);
    return merge(merge(l, n), r);
}

// Example application: move the range [l, r) to index k
void move(Node*& t, int l, int r, int k) {
    Node *a, *b, *c;
    tie(a,b) = split(t, l); tie(b,c) = split(b, r - 1);
    if (k <= l) t = merge(ins(a, b, k), c);
    else t = merge(a, ins(c, b, k - r));
}
```

## FenwickTree.h

**Description:** Computes partial sums  $a[0] + a[1] + \dots + a[pos - 1]$ , and updates single elements  $a[i]$ , taking the difference between the old and new value.**Time:** Both operations are  $\mathcal{O}(\log N)$ .

e62fac, 22 lines

```

struct FT {
    vector<ll> s;
    FT(int n) : s(n) {}
    void update(int pos, ll dif) { // a[pos] += dif
        for (; pos < sz(s); pos |= pos + 1) s[pos] += dif;
    }
    ll query(int pos) { // sum of values in [0, pos)
        ll res = 0;
        for (; pos > 0; pos &= pos - 1) res += s[pos-1];
        return res;
    }
    int lower_bound(ll sum) { // min pos st sum of [0, pos] >= sum
        // Returns n if no sum is >= sum, or -1 if empty sum is.
        if (sum <= 0) return -1;
        int pos = 0;
        for (int pw = 1 << 25; pw; pw >>= 1) {
            if (pos + pw <= sz(s) && s[pos + pw-1] < sum)
                pos += pw, sum -= s[pos-1];
        }
        return pos;
    }
};
```

## FenwickTree2d.h

**Description:** Computes sums  $a[i,j]$  for all  $i < I, j < J$ , and increases single elements  $a[i,j]$ . Requires that the elements to be updated are known in advance (call fakeUpdate() before init()).**Time:**  $\mathcal{O}(\log^2 N)$ . (Use persistent segment trees for  $\mathcal{O}(\log N)$ .)

"FenwickTree.h" 157f07, 22 lines

```

struct FT2 {
    vector<vi> ys; vector<FT> ft;
    FT2(int limx) : ys(limx) {}
    void fakeUpdate(int x, int y) {
        for (; x < sz(ys); x |= x + 1) ys[x].push_back(y);
    }
    void init() {
        for (vi& v : ys) sort(all(v)), ft.emplace_back(sz(v));
    }
    int ind(int x, int y) {
        return (int)(lower_bound(all(ys[x]), y) - ys[x].begin()); }
    void update(int x, int y, ll dif) {
        for (; x < sz(ys); x |= x + 1)
            ft[x].update(ind(x, y), dif);
    }
    ll query(int x, int y) {
        ll sum = 0;
        for (; x; x &= x - 1)
            sum += ft[x-1].query(ind(x-1, y));
        return sum;
    }
};
```

## RMQ.h

**Description:** Range Minimum Queries on an array. Returns  $\min(V[a], V[a+1], \dots, V[b-1])$  in constant time.**Usage:** RMQ rmq(values);

rmq.query(inclusive, exclusive);

**Time:**  $\mathcal{O}(|V| \log |V| + Q)$ 

510c32, 16 lines

```

template<class T>
struct RMQ {
    vector<vector<T>> jmp;
    RMQ(const vector<T>& V) : jmp(1, V) {
```

```

for (int pw = 1, k = 1; pw * 2 <= sz(V); pw *= 2, ++k) {
    jmp.emplace_back(sz(V) - pw * 2 + 1);
    rep(j, 0, sz(jmp[k]))
        jmp[k][j] = min(jmp[k - 1][j], jmp[k - 1][j + pw]);
}

T query(int a, int b) {
    assert(a < b); // or return inf if a == b
    int dep = 31 - __builtin_clz(b - a);
    return min(jmp[dep][a], jmp[dep][b - (1 << dep)]);
}

```

## MoQueries.h

**Description:** Answer interval or tree path queries by finding an approximate TSP through the queries, and moving from one query to the next by adding/removing points at the ends. If values are on tree edges, change step to add/remove the edge  $(a, c)$  and remove the initial add call (but keep in).

**Time:**  $\mathcal{O}(N\sqrt{Q})$

```

void add(int ind, int end) { ... } // add a[ind] (end = 0 or 1)
void del(int ind, int end) { ... } // remove a[ind]
int calc() { ... } // compute current answer

```

```

vi mo(vector<pii> Q) {
    int L = 0, R = 0, blk = 350; // ~N/sqrt(Q)
    vi s(sz(Q)), res = s;
#define K(x) pii(x.first/blk, x.second ^ -(x.first/blk & 1))
    iota(all(s), 0);
    sort(all(s), [&](int s, int t){ return K(Q[s]) < K(Q[t]); });
    for (int qi : s) {
        pii q = Q[qi];
        while (L > q.first) add(--L, 0);
        while (R < q.second) add(R++, 1);
        while (L < q.first) del(L++, 0);
        while (R > q.second) del(--R, 1);
        res[qi] = calc();
    }
    return res;
}

```

```

vi moTree(vector<array<int, 2>> Q, vector<vi> ed, int root=0) {
    int N = sz(ed), pos[2] = {}, blk = 350; // ~N/sqrt(Q)
    vi s(sz(Q)), res = s, I(N), L(N), R(N), in(N), par(N);
    add(0, 0), in[0] = 1;
    auto dfs = [&](int x, int p, int dep, auto& f) -> void {
        par[x] = p;
        L[x] = N;
        if (dep) I[x] = N++;
        for (int y : ed[x]) if (y != p) f(y, x, !dep, f);
        if (!dep) I[x] = N++;
        R[x] = N;
    };
    dfs(root, -1, 0, dfs);
#define K(x) pii(I[x[0]] / blk, I[x[1]] ^ -(I[x[0]] / blk & 1))
    iota(all(s), 0);
    sort(all(s), [&](int s, int t){ return K(Q[s]) < K(Q[t]); });
    for (int qi : s) rep(end, 0, 2) {
        int &a = pos[end], b = Q[qi][end], i = 0;
#define step(c) { if (in[c]) { del(a, end); in[a] = 0; } \
            else { add(c, end); in[c] = 1; } a = c; }
        while (!!(L[b] <= L[a] && R[a] <= R[b])) {
            I[i++] = b, b = par[b];
        }
        while (a != b) step(par[a]);
        while (i--) step(I[i]);
        if (end) res[qi] = calc();
    }
    return res;
}

```

PersistentSegTree.h

**Description:** Persistent Segment Tree for range sum. Remember to save the roots when needed.

**Time:**  $\mathcal{O}(\log N)$

---

```

class PersistentSegtree {
private:
    struct Node { ll sum = 0; int l = 0, r = 0; };
    const int n;
    vector<Node> tree;
    int timer = 1;

    Node join(int l, int r) { return Node{tree[l].sum + tree[r].sum, l, r}; }

    int build(int tl, int tr, const vector<int> &arr) {
        if (tl == tr) {
            tree[timer] = {arr[tl], 0, 0};
            return timer++;
        }

        int mid = (tl + tr) / 2;
        tree[timer] = join(build(tl, mid, arr), build(mid + 1, tr, arr));
        return timer++;
    }

    int set(int v, int pos, int val, int tl, int tr) {
        if (tl == tr) {
            tree[timer] = {val, 0, 0};
            return timer++;
        }

        int mid = (tl + tr) / 2;
        if (pos <= mid) {
            tree[timer] = join(set(tree[v].l, pos, val, tl, mid),
                               tree[v].r);
        } else {
            tree[timer] = join(tree[v].l, set(tree[v].r, pos, val,
                                              mid + 1, tr));
        }
        return timer++;
    }

    ll range_sum(int v, int ql, int qr, int tl, int tr) {
        if (qr < tl || tr < ql) { return 0ll; }
        if (ql <= tl && tr <= qr) { return tree[v].sum; }

        int mid = (tl + tr) / 2;
        return range_sum(tree[v].l, ql, qr, tl, mid) +
               range_sum(tree[v].r, ql, qr, mid + 1, tr);
    }

public:
    // MX_NODES = 2 * n + q * (3 + __lg(n));
    PersistentSegtree(int n, int MX_NODES) : n(n), tree(MX_NODES)
    {
        int build(const vector<int> &arr) { return build(0, n - 1, arr); }
        int set(int root, int pos, int val) { return set(root, pos, val, 0, n - 1); }
        ll range_sum(int root, int l, int r) { return range_sum(root, l, r, 0, n - 1); }
        int add_copy(int root) {
            tree[timer] = tree[root];
            return timer++;
        }
    }
}

```

};

## Numerical (4)

## 4.1 Polynomials and recurrences

## Polynomial.h

c9b7b0, 17 lines

```

struct Poly {
    vector<double> a;
    double operator()(double x) const {
        double val = 0;
        for (int i = sz(a); i--;) (val *= x) += a[i];
        return val;
    }
    void diff() {
        rep(i, 1, sz(a)) a[i-1] = i*a[i];
        a.pop_back();
    }
    void divroot(double x0) {
        double b = a.back(), c; a.back() = 0;
        for (int i=sz(a)-1; i--;) c = a[i], a[i] = a[i+1]*x0+b, b=c;
        a.pop_back();
    }
}

```

## PolyRoots.h

**Description:** Finds the real roots to a polynomial.**Usage:** polyRoots({{2,-3,1}}, -1e9, 1e9) // solve  $x^2-3x+2 = 0$ **Time:**  $\mathcal{O}(n^2 \log(1/\epsilon))$ 

```

"Polynomial.h" b00bfe, 23 lines
vector<double> polyRoots(Poly p, double xmin, double xmax) {
    if (sz(p.a) == 2) { return {-p.a[0]/p.a[1]}; }
    vector<double> ret;
    Poly der = p;
    der.diff();
    auto dr = polyRoots(der, xmin, xmax);
    dr.push_back(xmin-1);
    dr.push_back(xmax+1);
    sort(all(dr));
    rep(i, 0, sz(dr)-1) {
        double l = dr[i], h = dr[i+1];
        bool sign = p(l) > 0;
        if (sign ^ (p(h) > 0)) {
            rep(it, 0, 60) { // while (h - l > 1e-8)
                double m = (l + h) / 2, f = p(m);
                if ((f <= 0) ^ sign) l = m;
                else h = m;
            }
            ret.push_back((l + h) / 2);
        }
    }
    return ret;
}

```

## PolyInterpolate.h

**Description:** Given  $n$  points  $(x[i], y[i])$ , computes an  $n-1$ -degree polynomial  $p$  that passes through them:  $p(x) = a[0] * x^0 + \dots + a[n-1] * x^{n-1}$ . For numerical precision, pick  $x[k] = c * \cos(k/(n-1) * \pi)$ ,  $k = 0 \dots n-1$ .

**Time:**  $\mathcal{O}(n^2)$ 

08bf48, 13 lines

```

typedef vector<double> vd;
vd interpolate(vd x, vd y, int n) {
    vd res(n), temp(n);
    rep(k, 0, n-1) rep(i, k+1, n)
        y[i] = (y[i] - y[k]) / (x[i] - x[k]);
    double last = 0; temp[0] = 1;
    rep(k, 0, n) rep(i, 0, n) {

```

```

res[i] += y[k] * temp[i];
swap(last, temp[i]);
temp[i] -= last * x[k];
}
return res;
}

```

## BerlekampMassey.h

**Description:** Recovers any  $n$ -order linear recurrence relation from the first  $2n$  terms of the recurrence. Useful for guessing linear recurrences after brute-forcing the first terms. Should work on any field, but numerical stability for floats is not guaranteed. Output will have size  $\leq n$ .

**Usage:** berlekampMassey({0, 1, 1, 3, 5, 11}) // {1, 2}

**Time:**  $\mathcal{O}(N^2)$

.../number-theory/ModPow.h\* 96548b, 20 lines

```

vector<ll> berlekampMassey(vector<ll> s) {
    int n = sz(s), L = 0, m = 0;
    vector<ll> C(n), B(n), T;
    C[0] = B[0] = 1;

    ll b = 1;
    rep(i, 0, n) { ++m;
        ll d = s[i] % mod;
        rep(j, 1, L+1) d = (d + C[j] * s[i - j]) % mod;
        if (!d) continue;
        T = C; ll coef = d * modpow(b, mod-2) % mod;
        rep(j, m, n) C[j] = (C[j] - coef * B[j - m]) % mod;
        if (2 * L > i) continue;
        L = i + 1 - L; B = T; b = d; m = 0;
    }
}

```

```

C.resize(L + 1); C.erase(C.begin());
for (ll& x : C) x = (mod - x) % mod;
return C;
}

```

## LinearRecurrence.h

**Description:** Generates the  $k$ 'th term of an  $n$ -order linear recurrence  $S[i] = \sum_j S[i - j - 1]tr[j]$ , given  $S[0 \dots \geq n - 1]$  and  $tr[0 \dots n - 1]$ . Faster than matrix multiplication. Useful together with Berlekamp-Massey.

**Usage:** linearRec({0, 1}, {1, 1}, k) // k'th Fibonacci number

**Time:**  $\mathcal{O}(n^2 \log k)$

f4e444, 26 lines

```

typedef vector<ll> Poly;
ll linearRec(Poly S, Poly tr, ll k) {
    int n = sz(tr);
    auto combine = [&](Poly a, Poly b) {
        Poly res(n * 2 + 1);
        rep(i, 0, n+1) rep(j, 0, n+1)
            res[i + j] = (res[i + j] + a[i] * b[j]) % mod;
        for (int i = 2 * n; i > n; --i) rep(j, 0, n)
            res[i - 1 - j] = (res[i - 1 - j] + res[i] * tr[j]) % mod;
        res.resize(n + 1);
        return res;
    };

    Poly pol(n + 1), e(pol);
    pol[0] = e[1] = 1;

    for (++k; k; k /= 2) {
        if (k % 2) pol = combine(pol, e);
        e = combine(e, e);
    }

    ll res = 0;
    rep(i, 0, n) res = (res + pol[i + 1] * S[i]) % mod;
    return res;
}

```

```

}

```

## GaussianElimination.h

**Description:** Gaussian elimination. Returns -1 if there aren't solutions, 1 if the solution is unique, 2 if there's infinite solutions.

**Time:**  $\mathcal{O}(N^3)$

09f2c8, 33 lines

```

const double eps = 1e-9;
int Gauss(vector<vector<double>> a, vector<double> &ans) {
    int n = (int)a.size(), m = (int)a[0].size() - 1;
    vector<int> pos(m, -1);
    double det = 1; int rank = 0;
    for(int col = 0, row = 0; col < m && row < n; ++col) {
        int mx = row;
        for(int i = row; i < n; i++) if(fabs(a[i][col]) > fabs(a[mx][col])) mx = i;
        if(fabs(a[mx][col]) < eps) {det = 0; continue;}
        for(int i = col; i <= m; i++) swap(a[row][i], a[mx][i]);
        if (row != mx) det = -det;
        det *= a[row][col];
        pos[col] = row;
        for(int i = 0; i < n; i++) {
            if(i != row && fabs(a[i][col]) > eps) {
                double c = a[i][col] / a[row][col];
                for(int j = col; j <= m; j++) a[i][j] -= a[row][j] * c;
            }
        }
        ++row; ++rank;
    }
    ans.assign(m, 0);
    for(int i = 0; i < m; i++) {
        if(pos[i] != -1) ans[i] = a[pos[i]][m] / a[pos[i]][i];
    }
    for(int i = 0; i < n; i++) {
        double sum = 0;
        for(int j = 0; j < m; j++) sum += ans[j] * a[i][j];
        if(fabs(sum - a[i][m]) > eps) return -1; //no solution
    }
    for(int i = 0; i < m; i++) if(pos[i] == -1) return 2; //infinite solutions
    return 1; //unique solution
}

```

## GaussMod2.h

**Description:** Gaussian elimination mod 2. Returns -1 if there aren't solutions. Returns number of free variables otherwise. n = number of equations, m = number of variables

**Time:**  $\mathcal{O}((N^3)/64)$

3880dc, 33 lines

```

const int N = 100 + 6;
int Gauss(int n, int m, vector<bitset<N>> a, bitset<N> &ans) {
    int rank = 0, det = 1;
    vi pos(N, -1);
    for(int col = 0, row = 0; col < m && row < n; ++col) {
        int mx = row;
        rep(i, row, n) if(a[i][col]) {mx = i; break;}
        if(!a[mx][col]) {det = 0; continue;}
        swap(a[mx], a[row]);
        if(row != mx) det = det == 0 ? 0 : 1;
        det &= a[row][col];
        pos[col] = row;
        //forward elimination
        rep(i, row+1, n) if (a[i][col]) a[i] ^= a[row];
        ++row, ++rank;
    }
    ans.reset();
    //backward substitution
    for (int i = m - 1; i >= 0; i--) {
        if (pos[i] == -1) ans[i] = true;
    }
}

```

```

else {
    int k = pos[i];
    rep(j, i+1, m) if (a[k][j]) ans[i] = ans[i] ^ ans[j];
    ans[i] = ans[i] ^ a[k][m];
}
}

rep(i, rank, n) if(a[i][m]) return -1; //no solution

int free_var = 0;
rep(i, 0, m) if(pos[i] == -1) free_var++;
return free_var; //has solution
}

```

## 4.2 Optimization

## GoldenSectionSearch.h

**Description:** Finds the argument minimizing the function  $f$  in the interval  $[a, b]$  assuming  $f$  is unimodal on the interval, i.e. has only one local minimum and no local maximum. The maximum error in the result is  $eps$ . Works equally well for maximization with a small change in the code. See TernarySearch.h in the Various chapter for a discrete version.

**Usage:** double func(double x) { return 4+x+.3\*x\*x; }

double xmin = gss(-1000, 1000, func);

**Time:**  $\mathcal{O}(\log((b-a)/\epsilon))$

31d45b, 14 lines

```

double gss(double a, double b, double (*f)(double)) {
    double r = (sqrt(5)-1)/2, eps = 1e-7;
    double x1 = b - r*(b-a), x2 = a + r*(b-a);
    double f1 = f(x1), f2 = f(x2);
    while (b-a > eps) {
        if (f1 < f2) { //change to > to find maximum
            b = x2; x2 = x1; f2 = f1;
            x1 = b - r*(b-a); f1 = f(x1);
        } else {
            a = x1; x1 = x2; f1 = f2;
            x2 = a + r*(b-a); f2 = f(x2);
        }
    }
    return a;
}

```

## HillClimbing.h

**Description:** Poor man's optimization for unimodal functions, 8eeeaaf, 14 lines

```

typedef array<double, 2> P;

template<class F> pair<double, P> hillClimb(P start, F f) {
    pair<double, P> cur(f(start), start);
    for (double jmp = 1e9; jmp > 1e-20; jmp /= 2) {
        rep(j, 0, 100) rep(dx, -1, 2) rep(dy, -1, 2) {
            P p = cur.second;
            p[0] += dx*jmp;
            p[1] += dy*jmp;
            cur = min(cur, make_pair(f(p), p));
        }
    }
    return cur;
}

```

## Integrate.h

**Description:** Simple integration of a function over an interval using Simpson's rule. The error should be proportional to  $h^4$ , although in practice you will want to verify that the result is stable to desired precision when epsilon changes.

4756fc, 7 lines

```

template<class F>
double quad(double a, double b, F f, const int n = 1000) {
    double h = (b - a) / 2 / n, v = f(a) + f(b);
    rep(i, 1, n*2)
        v += f(a + i*h) * (i&1 ? 4 : 2);
}

```

```
    return v * h / 3;
}
```

**IntegrateAdaptive.h**

**Description:** Fast integration using an adaptive Simpson's rule.  
**Usage:** double sphereVolume = quad(-1, 1, [] (double x) {  
 return quad(-1, 1, [&] (double y) {  
 return quad(-1, 1, [&] (double z) {  
 return x\*x + y\*y + z\*z < 1; })});});};

92dd79, 15 lines

```
typedef double d;
#define S(a,b) (f(a) + 4*f((a+b)/2) + f(b)) * (b-a) / 6

template <class F>
d rec(F& f, d a, d b, d eps, d S) {
    d c = (a + b) / 2;
    d S1 = S(a, c), S2 = S(c, b), T = S1 + S2;
    if (abs(T - S) <= 15 * eps || b - a < 1e-10)
        return T + (T - S) / 15;
    return rec(f, a, c, eps / 2, S1) + rec(f, c, b, eps / 2, S2);
}

template<class F>
d quad(d a, d b, F f, d eps = 1e-8) {
    return rec(f, a, b, eps, S(a, b));
}
```

**Simplex.h**

**Description:** Solves a general linear maximization problem: maximize  $c^T x$  subject to  $Ax \leq b$ ,  $x \geq 0$ . Returns -inf if there is no solution, inf if there are arbitrarily good solutions, or the maximum value of  $c^T x$  otherwise. The input vector is set to an optimal  $x$  (or in the unbounded case, an arbitrary solution fulfilling the constraints). Numerical stability is not guaranteed. For better performance, define variables such that  $x = 0$  is viable.

**Usage:** vvd A = {{1,-1}, {-1,1}, {-1,-2}};

vd b = {1,1,-4}, c = {-1,-1}, x;

T val = LPSolver(A, b, c).solve(x);

**Time:**  $\mathcal{O}(NM * \#pivots)$ , where a pivot may be e.g. an edge relaxation.  
 $\mathcal{O}(2^n)$  in the general case.

aa8530, 68 lines

```
typedef double T; // long double, Rational, double + modP>...
typedef vector<T> vd;
typedef vector<vd> vvd;

const T eps = 1e-8, inf = 1./0;
#define MP make_pair
#define ltj(X) if(s == -1 || MP(X[j], N[j]) < MP(X[s], N[s])) s=j

struct LPSolver {
    int m, n;
    vi N, B;
    vvd D;

    LPSolver(const vvd& A, const vd& b, const vd& c) :
        m(sz(b)), n(sz(c)), N(n+1), B(m), D(m+2, vd(n+2)) {
            rep(i,0,m) rep(j,0,n) D[i][j] = A[i][j];
            rep(i,0,m) { B[i] = n+i; D[i][n] = -1; D[i][n+1] = b[i]; }
            rep(j,0,n) { N[j] = j; D[m][j] = -c[j]; }
            N[n] = -1; D[m+1][n] = 1;
    }

    void pivot(int r, int s) {
        T *a = D[r].data(), inv = 1 / a[s];
        rep(i,0,m+2) if (i != r && abs(D[i][s]) > eps) {
            T *b = D[i].data(), inv2 = b[s] * inv;
            rep(j,0,n+2) b[j] -= a[j] * inv2;
            b[s] = a[s] * inv2;
        }
        rep(j,0,n+2) if (j != s) D[r][j] *= inv;
        rep(i,0,m+2) if (i != r) D[i][s] *= -inv;
    }
}
```

```
    return v * h / 3;
}

IntegrateAdaptive.h
Description: Fast integration using an adaptive Simpson's rule.
Usage: double sphereVolume = quad(-1, 1, [] (double x) {
    return quad(-1, 1, [&] (double y) {
        return quad(-1, 1, [&] (double z) {
            return x*x + y*y + z*z < 1; })});});};
```

```
D[r][s] = inv;
swap(B[r], N[s]);
}

bool simplex(int phase) {
    int x = m + phase - 1;
    for (;;) {
        int s = -1;
        rep(j,0,n+1) if (N[j] != -phase) ltj(D[x]);
        if (D[x][s] >= -eps) return true;
        int r = -1;
        rep(i,0,m) {
            if (D[i][s] <= eps) continue;
            if (r == -1 || MP(D[i][n+1] / D[i][s], B[i])
                < MP(D[r][n+1] / D[r][s], B[r])) r = i;
        }
        if (r == -1) return false;
        pivot(r, s);
    }
}

T solve(vd &x) {
    int r = 0;
    rep(i,1,m) if (D[i][n+1] < D[r][n+1]) r = i;
    if (D[r][n+1] < -eps) {
        pivot(r, n);
        if (!simplex(2) || D[m+1][n+1] < -eps) return -inf;
        rep(i,0,m) if (B[i] == -1) {
            int s = 0;
            rep(j,1,n+1) ltj(D[i]);
            pivot(i, s);
        }
    }
    bool ok = simplex(1); x = vd(n);
    rep(i,0,m) if (B[i] < n) x[B[i]] = D[i][n+1];
    return ok ? D[m][n+1] : inf;
}
```

**4.3 Matrices****Determinant.h**

**Description:** Calculates determinant of a matrix. Destroys the matrix.

**Time:**  $\mathcal{O}(N^3)$

```
double det(vector<vector<double>>& a) {
    int n = sz(a); double res = 1;
    rep(i,0,n) {
        int b = i;
        rep(j,i+1,n) if (fabs(a[j][i]) > fabs(a[b][i])) b = j;
        if (i != b) swap(a[i], a[b]), res *= -1;
        res *= a[i][i];
        if (res == 0) return 0;
        rep(j,i+1,n) {
            double v = a[j][i] / a[i][i];
            if (v != 0) rep(k,i+1,n) a[j][k] -= v * a[i][k];
        }
    }
    return res;
}
```

**IntDeterminant.h**

**Description:** Calculates determinant using modular arithmetics. Modulos can also be removed to get a pure-integer version.

**Time:**  $\mathcal{O}(N^3)$

```
const ll mod = 12345;
ll det(vector<vector<ll>>& a) {
    int n = sz(a); ll ans = 1;
    rep(i,0,n) {
        int s = inv(a[i][i]);
        rep(j,i+1,n) a[j][i] = (a[j][i] * s) % mod;
        ans = (ans * a[i][i]) % mod;
    }
    return ans;
}
```

```
rep(j,i+1,n) {
    while (a[j][i] != 0) { // gcd step
        ll t = a[i][i] / a[j][i];
        if (t) rep(k,i,n)
            a[i][k] = (a[i][k] - a[j][k] * t) % mod;
        swap(a[i], a[j]);
        ans *= -1;
    }
}
ans = ans * a[i][i] % mod;
if (!ans) return 0;
}
return (ans + mod) % mod;
}
```

**SolveLinear.h**

**Description:** Solves  $A * x = b$ . If there are multiple solutions, an arbitrary one is returned. Returns rank, or -1 if no solutions. Data in  $A$  and  $b$  is lost.

**Time:**  $\mathcal{O}(n^2m)$

44c9ab, 38 lines

```
typedef vector<double> vd;
const double eps = 1e-12;

int solveLinear(vector<vd>& A, vd& b, vd& x) {
    int n = sz(A), m = sz(x), rank = 0, br, bc;
    if (n) assert(sz(A[0]) == m);
    vi col(m); iota(all(col), 0);

    rep(i,0,n) {
        double v, bv = 0;
        rep(r,i,n) rep(c,i,m)
            if ((v = fabs(A[r][c])) > bv)
                br = r, bc = c, bv = v;
        if (bv <= eps) {
            rep(j,i,n) if (fabs(b[j]) > eps) return -1;
            break;
        }
        swap(A[i], A[br]);
        swap(b[i], b[br]);
        swap(col[i], col[bc]);
        rep(j,0,n) swap(A[j][i], A[j][bc]);
        bv = 1/A[i][i];
        rep(j,i+1,n) {
            double fac = A[j][i] * bv;
            b[j] -= fac * b[i];
            rep(k,i+1,m) A[j][k] -= fac * A[i][k];
        }
        rank++;
    }

    x.assign(m, 0);
    for (int i = rank; i--;) {
        b[i] /= A[i][i];
        x[col[i]] = b[i];
        rep(j,0,i) b[j] -= A[j][i] * b[i];
    }
    return rank; // (multiple solutions if rank < m)
}
```

**SolveLinear2.h**

**Description:** To get all uniquely determined values of  $x$  back from SolveLinear, make the following changes:

```
"SolveLinear.h" 08e495, 7 lines
rep(j,0,n) if (j != i) // instead of rep(j, i+1,n)
// ... then at the end:
x.assign(m, undefined);
rep(i,0,rank) {
    rep(j,rank,m) if (fabs(A[i][j]) > eps) goto fail;
    x[col[i]] = b[i] / A[i][i];
}
```

```
fail; }
```

**SolveLinearBinary.h**

**Description:** Solves  $Ax = b$  over  $\mathbb{F}_2$ . If there are multiple solutions, one is returned arbitrarily. Returns rank, or -1 if no solutions. Destroys  $A$  and  $b$ .

**Time:**  $\mathcal{O}(n^2m)$

fa2d7a, 34 lines

```
typedef bitset<1000> bs;
```

```
int solveLinear(vector<bs>& A, vi& b, bs& x, int m) {
```

```
    int n = sz(A), rank = 0, br;
    assert(m <= sz(x));
    vi col(m); iota(all(col), 0);
    rep(i, 0, n) {
        for (br=i; br<n; ++br) if (A[br].any()) break;
        if (br == n) {
            rep(j, i, n) if (b[j]) return -1;
            break;
        }
        int bc = (int)A[br]._Find_next(i-1);
        swap(A[i], A[br]);
        swap(b[i], b[br]);
        swap(col[i], col[bc]);
        rep(j, 0, n) if (A[j][i] != A[j][bc]) {
            A[j].flip(i); A[j].flip(bc);
        }
        rep(j, i+1, n) if (A[j][i]) {
            b[j] ^= b[i];
            A[j] ^= A[i];
        }
        rank++;
    }
}
```

```
x = bs();
for (int i = rank; i--;) {
    if (!b[i]) continue;
    x[col[i]] = 1;
    rep(j, 0, i) b[j] ^= A[j][i];
}
return rank; // (multiple solutions if rank < m)
}
```

**MatrixInverse.h**

**Description:** Invert matrix  $A$ . Returns rank; result is stored in  $A$  unless singular ( $\text{rank} < n$ ). Can easily be extended to prime moduli; for prime powers, repeatedly set  $A^{-1} = A^{-1}(2I - AA^{-1}) \pmod{p^k}$  where  $A^{-1}$  starts as the inverse of  $A$  mod  $p$ , and  $k$  is doubled in each step.

Time:  $\mathcal{O}(n^3)$ 

ebfff6, 35 lines

```
int matInv(vector<vector<double>>& A) {
    int n = sz(A); vi col(n);
    vector<vector<double>> tmp(n, vector<double>(n));
    rep(i, 0, n) tmp[i][i] = 1, col[i] = i;

    rep(i, 0, n) {
        int r = i, c = i;
        rep(j, i, n) rep(k, i, n)
            if (fabs(A[j][k]) > fabs(A[r][c]))
                r = j, c = k;
        if (fabs(A[r][c]) < 1e-12) return i;
        A[i].swap(A[r]); tmp[i].swap(tmp[r]);
        rep(j, 0, n)
            swap(A[j][i], A[j][c]), swap(tmp[j][i], tmp[j][c]);
        swap(col[i], col[c]);
        double v = A[i][i];
        rep(j, i+1, n)
            double f = A[j][i] / v;
            A[j][i] = 0;
            rep(k, i+1, n) A[j][k] -= f * A[i][k];
    }
}
```

```
    rep(k, 0, n) tmp[j][k] -= f * tmp[i][k];
}
rep(j, i+1, n) A[i][j] /= v;
rep(j, 0, n) tmp[i][j] /= v;
A[i][i] = 1;

for (int i = n-1; i > 0; --i) rep(j, 0, i) {
    double v = A[j][i];
    rep(k, 0, n) tmp[j][k] -= v * tmp[i][k];
}

rep(i, 0, n) rep(j, 0, n) A[col[i]][col[j]] = tmp[i][j];
return n;
}
```

**Tridiagonal.h**

**Description:**  $x = \text{tridiagonal}(d, p, q, b)$  solves the equation system

$$\begin{pmatrix} b_0 \\ b_1 \\ b_2 \\ b_3 \\ \vdots \\ b_{n-1} \end{pmatrix} = \begin{pmatrix} d_0 & p_0 & 0 & 0 & \cdots & 0 \\ q_0 & d_1 & p_1 & 0 & \cdots & 0 \\ 0 & q_1 & d_2 & p_2 & \cdots & 0 \\ \vdots & \vdots & \ddots & \ddots & \ddots & \vdots \\ 0 & 0 & \cdots & q_{n-3} & d_{n-2} & p_{n-2} \\ 0 & 0 & \cdots & 0 & q_{n-2} & d_{n-1} \end{pmatrix} \begin{pmatrix} x_0 \\ x_1 \\ x_2 \\ x_3 \\ \vdots \\ x_{n-1} \end{pmatrix}.$$

This is useful for solving problems on the type

$$a_i = b_i a_{i-1} + c_i a_{i+1} + d_i, \quad 1 \leq i \leq n,$$

where  $a_0, a_{n+1}, b_i, c_i$  and  $d_i$  are known.  $a$  can then be obtained from

$$\{a_i\} = \text{tridiagonal}(\{1, -1, -1, \dots, -1, 1\}, \{0, c_1, c_2, \dots, c_n\}, \{b_1, b_2, \dots, b_n, 0\}, \{a_0, d_1, d_2, \dots, d_n, a_{n+1}\}).$$

Fails if the solution is not unique.

If  $|d_i| > |p_i| + |q_{i-1}|$  for all  $i$ , or  $|d_i| > |p_{i-1}| + |q_i|$ , or the matrix is positive definite, the algorithm is numerically stable and neither `tr` nor the check for `diag[i] == 0` is needed.

Time:  $\mathcal{O}(N)$ 

8f9fa8, 26 lines

```
typedef double T;
vector<T> tridiagonal(vector<T> diag, const vector<T>& super,
                       const vector<T>& sub, vector<T> b) {
    int n = sz(b); vi tr(n);
    rep(i, 0, n-1) {
        if (abs(diag[i]) < 1e-9 * abs(super[i])) { // diag[i] == 0
            b[i+1] -= b[i] * diag[i+1] / super[i];
            if (i+2 < n) b[i+2] -= b[i] * sub[i+1] / super[i];
            diag[i+1] = sub[i]; tr[++i] = 1;
        } else {
            diag[i+1] -= super[i] * sub[i] / diag[i];
            b[i+1] -= b[i] * sub[i] / diag[i];
        }
    }
    for (int i = n; i--;) {
        if (tr[i]) {
            swap(b[i], b[i-1]);
            diag[i-1] = diag[i];
            b[i] /= super[i-1];
        } else {
            b[i] /= diag[i];
            if (i) b[i-1] -= b[i] * super[i-1];
        }
    }
    return b;
}
```

**4.4 Fourier transforms****FastFourierTransform.h**

**Description:**  $\text{fft}(a)$  computes  $\hat{f}(k) = \sum_x a[x] \exp(2\pi i \cdot kx/N)$  for all  $k$ .  $N$  must be a power of 2. Useful for convolution:  $\text{conv}(a, b) = c$ , where  $c[x] = \sum a[i]b[x-i]$ . For convolution of complex numbers or more than two vectors: FFT, multiply pointwise, divide by  $n$ , reverse(start+1, end), FFT back. Rounding is safe if  $(\sum a_i^2 + \sum b_i^2) \log_2 N < 9 \cdot 10^{14}$  (in practice  $10^{16}$ ; higher for random inputs). Otherwise, use NTT/FFTMod.

Time:  $\mathcal{O}(N \log N)$  with  $N = |A| + |B|$  ( $\sim 1s$  for  $N = 2^{22}$ ) 00ced6, 35 lines

```
typedef complex<double> C;
typedef vector<double> vd;
void fft(vector<C>& a) {
    int n = sz(a), L = 31 - __builtin_clz(n);
    static vector<complex<long double>> R(2, 1);
    static vector<C> rt(2, 1); // (^ 10% faster if double)
    for (static int k = 2; k < n; k *= 2) {
        R.resize(n); rt.resize(n);
        auto x = polar(1.0L, acos(-1.0L) / k);
        rep(i, k, 2*k) rt[i] = R[i] = i&1 ? R[i/2] * x : R[i/2];
    }
    vi rev(n);
    rep(i, 0, n) rev[i] = (rev[i / 2] | (i & 1) << L) / 2;
    rep(i, 0, n) if (i < rev[i]) swap(a[i], a[rev[i]]);
    for (int k = 1; k < n; k *= 2)
        for (int i = 0; i < n; i += 2 * k) rep(j, 0, k) {
            C z = rt[j+k] * a[i+j+k]; // (25% faster if hand-rolled)
            a[i + j + k] = a[i + j] - z;
            a[i + j] += z;
        }
    }
    vd conv(const vd& a, const vd& b) {
        if (a.empty() || b.empty()) return {};
        vd res(sz(a) + sz(b) - 1);
        int L = 32 - __builtin_clz(sz(res)), n = 1 << L;
        vector<C> in(n), out(n);
        copy(all(a), begin(in));
        rep(i, 0, sz(b)) in[i].imag(b[i]);
        fft(in);
        for (C &x : in) x *= x;
        rep(i, 0, n) out[i] = in[-i & (n - 1)] - conj(in[i]);
        fft(out);
        rep(i, 0, sz(res)) res[i] = imag(out[i]) / (4 * n);
        return res;
    }
}
```

**FastFourierTransformMod.h**

**Description:** Higher precision FFT, can be used for convolutions modulo arbitrary integers as long as  $N \log_2 N \cdot \text{mod} < 8.6 \cdot 10^{14}$  (in practice  $10^{16}$  or higher). Inputs must be in  $[0, \text{mod}]$ .

Time:  $\mathcal{O}(N \log N)$ , where  $N = |A| + |B|$  (twice as slow as NTT or FFT) FastFourierTransform.h b82773, 22 lines

```
typedef vector<ll> vl;
template<int M> vl convMod(const vl &a, const vl &b) {
    if (a.empty() || b.empty()) return {};
    vl res(sz(a) + sz(b) - 1);
    int B=32-__builtin_clz(sz(res)), n=1<<B, cut=__int(sqrt(M));
    vector<C> L(n), R(n), outs(n), outl(n);
    rep(i, 0, sz(a)) L[i] = C((int)a[i] / cut, (int)a[i] % cut);
    rep(i, 0, sz(b)) R[i] = C((int)b[i] / cut, (int)b[i] % cut);
    fft(L), fft(R);
    rep(i, 0, n) {
        int j = -i & (n - 1);
        outl[j] = (L[i] + conj(L[j])) * R[i] / (2.0 * n);
        outs[j] = (L[i] - conj(L[j])) * R[i] / (2.0 * n) / li;
    }
    fft(outl), fft(outs);
    rep(i, 0, sz(res)) {
}
```

```

11 av = ll(real(outl[i])+.5), cv = ll(imag(outs[i])+.5);
11 bv = ll(imag(outl[i])+.5) + ll(real(outs[i])+.5);
res[i] = ((av % M * cut + bv) % M * cut + cv) % M;
}
return res;
}

```

## NumberTheoreticTransform.h

**Description:** ntta(a) computes  $\hat{f}(k) = \sum_x a[x]g^{xk}$  for all  $k$ , where  $g = \text{root}^{(mod-1)/N}$ .  $N$  must be a power of 2. Useful for convolution modulo specific nice primes of the form  $2^a + 1$ , where the convolution result has size at most  $2^a$ . For arbitrary modulo, see FFTMod. conv(a, b) = c, where  $c[x] = \sum a[i]b[x-i]$ . For manual convolution: NTT the inputs, multiply pointwise, divide by n, reverse(start+1, end), NTT back. Inputs must be in [0, mod).

**Time:**  $\mathcal{O}(N \log N)$

.../number-theory/ModPow.h" ced03d, 35 lines

```

const ll mod = (119 << 23) + 1, root = 62; // = 998244353
// For p < 2^30 there is also e.g. 5 << 25, 7 << 26, 479 << 21
// and 483 << 21 (same root). The last two are > 10^9.
typedef vector<ll> vl;
void ntta(vl &a) {
    int n = sz(a), L = 31 - __builtin_clz(n);
    static vl rt(2, 1);
    for (static int k = 2, s = 2; k < n; k *= 2, s++) {
        rt.resize(n);
        ll z[] = {1, modpow(root, mod >> s)};
        rep(i, k, 2*k) rt[i] = rt[i / 2] * z[i & 1] % mod;
    }
    vi rev(n);
    rep(i, 0, n) rev[i] = (rev[i / 2] | (i & 1) << L) / 2;
    rep(i, 0, n) if (i < rev[i]) swap(a[i], a[rev[i]]);
    for (int k = 1; k < n; k *= 2)
        for (int i = 0; i < n; i += 2 * k) rep(j, 0, k) {
            ll z = rt[j + k] * a[i + j + k] % mod, &ai = a[i + j];
            a[i + j + k] = ai - z + (z > ai ? mod : 0);
            ai += (ai + z >= mod ? z - mod : z);
        }
}

```

```

vl conv(const vl &a, const vl &b) {
    if (a.empty() || b.empty()) return {};
    int s = sz(a) + sz(b) - 1, B = 32 - __builtin_clz(s),
        n = 1 << B;
    int inv = modpow(n, mod - 2);
    vl L(a), R(b), out(n);
    L.resize(n), R.resize(n);
    ntt(L), ntt(R);
    rep(i, 0, n)
        out[-i & (n - 1)] = (ll)L[i] * R[i] % mod * inv % mod;
    ntt(out);
    return {out.begin(), out.begin() + s};
}

```

## FastSubsetTransform.h

**Description:** Transform to a basis with fast convolutions of the form  $c[z] = \sum_{z=x \oplus y} a[x] \cdot b[y]$ , where  $\oplus$  is one of AND, OR, XOR. The size of  $a$  must be a power of two.

**Time:**  $\mathcal{O}(N \log N)$

464cf3, 16 lines

```

void FST(vi& a, bool inv) {
    for (int n = sz(a), step = 1; step < n; step *= 2) {
        for (int i = 0; i < n; i += 2 * step) rep(j, i, i+step) {
            int &u = a[j], &v = a[j + step]; tie(u, v) =
                inv ? pii(v - u, u) : pii(v, u + v); // AND
                inv ? pii(v, u - v) : pii(u + v, u); // OR
                pii(u + v, u - v); // XOR
        }
    }
}

```

```

    if (inv) for (int& x : a) x /= sz(a); // XOR only
}
vi conv(vi a, vi b) {
    FST(a, 0); FST(b, 0);
    rep(i, 0, sz(a)) a[i] *= b[i];
    FST(a, 1); return a;
}

```

## Number theory (5)

## 5.1 Modular arithmetic

## ModularArithmetic.h

**Description:** Operators for modular arithmetic. You need to set mod to some number first and then you can use the structure.

```

"euclid.h" 35bfea, 18 lines
const ll mod = 17; // change to something else
struct Mod {
    ll x;
    Mod(ll xx) : x(xx) {}
    Mod operator+(Mod b) { return Mod((x + b.x) % mod); }
    Mod operator-(Mod b) { return Mod((x - b.x + mod) % mod); }
    Mod operator*(Mod b) { return Mod((x * b.x) % mod); }
    Mod operator/(Mod b) { return *this * invert(b); }
    Mod invert(Mod a) {
        ll x, y, g = euclid(a.x, mod, x, y);
        assert(g == 1); return Mod((x + mod) % mod);
    }
    Mod operator^(ll e) {
        if (!e) return Mod(1);
        Mod r = *this ^ (e / 2); r = r * r;
        return e & 1 ? *this * r : r;
    }
};

```

## ModInverse.h

**Description:** Pre-computation of modular inverses. Assumes LIM  $\leq$  mod and that mod is a prime.

```

const ll mod = 1000000007, LIM = 200000;
ll* inv = new ll[LIM] - 1; inv[1] = 1;
rep(i, 2, LIM) inv[i] = mod - (mod / i) * inv[mod % i] % mod;

```

## ModPow.h

b83e45, 8 lines

```

const ll mod = 1000000007; // faster if const
ll modpow(ll b, ll e) {
    ll ans = 1;
    for (; e; b = b * b % mod, e /= 2)
        if (e & 1) ans = ans * b % mod;
    return ans;
}

```

## ModLog.h

**Description:** Returns the smallest  $x > 0$  s.t.  $a^x \equiv b \pmod{m}$ , or -1 if no such  $x$  exists. modLog(a, 1, m) can be used to calculate the order of  $a$ .

**Time:**  $\mathcal{O}(\sqrt{m})$

c040b8, 11 lines

```

ll modLog(ll a, ll b, ll m) {
    ll n = (ll)sqrt(m) + 1, e = 1, f = 1, j = 1;
    unordered_map<ll, ll> A;
    while (j <= n && (e = f = e * a % m) != b % m)
        A[e * b % m] = j++;
    if (e == b % m) return j;
    if (__gcd(m, e) == __gcd(m, b))
        rep(i, 2, n+2) if (A.count(e = e * f % m))
            return n * i - A[e];
}

```

```

    return -1;
}

```

## ModSum.h

**Description:** Sums of mod'ed arithmetic progressions.

$\text{modsum}(t_0, c, k, m) = \sum_{i=0}^{t_0-1} (ki + c) \% m$ . divsum is similar but for floored division.

**Time:**  $\log(m)$ , with a large constant.

5c5bc5, 16 lines

```

typedef unsigned long long ull;
ull sumsq(ull to) { return to / 2 * ((to-1) | 1); }

```

```

ull divsum(ull to, ull c, ull k, ull m) {
    ull res = k / m * sumsq(to) + c / m * to;
    k %= m; c %= m;
    if (!k) return res;
    ull to2 = (to * k + c) / m;
    return res + (to - 1) * to2 - divsum(to2, m-1 - c, m, k);
}

```

```

ll modsum(ull to, ll c, ll k, ll m) {
    c = ((c % m) + m) % m;
    k = ((k % m) + m) % m;
    return to * c + k * sumsq(to) - m * divsum(to, c, k, m);
}

```

## ModMulLL.h

**Description:** Calculate  $a \cdot b \pmod{c}$  (or  $a^b \pmod{c}$ ) for  $0 \leq a, b \leq c \leq 7.2 \cdot 10^{18}$ .

**Time:**  $\mathcal{O}(1)$  for modmul,  $\mathcal{O}(\log b)$  for modpow

bbbd8f, 11 lines

```

typedef unsigned long long ull;
ull modmul(ull a, ull b, ull M) {
    ll ret = a * b - M * ull(1.L / M * a * b);
    return ret + M * (ret < 0) - M * (ret >= (11.M));
}
ull modpow(ull b, ull e, ull mod) {
    ull ans = 1;
    for (; e; b = modmul(b, b, mod), e /= 2)
        if (e & 1) ans = modmul(ans, b, mod);
    return ans;
}

```

## ModSqrt.h

**Description:** Tonelli-Shanks algorithm for modular square roots. Finds  $x$  s.t.  $x^2 \equiv a \pmod{p}$  ( $-x$  gives the other solution).

**Time:**  $\mathcal{O}(\log^2 p)$  worst case,  $\mathcal{O}(\log p)$  for most  $p$

"ModPow.h" 19a793, 24 lines

```

ll sqrt(ll a, ll p) {
    a %= p; if (a < 0) a += p;
    if (a == 0) return 0;
    assert(modpow(a, (p-1)/2, p) == 1); // else no solution
    if (p % 4 == 3) return modpow(a, (p+1)/4, p);
    // a^(n+3)/8 or 2^(n+3)/8 * 2^(n-1)/4 works if p % 8 == 5
    ll s = p - 1, n = 2;
    int r = 0, m;
    while (s % 2 == 0)
        ++r, s /= 2;
    while (modpow(n, (p - 1) / 2, p) != p - 1) ++n;
    ll x = modpow(a, (s + 1) / 2, p);
    ll b = modpow(a, s, p), g = modpow(n, s, p);
    for (; r = m) {
        ll t = b;
        for (m = 0; m < r && t != 1; ++m)
            t = t * t % p;
        if (m == 0) return x;
        ll gs = modpow(g, 1LL << (r - m - 1), p);
        g = gs * gs % p;
        x = x * gs % p;
        b = b * g % p;
    }
}

```

}

## PrimitiveRoot.h

**Description:** Calculates primitive root modulo p. p is prime, to make it work with any number, add the calculation of phi(p)

a14d60, 33 lines

```
int p_root(int p) {
    // divisores de phi (p primo -> phi = p - 1)
    vi facts;
    int phi = p - 1, n = phi;
    for(int i = 2; i * i <= n; i++) {
        if(n % i == 0) {
            facts.push_back(i);
            while(n % i == 0) n /= i;
        }
    }
    if(n > 1) facts.push_back(n);

    auto bp = [&](int a, int b) {
        int res = 1;
        while(b) {
            if(b & 1) res = 1LL * res * a % p;
            a = 1LL * a * a % p;
            b >>= 1;
        }
        return res;
    };

    rep(res, 2, p+1) {
        bool ok = true;
        for(int f : facts) {
            // binpow modulo p
            ok &= (bp(res, phi/f) != 1);
            if(!ok) break;
        }
        if(ok) return res;
    }
    assert(false); // por si acaso
}
```

## 5.2 Primality

## FastEratosthenes.h

**Description:** Prime sieve for generating all primes smaller than LIM.

**Time:**  $LIM=1e9 \approx 1.5s$

6b2912, 20 lines

```
const int LIM = 1e6;
bitset<LIM> isPrime;
vi eratosthenes() {
    const int S = (int)round(sqrt(LIM)), R = LIM / 2;
    vi pr = {2}, sieve(S+1); pr.reserve(int(LIM/log(LIM)*1.1));
    vector<pii> cp;
    for (int i = 3; i <= S; i += 2) if (!sieve[i]) {
        cp.push_back({i, i * i / 2});
        for (int j = i * i; j <= S; j += 2 * i) sieve[j] = 1;
    }
    for (int L = 1; L <= R; L += S) {
        array<bool, S> block{};
        for (auto &[p, idx] : cp)
            for (int i=idx; i < S+L; idx = (i+=p)) block[i-L] = 1;
        rep(i, 0, min(S, R - L))
            if (!block[i]) pr.push_back((L + i) * 2 + 1);
    }
    for (int i : pr) isPrime[i] = 1;
    return pr;
}
```

## MillerRabin.h

**Description:** Deterministic Miller-Rabin primality test. Guaranteed to work for numbers up to  $7 \cdot 10^{18}$ ; for larger numbers, use Python and extend A randomly.

**Time:** 7 times the complexity of  $a^b \pmod{c}$ .

"ModMullL.h" 60dcd1, 12 lines

```
bool isPrime(ull n) {
    if (n < 2 || n % 6 % 4 != 1) return (n | 1) == 3;
    ull A[] = {2, 325, 9375, 28178, 450775, 9780504, 1795265022},
        s = __builtin_ctzll(n-1), d = n >> s;
    for (ull a : A) { // count trailing zeroes
        ull p = modpow(a%n, d, n), i = s;
        while (p != 1 && p != n - 1 && a % n && i--)
            p = modmul(p, p, n);
        if (p != n-1 && i != s) return 0;
    }
    return 1;
}
```

## Factor.h

**Description:** Pollard-rho randomized factorization algorithm. Returns prime factors of a number, in arbitrary order (e.g.  $2299 \rightarrow \{11, 19, 11\}$ ).

**Time:**  $\mathcal{O}(n^{1/4})$ , less for numbers with small factors.

"ModMullL.h", "MillerRabin.h" d8d98d, 18 lines

```
ull pollard(ull n) {
    ull x = 0, y = 0, t = 30, prd = 2, i = 1, q;
    auto f = [&](ull x) { return modmul(x, x, n) + i; };
    while (t++ % 40 || __gcd(prd, n) == 1) {
        if (x == y) x = ++i, y = f(x);
        if ((q = modmul(prd, max(x,y) - min(x,y), n))) prd = q;
        x = f(x), y = f(f(y));
    }
    return __gcd(prd, n);
}

vector<ull> factor(ull n) {
    if (n == 1) return {};
    if (isPrime(n)) return {n};
    ull x = pollard(n);
    auto l = factor(x), r = factor(n / x);
    l.insert(l.end(), all(r));
    return l;
}
```

## 5.3 Divisibility

## euclid.h

**Description:** Finds two integers  $x$  and  $y$ , such that  $ax + by = \gcd(a, b)$ . If you just need gcd, use the built in `_gcd` instead. If  $a$  and  $b$  are coprime, then  $x$  is the inverse of  $a \pmod{b}$ .

33ba8f, 5 lines

```
11 euclid(ll a, ll b, ll &x, ll &y) {
    if (!b) return x = 1, y = 0, a;
    ll d = euclid(b, a % b, y, x);
    return y -= a/b * x, d;
}
```

## CRT.h

**Description:** Chinese Remainder Theorem.

`crt(a, m, b, n)` computes  $x$  such that  $x \equiv a \pmod{m}$ ,  $x \equiv b \pmod{n}$ . If  $|a| < m$  and  $|b| < n$ ,  $x$  will obey  $0 \leq x < \text{lcm}(m, n)$ . Assumes  $mn < 2^{62}$ .

**Time:**  $\log(n)$

"euclid.h" 04d93a, 7 lines

```
11 crt(ll a, ll m, ll b, ll n) {
    if (n > m) swap(a, b), swap(m, n);
    ll x, y, g = euclid(m, n, x, y);
    assert((a - b) % g == 0); // else no solution
    x = (b - a) % n * x % n / g * m + a;
    return x < 0 ? x + m*n/g : x;
}
```

}

## 5.3.1 Bézout's identity

For  $a \neq b \neq 0$ , then  $d = \gcd(a, b)$  is the smallest positive integer for which there are integer solutions to

$$ax + by = d$$

If  $(x, y)$  is one solution, then all solutions are given by

$$\left( x + \frac{kb}{\gcd(a, b)}, y - \frac{ka}{\gcd(a, b)} \right), \quad k \in \mathbb{Z}$$

## phiFunction.h

**Description:** Euler's  $\phi$  function is defined as  $\phi(n) := \#$  of positive integers  $\leq n$  that are coprime with  $n$ .  $\phi(1) = 1$ ,  $p$  prime  $\Rightarrow \phi(p^k) = (p-1)p^{k-1}$ ,  $m, n$  coprime  $\Rightarrow \phi(mn) = \phi(m)\phi(n)$ . If  $n = p_1^{k_1}p_2^{k_2}\dots p_r^{k_r}$  then  $\phi(n) = (p_1 - 1)p_1^{k_1 - 1}\dots(p_r - 1)p_r^{k_r - 1}$ .  $\phi(n) = n \cdot \prod_{p|n} (1 - 1/p)$ .

$\sum_{d|n} \phi(d) = n$ ,  $\sum_{1 \leq k \leq n, \gcd(k, n)=1} k = n\phi(n)/2$ ,  $n > 1$

**Euler's thm:**  $a, n$  coprime  $\Rightarrow a^{\phi(n)} \equiv 1 \pmod{n}$ .

**Fermat's little thm:**  $p$  prime  $\Rightarrow a^{p-1} \equiv 1 \pmod{p} \forall a$ .

cf7d6d, 8 lines

```
const int LIM = 5000000;
int phi[LIM];
```

```
void calculatePhi() {
    rep(i, 0, LIM) phi[i] = i & 1 ? i : i/2;
    for (int i = 3; i < LIM; i += 2) if(phi[i] == i)
        for (int j = i; j < LIM; j += i) phi[j] -= phi[j] / i;
}
```

## 5.4 Fractions

## ContinuedFractions.h

**Description:** Given  $N$  and a real number  $x \geq 0$ , finds the closest rational approximation  $p/q$  with  $p, q \leq N$ . It will obey  $|p/q - x| \leq 1/qN$ . For consecutive convergents,  $p_{k+1}q_k - q_{k+1}p_k = (-1)^k$ . ( $p_k/q_k$  alternates between  $> x$  and  $< x$ ) If  $x$  is rational,  $y$  eventually becomes  $\infty$ ; if  $x$  is the root of a degree 2 polynomial the  $a$ 's eventually become cyclic.

**Time:**  $\mathcal{O}(\log N)$

dd6c5e, 21 lines

```
typedef double d; // for N ~ 1e7; long double for N ~ 1e9
pair<ll, ll> approximate(d x, ll N) {
    ll LP = 0, LQ = 1, P = 1, Q = 0, inf = LLONG_MAX; d y = x;
    for (;;) {
        ll lim = min(P ? (N-LP) / P : inf, Q ? (N-LQ) / Q : inf),
            a = (ll)floor(y), b = min(a, lim),
            NP = b*P + LP, NQ = b*Q + LQ;
        if (a > b) {
            // If b > a/2, we have a semi-convergent that gives us a
            // better approximation; if b = a/2, we *may* have one.
            // Return {P, Q} here for a more canonical approximation.
            return (abs(x - (d)NP / (d)NQ) < abs(x - (d)P / (d)Q)) ?
                make_pair(NP, NQ) : make_pair(P, Q);
        }
        if (abs(y = 1/(y - (d)a)) > 3*N) {
            return {NP, NQ};
        }
        LP = P; P = NP;
        LQ = Q; Q = NQ;
    }
}
```

## FracBinarySearch.h

**Description:** Given  $f$  and  $N$ , finds the smallest fraction  $p/q \in [0, 1]$  such that  $f(p/q)$  is true, and  $p, q \leq N$ . You may want to throw an exception from  $f$  if it finds an exact solution, in which case  $N$  can be removed.

**Usage:** `fracBS([](Frac f) { return f.p>=3*f.q; }, 10); // {1,3}`  
**Time:**  $\mathcal{O}(\log(N))$       27ab3e, 25 lines

**struct** Frac { ll p, q; };

```
template<class F>
Frac fracBS(F f, ll N) {
    bool dir = 1, A = 1, B = 1;
    Frac lo{0, 1}, hi{1, 1}; // Set hi to 1/0 to search (0, N]
    if (f(lo)) return lo;
    assert(f(hi));
    while (A || B) {
        ll adv = 0, step = 1; // move hi if dir, else lo
        for (int si = 0; step; (step *= 2) >= si) {
            adv += step;
            Frac mid{lo.p * adv + hi.p, lo.q * adv + hi.q};
            if (abs(mid.p) > N || mid.q > N || dir == !f(mid)) {
                adv -= step; si = 2;
            }
        }
        hi.p += lo.p * adv;
        hi.q += lo.q * adv;
        dir = !dir;
        swap(lo, hi);
        A = B; B = !!adv;
    }
    return dir ? hi : lo;
}
```

## 5.5 Pythagorean Triples

The Pythagorean triples are uniquely generated by

$$a = k \cdot (m^2 - n^2), \quad b = k \cdot (2mn), \quad c = k \cdot (m^2 + n^2),$$

with  $m > n > 0$ ,  $k > 0$ ,  $m \perp n$ , and either  $m$  or  $n$  even.

## 5.6 Primes

$p = 962592769$  is such that  $2^{21} \mid p - 1$ , which may be useful. For hashing use 970592641 (31-bit number), 31443539979727 (45-bit), 3006703054056749 (52-bit). There are 78498 primes less than 1 000 000.

Primitive roots exist modulo any prime power  $p^a$ , except for  $p = 2, a > 2$ , and there are  $\phi(\phi(p^a))$  many. For  $p = 2, a > 2$ , the group  $\mathbb{Z}_{2^a}^\times$  is instead isomorphic to  $\mathbb{Z}_2 \times \mathbb{Z}_{2^{a-2}}$ .

## 5.7 Estimates

$$\sum_{d|n} d = O(n \log \log n).$$

The number of divisors of  $n$  is at most around 100 for  $n < 5e4$ , 500 for  $n < 1e7$ , 2000 for  $n < 1e10$ , 200 000 for  $n < 1e19$ .

## 5.8 Möbius Function

$$\mu(n) = \begin{cases} 0 & n \text{ is not square free} \\ 1 & n \text{ has even number of prime factors} \\ -1 & n \text{ has odd number of prime factors} \end{cases}$$

Möbius Inversion:

$$g(n) = \sum_{d|n} f(d) \Leftrightarrow f(n) = \sum_{d|n} \mu(d)g(n/d)$$

## IntPerm multinomial

Other useful formulas/forms:

$$\sum_{d|n} \mu(d) = [n = 1] \text{ (very useful)}$$

$$g(n) = \sum_{n|d} f(d) \Leftrightarrow f(n) = \sum_{n|d} \mu(d/n)g(d)$$

$$g(n) = \sum_{1 \leq m \leq n} f(\lfloor \frac{n}{m} \rfloor) \Leftrightarrow f(n) = \sum_{1 \leq m \leq n} \mu(m)g(\lfloor \frac{n}{m} \rfloor)$$

## Combinatorial (6)

### 6.1 Permutations

#### 6.1.1 Factorial

$n$	1	2	3	4	5	6	7	8	9	10
$n!$	1	2	6	24	120	720	5040	40320	362880	3628800
$n$	11	12	13	14	15	16	17			
$n!$	4.0e7	4.8e8	6.2e9	8.7e10	1.3e12	2.1e13	3.6e14			
$n$	20	25	30	40	50	100	150			
$n!$	2e18	2e25	3e32	8e47	3e64	9e157	6e262	>DBL_MAX		

IntPerm.h

**Description:** Permutation  $\rightarrow$  integer conversion. (Not order preserving.) Integer  $\rightarrow$  permutation can use a lookup table.

**Time:**  $\mathcal{O}(n)$  Hola toy saludando

044568, 6 lines

```
int permToInt(vi& v) {
    int use = 0, i = 0, r = 0;
    for(int x:v) r = r * ++i + __builtin_popcount(use & -(1<<x));
    use |= 1 << x; // (note: minus, not ~!)
    return r;
}
```

#### 6.1.2 Cycles

Let  $g_S(n)$  be the number of  $n$ -permutations whose cycle lengths all belong to the set  $S$ . Then

$$\sum_{n=0}^{\infty} g_S(n) \frac{x^n}{n!} = \exp\left(\sum_{n \in S} \frac{x^n}{n}\right)$$

#### 6.1.3 Derangements

Permutations of a set such that none of the elements appear in their original position.

$$D(n) = (n-1)(D(n-1) + D(n-2)) = nD(n-1) + (-1)^n = \left\lfloor \frac{n!}{e} \right\rfloor$$

#### 6.1.4 Burnside's lemma

Given a group  $G$  of symmetries and a set  $X$ , the number of elements of  $X$  up to symmetry equals

$$\frac{1}{|G|} \sum_{g \in G} |X^g|,$$

where  $X^g$  are the elements fixed by  $g$  ( $g.x = x$ ).

If  $f(n)$  counts “configurations” (of some sort) of length  $n$ , we can ignore rotational symmetry using  $G = \mathbb{Z}_n$  to get

$$g(n) = \frac{1}{n} \sum_{k=0}^{n-1} f(\gcd(n, k)) = \frac{1}{n} \sum_{k|n} f(k)\phi(n/k).$$

## 6.2 Partitions and subsets

### 6.2.1 Partition function

Number of ways of writing  $n$  as a sum of positive integers, disregarding the order of the summands.

$$p(0) = 1, \quad p(n) = \sum_{k \in \mathbb{Z} \setminus \{0\}} (-1)^{k+1} p(n - k(3k - 1)/2)$$

$$p(n) \sim 0.145/n \cdot \exp(2.56\sqrt{n})$$

$n$	0	1	2	3	4	5	6	7	8	9	20	50	100
$p(n)$	1	1	2	3	5	7	11	15	22	30	627	$\sim 2e5$	$\sim 2e8$

### 6.2.2 Lucas' Theorem

Let  $n, m$  be non-negative integers and  $p$  a prime. Write  $n = n_k p^k + \dots + n_1 p + n_0$  and  $m = m_k p^k + \dots + m_1 p + m_0$ . Then  $\binom{n}{m} \equiv \prod_{i=0}^k \binom{n_i}{m_i} \pmod{p}$ .

### 6.2.3 Binomials

multinomial.h

**Description:** Computes  $\binom{k_1 + \dots + k_n}{k_1, k_2, \dots, k_n} = \frac{(\sum k_i)!}{k_1! k_2! \dots k_n!}$

```
ll multinomial(vi& v) {
    ll c = 1, m = v.empty() ? 1 : v[0];
    rep(i, 1, sz(v)) rep(j, 0, v[i]) c = c * ++m / (j+1);
    return c;
}
```

## 6.3 General purpose numbers

### 6.3.1 Bernoulli numbers

EGF of Bernoulli numbers is  $B(t) = \frac{t}{e^t - 1}$  (FFT-able).

$$B[0, \dots] = [1, -\frac{1}{2}, \frac{1}{6}, 0, -\frac{1}{30}, 0, \frac{1}{42}, \dots]$$

Sums of powers:

$$\sum_{i=1}^n n^m = \frac{1}{m+1} \sum_{k=0}^m \binom{m+1}{k} B_k \cdot (n+1)^{m+1-k}$$

Euler-Maclaurin formula for infinite sums:

$$\sum_{i=m}^{\infty} f(i) = \int_m^{\infty} f(x)dx - \sum_{k=1}^{\infty} \frac{B_k}{k!} f^{(k-1)}(m) \\ \approx \int_m^{\infty} f(x)dx + \frac{f(m)}{2} - \frac{f'(m)}{12} + \frac{f''(m)}{720} + O(f^{(5)}(m))$$

### 6.3.2 Stirling numbers of the first kind

Number of permutations on  $n$  items with  $k$  cycles.

$$c(n, k) = c(n-1, k-1) + (n-1)c(n-1, k), \quad c(0, 0) = 1$$

$$\sum_{k=0}^n c(n, k)x^k = x(x+1) \dots (x+n-1)$$

## UNSA-CC

$$c(8, k) = 8, 0, 5040, 13068, 13132, 6769, 1960, 322, 28, 1$$

$$c(n, 2) = 0, 0, 1, 3, 11, 50, 274, 1764, 13068, 109584, \dots$$

### 6.3.3 Eulerian numbers

Number of permutations  $\pi \in S_n$  in which exactly  $k$  elements are greater than the previous element.  $k$  j:s s.t.  $\pi(j) > \pi(j+1)$ ,  $k+1$  j:s s.t.  $\pi(j) \geq j$ ,  $k$  j:s s.t.  $\pi(j) > j$ .

$$E(n, k) = (n-k)E(n-1, k-1) + (k+1)E(n-1, k)$$

$$E(n, 0) = E(n, n-1) = 1$$

$$E(n, k) = \sum_{j=0}^k (-1)^j \binom{n+1}{j} (k+1-j)^n$$

### 6.3.4 Stirling numbers of the second kind

Partitions of  $n$  distinct elements into exactly  $k$  groups.

$$S(n, k) = S(n-1, k-1) + kS(n-1, k)$$

$$S(n, 1) = S(n, n) = 1$$

$$S(n, k) = \frac{1}{k!} \sum_{j=0}^k (-1)^{k-j} \binom{k}{j} j^n$$

### 6.3.5 Bell numbers

Total number of partitions of  $n$  distinct elements.  $B(n) = 1, 1, 2, 5, 15, 52, 203, 877, 4140, 21147, \dots$ . For  $p$  prime,

$$B(p^m + n) \equiv mB(n) + B(n+1) \pmod{p}$$

### 6.3.6 Labeled unrooted trees

# on  $n$  vertices:  $n^{n-2}$

# on  $k$  existing trees of size  $n_i$ :  $n_1 n_2 \cdots n_k n^{k-2}$

# with degrees  $d_i$ :  $(n-2)! / ((d_1-1)! \cdots (d_n-1)!)$

### 6.3.7 Catalan numbers

$$C_n = \frac{1}{n+1} \binom{2n}{n} = \binom{2n}{n} - \binom{2n}{n+1} = \frac{(2n)!}{(n+1)!n!}$$

$$C_0 = 1, C_{n+1} = \frac{2(2n+1)}{n+2} C_n, C_{n+1} = \sum C_i C_{n-i}$$

$C_n = 1, 1, 2, 5, 14, 42, 132, 429, 1430, 4862, 16796, 58786, \dots$

- sub-diagonal monotone paths in an  $n \times n$  grid.
- strings with  $n$  pairs of parenthesis, correctly nested.
- binary trees with  $n+1$  leaves (0 or 2 children).
- ordered trees with  $n+1$  vertices.
- ways a convex polygon with  $n+2$  sides can be cut into triangles by connecting vertices with straight lines.
- permutations of  $[n]$  with no 3-term increasing subseq.

## BellmanFord FloydWarshall TopoSort PushRelabel MinCostMaxFlow

### Graph (7)

#### 7.1 Fundamentals

##### BellmanFord.h

**Description:** Calculates shortest paths from  $s$  in a graph that might have negative edge weights. Unreachable nodes get  $\text{dist} = \text{inf}$ ; nodes reachable through negative-weight cycles get  $\text{dist} = -\text{inf}$ . Assumes  $V^2 \max|w_i| < \sim 2^{63}$ .

**Time:**  $\mathcal{O}(VE)$  830a8f, 23 lines

```
const ll inf = LLONG_MAX;
struct Ed { int a, b, w, s() { return a < b ? a : -a; } };
struct Node { ll dist = inf; int prev = -1; };

void bellmanFord(vector<Node>& nodes, vector<Ed>& eds, int s) {
    nodes[s].dist = 0;
    sort(all(eds), [](Ed a, Ed b) { return a.s() < b.s(); });

    int lim = sz(nodes) / 2 + 2; // /3+100 with shuffled vertices
    rep(i, 0, lim) for (Ed ed : eds) {
        Node cur = nodes[ed.a], &dest = nodes[ed.b];
        if (abs(cur.dist) == inf) continue;
        ll d = cur.dist + ed.w;
        if (d < dest.dist) {
            dest.prev = ed.a;
            dest.dist = (i < lim-1 ? d : -inf);
        }
    }
    rep(i, 0, lim) for (Ed e : eds) {
        if (nodes[e.a].dist == -inf)
            nodes[e.b].dist = -inf;
    }
}
```

##### FloydWarshall.h

**Description:** Calculates all-pairs shortest path in a directed graph that might have negative edge weights. Input is a distance matrix  $m$ , where  $m[i][j] = \text{inf}$  if  $i$  and  $j$  are not adjacent. As output,  $m[i][j]$  is set to the shortest distance between  $i$  and  $j$ ,  $\text{inf}$  if no path, or  $-\text{inf}$  if the path goes through a negative-weight cycle.

**Time:**  $\mathcal{O}(N^3)$  531245, 12 lines

```
const ll inf = 1LL << 62;
void floydWarshall(vector<vector<ll>>& m) {
    int n = sz(m);
    rep(i, 0, n) m[i][i] = min(m[i][i], 0LL);
    rep(k, 0, n) rep(i, 0, n) rep(j, 0, n)
        if (m[i][k] != inf && m[k][j] != inf) {
            auto newDist = max(m[i][k] + m[k][j], -inf);
            m[i][j] = min(m[i][j], newDist);
        }
    rep(k, 0, n) if (m[k][k] < 0) rep(i, 0, n) rep(j, 0, n)
        if (m[i][k] != inf && m[k][j] != inf) m[i][j] = -inf;
}
```

##### TopoSort.h

**Description:** Topological sorting. Given is an oriented graph. Output is an ordering of vertices, such that there are edges only from left to right. If there are cycles, the returned list will have size smaller than  $n$  – nodes reachable from cycles will not be returned.

**Time:**  $\mathcal{O}(|V| + |E|)$  d678d8, 8 lines

```
vi topoSort(const vector<vi>& gr) {
    vi indeg(sz(gr)), q;
    for (auto& li : gr) for (int x : li) indeg[x]++;
    rep(i, 0, sz(gr)) if (indeg[i] == 0) q.push_back(i);
    rep(j, 0, sz(q)) for (int x : gr[q[j]]) {
        if (--indeg[x] == 0) q.push_back(x);
    }
    return q;
}
```

}

### 7.2 Network flow

##### PushRelabel.h

**Description:** Push-relabel using the highest label selection rule and the gap heuristic. Quite fast in practice. To obtain the actual flow, look at positive values only.

**Time:**  $\mathcal{O}(V^2 \sqrt{E})$  0ae1d4, 48 lines

```
struct PushRelabel {
    struct Edge {
        int dest, back;
        ll f, c;
    };
    vector<vector<Edge>> g;
    vector<ll> ec;
    vector<Edge*> cur;
    vector<vi> hs; vi H;
    PushRelabel(int n) : g(n), ec(n), cur(n), hs(2*n), H(n) {}

    void addEdge(int s, int t, ll cap, ll rcap=0) {
        if (s == t) return;
        g[s].push_back({t, sz(g[t]), 0, cap});
        g[t].push_back({s, sz(g[s])-1, 0, rcap});
    }

    void addFlow(Edge& e, ll f) {
        Edge &back = g[e.dest][e.back];
        if (!ec[e.dest] && f) hs[H[e.dest]].push_back(e.dest);
        e.f += f; e.c -= f; ec[e.dest] += f;
        back.f -= f; back.c += f; ec[back.dest] -= f;
    }

    ll calc(int s, int t) {
        int v = sz(g); H[s] = v; ec[t] = 1;
        vi co(2*v); co[0] = v-1;
        rep(i, 0, v) cur[i] = g[i].data();
        for (Edge& e : g[s]) addFlow(e, e.c);

        for (int hi = 0;;) {
            while (hs[hi].empty()) if (!hi--) return -ec[s];
            int u = hs[hi].back(); hs[hi].pop_back();
            while (ec[u] > 0) // discharge u
                if (cur[u] == g[u].data() + sz(g[u])) {
                    H[u] = 1e9;
                    for (Edge& e : g[u]) if (e.c && H[u] > H[e.dest]+1)
                        H[u] = H[e.dest]+1, cur[u] = &e;
                    if (++co[H[u]], !--co[hi] && hi < v)
                        rep(i, 0, v) if (hi < H[i] && H[i] < v)
                            --co[H[i]], H[i] = v+1;
                    hi = H[u];
                } else if (cur[u]->c && H[u] == H[cur[u]->dest]+1)
                    addFlow(*cur[u], min(ec[u], cur[u]->c));
                else ++cur[u];
            }
            bool leftOfMinCut(int a) { return H[a] >= sz(g); }
        }
    }
};
```

##### MinCostMaxFlow.h

**Description:** Min-cost max-flow. If costs can be negative, call setpi before maxflow, but note that negative cost cycles are not supported. To obtain the actual flow, look at positive values only.

**Time:**  $\mathcal{O}(FE \log(V))$  where  $F$  is max flow.  $\mathcal{O}(VE)$  for setpi. 58385b, 79 lines

```
#include <bits/extc++.h>

const ll INF = numeric_limits<ll>::max() / 4;
```

```

struct MCMF {
    struct edge {
        int from, to, rev;
        ll cap, cost, flow;
    };
    int N;
    vector<vector<edge>> ed;
    vi seen;
    vector<ll> dist, pi;
    vector<edge*> par;

    MCMF(int N) : N(N), ed(N), seen(N), dist(N), pi(N), par(N) {}

    void addEdge(int from, int to, ll cap, ll cost) {
        if (from == to) return;
        ed[from].push_back(edge{ from,to,sz(ed[to]),cap,cost,0 });
        ed[to].push_back(edge{ to,from,sz(ed[from])-1,0,-cost,0 });
    }

    void path(int s) {
        fill(all(seen), 0);
        fill(all(dist), INF);
        dist[s] = 0; ll di;

        __gnu_pbds::priority_queue<pair<ll, int>> q;
        vector<decltype(q)::point_iterator> its(N);
        q.push({ 0, s });

        while (!q.empty()) {
            s = q.top().second; q.pop();
            seen[s] = 1; di = dist[s] + pi[s];
            for (edge& e : ed[s]) if (!seen[e.to]) {
                ll val = di - pi[e.to] + e.cost;
                if (e.cap - e.flow > 0 && val < dist[e.to]) {
                    dist[e.to] = val;
                    par[e.to] = &e;
                    if (its[e.to] == q.end())
                        its[e.to] = q.push({ -dist[e.to], e.to });
                    else
                        q.modify(its[e.to], { -dist[e.to], e.to });
                }
            }
        }
        rep(i,0,N) pi[i] = min(pi[i] + dist[i], INF);
    }

    pair<ll, ll> maxflow(int s, int t) {
        ll totflow = 0, totcost = 0;
        while (path(s), seen[t]) {
            ll fl = INF;
            for (edge* x = par[t]; x; x = par[x->from])
                fl = min(fl, x->cap - x->flow);

            totflow += fl;
            for (edge* x = par[t]; x; x = par[x->from])
                x->flow += fl;
            ed[x->to][x->rev].flow -= fl;
        }
        rep(i,0,N) for(edge& e : ed[i]) totcost += e.cost * e.flow;
        return {totflow, totcost/2};
    }

    // If some costs can be negative, call this before maxflow:
    void setpi(int s) { // (otherwise, leave this out)
        fill(all(pi), INF); pi[s] = 0;
        int it = N, ch = 1; ll v;
        while (ch-- && it--)
            rep(i,0,N) if (pi[i] != INF)
    }
}

```

## EdmondsKarp Dinic MinCut GlobalMinCut GomoryHu

```

        for (edge& e : ed[i]) if (e.cap)
            if ((v = pi[i] + e.cost) < pi[e.to])
                pi[e.to] = v, ch = 1;
            assert(it >= 0); // negative cost cycle
        }

EdmondsKarp.h
Description: Flow algorithm with guaranteed complexity  $O(VE^2)$ . To get edge flow values, compare capacities before and after, and take the positive values only. 482fe0, 36 lines

template<class T> T edmondsKarp(vector<unordered_map<int, T>>& graph, int source, int sink) {
    assert(source != sink);
    T flow = 0;
    vi par(sz(graph)), q = par;

    for (;;) {
        fill(all(par), -1);
        par[source] = 0;
        int ptr = 1;
        q[0] = source;

        rep(i,0,ptr) {
            int x = q[i];
            for (auto e : graph[x]) {
                if (par[e.first] == -1 && e.second > 0) {
                    par[e.first] = x;
                    q[ptr++] = e.first;
                    if (e.first == sink) goto out;
                }
            }
        }
        return flow;
    out:
        T inc = numeric_limits<T>::max();
        for (int y = sink; y != source; y = par[y])
            inc = min(inc, graph[par[y]][y]);

        flow += inc;
        for (int y = sink; y != source; y = par[y]) {
            int p = par[y];
            if ((graph[p][y] -= inc) <= 0) graph[p].erase(y);
            graph[y][p] += inc;
        }
    }
}

Dinic.h
Description: Flow algorithm with complexity  $O(VE \log U)$  where  $U = \max|\text{cap}|$ .  $O(\min(E^{1/2}, V^{2/3})E)$  if  $U = 1$ ;  $O(\sqrt{V}E)$  for bipartite matching. d7f0f1, 42 lines

struct Dinic {
    struct Edge {
        int to, rev;
        ll c, oc;
        ll flow() { return max(oc - c, 0LL); } // if you need flows
    };
    vi lvl, ptr, q;
    vector<vector<Edge>> adj;
    Dinic(int n) : lvl(n), ptr(n), q(n), adj(n) {}
    void addEdge(int a, int b, ll c, ll rcap = 0) {
        adj[a].push_back({b, sz(adj[b]), c, c});
        adj[b].push_back({a, sz(adj[a]) - 1, rcap, rcap});
    }
    ll dfs(int v, int t, ll f) {
        if (v == t || !f) return f;
        for (Edge& e : adj[v])

```

```

            for (int i = ptr[v]; i < sz(adj[v]); i++) {
                Edge& e = adj[v][i];
                if (lvl[e.to] == lvl[v] + 1)
                    if (ll p = dfs(e.to, t, min(f, e.c))) {
                        e.c -= p, adj[e.to][e.rev].c += p;
                        return p;
                    }
            }
            return 0;
        }
        ll calc(int s, int t) {
            ll flow = 0; q[0] = s;
            rep(L,0,31) do { // int L=30' maybe faster for random data
                lvl = ptr = vi(sz(q));
                int qi = 0, qe = lvl[s] = 1;
                while (qi < qe && !lvl[t]) {
                    int v = q[qi++];
                    for (Edge e : adj[v])
                        if (!lvl[e.to] && e.c >> (30 - L))
                            q[qe++] = e.to, lvl[e.to] = lvl[v] + 1;
                }
                while (ll p = dfs(s, t, LLONG_MAX)) flow += p;
            } while (lvl[t]);
            return flow;
        }
        bool leftOfMinCut(int a) { return lvl[a] != 0; }
    };

```

## MinCut.h

**Description:** After running max-flow, the left side of a min-cut from  $s$  to  $t$  is given by all vertices reachable from  $s$ , only traversing edges with positive residual capacity.

## GlobalMinCut.h

**Description:** Find a global minimum cut in an undirected graph, as represented by an adjacency matrix.

**Time:**  $\mathcal{O}(V^3)$  8b0e19, 21 lines

```

pair<int, vi> globalMinCut(vector<vi> mat) {
    pair<int, vi> best = {INT_MAX, {}};
    int n = sz(mat);
    vector<vi> co(n);
    rep(i,0,n) co[i] = {i};
    rep(ph,1,n) {
        vi w = mat[0];
        size_t s = 0, t = 0;
        rep(it,0,n-ph) { // O(V^2) -> O(E log V) with prio. queue
            w[t] = INT_MIN;
            s = t, t = max_element(all(w)) - w.begin();
            rep(i,0,n) w[i] += mat[t][i];
        }
        best = min(best, {w[t] - mat[t][t], co[t]});
        co[s].insert(co[s].end(), all(co[t]));
        rep(i,0,n) mat[s][i] += mat[t][i];
        rep(i,0,n) mat[i][s] = mat[s][i];
        mat[0][t] = INT_MIN;
    }
    return best;
}

```

## GomoryHu.h

**Description:** Given a list of edges representing an undirected flow graph, returns edges of the Gomory-Hu tree. The max flow between any pair of vertices is given by minimum edge weight along the Gomory-Hu tree path.

**Time:**  $\mathcal{O}(V)$  Flow Computations

```

"PushRelabel.h" 0418b3, 13 lines
typedef array<ll, 3> Edge;

```

```

vector<Edge> gomoryHu(int N, vector<Edge> ed) {
    vector<Edge> tree;
    vi par(N);
    rep(i,1,N) {
        PushRelabel D(N); // Dinic also works
        for (Edge t : ed) D.addEdge(t[0], t[1], t[2], t[2]);
        tree.push_back({i, par[i], D.calc(i, par[i])});
        rep(j,i+1,N)
            if (par[j] == par[i] && D.leftOfMinCut(j)) par[j] = i;
    }
    return tree;
}

```

## 7.3 Matching

hopcroftKarp.h

**Description:** Fast bipartite matching algorithm. Graph  $g$  should be a list of neighbors of the left partition, and  $btoa$  should be a vector full of -1's of the same size as the right partition. Returns the size of the matching.  $btoa[i]$  will be the match for vertex  $i$  on the right side, or -1 if it's not matched.

**Usage:** `vi btoa(m, -1); hopcroftKarp(g, btoa);`

**Time:**  $\mathcal{O}(\sqrt{V}E)$

f612e4, 42 lines

```

bool dfs(int a, int L, vector<vi>& g, vi& btoa, vi& A, vi& B) {
    if (A[a] != L) return 0;
    A[a] = -1;
    for (int b : g[a]) if (B[b] == L + 1) {
        B[b] = 0;
        if (btoa[b] == -1 || dfs(btoa[b], L + 1, g, btoa, A, B))
            return btoa[b] = a, 1;
    }
    return 0;
}

int hopcroftKarp(vector<vi>& g, vi& btoa) {
    int res = 0;
    vi A(g.size()), B(btoa.size()), cur, next;
    for (;;) {
        fill(all(A), 0);
        fill(all(B), 0);
        cur.clear();
        for (int a : btoa) if(a != -1) A[a] = -1;
        rep(a,0,sz(g)) if(A[a] == 0) cur.push_back(a);
        for (int lay = 1;; lay++)
            {
                bool islast = 0;
                next.clear();
                for (int a : cur) for (int b : g[a])
                    if (btoa[b] == -1) {
                        B[b] = lay;
                        islast = 1;
                    }
                else if (btoa[b] != a && !B[b]) {
                    B[b] = lay;
                    next.push_back(btoa[b]);
                }
                if (islast) break;
                if (next.empty()) return res;
                for (int a : next) A[a] = lay;
                cur.swap(next);
            }
        rep(a,0,sz(g))
            res += dfs(a, 0, g, btoa, A, B);
    }
}

```

DFSMatching.h

**Description:** Simple bipartite matching algorithm. Graph  $g$  should be a list of neighbors of the left partition, and  $btoa$  should be a vector full of -1's of the same size as the right partition. Returns the size of the matching.  $btoa[i]$  will be the match for vertex  $i$  on the right side, or -1 if it's not matched.

**Usage:** `vi btoa(m, -1); dfsMatching(g, btoa);`

**Time:**  $\mathcal{O}(VE)$

522b98, 22 lines

```

bool find(int j, vector<vi>& g, vi& btoa, vi& vis) {
    if (btoa[j] == -1) return 1;
    vis[j] = 1; int di = btoa[j];
    for (int e : g[di])
        if (!vis[e] && find(e, g, btoa, vis)) {
            btoa[e] = di;
            return 1;
        }
    return 0;
}

int dfsMatching(vector<vi>& g, vi& btoa) {
    vi vis;
    rep(i,0,sz(g)) {
        vis.assign(sz(btoa), 0);
        for (int j : g[i])
            if (find(j, g, btoa, vis)) {
                btoa[j] = i;
                break;
            }
    }
    return sz(btoa) - (int)count(all(btoa), -1);
}

```

MinimumVertexCover.h

**Description:** Finds a minimum vertex cover in a bipartite graph. The size is the same as the size of a maximum matching, and the complement is a maximum independent set.

DFSMatching.h

da4196, 20 lines

```

vi cover(vector<vi>& g, int n, int m) {
    vi match(m, -1);
    int res = dfsMatching(g, match);
    vector<bool> lfound(n, true), seen(m);
    for (int it : match) if (it != -1) lfound[it] = false;
    vi q, cover;
    rep(i,0,n) if (lfound[i]) q.push_back(i);
    while (!q.empty()) {
        int i = q.back(); q.pop_back();
        lfound[i] = 1;
        for (int e : g[i]) if (!seen[e] && match[e] != -1) {
            seen[e] = true;
            q.push_back(match[e]);
        }
    }
    rep(i,0,n) if (!lfound[i]) cover.push_back(i);
    rep(i,0,m) if (seen[i]) cover.push_back(n+i);
    assert(sz(cover) == res);
    return cover;
}

```

WeightedMatching.h

**Description:** Given a weighted bipartite graph, matches every node on the left with a node on the right such that no nodes are in two matchings and the sum of the edge weights is minimal. Takes cost[N][M], where cost[i][j] = cost for L[i] to be matched with R[j] and returns (min cost, match), where L[i] is matched with R[match[i]]. Negate costs for max cost. Requires  $N \leq M$ .

**Time:**  $\mathcal{O}(N^2M)$

1e0fe9, 31 lines

```

pair<int, vi> hungarian(const vector<vi> &a) {
    if (a.empty()) return {0, {}};
    int n = sz(a) + 1, m = sz(a[0]) + 1;
    vi u(n), v(m), p(m), ans(n - 1);
    rep(i,1,n) {

```

```

        p[i] = i;
        int j0 = 0; // add "dummy" worker 0
        vi dist(m, INT_MAX), pre(m, -1);
        vector<bool> done(m + 1);
        do { // dijkstra
            done[j0] = true;
            int i0 = p[j0], j1, delta = INT_MAX;
            rep(j,1,m) if (!done[j]) {
                auto cur = a[i0 - 1][j - 1] - u[i0] - v[j];
                if (cur < dist[j]) dist[j] = cur, pre[j] = j0;
                if (dist[j] < delta) delta = dist[j], j1 = j;
            }
            rep(j,0,m) {
                if (done[j]) u[p[j]] += delta, v[j] -= delta;
                else dist[j] -= delta;
            }
            j0 = j1;
        } while (p[j0]);
        while (j0) { // update alternating path
            int j1 = pre[j0];
            p[j0] = p[j1], j0 = j1;
        }
    }
    rep(j,1,m) if (p[j]) ans[p[j] - 1] = j - 1;
    return {-v[0], ans}; // min cost
}

```

GeneralMatching.h

**Description:** Matching for general graphs. Fails with probability  $N/mod$ .

**Time:**  $\mathcal{O}(N^3)$

...numerical/MatrixInverse-mod.h"

cb1912, 40 lines

```

vector<pii> generalMatching(int N, vector<pii>& ed) {
    vector<vector<ll>> mat(N, vector<ll>(N));
    for (pii pa : ed) {
        int a = pa.first, b = pa.second, r = rand() % mod;
        mat[a][b] = r, mat[b][a] = (mod - r) % mod;
    }

    int r = matInv(A = mat), M = 2*N - r, fi, fj;
    assert(r % 2 == 0);

    if (M != N) do {
        mat.resize(M, vector<ll>(M));
        rep(i,0,N) {
            mat[i].resize(M);
            rep(j,N,M) {
                int r = rand() % mod;
                mat[i][j] = r, mat[j][i] = (mod - r) % mod;
            }
        }
    } while (matInv(A = mat) != M);

    vi has(M, 1); vector<pii> ret;
    rep(it,0,M/2) {
        rep(i,0,M) if (has[i])
            rep(j,i+1,M) if (A[i][j] && mat[i][j]) {
                fi = i; fj = j; goto done;
            }
        assert(0); done:
        if (fj < N) ret.emplace_back(fi, fj);
        has[fi] = has[fj] = 0;
        rep(sw,0,2) {
            ll a = modpow(A[fi][fj], mod-2);
            rep(i,0,M) if (has[i] && A[i][fj]) {
                ll b = A[i][fj] * a % mod;
                rep(j,0,M) A[i][j] = (A[i][j] - A[fi][j] * b) % mod;
            }
            swap(fi,fj);
        }
    }
}

```

```
return ret;
}
```

## 7.4 DFS algorithms

### SCC.h

**Description:** Finds strongly connected components in a directed graph. If vertices  $u, v$  belong to the same component, we can reach  $u$  from  $v$  and vice versa.

**Usage:** `scc(graph, [&](vi& v) { ... })` visits all components in reverse topological order. `comp[i]` holds the component index of a node (a component only has edges to components with lower index). `ncomps` will contain the number of components.

**Time:**  $\mathcal{O}(E + V)$

76b5c9, 24 lines

```
vi val, comp, z, cont;
int Time, ncomps;
template<class G, class F> int dfs(int j, G& g, F& f) {
    int low = val[j] = ++Time, x; z.push_back(j);
    for (auto e : g[j]) if (comp[e] < 0)
        low = min(low, val[e] ?: dfs(e, g, f));
    if (low == val[j]) {
        do {
            x = z.back(); z.pop_back();
            comp[x] = ncomps;
            cont.push_back(x);
        } while (x != j);
        f(cont); cont.clear();
        ncomps++;
    }
    return val[j] = low;
}
template<class G, class F> void scc(G& g, F f) {
    int n = sz(g);
    val.assign(n, 0); comp.assign(n, -1);
    Time = ncomps = 0;
    rep(i, 0, n) if (comp[i] < 0) dfs(i, g, f);
}
```

### BiconnectedComponents.h

**Description:** Finds all biconnected components in an undirected graph, and runs a callback for the edges in each. In a biconnected component there are at least two distinct paths between any two nodes. Note that a node can be in several components. An edge which is not in a component is a bridge, i.e., not part of any cycle.

**Usage:** `int eid = 0; ed.resize(N);`

```
for each edge (a,b) {
    ed[a].emplace_back(b, eid);
    ed[b].emplace_back(a, eid++);
}
bicoms([&](const vi& edgelist) {...});
Time:  $\mathcal{O}(E + V)$ 
```

c6b7c7, 32 lines

```
vi num, st;
vector<vector<pii>> ed;
int Time;
template<class F>
int dfs(int at, int par, F& f) {
    int me = num[at] = ++Time, top = me;
    for (auto [y, e] : ed[at]) if (e != par) {
        if (num[y]) {
            top = min(top, num[y]);
            if (num[y] < me)
                st.push_back(e);
        } else {
            int si = sz(st);
            int up = dfs(y, e, f);
            top = min(top, up);
            if (up == me)
                st.push_back(e);
        }
    }
}
```

```
f(vi(st.begin() + si, st.end()));
st.resize(si);
}
else if (up < me) st.push_back(e);
else /* e is a bridge */
}
return top;
}

template<class F>
void bicoms(F f) {
    num.assign(sz(ed), 0);
    rep(i, 0, sz(ed)) if (!num[i]) dfs(i, -1, f);
}

CentroidDecomposition.h
Description: Todo
```

11aa82, 114 lines

```
#pragma once
const int INF = 1e6;
const int LOG = 18;
struct CentroidDecomposition{
    vvi tree, cd;
    vi subt, par, ans, dep;
    vector<bool> removed;
    vvi up;
    int root;
    CentroidDecomposition(int n) : tree(n), cd(n), root(-1),
        subt(n), par(n), ans(n, INF), dep(n), removed(n) {
        up.assign(LOG, vi(n, -1));
    }

    void add_edge(int u, int v) {
        tree[u].push_back(v);
        tree[v].push_back(u);
    }

    int dfs(int u, int p = -1) {
        subt[u] = 1;
        for(int v : tree[u]) {
            if(removed[v] || v == p) continue;
            subt[u] += dfs(v, u);
        }
        return subt[u];
    }

    int find_centroid(int u, int comp_sz, int p = -1) {
        for(int v : tree[u]) {
            if(removed[v] || v == p) continue;
            if(2 * subt[v] > comp_sz) return find_centroid(v,
                comp_sz, u);
        }
        return u;
    }

    void decompose(int u, int p = -1) {
        int comp_sz = dfs(u);
        int centroid = find_centroid(u, comp_sz);
        if(root == -1) root = centroid;
        par[centroid] = p;
        if(p != -1) {
            cd[p].push_back(centroid);
            cd[centroid].push_back(p);
        }
        removed[centroid] = true;
        for(int v : tree[centroid]) {
            if(!removed[v]) decompose(v, centroid);
        }
    }
}
```

```
}
void dfs_LCA(int u, int p = -1) {
    if(p != -1) dep[u] = dep[p] + 1;
    up[0][u] = p;
    for(int v : tree[u]) if(v != p) {
        dfs_LCA(v, u);
    }
}

void init_LCA(int n) {
    dfs_LCA(0);
    for(int lg = 1; lg < LOG; lg++) {
        for(int i = 0; i < n; i++) {
            if(up[lg - 1][i] != -1)
                up[lg][i] = up[lg - 1][up[lg - 1][i]];
        }
    }
}

int lift(int u, int len) {
    while(len) {
        int jump = __builtin_ctz(len);
        u = up[jump][u];
        len &= (len - 1);
    }
    return u;
}

int LCA(int u, int v) {
    if(dep[u] > dep[v]) swap(u, v);
    v = lift(v, dep[v] - dep[u]);
    if(u == v) return u;
    for(int lg = LOG - 1; lg >= 0; lg--) {
        if(up[lg][u] != up[lg][v]){
            u = up[lg][u];
            v = up[lg][v];
        }
    }
    return up[0][u];
}

int dist(int u, int v) {
    int lca = LCA(u, v);
    return dep[u] + dep[v] - 2 * dep[lca];
}

void update(int u) {
    int fu = u;
    while(u != -1) {
        ans[u] = min(ans[u], dist(fu, u));
        u = par[u];
    }
}

int query(int u) {
    int fu = u;
    int res = INF;
    while(u != -1) {
        res = min(res, ans[u] + dist(u, fu));
        u = par[u];
    }
    return res;
}
```

## 2sat.h

**Description:** Calculates a valid assignment to boolean variables a, b, c,... to a 2-SAT problem, so that an expression of the type  $(a||b)&&(!a||c)&&(!d||b)&&\dots$  becomes true, or reports that it is unsatisfiable. Negated variables are represented by bit-inversions ( $\sim x$ ).  
**Usage:** TwoSat ts(number of boolean variables);  
ts.either(0, ~3); // Var 0 is true or var 3 is false  
ts.setValue(2); // Var 2 is true  
ts.atMostOne({0,~1,2}); // <= 1 of vars 0, ~1 and 2 are true  
ts.solve(); // Returns true iff it is solvable  
ts.values[0..N-1] holds the assigned values to the vars  
**Time:**  $\mathcal{O}(N + E)$ , where N is the number of boolean variables, and E is the number of clauses.

5f9706, 56 lines

```
struct TwoSat {
    int N;
    vector<vi> gr;
    vi values; // 0 = false, 1 = true

    TwoSat(int n = 0) : N(n), gr(2*n) {}

    int addVar() { // (optional)
        gr.emplace_back();
        gr.emplace_back();
        return N++;
    }

    void either(int f, int j) {
        f = max(2*f, -1-2*f);
        j = max(2*j, -1-2*j);
        gr[f].push_back(j^1);
        gr[j].push_back(f^1);
    }

    void setValue(int x) { either(x, x); }

    void atMostOne(const vi& li) { // (optional)
        if (sz(li) <= 1) return;
        int cur = ~li[0];
        rep(i, 2, sz(li)) {
            int next = addVar();
            either(cur, ~li[i]);
            either(cur, next);
            either(~li[i], next);
            cur = ~next;
        }
        either(cur, ~li[1]);
    }

    vi val, comp, z; int time = 0;
    int dfs(int i) {
        int low = val[i] = ++time, x; z.push_back(i);
        for(int e : gr[i]) if (!comp[e])
            low = min(low, val[e] ?: dfs(e));
        if (low == val[i]) do {
            x = z.back(); z.pop_back();
            comp[x] = low;
            if (values[x>>1] == -1)
                values[x>>1] = x&1;
        } while (x != i);
        return val[i] = low;
    }

    bool solve() {
        values.assign(N, -1);
        val.assign(2*N, 0); comp = val;
        rep(i, 0, 2*N) if (!comp[i]) dfs(i);
        rep(i, 0, N) if (comp[2*i] == comp[2*i+1]) return 0;
        return 1;
    }
}
```

};

## EulerWalk.h

**Description:** Eulerian undirected/directed path/cycle algorithm. Input should be a vector of (dest, global edge index), where for undirected graphs, forward/backward edges have the same index. Returns a list of nodes in the Eulerian path/cycle with src at both start and end, or empty list if no cycle/path exists. To get edge indices back, add .second to s and ret.  
**Time:**  $\mathcal{O}(V + E)$

780b64, 15 lines

```
vi eulerWalk(vector<vector<pii>>& gr, int nedges, int src=0) {
    int n = sz(gr);
    vi D(n), its(n), eu(nedges), ret, s = {src};
    D[src]++;
    while (!s.empty()) {
        int x = s.back(), y, e, &it = its[x], end = sz(gr[x]);
        if (it == end) { ret.push_back(x); s.pop_back(); continue; }
        tie(y, e) = gr[x][it++];
        if (!eu[e]) {
            D[x]--;
            eu[e] = 1; s.push_back(y);
        }
        for (int x : D) if (x < 0 || sz(ret) != nedges+1) return {};
    }
    return {ret.rbegin(), ret.rend()};
}
```

## 7.5 Coloring

## EdgeColoring.h

**Description:** Given a simple, undirected graph with max degree  $D$ , computes a  $(D + 1)$ -coloring of the edges such that no neighboring edges share a color. ( $D$ -coloring is NP-hard, but can be done for bipartite graphs by repeated matchings of max-degree nodes.)  
**Time:**  $\mathcal{O}(NM)$

e210e2, 31 lines

```
vi edgeColoring(int N, vector<pii> eds) {
    vi cc(N + 1), ret(sz(eds)), fan(N), free(N), loc;
    for (pii e : eds) ++cc[e.first], ++cc[e.second];
    int u, v, ncols = *max_element(all(cc)) + 1;
    vector<vi> adj(N, vi(ncols, -1));
    for (pii e : eds) {
        tie(u, v) = e;
        fan[0] = v;
        loc.assign(ncols, 0);
        int at = u, end = u, d, c = free[u], ind = 0, i = 0;
        while (d = free[v], !loc[d] && (v = adj[u][d]) != -1)
            loc[d] = ++ind, cc[ind] = d, fan[ind] = v;
        cc[loc[d]] = c;
        for (int cd = d; at != -1; cd ^= c ^ d, at = adj[at][cd])
            swap(adj[at][cd], adj[end = at][cd ^ c ^ d]);
        while (adj[fan[i][d]] != -1) {
            int left = fan[i], right = fan[++i], e = cc[i];
            adj[u][e] = left;
            adj[left][e] = u;
            adj[right][e] = -1;
            free[right] = e;
        }
        adj[u][d] = fan[i];
        adj[fan[i]][d] = u;
        for (int y : {fan[0], u, end})
            for (int& z = free[y] = 0; adj[y][z] != -1; z++)
                rep(i, 0, sz(eds))
                    for (tie(u, v) = eds[i], adj[u][ret[i]] != v;) ++ret[i];
        return ret;
    }
}
```

## 7.6 Heuristics

## MaximalCliques.h

**Description:** Runs a callback for all maximal cliques in a graph (given as a symmetric bitset matrix; self-edges not allowed). Callback is given a bitset representing the maximal clique.  
**Time:**  $\mathcal{O}(3^{n/3})$ , much faster for sparse graphs

b0d5b1, 12 lines

```
typedef bitset<128> B;
template<class F>
void cliques(vector<B>& eds, F f, B P = ~B(), B X={}, B R={}) {
    if (!P.any()) { if (!X.any()) f(R); return; }
    auto q = (P | X).FindFirst();
    auto cands = P & ~eds[q];
    rep(i, 0, sz(eds)) if (cands[i]) {
        R[i] = 1;
        cliques(eds, f, P & eds[i], X & eds[i], R);
        R[i] = P[i] = 0; X[i] = 1;
    }
}
```

## MaximumClique.h

**Description:** Quickly finds a maximum clique of a graph (given as symmetric bitset matrix; self-edges not allowed). Can be used to find a maximum independent set by finding a clique of the complement graph.  
**Time:** Runs in about 1s for n=155 and worst case random graphs (p=.90).

Runs faster for sparse graphs.

f7c0bc, 49 lines

```
typedef vector<bitset<200>> vb;
struct Maxclique {
    double limit=0.025, pk=0;
    struct Vertex { int i, d=0; };
    typedef vector<Vertex> vv;
    vb e;
    vv V;
    vector<vi> C;
    vi qmax, q, S, old;
    void init(vv& r) {
        for (auto& v : r) v.d = 0;
        for (auto& v : r) for (auto j : r) v.d += e[v.i][j.i];
        sort(all(r), [] (auto a, auto b) { return a.d > b.d; });
        int mxd = r[0].d;
        rep(i, 0, sz(r)) r[i].d = min(i, mxd) + 1;
    }
    void expand(vv& R, int lev = 1) {
        S[lev] += S[lev - 1] - old[lev];
        old[lev] = S[lev - 1];
        while (sz(R)) {
            if (sz(q) + R.back().d <= sz(qmax)) return;
            q.push_back(R.back().i);
            vv T;
            for (auto v : R) if (e[R.back().i][v.i]) T.push_back({v.i});
            if (sz(T)) {
                if (S[lev]++ / ++pk < limit) init(T);
                int j = 0, mxk = 1, mnk = max(sz(qmax) - sz(q) + 1, 1);
                C[1].clear(), C[2].clear();
                for (auto v : T) {
                    int k = 1;
                    auto f = [&] (int i) { return e[v.i][i]; };
                    while (any_of(all(C[k]), f)) k++;
                    if (k > mxk) mxk = k, C[mxk + 1].clear();
                    if (k < mnk) T[j++].i = v.i;
                    C[k].push_back(v.i);
                }
                if (j > 0) T[j - 1].d = 0;
                rep(k, mnk, mxk + 1) for (int i : C[k])
                    T[j].i = i, T[j].d = k;
                expand(T, lev + 1);
            } else if (sz(q) > sz(qmax)) qmax = q;
            q.pop_back(), R.pop_back();
        }
}
```

```

    }
    vi maxClique() { init(V), expand(V); return qmax; }
    Maxclique(vb conn) : e(conn), C(sz(e)+1), S(sz(C)), old(S) {
        rep(i,0,sz(e)) V.push_back({i});
    }
}

```

### MaximumIndependentSet.h

**Description:** To obtain a maximum independent set of a graph, find a max clique of the complement. If the graph is bipartite, see MinimumVertexCover.

## 7.7 Trees

### BinaryLifting.h

**Description:** Calculate power of two jumps in a tree, to support fast upward jumps and LCAs. Assumes the root node points to itself.

**Time:** construction  $\mathcal{O}(N \log N)$ , queries  $\mathcal{O}(\log N)$

bfce85, 25 lines

```

vector<vi> treeJump(vi& P) {
    int on = 1, d = 1;
    while(on < sz(P)) on *= 2, d++;
    vector<vi> jmp(d, P);
    rep(i,1,d) rep(j,0,sz(P))
        jmp[i][j] = jmp[i-1][jmp[i-1][j]];
    return jmp;
}

```

```

int jmp(vector<vi>& tbl, int nod, int steps){
    rep(i,0,sz(tbl))
        if(steps&(1<i)) nod = tbl[i][nod];
    return nod;
}

```

```

int lca(vector<vi>& tbl, vi& depth, int a, int b) {
    if (depth[a] < depth[b]) swap(a, b);
    a = jmp(tbl, a, depth[a] - depth[b]);
    if (a == b) return a;
    for (int i = sz(tbl); i--;) {
        int c = tbl[i][a], d = tbl[i][b];
        if (c != d) a = c, b = d;
    }
    return tbl[0][a];
}

```

### LCA.h

**Description:** Data structure for computing lowest common ancestors in a tree (with 0 as root). C should be an adjacency list of the tree, either directed or undirected.

**Time:**  $\mathcal{O}(N \log N + Q)$

..../data-structures/RMQ.h

0f62fb, 21 lines

```

struct LCA {
    int T = 0;
    vi time, path, ret;
    RMQ<int> rmq;

    LCA(vector<vi>& C) : time(sz(C)), rmq((dfs(C,0,-1), ret)) {}
    void dfs(vector<vi>& C, int v, int par) {
        time[v] = T++;
        for (int y : C[v]) if (y != par) {
            path.push_back(v), ret.push_back(time[v]);
            dfs(C, y, v);
        }
    }

    int lca(int a, int b) {
        if (a == b) return a;

```

```

        tie(a, b) = minmax(time[a], time[b]);
        return path[rmq.query(a, b)];
    }
    //dist(a,b){return depth[a] + depth[b] - 2*depth[lca(a,b)];}
};

```

### CompressTree.h

**Description:** Given a rooted tree and a subset S of nodes, compute the minimal subtree that contains all the nodes by adding all (at most  $|S| - 1$ ) pairwise LCAs's and compressing edges. Returns a list of (par, orig\_index) representing a tree rooted at 0. The root points to itself.

**Time:**  $\mathcal{O}(|S| \log |S|)$

"LCA.h"

9775a0, 21 lines

```

typedef vector<pair<int, int>> vpi;
vpi compressTree(LCA& lca, const vi& subset) {
    static vi rev; rev.resize(sz(lca.time));
    vi li = subset, &T = lca.time;
    auto cmp = [&](int a, int b) { return T[a] < T[b]; };
    sort(all(li), cmp);
    int m = sz(li)-1;
    rep(i,0,m) {
        int a = li[i], b = li[i+1];
        li.push_back(lca.lca(a, b));
    }
    sort(all(li), cmp);
    li.erase(unique(all(li)), li.end());
    rep(i,0,sz(li)) rev[li[i]] = i;
    vpi ret = {pi(0, li[0])};
    rep(i,0,sz(li)-1) {
        int a = li[i], b = li[i+1];
        ret.emplace_back(rev[lca.lca(a, b)], b);
    }
    return ret;
}

```

### HLD.h

**Description:** Decomposes a tree into vertex disjoint heavy paths and light edges such that the path from any leaf to the root contains at most  $\log(n)$  light edges. Code does additive modifications and max queries, but can support commutative segtree modifications/queries on paths and subtrees. Takes as input the full adjacency list. VALS\_EDGES being true means that values are stored in the edges, as opposed to the nodes. All values initialized to the segtree default. Root must be 0.

**Time:**  $\mathcal{O}((\log N)^2)$

"../data-structures/LazySegmentTree.h"

9547af, 46 lines

```

template <bool VALS_EDGES> struct HLD {
    int N, tim = 0;
    vector<vi> adj;
    vi par, siz, rt, pos;
    Node *tree;
    HLD(vector<vi> adj_) {
        N(sz(adj_)), adj(adj_), par(N, -1), siz(N, 1),
        rt(N), pos(N), tree(new Node(0, N)){ dfsSz(0); dfsHld(0); }
    }
    void dfsSz(int v) {
        for (int& u : adj[v]) {
            adj[u].erase(find(all(adj[u]), v));
            par[u] = v;
            dfsSz(u);
            siz[v] += siz[u];
            if (siz[u] > siz[adj[v][0]]) swap(u, adj[v][0]);
        }
    }
    void dfsHld(int v) {
        pos[v] = tim++;
        for (int u : adj[v]) {
            rt[u] = (u == adj[v][0] ? rt[v] : u);
            dfsHld(u);
        }
    }
}

```

```

}
template <class B> void process(int u, int v, B op) {
    for (;;) v = par[rt[v]] {
        if (pos[u] > pos[v]) swap(u, v);
        if (rt[u] == rt[v]) break;
        op(pos[rt[v]], pos[v] + 1);
    }
    op(pos[u] + VALS_EDGES, pos[v] + 1);
}
void modifyPath(int u, int v, int val) {
    process(u, v, [&](int l, int r) { tree->add(l, r, val); });
}
int queryPath(int u, int v) { // Modify depending on problem
    int res = -1e9;
    process(u, v, [&](int l, int r) {
        res = max(res, tree->query(l, r));
    });
    return res;
}
int querySubtree(int v) { // modifySubtree is similar
    return tree->query(pos[v] + VALS_EDGES, pos[v] + siz[v]);
}
}

```

### LinkCutTree.h

**Description:** Represents a forest of unrooted trees. You can add and remove edges (as long as the result is still a forest), and check whether two nodes are in the same tree.

**Time:** All operations take amortized  $\mathcal{O}(\log N)$ .

0fb462, 90 lines

```

struct Node { // Splay tree. Root's pp contains tree's parent.
    Node *p, *pp = 0, *c[2];
    bool flip = 0;
    Node() { c[0] = c[1] = 0; fix(); }
    void fix() {
        if (c[0]) c[0]->p = this;
        if (c[1]) c[1]->p = this;
        // (+ update sum of subtree elements etc. if wanted)
    }
    void pushFlip() {
        if (!flip) return;
        flip = 0; swap(c[0], c[1]);
        if (c[0]) c[0]->flip ^= 1;
        if (c[1]) c[1]->flip ^= 1;
    }
    int up() { return p ? p->c[1] == this : -1; }
    void rot(int i, int b) {
        int h = i ^ b;
        Node *x = c[i], *y = b == 2 ? x : x->c[h], *z = b ? y : x;
        if ((y->p) == p) p->c[up()] = y;
        c[i] = z->c[i ^ 1];
        if (b < 2) {
            x->c[h] = y->c[h ^ 1];
            y->c[h ^ 1] = x;
        }
        z->c[i ^ 1] = this;
        fix(); x->fix(); y->fix();
        if (p) p->fix();
        swap(pp, y->pp);
    }
    void splay() {
        for (pushFlip(); p; ) {
            if (p->p) p->p->pushFlip();
            p->pushFlip(); pushFlip();
            int cl = up(), c2 = p->up();
            if (c2 == -1) p->rot(cl, 2);
            else p->p->rot(c2, cl != c2);
        }
    }
}

```

```

Node* first() {
    pushFlip();
    return c[0] ? c[0]->first() : (splay(), this);
}

struct LinkCut {
    vector<Node> node;
    LinkCut(int N) : node(N) {}

    void link(int u, int v) { // add an edge (u, v)
        assert(!connected(u, v));
        makeRoot(&node[u]);
        node[u].pp = &node[v];
    }

    void cut(int u, int v) { // remove an edge (u, v)
        Node *x = &node[u], *top = &node[v];
        makeRoot(top); x->splay();
        assert(top == (x->pp ?: x->c[0]));
        if (x->pp) x->pp = 0;
        else {
            x->c[0] = top->p = 0;
            x->fix();
        }
    }

    bool connected(int u, int v) { // are u, v in the same tree?
        Node* nu = access(&node[u])->first();
        return nu == access(&node[v])->first();
    }

    void makeRoot(Node* u) {
        access(u);
        u->splay();
        if(u->c[0]) {
            u->c[0]->p = 0;
            u->c[0]->flip ^= 1;
            u->c[0]->pp = u;
            u->c[0] = 0;
            u->fix();
        }
    }

    Node* access(Node* u) {
        u->splay();
        while (Node* pp = u->pp) {
            pp->splay(); u->pp = 0;
            if (pp->c[1]) {
                pp->c[1]->p = 0; pp->c[1]->pp = pp; }
            pp->c[1] = u; pp->fix(); u = pp;
        }
        return u;
    }
}

```

## DirectedMST.h

**Description:** Finds a minimum spanning tree/arborescence of a directed graph, given a root node. If no MST exists, returns -1.

**Time:**  $\mathcal{O}(E \log V)$

.../data-structures/UnionFindRollback.h

39e620, 60 lines

```

struct Edge { int a, b; ll w; };
struct Node {
    Edge key;
    Node *l, *r;
    ll delta;
    void prop() {
        key.w += delta;
        if (l) l->delta += delta;
        if (r) r->delta += delta;
        delta = 0;
    }
    Edge top() { prop(); return key; }
}

```

## DirectedMST Point lineDistance

```

};

Node *merge(Node *a, Node *b) {
    if (!a || !b) return a ?: b;
    a->prop(), b->prop();
    if (a->key.w > b->key.w) swap(a, b);
    swap(a->l, (a->r = merge(b, a->r)));
    return a;
}

void pop(Node*& a) { a->prop(); a = merge(a->l, a->r); }

pair<ll, vi> dmst(int n, int r, vector<Edge>& g) {
    RollbackUF uf(n);
    vector<Node*> heap(n);
    for (Edge e : g) heap[e.b] = merge(heap[e.b], new Node{e});
    ll res = 0;
    vi seen(n, -1), path(n), par(n);
    seen[r] = r;
    vector<Edge> Q(n), in(n, {-1, -1}), comp;
    deque<tuple<int, int, vector<Edge>>> cycs;
    rep(s, 0, n) {
        int u = s, qi = 0, w;
        while (seen[u] < 0) {
            if (!heap[u]) return {-1, {}};
            Edge e = heap[u]->top();
            heap[u]->delta -= e.w, pop(heap[u]);
            Q[qi] = e, path[qi++].push_back(u), seen[u] = s;
            res += e.w, u = uf.find(e.a);
            if (seen[u] == s) {
                Node* cyc = 0;
                int end = qi, time = uf.time();
                do cyc = merge(cyc, heap[w = path[--qi]]);
                while (uf.join(u, w));
                u = uf.find(u), heap[u] = cyc, seen[u] = -1;
                cycs.push_front({u, time, {&Q[qi], &Q[end]}});
            }
            rep(i, 0, qi) in[uf.find(Q[i].b)] = Q[i];
        }

        for (auto& [u, t, comp] : cycs) { // restore sol (optional)
            uf.rollback(t);
            Edge inEdge = in[u];
            for (auto& e : comp) in[uf.find(e.b)] = e;
            in[uf.find(inEdge.b)] = inEdge;
        }
        rep(i, 0, n) par[i] = in[i].a;
        return {res, par};
    }
}

```

## 7.8 Math

## 7.8.1 Number of Spanning Trees

Create an  $N \times N$  matrix mat, and for each edge  $a \rightarrow b \in G$ , do  $\text{mat}[a][b]--$ ,  $\text{mat}[b][b]++$  (and  $\text{mat}[b][a]--$ ,  $\text{mat}[a][a]++$  if  $G$  is undirected). Remove the  $i$ th row and column and take the determinant; this yields the number of directed spanning trees rooted at  $i$  (if  $G$  is undirected, remove any row/column).

## 7.8.2 Erdős–Gallai theorem

A simple graph with node degrees  $d_1 \geq \dots \geq d_n$  exists iff  $d_1 + \dots + d_n$  is even and for every  $k = 1 \dots n$ ,

$$\sum_{i=1}^k d_i \leq k(k-1) + \sum_{i=k+1}^n \min(d_i, k).$$

## 7.8.3 Vértices que pertenecen a todos los maximum matching bipartitos

Crea un grafo auxiliar. Dirige las aristas no emparejadas de  $L \rightarrow R$  y las emparejadas de  $R \rightarrow L$ . Calcula  $Z_L$ , vértices que alcanzables desde vértices libres en  $L$ . De forma análoga calcula  $Z_R$ , el conjunto buscado es  $(L - Z_L) \cup (R - Z_R)$ .

## 7.8.4 L-R Flow

Flow with demands. Nuevos vértices  $S'$  y  $T'$ . Reemplaza las aristas  $(u, v, r-l)$ ,  $(S', v, l)$  y  $(u, T', l)$ . Una arista más  $(T, S, \infty)$ . Corre un primer maxflow de  $S'$  a  $T'$ , si es menor a la suma de todos los  $l$ , el flujo buscado no existe. Corre un segundo maxflow de  $S$  a  $T$ , este es el flujo máximo buscado originalmente.

## Geometry (8)

## 8.1 Geometric primitives

## Point.h

**Description:** Class to handle points in the plane. T can be e.g. double or long long. (Avoid int.)

47ec0a, 28 lines

```

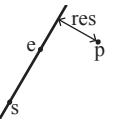
template <class T> int sgn(T x) { return (x > 0) - (x < 0); }
template <class T>
struct Point {
    typedef Point P;
    T x, y;
    explicit Point(T x=0, T y=0) : x(x), y(y) {}
    bool operator<(P p) const { return tie(x,y) < tie(p.x,p.y); }
    bool operator==(P p) const { return tie(x,y)==tie(p.x,p.y); }
    P operator+(P p) const { return P(x+p.x, y+p.y); }
    P operator-(P p) const { return P(x-p.x, y-p.y); }
    P operator*(T d) const { return P(x*d, y*d); }
    P operator/(T d) const { return P(x/d, y/d); }
    T dot(P p) const { return x*p.x + y*p.y; }
    T cross(P p) const { return x*p.y - y*p.x; }
    T cross(P a, P b) const { return (a-*this).cross(b-*this); }
    T dist2() const { return x*x + y*y; }
    double dist() const { return sqrt((double)dist2()); }
    // angle to x-axis in interval [-pi, pi]
    double angle() const { return atan2(y, x); }
    P unit() const { return *this/dist(); } // makes dist()==1
    P perp() const { return P(-y, x); } // rotates +90 degrees
    P normal() const { return perp().unit(); }
    // returns point rotated 'a' radians ccw around the origin
    P rotate(double a) const {
        return P(x*cos(a)-y*sin(a), x*sin(a)+y*cos(a)); }
    friend ostream& operator<<(ostream& os, P p) {
        return os << "(" << p.x << "," << p.y << ")";
    }
}

```

## lineDistance.h

**Description:**

Returns the signed distance between point p and the line containing points a and b. Positive value on left side and negative on right as seen from a towards b.  $a==b$  gives nan. P is supposed to be Point<T> or Point3D<T> where T is e.g. double or long long. It uses products in intermediate steps so watch out for overflow if using int or long long. Using Point3D will always give a non-negative distance. For Point3D, call .dist on the result of the cross product.



Point.h

template <class P>

f6bf6b, 4 lines

```
double lineDist(const P& a, const P& b, const P& p) {
    return (double)(b-a).cross(p-a)/(b-a).dist();
}
```

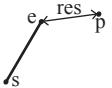
### SegmentDistance.h

#### Description:

Returns the shortest distance between point p and the line segment from point s to e.

**Usage:** Point<double> a, b(2,2), p(1,1);  
bool onSegment = segDist(a,b,p) < 1e-10;

"Point.h"



5c88f4, 6 lines

### typedef Point<double> P;

```
double segDist(P& s, P& e, P& p) {
    if (s==e) return (p-s).dist();
    auto d = (e-s).dist2(), t = min(d,max(.0,(p-s).dot(e-s)));
    return ((p-s)*d-(e-s)*t).dist()/d;
}
```

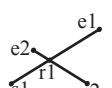
### SegmentIntersection.h

#### Description:

If a unique intersection point between the line segments going from s1 to e1 and from s2 to e2 exists then it is returned. If no intersection point exists an empty vector is returned. If infinitely many exist a vector with 2 elements is returned, containing the endpoints of the common line segment. The wrong position will be returned if P is Point<ll> and the intersection point does not have integer coordinates. Products of three coordinates are used in intermediate steps so watch out for overflow if using int or long long.

**Usage:** vector<P> inter = segInter(s1,e1,s2,e2);  
if (sz(inter)==1)  
cout << "segments intersect at " << inter[0] << endl;

"Point.h", "OnSegment.h"



9d57f2, 13 lines

```
template<class P> vector<P> segInter(P a, P b, P c, P d) {
    auto oa = c.cross(d, a), ob = c.cross(d, b),
        oc = a.cross(b, c), od = a.cross(b, d);
    // Checks if intersection is single non-endpoint point.
    if (sgn(oa) * sgn(ob) < 0 && sgn(oc) * sgn(od) < 0)
        return {(a * ob - b * oa) / (ob - oa)};
    set<P> s;
    if (onSegment(c, d, a)) s.insert(a);
    if (onSegment(c, d, b)) s.insert(b);
    if (onSegment(a, b, c)) s.insert(c);
    if (onSegment(a, b, d)) s.insert(d);
    return {all(s)};
}
```

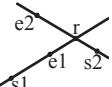
### lineIntersection.h

#### Description:

If a unique intersection point of the lines going through s1,e1 and s2,e2 exists {1, point} is returned. If no intersection point exists {0, (0,0)} is returned and if infinitely many exists {-1, (0,0)} is returned. The wrong position will be returned if P is Point<ll> and the intersection point does not have integer coordinates. Products of three coordinates are used in intermediate steps so watch out for overflow if using int or ll.

**Usage:** auto res = lineInter(s1,e1,s2,e2);  
if (res.first == 1)  
cout << "intersection point at " << res.second << endl;

"Point.h"



a01f81, 8 lines

```
template<class P>
pair<int, P> lineInter(P s1, P e1, P s2, P e2) {
    auto d = (e1 - s1).cross(e2 - s2);
    if (d == 0) // if parallel
        return {-(s1.cross(e1, e2) == 0), P(0, 0)};
    auto p = s2.cross(e1, e2), q = s2.cross(e2, s1);
    return {1, (s1 * p + e1 * q) / d};
}
```

### sideOf.h

**Description:** Returns where p is as seen from s towards e.  $1/0/-1 \Leftrightarrow$  left/on line/right. If the optional argument eps is given 0 is returned if p is within distance eps from the line. P is supposed to be Point<T> where T is e.g. double or long long. It uses products in intermediate steps so watch out for overflow if using int or long long.

**Usage:** bool left = sideOf(p1,p2,q)==1;

"Point.h"

3af81c, 9 lines

### template<class P>

```
int sideOf(P s, P e, P p) { return sgn(s.cross(e, p)); }
```

### template<class P>

```
int sideOf(const P& s, const P& e, const P& p, double eps) {
    auto a = (e-s).cross(p-s);
    double l = (e-s).dist()*eps;
    return (a > l) - (a < -l);
}
```

### OnSegment.h

**Description:** Returns true iff p lies on the line segment from s to e. Use (`segDist(s,e,p)<=epsilon`) instead when using Point<double>.

"Point.h"

c597e8, 3 lines

```
template<class P> bool onSegment(P s, P e, P p) {
    return p.cross(s, e) == 0 && (s - p).dot(e - p) <= 0;
}
```

### linearTransformation.h

#### Description:

Apply the linear transformation (translation, rotation and scaling) which takes line p0-p1 to line q0-q1 to point r.

"Point.h"

03a306, 6 lines

```
typedef Point<double> P;
P linearTransformation(const P& p0, const P& p1,
                      const P& q0, const P& q1, const P& r) {
    P dp = p1-p0, dq = q1-q0, num(dp.cross(dq), dp.dot(dq));
    return q0 + P((r-p0).cross(num), (r-p0).dot(num))/dp.dist2();
}
```

### Angle.h

**Description:** A class for ordering angles (as represented by int points and a number of rotations around the origin). Useful for rotational sweeping. Sometimes also represents points or vectors.

**Usage:** vector<Angle> v = {w[0], w[0].t360() ...}; // sorted

```
int j = 0; rep(i,0,n) { while (v[j] < v[i].t180()) ++j; }
// sweeps j such that (j-i) represents the number of positively
oriented triangles with vertices at 0 and i
```

0f0602, 35 lines

```
struct Angle {
    int x, y;
    int t;
    Angle(int x, int y, int t=0) : x(x), y(y), t(t) {}
    Angle operator-(Angle b) const { return {x-b.x, y-b.y, t}; }
    int half() const {
        assert(x || y);
        return y < 0 || (y == 0 && x < 0);
    }
    Angle t90() const { return {-y, x, t + (half() && x >= 0)}; }
    Angle t180() const { return {-x, -y, t + half()}; }
    Angle t360() const { return {x, y, t + 1}; }
};

bool operator<(Angle a, Angle b) {
    // add a.dist2() and b.dist2() to also compare distances
    return make_tuple(a.t, a.half(), a.y * (ll)b.x) <
           make_tuple(b.t, b.half(), a.x * (ll)b.y);
}
```

// Given two points, this calculates the smallest angle between

// them, i.e., the angle that covers the defined line segment.

pair<Angle, Angle> segmentAngles(Angle a, Angle b) {

if (b < a) swap(a, b);

return (b < a.t180()) ?

make\_pair(a, b) : make\_pair(b, a.t360());

}

Angle operator+(Angle a, Angle b) { // point a + vector b

Angle r(a.x + b.x, a.y + b.y, a.t);

if (a.t180() < r) r.t--;

return r.t180() < a ? r.t360() : r;

}

Angle angleDiff(Angle a, Angle b) { // angle b - angle a

```
int tu = b.t - a.t; a.t = b.t;
return {a.x*b.x + a.y*b.y, a.x*b.y - a.y*b.x, tu - (b < a)};
```

}

## 8.2 Circles

### CircleIntersection.h

**Description:** Computes the pair of points at which two circles intersect. Returns false in case of no intersection.

"Point.h"

84d6d3, 11 lines

### typedef Point<double> P;

```
bool circleInter(P a, P b, double r1, double r2, pair<P, P>* out) {
    if (a == b) { assert(r1 != r2); return false; }
    P vec = b - a;
    double d2 = vec.dist2(), sum = r1+r2, dif = r1-r2,
        p = (d2 + r1*r1 - r2*r2)/(d2*2), h2 = r1*r1 - p*p*d2;
    if (sum*sum < d2 || dif*dif > d2) return false;
    P mid = a + vec*p, per = vec.perp() * sqrt(fmax(0, h2) / d2);
    *out = {mid + per, mid - per};
    return true;
}
```

### CircleTangents.h

**Description:** Finds the external tangents of two circles, or internal if r2 is negated. Can return 0, 1, or 2 tangents – 0 if one circle contains the other (or overlaps it, in the internal case, or if the circles are the same); 1 if the circles are tangent to each other (in which case .first = .second and the tangent line is perpendicular to the line between the centers). .first and .second give the tangency points at circle 1 and 2 respectively. To find the tangents of a circle with a point set r2 to 0.

"Point.h"

b0153d, 13 lines

### template<class P>

```
vector<pair<P, P>> tangents(P c1, double r1, P c2, double r2) {
    P d = c2 - c1;
    double dr = r1 - r2, d2 = d.dist2(), h2 = d2 - dr * dr;
    if (d2 == 0 || h2 < 0) return {};
    vector<pair<P, P>> out;
    for (double sign : {-1, 1}) {
        P v = (d * dr + d.perp() * sqrt(h2) * sign) / d2;
        out.push_back({c1 + v * r1, c2 + v * r2});
    }
    if (h2 == 0) out.pop_back();
    return out;
}
```

### CircleLine.h

**Description:** Finds the intersection between a circle and a line. Returns a vector of either 0, 1, or 2 intersection points. P is intended to be Point<double>.

"Point.h"

e0cfba, 9 lines

### template<class P>

```
vector<P> circleLine(P c, double r, P a, P b) {
    P ab = b - a, p = a + ab * (c-a).dot(ab) / ab.dist2();
    double s = a.cross(b, c), h2 = r*r - s*s / ab.dist2();
    if (h2 < 0) return {};
    if (h2 == 0) return {p};
```

```
P h = ab.unit() * sqrt(h2);
return {p - h, p + h};
}
```

**CirclePolygonIntersection.h**

**Description:** Returns the area of the intersection of a circle with a ccw polygon.

**Time:**  $\mathcal{O}(n)$

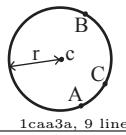
`"../../../../content/geometry/Point.h"` 19add1, 19 lines

```
typedef Point<double> P;
#define arg(p, q) atan2(p.cross(q), p.dot(q))
double circlePoly(P c, double r, vector<P> ps) {
    auto tri = [&](P p, P q) {
        auto r2 = r * r / 2;
        P d = q - p;
        auto a = d.dot(p)/d.dist2(), b = (p.dist2()-r*r)/d.dist2();
        auto det = a * a - b;
        if (det <= 0) return arg(p, q) * r2;
        auto s = max(0., -a-sqrt(det)), t = min(1., -a+sqrt(det));
        if (t < 0 || 1 <= s) return arg(p, q) * r2;
        P u = p + d * s, v = q + d * (t-1);
        return arg(p,u) * r2 + u.cross(v)/2 + arg(v,q) * r2;
    };
    auto sum = 0.0;
    rep(i,0,sz(ps))
        sum += tri(ps[i] - c, ps[(i + 1) % sz(ps)] - c);
    return sum;
}
```

**circumcircle.h**

**Description:**

The circumcircle of a triangle is the circle intersecting all three vertices. ccRadius returns the radius of the circle going through points A, B and C and ccCenter returns the center of the same circle.



`"Point.h"`

```
typedef Point<double> P;
double ccRadius(const P& A, const P& B, const P& C) {
    return (B-A).dist()*(C-B).dist()*(A-C).dist()/
        abs((B-A).cross(C-A))/2;
}
P ccCenter(const P& A, const P& B, const P& C) {
    P b = C-A, c = B-A;
    return A + (b*c.dist2()-c*b.dist2()).perp()/b.cross(c)/2;
}
```

**MinimumEnclosingCircle.h**

**Description:** Computes the minimum circle that encloses a set of points.

**Time:** expected  $\mathcal{O}(n)$

`"circumcircle.h"` 09dd0a, 17 lines

```
pair<P, double> mec(vector<P> ps) {
    shuffle(all(ps), mt19937(time(0)));
    P o = ps[0];
    double r = 0, EPS = 1 + 1e-8;
    rep(i,0,sz(ps)) if ((o - ps[i]).dist() > r * EPS) {
        o = ps[i], r = 0;
        rep(j,0,i) if ((o - ps[j]).dist() > r * EPS) {
            o = (ps[i] + ps[j]) / 2;
            r = (o - ps[i]).dist();
            rep(k,0,j) if ((o - ps[k]).dist() > r * EPS) {
                o = ccCenter(ps[i], ps[j], ps[k]);
                r = (o - ps[i]).dist();
            }
        }
    }
    return {o, r};
}
```

**8.3 Polygons****InsidePolygon.h**

**Description:** Returns true if p lies within the polygon. If strict is true, it returns false for points on the boundary. The algorithm uses products in intermediate steps so watch out for overflow.

**Usage:** `vector<P> v = {P{4,4}, P{1,2}, P{2,1}};`

`bool in = inPolygon(v, P{3, 3}, false);`

**Time:**  $\mathcal{O}(n)$

`"Point.h", "OnSegment.h", "SegmentDistance.h"` 2bf504, 11 lines

```
template<class P>
bool inPolygon(vector<P> &p, P a, bool strict = true) {
    int cnt = 0, n = sz(p);
    rep(i,0,n) {
        P q = p[(i + 1) % n];
        if (onSegment(p[i], q, a)) return !strict;
        //or: if (segDist(p[i], q, a) <= eps) return !strict;
        cnt += ((a.y<p[i].y) - (a.y<q.y)) * a.cross(p[i], q) > 0;
    }
    return cnt;
}
```

**PolygonArea.h**

**Description:** Returns twice the signed area of a polygon. Clockwise enumeration gives negative area. Watch out for overflow if using int as T!

`"Point.h"` f12300, 6 lines

```
template<class T>
T polygonArea2(vector<Point<T>>& v) {
    T a = v.back().cross(v[0]);
    rep(i,0,sz(v)-1) a += v[i].cross(v[i+1]);
    return a;
}
```

**PolygonCenter.h**

**Description:** Returns the center of mass for a polygon.

**Time:**  $\mathcal{O}(n)$

`"Point.h"` 9706dc, 9 lines

```
typedef Point<double> P;
P polygonCenter(const vector<P>& v) {
    P res(0, 0); double A = 0;
    for (int i = 0, j = sz(v) - 1; i < sz(v); j = i++) {
        res = res + (v[i] + v[j]) * v[j].cross(v[i]);
        A += v[j].cross(v[i]);
    }
    return res / A / 3;
}
```

**PolygonCut.h**

**Description:**

Returns a vector with the vertices of a polygon with everything to the left of the line going from s to e cut away.

**Usage:** `vector<P> p = ...;`

`p = polygonCut(p, P(0,0), P(1,0));`

`"Point.h"` d07181, 13 lines

```
typedef Point<double> P;
vector<P> polygonCut(const vector<P>& poly, P s, P e) {
    vector<P> res;
    rep(i,0,sz(poly)) {
        P cur = poly[i], prev = i ? poly[i-1] : poly.back();
        auto a = s.cross(e, cur), b = s.cross(e, prev);
        if ((a < 0) != (b < 0))
            res.push_back(cur + (prev - cur) * (a / (a - b)));
        if (a < 0)
            res.push_back(cur);
    }
    return res;
}
```

**PolygonUnion.h**

**Description:** Calculates the area of the union of  $n$  polygons (not necessarily convex). The points within each polygon must be given in CCW order. (Epsilon checks may optionally be added to sideOf/sgn, but shouldn't be needed.)

**Time:**  $\mathcal{O}(N^2)$ , where  $N$  is the total number of points

`"Point.h", "sideOf.h"` 3931c6, 33 lines

```
typedef Point<double> P;
double rat(P a, P b) { return sgn(b.x) ? a.x/b.x : a.y/b.y; }
double polyUnion(vector<vector<P>>& poly) {
    double ret = 0;
    rep(i,0,sz(poly)) rep(j,0,sz(poly[i])) {
        P A = poly[i][j], B = poly[i][(j + 1) % sz(poly[i])];
        vector<pair<double, int>> segs = {{0, 0}, {1, 0}};
        rep(j,0,sz(poly)) if (i != j) {
            rep(u,0,sz(poly[j])) {
                P C = poly[j][u], D = poly[j][(u + 1) % sz(poly[j])];
                int sc = sideOf(A, B, C), sd = sideOf(A, B, D);
                if (sc != sd) {
                    double sa = C.cross(D, A), sb = C.cross(D, B);
                    if (min(sc, sd) < 0)
                        segs.emplace_back(sa / (sa - sb), sgn(sc - sd));
                } else if (!sc && !sd && j < i && sgn((B-A).dot(D-C)) > 0) {
                    segs.emplace_back(rat(C - A, B - A), 1);
                    segs.emplace_back(rat(D - A, B - A), -1);
                }
            }
        }
        sort(all(segs));
        for (auto &s : segs) s.first = min(max(s.first, 0.0), 1.0);
        double sum = 0;
        int cnt = segs[0].second;
        rep(j,1,sz(segs)) {
            if (!cnt) sum += segs[j].first - segs[j - 1].first;
            cnt += segs[j].second;
        }
        ret += A.cross(B) * sum;
    }
    return ret / 2;
}
```

**ConvexHull.h**

**Description:**

Returns a vector of the points of the convex hull in counter-clockwise order. Points on the edge of the hull between two other points are not considered part of the hull.

**Time:**  $\mathcal{O}(n \log n)$

`"Point.h"`

```
typedef Point<ll> P;
vector<P> convexHull(vector<P> pts) {
    if (sz(pts) <= 1) return pts;
    sort(all(pts));
    vector<P> h(sz(pts)+1);
    int s = 0, t = 0;
    for (int it = 2; it-- > s; s = --t, reverse(all(pts)))
        for (P p : pts) {
            while (t >= s + 2 && h[t-2].cross(h[t-1], p) <= 0) t--;
            h[t++] = p;
        }
    return {h.begin(), h.begin() + t - (t == 2 && h[0] == h[1])};
}
```



310954, 13 lines

**HullDiameter.h**

**Description:** Returns the two points with max distance on a convex hull (ccw, no duplicate/collinear points).

**Time:**  $\mathcal{O}(n)$

`"Point.h"`

```
typedef Point<ll> P;

```

```
array<P, 2> hullDiameter(vector<P> S) {
    int n = sz(S), j = n < 2 ? 0 : 1;
    pair<ll, array<P, 2>> res({0, {S[0], S[0]}});
    rep(i, 0, j)
        for (;;) j = (j + 1) % n {
            res = max(res, {(S[i] - S[j]).dist2(), {S[i], S[j]}});
            if ((S[(j + 1) % n] - S[j]).cross(S[i + 1] - S[i]) >= 0)
                break;
        }
    return res.second;
}
```

**PointInsideHull.h**

**Description:** Determine whether a point t lies inside a convex hull (CCW order, with no collinear points). Returns true if point lies within the hull. If strict is true, points on the boundary aren't included.

**Time:**  $\mathcal{O}(\log N)$

"Point.h", "SideOf.h", "OnSegment.h"

71446b, 14 lines

**typedef** Point<ll> P;

```
bool inHull(const vector<P>& l, P p, bool strict = true) {
    int a = 1, b = sz(l) - 1, r = !strict;
    if (sz(l) < 3) return r && onSegment(l[0], l.back(), p);
    if (sideOf(l[0], l[a], l[b]) > 0) swap(a, b);
    if (sideOf(l[0], l[a], p) >= r || sideOf(l[0], l[b], p) <= -r)
        return false;
    while (abs(a - b) > 1) {
        int c = (a + b) / 2;
        (sideOf(l[0], l[c], p) > 0 ? b : a) = c;
    }
    return sgn(l[a].cross(l[b], p)) < r;
}
```

**PolyTangents.h**

**Description:** Calculates the tangent from a point to a polygon. The polygon must be given in CCW order.

**Time:**  $\mathcal{O}(\log N)$

"Point.h"

92f0a7, 23 lines

```
template<class Fun>
// tangent from p to poly
// auto t = extreme(poly, [&](const P q) { return p - q; });
int extreme(const vector<P>& poly, Fun dir) {
    int n = sz(poly), low = 0, low_sgn;
    auto nx = [&](int i) { return i + 1 == n ? 0 : i + 1; };
    auto pr = [&](int i) { return i ? i - 1 : n - 1; };
    auto vertexCmp = [&](int i, int j) {
        return sgn(dir(poly[j]).cross(poly[j] - poly[i]));
    };
    auto isExtreme = [&](int i, int &i_sgn) {
        return (i_sgn = vertexCmp(nx(i), i)) >= 0 && vertexCmp(i, pr(i)) < 0;
    };
    for(int high = isExtreme(0, low_sgn) ? 1 : n; low + 1 < high;) {
        int mid = (low + high) / 2, mid_sgn;
        if(isExtreme(mid, mid_sgn)) return mid;
        if(low_sgn != mid_sgn ? low_sgn < mid_sgn
            : low_sgn == vertexCmp(low, mid)) high = mid;
        else low = mid, low_sgn = mid_sgn;
    }
    return low;
}
```

**MinkowskiSum.h**

**Description:** Calculates the Minkowski sum of two polygons. Be careful with precision issues, use sgn with epsilons instead of  $c \leq 0$

**Time:**  $\mathcal{O}(N + M)$ , where N and M are the size of the polygons.  
 "Point.h"

243a8e, 21 lines

```
void fix(poly &a) {
    int pos = 0;
    rep(i, 0, sz(a)) {
        if(a[i].y < a[pos].y || (a[i].y == a[pos].y && a[i].x < a[pos].x)) pos = i;
    }
    rotate(a.begin(), a.begin() + pos, a.end());
}
poly minkowski_sum(poly a, poly b) {
    fix(a); fix(b);
    rep(it, 0, 2) a.push_back(a[it]), b.push_back(b[it]);
    int i = 0, j = 0;
    poly res;
    while(i < sz(a) - 2 || j < sz(b) - 2) {
        res.push_back(a[i] + b[j]);
        auto c = (a[i + 1] - a[i]).cross(b[j + 1] - b[j]);
        // a veces solo se necesita la segunda comprobacion
        if(i < sz(a) - 2 && c >= 0) i++;
        if(j < sz(b) - 2 && c <= 0) j++;
    }
    return res;
}
```

**LineHullIntersection.h**

**Description:** Line-convex polygon intersection. The polygon must be ccw and have no collinear points. lineHull(line, poly) returns a pair describing the intersection of a line with the polygon:  $\bullet(-1, -1)$  if no collision,  $\bullet(i, -1)$  if touching the corner  $i$ ,  $\bullet(i, i)$  if along side  $(i, i + 1)$ ,  $\bullet(i, j)$  if crossing sides  $(i, i + 1)$  and  $(j, j + 1)$ . In the last case, if a corner  $i$  is crossed, this is treated as happening on side  $(i, i + 1)$ . The points are returned in the same order as the line hits the polygon. extrVertex returns the point of a hull with the max projection onto a line.

**Time:**  $\mathcal{O}(\log n)$

"Point.h"

7cf45b, 39 lines

```
#define cmp(i, j) sgn(dir.perp().cross(poly[(i)%n]-poly[(j)%n]))
#define extr(i) cmp(i + 1, i) >= 0 && cmp(i, i - 1 + n) < 0
template <class P> int extrVertex(vector<P>& poly, P dir) {
    int n = sz(poly), lo = 0, hi = n;
    if (extr(0)) return 0;
    while (lo + 1 < hi) {
        int m = (lo + hi) / 2;
        if (extr(m)) return m;
        int ls = cmp(lo + 1, lo), ms = cmp(m + 1, m);
        (ls < ms || (ls == ms && ls == cmp(lo, m)) ? hi : lo) = m;
    }
    return lo;
}

#define cmpl(i) sgn(a.cross(poly[i], b))
template <class P>
array<int, 2> lineHull(P a, P b, vector<P>& poly) {
    int endA = extrVertex(poly, (a - b).perp());
    int endB = extrVertex(poly, (b - a).perp());
    if (cmpL(endA) < 0 || cmpL(endB) > 0)
        return {-1, -1};
    array<int, 2> res;
    rep(i, 0, 2) {
        int lo = endB, hi = endA, n = sz(poly);
        while ((lo + 1) % n != hi) {
            int m = ((lo + hi + (lo < hi ? 0 : n)) / 2) % n;
            (cmpL(m) == cmpL(endB) ? lo : hi) = m;
        }
        res[i] = (lo + !cmpl(hi)) % n;
        swap(endA, endB);
    }
    if (res[0] == res[1]) return {res[0], -1};
}
```

if (!cmpL(res[0]) && !cmpL(res[1]))  
 switch ((res[0] - res[1] + sz(poly) + 1) % sz(poly)) {  
 case 0: return {res[0], res[0]};  
 case 2: return {res[1], res[1]};  
 }  
 return res;
}

**8.4 Misc. Point Set Problems****ClosestPair.h**

**Description:** Finds the closest pair of points.

**Time:**  $\mathcal{O}(n \log n)$

"Point.h"

ac41a6, 17 lines

```
typedef Point<ll> P;
pair<P, P> closest(vector<P> v) {
    assert(sz(v) > 1);
    set<P> S;
    sort(all(v), [](P a, P b) { return a.y < b.y; });
    pair<ll, pair<P, P>> ret(LLONG_MAX, {P(), P()});
    int j = 0;
    for (P p : v) {
        P d{1 + (11)sqrt(ret.first), 0};
        while (v[j].y <= p.y - d.x) S.erase(v[j++]);
        auto lo = S.lower_bound(p - d), hi = S.upper_bound(p + d);
        for (; lo != hi; ++lo)
            ret = min(ret, {(*lo - p).dist2(), {*lo, p}});
        S.insert(p);
    }
    return ret.second;
}
```

**ManhattanMST.h**

**Description:** Given N points, returns up to  $4^*N$  edges, which are guaranteed to contain a minimum spanning tree for the graph with edge weights  $w(p, q) = -p.x - q.x + -p.y - q.y$ . Edges are in the form (distance, src, dst). Use a standard MST algorithm on the result to find the final MST.

**Time:**  $\mathcal{O}(N \log N)$

"Point.h"

df6f59, 23 lines

```
typedef Point<int> P;
vector<array<int, 3>> manhattanMST(vector<P> ps) {
    vi id{sz(ps)};
    iota(all(id), 0);
    vector<array<int, 3>> edges;
    rep(k, 0, 4) {
        sort(all(id), [&](int i, int j) {
            return (ps[i]-ps[j]).x < (ps[j]-ps[i]).y;
        });
        map<int, int> sweep;
        for (int i : id) {
            for (auto it = sweep.lower_bound(-ps[i].y);
                 it != sweep.end(); sweep.erase(it++)) {
                int j = it->second;
                P d = ps[i] - ps[j];
                if (d.y > d.x) break;
                edges.push_back({d.y + d.x, i, j});
            }
            sweep[-ps[i].y] = i;
        }
        for (P& p : ps) if (k & 1) p.x = -p.x; else swap(p.x, p.y);
    }
    return edges;
}
```

**kdTree.h**

**Description:** KD-tree (2d, can be extended to 3d)

"Point.h"

bac5b0, 63 lines

```
typedef long long T;
typedef Point<T> P;
```

```

const T INF = numeric_limits<T>::max();

bool on_x(const P& a, const P& b) { return a.x < b.x; }
bool on_y(const P& a, const P& b) { return a.y < b.y; }

struct Node {
    P pt; // if this is a leaf, the single point in it
    T x0 = INF, x1 = -INF, y0 = INF, y1 = -INF; // bounds
    Node *first = 0, *second = 0;

    T distance(const P& p) { // min squared distance to a point
        T x = (p.x < x0 ? x0 : p.x) > x1 ? x1 : p.x);
        T y = (p.y < y0 ? y0 : p.y) > y1 ? y1 : p.y);
        return (P(x,y) - p).dist2();
    }

    Node(vector<P>&& vp) : pt(vp[0]) {
        for (P p : vp) {
            x0 = min(x0, p.x); x1 = max(x1, p.x);
            y0 = min(y0, p.y); y1 = max(y1, p.y);
        }
        if (vp.size() > 1) {
            // split on x if width >= height (not ideal...)
            sort(all(vp), x1 - x0 >= y1 - y0 ? on_x : on_y);
            // divide by taking half the array for each child (not
            // best performance with many duplicates in the middle)
            int half = sz(vp)/2;
            first = new Node({vp.begin(), vp.begin() + half});
            second = new Node({vp.begin() + half, vp.end()});
        }
    }
};

struct KDTree {
    Node* root;
    KDTree(const vector<P>& vp) : root(new Node({all(vp)})) {}

    pair<T, P> search(Node *node, const P& p) {
        if (!node->first) {
            // uncomment if we should not find the point itself:
            // if (p == node->pt) return {INF, P()};
            return make_pair((p - node->pt).dist2(), node->pt);
        }

        Node *f = node->first, *s = node->second;
        T bfirst = f->distance(p), bsec = s->distance(p);
        if (bfirst > bsec) swap(bsec, bfirst), swap(f, s);

        // search closest side first, other side if needed
        auto best = search(f, p);
        if (bsec < best.first)
            best = min(best, search(s, p));
        return best;
    }

    // find nearest point to a point, and its squared distance
    // (requires an arbitrary operator< for Point)
    pair<T, P> nearest(const P& p) {
        return search(root, p);
    }
};

DelaunayTriangulation.h
Description: Computes the Delaunay triangulation of a set of points. Each circumcircle contains none of the input points. If any three points are collinear or any four are on the same circle, behavior is undefined.
Time:  $\mathcal{O}(n^2)$ 
"Point.h", "3dHull.h"
template<class P, class F>
c0e7bc, 10 lines

```

**DelaunayTriangulation** **FastDelaunay** **HalfPlaneIntersection**

```

void delaunay(vector<P>& ps, F trifun) {
    if (sz(ps) == 3) { int d = (ps[0].cross(ps[1], ps[2]) < 0);
        trifun(0,1+d,2-d); }
    vector<P> p3;
    for (P p : ps) p3.emplace_back(p.x, p.y, p.dist2());
    if (sz(ps) > 3) for(auto t:hull3d(p3)) if ((p3[t.b]-p3[t.a]).cross(p3[t.c]-p3[t.a]).dot(P3(0,0,1)) < 0)
        trifun(t.a, t.c, t.b);
}

```

**FastDelaunay.h**

**Description:** Fast Delaunay triangulation. Each circumcircle contains none of the input points. There must be no duplicate points. If all points are on a line, no triangles will be returned. Should work for doubles as well, though there may be precision issues in 'circ'. Returns triangles in order {t[0][0], t[0][1], t[0][2], t[1][0], ...}, all counter-clockwise.

**Time:**  $\mathcal{O}(n \log n)$

**"point.h"** **eefdf5, 88 lines**

```

typedef Point<ll> P;
typedef struct Quad* Q;
typedef __int128_t l1l; // (can be ll if coords are < 2e4)
P arb(LLONG_MAX,LLONG_MAX); // not equal to any other point

```

```

struct Quad {
    Q rot, o; P p = arb; bool mark;
    P& F() { return r()->p; }
    Q& r() { return rot->rot; }
    Q prev() { return rot->o->rot; }
    Q next() { return r()->prev(); }
} *H;

```

```

bool circ(P p, P a, P b, P c) { // is p in the circumcircle?
    l1l p2 = p.dist2(), A = a.dist2()-p2,
    B = b.dist2()-p2, C = c.dist2()-p2;
    return p.cross(a,b)*C + p.cross(b,c)*A + p.cross(c,a)*B > 0;
}

```

```

Q makeEdge(P orig, P dest) {
    Q r = H ? H : new Quad{new Quad{new Quad{new Quad{0}}}};
    H = r->o; r->r()->r() = r;
    rep(i,0,4) r = r->rot, r->p = arb, r->o = i & 1 ? r : r->r();
    r->p = orig; r->F() = dest;
    return r;
}

```

```

void splice(Q a, Q b) {
    swap(a->o->rot->o, b->o->rot->o); swap(a->o, b->o);
}

```

```

Q connect(Q a, Q b) {
    Q q = makeEdge(a->F(), b->p);
    splice(q, a->next());
    splice(q->r(), b);
    return q;
}

```

```

pair<Q,Q> rec(const vector<P>& s) {
    if (sz(s) <= 3) {
        Q a = makeEdge(s[0], s[1]), b = makeEdge(s[1], s.back());
        if (sz(s) == 2) return {a, a->r()};
        splice(a->r(), b);
        auto side = s[0].cross(s[1], s[2]);
        Q c = side ? connect(b, a) : 0;
        return {side < 0 ? c->r() : a, side < 0 ? c : b->r()};
    }
}

```

```

#define H(e) e->F(), e->p
#define valid(e) (e->F()).cross(H(base)) > 0
Q A, B, ra, rb;
int half = sz(s) / 2;
tie(ra, A) = rec({all(s) - half});
tie(B, rb) = rec({sz(s) - half + all(s)});

```

```

while ((B->p.cross(H(A)) < 0 && (A = A->next())) ||
        (A->p.cross(H(B)) > 0 && (B = B->r()->o)));
Q base = connect(B->r(), A);
if (A->p == ra->p) ra = base->r();
if (B->p == rb->p) rb = base;

```

```

#define DEL(e, init, dir) Q e = init->dir; if (valid(e)) \
while (circ(e->dir->F(), H(base), e->F())) { \
    Q t = e->dir; \
    splice(e, e->prev()); \
    splice(e->r(), e->r()->prev()); \
    e->o = H; H = e; e = t; \
}
for (;;) {
    DEL(LC, base->r(), o); DEL(RC, base, prev());
    if (!valid(LC) && !valid(RC)) break;
    if (!valid(LC) || (valid(RC) && circ(H(RC), H(LC)))) \
        base = connect(RC, base->r());
    else
        base = connect(base->r(), LC->r());
}
return {ra, rb};
}

```

```

vector<P> triangulate(vector<P> pts) {
    sort(all(pts)); assert(unique(all(pts)) == pts.end());
    if (sz(pts) < 2) return {};
    Q e = rec(pts).first;
    vector<Q> q = {e};
    int qi = 0;
    while (e->o->F().cross(e->F(), e->p) < 0) e = e->o;
#define ADD { Q c = e; do { c->mark = 1; pts.push_back(c->p); \
    q.push_back(c->r()); c = c->next(); } while (c != e); }
    ADD; pts.clear();
    while (qi < sz(q)) if (!(e = q[qi++])->mark) ADD;
    return pts;
}

```

**HalfPlaneIntersection.h**

**Description:** Returns a convex polygon, the intersection of some half-planes. You can add a bounding box at the beginning.

**Time:**  $\mathcal{O}(n \log n)$

**"Point.h"** **ce46b9, 56 lines**

```

struct HP {
    P a, b;
    HP() {}
    HP(P a, P b) : a(a), b(b) {}
    HP(const HP& rhs) : a(rhs.a), b(rhs.b) {}
    int operator < (const HP& rhs) const {
        P p = b - a;
        P q = rhs.b - rhs.a;
        int fp = (p.y < 0 || (fabsl(p.y) < eps && p.x < 0));
        int fq = (q.y < 0 || (fabsl(q.y) < eps && q.x < 0));
        if (fp != fq) return fp == 0;
        if (p.cross(q)) return p.cross(q) > 0;
        return p.cross(rhs.b - a) < 0;
    }
    P line_line_intersection(P a, P b, P c, P d) {
        b = b - a; d = c - d; c = c - a;
        return a + b * c.cross(d) / b.cross(d);
    }
    P intersection(const HP &v) {
        return line_line_intersection(a, b, v.a, v.b);
    }
};

int check(HP a, HP b, HP c) {
    return (a.b - a.a).cross(b.intersection(c) - a.a) > -eps;
}

```

```

vector<P> half_plane_intersection(vector<HP> h) {
    sort(all(h));
    vector<HP> tmp;
    rep(i,0,sz(h)) {
        if(!i || (h[i].b - h[i].a).cross(h[i-1].b - h[i-1].a)) {
            tmp.push_back(h[i]);
        }
    }

    h = tmp;
    vector<HP> q(sz(h) + 10);
    int qh = 0, qe = 0;
    rep(i,0,sz(h)) {
        while (qe - qh > 1 && !check(h[i], q[qe-2], q[qe-1])) qe--;
        while (qe - qh > 1 && !check(h[i], q[qh], q[qh+1])) qh++;
        q[qe++] = h[i];
    }

    while (qe - qh > 2 && !check(q[qh], q[qe-2], q[qe-1])) qe--;
    while (qe - qh > 2 && !check(q[qe-1], q[qh], q[qh+1])) qh++;

    vector<HP> res; rep(i,qh,qe) res.push_back(q[i]);
    vector<P> hull;
    if (sz(res) > 2) {
        rep(i,0,sz(res))
            hull.push_back(res[i].intersection(res[(i+1)%((int)res.size()))));
    }
    return hull;
}

```

## HalfPlaneIntersectionRandom.h

**Description:** Checks if the intersection of some half-planes is non-empty  
**Time:**  $\mathcal{O}(n)$

```

"Point.h"                                9dbd8c, 35 lines
struct line { P p, q; }
bool HPintersect(vector<line> v) {
    auto side = [] (line &l, P p) {
        return sideOf(l.p, l.q, p) >= 0;
    };

    auto crosspoint = [] (const line &l, const line &m, P &x) {
        auto inter = lineInter(l.p, l.q, m.p, m.q);
        if (inter.first <= 0) return false;
        x = inter.second;
        return true;
    };

    shuffle(all(v), mt19937(time(0)));
    P cen(0,1e9);
    rep(i,0,sz(v)) {
        line &S = v[i];
        if (side(S, cen)) continue;
        P d = (S.q - S.p).unit();
        P A = S.p - d * 1e8, B = S.p + d * 1e8;
        rep(j,0,i) {
            P x;
            line &T = v[j];
            if (crosspoint(T, S, x)) {
                int cnt = 0;
                if (!side(T, A)) A = x, cnt++;
                if (!side(T, B)) B = x, cnt++;
                if (cnt == 2) return false;
            }
        }
    }
}

```

```

        } else if (!side(T, A)) return false;
        if (B.y > A.y) swap(A, B);
        cen = A;
    }
    return true;
}

```

## 8.5 3D

### PolyhedronVolume.h

**Description:** Magic formula for the volume of a polyhedron. Faces should point outwards.

```

3058c3, 6 lines
template<class V, class L>
double signedPolyVolume(const V& p, const L& trilist) {
    double v = 0;
    for (auto i : trilist) v += p[i.a].cross(p[i.b]).dot(p[i.c]);
    return v / 6;
}

```

### Point3D.h

**Description:** Class to handle points in 3D space. T can be e.g. double or long long.

```

8058ae, 32 lines
template<class T> struct Point3D {
    typedef Point3D P;
    typedef const P & R;
    T x, y, z;
    explicit Point3D(T x=0, T y=0, T z=0) : x(x), y(y), z(z) {}
    bool operator<(R p) const {
        return tie(x, y, z) < tie(p.x, p.y, p.z); }
    bool operator==(R p) const {
        return tie(x, y, z) == tie(p.x, p.y, p.z); }
    P operator+(R p) const { return P(x+p.x, y+p.y, z+p.z); }
    P operator-(R p) const { return P(x-p.x, y-p.y, z-p.z); }
    P operator*(T d) const { return P(x*d, y*d, z*d); }
    P operator/(T d) const { return P(x/d, y/d, z/d); }
    T dot(R p) const { return x*p.x + y*p.y + z*p.z; }
    P cross(R p) const {
        return P(y*p.z - z*p.y, z*p.x - x*p.z, x*p.y - y*p.x); }
    }

```

```

T dist2() const { return x*x + y*y + z*z; }
double dist() const { return sqrt((double)dist2()); }
//Azimuthal angle (longitude) to x-axis in interval [-pi, pi]
double phi() const { return atan2(y, x); }
//Zenith angle (latitude) to the z-axis in interval [0, pi]
double theta() const { return atan2(sqrt(x*x+y*y), z); }
P unit() const { return *this/(T)dist(); } //makes dist()=1
//returns unit vector normal to *this and p
P normal(P p) const { return cross(p).unit(); }
//returns point rotated 'angle' radians ccw around axis
P rotate(double angle, P axis) const {
    double s = sin(angle), c = cos(angle); P u = axis.unit();
    return u*dot(u)*(1-c) + (*this)*c - cross(u)*s;
}

```

### 3dHull.h

**Description:** Computes all faces of the 3-dimension hull of a point set. \*No four points must be coplanar\*, or else random results will be returned. All faces will point outwards.

**Time:**  $\mathcal{O}(n^2)$

```

"Point3D.h"                                5b45fc, 49 lines
typedef Point3D<double> P3;

```

```

struct PR {
    void ins(int x) { (a == -1 ? a : b) = x; }
    void rem(int x) { (a == x ? a : b) = -1; }
}

```

```

int cnt() { return (a != -1) + (b != -1); }
int a, b;
};

struct F { P3 q; int a, b, c; };


```

```

vector<F> hull3d(const vector<P3> &A) {
    assert(sz(A) >= 4);
    vector<vector<PR>> E(sz(A), vector<PR>(sz(A), {-1, -1}));
#define E(x,y) E[f.x][f.y]
    vector<F> FS;

```

```

auto mf = [&] (int i, int j, int k, int l) {
    P3 q = (A[j] - A[i]).cross((A[k] - A[i]));
    if (q.dot(A[l]) > q.dot(A[i]))
        q = q * -1;
    F f{q, i, j, k};
    E(a,b).ins(k); E(a,c).ins(j); E(b,c).ins(i);
    FS.push_back(f);
};

rep(i,0,4) rep(j,i+1,4) rep(k,j+1,4)
mf(i, j, k, 6 - i - j - k);

rep(i,4,sz(A)) {
    rep(j,0,sz(FS)) {
        F f = FS[j];
        if (f.q.dot(A[i]) > f.q.dot(A[f.a])) {
            E(a,b).rem(f.c);
            E(a,c).rem(f.b);
            E(b,c).rem(f.a);
            swap(FS[j--], FS.back());
            FS.pop_back();
        }
    }
}

int nw = sz(FS);
rep(j,0,nw) {
    F f = FS[j];
#define C(a, b, c) if (E(a,b).cnt() != 2) mf(f.a, f.b, i, f.c);
    C(a, b, c); C(a, c, b); C(b, c, a);
}

```

```

for (F & it : FS) if ((A[it.b] - A[it.a]).cross(
    A[it.c] - A[it.a]).dot(it.q) <= 0) swap(it.c, it.b);
return FS;
};

```

### sphericalDistance.h

**Description:** Returns the shortest distance on the sphere with radius radius between the points with azimuthal angles (longitude)  $f_1(\phi_1)$  and  $f_2(\phi_2)$  from x axis and zenith angles (latitude)  $t_1(\theta_1)$  and  $t_2(\theta_2)$  from z axis ( $0 =$  north pole). All angles measured in radians. The algorithm starts by converting the spherical coordinates to cartesian coordinates so if that is what you have you can use only the two last rows.  $dx \cdot radius$  is then the difference between the two points in the x direction and  $d \cdot radius$  is the total distance between the points.

```

611f07, 8 lines
double sphericalDistance(double f1, double t1,
    double f2, double t2, double radius) {
    double dx = sin(t2)*cos(f2) - sin(t1)*cos(f1);
    double dy = sin(t2)*sin(f2) - sin(t1)*sin(f1);
    double dz = cos(t2) - cos(t1);
    double d = sqrt(dx*dx + dy*dy + dz*dz);
    return radius*2*asin(d/2);
}

```

## Strings (9)

## KMP.h

**Description:** pi[x] computes the length of the longest prefix of s that ends at x, other than s[0..x] itself (abacaba -> 0010123). Can be used to find all occurrences of a string.

**Time:**  $\mathcal{O}(n)$

d4375c, 16 lines

```
vi pi(const string& s) {
    vi p(sz(s));
    rep(i,1,sz(s)) {
        int g = p[i-1];
        while (g && s[i] != s[g]) g = p[g-1];
        p[i] = g + (s[i] == s[g]);
    }
    return p;
}

vi match(const string& s, const string& pat) {
    vi p = pi(pat + '\0' + s), res;
    rep(i,sz(p)-sz(s),sz(p))
        if (p[i] == sz(pat)) res.push_back(i - 2 * sz(pat));
    return res;
}
```

## Zfunc.h

**Description:** z[i] computes the length of the longest common prefix of s[i:] and s, except z[0] = 0. (abacaba -> 0010301)

**Time:**  $\mathcal{O}(n)$

ee09e2, 12 lines

```
vi Z(const string& S) {
    vi z(sz(S));
    int l = -1, r = -1;
    rep(i,1,sz(S)) {
        z[i] = i >= r ? 0 : min(r - i, z[i - 1]);
        while (i + z[i] < sz(S) && S[i + z[i]] == S[z[i]])
            z[i]++;
        if (i + z[i] > r)
            l = i, r = i + z[i];
    }
    return z;
}
```

## Manacher.h

**Description:** For each position in a string, computes half length of longest even palindrome around pos i

**Time:**  $\mathcal{O}(N)$

3af119, 28 lines

```
vi manacher_odd(string s) {
    int n = s.size();
    s = "@" + s + "$";
    vi len(n + 1);
    int l = 1, r = 1;
    for(int i = 1; i <= n; i++) {
        len[i] = min(r - i, len[l + (r - i)]);
        while(s[i - len[i]] == s[i + len[i]]) len[i]++;
        if(i + len[i] > r) {
            l = i - len[i];
            r = i + len[i];
        }
    }
    len.erase(begin(len));
    return len;
}

// para verificar si un substring es palindromo
// return pal[l + r] >= (r - l + 1) + 1; indexando en 0
vi manacher(string s) {
    string ns(1, '#');
    for(char c : s) {
        ns.push_back(c);
        ns.push_back('#');
    }
}
```

```
}
auto res = manacher_odd(ns);
return vi(res.begin() + 1, res.end() - 1);
}
```

## MinRotation.h

**Description:** Finds the lexicographically smallest rotation of a string.

**Usage:** rotate(v.begin(), v.begin() + minRotation(v), v.end());

**Time:**  $\mathcal{O}(N)$

d07a42, 8 lines

```
int minRotation(string s) {
    int a=0, N=sz(s); s += s;
    rep(b,0,N) rep(k,0,N) {
        if (a+k == b || s[a+k] < s[b+k]) {b += max(0, k-1); break;}
        if (s[a+k] > s[b+k]) {a = b; break;}
    }
    return a;
}
```

## SuffixArray.h

**Description:** Builds suffix array for a string. sa[i] is the starting index of the suffix which is  $i^{\text{th}}$  in the sorted suffix array. The returned vector is of size  $n + 1$ , and  $\text{sa}[0] = n$ . The lcp array contains longest common prefixes for neighbouring strings in the suffix array:  $\text{lcp}[i] = \text{lcp}(\text{sa}[i], \text{sa}[i-1])$ ,  $\text{lcp}[0] = 0$ . The input string must not contain any null chars.

**Time:**  $\mathcal{O}(n \log n)$

635552, 33 lines

```
struct SuffixArray {
    vi sa, lcp;
    SuffixArray(string s, int lim=256) { // or vector<int>
        s.push_back(0); int n = sz(s), k = 0, a, b;
        vi x(all(s)), y(n), ws(max(n, lim));
        sa = lcp = y, iota(all(sa), 0);
        for (int j = 0, p = 0; p < n; j = max(1, j * 2), lim = p) {
            p = j, iota(all(y), n - j);
            rep(i,0,n) if (sa[i] >= j) y[p++] = sa[i] - j;
            fill(all(ws), 0);
            rep(i,0,n) ws[x[i]]++;
            rep(i,1,lim) ws[i] += ws[i - 1];
            for (int i = n; i-->0; sa[--ws[x[y[i]]]] = y[i]);
            swap(x, y), p = 1, x[sa[0]] = 0;
            rep(i,1,n) a = sa[i - 1], b = sa[i], x[b] =
                (y[a] == y[b] && y[a + j] == y[b + j]) ? p - 1 : p++;
        }
        for (int i = 0, j; i < n - 1; lcp[x[i++]] = k)
            for (k && k--, j = sa[x[i] - 1]; s[i + k] == s[j + k]; k++);
    }

    //Longest Common Substring: construir el suffixArray s = s1 +
    //    "#" + s2 + "$" y m = sz(s2)
    // pair<int, int> lcs() {
    //     int mx = -1, ind = -1;
    //     for (int i = 1; i < n; i++) {
    //         if (((sa[i] < n-m-1) != (sa[i-1] < n-m-1)) && mx
    //             < lcp[i]) {
    //             mx = lcp[i]; ind = i;
    //         }
    //     }
    //     return {mx, ind};
    // }
}
```

## SuffixTree.h

**Description:** Ukkonen's algorithm for online suffix tree construction. Each node contains indices [l, r) into the string, and a list of child nodes. Suffixes are given by traversals of this tree, joining [l, r) substrings. The root is 0 (has l = -1, r = 0), non-existent children are -1. To get a complete tree, append a dummy symbol – otherwise it may contain an incomplete path (still useful for substring matching, though).

**Time:**  $\mathcal{O}(26N)$

aae0b8, 50 lines

```
struct SuffixTree {
    enum { N = 200010, ALPHA = 26 }; // N ~ 2*maxlen+10
    int toi(char c) { return c - 'a'; }
    string a; // v = cur node, q = cur position
    int t[N][ALPHA], l[N], r[N], p[N], s[N], v=0, q=0, m=2;

    void ukkadd(int i, int c) { suff:
        if (r[v]<=q) {
            if (t[v][c]==-1) { t[v][c]=m; l[m]=i;
                p[m++]=v; v=s[v]; q=r[v]; goto suff; }
            v=t[v][c]; q=l[v];
        }
        if (q===-1 || c==toi(a[q])) q++; else {
            l[m+1]=i; p[m+1]=m; l[m]=l[v]; r[m]=q;
            p[m]=p[v]; t[m][c]=m+1; t[m][toi(a[q])]=v;
            l[v]=q; p[v]=m; t[p[m]][toi(a[l[m]])]=m;
            v=s[p[m]]; q=l[m];
            while (q<r[m]) { v=t[v][toi(a[q])]; q+=r[v]-1[v]; }
            if (q==r[m]) s[m]=v; else s[m]=m+2;
            q=r[v]-(q-r[m]); m+=2; goto suff;
        }
    }

    SuffixTree(string a) : a(a) {
        fill(r,r+N,sz(a));
        memset(s, 0, sizeof s);
        memset(t, -1, sizeof t);
        fill(t[1],t[1]+ALPHA,0);
        s[0] = 1; l[0] = 1; r[0] = -1; r[0] = r[1] = p[0] = p[1] = 0;
        rep(i,0,sz(a)) ukkadd(i, toi(a[i]));
    }

    // example: find longest common substring (uses ALPHA = 28)
    pii best;
    int lcs(int node, int i1, int i2, int olen) {
        if (l[node] <= i1 && i1 < r[node]) return 1;
        if (l[node] <= i2 && i2 < r[node]) return 2;
        int mask = 0, len = node ? olen + (r[node] - l[node]) : 0;
        rep(c,0,ALPHA) if (t[node][c] != -1)
            mask |= lcs(t[node][c], i1, i2, len);
        if (mask == 3)
            best = max(best, {len, r[node] - len});
        return mask;
    }

    static pii LCS(string s, string t) {
        SuffixTree st(s + (char)('z' + 1) + t + (char)('z' + 2));
        st.lcs(0, sz(s), sz(s) + 1 + sz(t), 0);
        return st.best;
    }
}
```

## Hashing.h

**Description:** Self-explanatory methods for string hashing.

2d2a67, 44 lines

```
// Arithmetic mod  $2^{64}-1$ . 2x slower than mod  $2^{64}$  and more
// code, but works on evil test data (e.g. Thue-Morse, where
// "ABBA..." and "BABA..." of length  $2^{10}$  hash the same mod  $2^{64}$ ).
// "typedef ull H;" instead if you think test data is random,
// or work mod  $10^{9}+7$  if the Birthday paradox is not a problem.
typedef uint64_t ull;
struct H {
    ull x; H(ull x=0) : x(x) {}
```

```

H operator+(H o) { return x + o.x + (x + o.x < x); }
H operator-(H o) { return *this + ~o.x; }
H operator*(H o) { auto m = (_uint128_t)x * o.x;
    return H((ull)m + (ull)(m >> 64)); }
ull get() const { return x + !~x; }
bool operator==(H o) const { return get() == o.get(); }
bool operator<(H o) const { return get() < o.get(); }
};

static const H C = (ll)1e11+3; // (order ~ 3e9; random also ok)

struct HashInterval {
    vector<H> ha, pw;
    HashInterval(string& str) : ha(sz(str)+1), pw(ha) {
        pw[0] = 1;
        rep(i,0,sz(str))
            ha[i+1] = ha[i] * C + str[i],
            pw[i+1] = pw[i] * C;
    }
    H hashInterval(int a, int b) { // hash [a, b)
        return ha[b] - ha[a] * pw[b-a];
    }
};

vector<H> getHashes(string& str, int length) {
    if (sz(str) < length) return {};
    H h = 0, pw = 1;
    rep(i,0,length)
        h = h * C + str[i], pw = pw * C;
    vector<H> ret = {h};
    rep(i,length,sz(str)) {
        ret.push_back(h = h * C + str[i] - pw * str[i-length]);
    }
    return ret;
}

H hashString(string& s){H h{}; for(char c:s) h=h*C+c;return h;}

```

### AhoCorasick.h

**Description:** Aho-Corasick automaton, used for multiple pattern matching. Initialize with AhoCorasick ac(patterns); the automaton start node will be at index 0. find(word) returns for each position the index of the longest word that ends there, or -1 if none. findAll(–, word) finds all words (up to  $N\sqrt{N}$  many if no duplicate patterns) that start at each position (shortest first). Duplicate patterns are allowed; empty patterns are not. To find the longest words that start at each position, reverse all input. For large alphabets, split each symbol into chunks, with sentinel bits for symbol boundaries.

**Time:** construction takes  $\mathcal{O}(26N)$ , where  $N$  = sum of length of patterns. find(x) is  $\mathcal{O}(N)$ , where  $N$  = length of x. findAll is  $\mathcal{O}(NM)$ . f35677, 66 lines

```

struct AhoCorasick {
    enum {alpha = 26, first = 'A'}; // change this!
    struct Node {
        // (nmatches is optional)
        int back, next[alpha], start = -1, end = -1, nmatches = 0;
        Node(int v) { memset(next, v, sizeof(next)); }
    };
    vector<Node> N;
    vi backp;
    void insert(string& s, int j) {
        assert(!s.empty());
        int n = 0;
        for (char c : s) {
            int& m = N[n].next[c - first];
            if (m == -1) { n = m = sz(N); N.emplace_back(-1); }
            else n = m;
        }
        if (N[n].end == -1) N[n].start = j;
        backp.push_back(N[n].end);
        N[n].end = j;
    }
};

```

### AhoCorasick Eertree IntervalContainer IntervalCover

```

N[n].nmatches++;
}
AhoCorasick(vector<string>& pat) : N(1, -1) {
    rep(i,0,sz(pat)) insert(pat[i], i);
    N[0].back = sz(N);
    N.emplace_back(0);

    queue<int> q;
    for (q.push(0); !q.empty(); q.pop()) {
        int n = q.front(), prev = N[n].back;
        rep(i,0,alpha) {
            int &ed = N[n].next[i], y = N[prev].next[i];
            if (ed == -1) ed = y;
            else {
                N[ed].back = y;
                (N[ed].end == -1 ? N[ed].end : backp[N[ed].start])
                    = N[y].end;
                N[ed].nmatches += N[y].nmatches;
                q.push(ed);
            }
        }
    }
    vi find(string word) {
        int n = 0;
        vi res; // ll count = 0;
        for (char c : word) {
            n = N[n].next[c - first];
            res.push_back(N[n].end);
            // count += N[n].nmatches;
        }
        return res;
    }
    vector<vi> findAll(vector<string>& pat, string word) {
        vi r = find(word);
        vector<vi> res(sz(word));
        rep(i,0,sz(word)) {
            int ind = r[i];
            while (ind != -1) {
                res[i - sz(pat[ind]) + 1].push_back(ind);
                ind = backp[ind];
            }
        }
        return res;
    }
};

```

### Eertree.h

**Description:** Get the number of unique palindromic substrings online. Time:  $\mathcal{O}(N)$

```

94ca78, 44 lines
struct palindromic_tree{
    struct node{
        int next[26], fail, len;
        int cnt, num, st, ed;
        node(int l=0):fail(l),len(l),cnt(0),num(0){
            for(int i=0;i<26;++i)next[i]=0;
        }
    };
    vector<node> state;
    vector<char> s;
    int last, n;

    void init(){
        state.clear();
        s.clear();
        last=1;
        n=0;
        state.push_back(0);
    }
};

```

```

state.push_back(-1);
state[0].fail=1;
s.push_back(-1);
}
int get_fail(int x){
    while(s[n-state[x].len-1]!=s[n])x=state[x].fail;
    return x;
}
void add(int c){
    s.push_back(c-'a');
    ++n;
    int cur=get_fail(last);
    if(!state[cur].next[c]){
        int now=state.size();
        state.push_back(state[cur].len+2);
        state[now].fail=state[get_fail(state[cur].fail)].next[c];
        state[cur].next[c]=now;
        state[now].num=state[state[now].fail].num+1;
    }
    last=state[cur].next[c];
    ++state[last].cnt;
}
int size(){
    return state.size()-2;
}
} pt;

```

### Various (10)

#### 10.1 Intervals

##### IntervalContainer.h

**Description:** Add and remove intervals from a set of disjoint intervals. Will merge the added interval with any overlapping intervals in the set when adding. Intervals are [inclusive, exclusive).

**Time:**  $\mathcal{O}(\log N)$

edce47, 23 lines

```

set<pii>::iterator addInterval(set<pii>& is, int L, int R) {
    if (L == R) return is.end();
    auto it = is.lower_bound({L, R}), before = it;
    while (it != is.end() && it->first <= R) {
        R = max(R, it->second);
        before = it = is.erase(it);
    }
    if (it != is.begin() && (--it)->second >= L) {
        L = min(L, it->first);
        R = max(R, it->second);
        is.erase(it);
    }
    return is.insert(before, {L,R});
}

```

```

void removeInterval(set<pii>& is, int L, int R) {
    if (L == R) return;
    auto it = addInterval(is, L, R);
    auto r2 = it->second;
    if (it->first == L) is.erase(it);
    else (int&it->second = L;
    if (R != r2) is.emplace(R, r2);
}

```

##### IntervalCover.h

**Description:** Compute indices of smallest set of intervals covering another interval. Intervals should be [inclusive, exclusive). To support [inclusive, inclusive], change (A) to add || R.empty(). Returns empty set on failure (or if G is empty).

**Time:**  $\mathcal{O}(N \log N)$

9e9d8d, 19 lines

```
template<class T>
vi cover(pair<T, T> G, vector<pair<T, T>> I) {
    vi S(sz(I)), R;
    iota(all(S), 0);
    sort(all(S), [&](int a, int b) { return I[a] < I[b]; });
    T cur = G.first;
    int at = 0;
    while (cur < G.second) { // (A)
        pair<T, int> mx = make_pair(cur, -1);
        while (at < sz(I) && I[S[at]].first <= cur) {
            mx = max(mx, make_pair(I[S[at]].second, S[at]));
            at++;
        }
        if (mx.second == -1) return {};
        cur = mx.first;
        R.push_back(mx.second);
    }
    return R;
}
```

**ConstantIntervals.h**

**Description:** Split a monotone function on [from, to) into a minimal set of half-open intervals on which it has the same value. Runs a callback g for each such interval.

**Usage:** constantIntervals(0, sz(v), [&](int x){return v[x];}, [&](int lo, int hi, T val){...});

**Time:**  $\mathcal{O}(k \log \frac{n}{k})$

753a4c, 19 lines

```
template<class F, class G, class T>
void rec(int from, int to, F& f, G& g, int& i, T& p, T q) {
    if (p == q) return;
    if (from == to) {
        g(i, to, p);
        i = to; p = q;
    } else {
        int mid = (from + to) >> 1;
        rec(from, mid, f, g, i, p, f(mid));
        rec(mid+1, to, f, g, i, p, q);
    }
}
template<class F, class G>
void constantIntervals(int from, int to, F f, G g) {
    if (to <= from) return;
    int i = from; auto p = f(i), q = f(to-1);
    rec(from, to-1, f, g, i, p, q);
    g(i, to, q);
}
```

**10.2 Misc. algorithms****TernarySearch.h**

**Description:** Find the smallest i in  $[a, b]$  that maximizes  $f(i)$ , assuming that  $f(a) < \dots < f(i) \geq \dots \geq f(b)$ . To reverse which of the sides allows non-strict inequalities, change the  $<$  marked with (A) to  $\leq$ , and reverse the loop at (B). To minimize  $f$ , change it to  $>$ , also at (B).

**Usage:** int ind = ternSearch(0, n-1, [&](int i){return a[i];});

**Time:**  $\mathcal{O}(\log(b-a))$

9155b4, 11 lines

```
template<class F>
int ternSearch(int a, int b, F f) {
    assert(a <= b);
    while (b - a >= 5) {
        int mid = (a + b) / 2;
        if (f(mid) < f(mid+1)) a = mid; // (A)
        else b = mid+1;
    }
    rep(i, a+1, b+1) if (f(a) < f(i)) a = i; // (B)
    return a;
}
```

**LIS.h**

**Description:** Compute indices for the longest increasing subsequence.

**Time:**  $\mathcal{O}(N \log N)$

2932a0, 17 lines

```
template<class I> vi lis(const vector<I>& S) {
    if (S.empty()) return {};
    vi prev(sz(S));
    typedef pair<I, int> p;
    vector<p> res;
    rep(i, 0, sz(S)) {
        // change 0 -> i for longest non-decreasing subsequence
        auto it = lower_bound(all(res), p{S[i], 0});
        if (it == res.end()) res.emplace_back(), it = res.end()-1;
        *it = {S[i], i};
        prev[i] = it == res.begin() ? 0 : (it-1)->second;
    }
    int L = sz(res), cur = res.back().second;
    vi ans(L);
    while (L--) ans[L] = cur, cur = prev[cur];
    return ans;
}
```

**FastKnapsack.h**

**Description:** Given N non-negative integer weights w and a non-negative target t, computes the maximum S  $\leq t$  such that S is the sum of some subset of the weights.

**Time:**  $\mathcal{O}(N \max(w_i))$

b20ccc, 16 lines

```
int knapsack(vi w, int t) {
    int a = 0, b = 0, x;
    while (b < sz(w) && a + w[b] <= t) a += w[b++];
    if (b == sz(w)) return a;
    int m = *max_element(all(w));
    vi u, v(2*m, -1);
    v[a+m-t] = b;
    rep(i, b, sz(w)) {
        u = v;
        rep(x, 0, m) v[x+w[i]] = max(v[x+w[i]], u[x]);
        for (x = 2*m; --x > m; ) rep(j, max(0, u[x]), v[x])
            v[x-w[j]] = max(v[x-w[j]], j);
    }
    for (a = t; v[a+m-t] < 0; a--) ;
    return a;
}
```

**10.3 Dynamic programming****KnuthDP.h**

**Description:** When doing DP on intervals:  $a[i][j] = \min_{i < k < j} (a[i][k] + a[k][j]) + f(i, j)$ , where the (minimal) optimal  $k$  increases with both  $i$  and  $j$ , one can solve intervals in increasing order of length, and search  $k = p[i][j]$  for  $a[i][j]$  only between  $p[i][j-1]$  and  $p[i+1][j]$ . This is known as Knuth DP. Sufficient criteria for this are if  $f(b, c) \leq f(a, d)$  and  $f(a, c) + f(b, d) \leq f(a, d) + f(b, c)$  for all  $a \leq b \leq c \leq d$ . Consider also: LineContainer (ch. Data structures), monotone queues, ternary search.

**Time:**  $\mathcal{O}(N^2)$

**DivideAndConquerDP.h**

**Description:** Given  $a[i] = \min_{lo(i) \leq k \leq hi(i)} (f(i, k))$  where the (minimal) optimal  $k$  increases with  $i$ , computes  $\bar{a}[i]$  for  $i = L..R-1$ .

**Time:**  $\mathcal{O}((N + (hi - lo)) \log N)$

d38d2b, 18 lines

```
struct DP { // Modify at will:
    int lo(int ind) { return 0; }
    int hi(int ind) { return ind; }
    ll f(int ind, int k) { return dp[ind][k]; }
    void store(int ind, int k, ll v) { res[ind] = pii(k, v); }
    void rec(int L, int R, int LO, int HI) {
```

**FastMod.h**

**Description:** Compute  $a\%b$  about 5 times faster than usual, where  $b$  is constant but not known at compile time. Returns a value congruent to  $a$  (mod  $b$ ) in the range  $[0, 2b)$ .

751a02, 8 lines

typedefed unsigned long long ull;

struct FastMod {

```
    ull b, m;
    FastMod(ull b) : b(b), m(-1ULL / b) {}
    ull reduce(ull a) { // a % b + (0 or b)
        return a - (ull)((__uint128_t(m) * a) >> 64) * b;
```

**10.4 Debugging tricks**

- signal(SIGSEGV, []() { \_Exit(0); }); converts segfaults into Wrong Answers. Similarly one can catch SIGABRT (assertion failures) and SIGFPE (zero divisions). `_GLIBCXX_DEBUG` failures generate SIGABRT (or SIGSEGV on gcc 5.4.0 apparently).
- feenableexcept(29); kills the program on NaNs (1), 0-divs (4), infinities (8) and denormals (16).

**10.5 Optimization tricks**

`__builtin_ia32_ldmxcsr(40896);` disables denormals (which make floats 20x slower near their minimum value).

**10.5.1 Bit hacks**

- $x \& -x$  is the least bit in  $x$ .
- for (int x = m; x; ) {  $--x \&= m$ ; ... } loops over all subset masks of  $m$  (except  $m$  itself).
- $c = x \& -x$ ,  $r = x + c$ ;  $((r^x) >> 2)/c$  |  $r$  is the next number after  $x$  with the same number of bits set.
- rep(b, 0, K) rep(i, 0, (1 << K))
   
if ( $i \& 1 << b$ )  $D[i] += D[i \wedge (1 << b)]$ ;
   
computes all sums of subsets.

**10.5.2 Pragmas**

- `#pragma GCC optimize ("Ofast")` will make GCC auto-vectorize loops and optimizes floating points better.
- `#pragma GCC target ("avx2")` can double performance of vectorized code, but causes crashes on old machines.
- `#pragma GCC optimize ("trapv")` kills the program on integer overflows (but is really slow).

**FastMod.h**

**Description:** Compute  $a\%b$  about 5 times faster than usual, where  $b$  is constant but not known at compile time. Returns a value congruent to  $a$  (mod  $b$ ) in the range  $[0, 2b)$ .

```
}
```

**FastInput.h**

**Description:** Read an integer from stdin. Usage requires your program to pipe in input from file.

**Usage:** ./a.out < input.txt

**Time:** About 5x as fast as cin/scanf.

7b3c70, 17 lines

```
inline char gc() { // like getchar()
    static char buf[1 << 16];
    static size_t bc, be;
    if (bc >= be) {
        buf[0] = 0, bc = 0;
        be = fread(buf, 1, sizeof(buf), stdin);
    }
    return buf[bc++]; // returns 0 on EOF
}
```

```
int readInt() {
    int a, c;
    while ((a = gc()) < 40);
    if (a == '-') return -readInt();
    while ((c = gc()) >= 48) a = a * 10 + c - 480;
    return a - 48;
}
```

**BumpAllocator.h**

**Description:** When you need to dynamically allocate many objects and don't care about freeing them. "new X" otherwise has an overhead of something like 0.05us + 16 bytes per allocation.

745db2, 8 lines

```
// Either globally or in a single class:
static char buf[450 << 20];
void* operator new(size_t s) {
    static size_t i = sizeof buf;
    assert(s < i);
    return (void*)&buf[i -= s];
}
void operator delete(void*) {}
```

**SmallPtr.h**

**Description:** A 32-bit pointer that points into BumpAllocator memory.

"BumpAllocator.h"

2dd6c9, 10 lines

```
template<class T> struct ptr {
    unsigned ind;
    ptr(T* p = 0) : ind(p ? unsigned((char*)p - buf) : 0) {
        assert(ind < sizeof buf);
    }
    T& operator*() const { return *(T*)(buf + ind); }
    T* operator->() const { return &**this; }
    T& operator[](int a) const { return (&**this)[a]; }
    explicit operator bool() const { return ind; }
};
```

**BumpAllocatorSTL.h**

**Description:** BumpAllocator for STL containers.

**Usage:** vector<vector<int, small<int>>> ed(N);

bb66d4, 14 lines

```
char buf[450 << 20] alignas(16);
size_t buf_ind = sizeof buf;
```

```
template<class T> struct small {
    typedef T value_type;
    small() {}
    template<class U> small(const U&) {}
    T* allocate(size_t n) {
        buf_ind -= n * sizeof(T);
        buf_ind &= 0 - alignof(T);
```

```
        return (T*)(buf + buf_ind);
    }
    void deallocate(T*, size_t) {}
};
```

**SIMD.h**

**Description:** Cheat sheet of SSE/AVX intrinsics, for doing arithmetic on several numbers at once. Can provide a constant factor improvement of about 4, orthogonal to loop unrolling. Operations follow the pattern "`_mm(256)_name_(si(128|256)|epi(8|16|32|64)|pd|ps)`". Not all are described here; grep for `_mm_` in `/usr/lib/gcc/*4.9/include/` for more. If AVX is unsupported, try 128-bit operations, "emmintrin.h" and `#define __SSE__` and `__MMX__` before including it. For aligned memory use `_mm_malloc(size, 32)` or `int buf[N] alignas(32)`, but prefer `loadu/storeu`.

551b82, 43 lines

```
#pragma GCC target ("avx2") // or sse4.1
#include "immintrin.h"
```

```
typedef __m256i mi;
#define L(x) _mm256_loadu_si256((mi*)&(x))
```

*// High-level/specific methods:*  
`// load(u)?_si256, store(u)?_si256, setzero_si256, _mm_malloc`  
`// blendv_(epi8|ps|pd) (z?y:x), movmask_epi8 (hbits of bytes)`  
`// i32gather_epi32(addr, x, 4): map addr[] over 32-b parts of x`  
`// sad_epu8: sum of absolute differences of u8, outputs 4xi64`  
`// maddubs_ep16: dot product of unsigned i7's, outputs 16xi15`  
`// madd_ep16: dot product of signed i16's, outputs 8xi32`  
`// extractf128_si256(, i) (256->128), cvtsi128_si32 (128->lo32)`  
`// permute2f128_si256(x,x,1) swaps 128-bit lanes`  
`// shuffle_epi32(x, 3*64+2*16+1*4+0) == x for each lane`  
`// shuffle_epi8(x, y) takes a vector instead of an imm`

*// Methods that work with most data types (append e.g. \_epi32):*  
`// set1, blend (i8?x:y), add, adds (sat.), mullo, sub, and/or,`  
`// andnot, abs, min, max, sign(1,x), cmp(gt|eq), unpack(lo|hi)`

```
int sumi32(mi m) { union {int v[8]; mi m;} u; u.m = m;
    int ret = 0; rep(i,0,8) ret += u.v[i]; return ret; }
mi zero() { return _mm256_setzero_si256(); }
mi one() { return _mm256_set1_epi32(-1); }
bool all_zero(mi m) { return _mm256_testz_si256(m, m); }
bool all_one(mi m) { return _mm256_testc_si256(m, one()); }
```

```
ll example_filteredDotProduct(int n, short* a, short* b) {
    int i = 0; ll r = 0;
    mi zero = _mm256_setzero_si256(), acc = zero;
    while (i + 16 <= n) {
        mi va = L(a[i]), vb = L(b[i]); i += 16;
        va = _mm256_and_si256(_mm256_cmplt_ep16(vb, va), va);
        mi vp = _mm256_madd_ep16(va, vb);
        acc = _mm256_add_ep164(_mm256_unpacklo_epi32(vp, zero),
            _mm256_add_ep164(acc, _mm256_unpackhi_epi32(vp, zero)));
    }
    union {ll v[4]; mi m;} u; u.m = acc; rep(i,0,4) r += u.v[i];
    for (i;n;+i) if (a[i] < b[i]) r += a[i]*b[i]; // <- equiv
    return r;
}
```

# Techniques (A)

## techniques.txt

159 lines

Recursion  
 Divide and conquer  
     Finding interesting points in  $N \log N$   
 Algorithm analysis  
     Master theorem  
     Amortized time complexity  
 Greedy algorithm  
     Scheduling  
     Max contiguous subvector sum  
 Invariants  
 Huffman encoding  
 Graph theory  
     Dynamic graphs (extra book-keeping)  
     Breadth first search  
     Depth first search  
         \* Normal trees / DFS trees  
     Dijkstra's algorithm  
     MST: Prim's algorithm  
     Bellman-Ford  
     Konig's theorem and vertex cover  
     Min-cost max flow  
     Lovasz toggle  
     Matrix tree theorem  
     Maximal matching, general graphs  
     Hopcroft-Karp  
     Hall's marriage theorem  
     Graphical sequences  
     Floyd-Warshall  
     Euler cycles  
     Flow networks  
         \* Augmenting paths  
         \* Edmonds-Karp  
     Bipartite matching  
     Min. path cover  
     Topological sorting  
     Strongly connected components  
 2-SAT  
 Cut vertices, cut-edges and biconnected components  
 Edge coloring  
     \* Trees  
 Vertex coloring  
     \* Bipartite graphs ( $\Rightarrow$  trees)  
     \*  $3^n$  (special case of set cover)  
 Diameter and centroid  
 K'th shortest path  
 Shortest cycle  
 Dynamic programming  
     Knapsack  
     Coin change  
     Longest common subsequence  
     Longest increasing subsequence  
     Number of paths in a dag  
     Shortest path in a dag  
     Dynprog over intervals  
     Dynprog over subsets  
     Dynprog over probabilities  
     Dynprog over trees  
      $3^n$  set cover  
 Divide and conquer  
 Knuth optimization  
 Convex hull optimizations  
 RMQ (sparse table a.k.a  $2^k$ -jumps)  
 Bitonic cycle  
 Log partitioning (loop over most restricted)  
 Combinatorics

Computation of binomial coefficients  
 Pigeon-hole principle  
 Inclusion/exclusion  
 Catalan number  
 Pick's theorem  
 Number theory  
     Integer parts  
     Divisibility  
     Euclidean algorithm  
     Modular arithmetic  
         \* Modular multiplication  
         \* Modular inverses  
         \* Modular exponentiation by squaring  
     Chinese remainder theorem  
     Fermat's little theorem  
     Euler's theorem  
     Phi function  
     Frobenius number  
     Quadratic reciprocity  
     Pollard-Rho  
     Miller-Rabin  
     Hensel lifting  
     Vieta root jumping  
 Game theory  
     Combinatorial games  
     Game trees  
     Mini-max  
     Nim  
     Games on graphs  
     Games on graphs with loops  
     Grundy numbers  
     Bipartite games without repetition  
     General games without repetition  
     Alpha-beta pruning  
 Probability theory  
 Optimization  
     Binary search  
     Ternary search  
     Unimodality and convex functions  
     Binary search on derivative  
 Numerical methods  
     Numeric integration  
     Newton's method  
     Root-finding with binary/ternary search  
     Golden section search  
 Matrices  
     Gaussian elimination  
     Exponentiation by squaring  
 Sorting  
     Radix sort  
 Geometry  
     Coordinates and vectors  
         \* Cross product  
         \* Scalar product  
     Convex hull  
     Polygon cut  
     Closest pair  
     Coordinate-compression  
     Quadtrees  
     KD-trees  
     All segment-segment intersection  
 Sweeping  
     Discretization (convert to events and sweep)  
     Angle sweeping  
     Line sweeping  
     Discrete second derivatives  
 Strings  
     Longest common substring  
     Palindrome subsequences

Knuth-Morris-Pratt  
 Tries  
 Rolling polynomial hashes  
 Suffix array  
 Suffix tree  
 Aho-Corasick  
 Manacher's algorithm  
 Letter position lists  
 Combinatorial search  
     Meet in the middle  
     Brute-force with pruning  
     Best-first (A\*)  
     Bidirectional search  
     Iterative deepening DFS / A\*

Data structures  
     LCA ( $2^k$ -jumps in trees in general)  
     Pull/push-technique on trees  
     Heavy-light decomposition  
     Centroid decomposition  
     Lazy propagation  
     Self-balancing trees  
     Convex hull trick ([wcipeg.com/wiki/Convex\\_hull\\_trick](http://wcipeg.com/wiki/Convex_hull_trick))  
     Monotone queues / monotone stacks / sliding queues  
     Sliding queue using 2 stacks  
     Persistent segment tree