

Solving ~~QFTs~~ convection-diffusion equations with finite volume methods

Kurganov and Tadmor (KT) $O(x^2)$ central scheme - An appetizer

Adrian Koenigstein¹ & Martin J. Steil²

¹Goethe Universität Frankfurt

²Technische Universität Darmstadt

QCD & beyond with the functional renormalisation group,
Heidelberg, July 17, 2019



- ▶ FRG flow eqs. especially LPA flow eqs. of low-energy effective models can be written as **Convection–diffusion equations¹**:

$$\partial_t u(t, x) + \partial_x F[t, u(t, x)] = \partial_x Q[t, x, u(t, x), \partial_x u(t, x)] + \partial_x S(t, x)$$

- Very common class of PDEs in Physics, Engineering and Numerical Mathematics
- Well established numerical methods available (see talks of N. Wink and D. Rischke) \Rightarrow among them are **Finite volume (FV) methods**

¹E. Grossi and N. Wink (2019), arXiv: 1903.09503 [hep-th]

$$\partial_t u(t, x) + \partial_x F[t, u(t, x)] = \partial_x Q[t, x, u(t, x), \partial_x u(t, x)] + \partial_x S(t, x) \quad (1)$$

- ▶ $u(t, x)$ vector of conserved quantities
- ▶ $F[t, u(t, x)]$ nonlinear convection flux
- ▶ $Q[t, x, u(t, x), \partial_x u(t, x)]$ dissipation flux
- ▶ $S(t, x)$ source term

Examples:

- ▶ Linear Advection and (inviscid/viscous) Burgers' eqs. with non-smooth ICs
- ▶ Euler Equations of Gas Dynamics (Shock tube problem)
- ▶ **FRG LPA flow equations**

Journal of Computational Physics **160**, 241–282 (2000)

doi:10.1006/jcph.2000.6459, available online at <http://www.idealibrary.com> on  IDEAL®

New High-Resolution Central Schemes for Nonlinear Conservation Laws and Convection–Diffusion Equations

Alexander Kurganov* and Eitan Tadmor†

*Department of Mathematics, University of Michigan, Ann Arbor, Michigan 48109;

and †Department of Mathematics, UCLA, Los Angeles, California 90095

E-mail: *kurganov@math.lsa.umich.edu, †tadmor@math.ucla.edu

Received April 8, 1999; revised December 8, 1999

A. Kurganov and E. Tadmor, J. Comput. Phys. **160** (May 2000)

Semi-discrete central scheme

- ▶ Equidistant spatial finite volume grid with n cells

$$\{x_j\} = \{x_0, x_0 + \Delta x, \dots, x_1\} \quad (2)$$

$$\{u_j\} = \{u(t, x_0), u(t, x_0 + \Delta x), \dots, u(t, x_1)\} \quad (3)$$

with extrapolated ghost points e.g. $u_{-1} = 2u_0 - u_1$

- ▶ Conservation form:

$$\begin{aligned} \frac{du_j}{dt} = & -\frac{H_{j+1/2}(t) - H_{j-1/2}(t)}{\Delta x} + \frac{P_{j+1/2}(t) - P_{j-1/2}(t)}{\Delta x} \\ & + \frac{S_{j+1/2}(t) - S_{j-1/2}(t)}{\Delta x} \end{aligned} \quad (4)$$

- $H_{j\pm 1/2}(t)$ Numerical convection flux on left/right cell boundary
- $P_{j\pm 1/2}(t)$ Numerical diffusion flux on left/right cell boundary
- $S_{j\pm 1/2}(t)$ Numerical source term on left/right cell boundary

$$H_{j+1/2}(t) = \frac{F[t, u_{j+1/2}^+] + F[t, u_{j+1/2}^-]}{2} - \frac{a_{j+1/2}}{2} (u_{j+1/2}^+ - u_{j+1/2}^-), \quad (5)$$

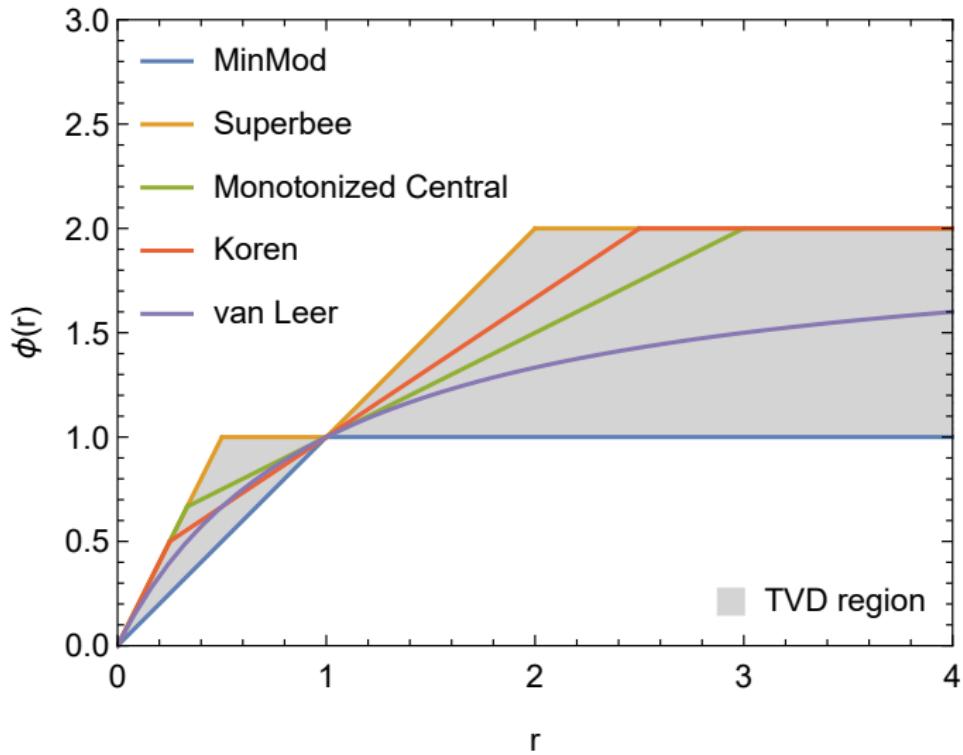
► Maximal local speed

$$a_{j+1/2} = \max \left(\rho \left(\frac{\partial F}{\partial u}(u_{j+1/2}^+) \right), \rho \left(\frac{\partial F}{\partial u}(u_{j+1/2}^-) \right) \right) \quad (6)$$

► Approximate derivatives (TVD reconstruction) with limiter ϕ

$$u_{j+1/2}^+ = u_{j+1} - \frac{\Delta x}{2} \partial_x u_{j+1} = u_{j+1} - \frac{1}{2} \phi \left(\frac{u_{j+1} - u_j}{u_{j+2} - u_{j+1}} \right) (u_{j+2} - u_{j+1}) \quad (7)$$

$$u_{j+1/2}^- = u_j + \frac{\Delta x}{2} \partial_x u_j = u_j + \frac{1}{2} \phi \left(\frac{u_j - u_{j-1}}{u_{j+1} - u_j} \right) (u_{j+1} - u_j) \quad (8)$$



expressions from: en.wikipedia.org/wiki/Flux_limiter - 2019.07.10 - 16:30

- Central difference approximation of diffusion flux:

$$\begin{aligned} P_{j+1/2}(t) = & \frac{1}{2} Q[t, x_j, u_j, (u_{j+1} - u_j)/\Delta x] + \\ & + \frac{1}{2} Q[t, x_{j+1}, u_{j+1}, (u_{j+1} - u_j)/\Delta x] \end{aligned} \quad (9)$$

- Diffusion flux for \dot{u}_j is based on the 3-point stencil $\{u_{j-1}, u_j, u_{j+1}\}$
- Analogous central difference approximation of source flux:

$$S_{j+1/2}(t) = \frac{1}{2} S(t, x_j) + \frac{1}{2} S(t, x_{j+1}) \quad (10)$$

- ▶ Method of Lines (MoL) finite volume PDE discretization \Rightarrow sparse (banded) ODE system
- ▶ Total RHS flux for \dot{u}_j is based on the 5-point stencil $\{u_{j-2}, u_{j-1}, u_j, u_{j+1}, u_{j+2}\}$
- ▶ Approximate derivatives are reconstructed from the computed cell averages using ϕ -Limiter
- ▶ Only additional information (apart from PDE and grid): spectral radius of jacobian $\rho = \max |\lambda_i(\partial F / \partial u)|$ to approximate local speeds

Godunov first order upwind scheme

$$\begin{aligned} \frac{du_j}{dt} = & -\frac{F[t, u_{j+1}] - F[t, u_j]}{\Delta x} \\ & + \frac{Q[t, x_{j+1}, u_{j+1}, (u_{j+1} - u_j)/\Delta x] - Q[t, x_j, u_j, (u_j - u_{j-1})/\Delta x]}{\Delta x} \\ & + \frac{S[t, x_{j+1}] - S[t, x_j]}{\Delta x} \end{aligned} \quad (11)$$

- ▶ Applicable only to convection–diffusion eqs. with $\partial F / \partial u < 0 \forall t, u$
 - Linear Advection eq. with negative velocity
 - FRG LPA flow eqs.
 - ...

Classical examples

- ▶ Linear Advection eq.:

$$\partial_t u(t, x) - \partial_x u(t, x) = 0, \quad u(0, x) = \begin{cases} 1 & 3 \leq x \leq 4 \\ 0 & \text{otherwise} \end{cases} \quad (\text{LA})$$

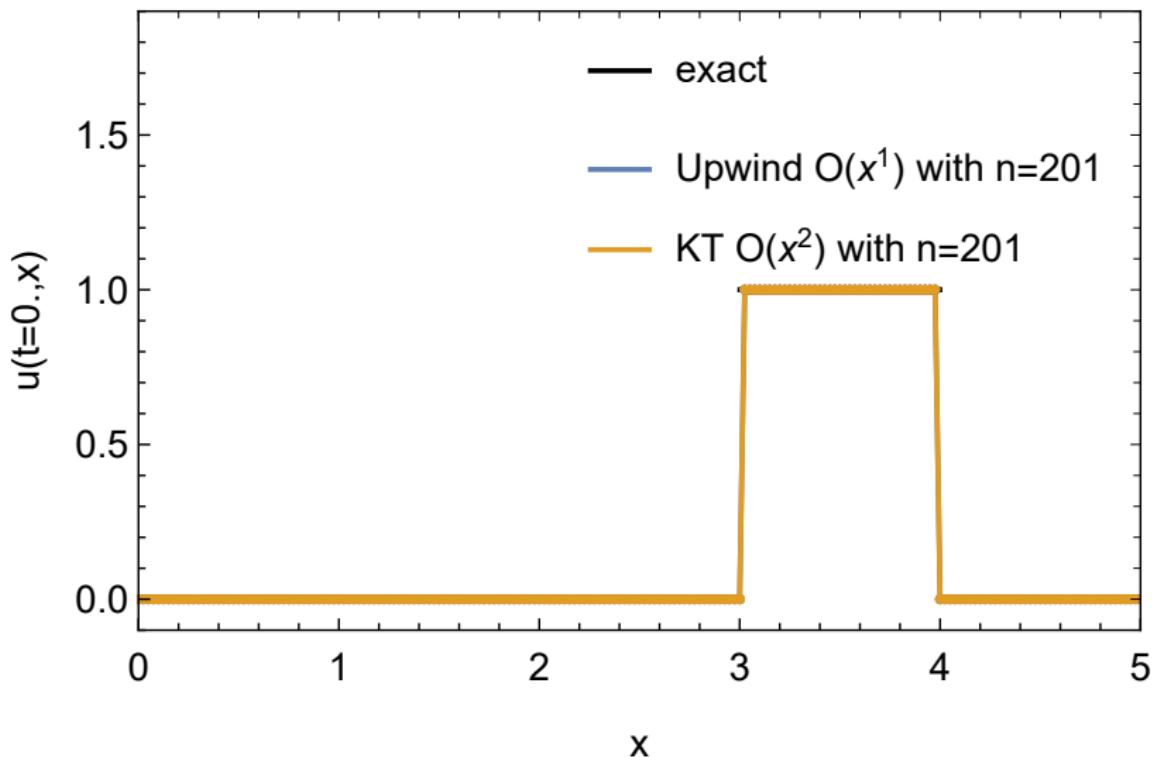
- ▶ Burgers' eq.:

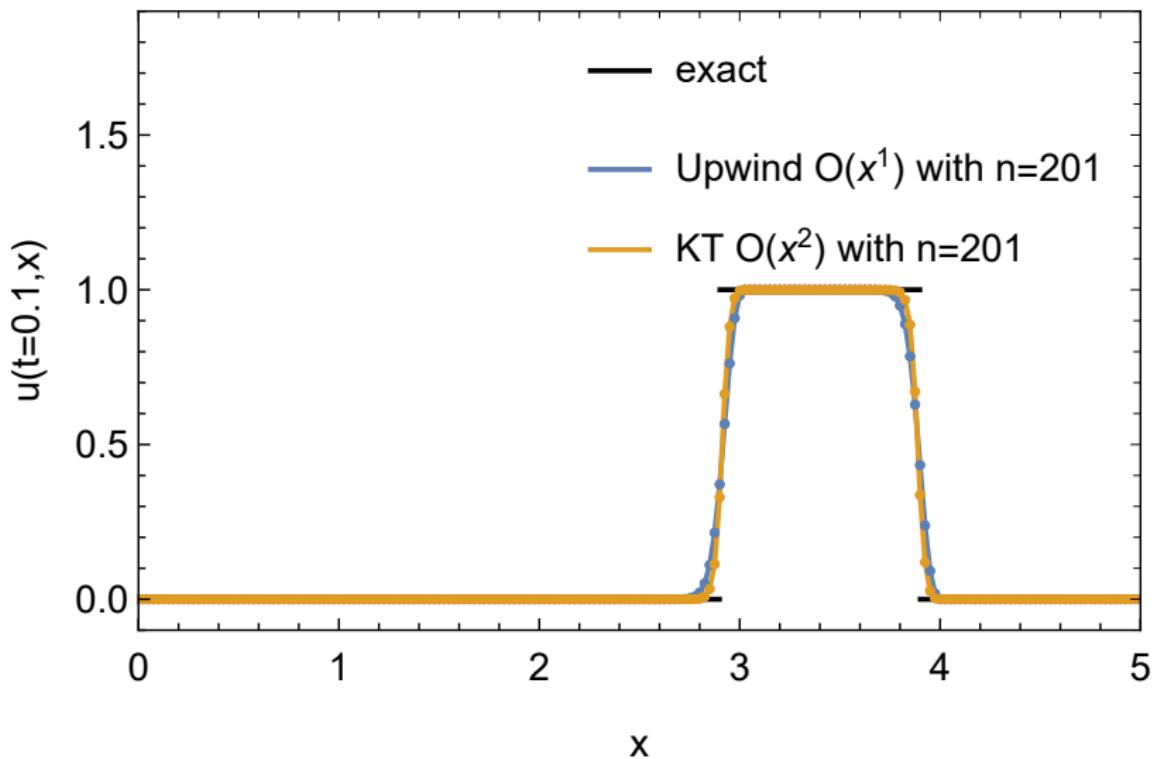
$$\partial_t u(t, x) + \partial_x \frac{u(t, x)^2}{2} = \nu \partial_x^2 u(t, x) \quad (\text{B})$$

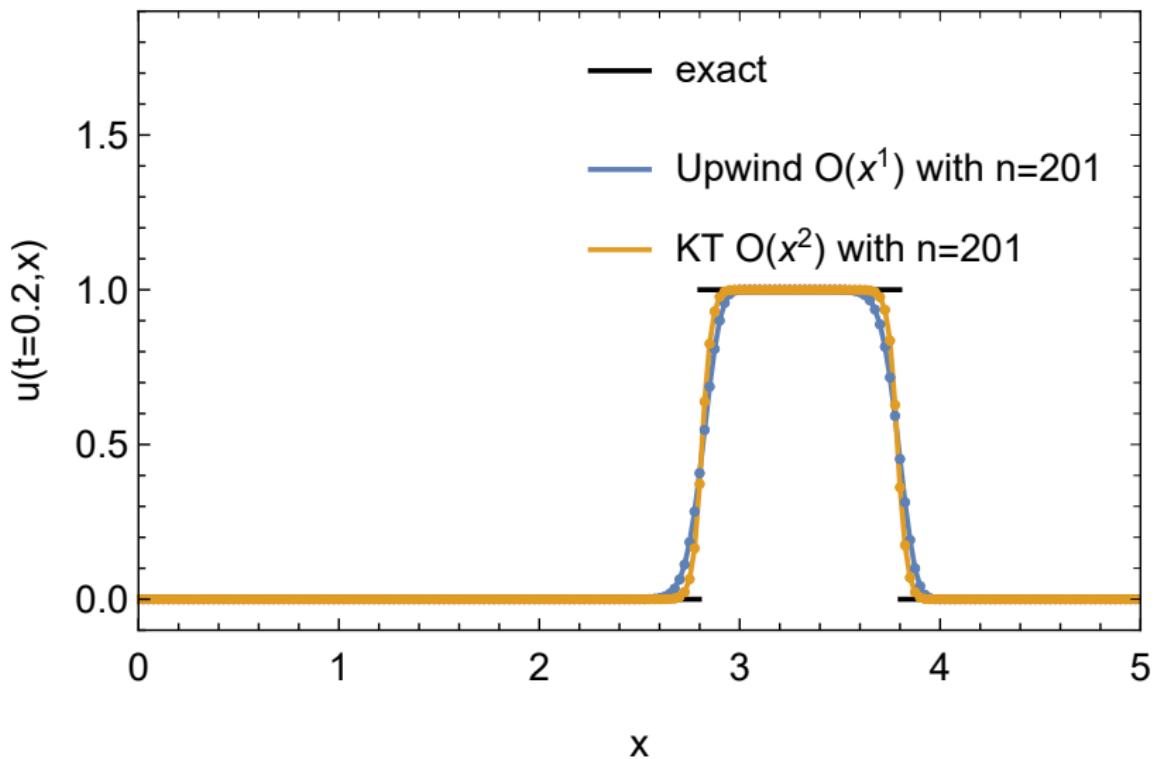
$$u(0, x) = 0.5 + \sin(x) \quad \text{and inviscid: } \nu = 0 \quad (\text{B.1})$$

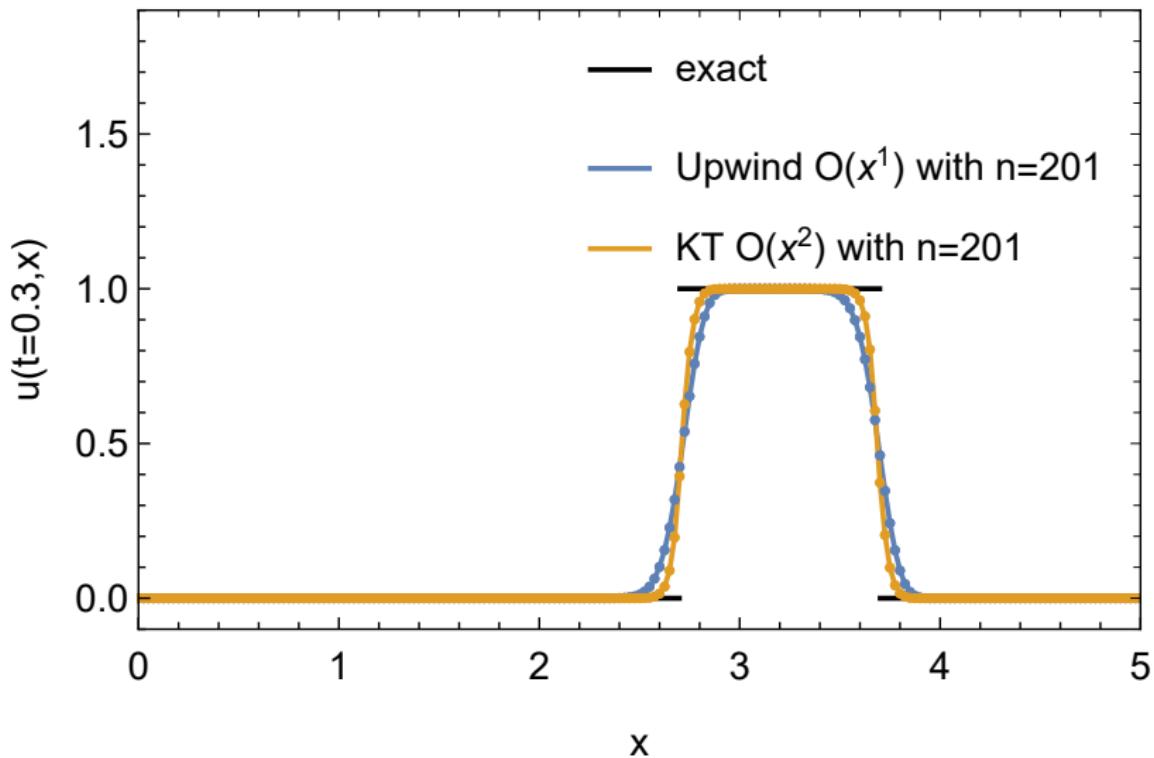
$$u(0, x) = 0.5 + \sin(x) \quad \text{and viscous: } \nu = 0.1 \quad (\text{B.2})$$

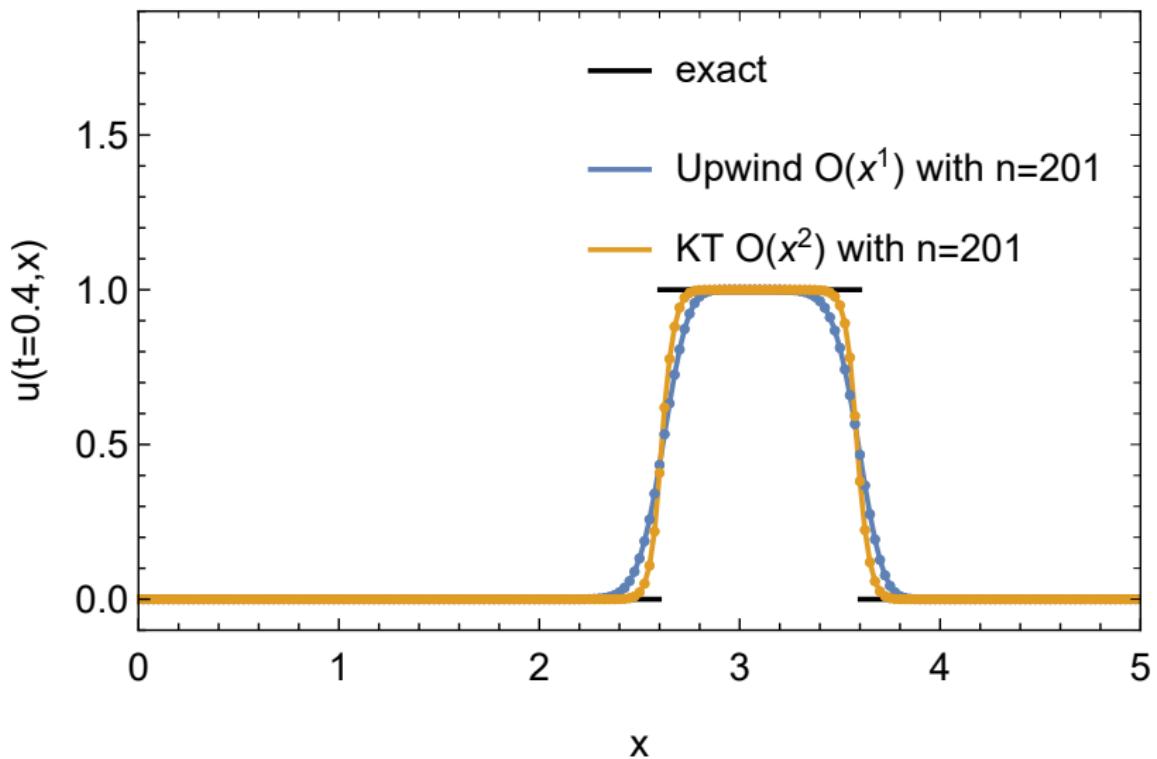
$$u(0, x) = \begin{cases} 1 & x \leq 2 \\ 0 & \text{otherwise} \end{cases} \quad \text{and viscous: } \nu = 0.01 \quad (\text{B.3})$$

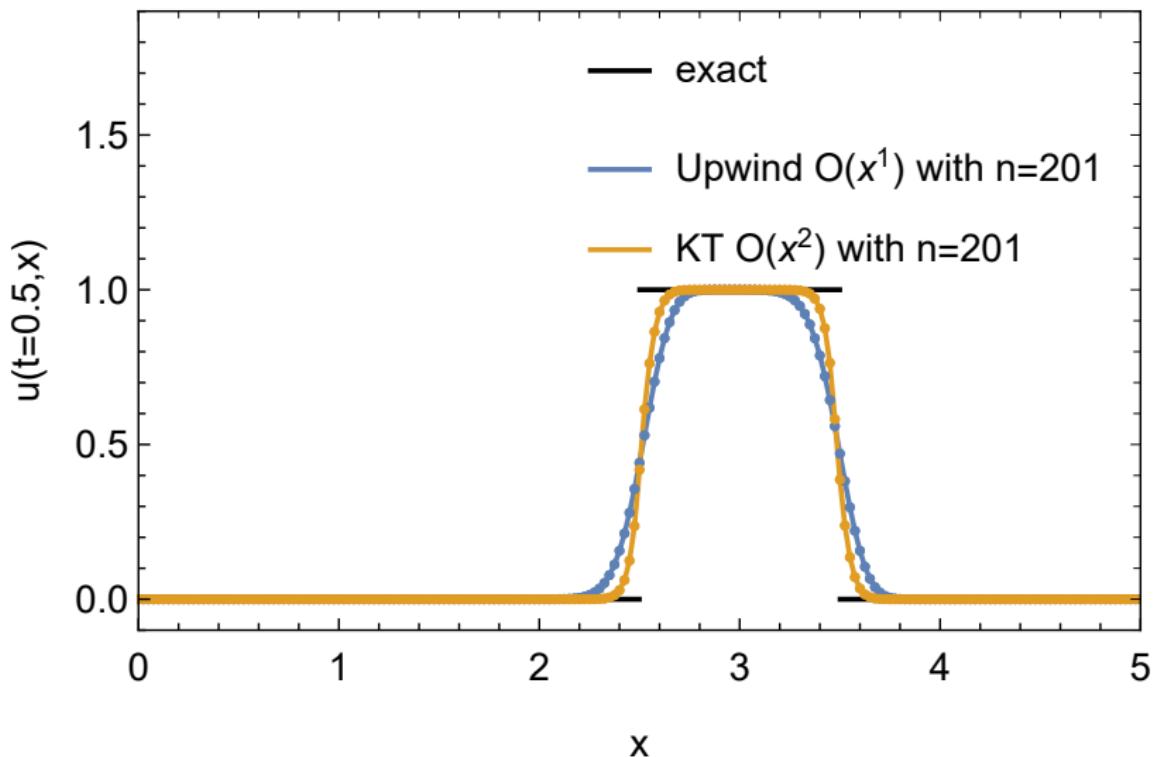


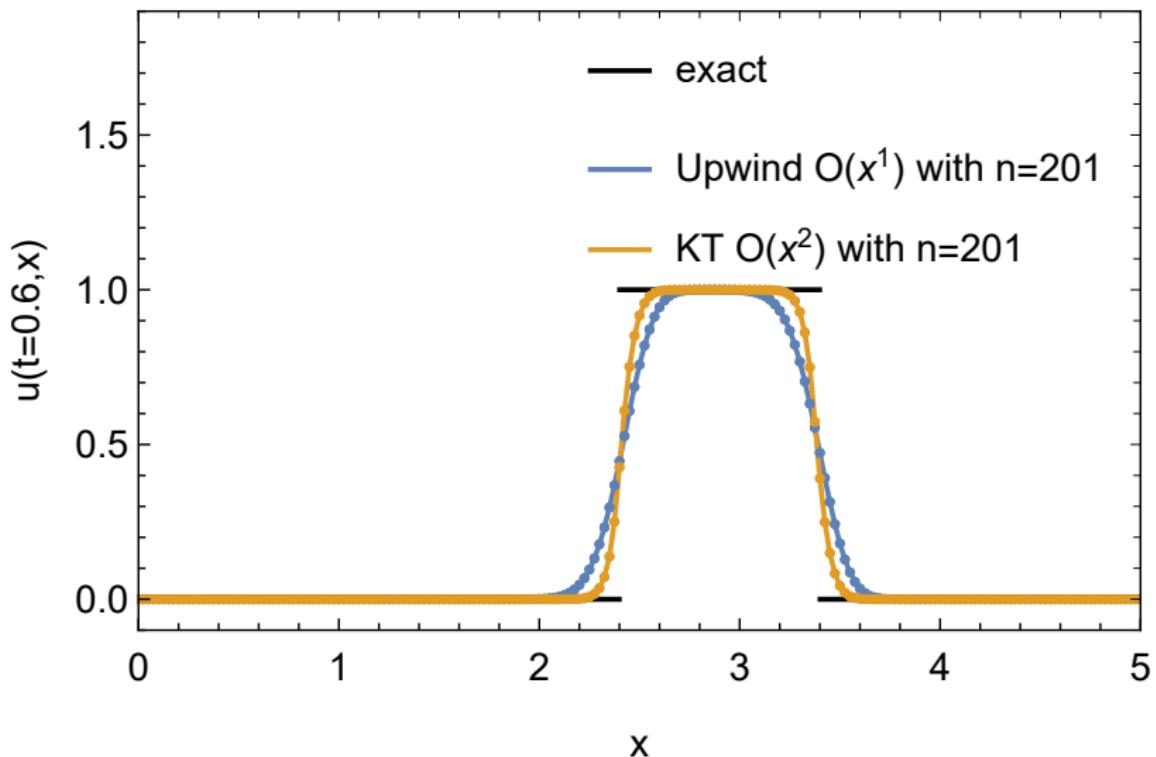


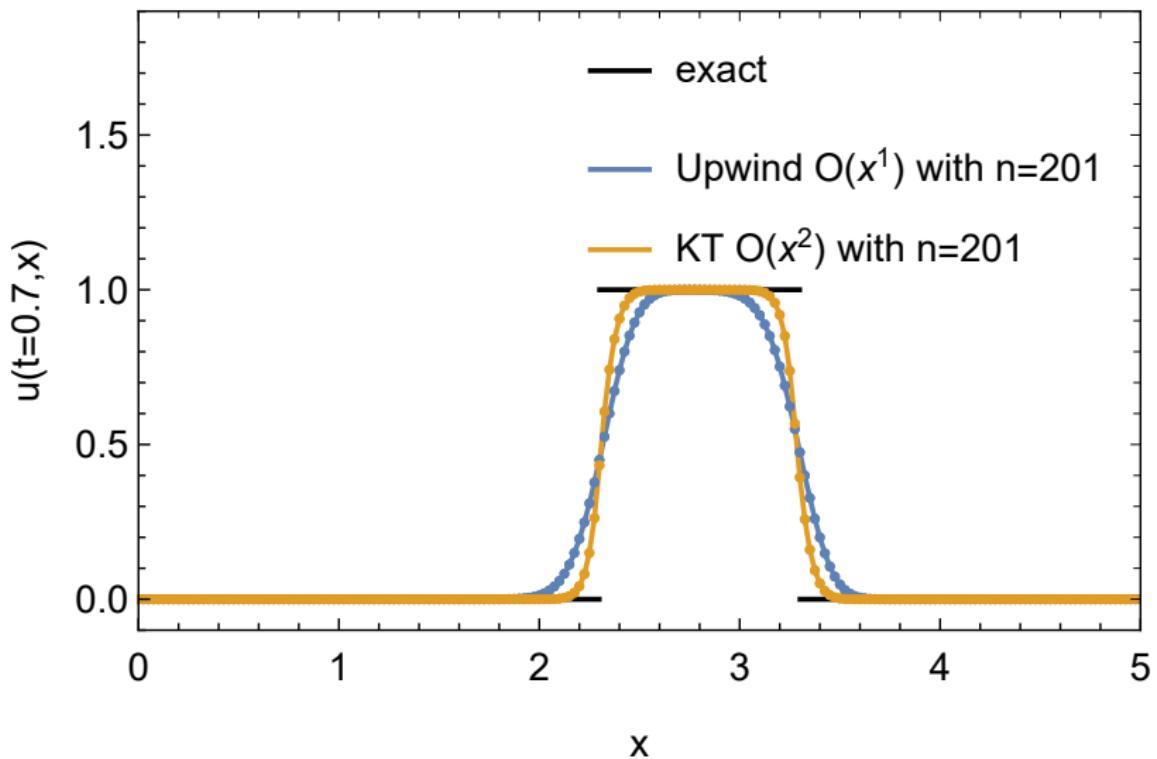


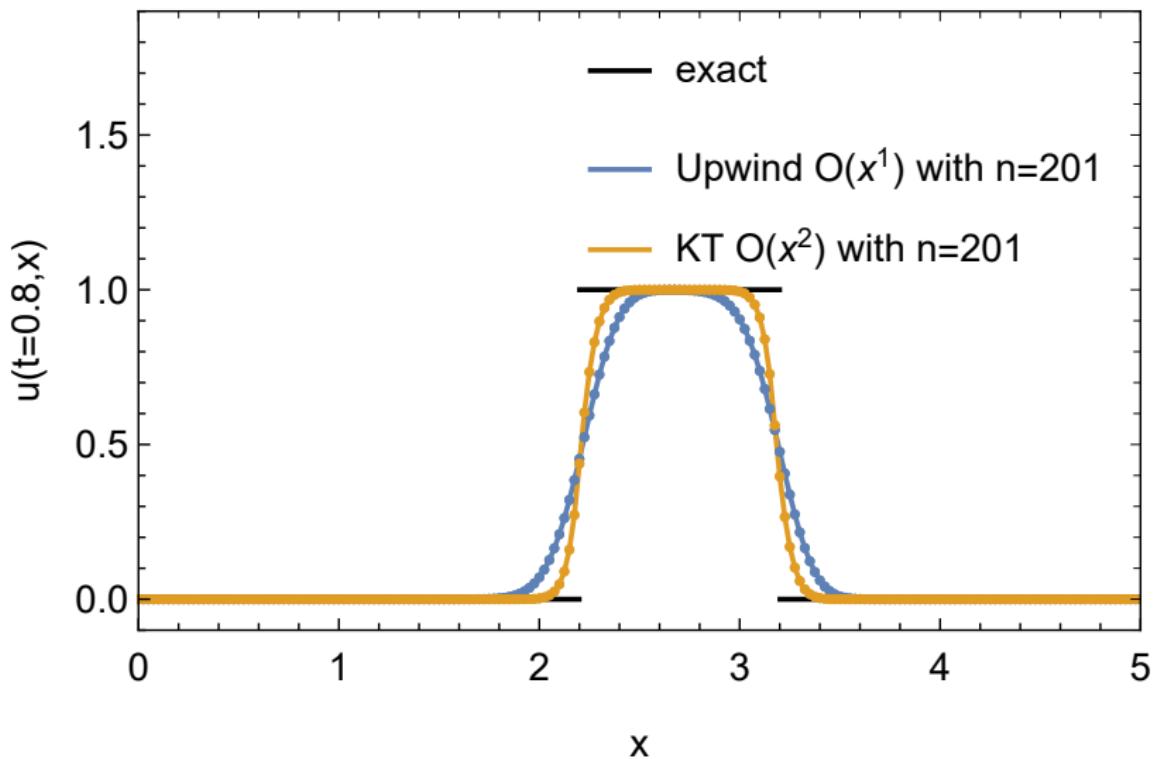


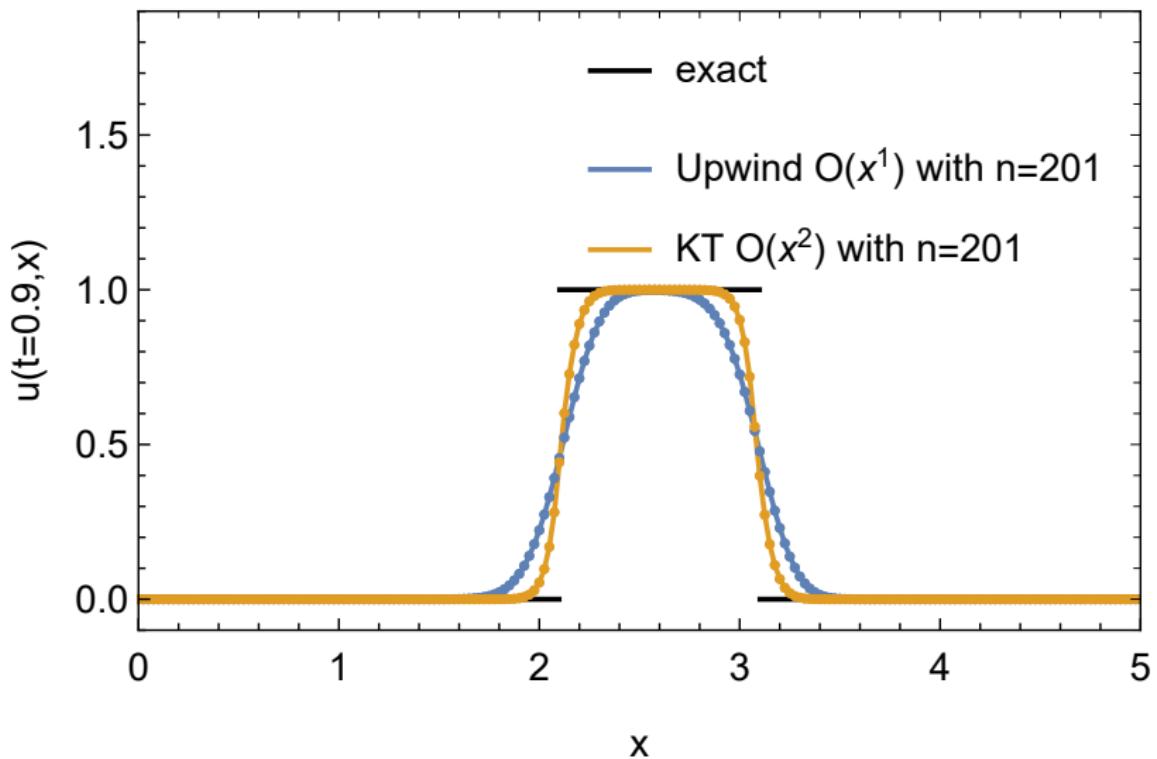


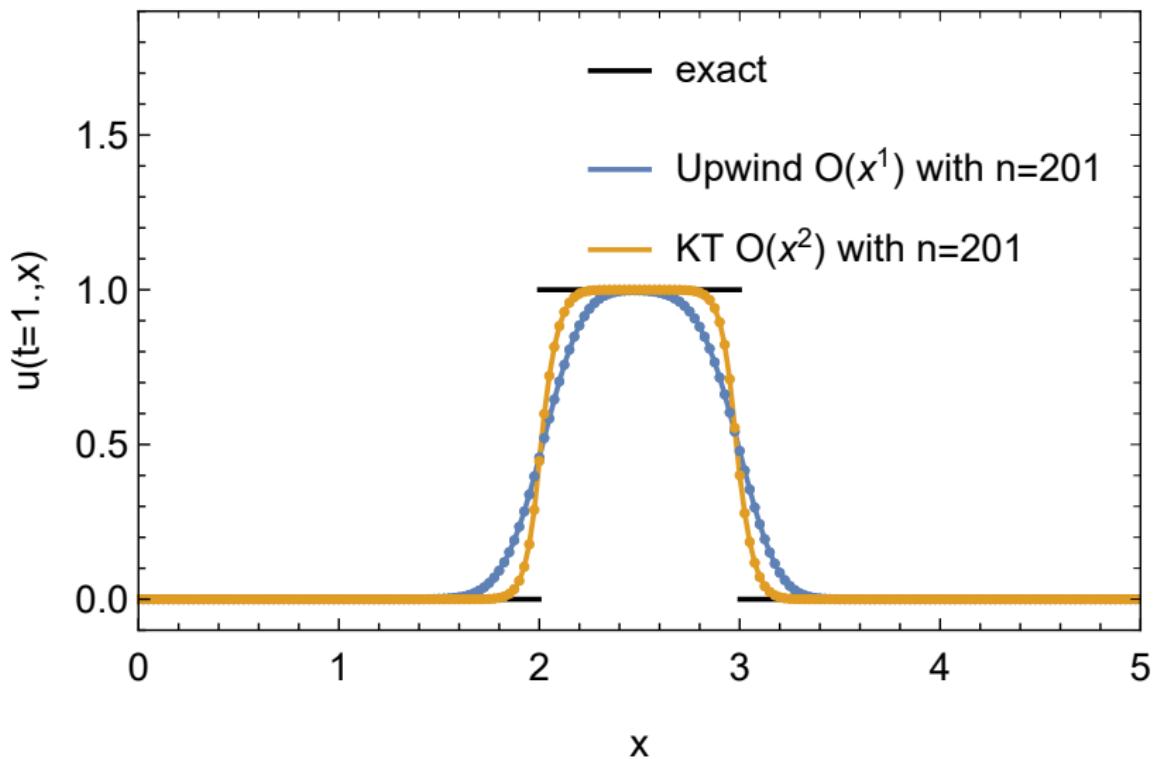


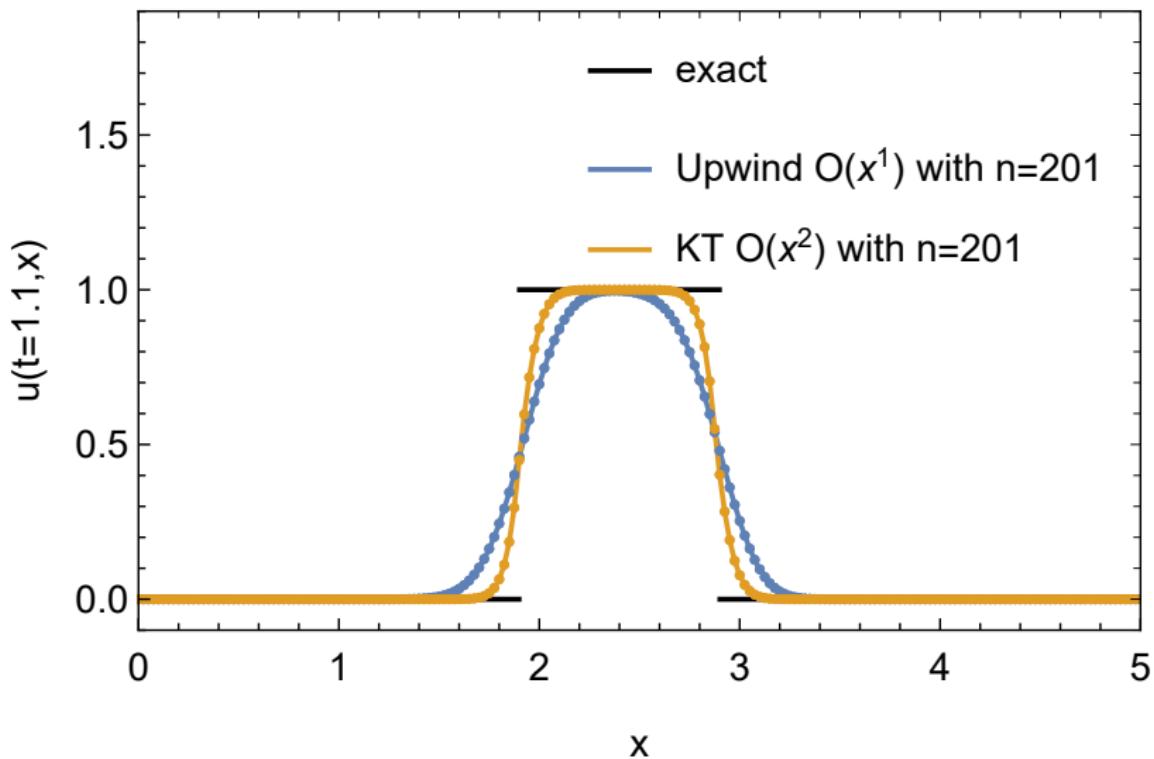


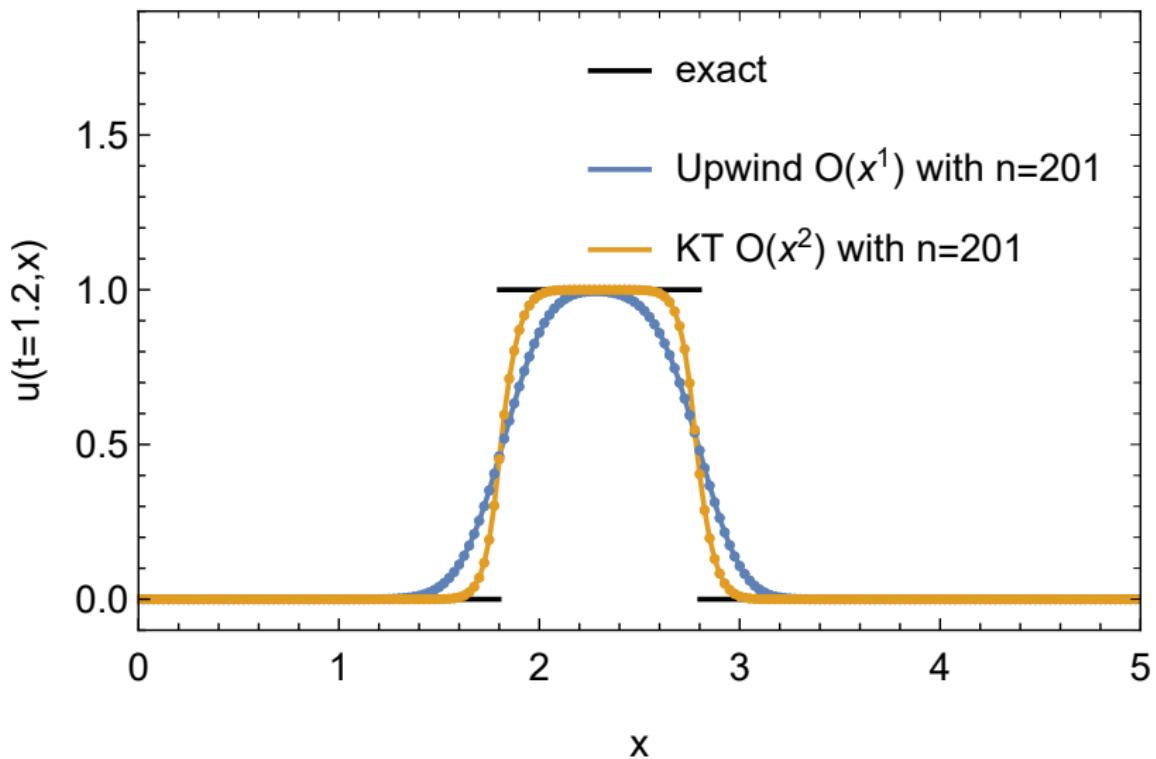


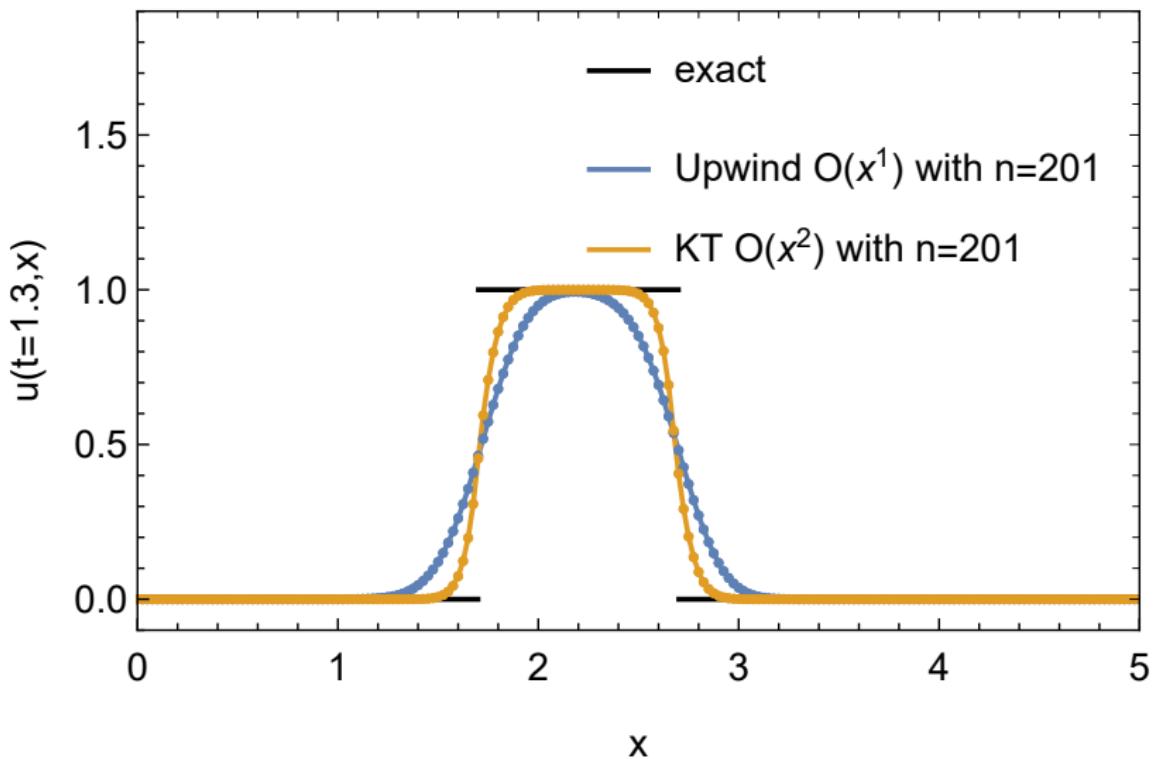


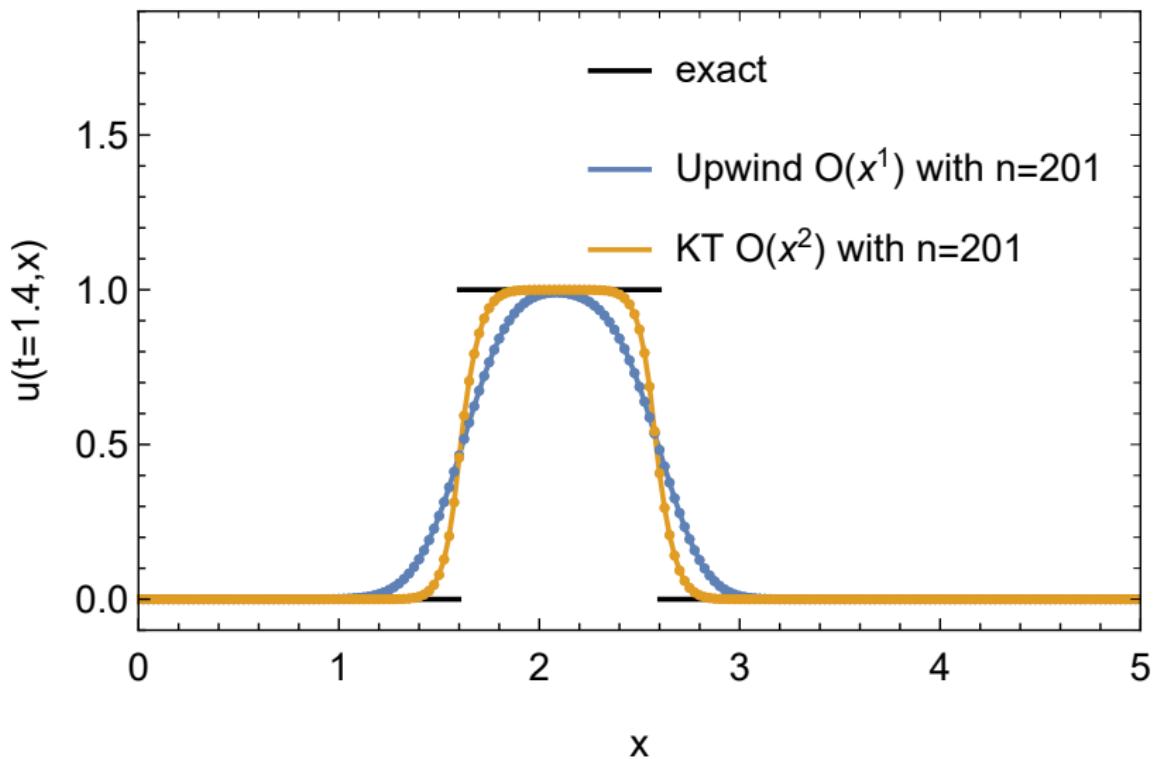


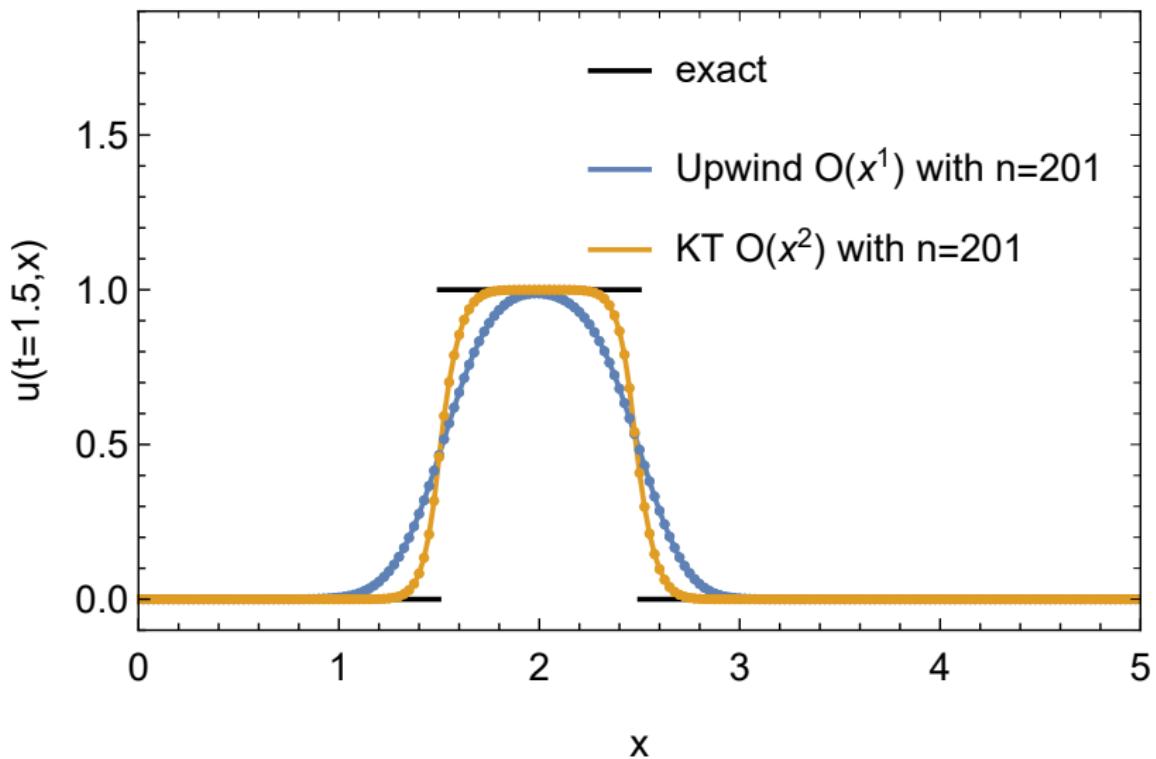


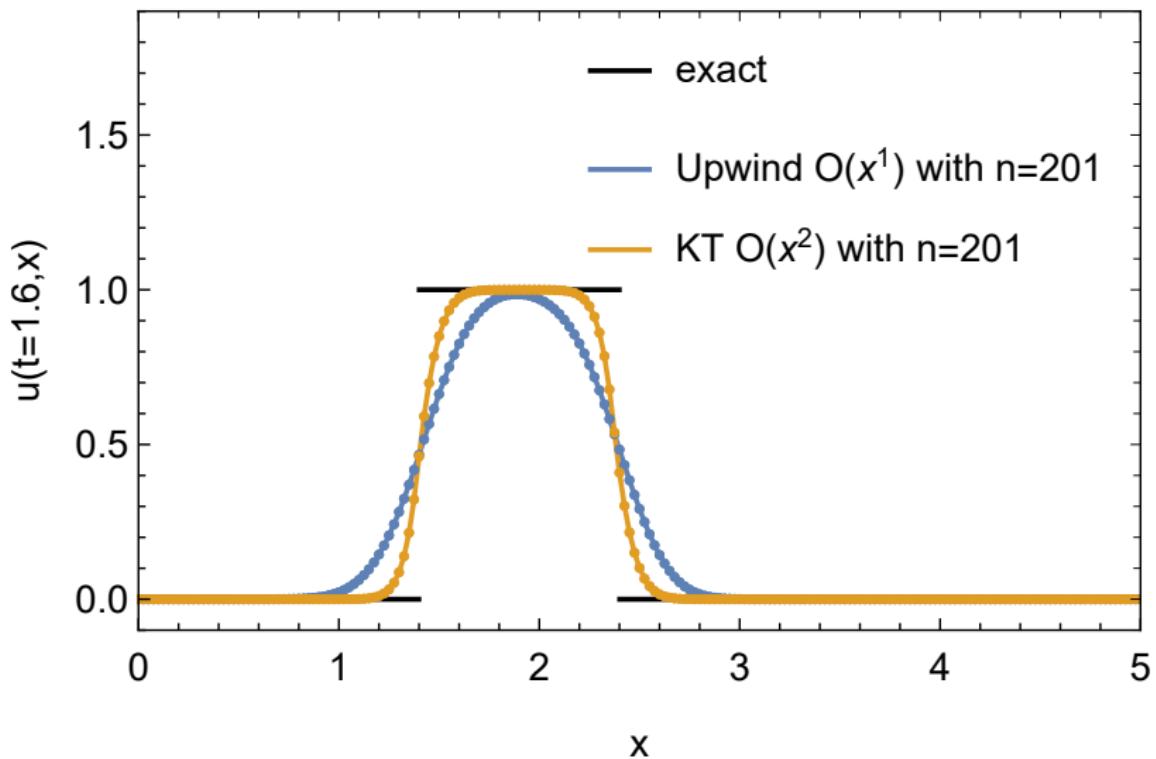


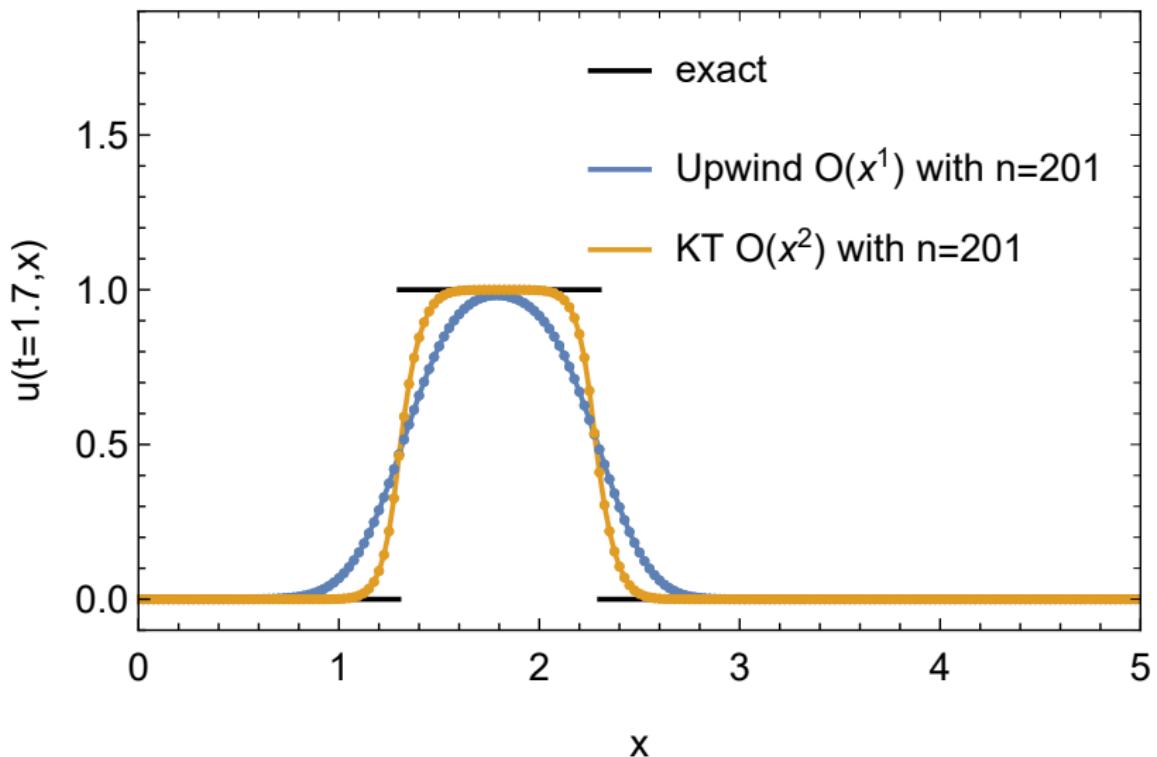


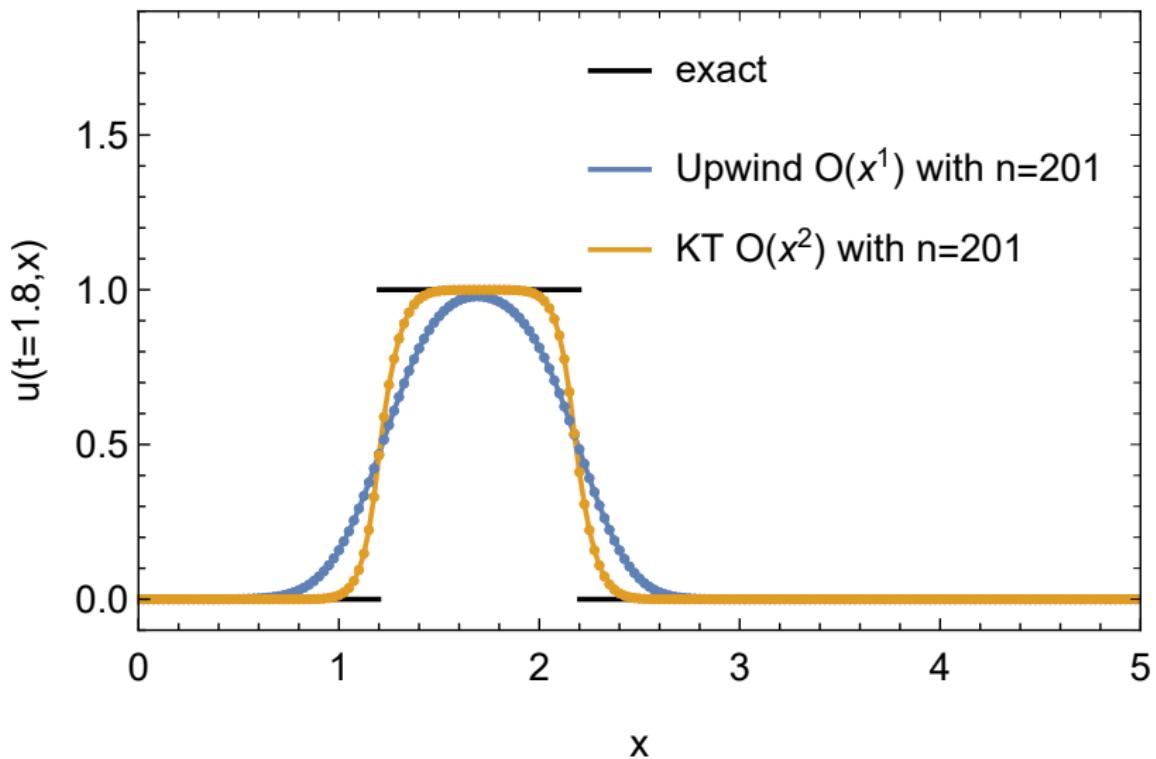


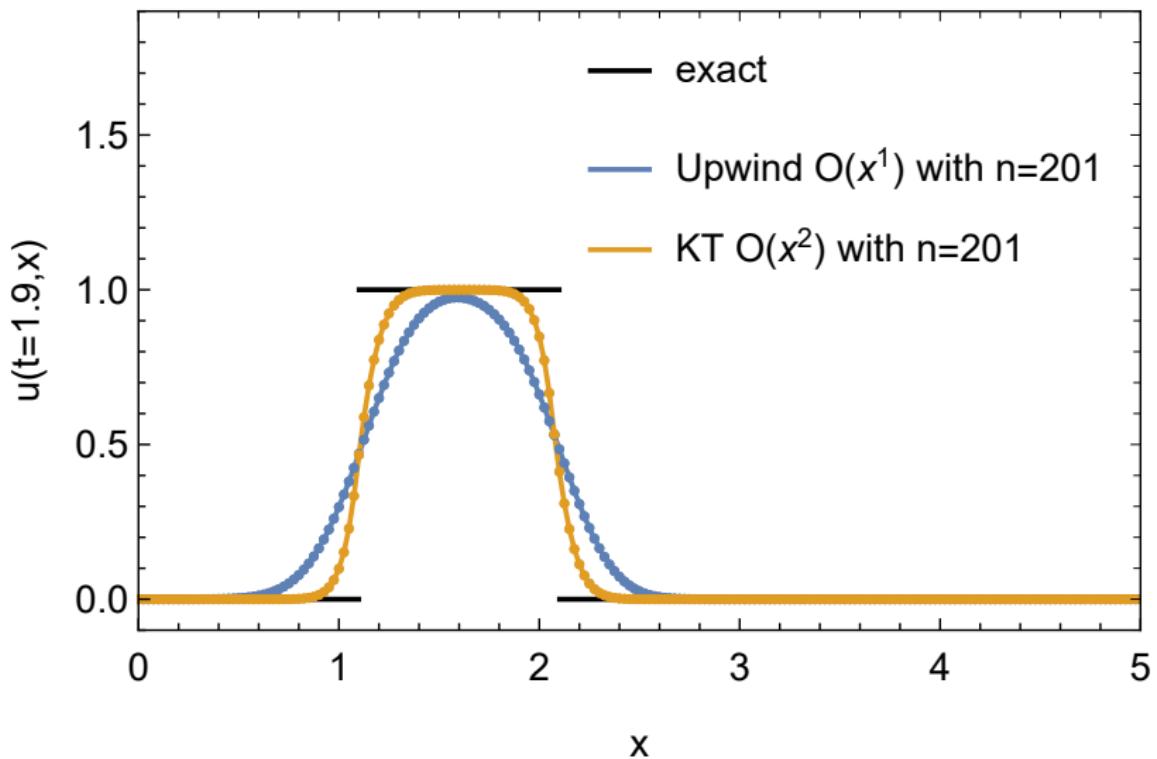


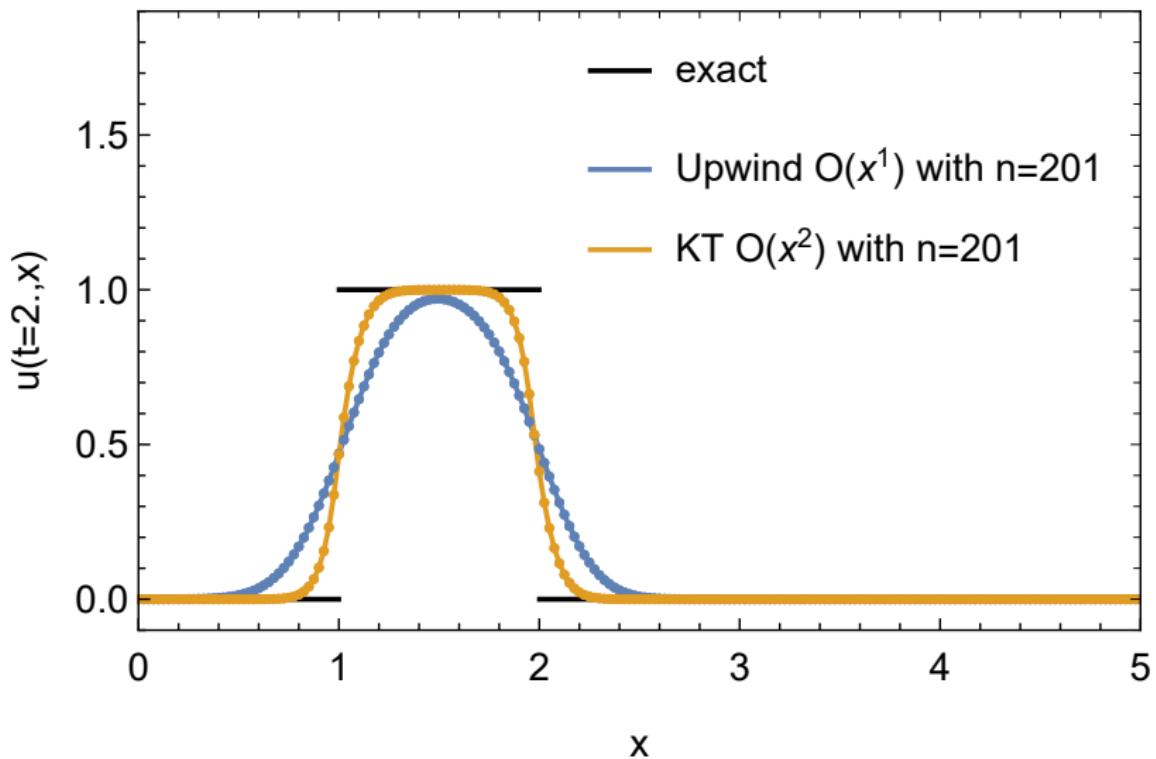


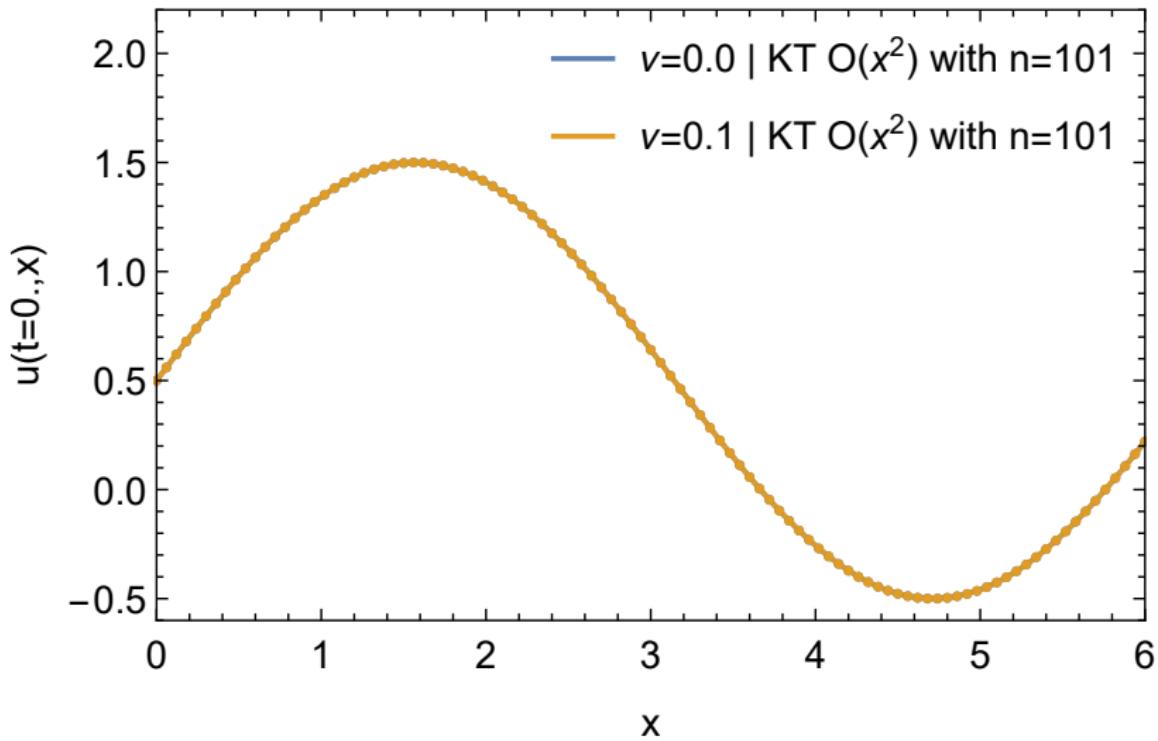


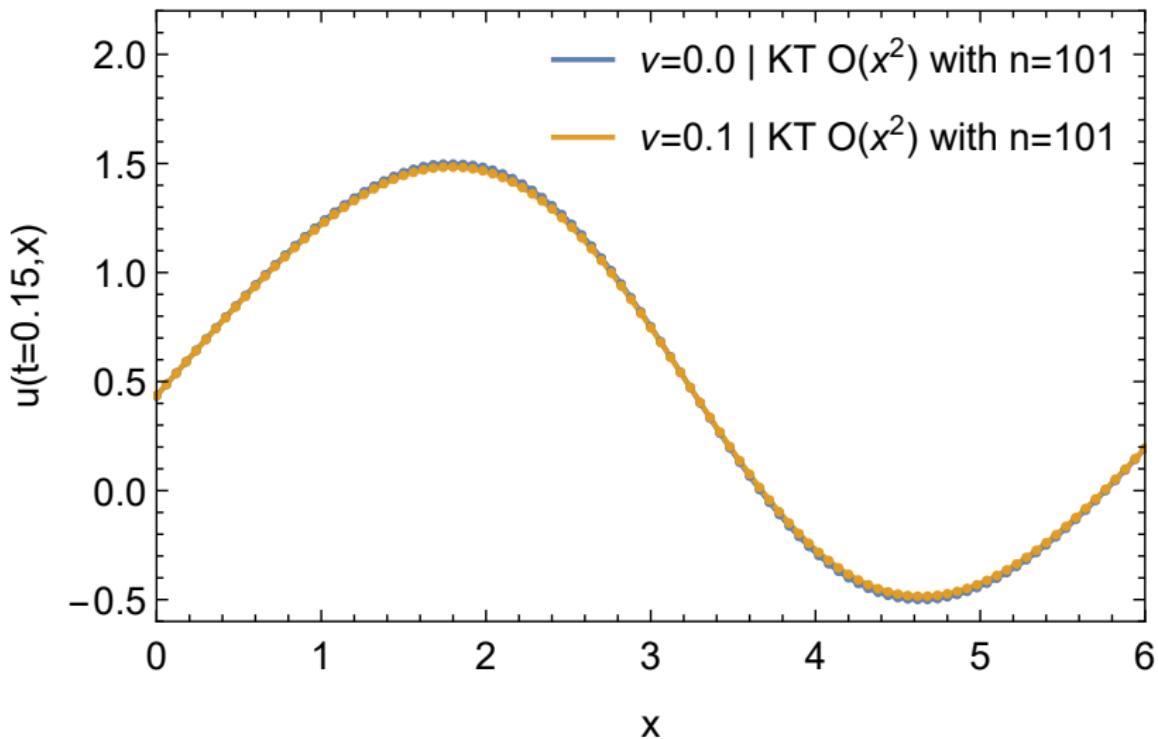


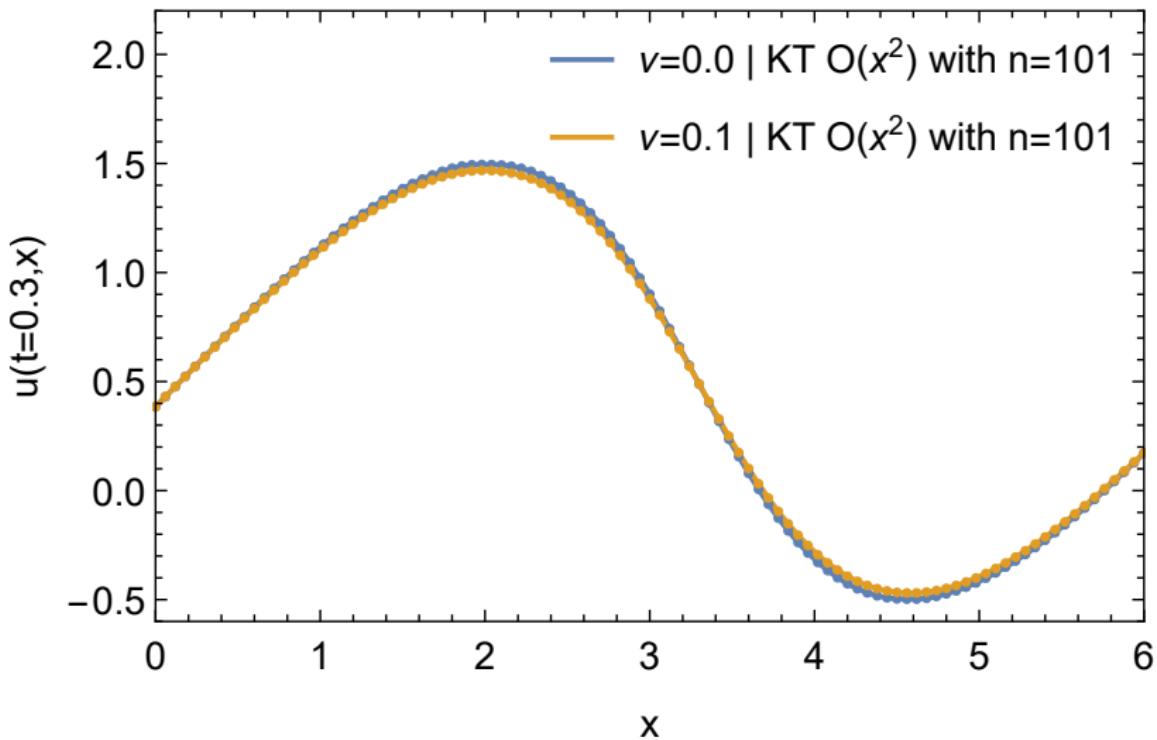


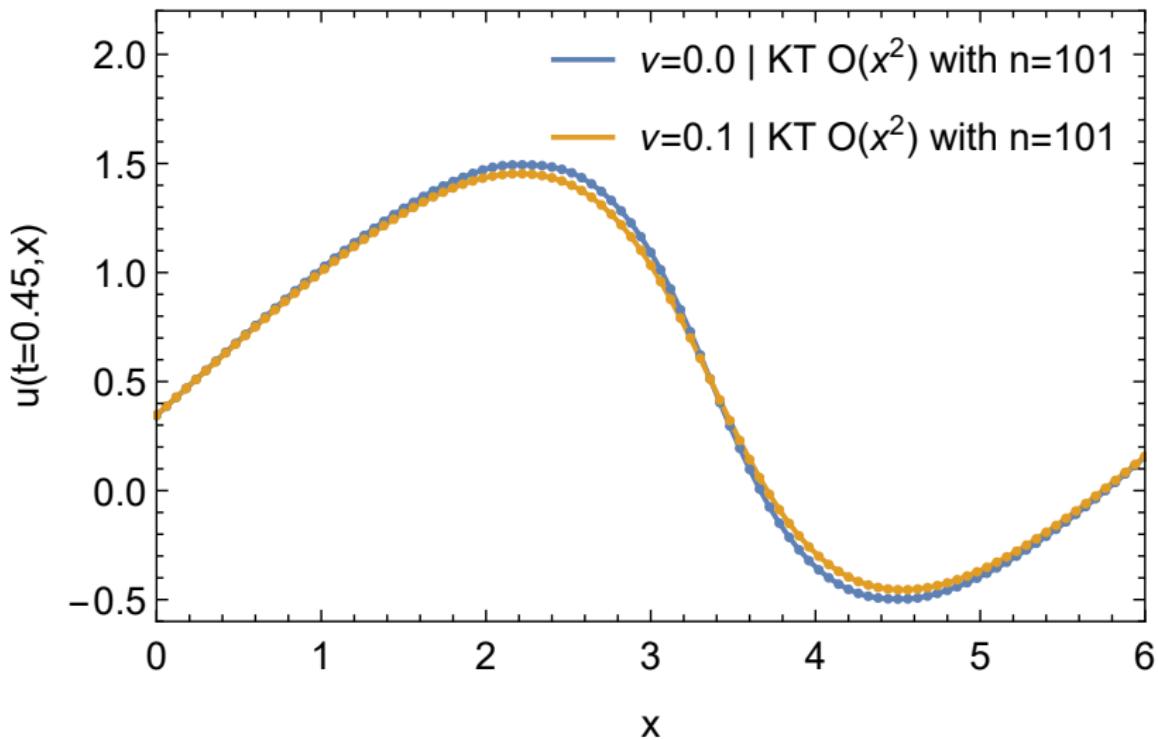


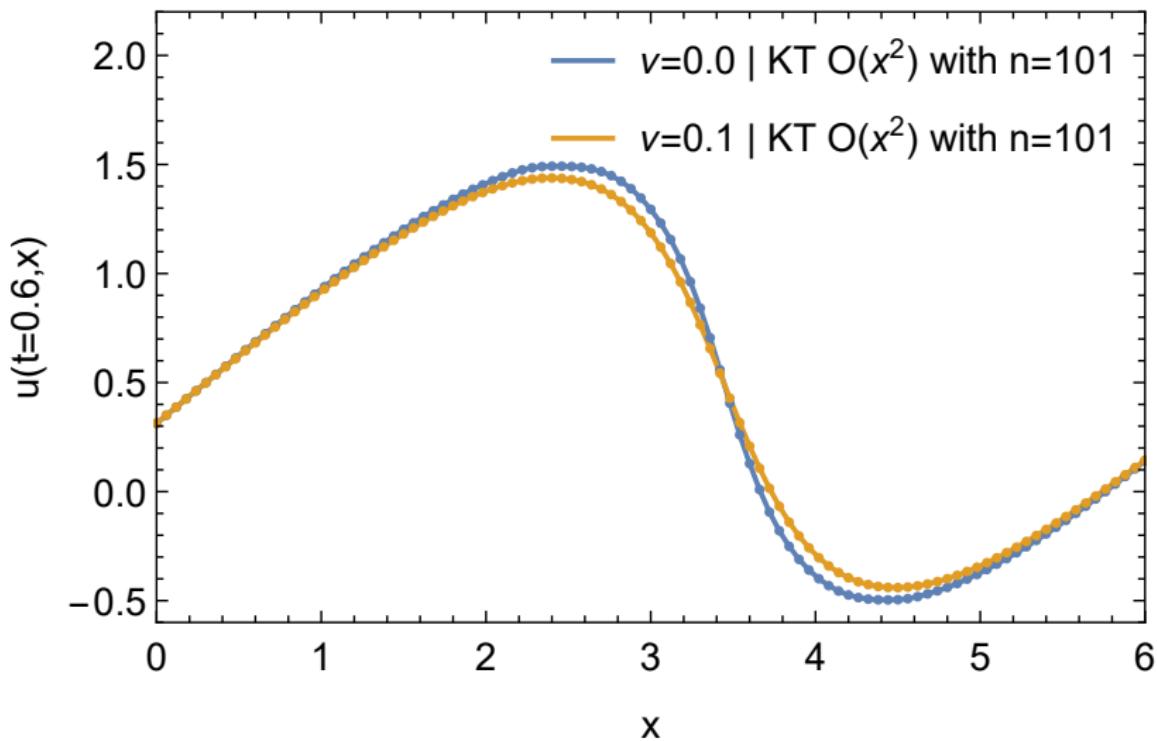


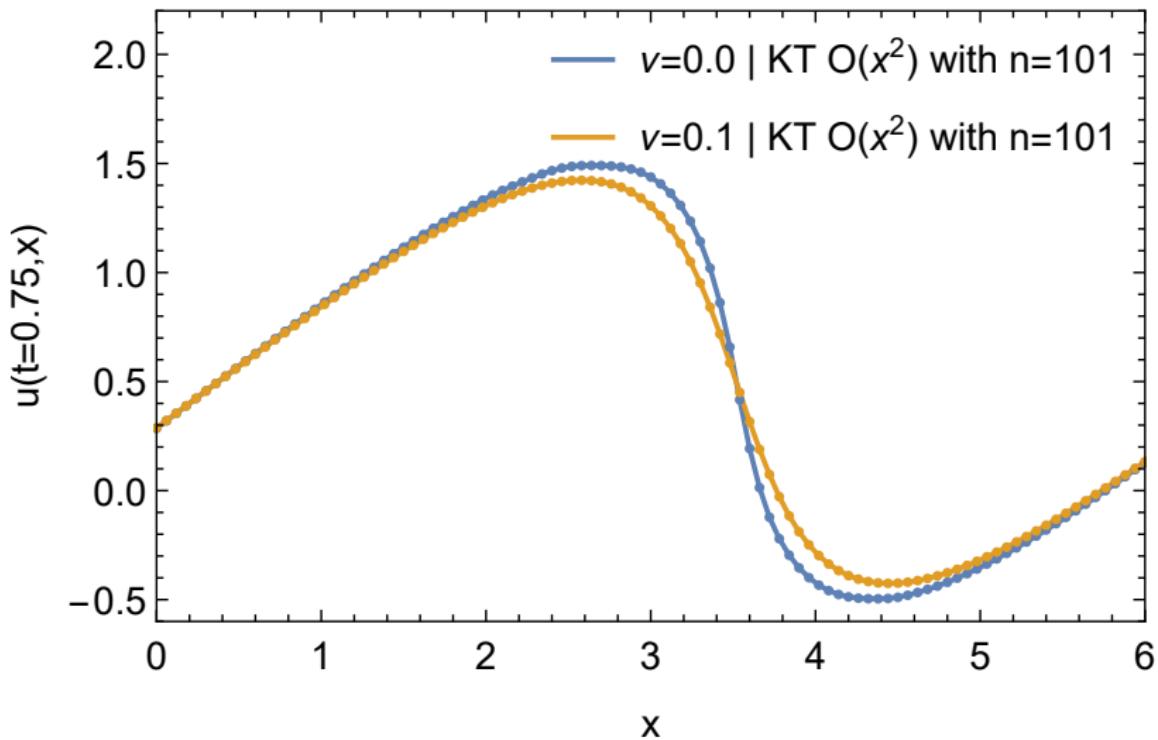


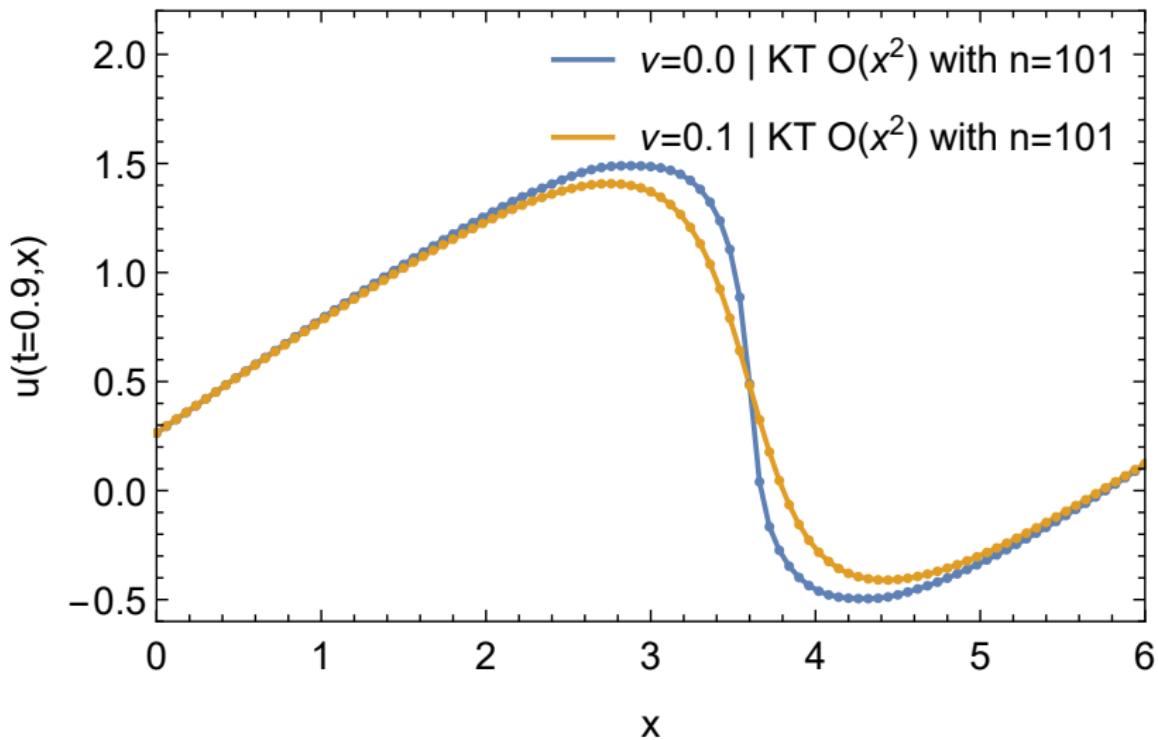


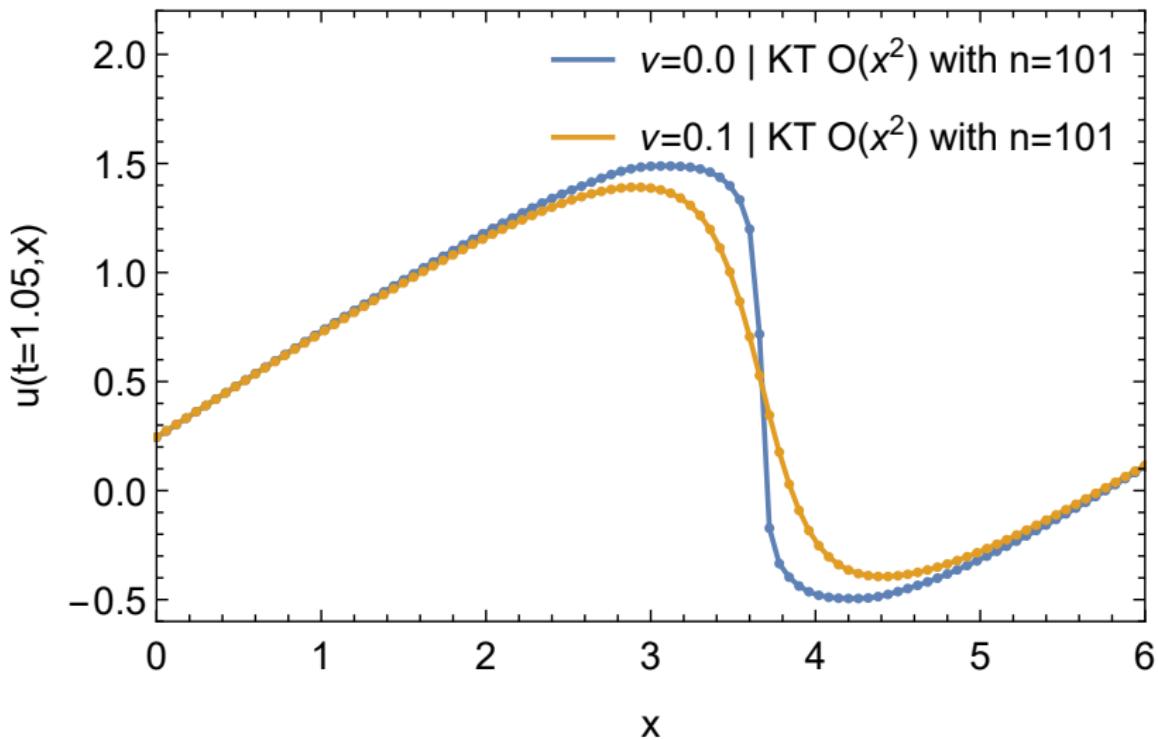


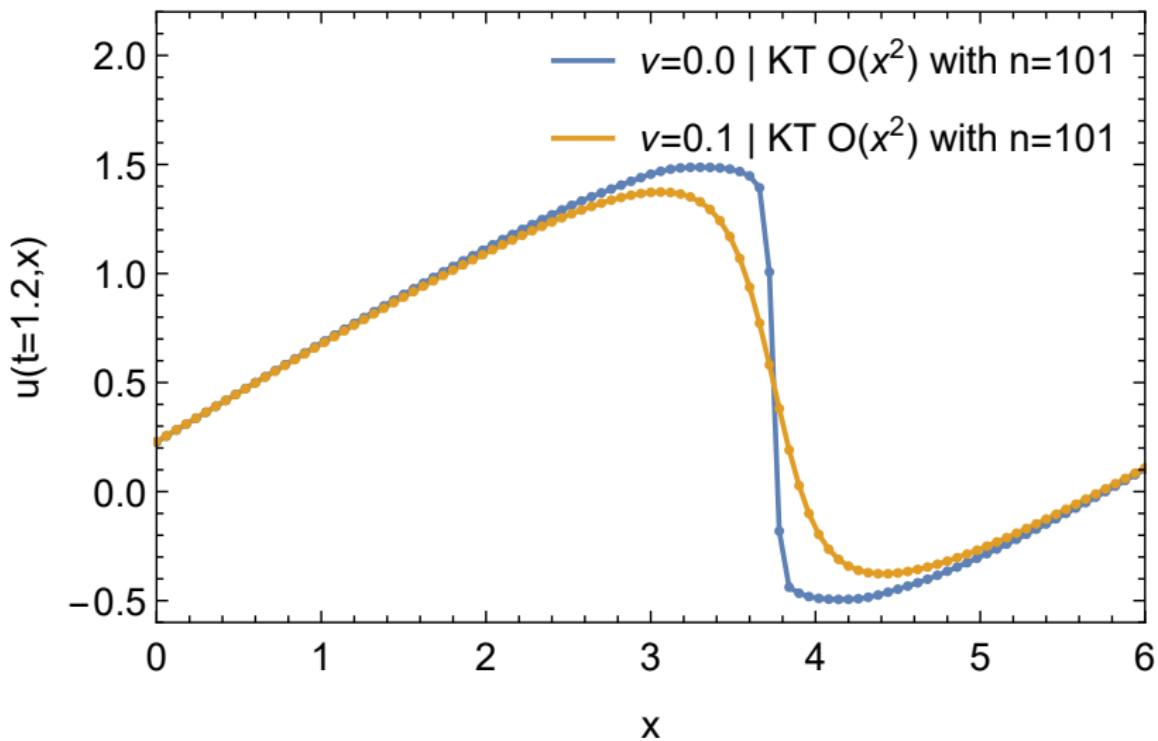


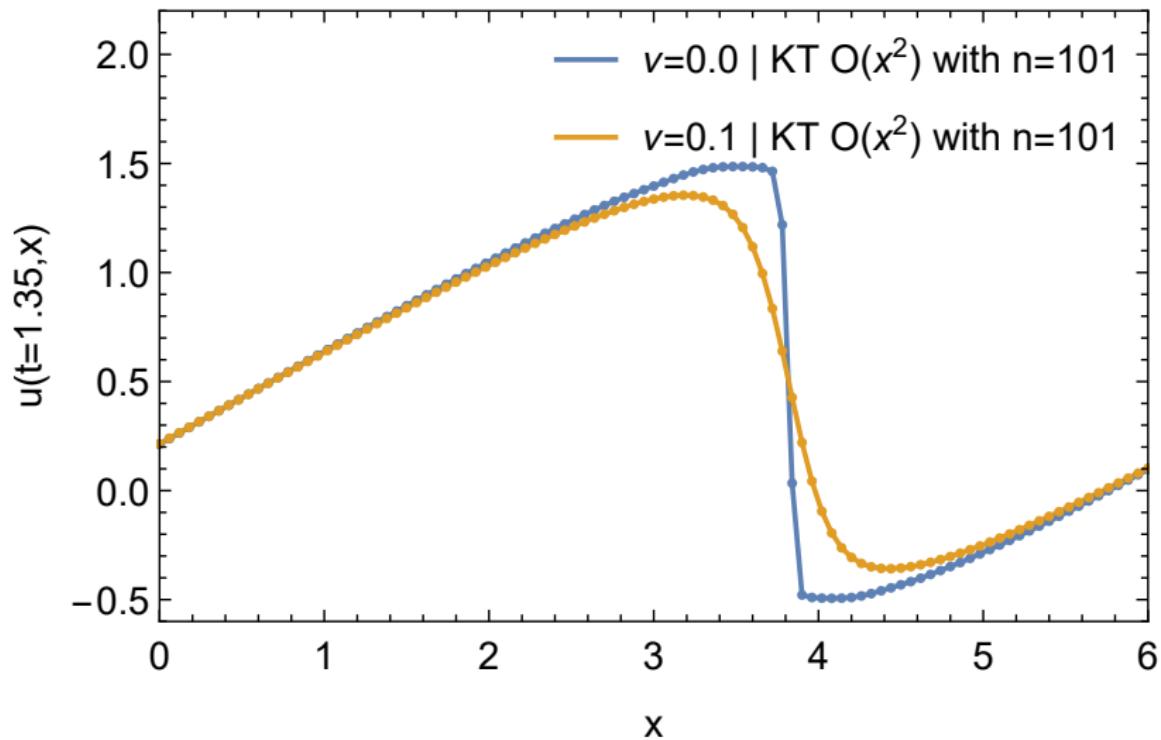


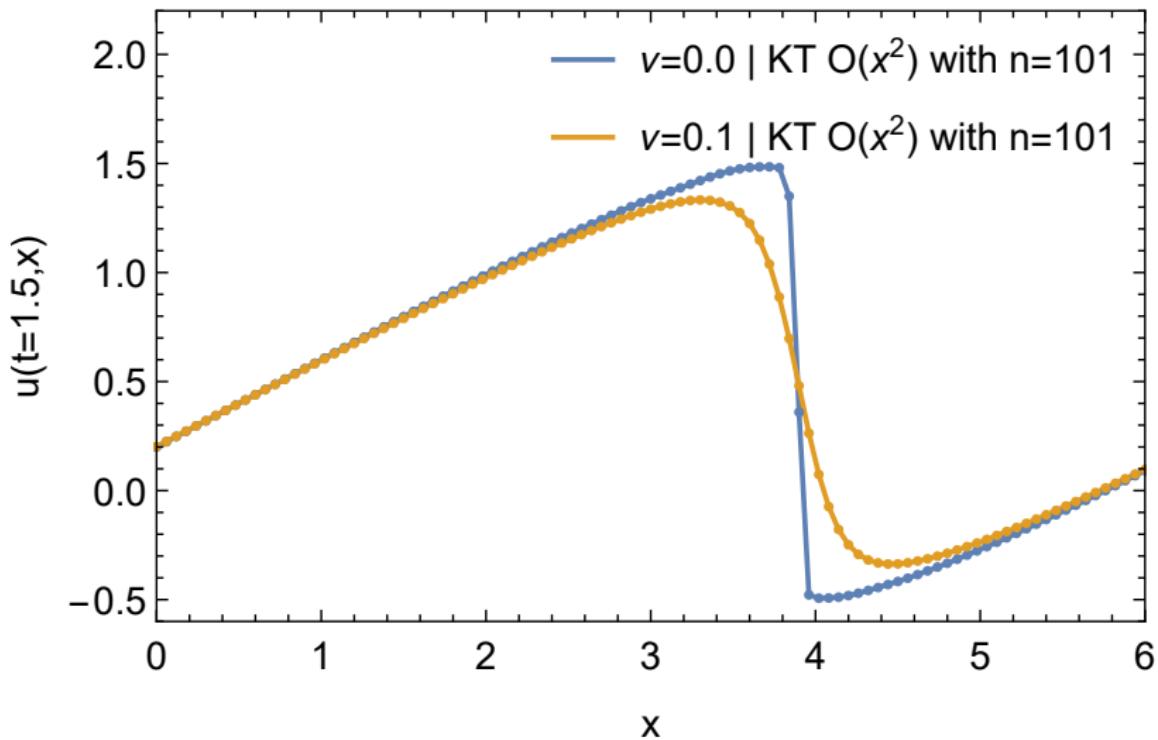


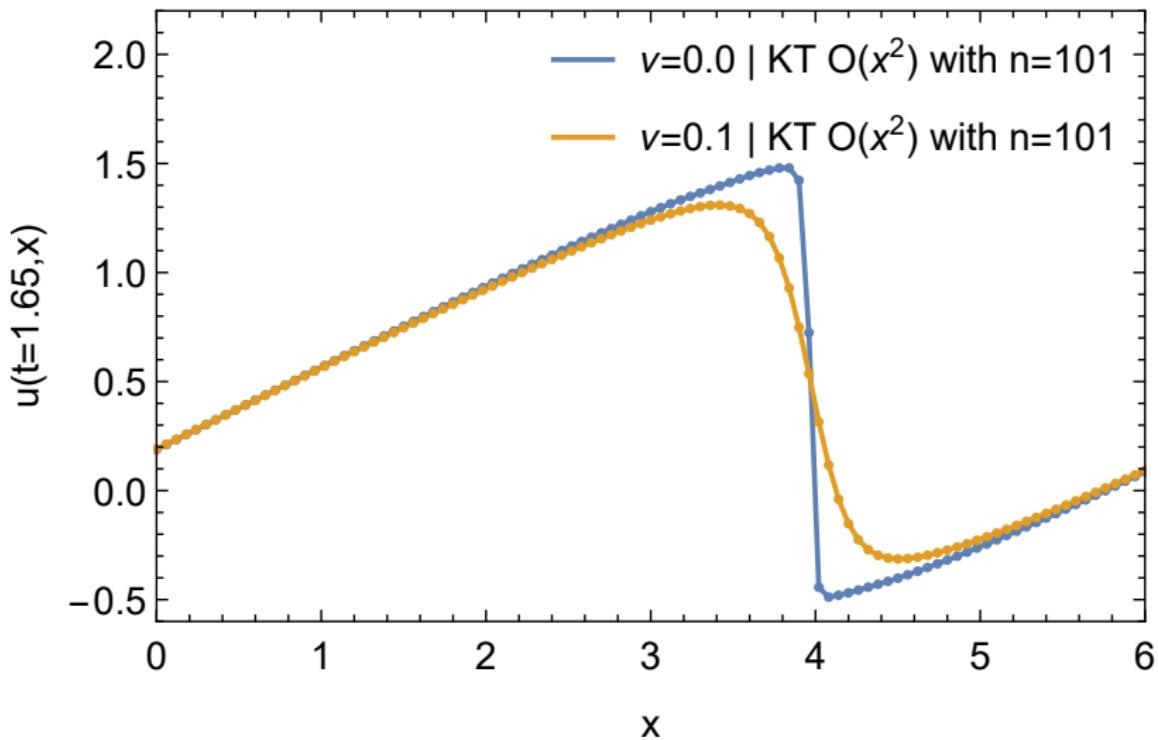


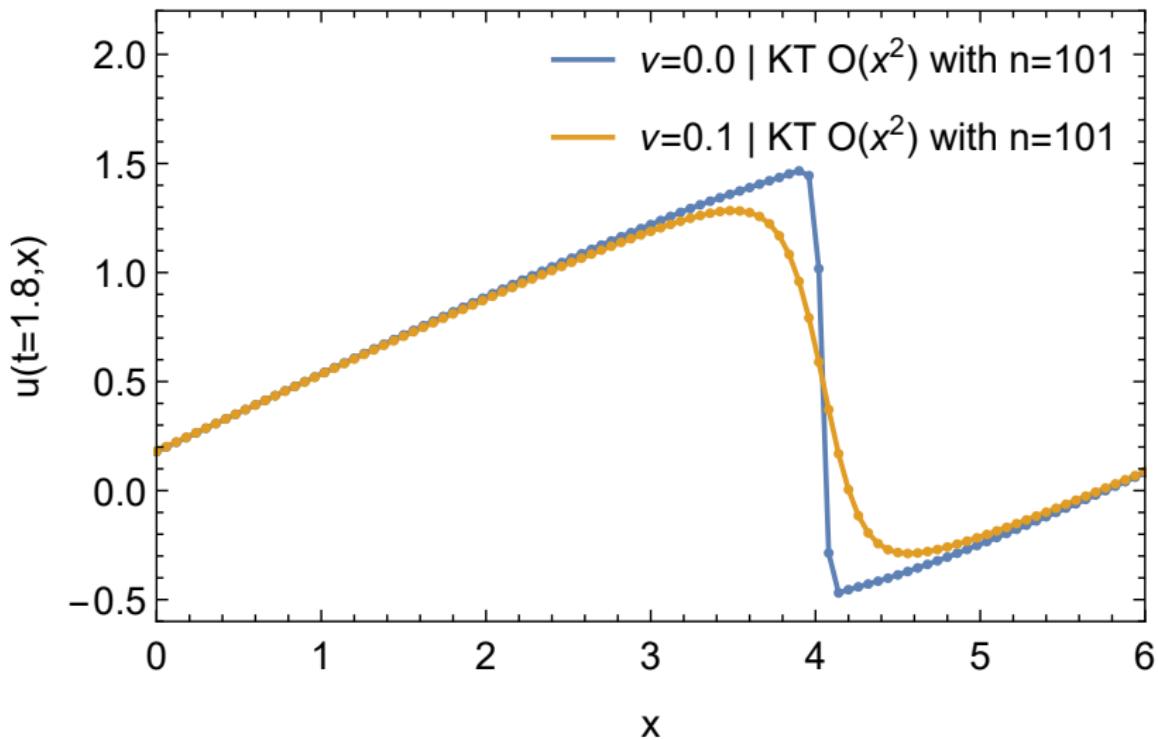


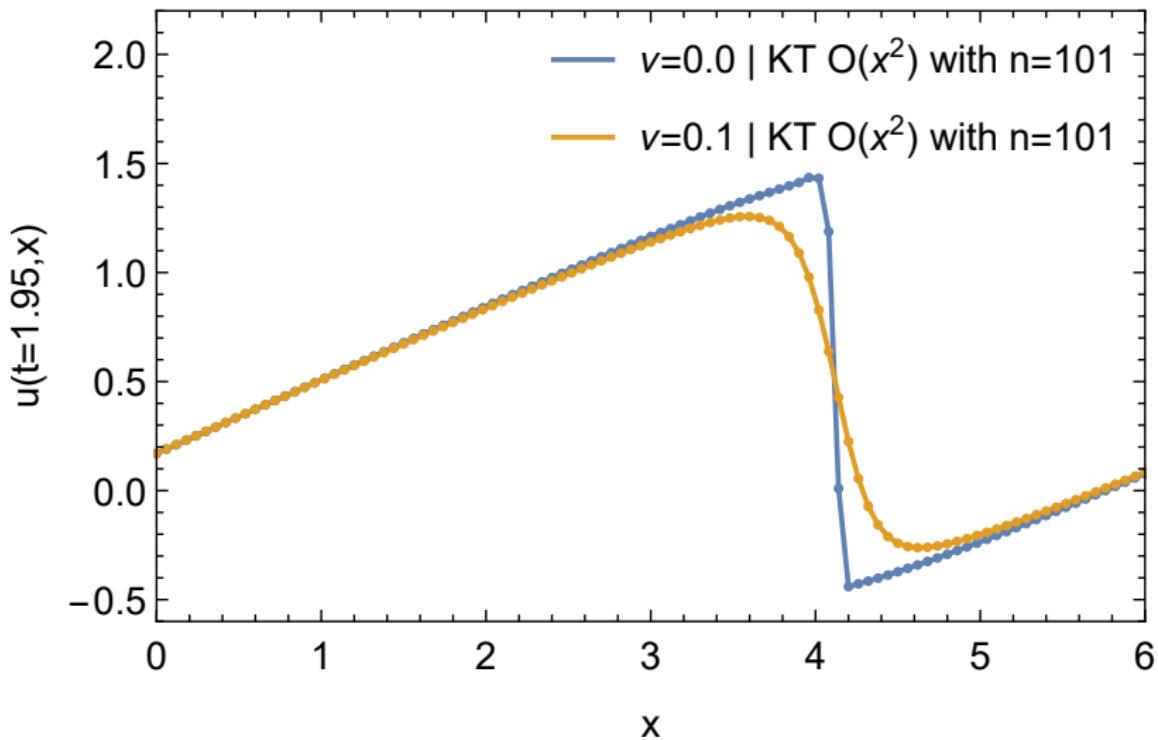


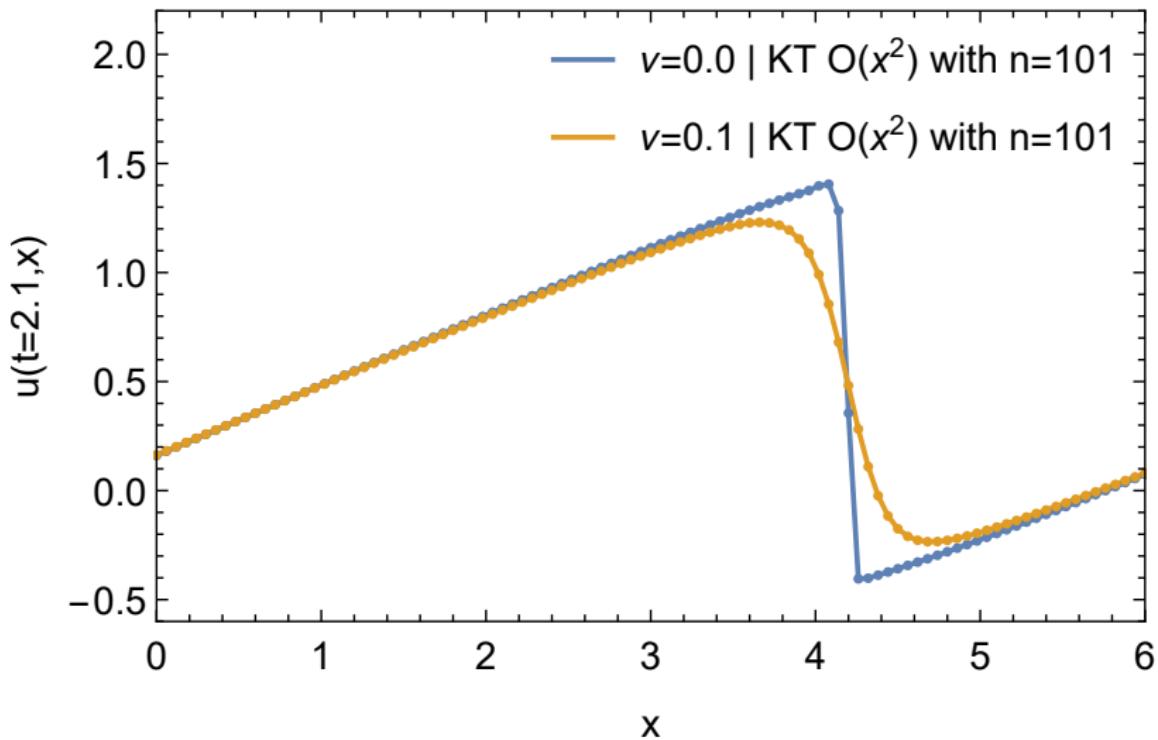


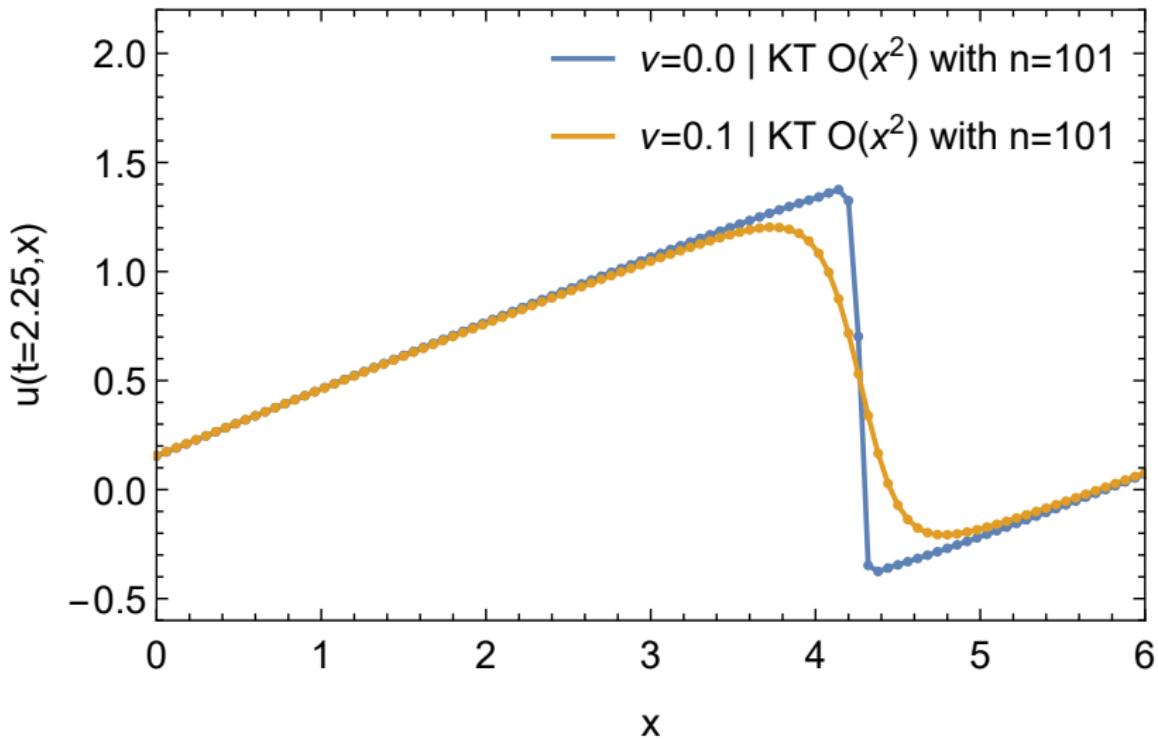


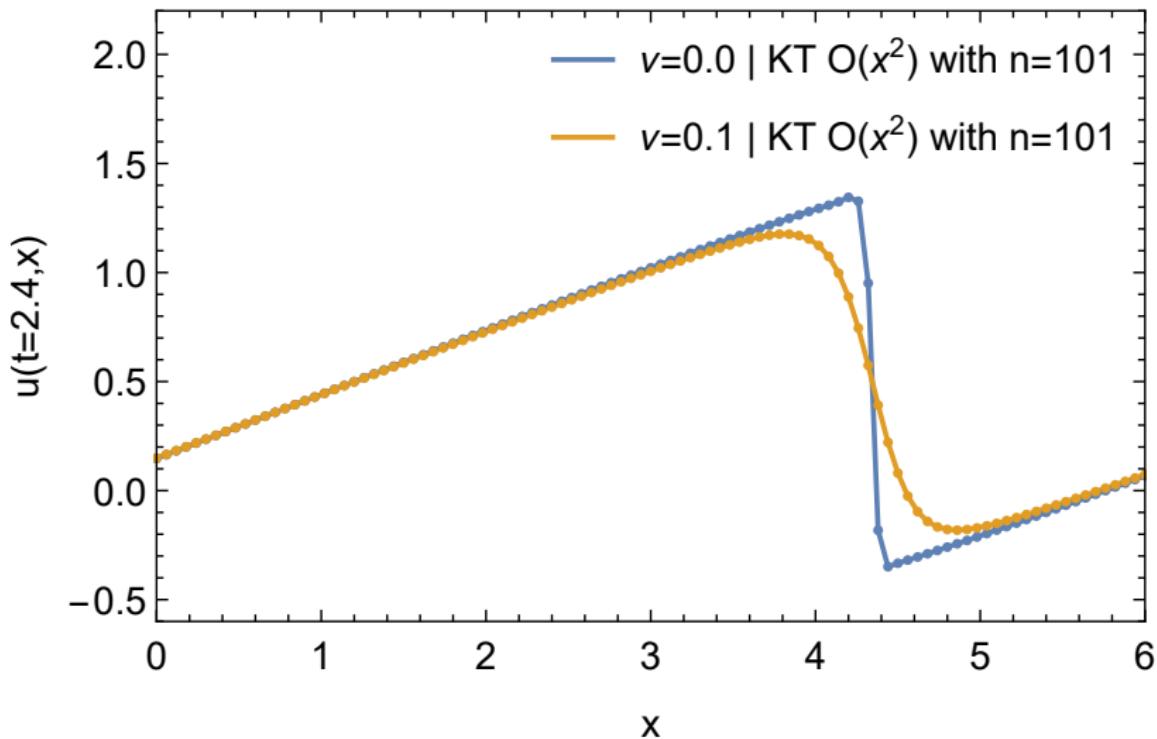


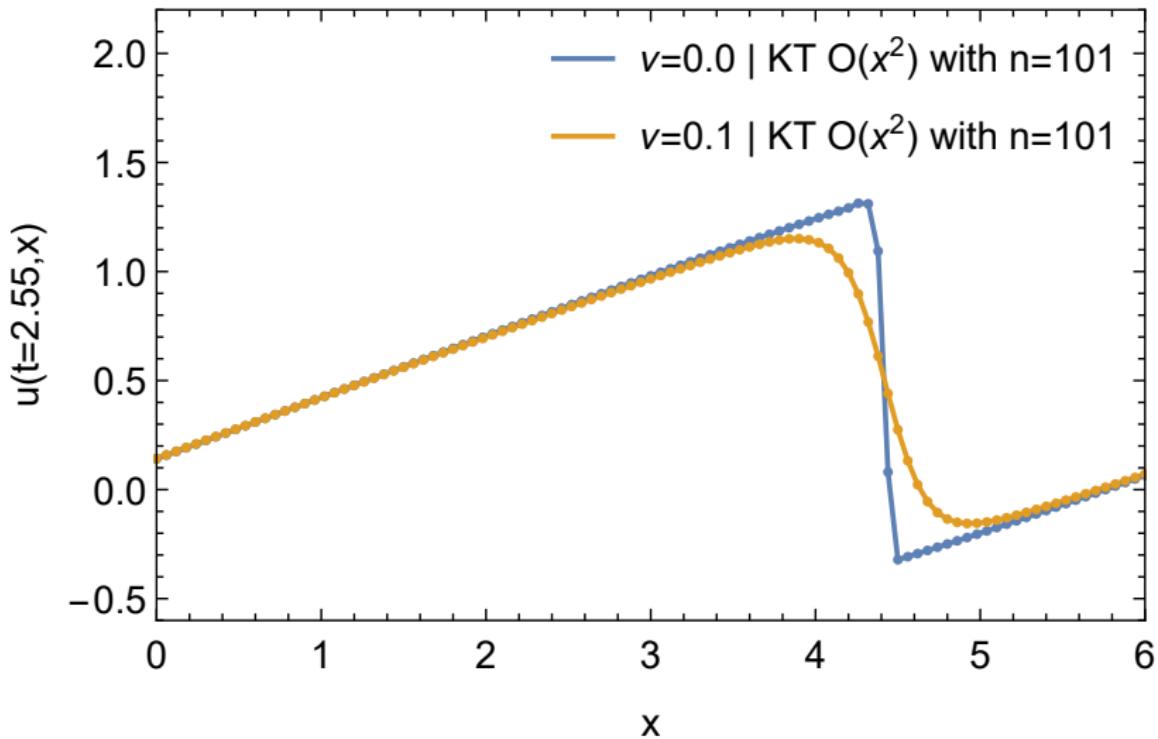


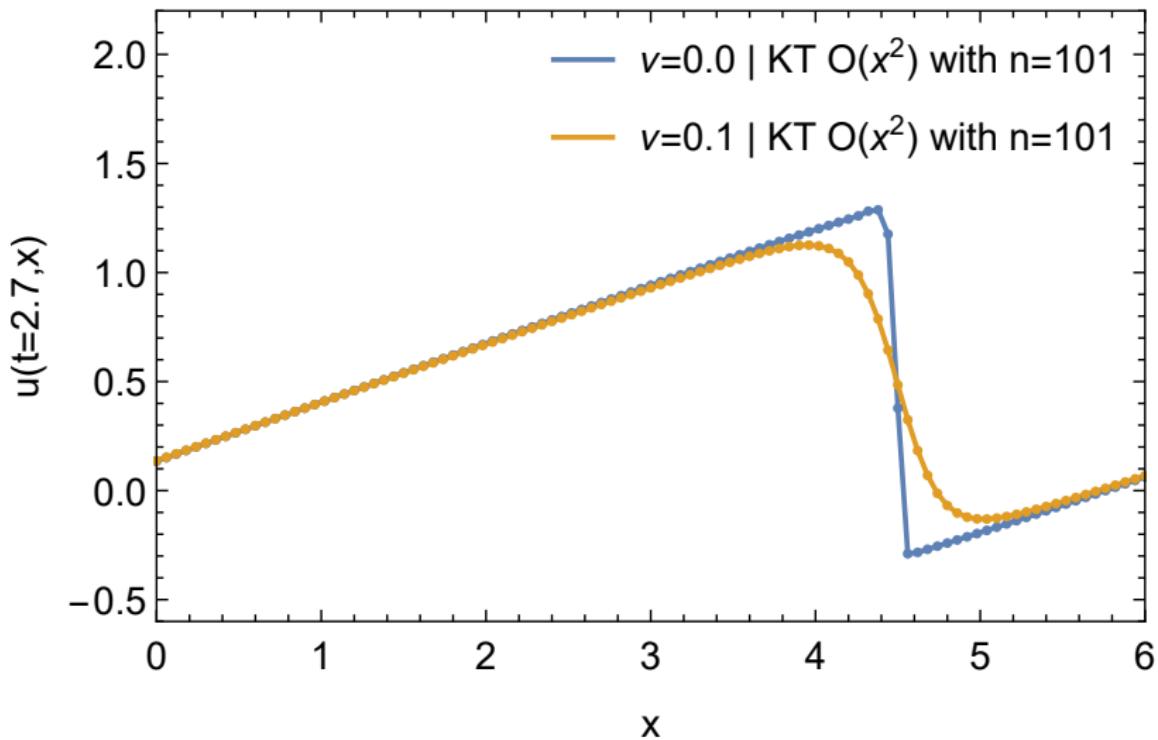


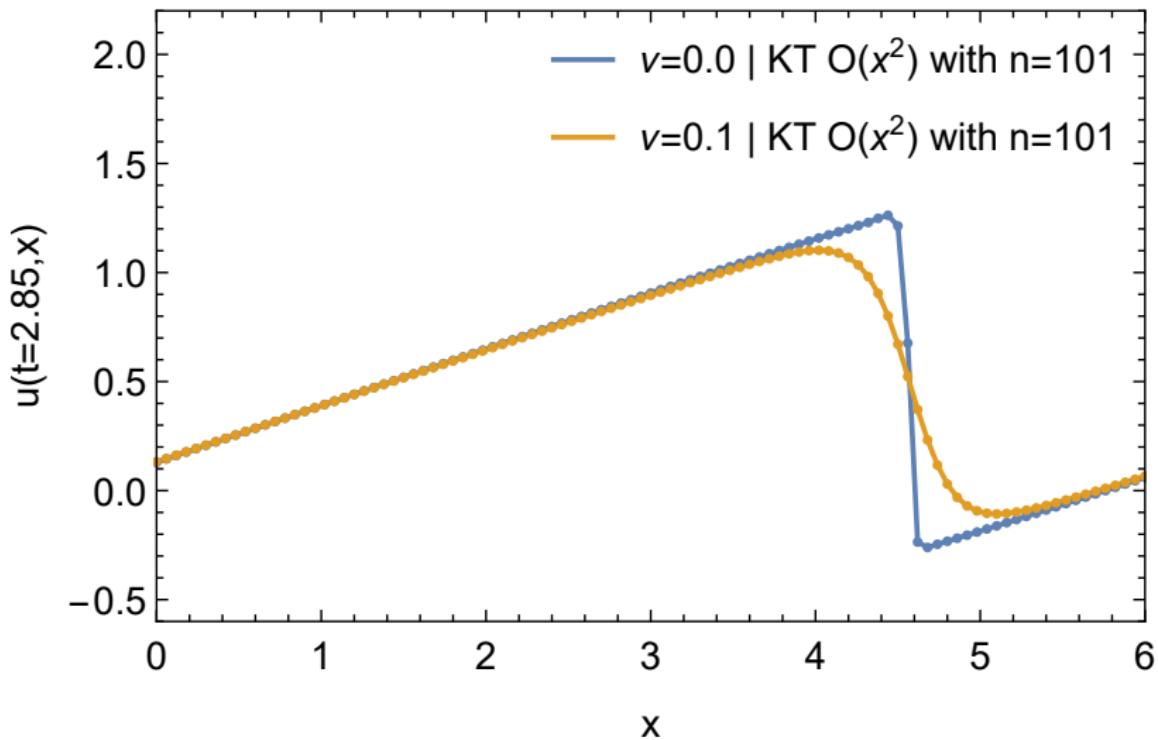


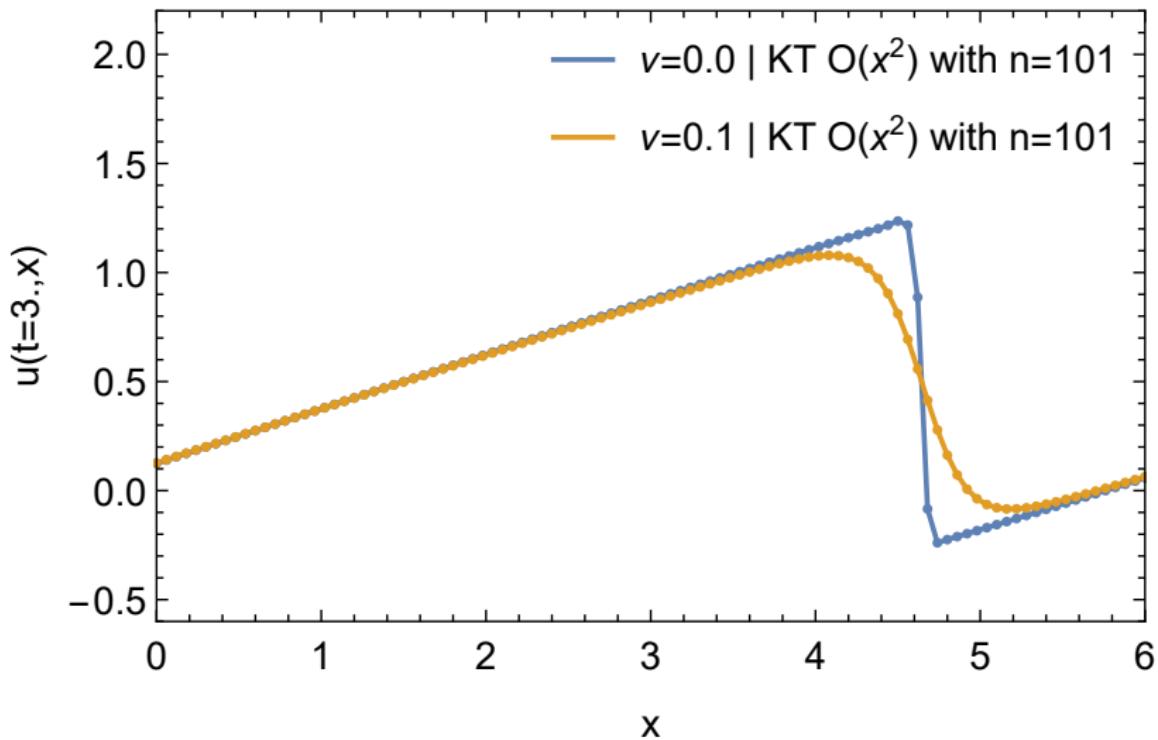


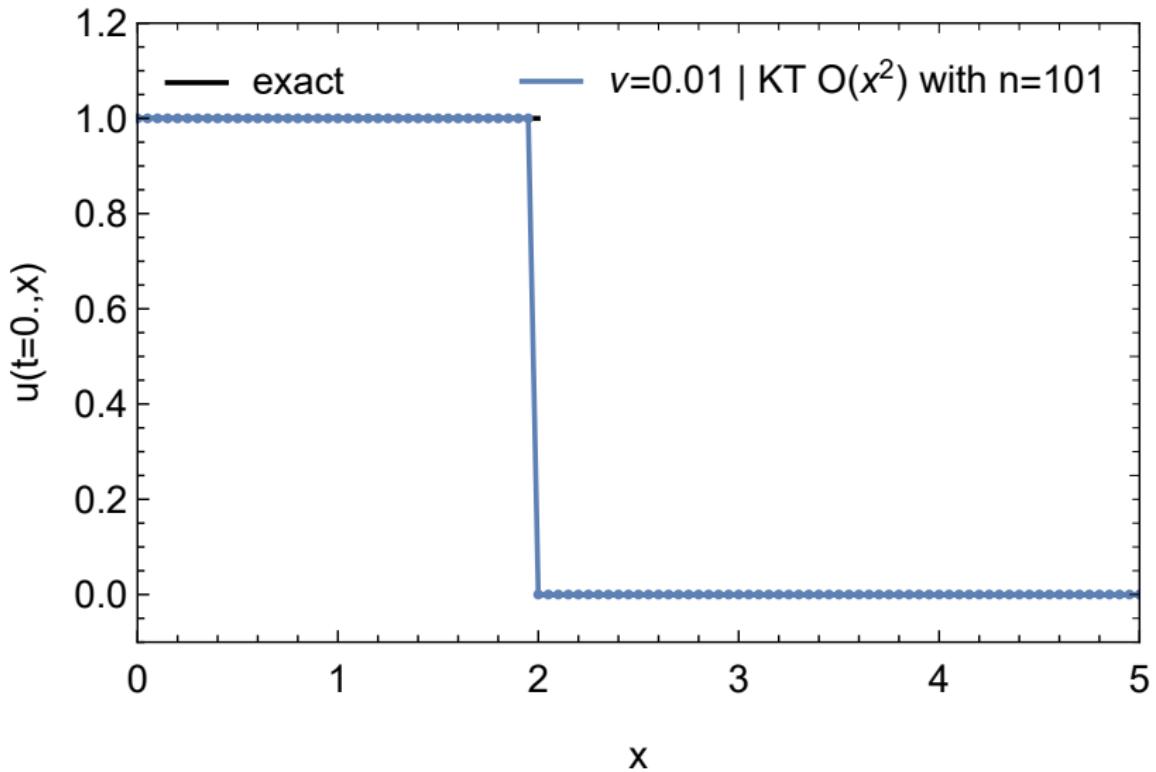


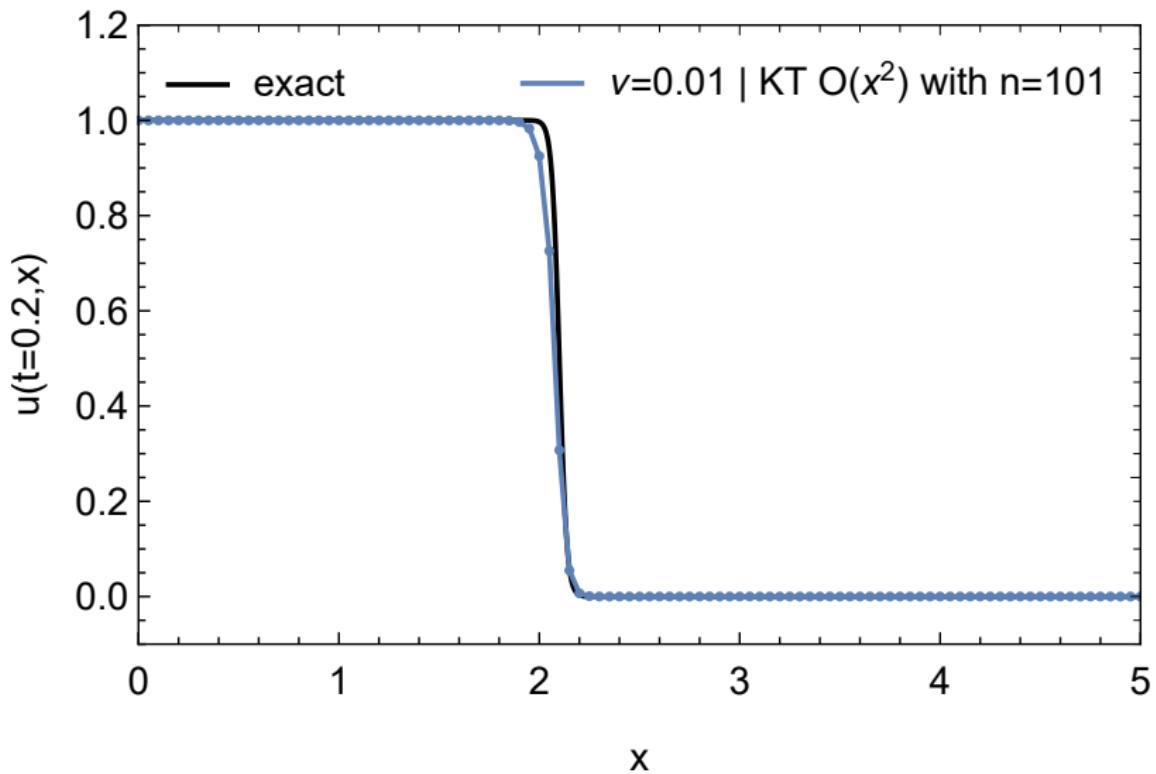


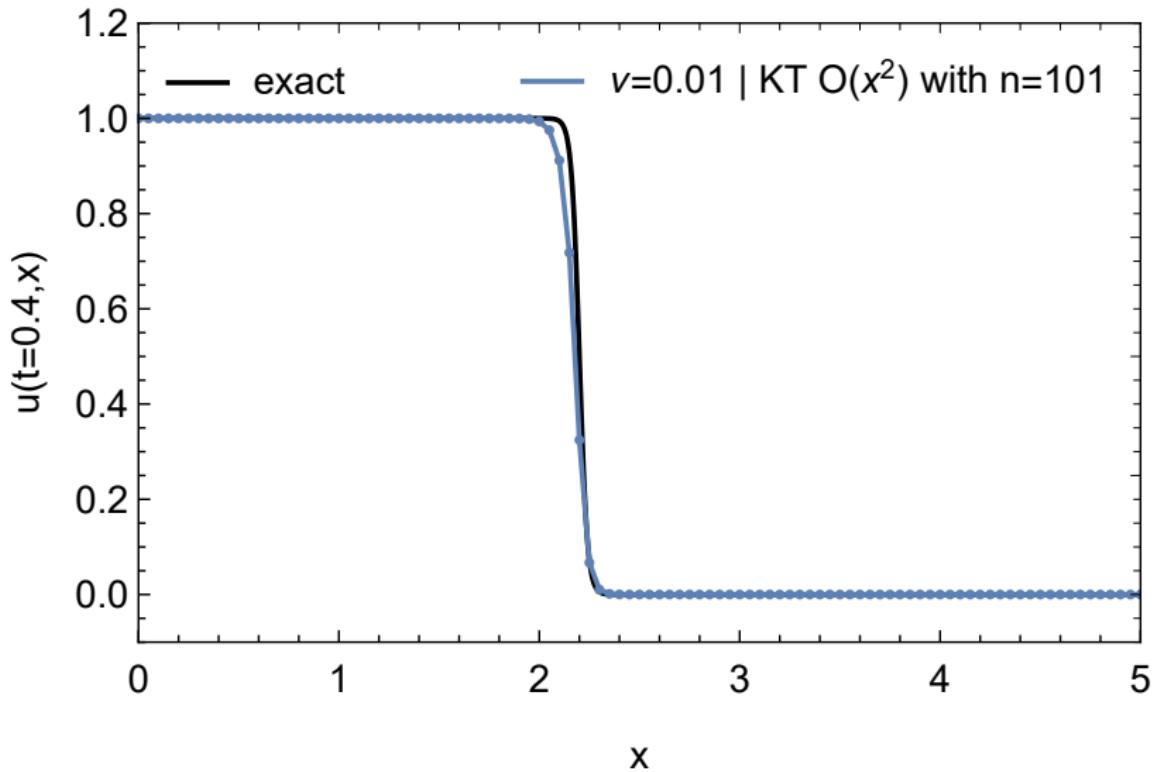


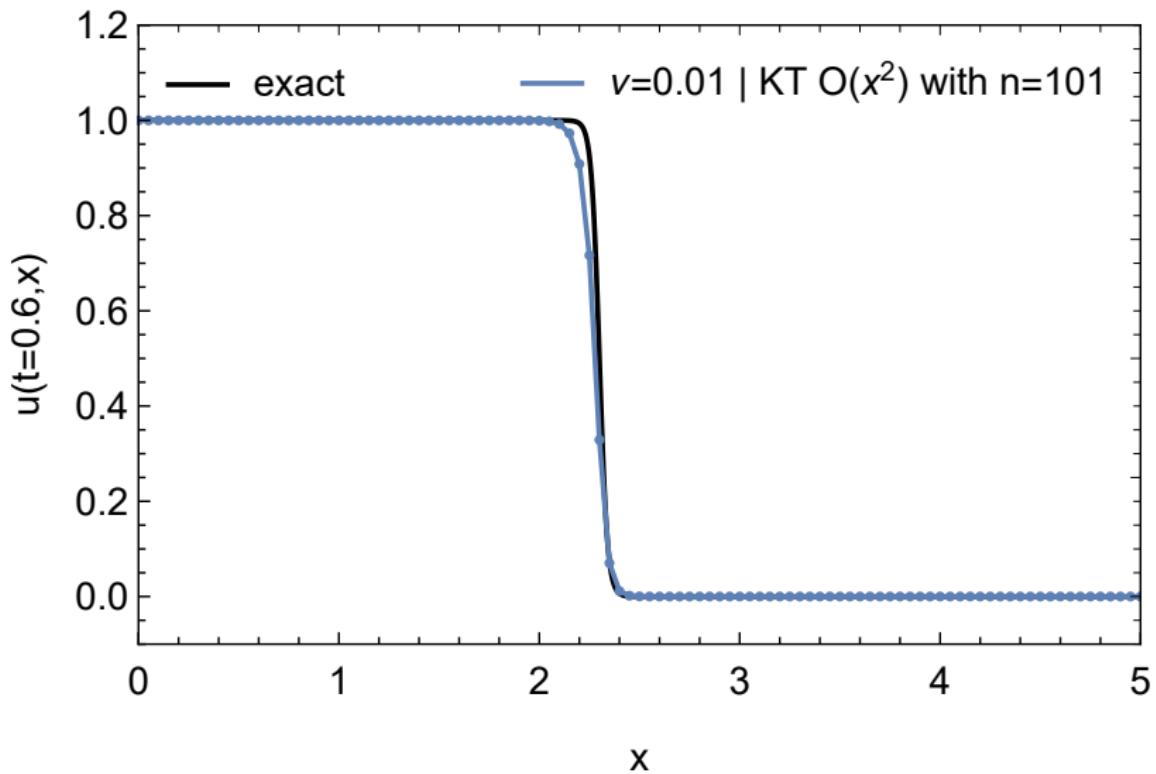


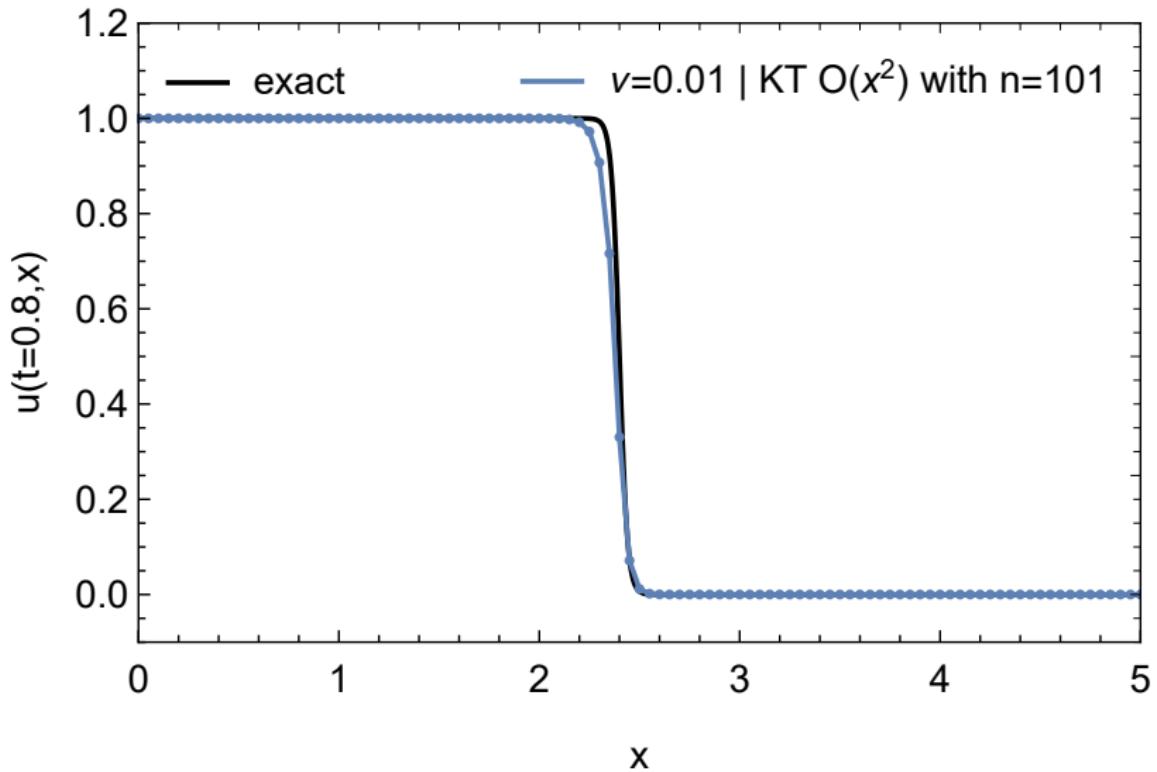


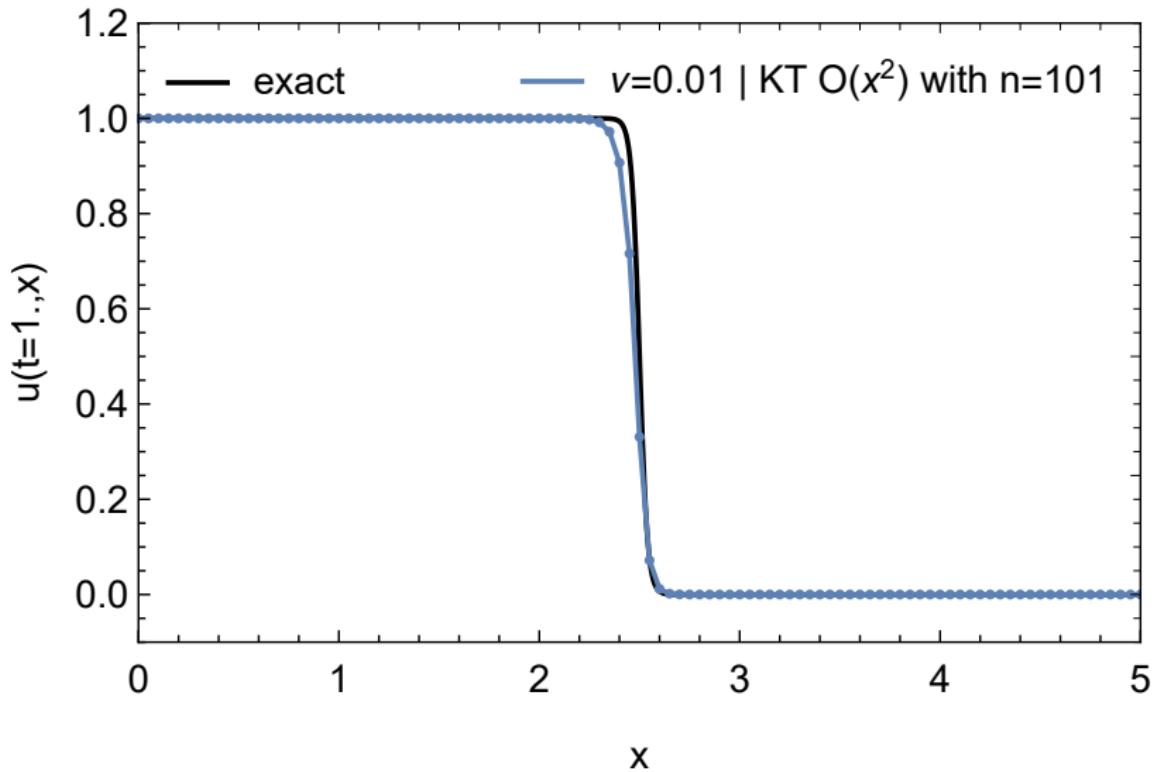


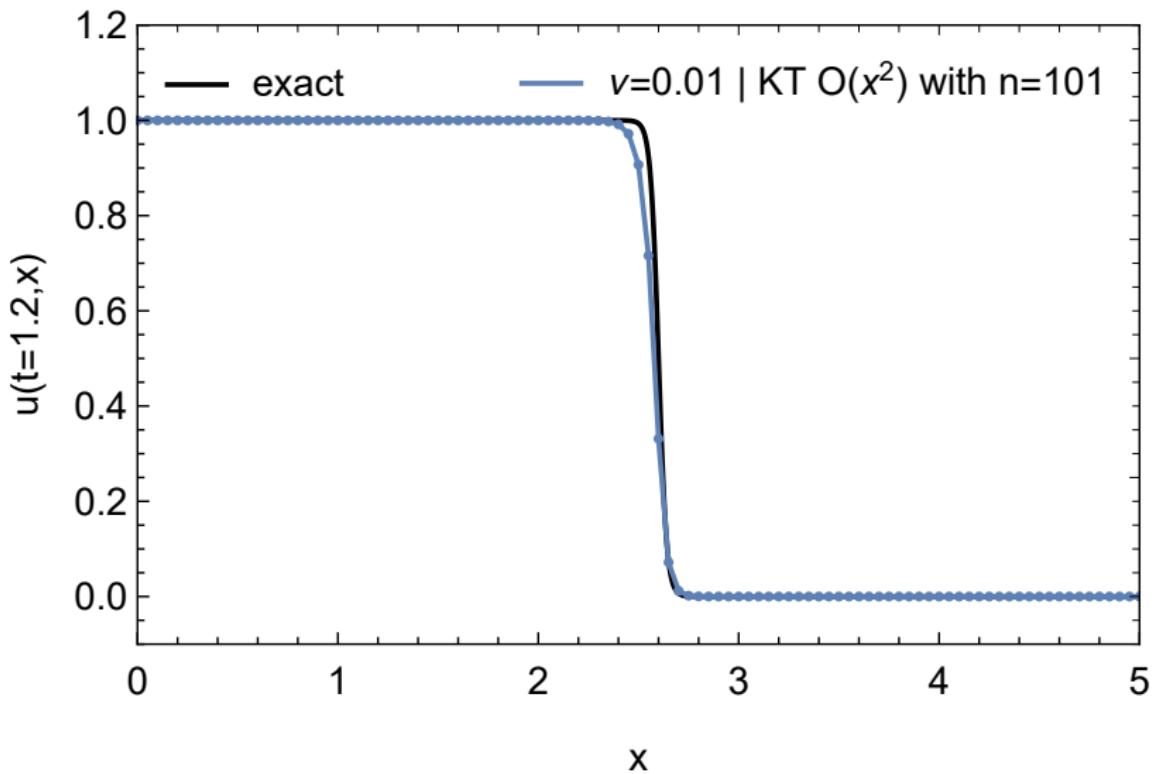


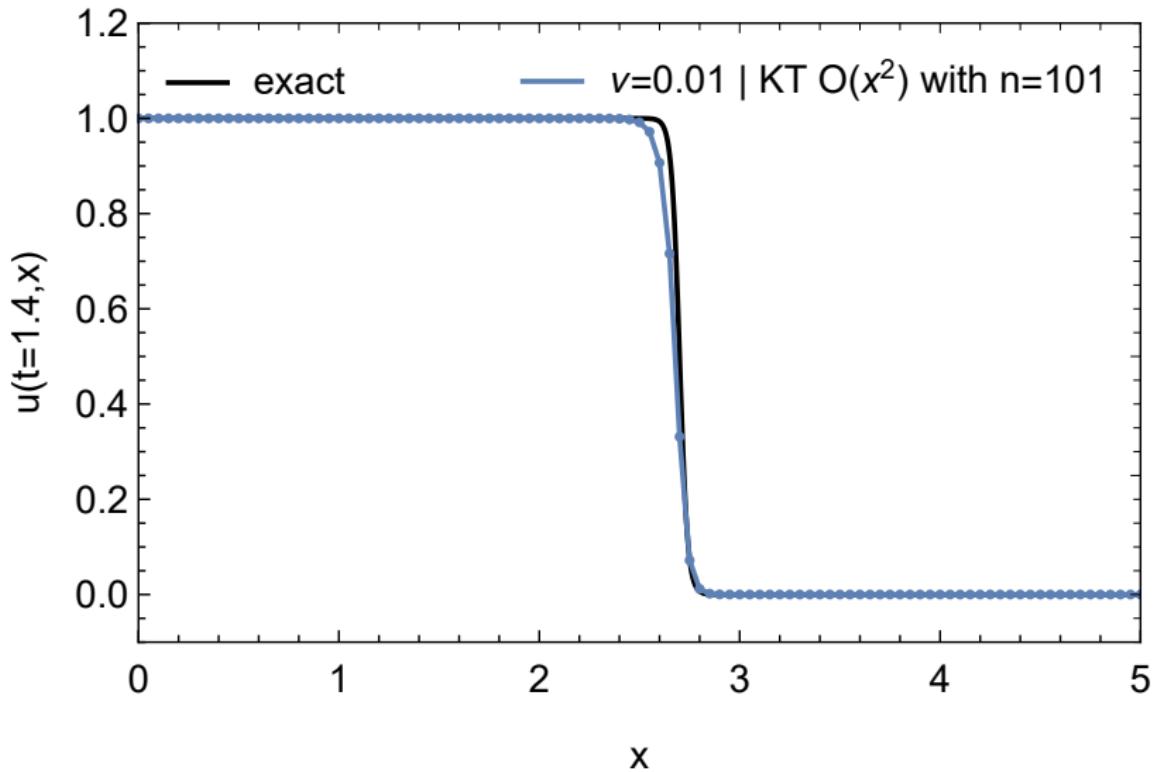


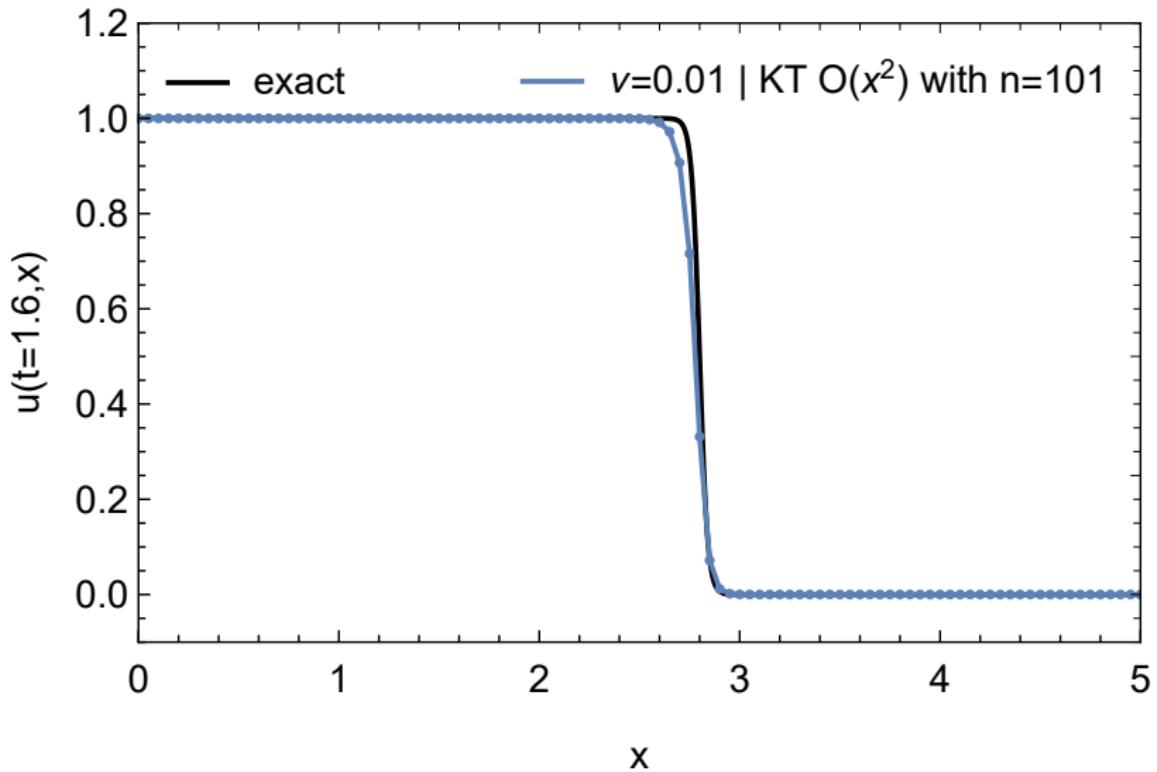


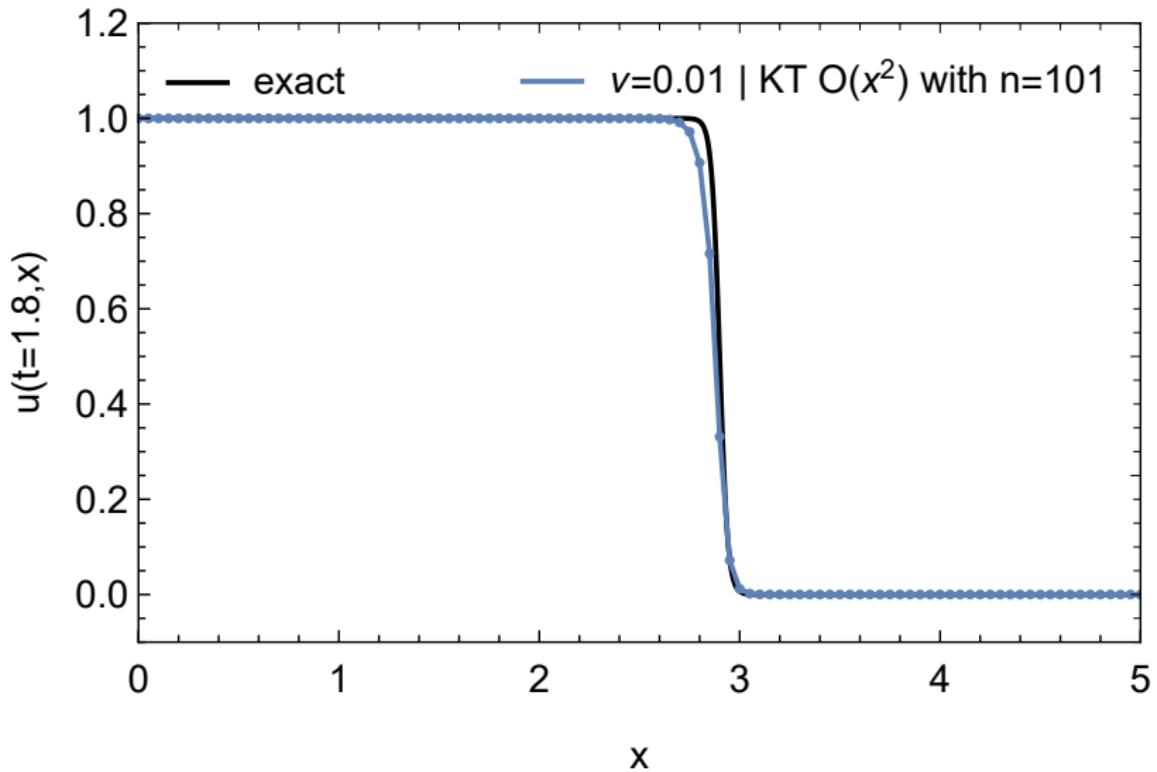


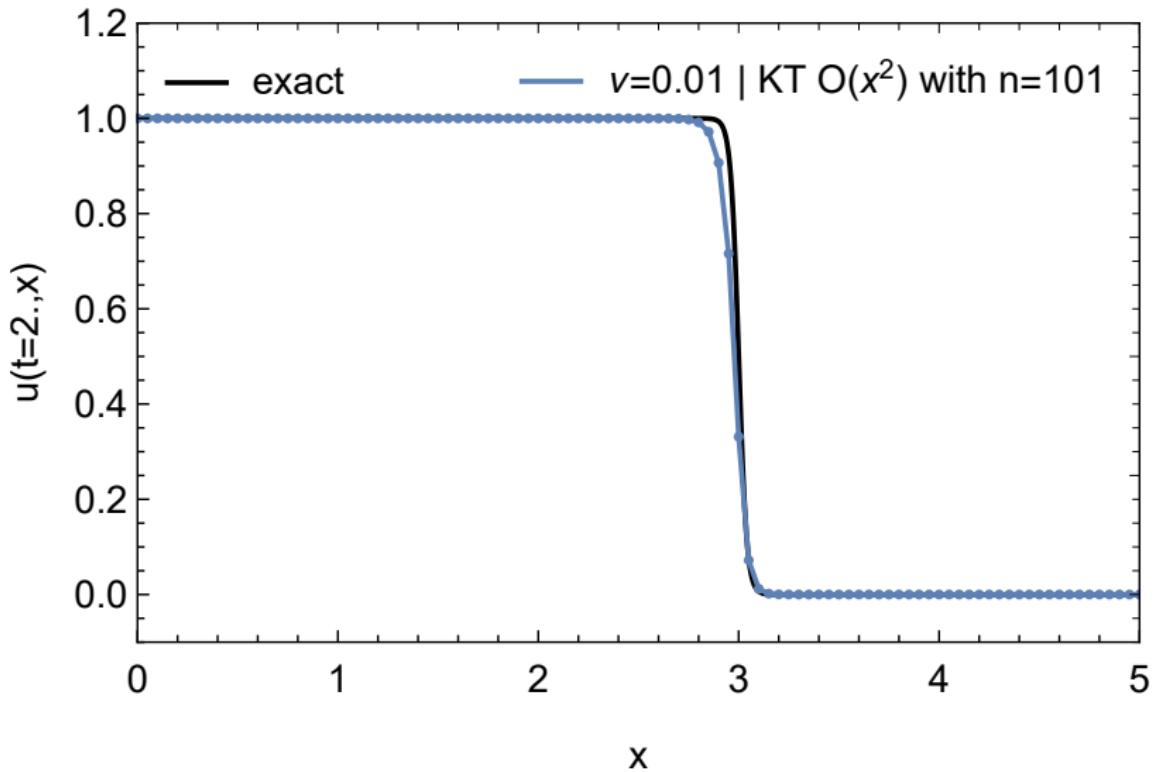


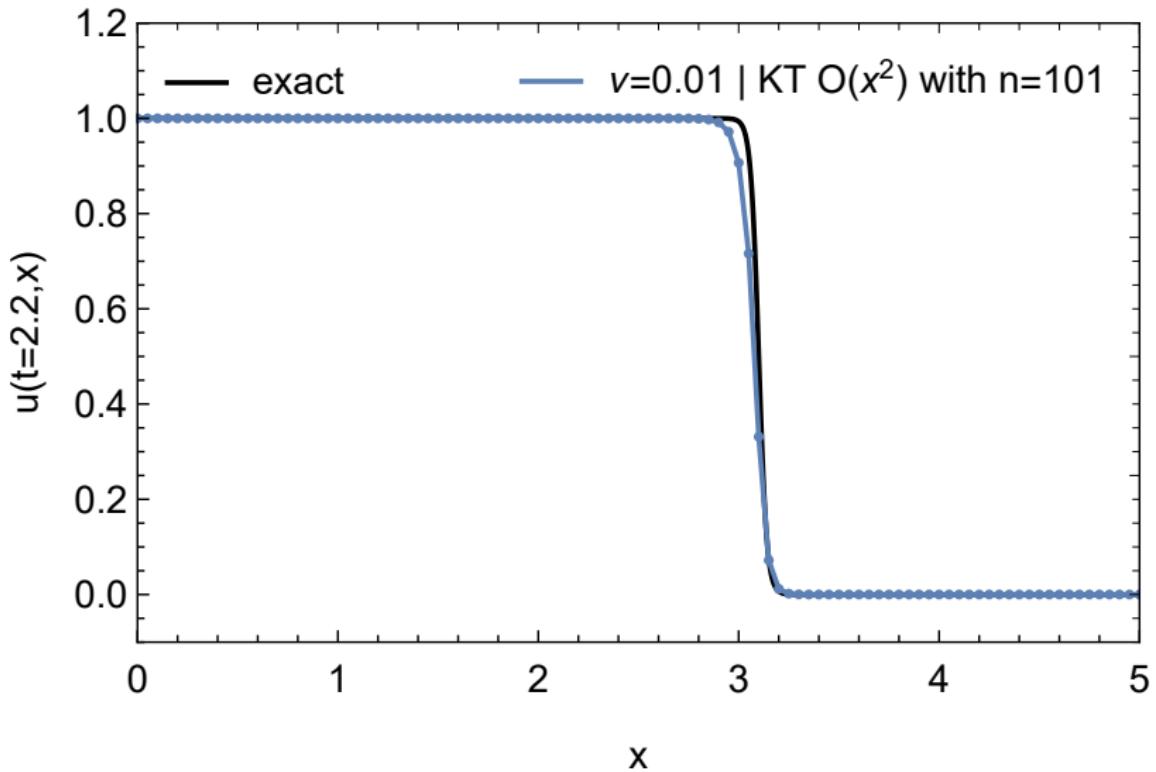


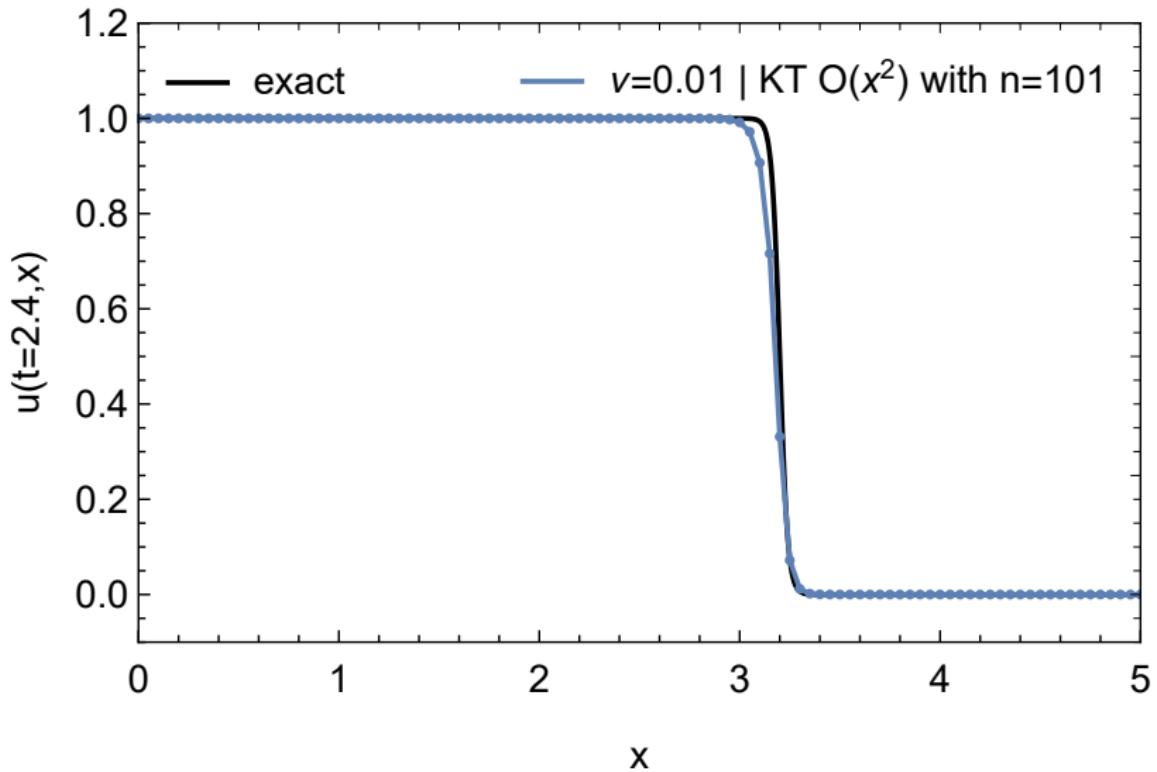


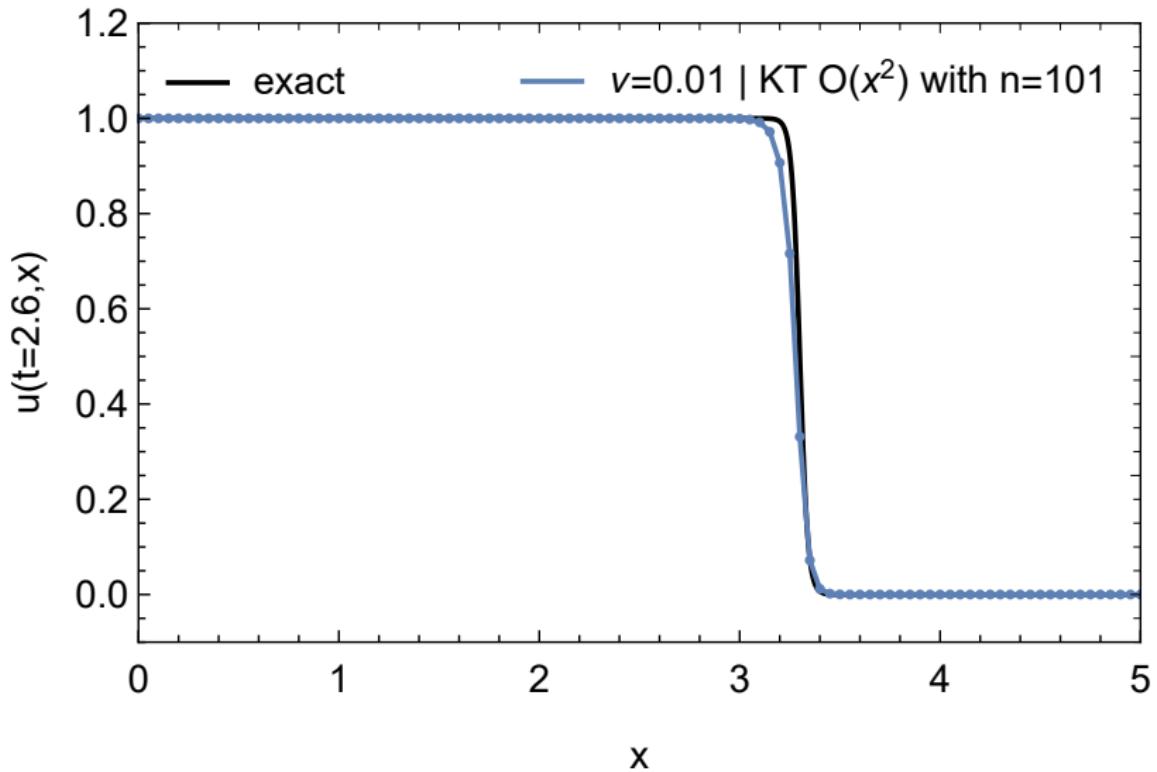


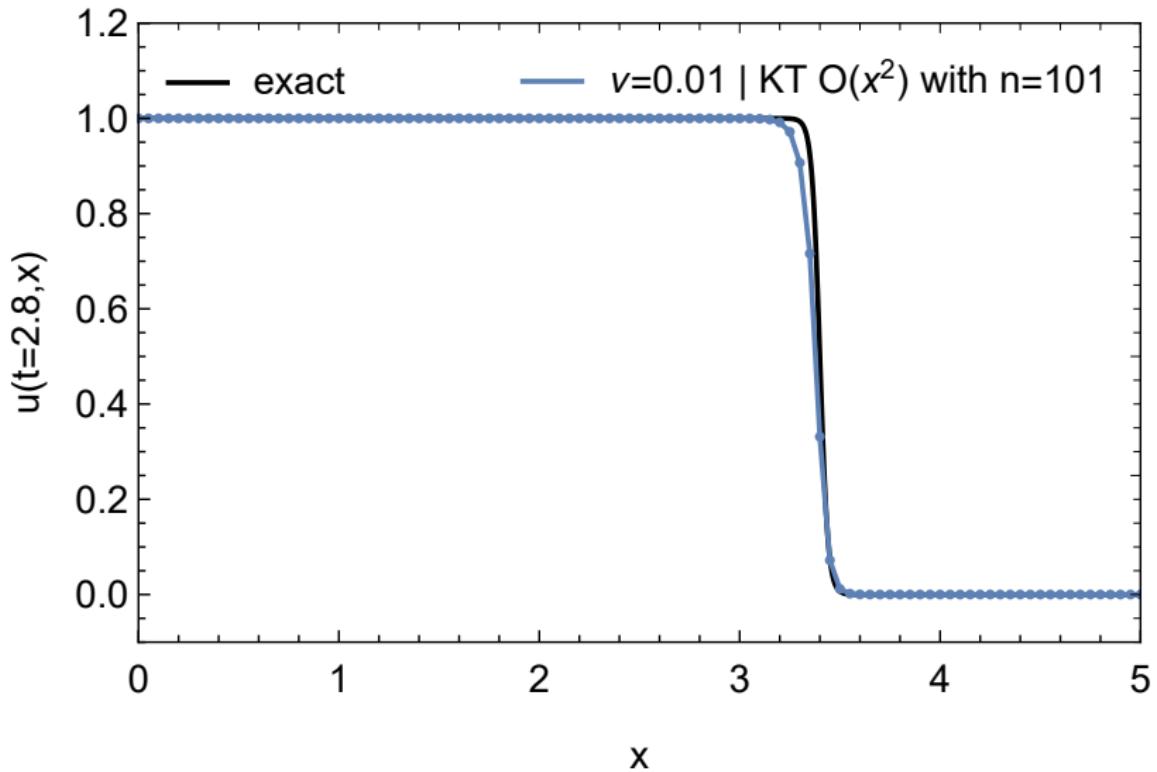


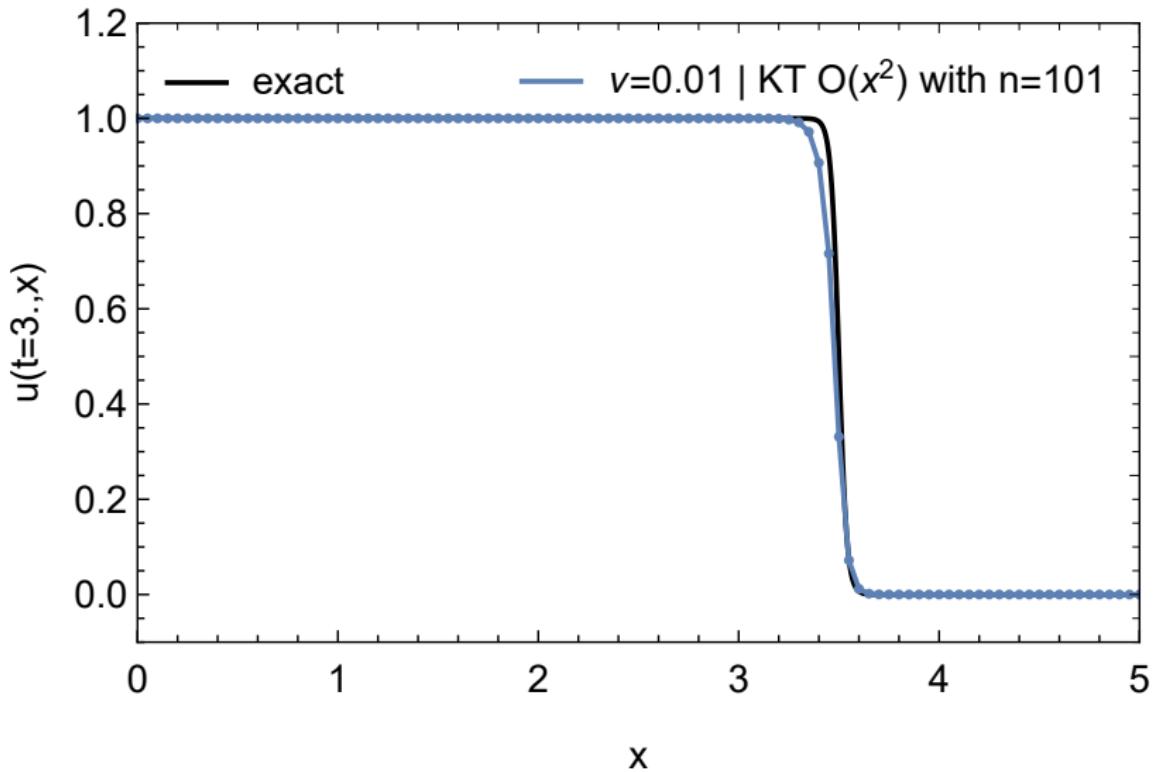


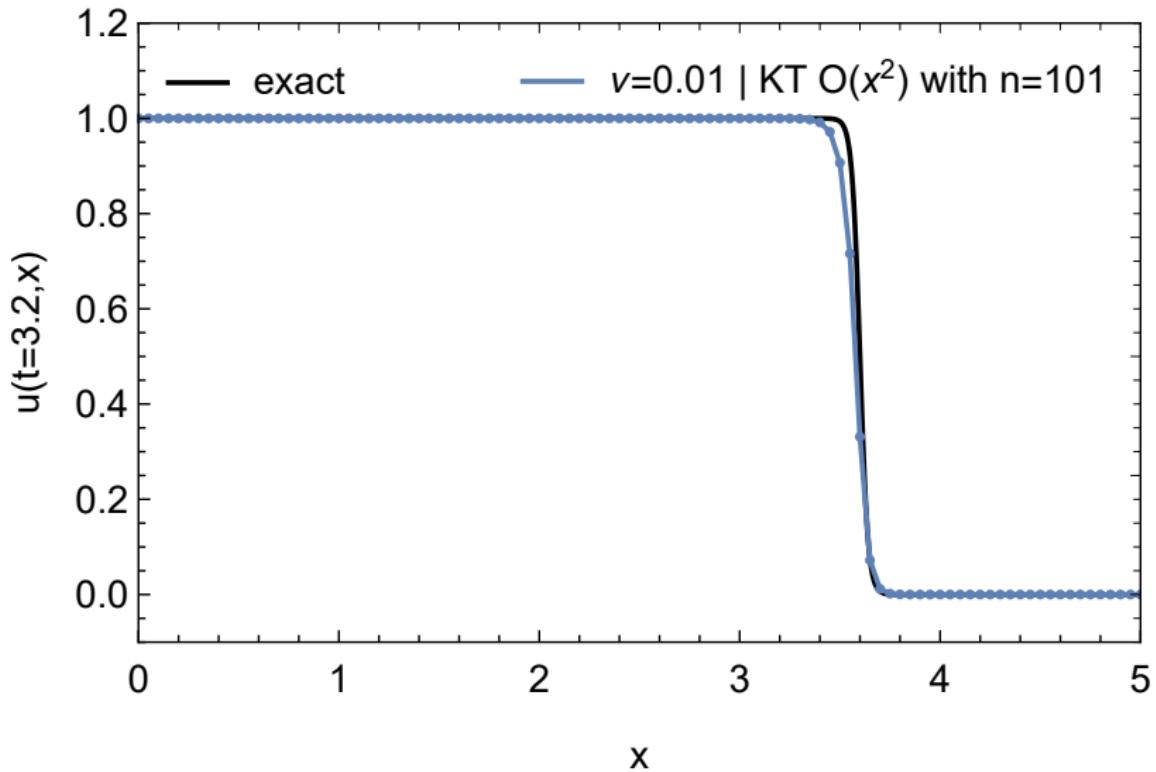


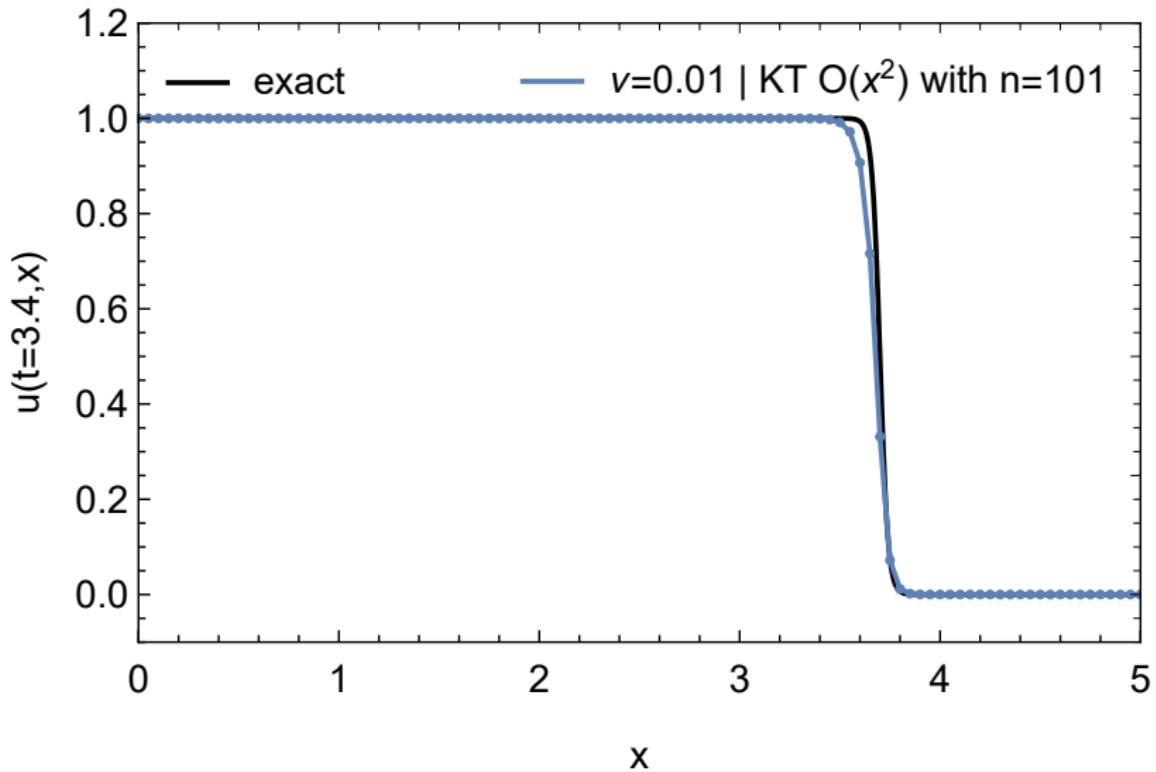


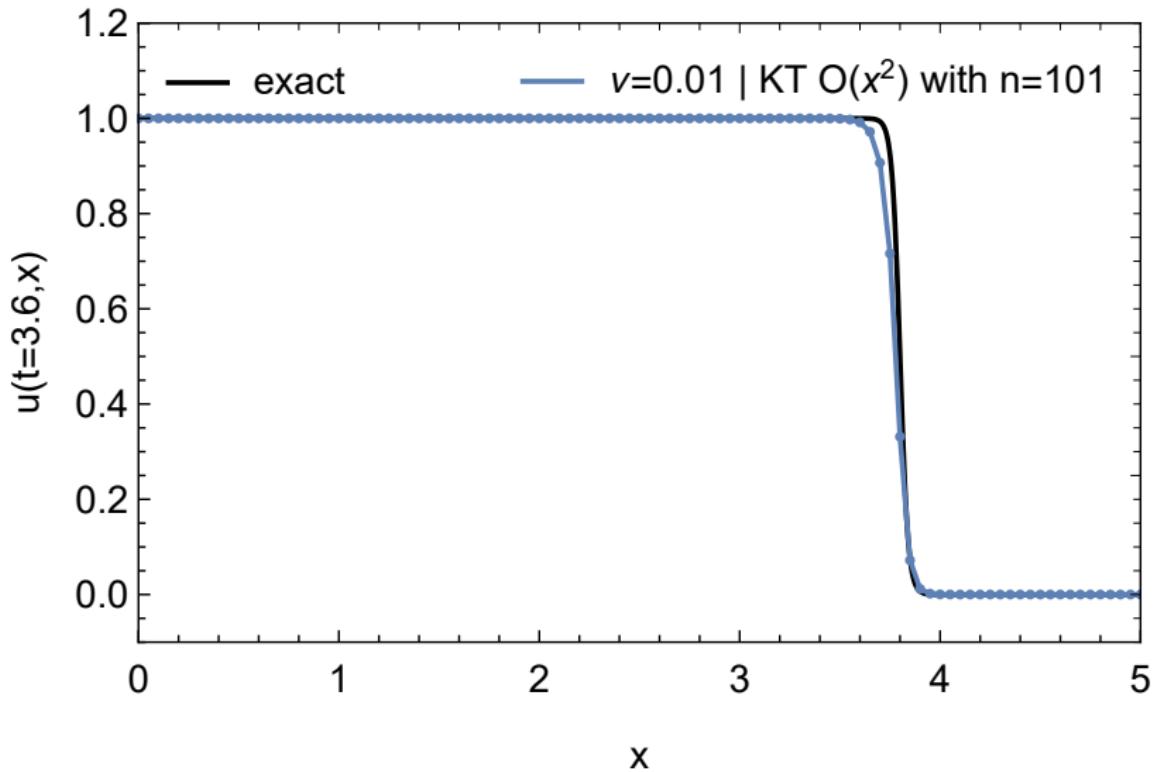


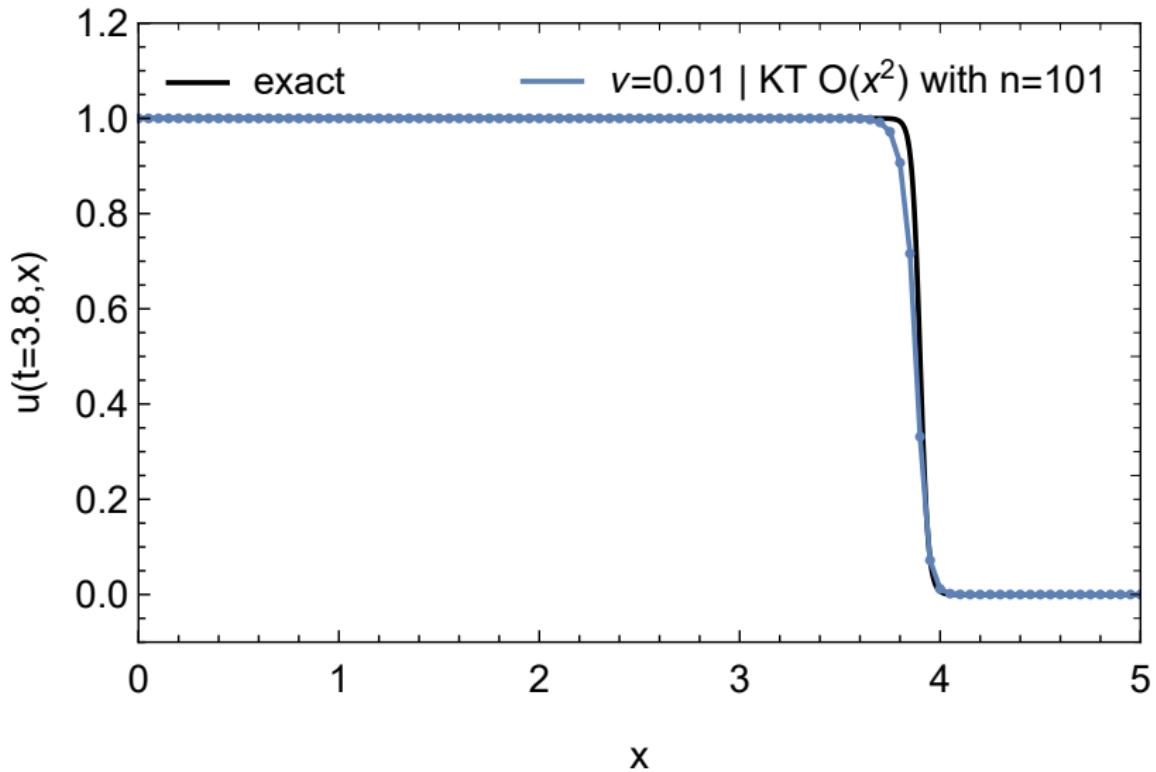


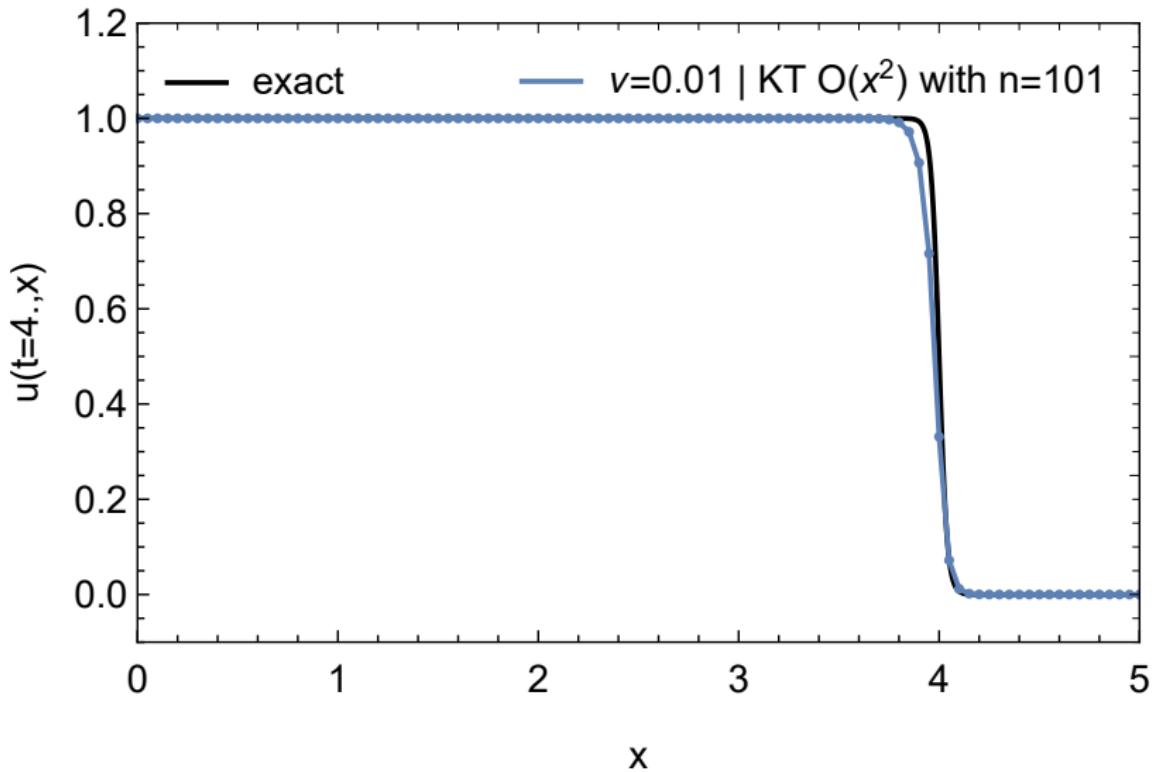












One-dimensional Euler System:

$$\partial_t \begin{pmatrix} \rho \\ \mu \\ \epsilon \end{pmatrix} + \partial_x \begin{pmatrix} \mu \\ \rho v^2 + p \\ (\epsilon + p)v \end{pmatrix} \equiv \partial_t u + \partial_x F[u] = 0, \quad (\text{E})$$

with $u = (\rho, \mu, \epsilon)^T$.

- ▶ Conserved quantities/densities: mass ρ , momentum $\mu = \rho v$ and energy ϵ
- ▶ Equation of state: $p = (\gamma - 1)(\epsilon - \rho v^2/2)$ with $\gamma = 1.4$
- ▶ Shock tube ICs:

$$u(0, x) = \begin{cases} (\rho_L, \mu_L, \epsilon_L)^T & x \leq x_0 \\ (\rho_R, \mu_R, \epsilon_R)^T & \text{otherwise} \end{cases} \quad (\text{EST})$$

Shock tube initial conditions

All initial conditions are given in SI units and have $x_0 = 0.5$ m:

- ▶ Sod's classical initial condition²:

$$u_L = (1.0, 0.0, 2.5)^T \quad u_R = (0.125, 0.0, 0.25)^T \quad (\text{EST.Sod})$$

- ▶ Very strong shock³:

$$u_L = (0.445, 0.311, 8.928)^T \quad u_R = (0.5, 0.0, 1.4275)^T \quad (\text{EST.Lax})$$

- ▶ Strong double rarefaction wave and vacuum limit⁴:

$$u_L = (1.0, -2.0, 3.0)^T \quad u_R = (1.0, 2.0, 3.0)^T \quad (\text{EST.Toro2})$$

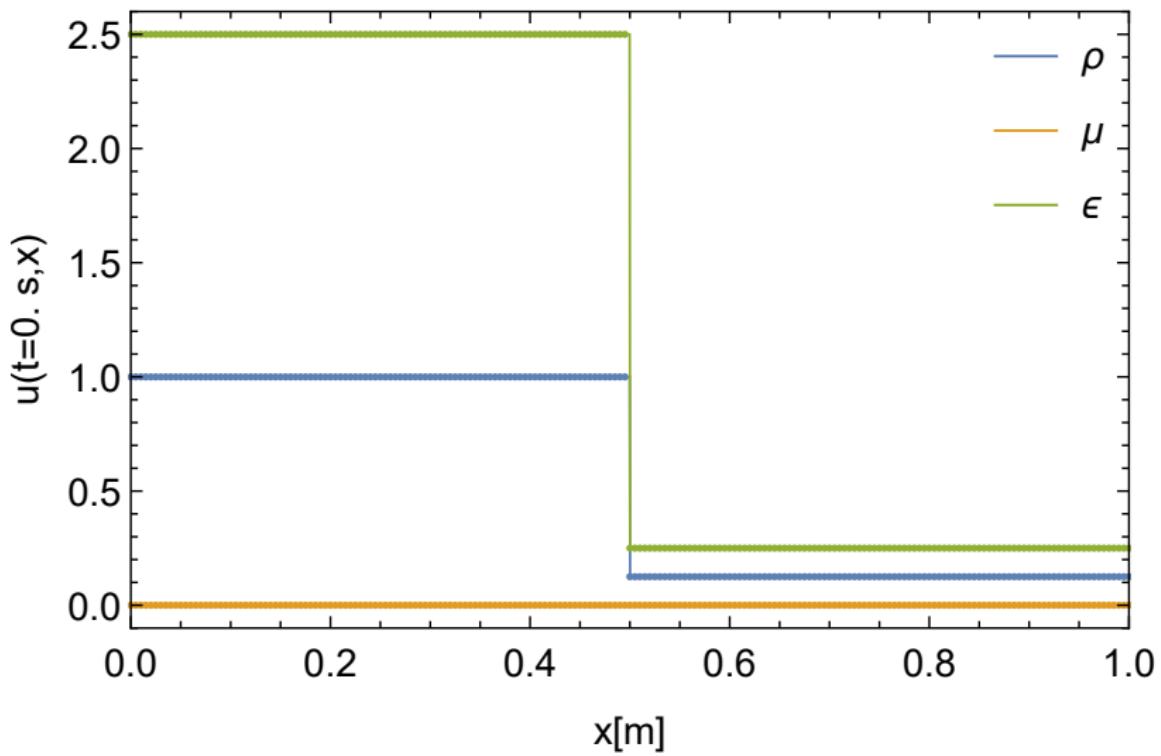
Exact solutions of the respective Riemann problems were computed with⁵

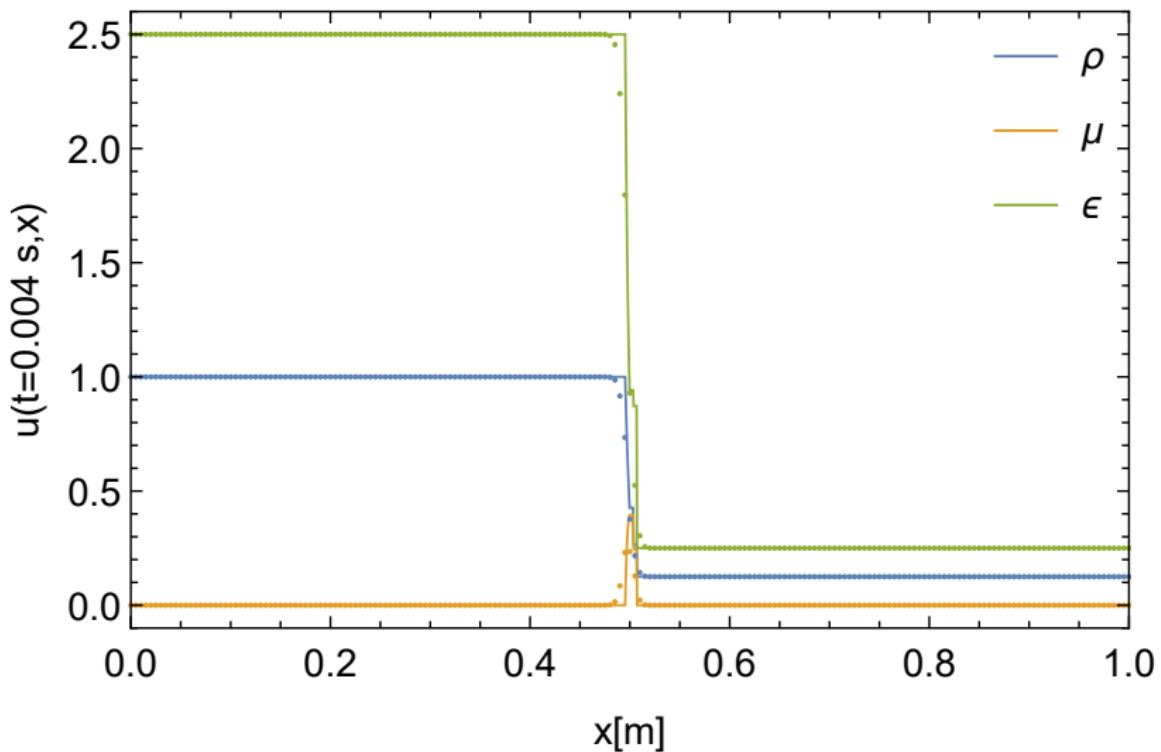
²G. A. Sod, J. Comput. Phys. 27.1 (1978)

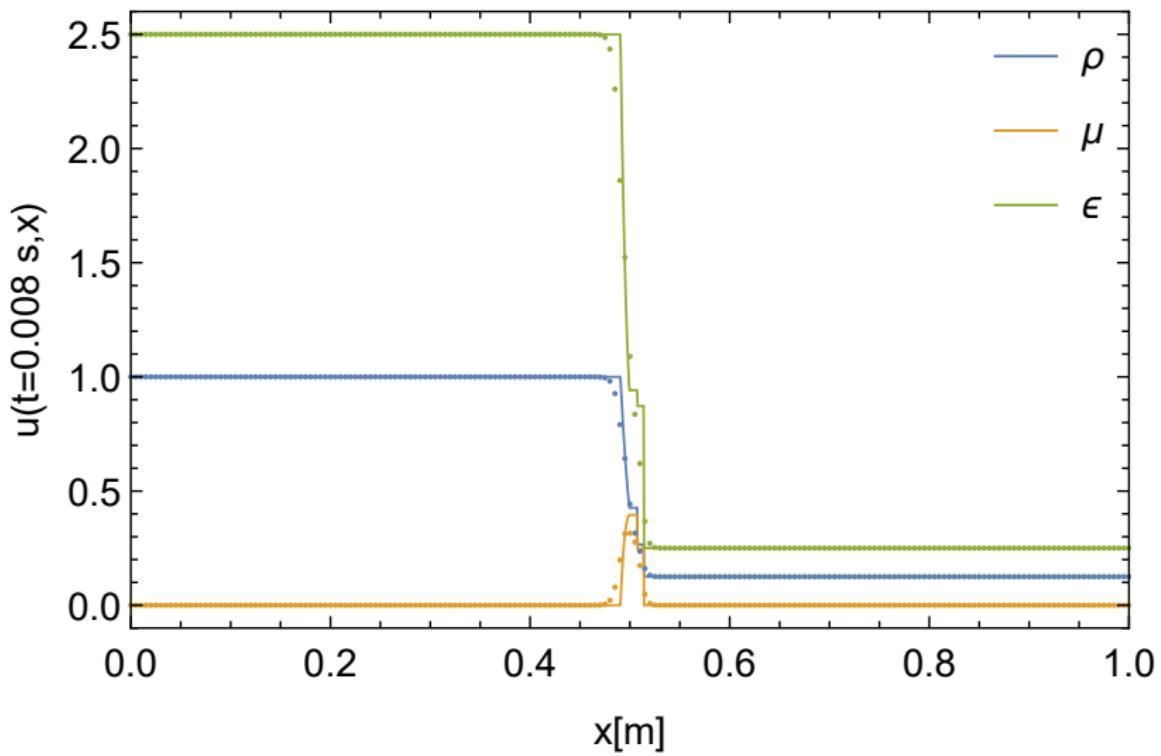
³P. D. Lax, Comm. Pure Appl. Math. 7.1 (1954)

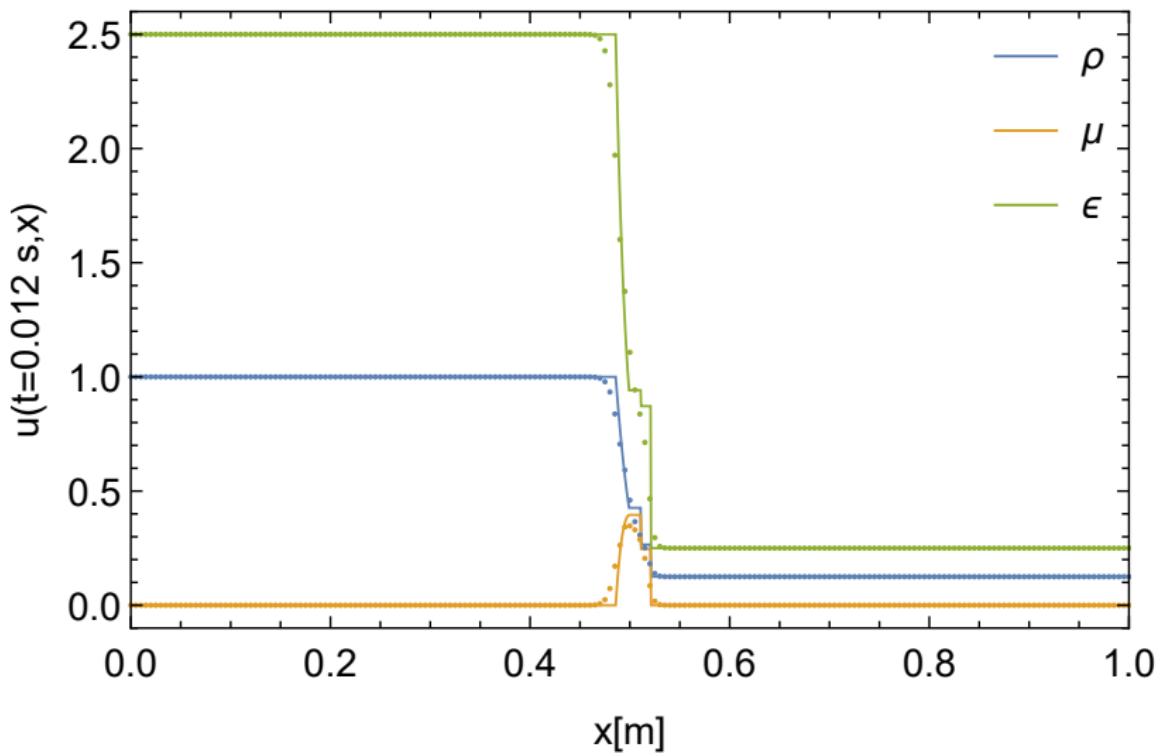
⁴E. Toro, *Riemann Solvers and Numerical Methods for Fluid Dynamics*, Berlin: Springer, 1999

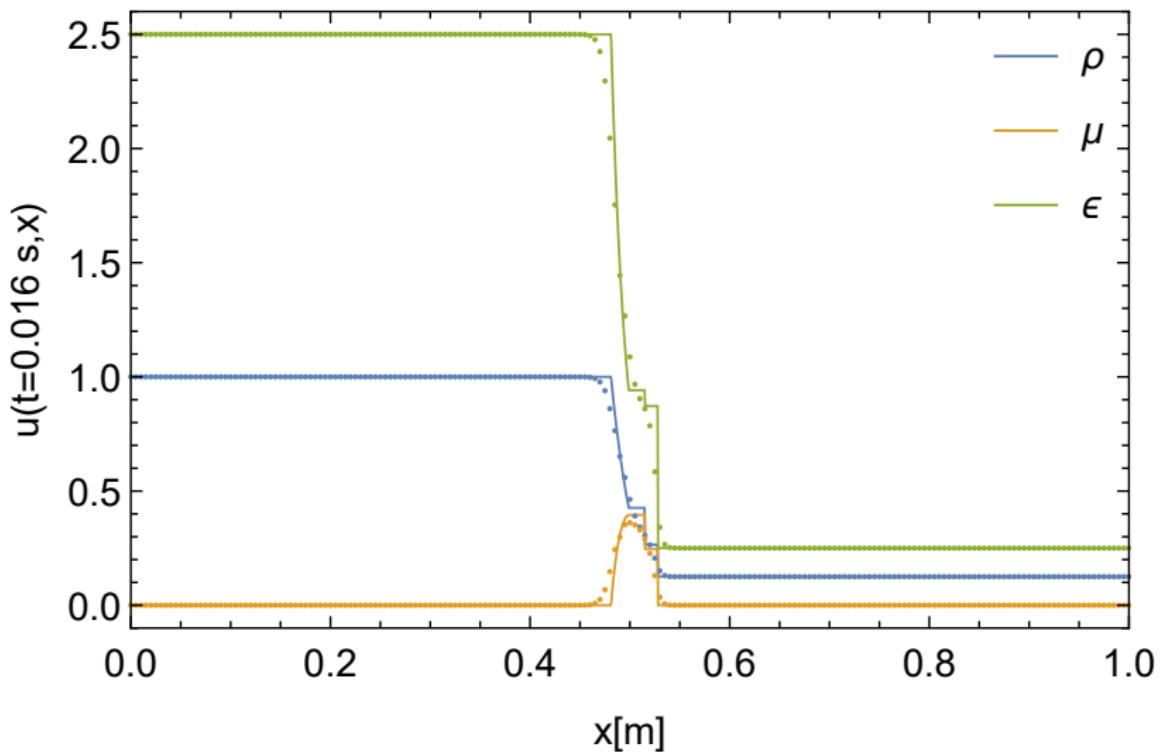
⁵D. I. Ketcheson and et al., Riemann Problems and Jupyter Solutions, github.com/clawpack/riemann_book - 2019.07.09 - 20:30

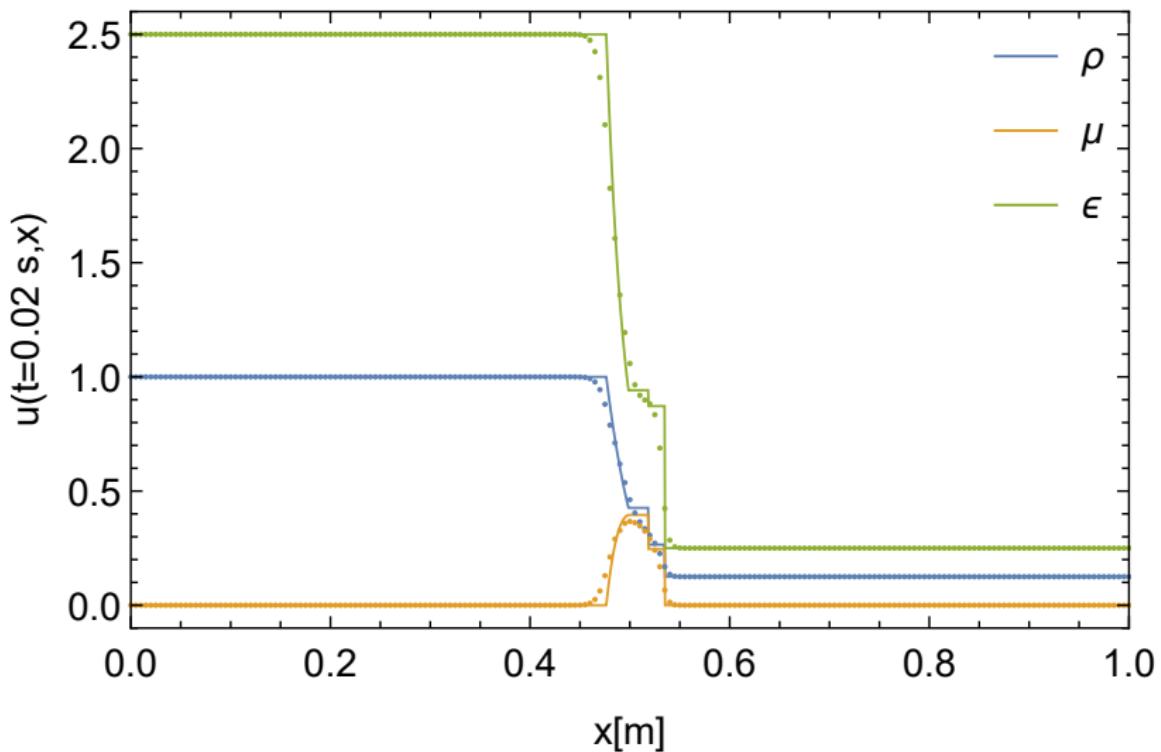


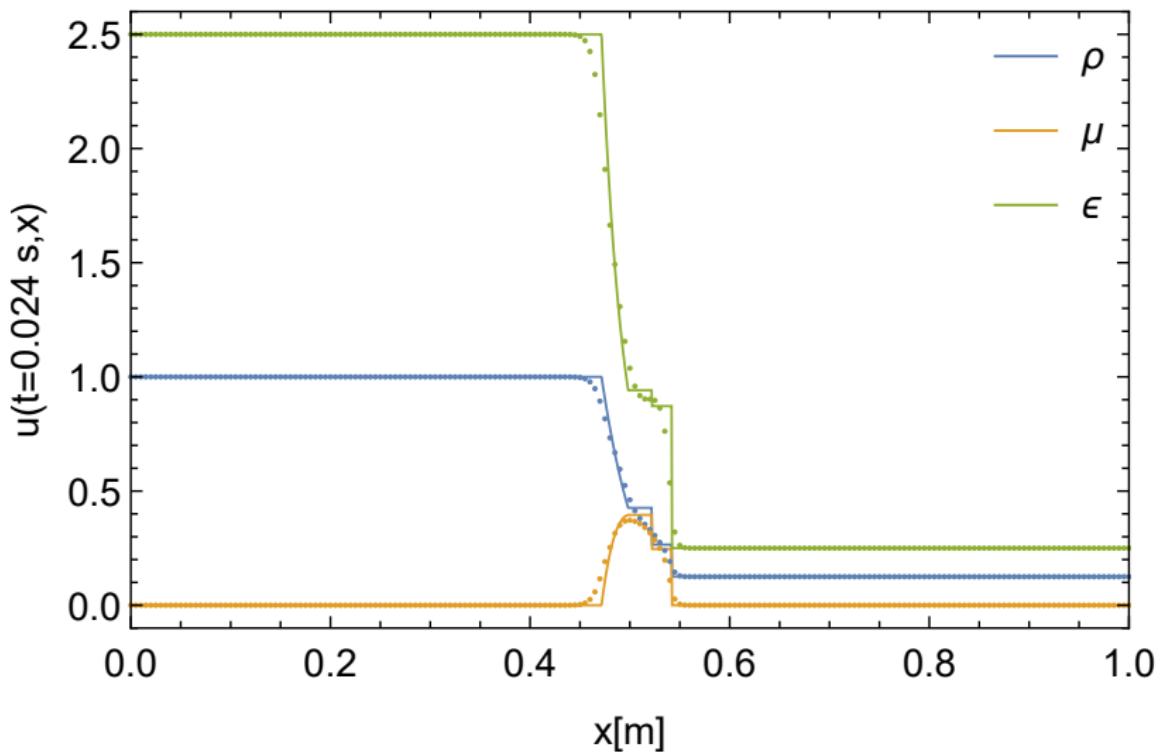


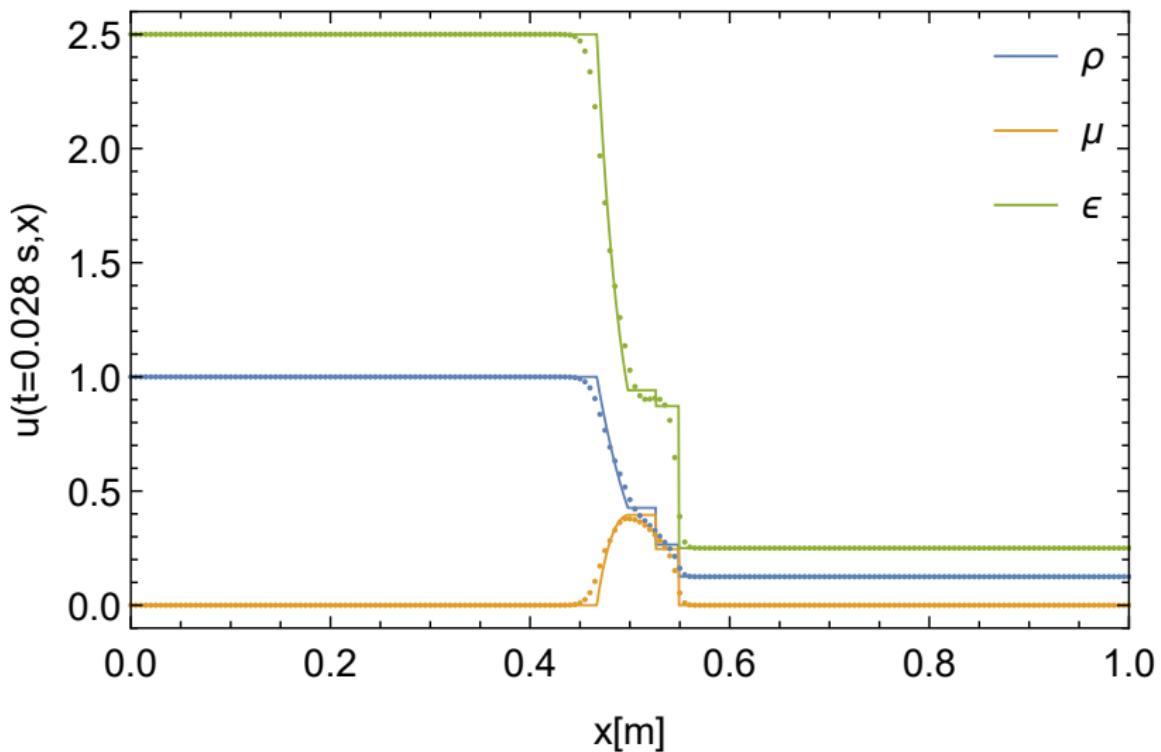


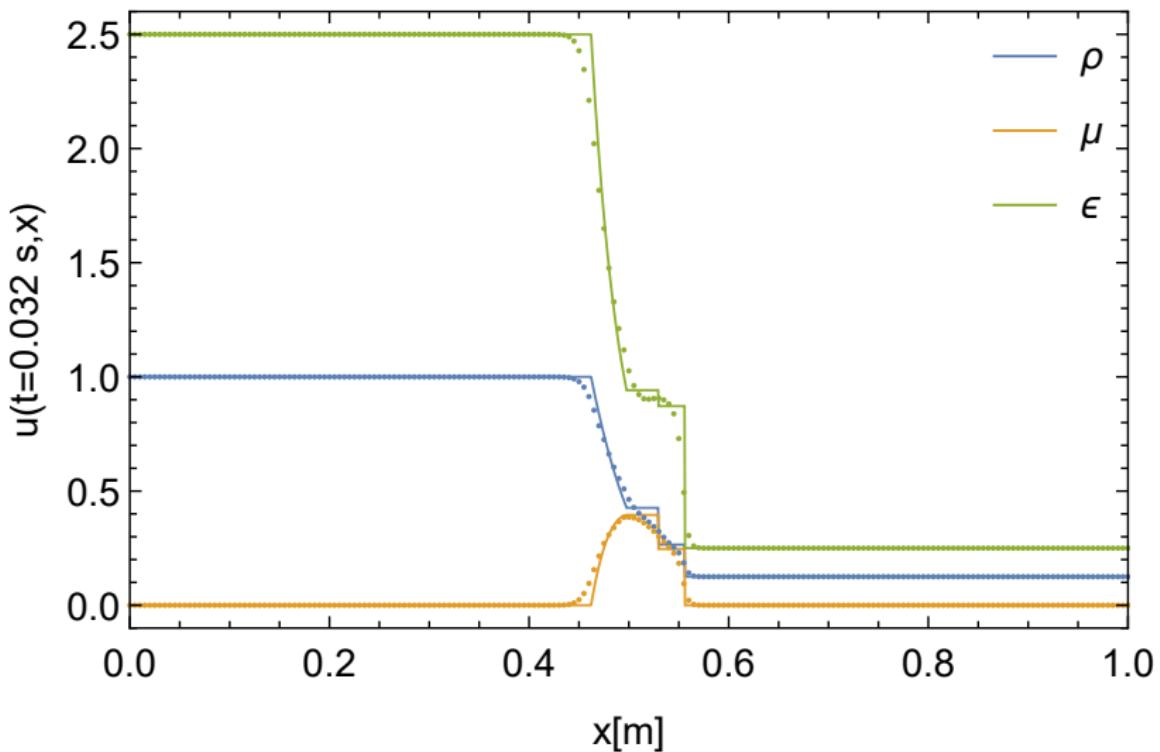


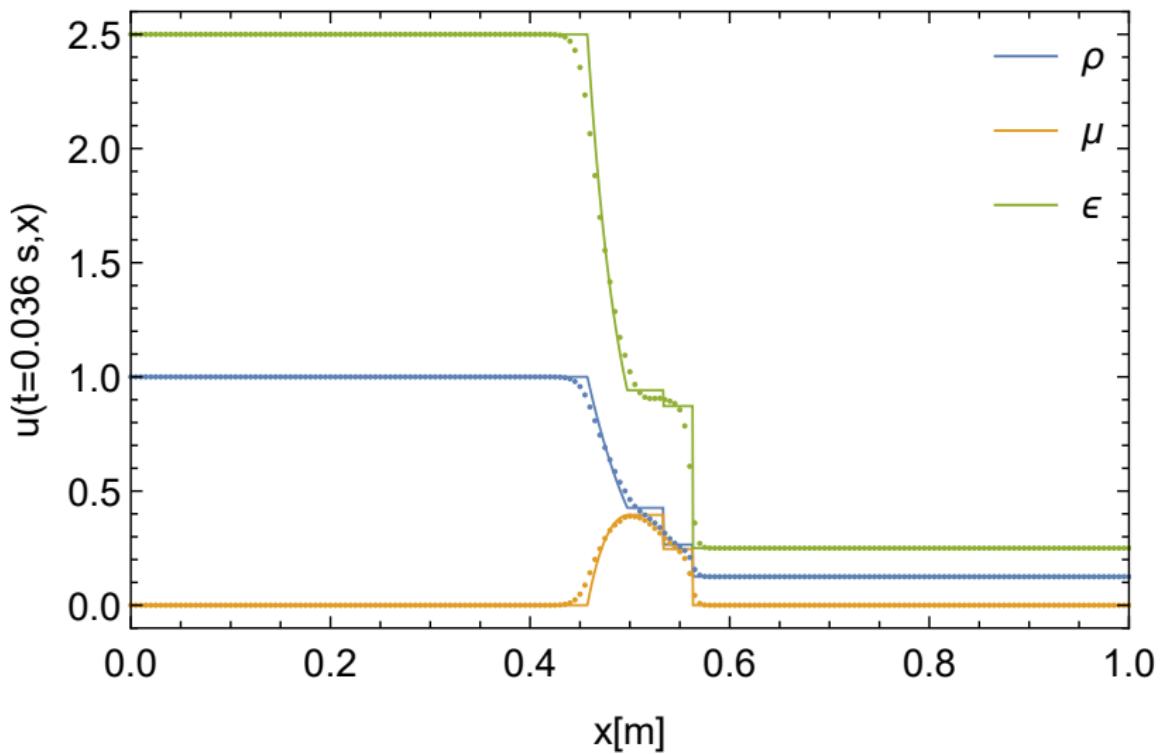


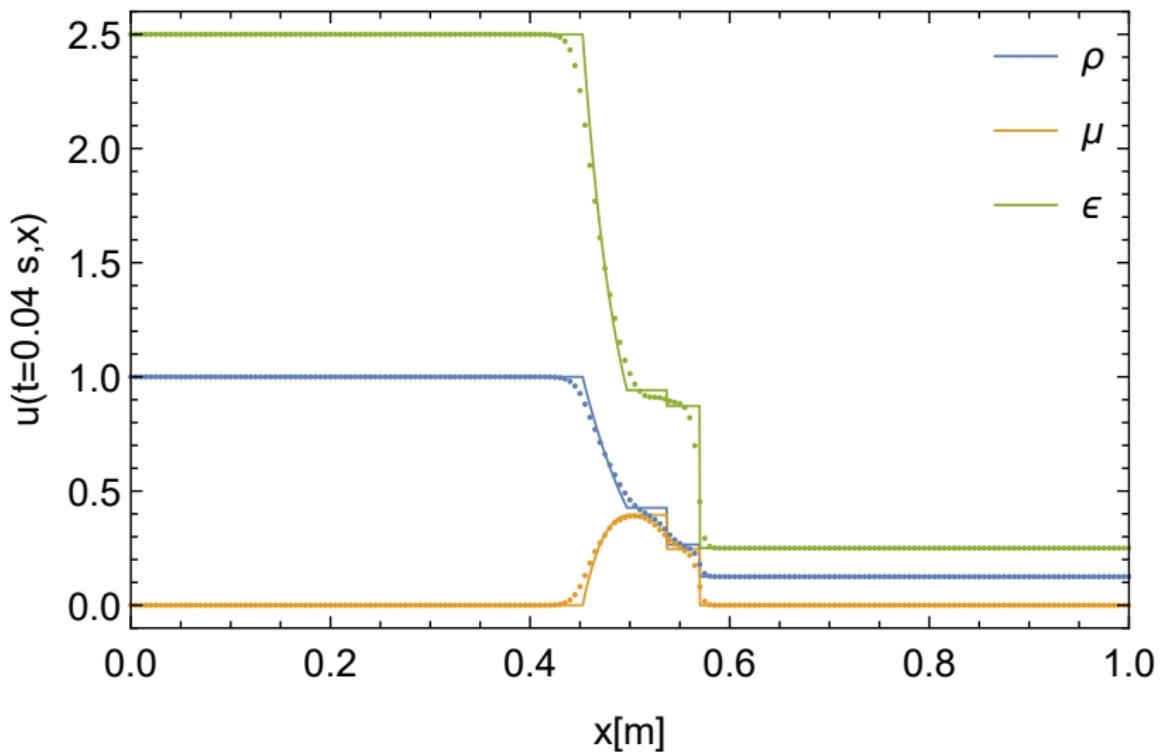


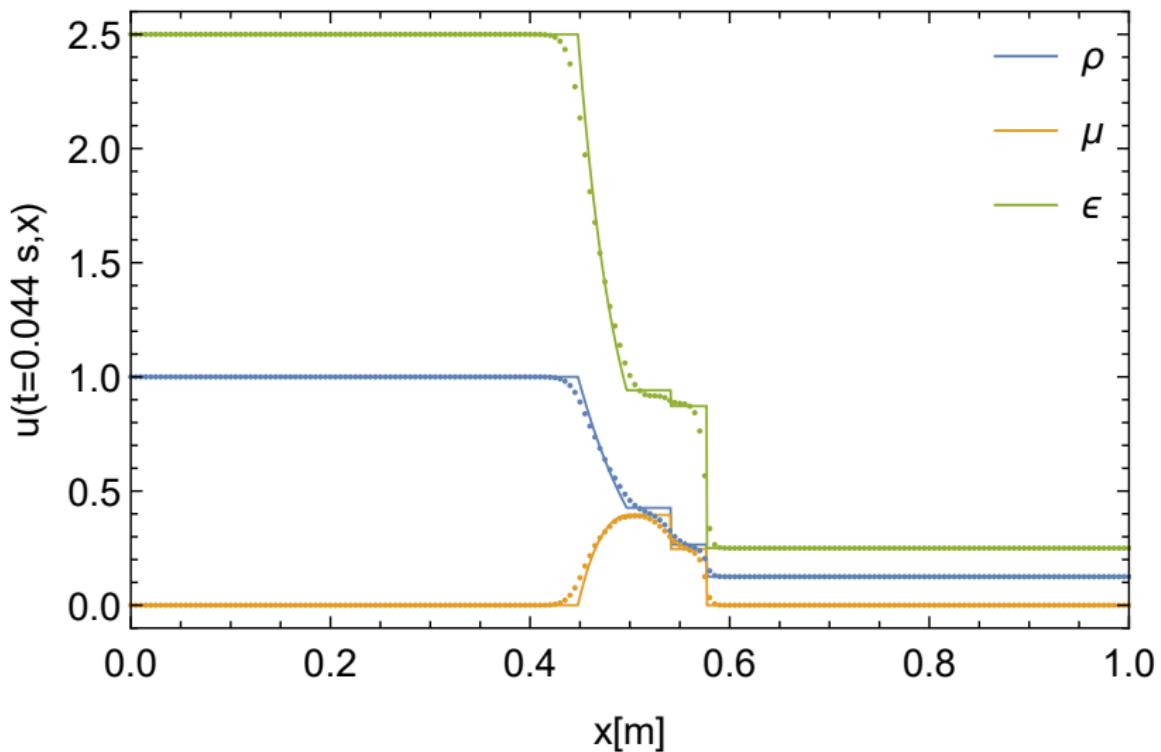


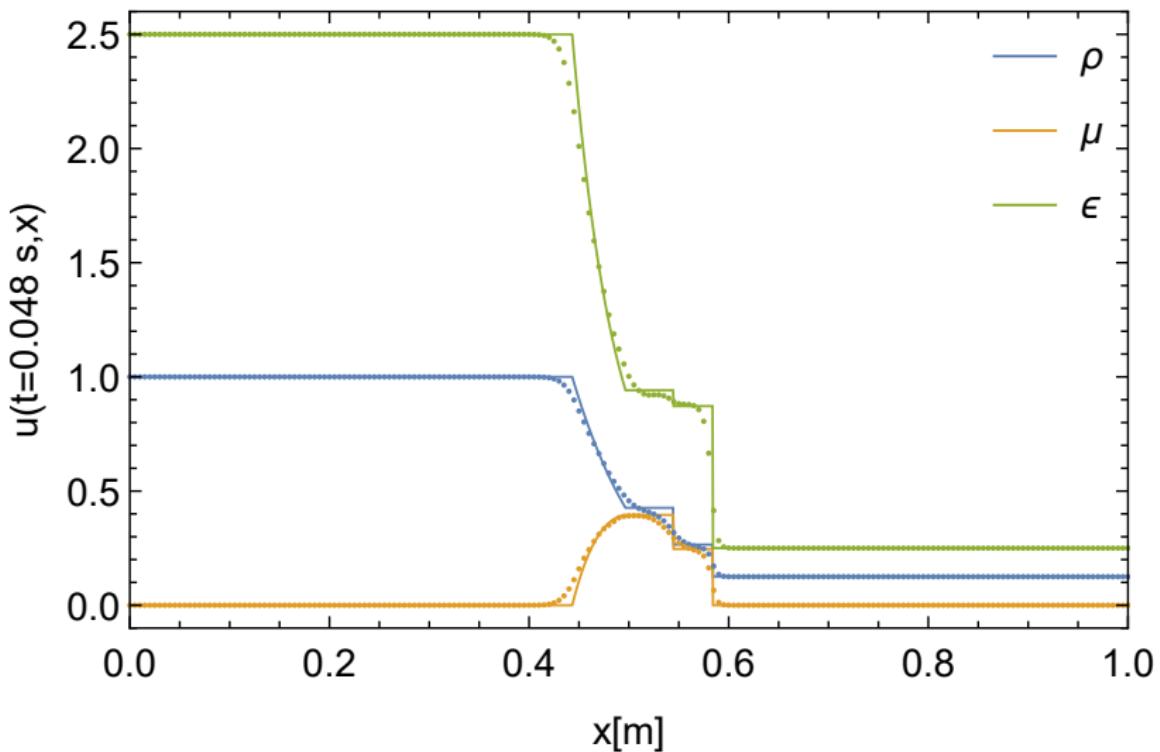


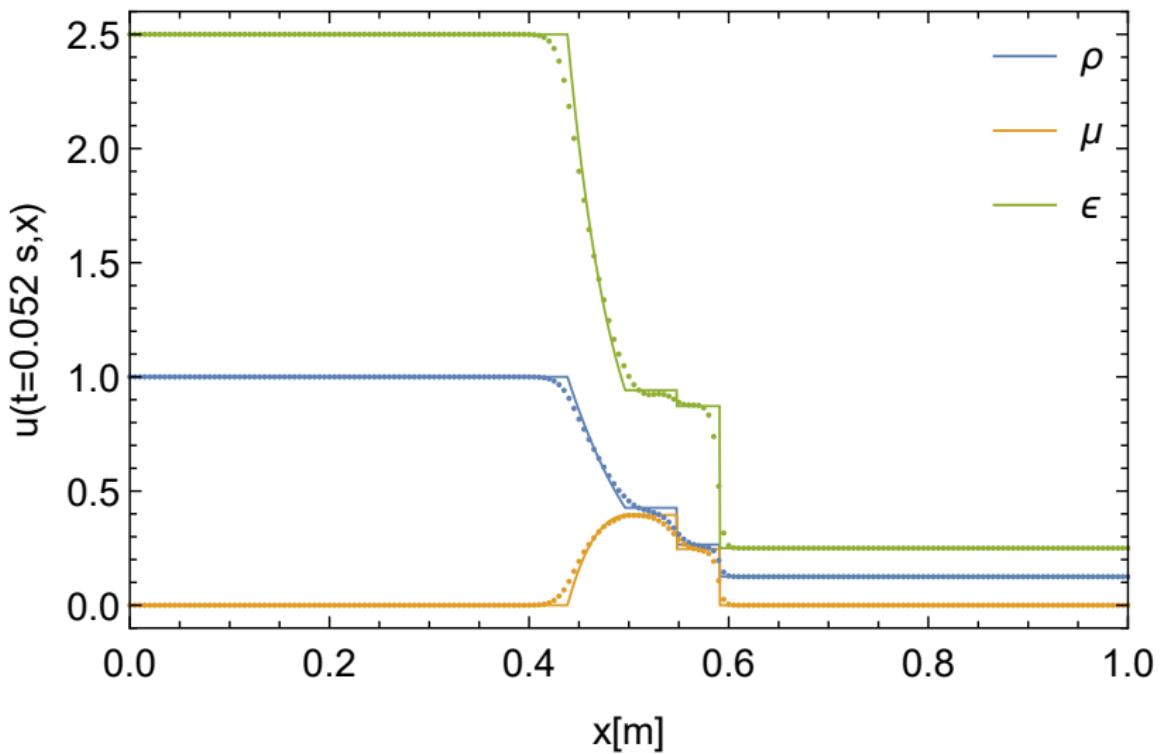


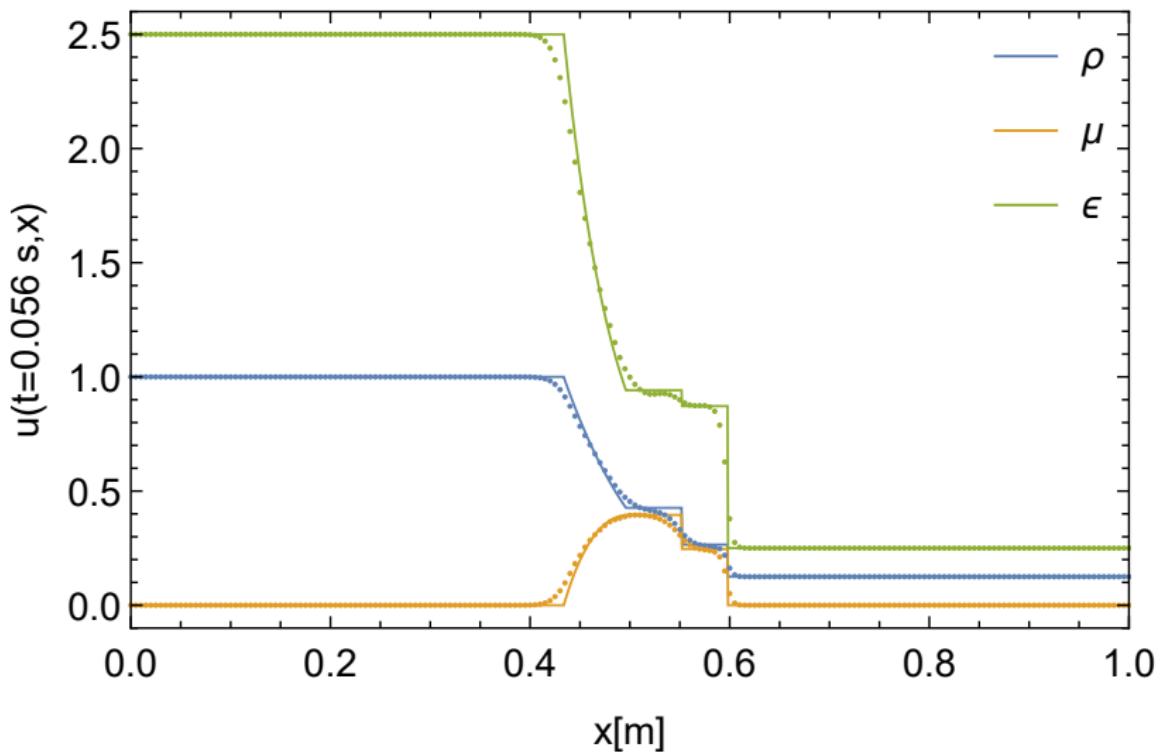


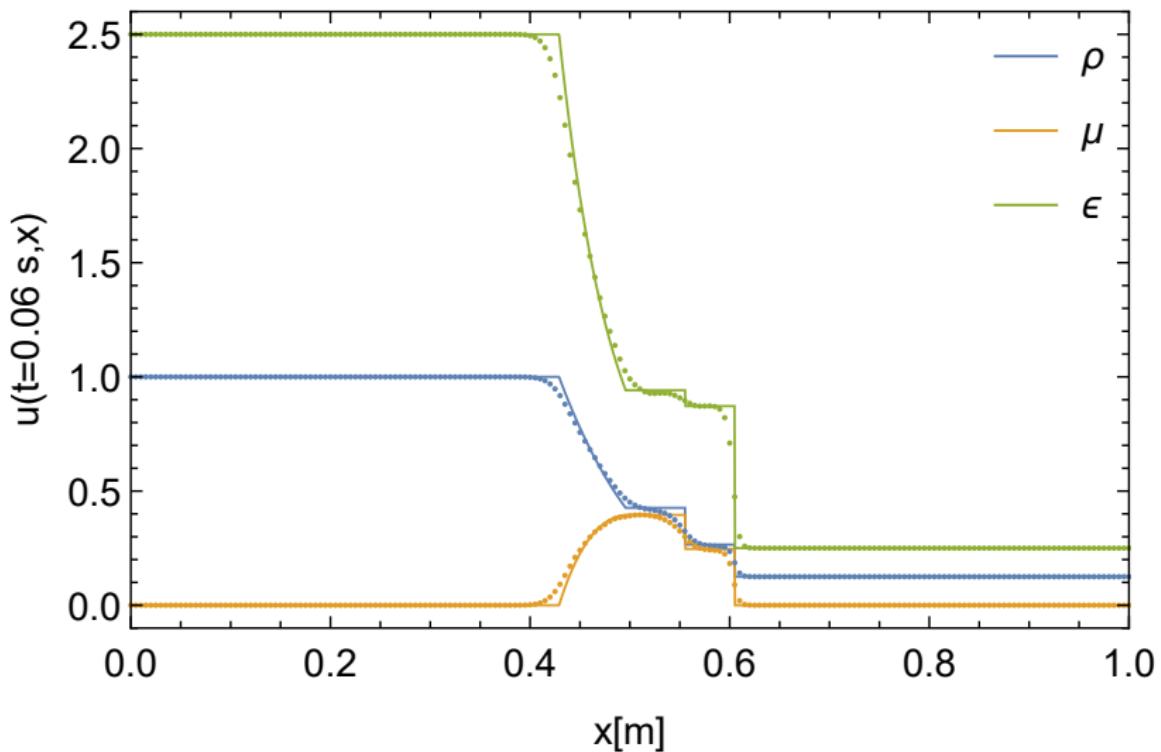


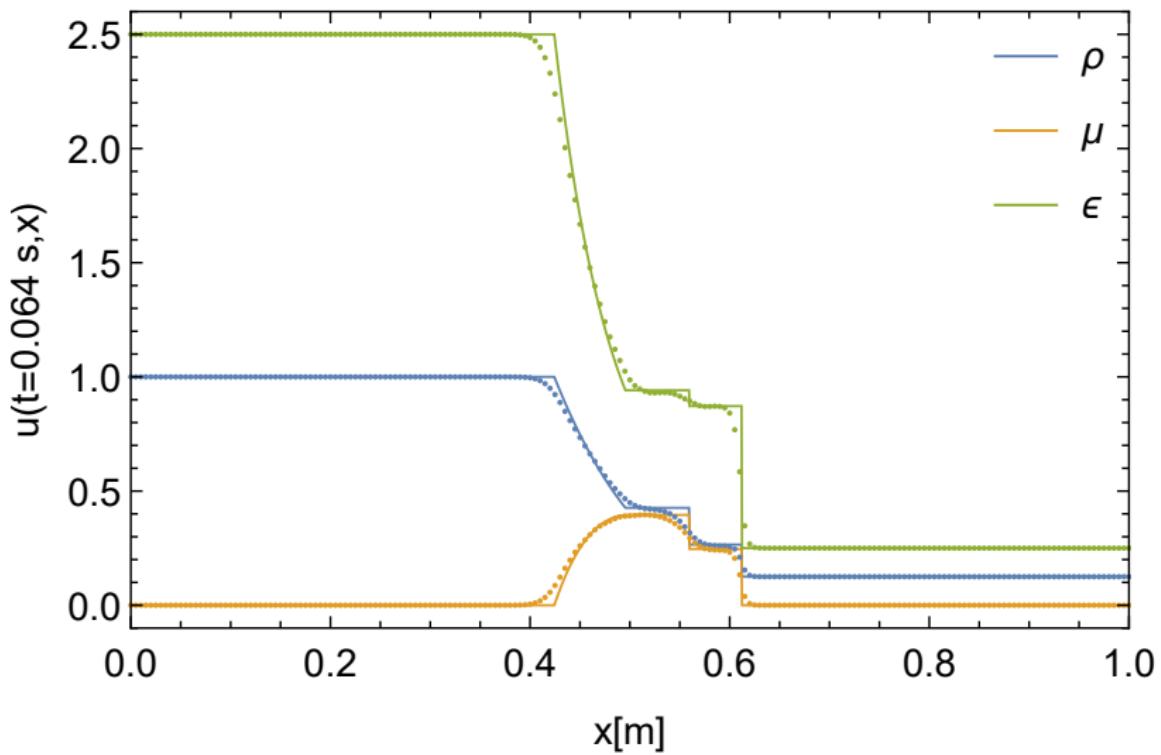


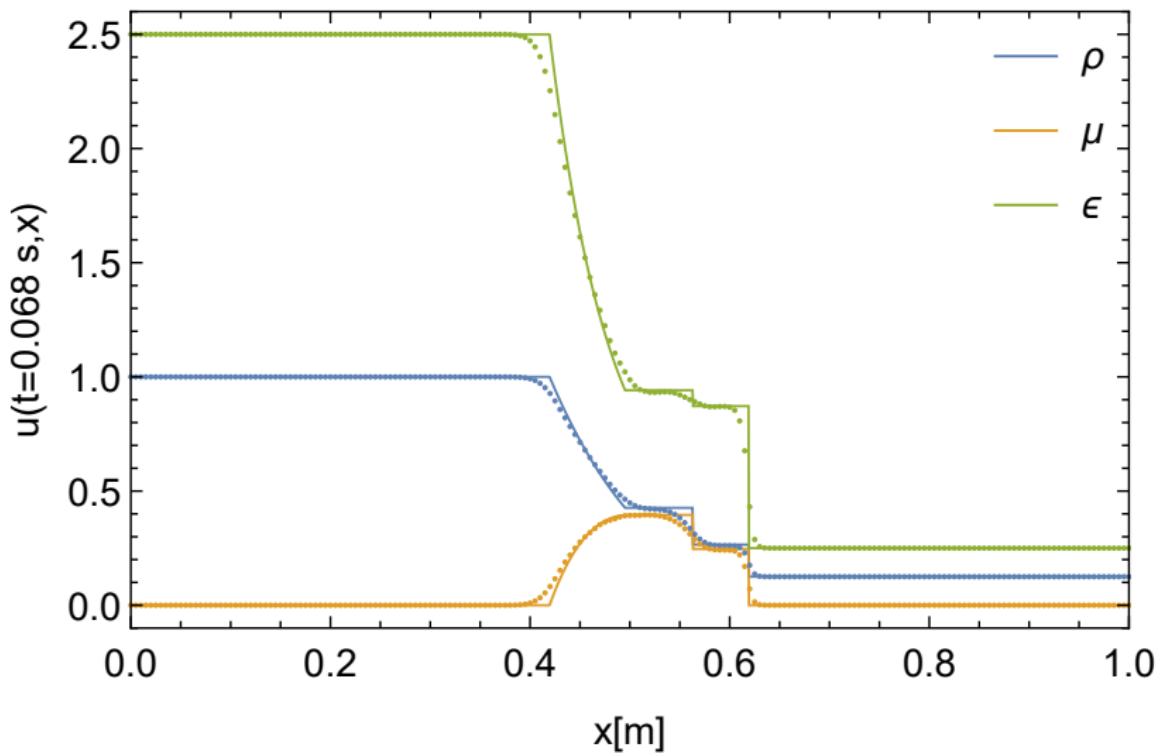


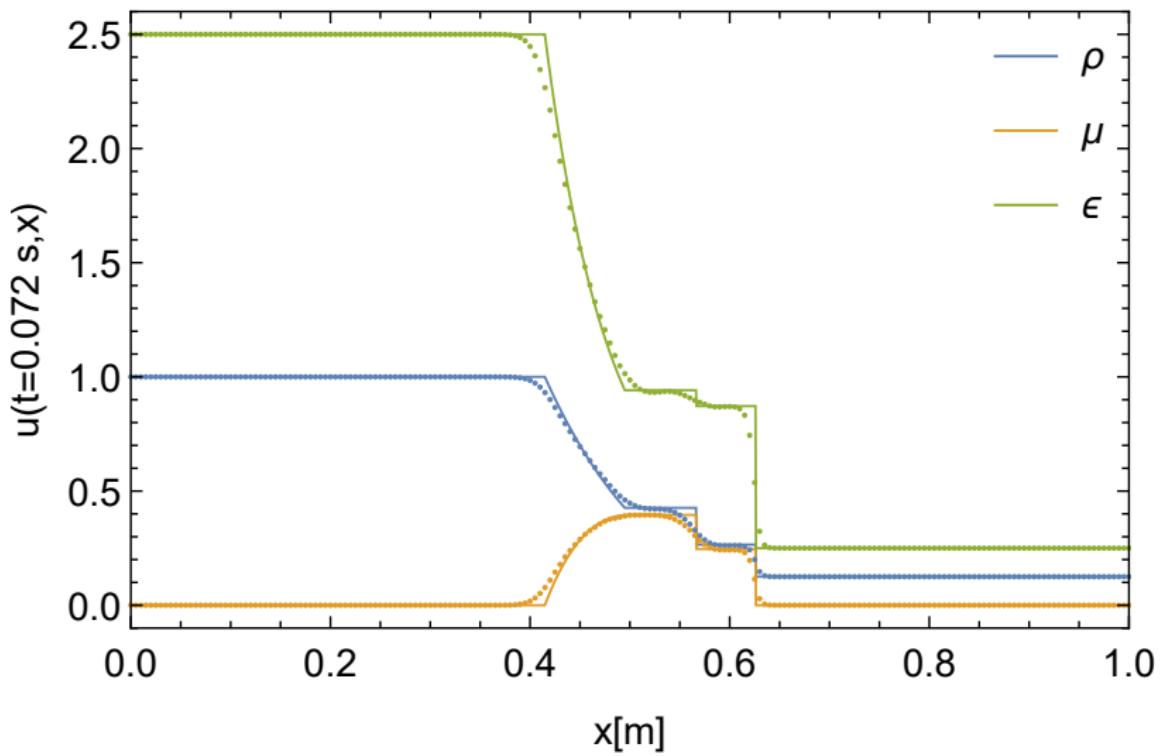


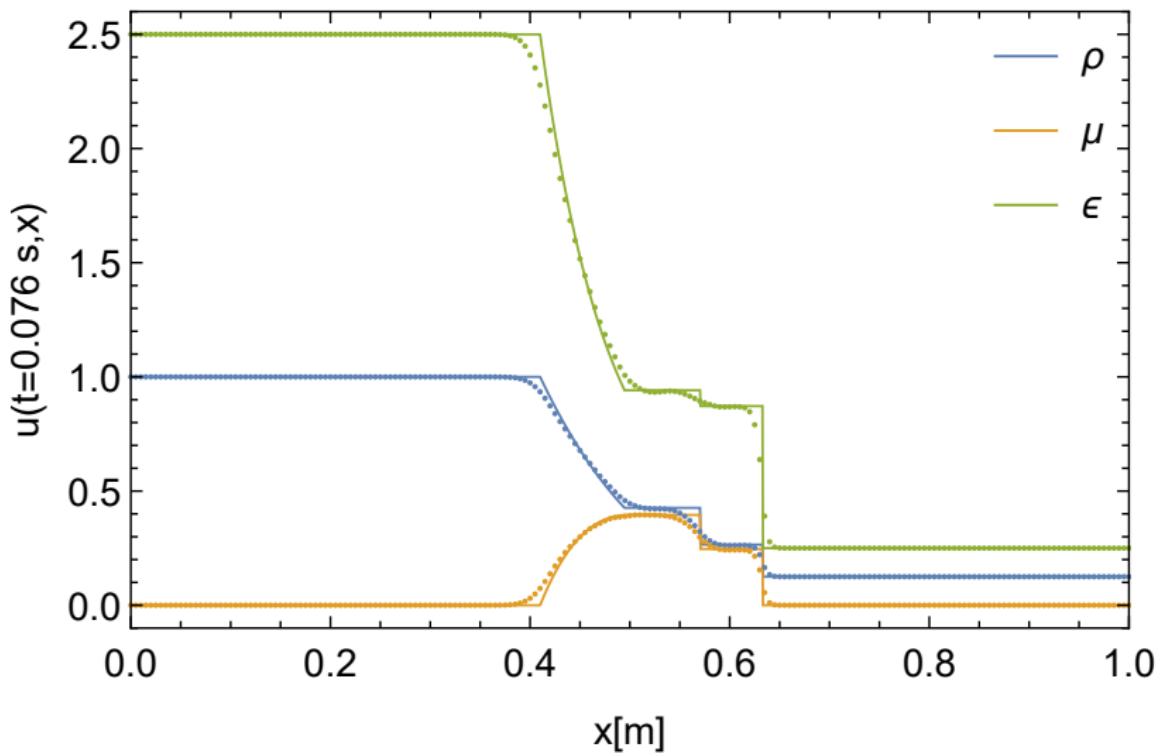


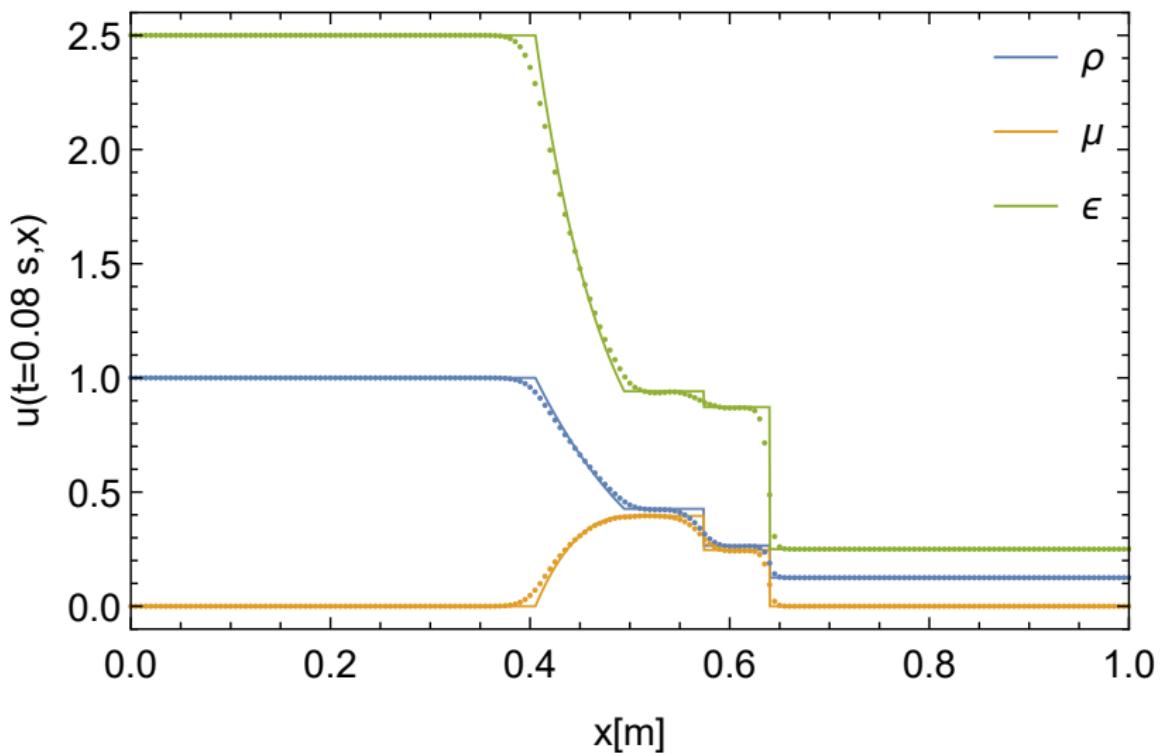


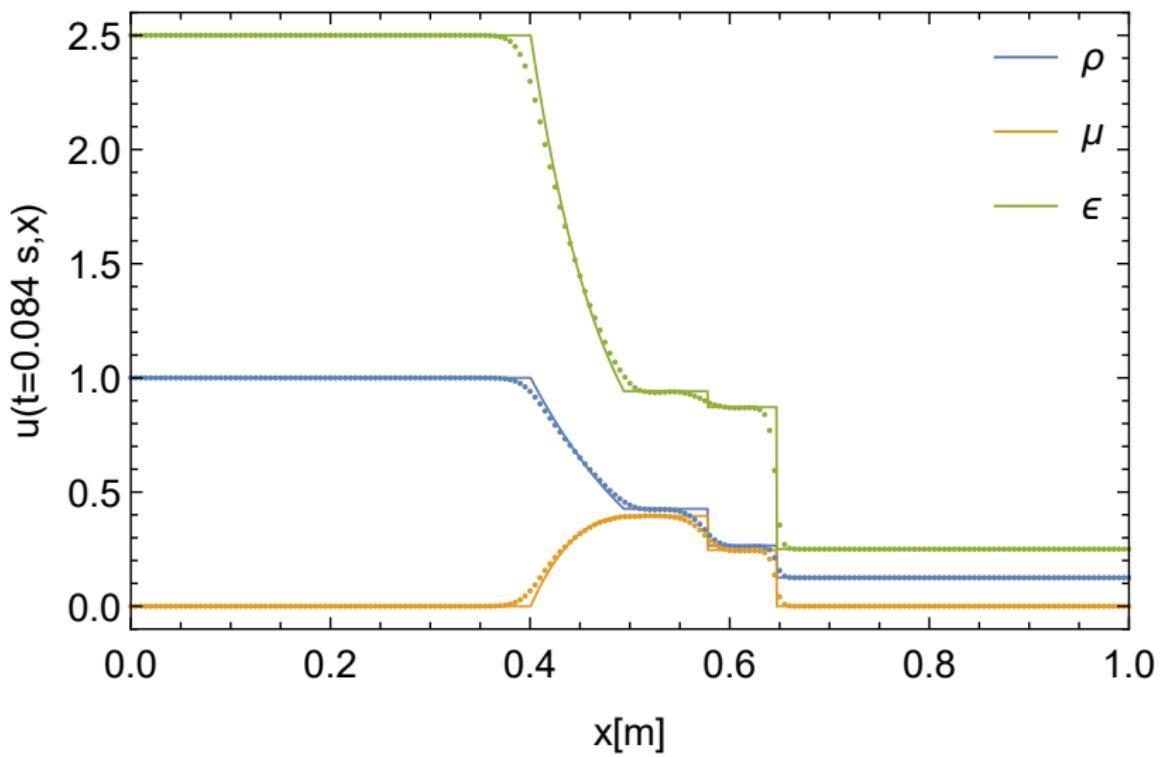


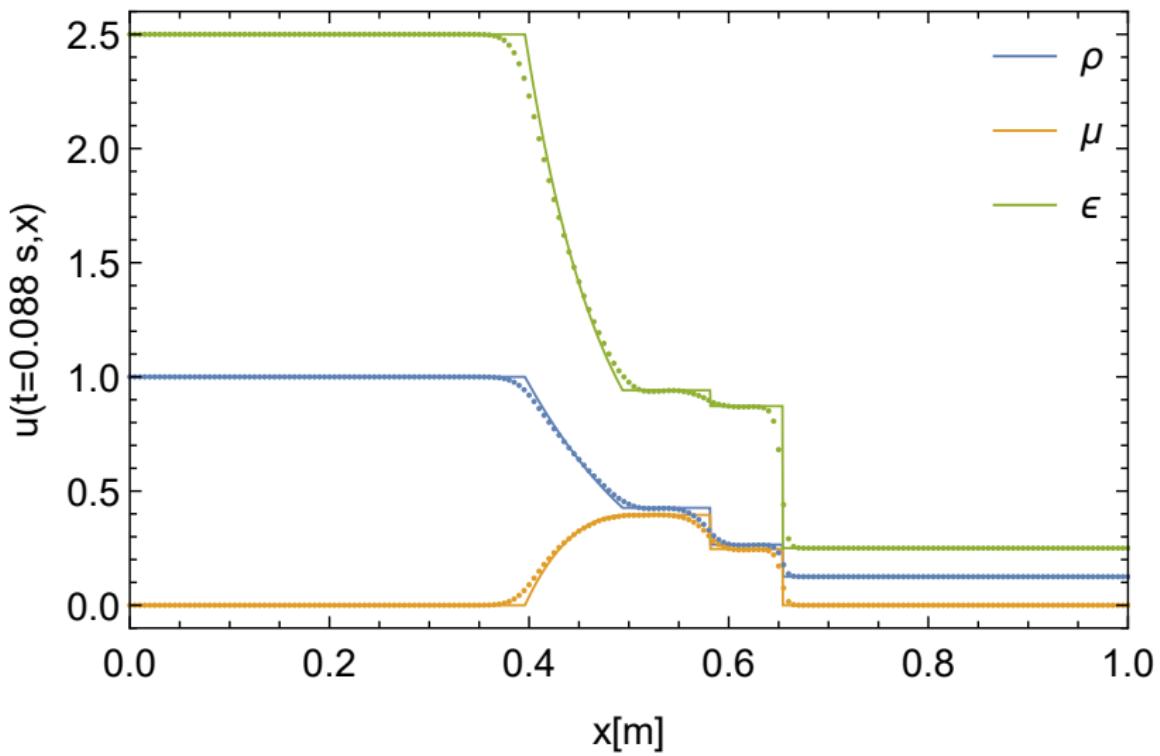


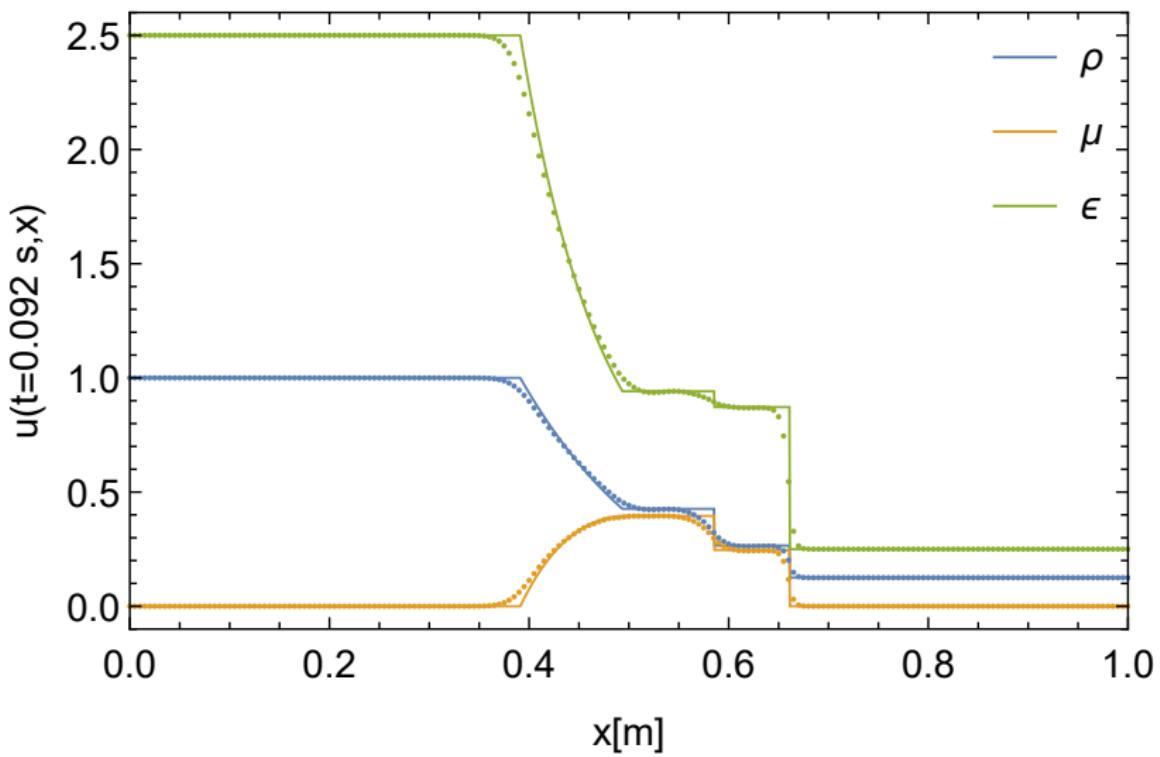


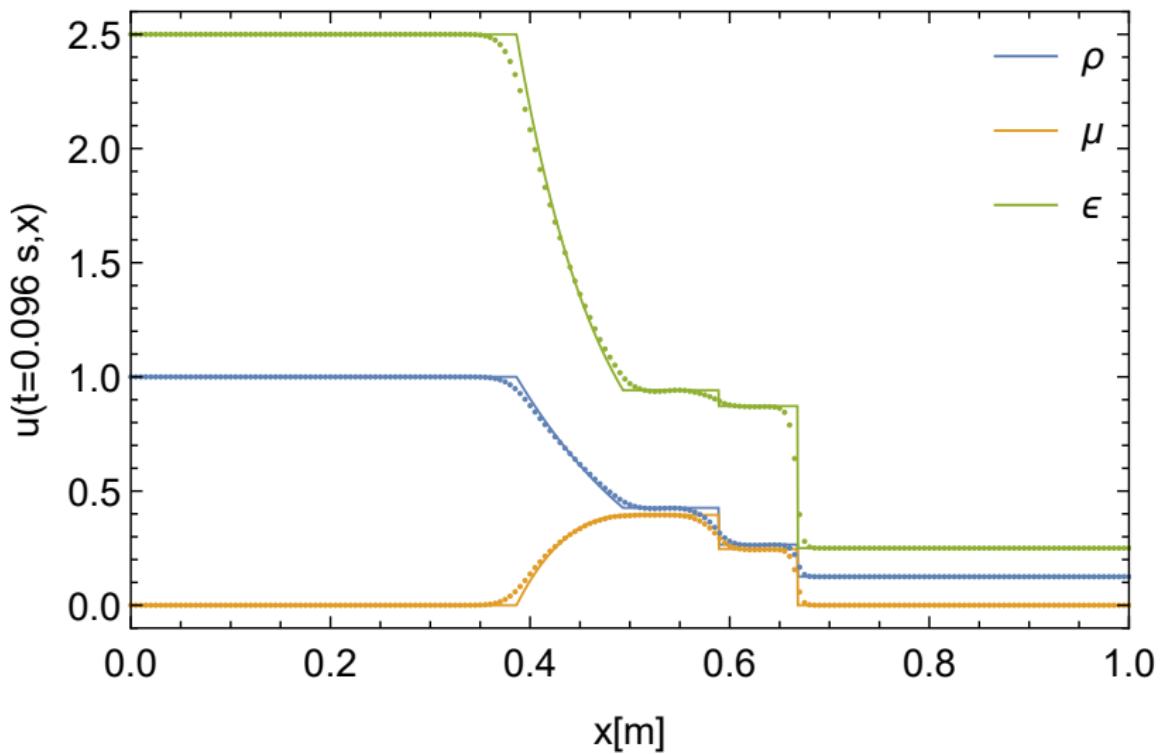


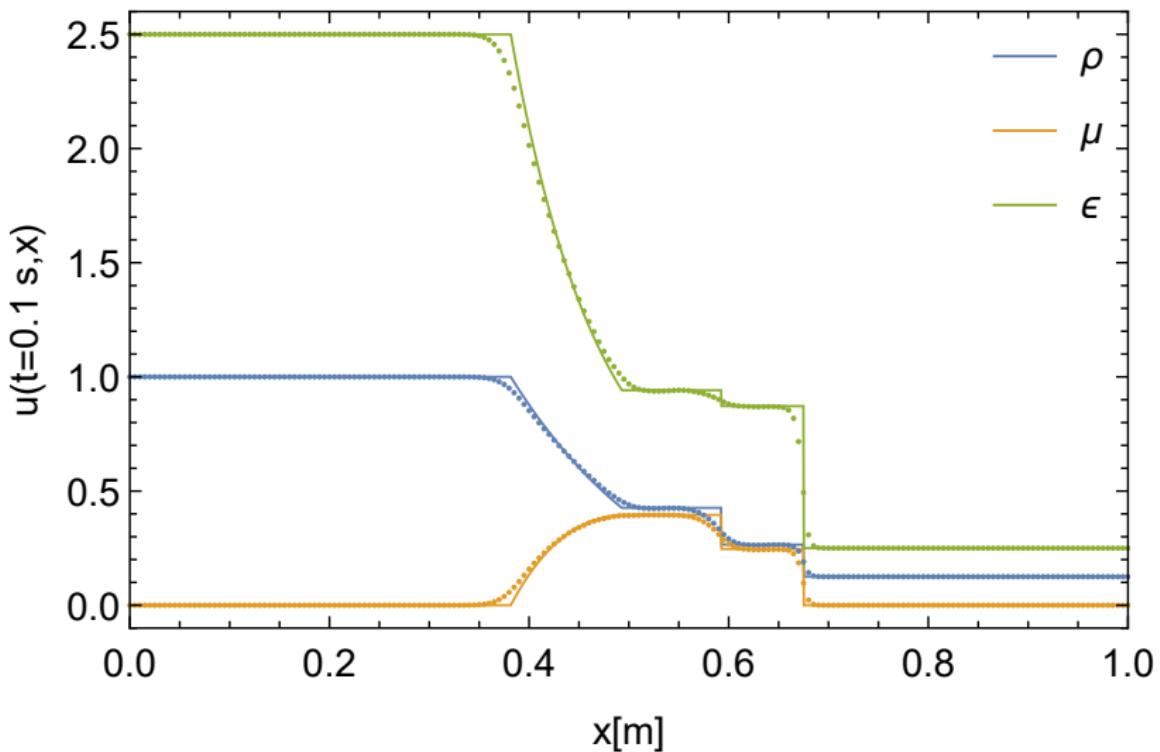


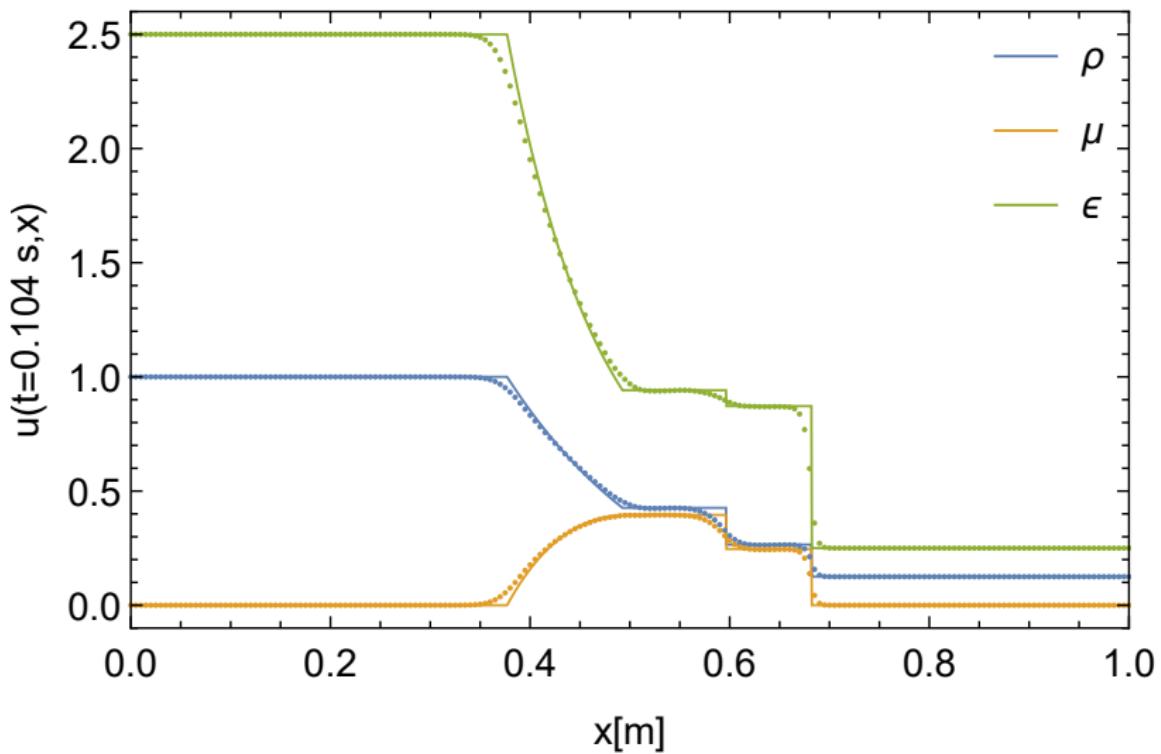


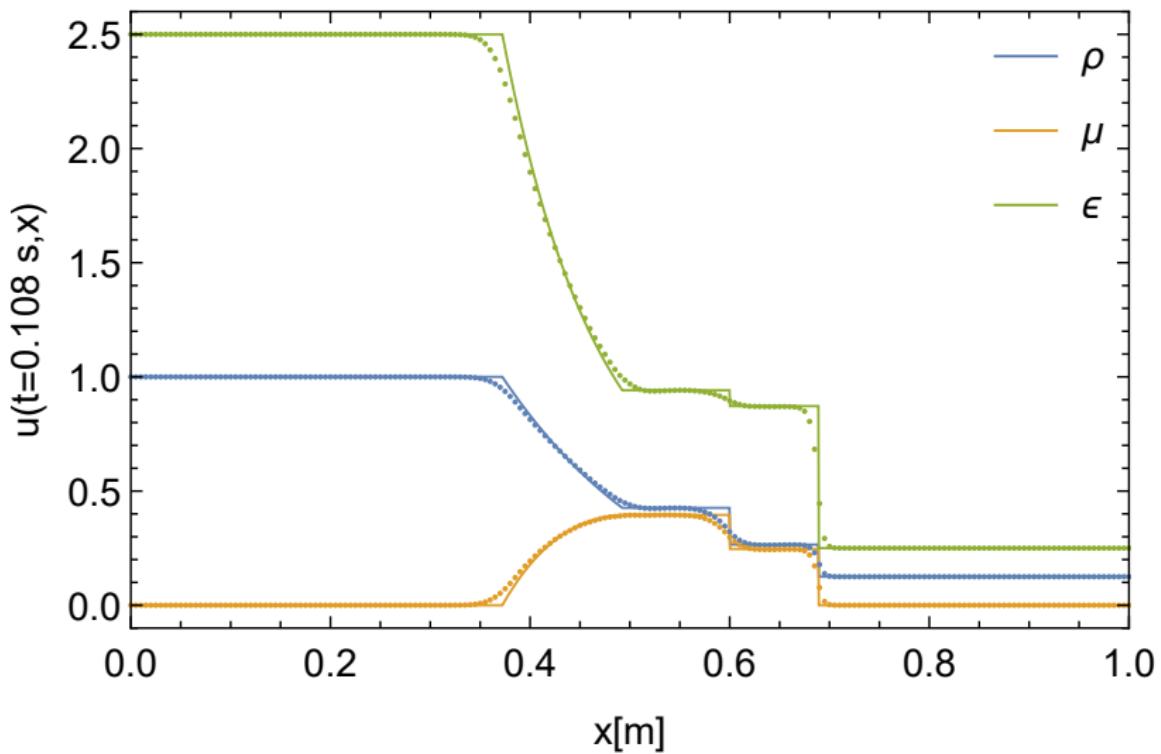


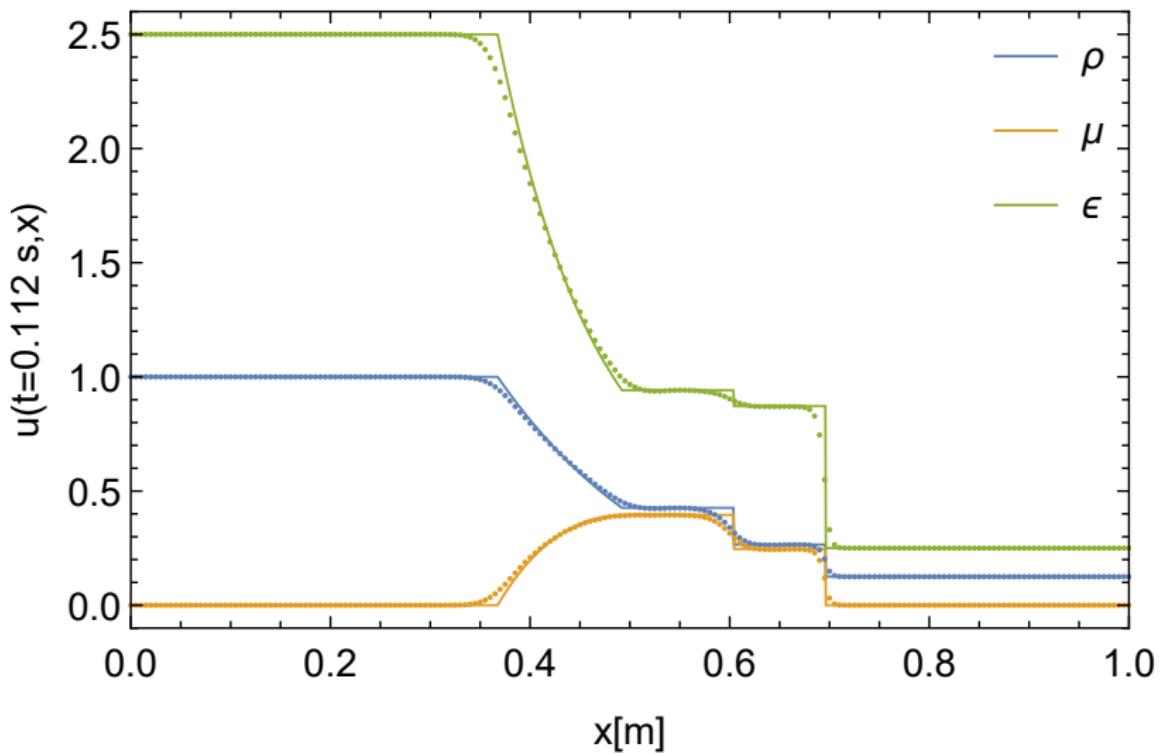


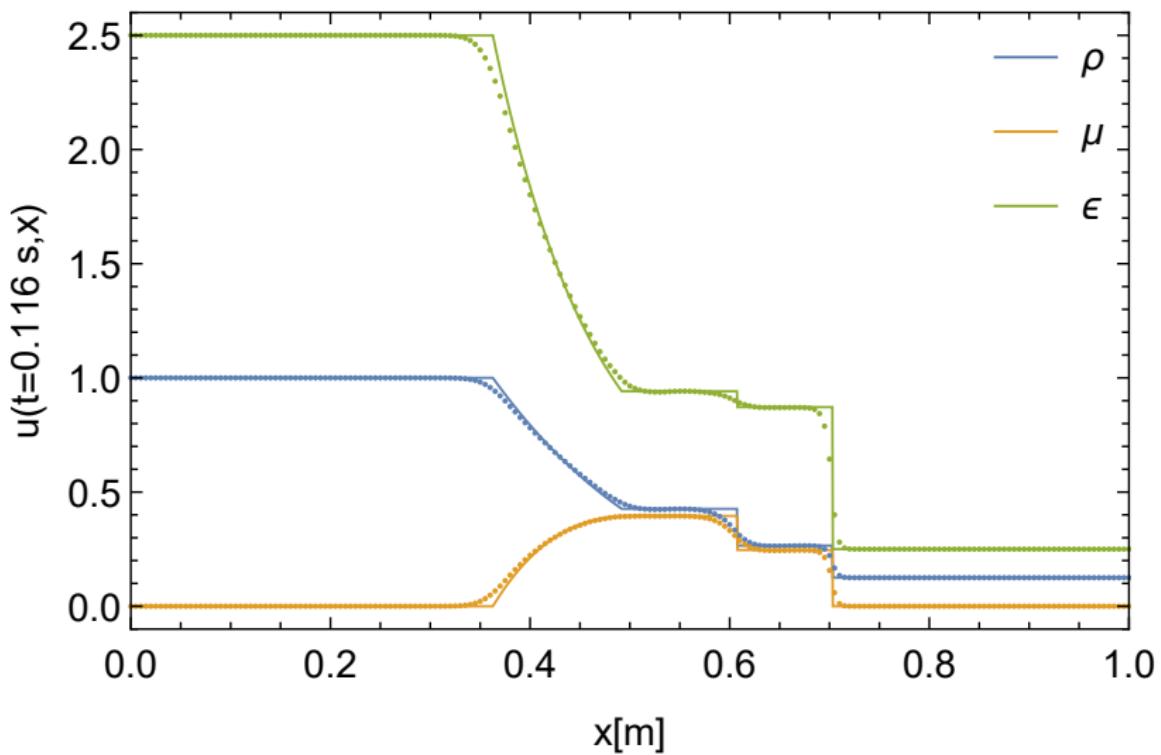


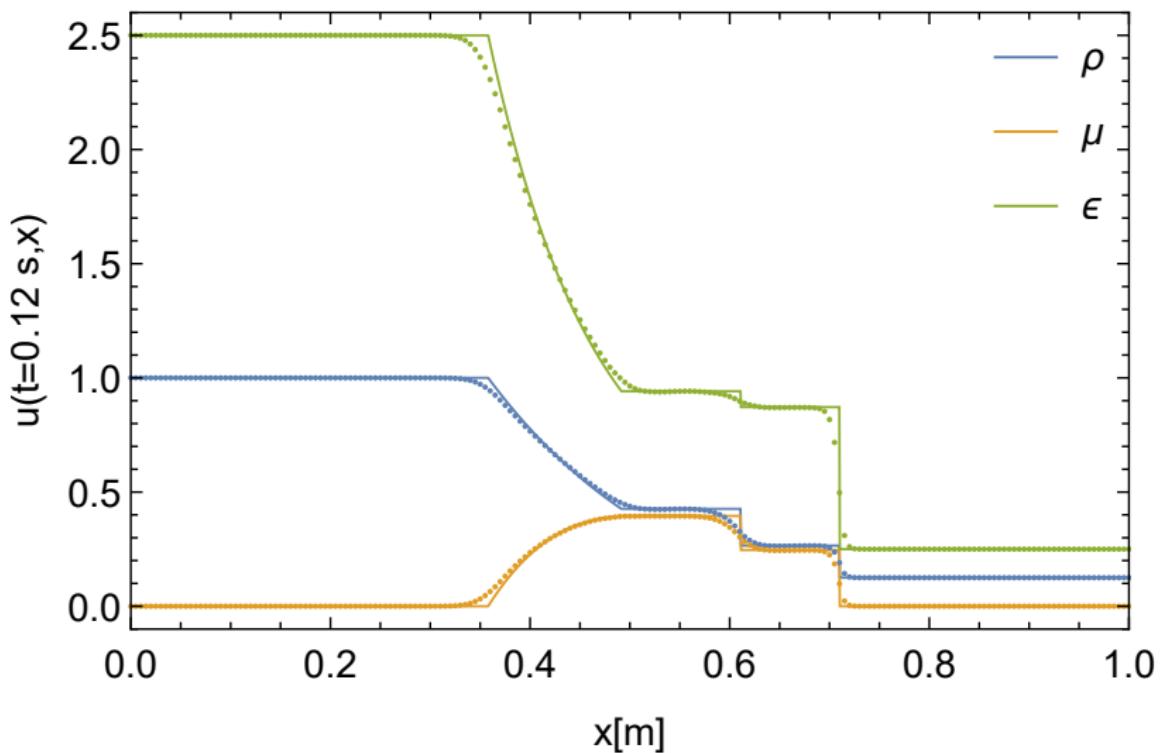


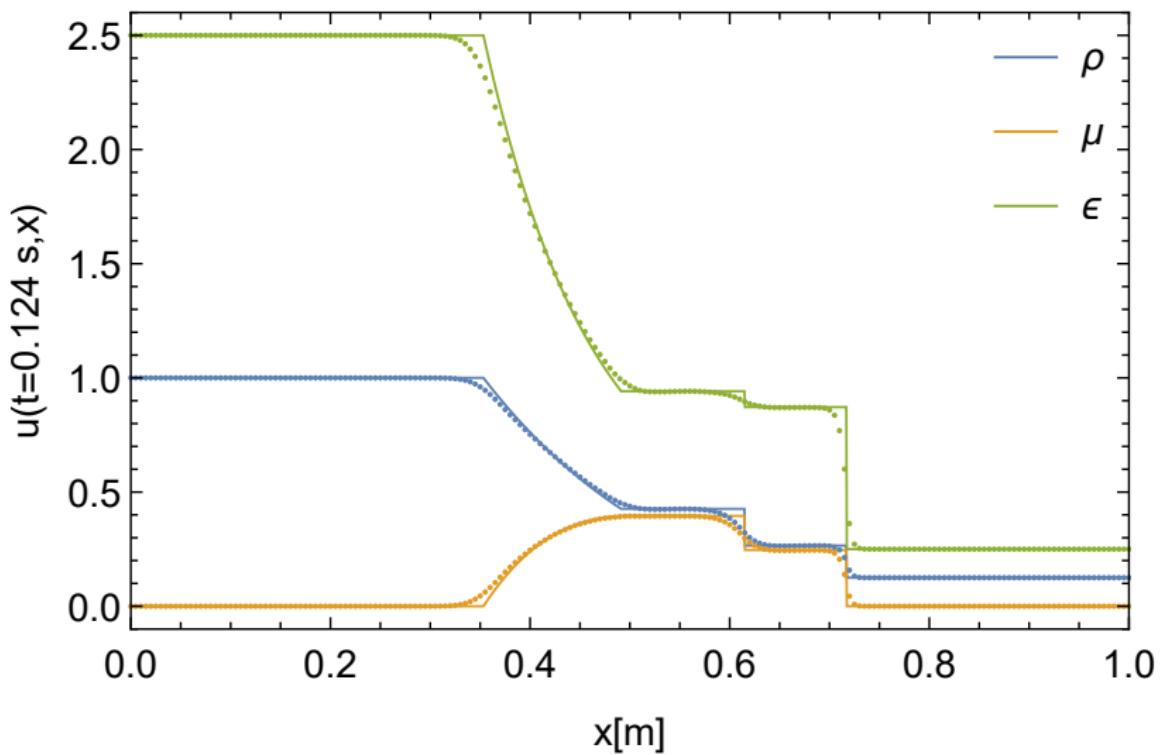


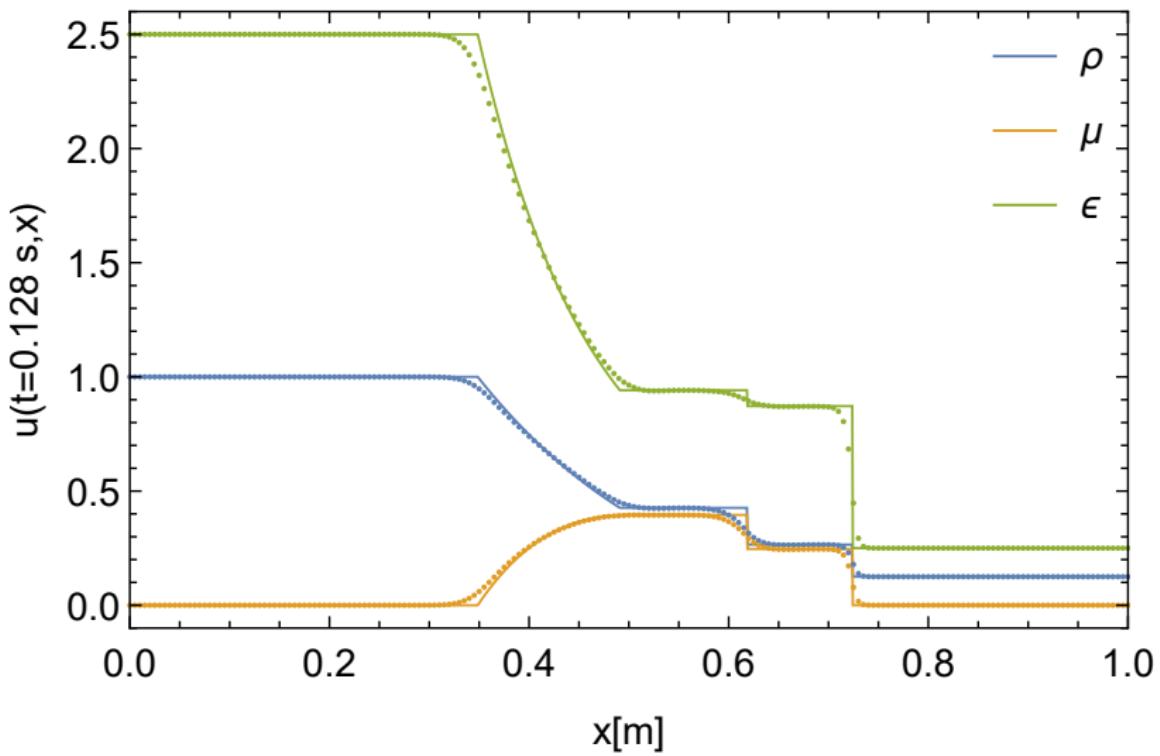


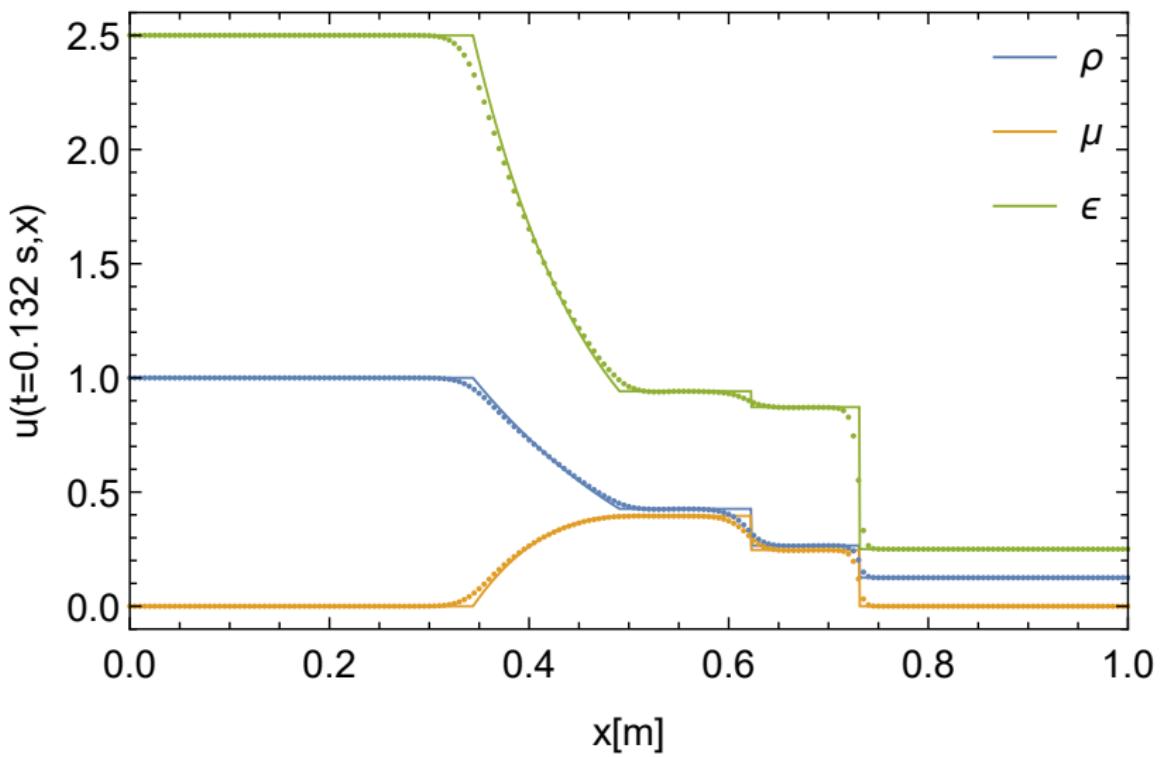


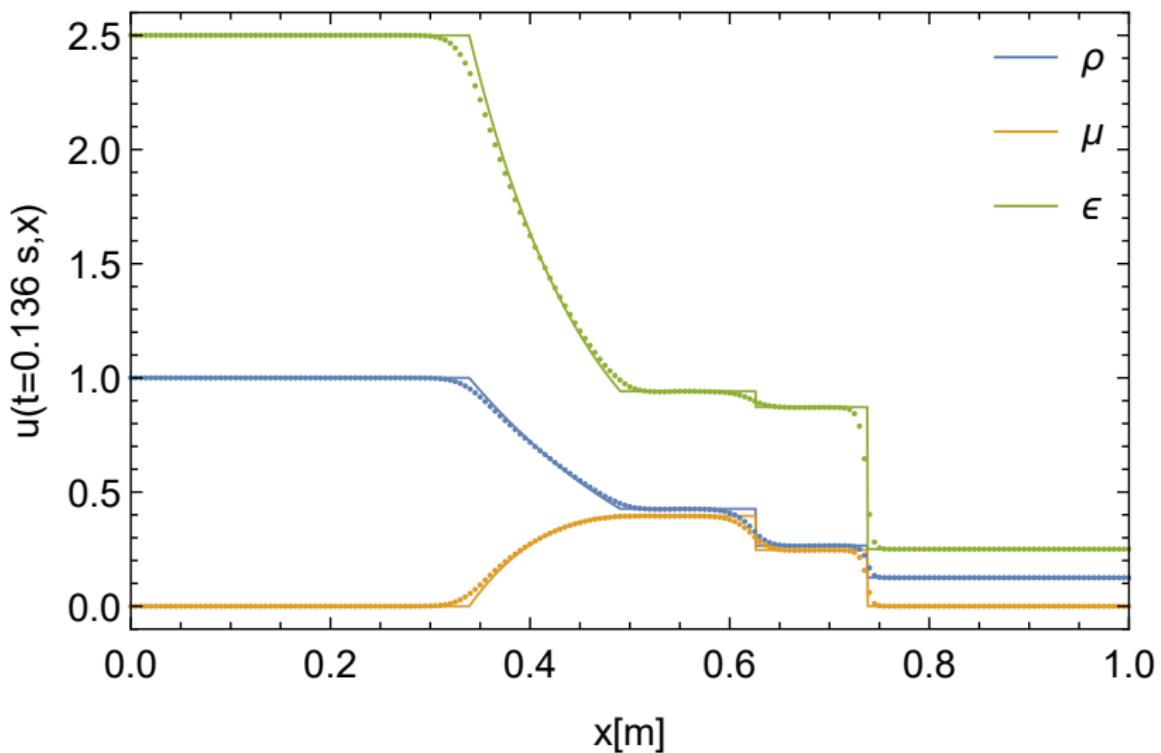


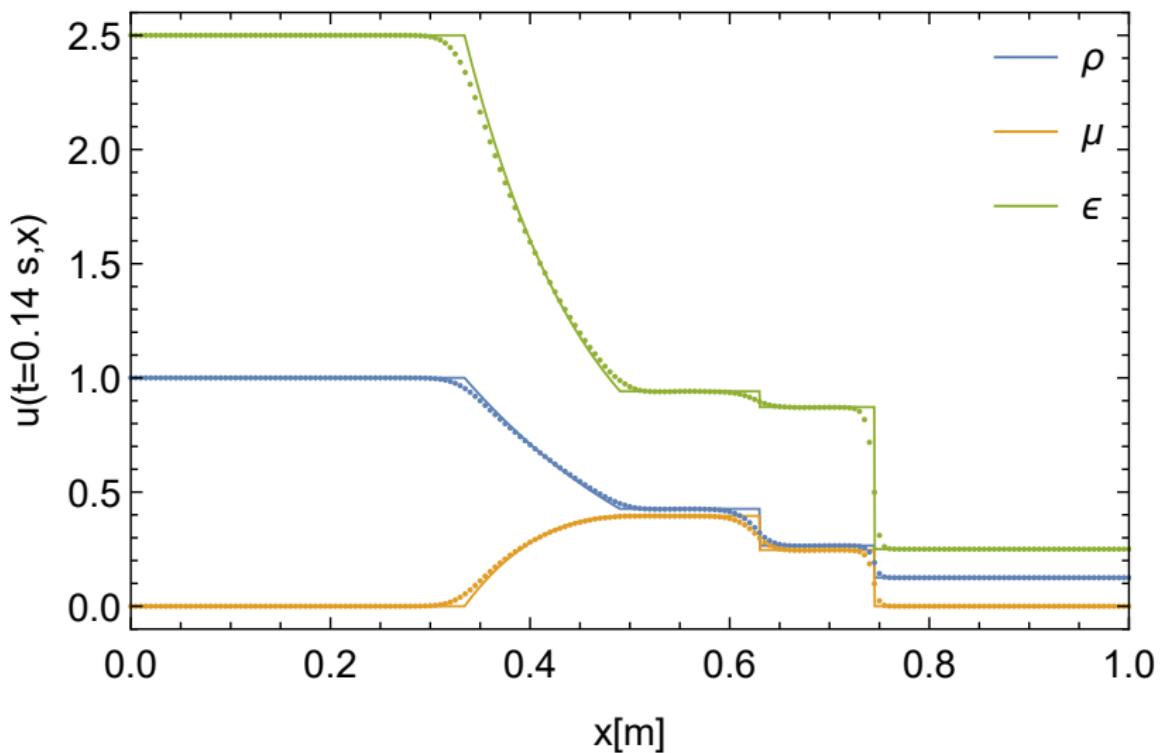


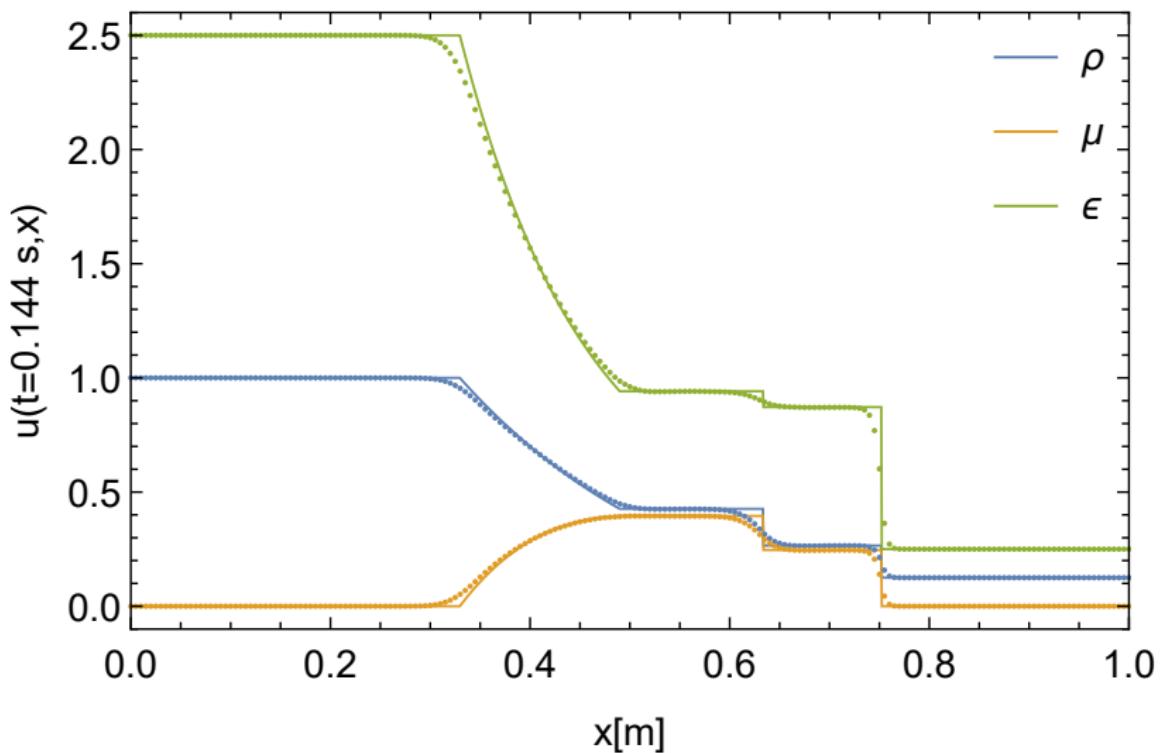


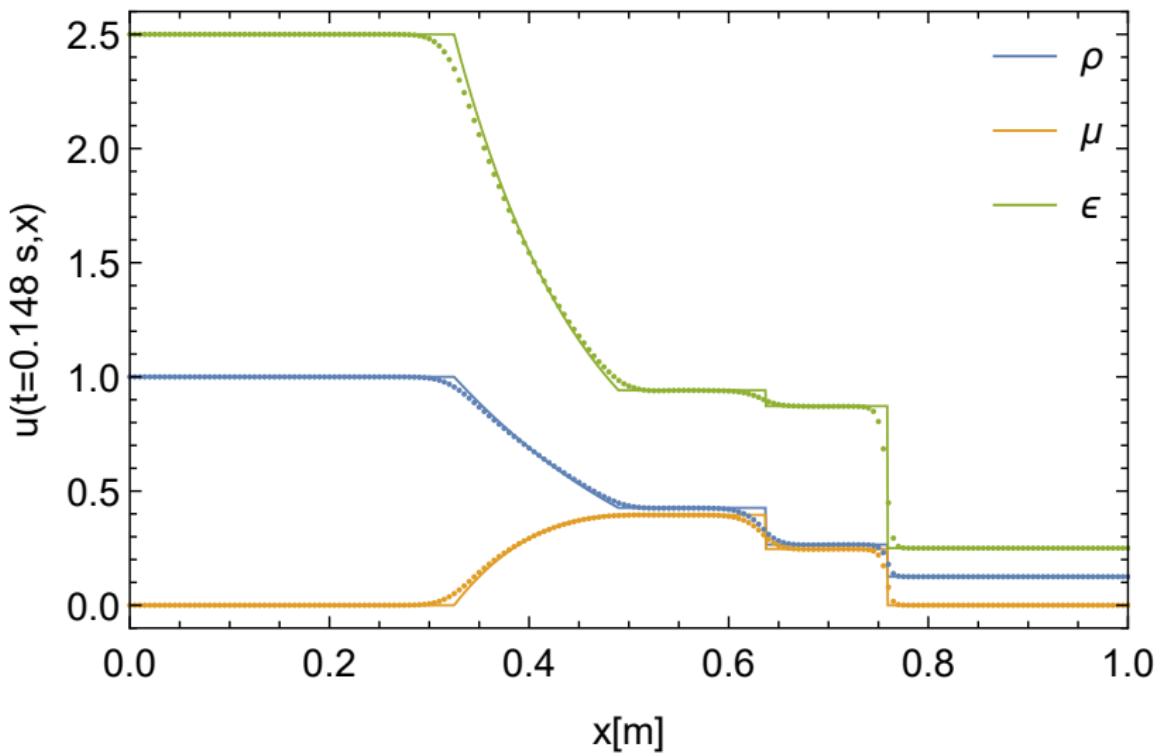


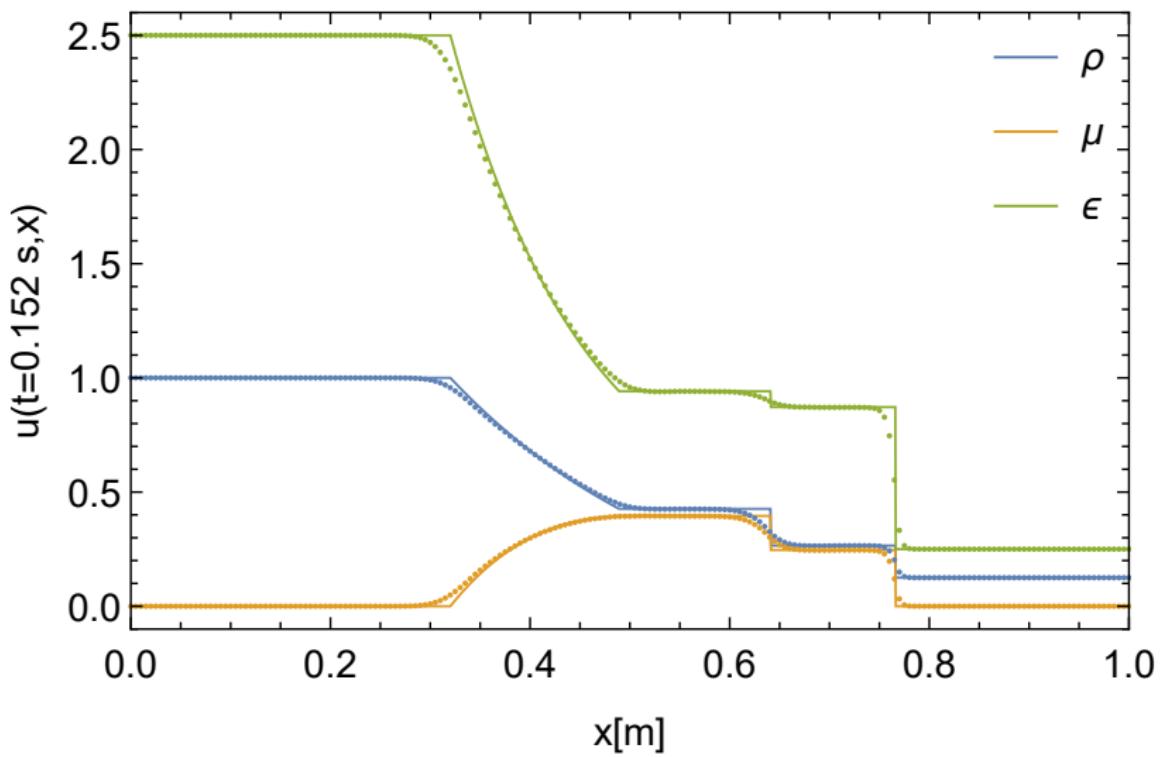


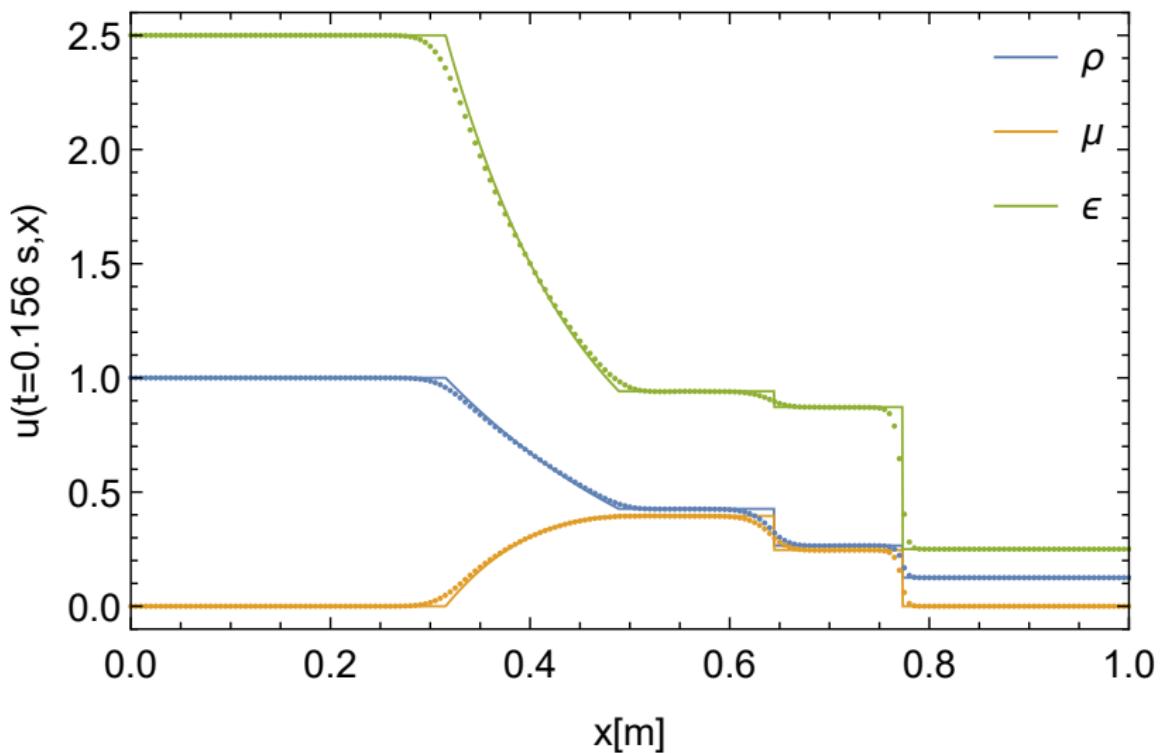


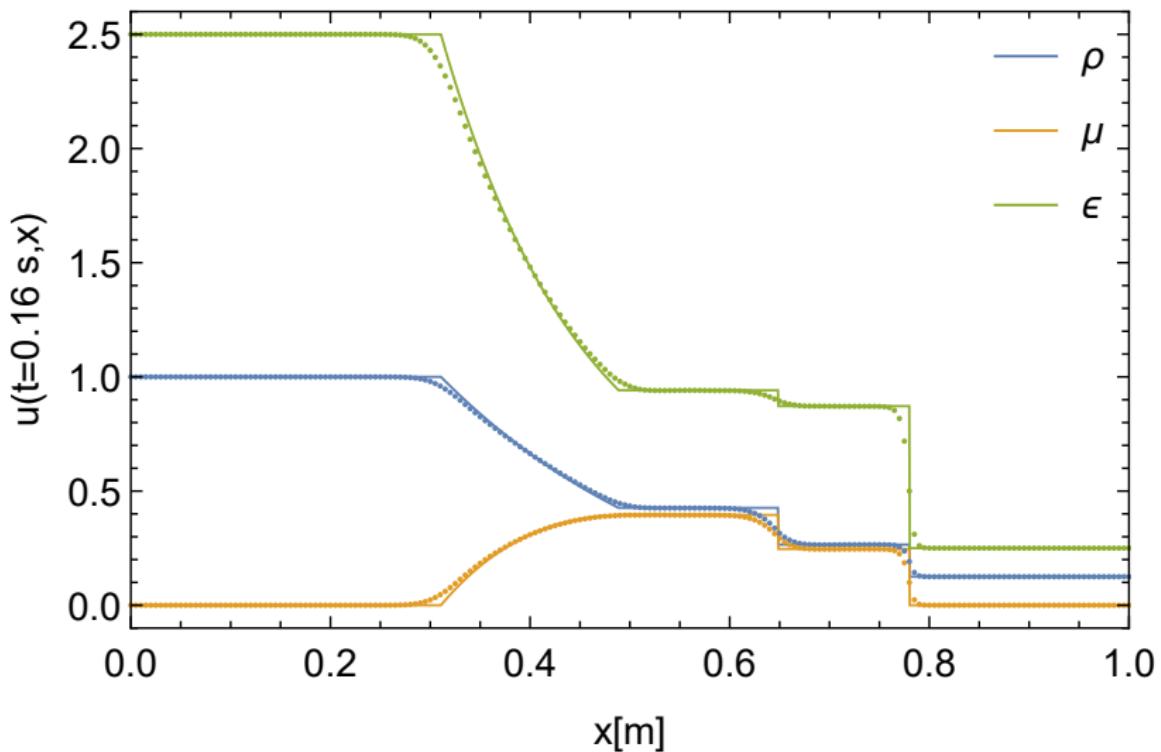


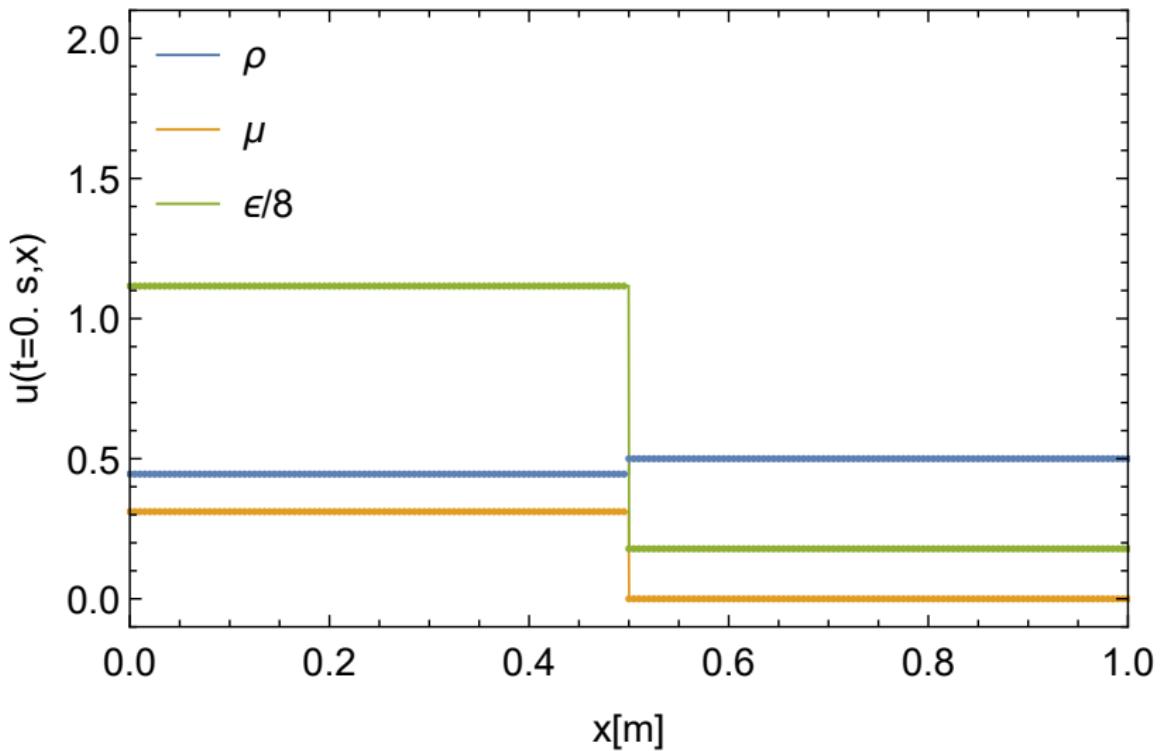


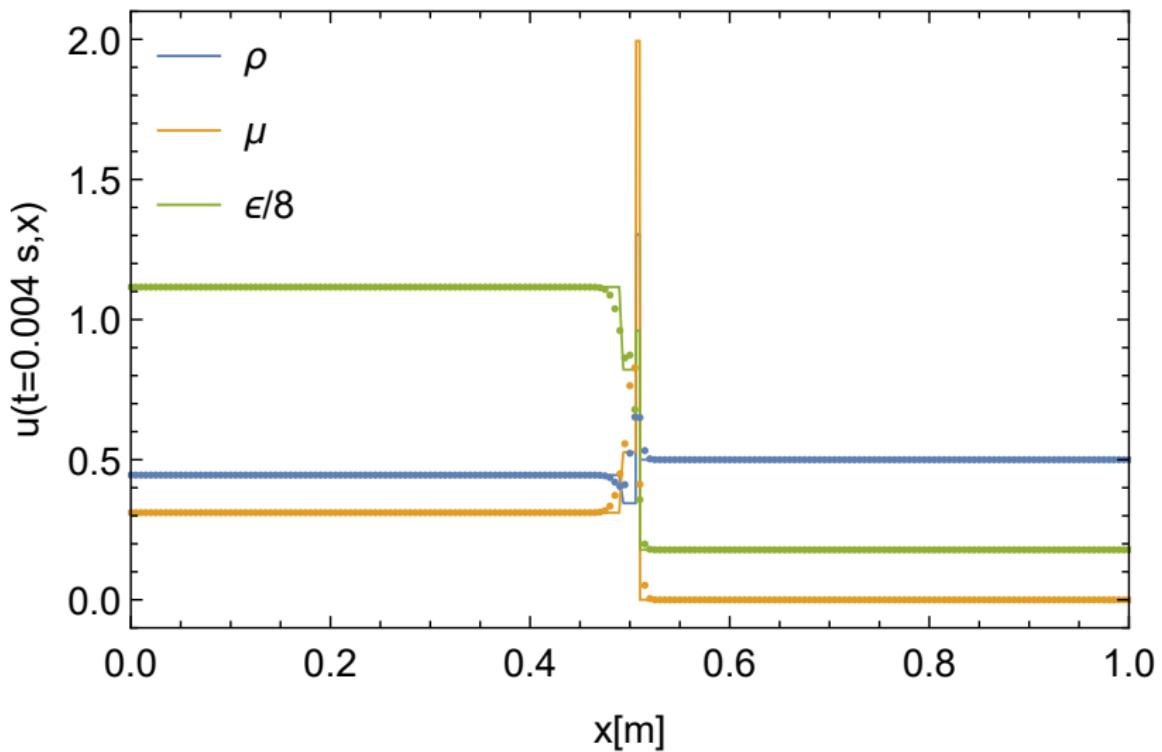


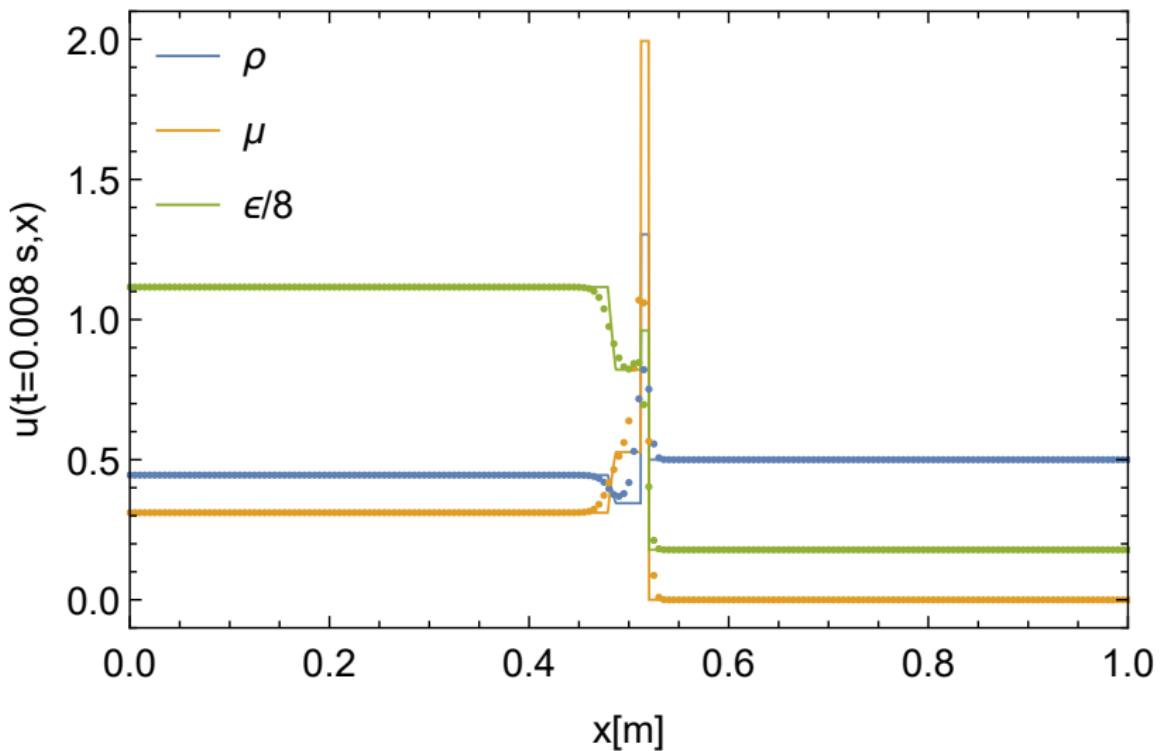


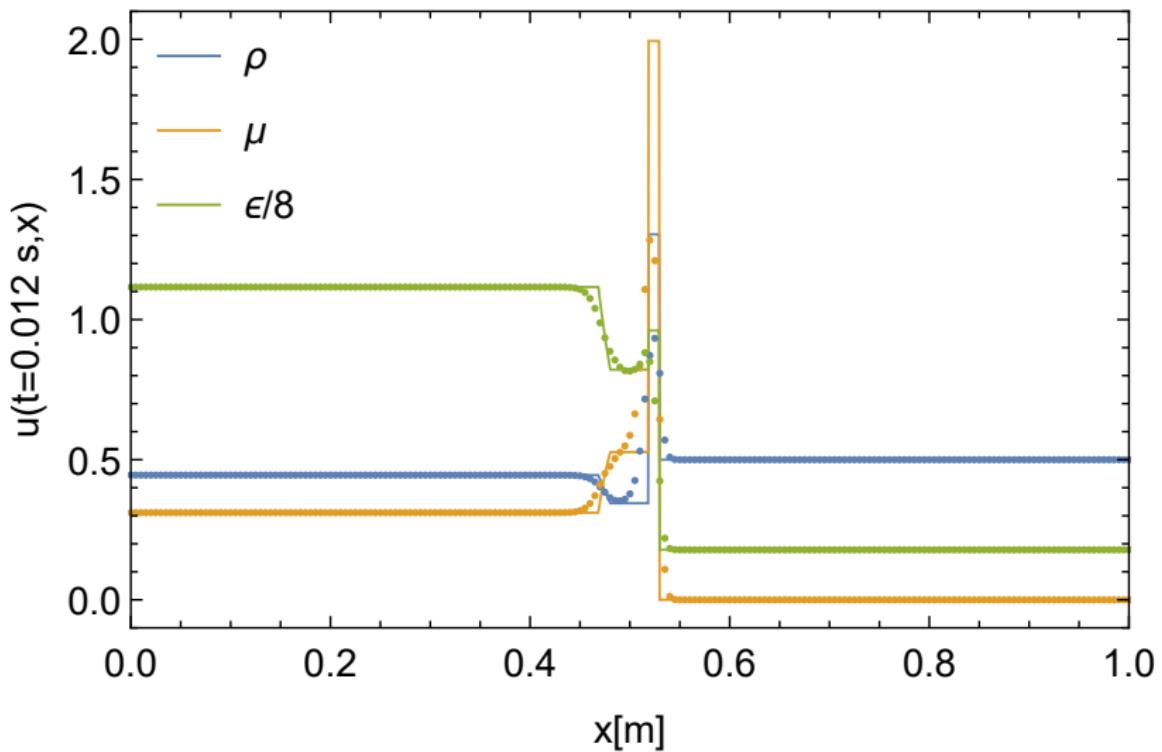


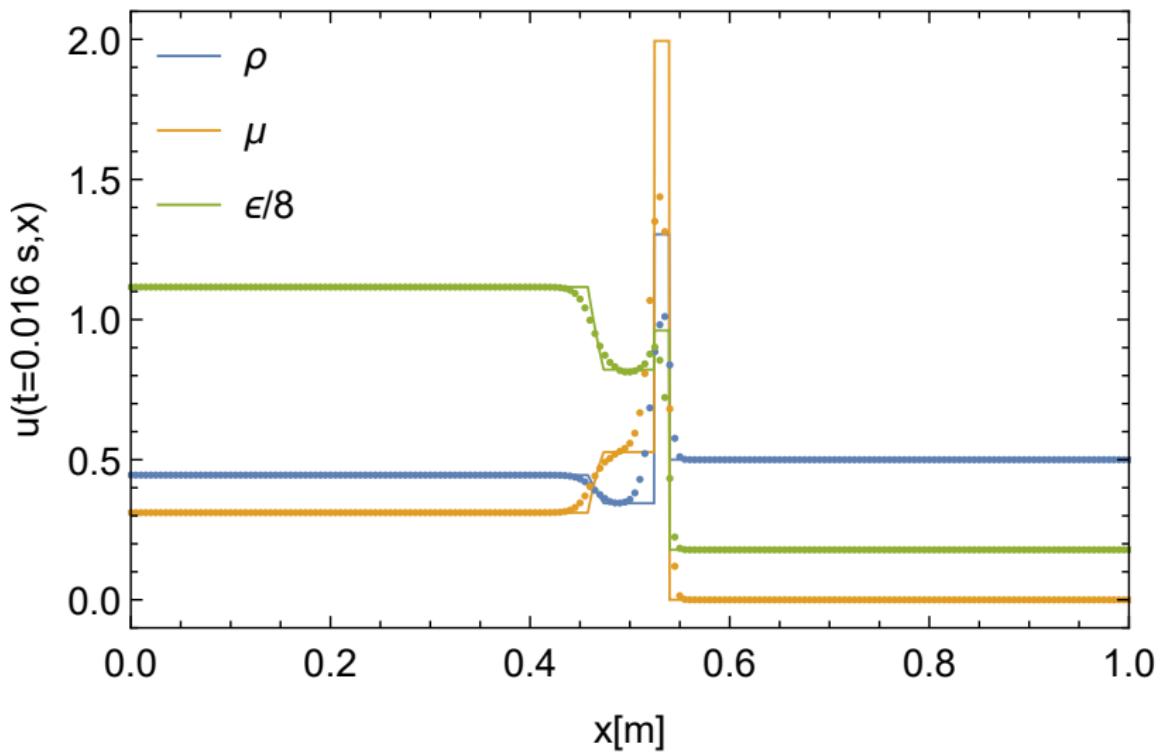


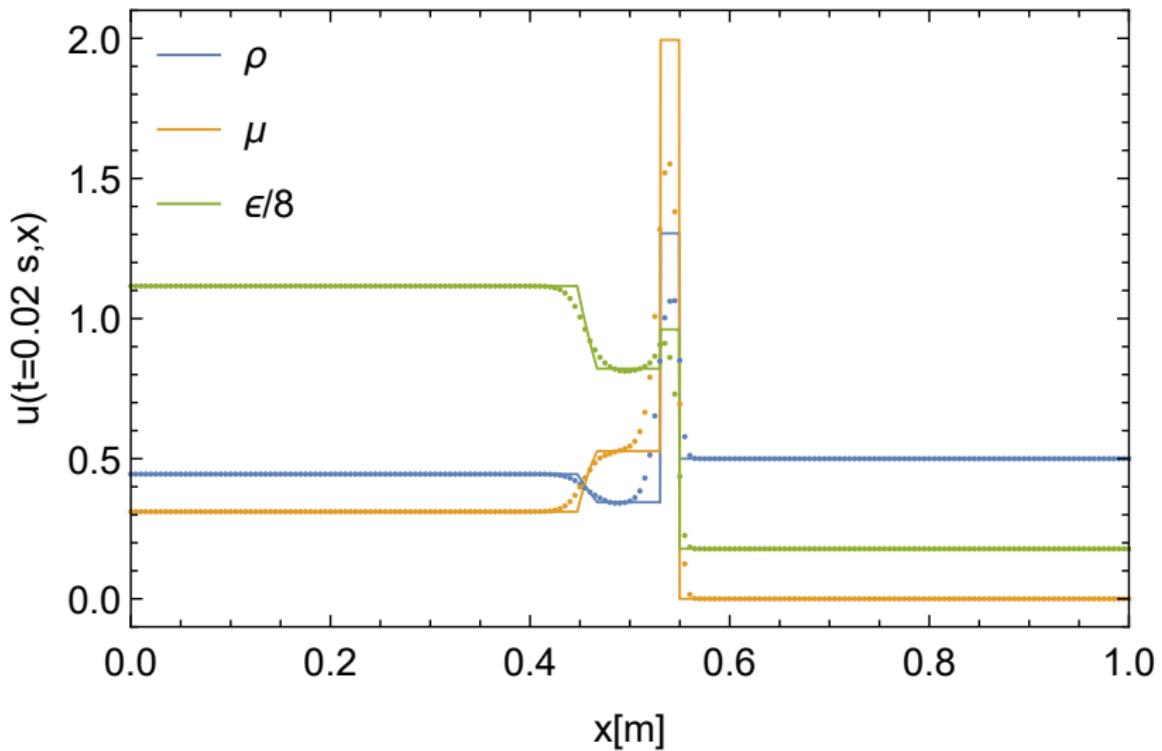


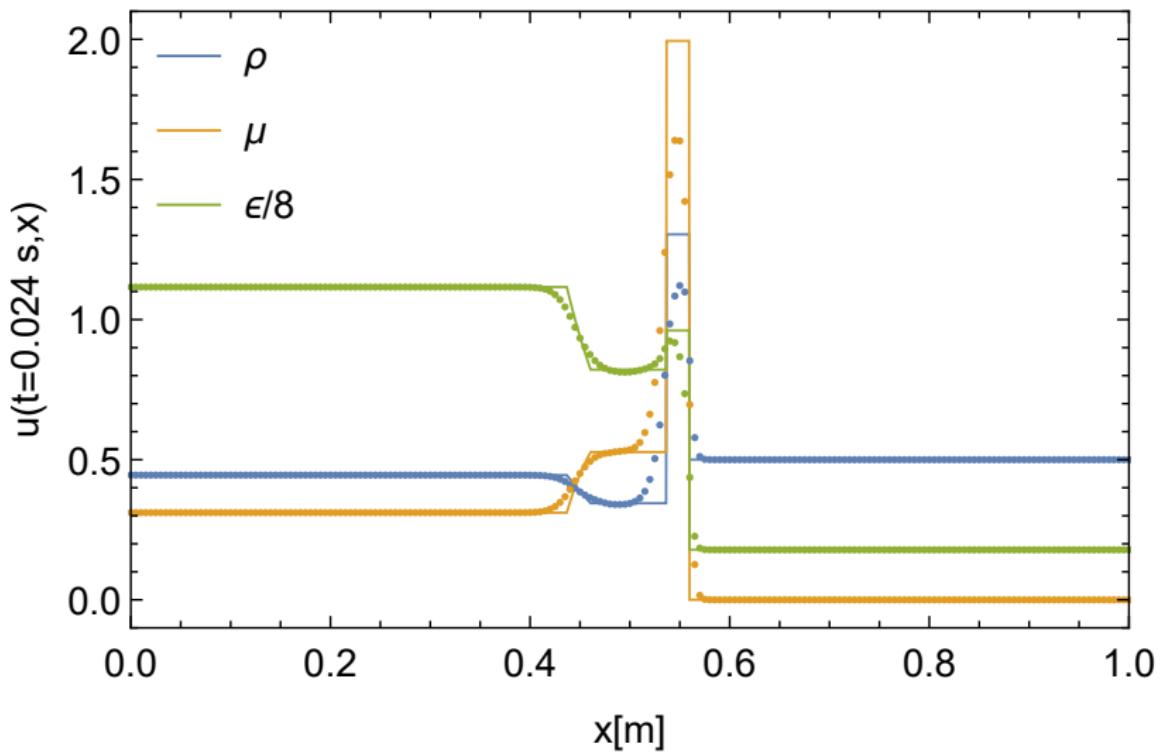


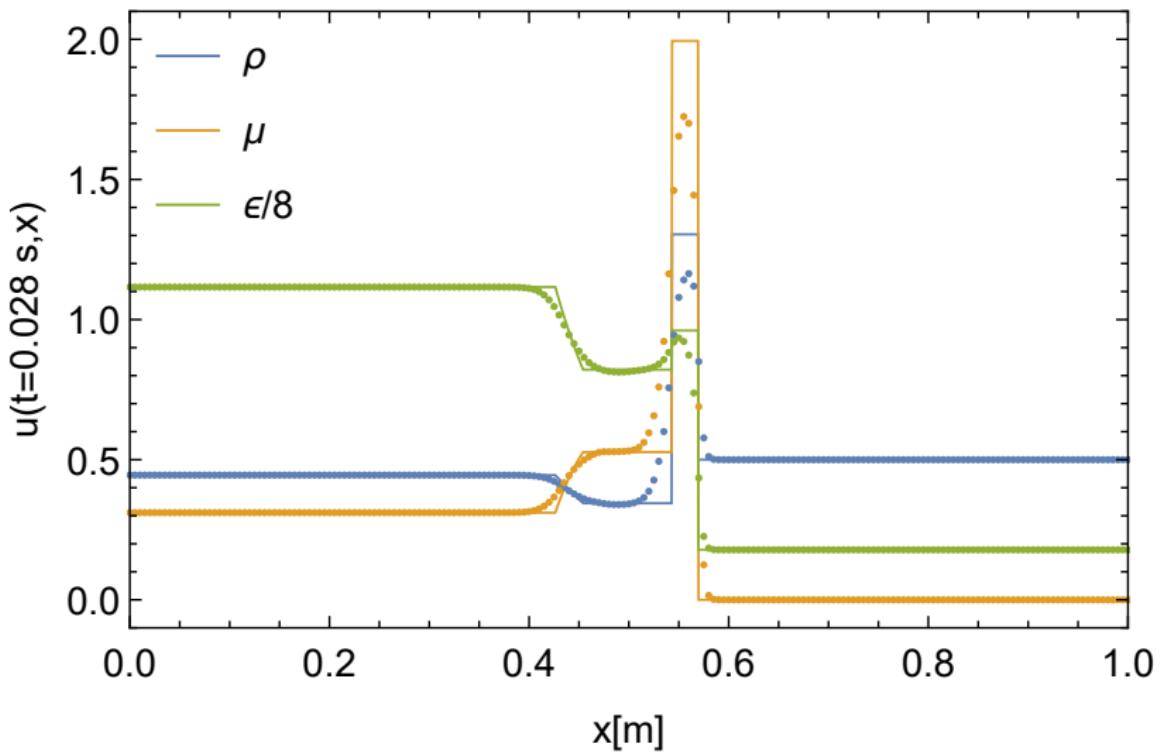


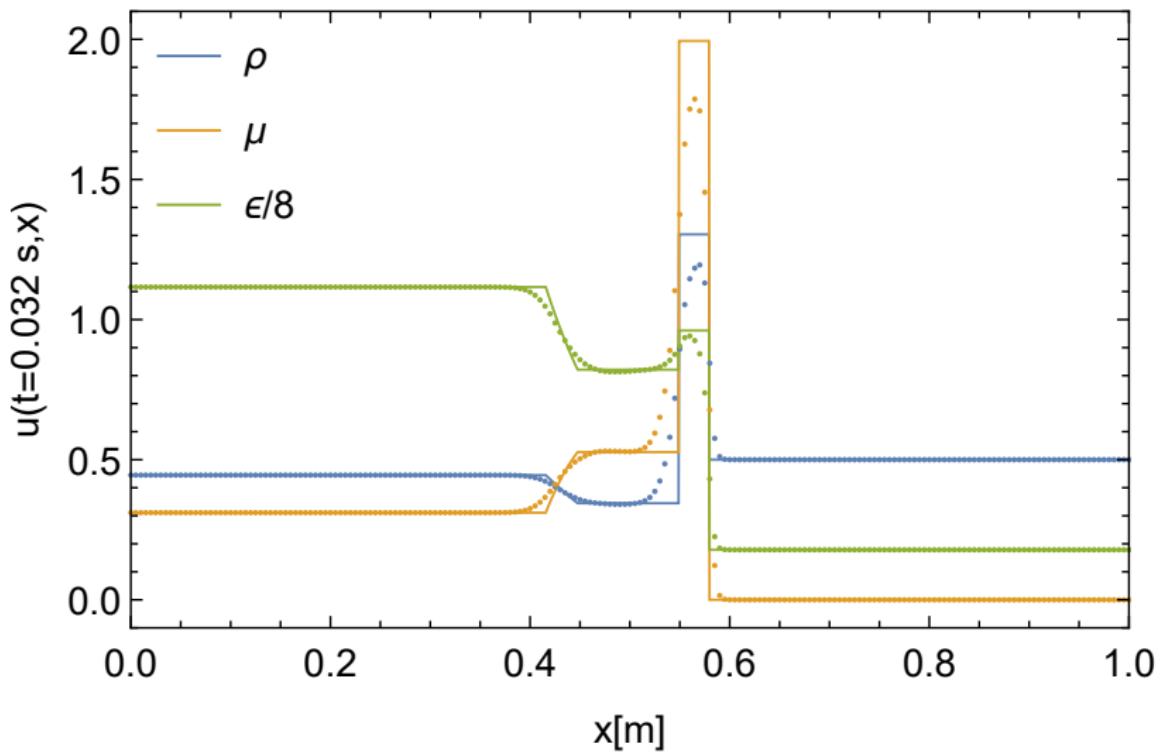


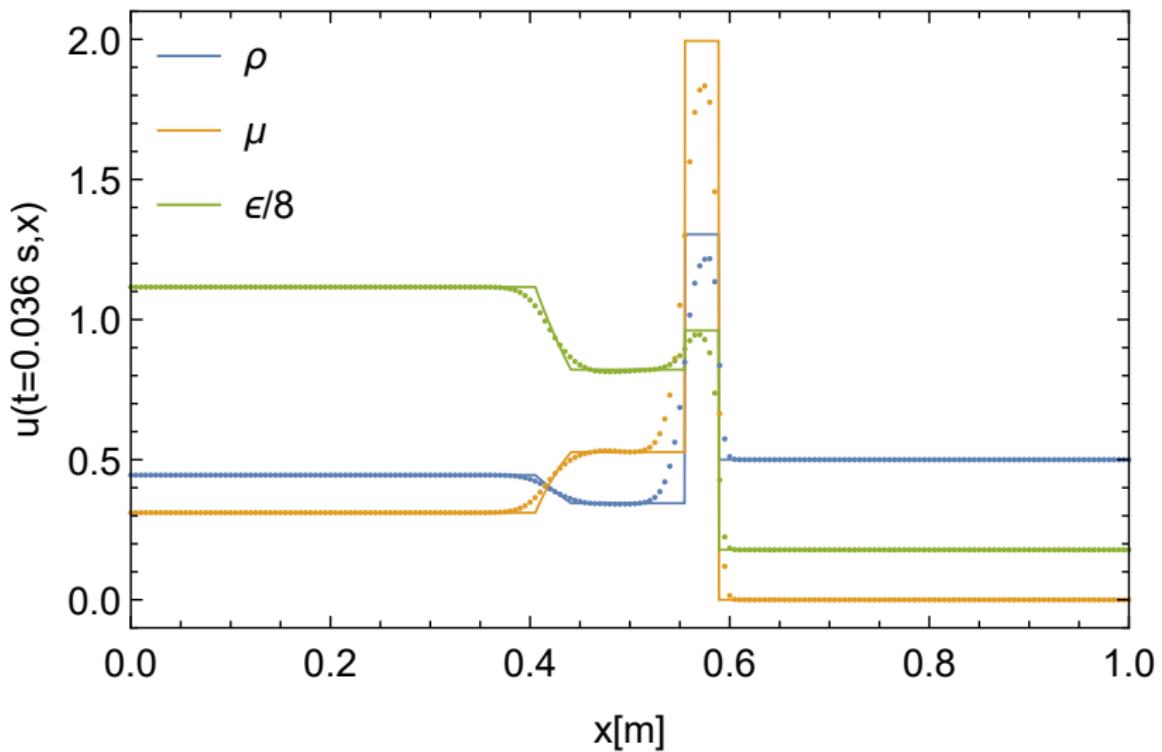


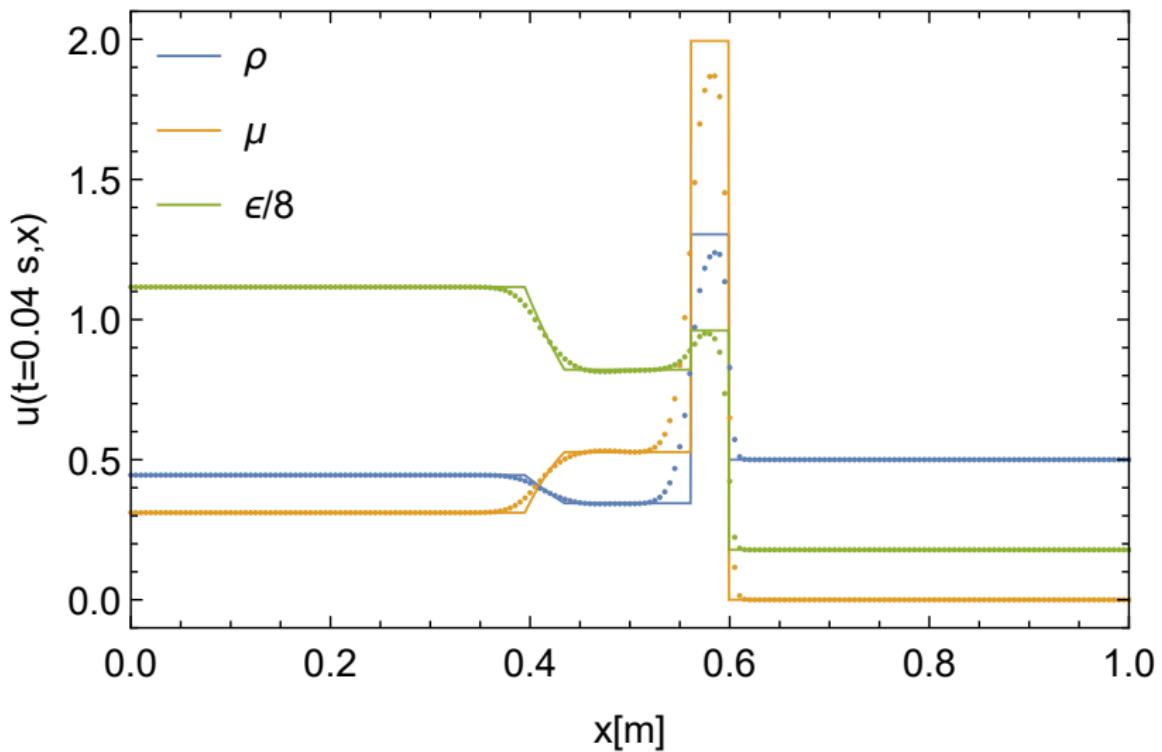


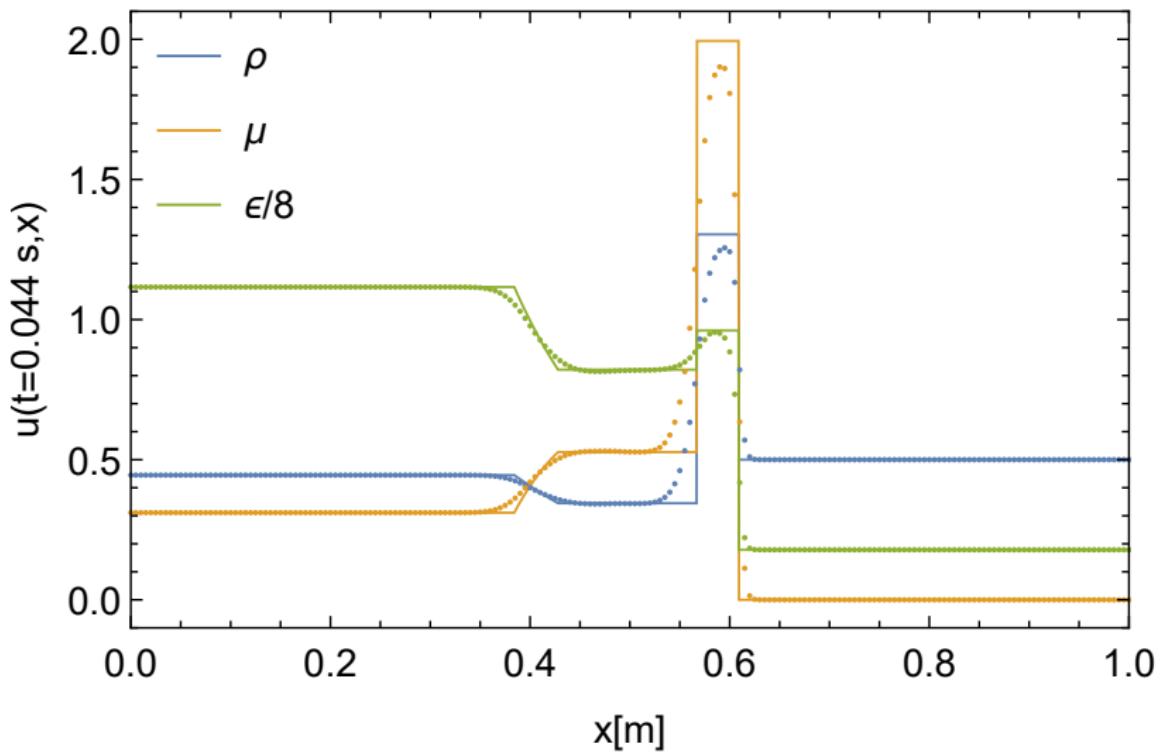


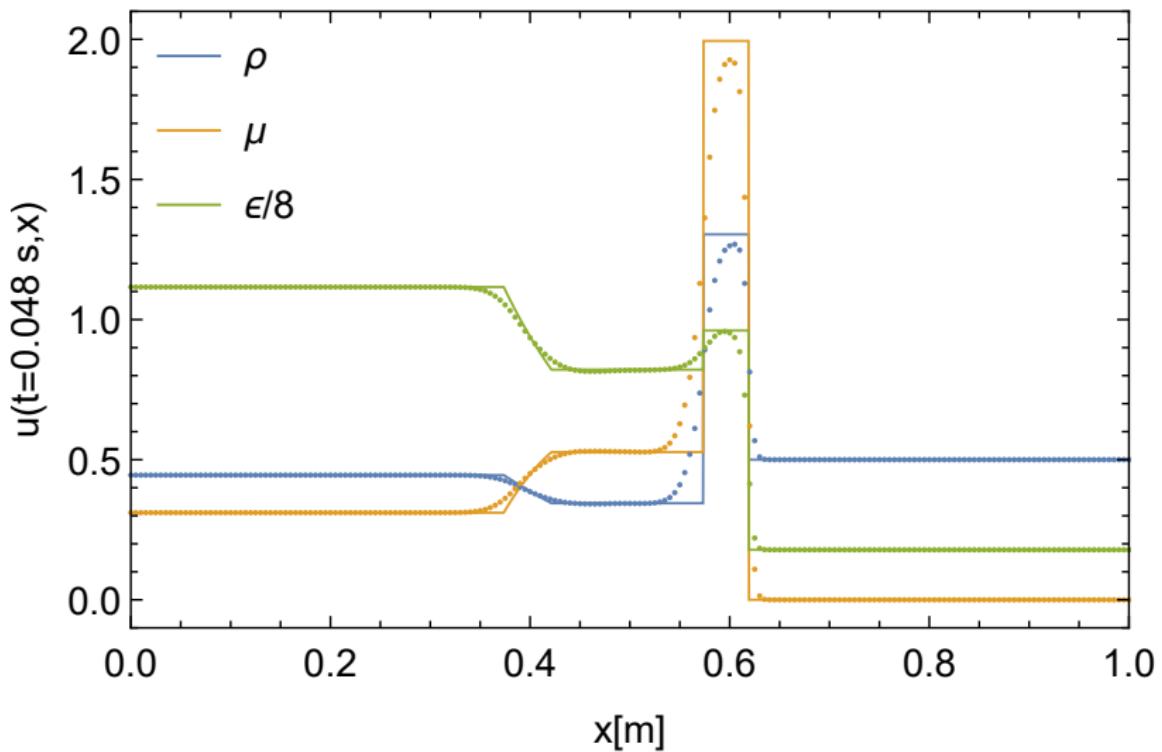


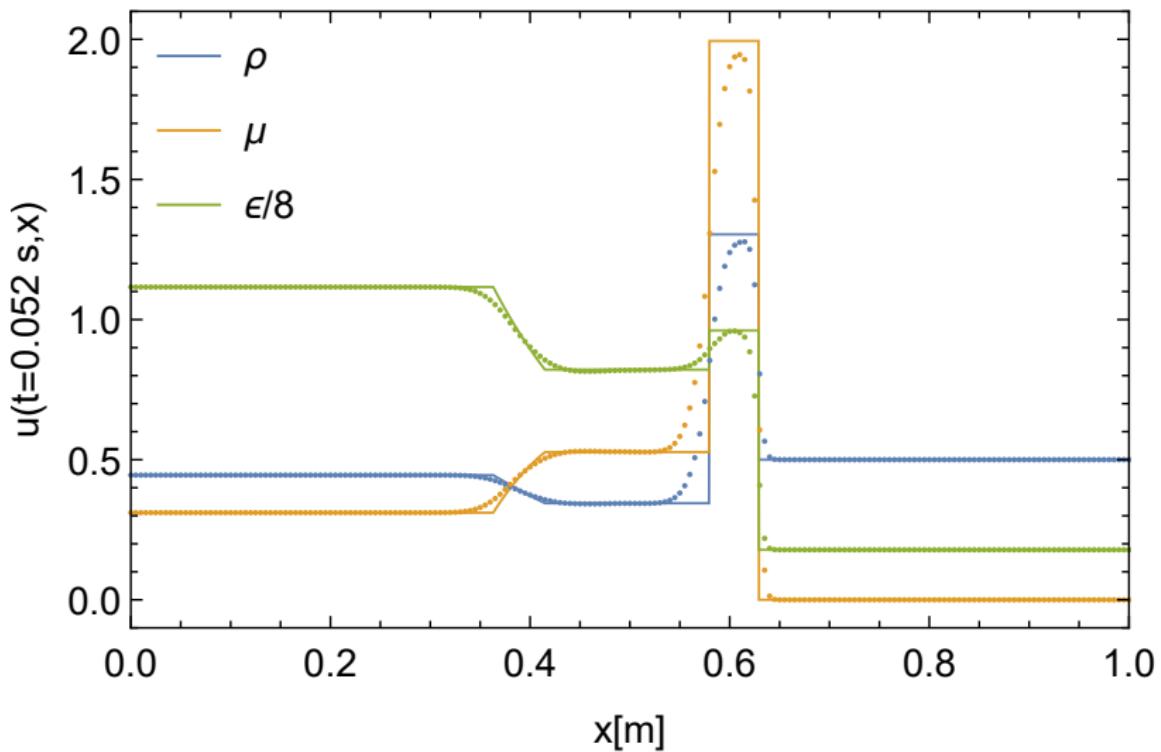


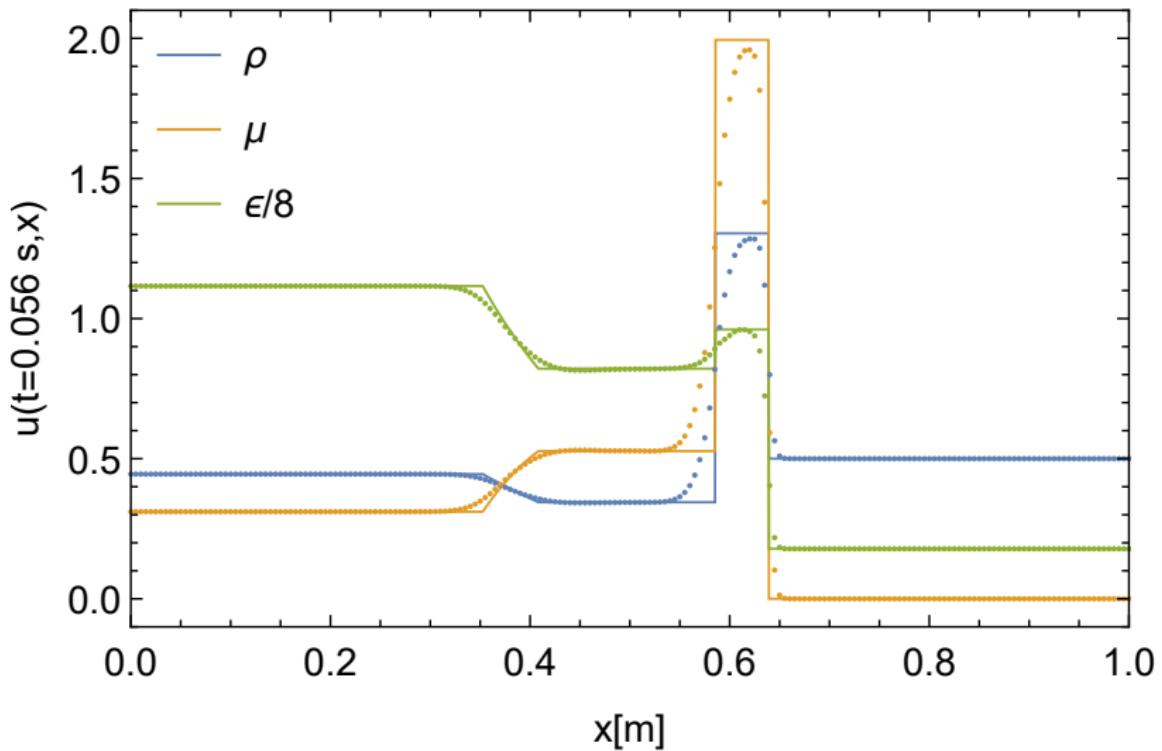


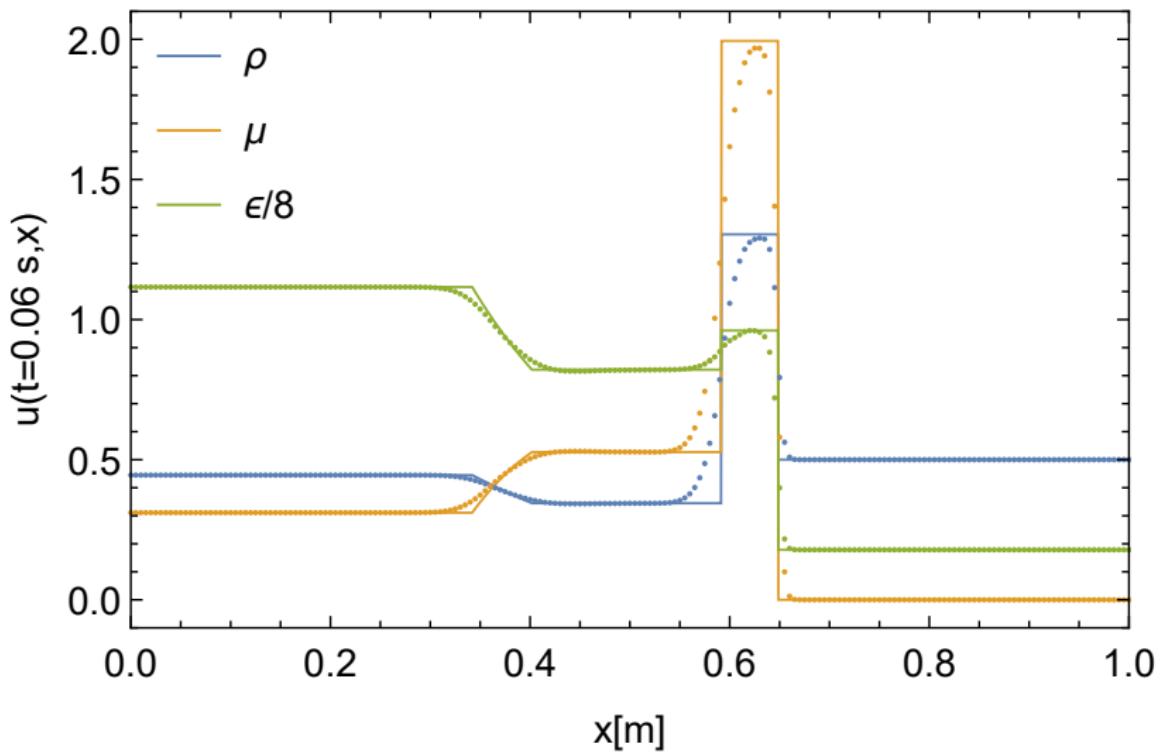


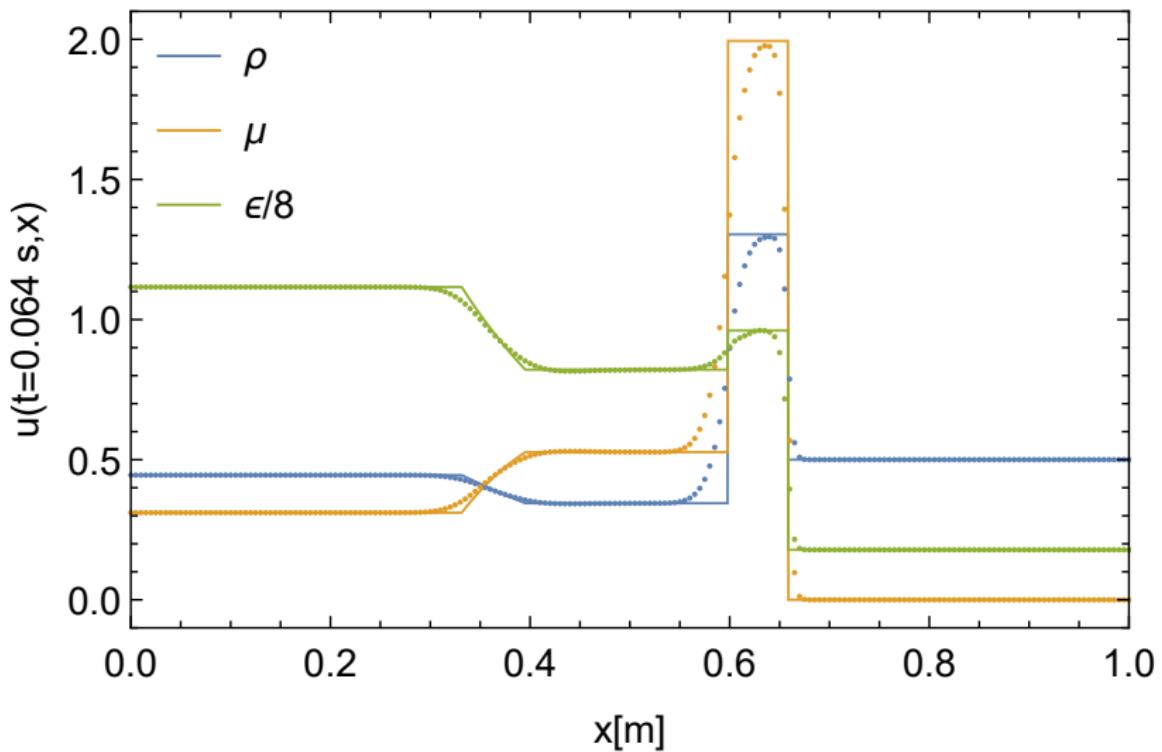


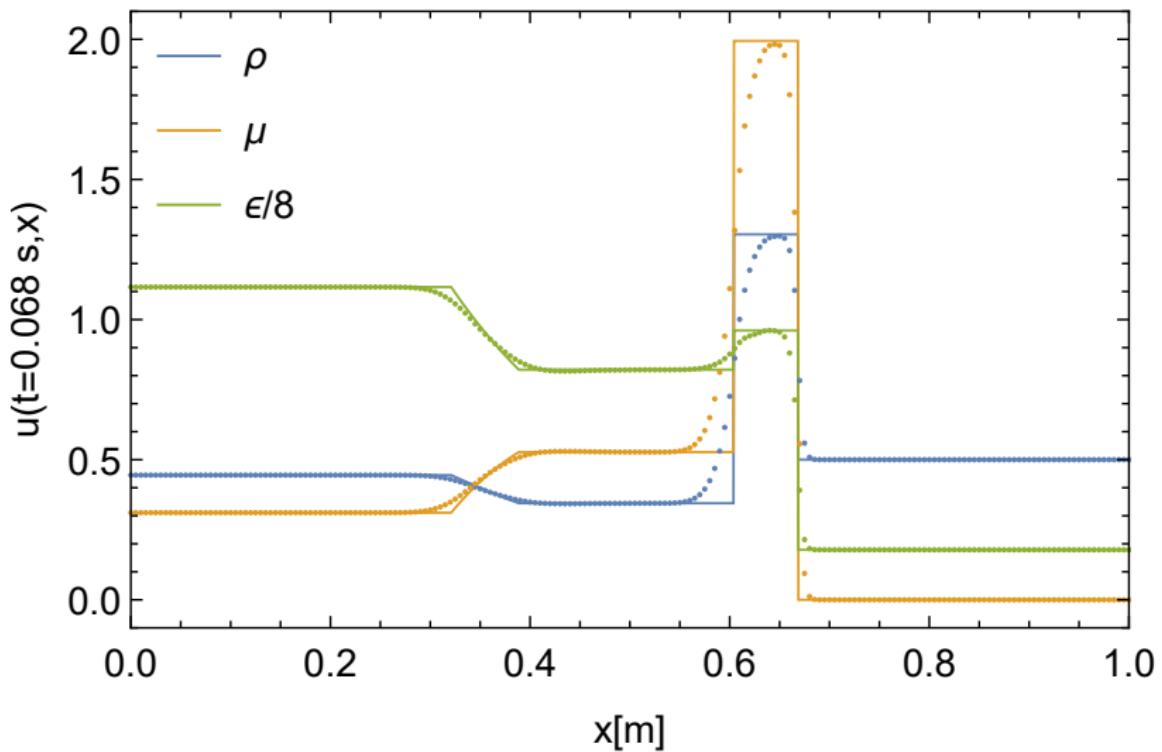


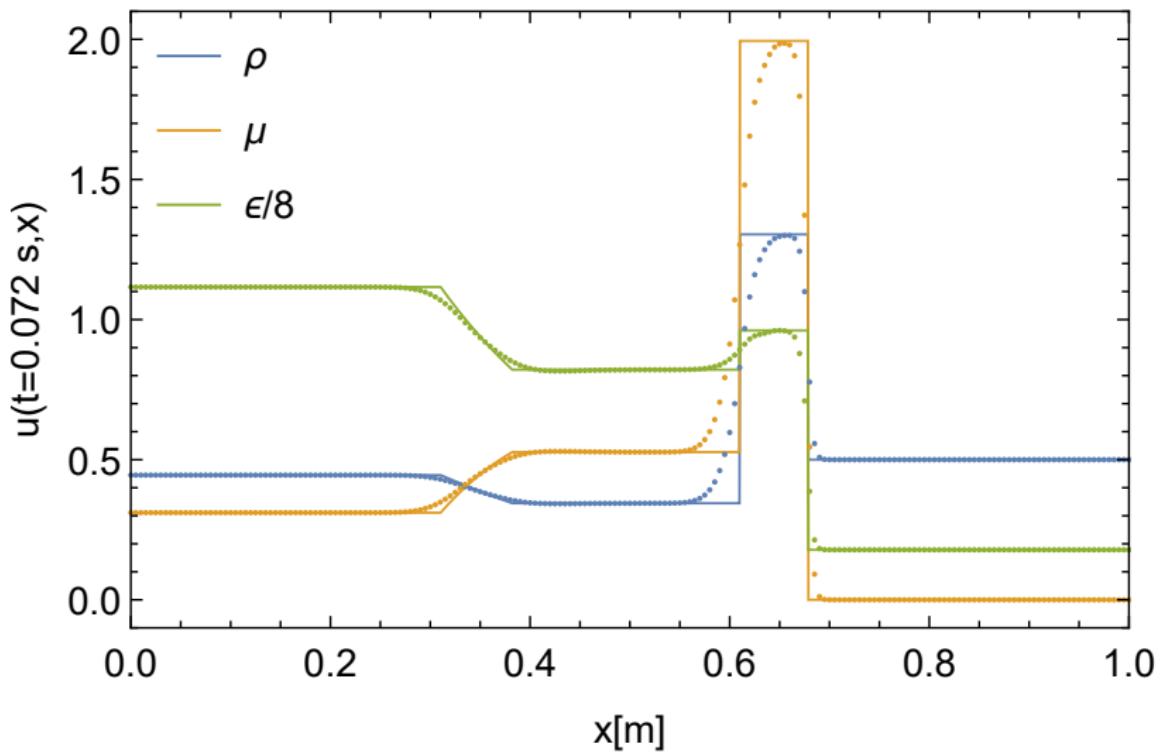


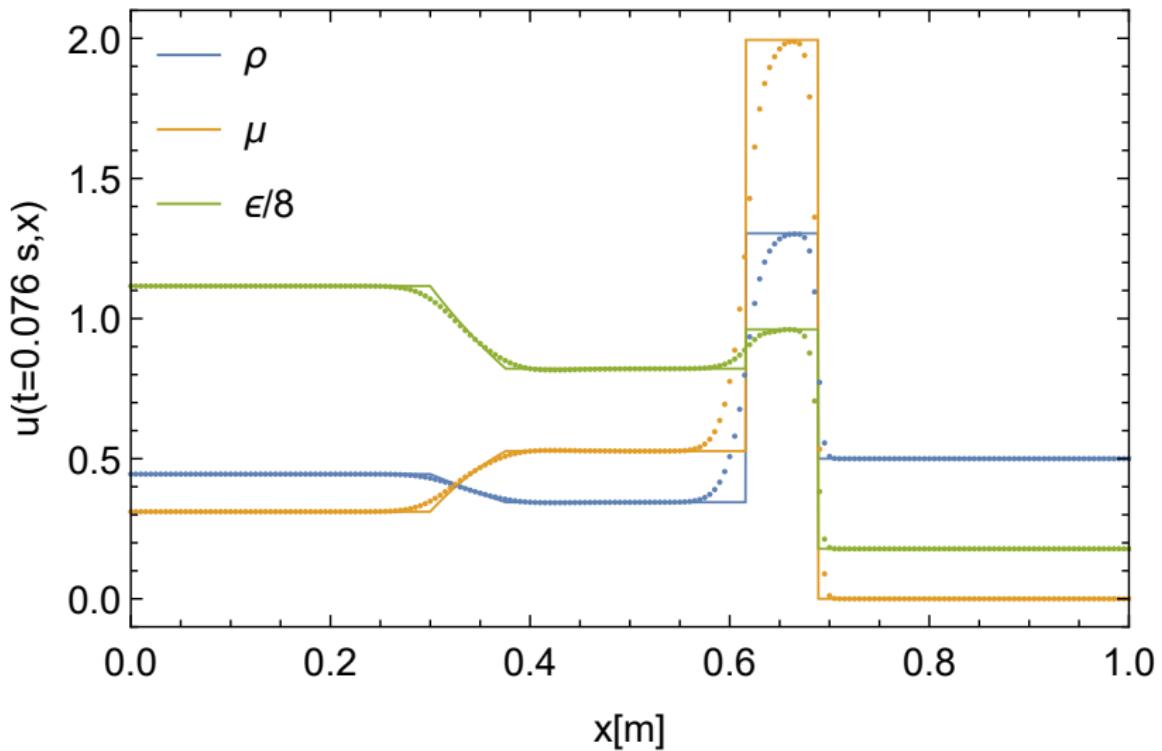


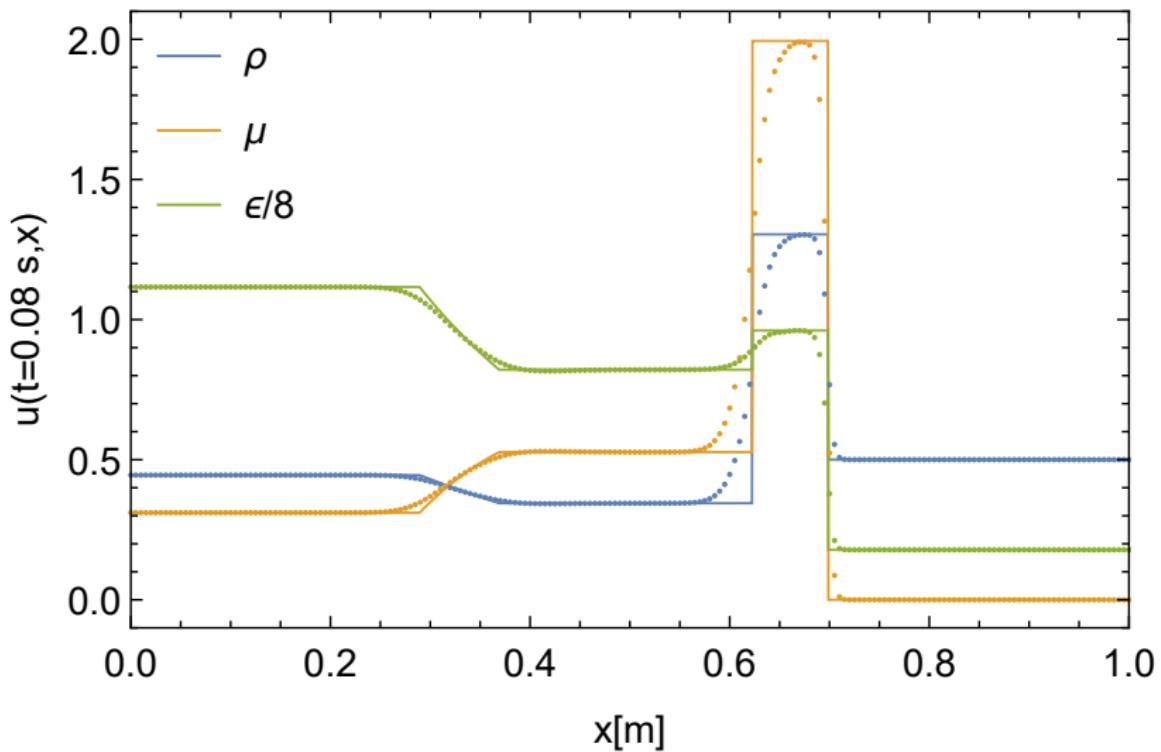


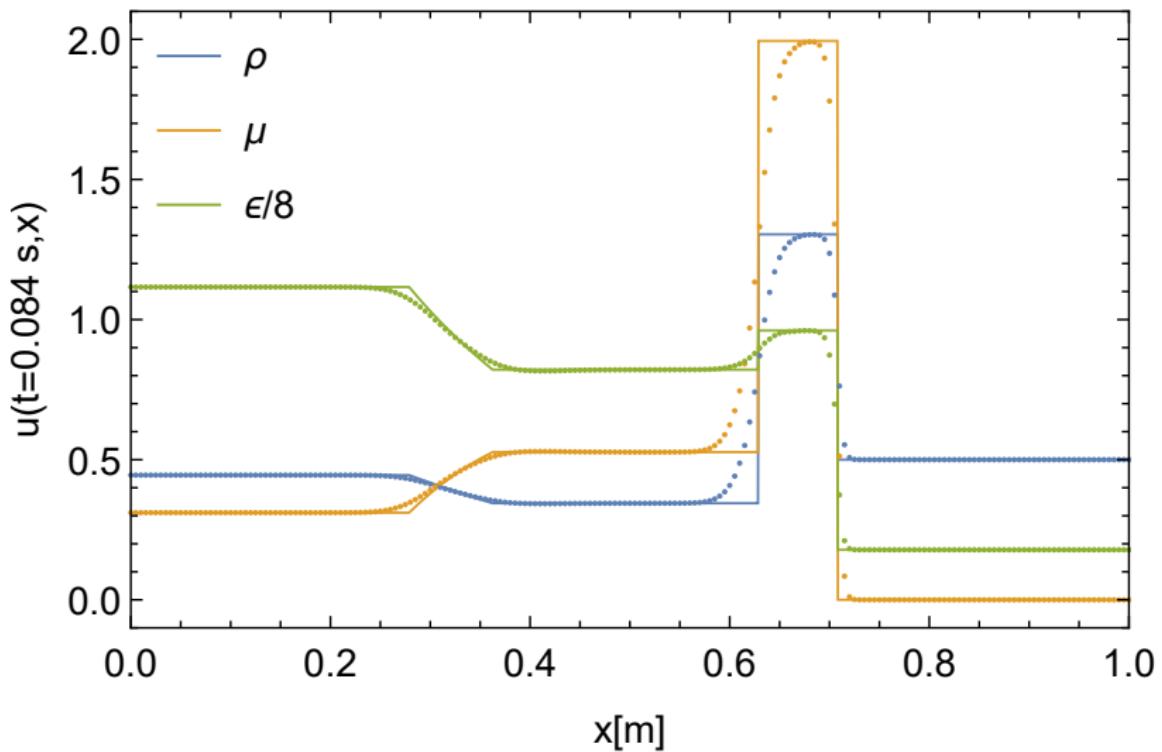


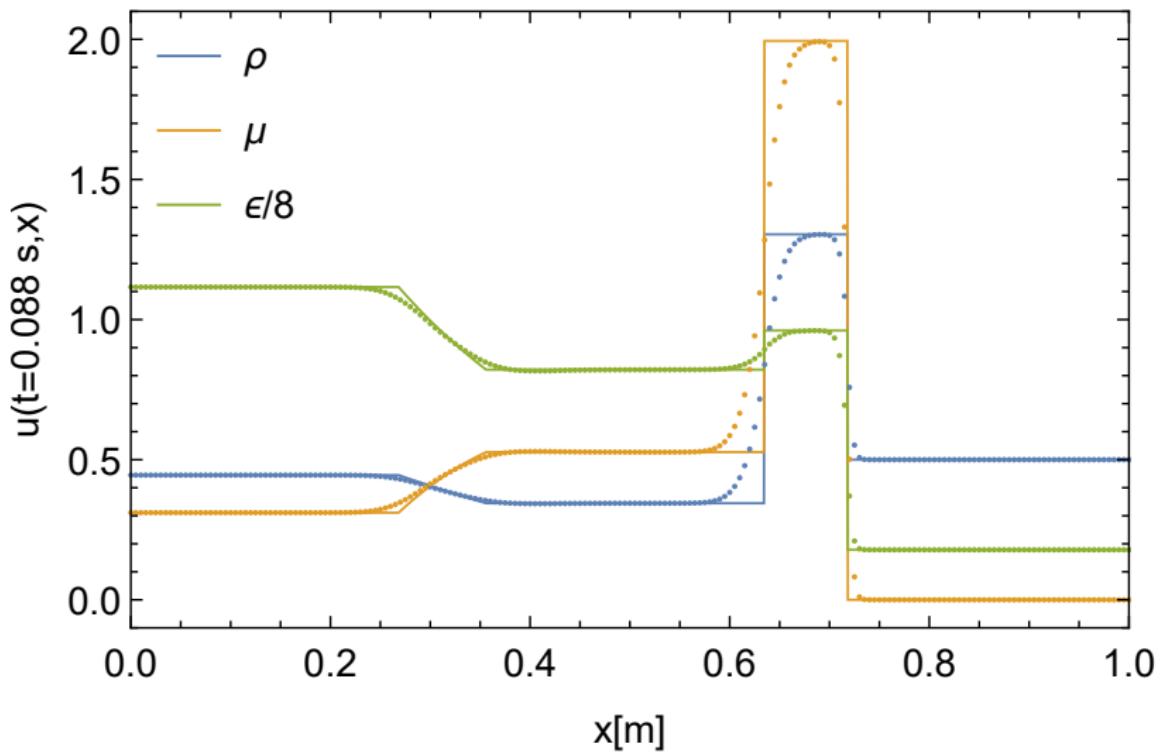


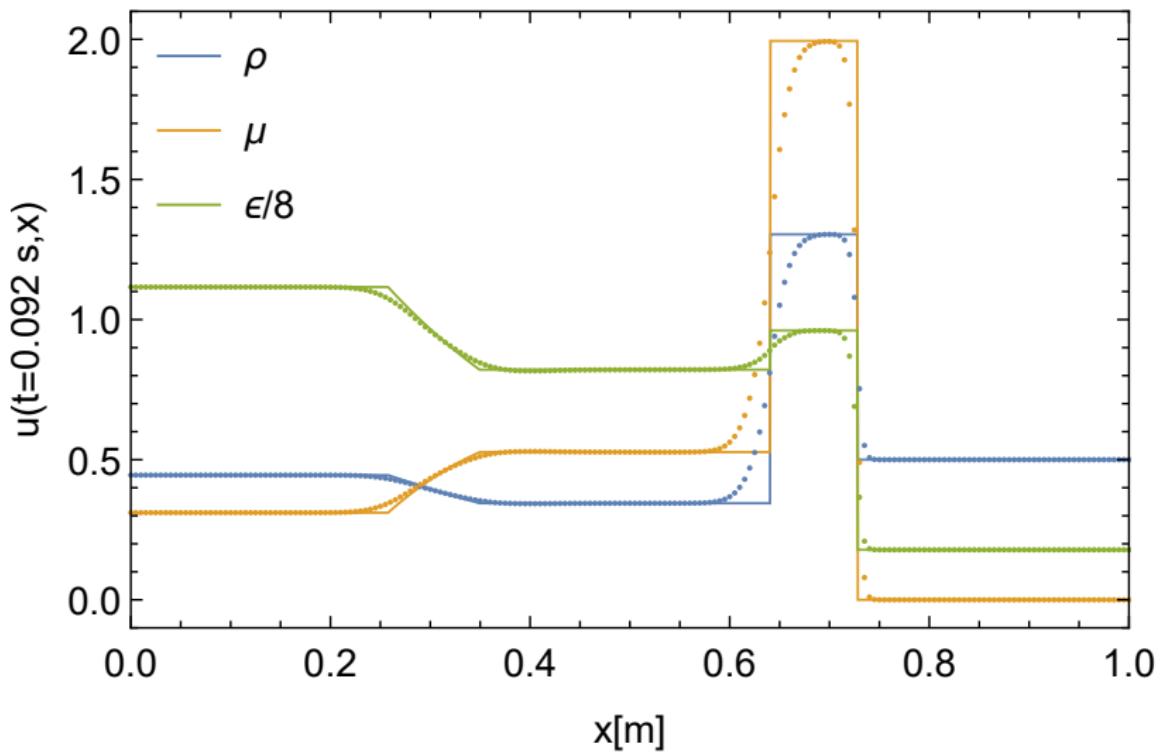


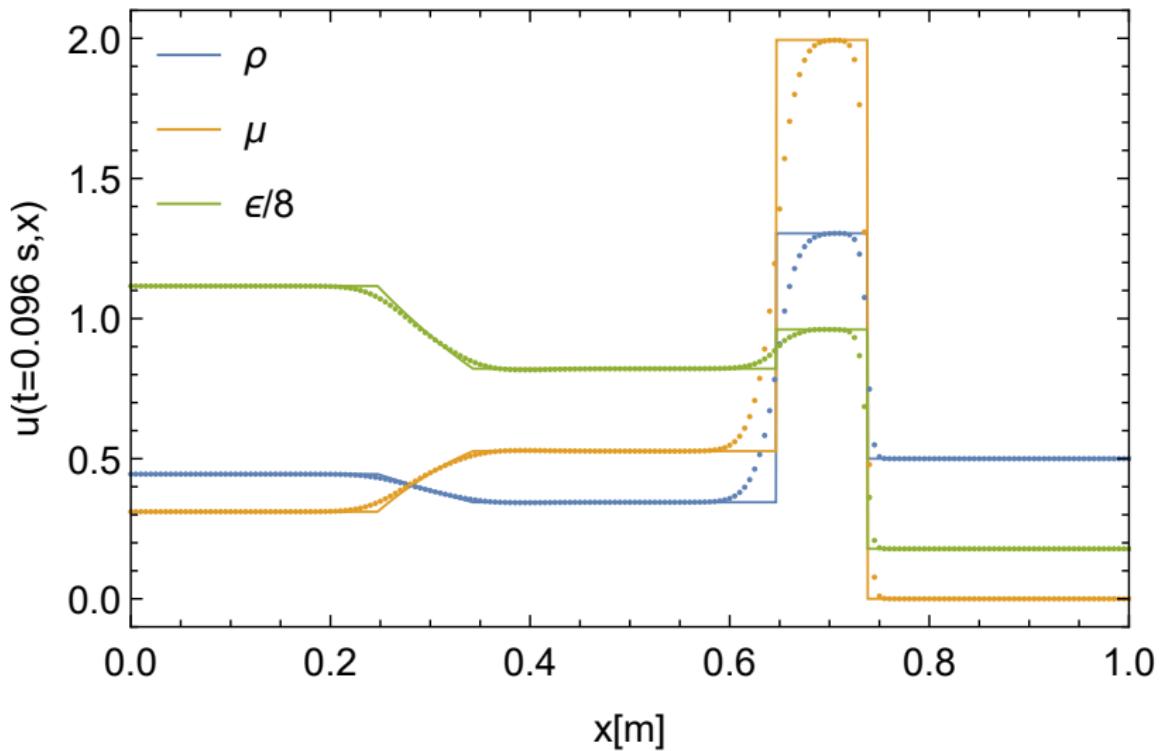


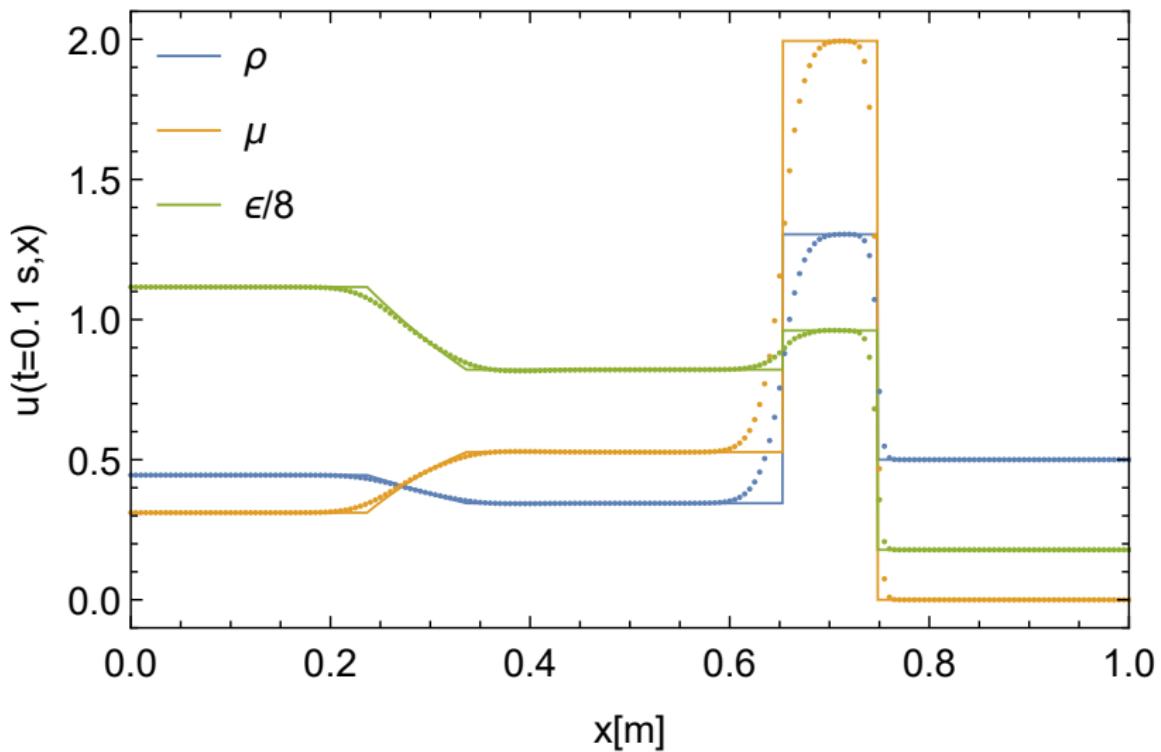


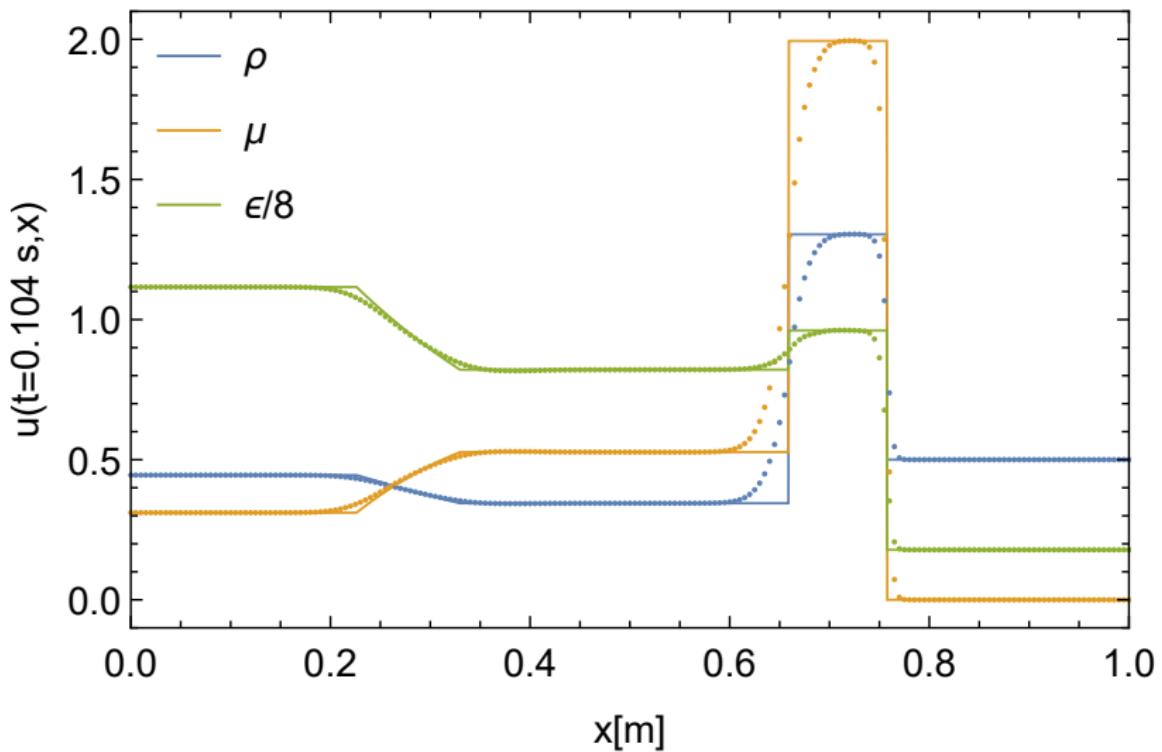


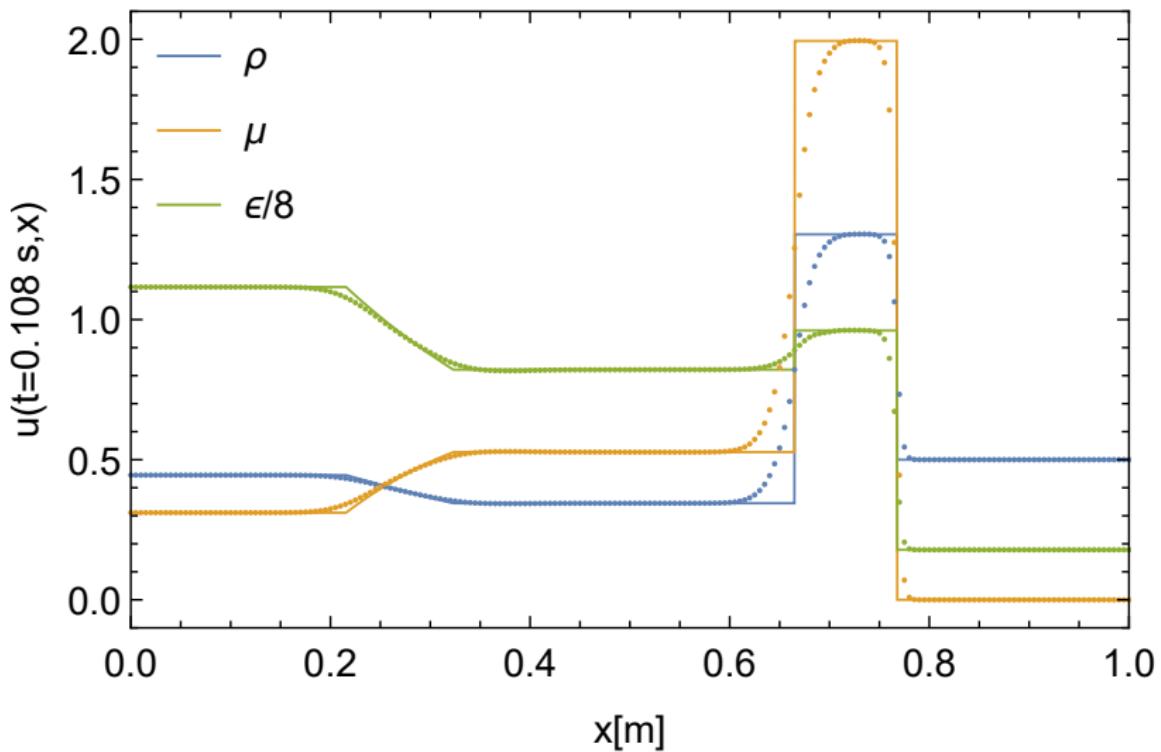


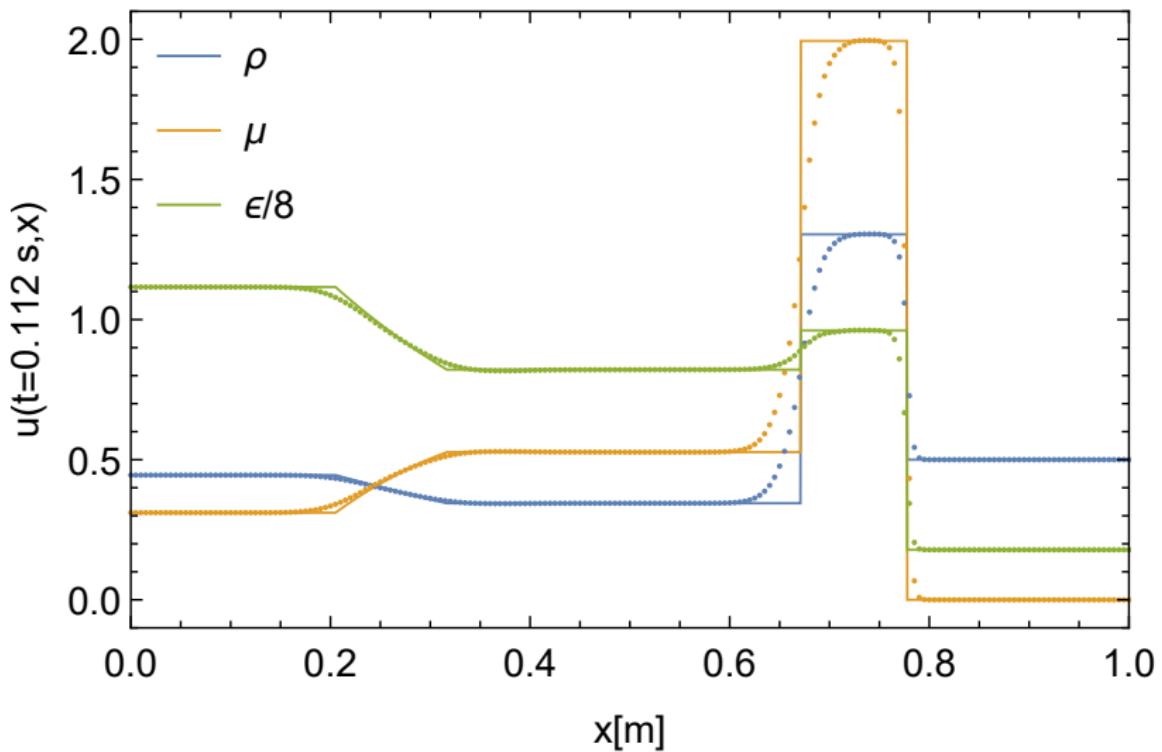


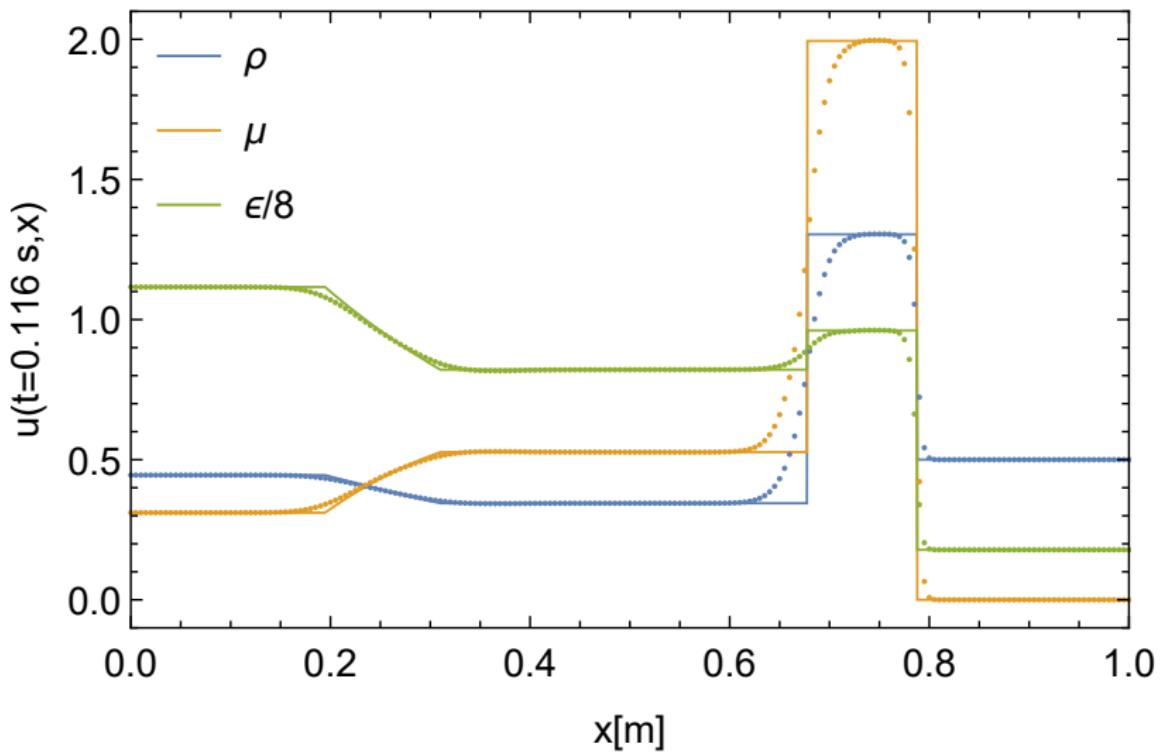


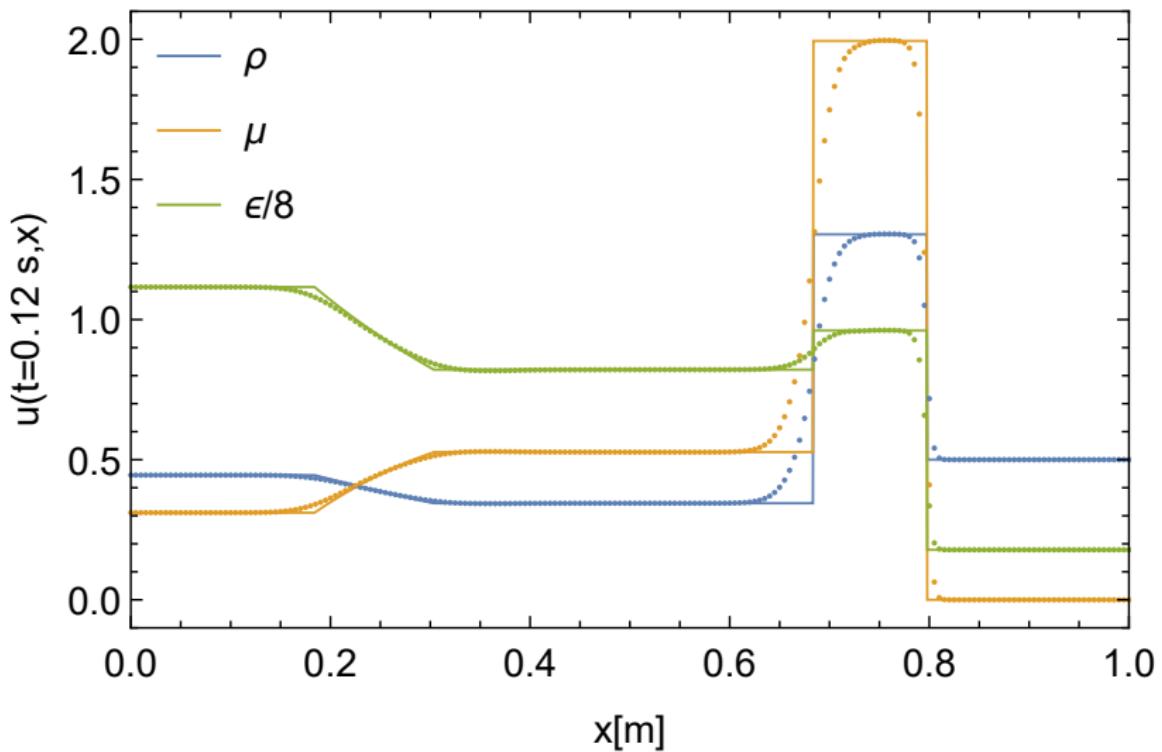


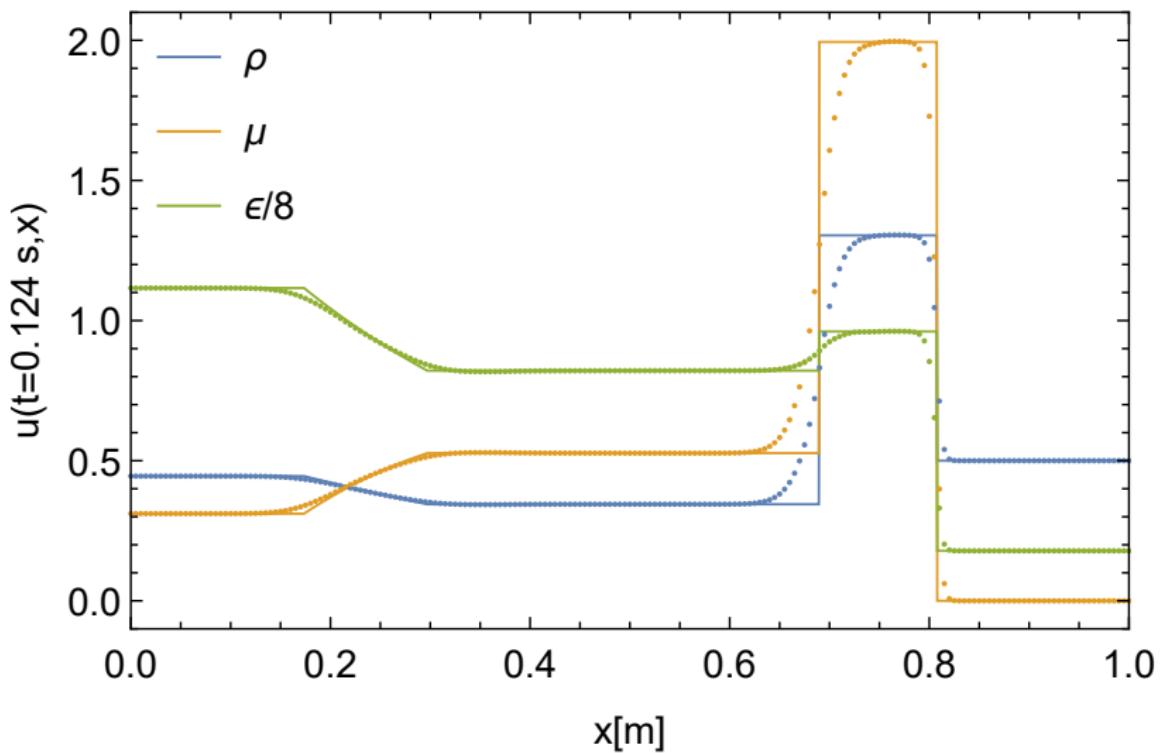


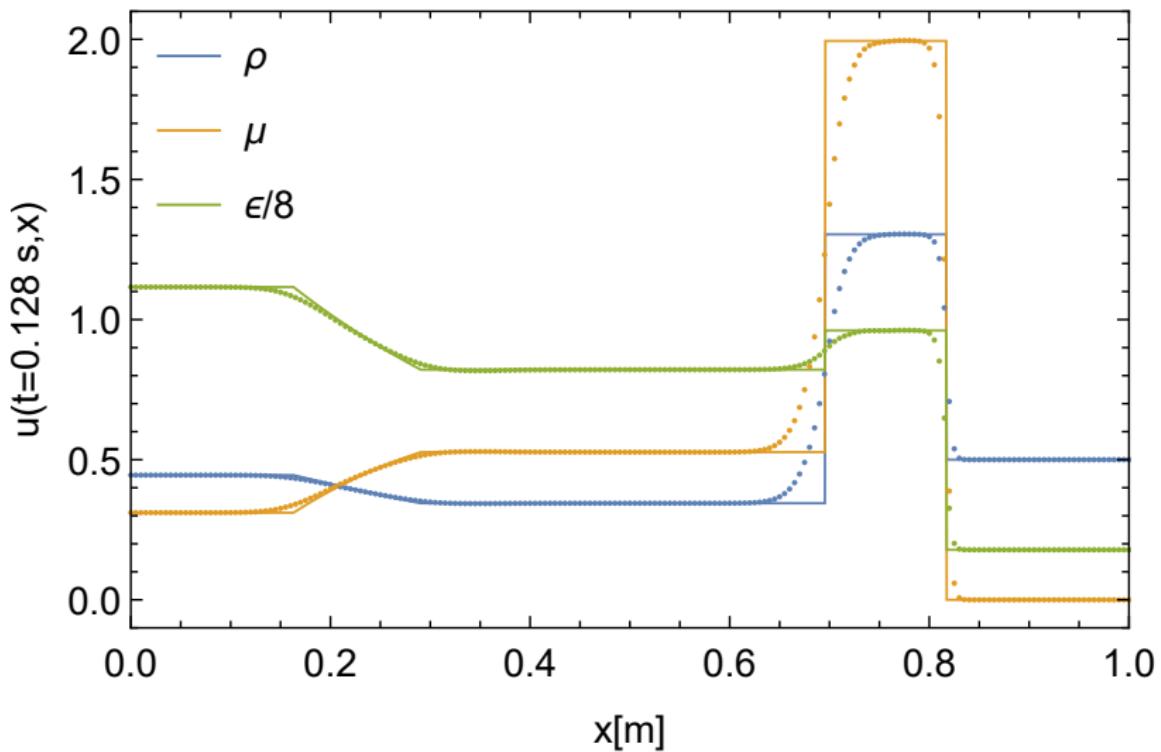


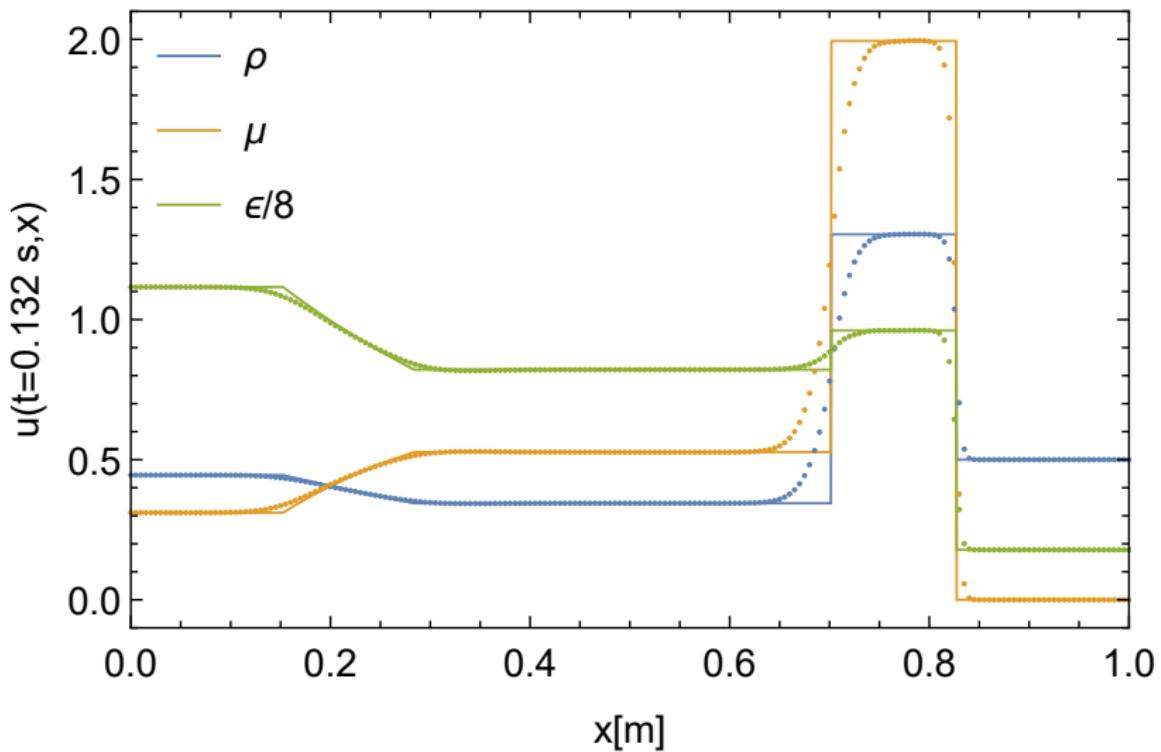


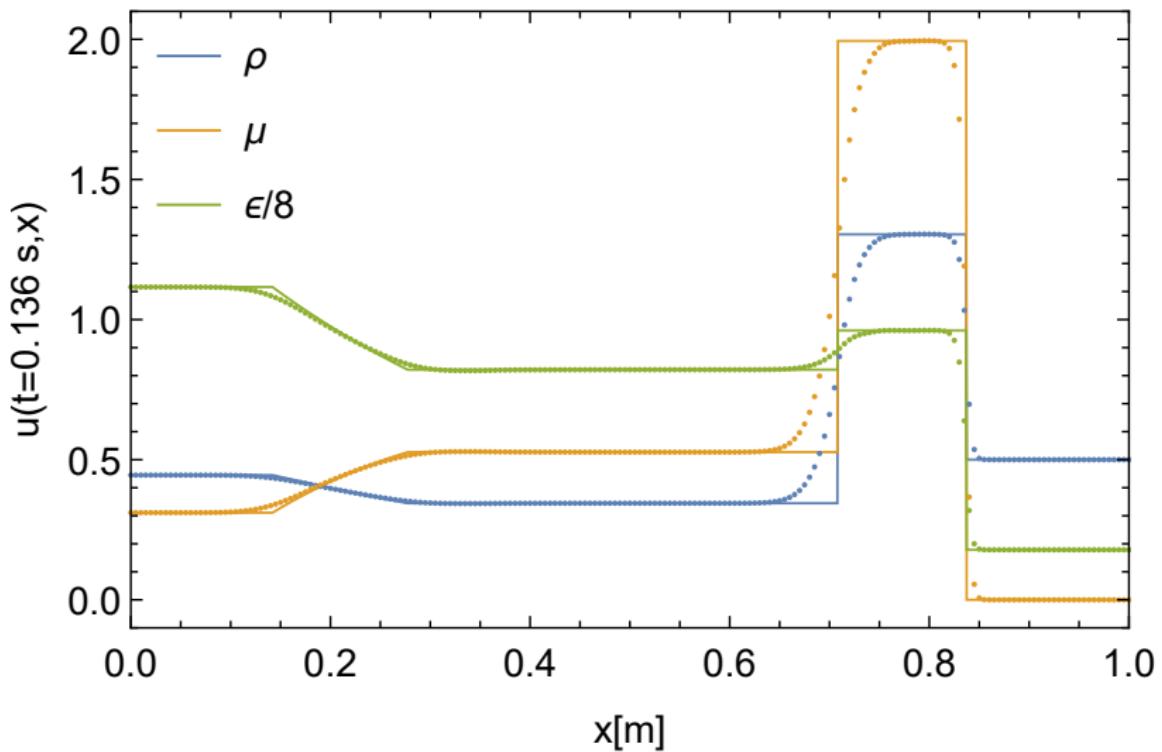


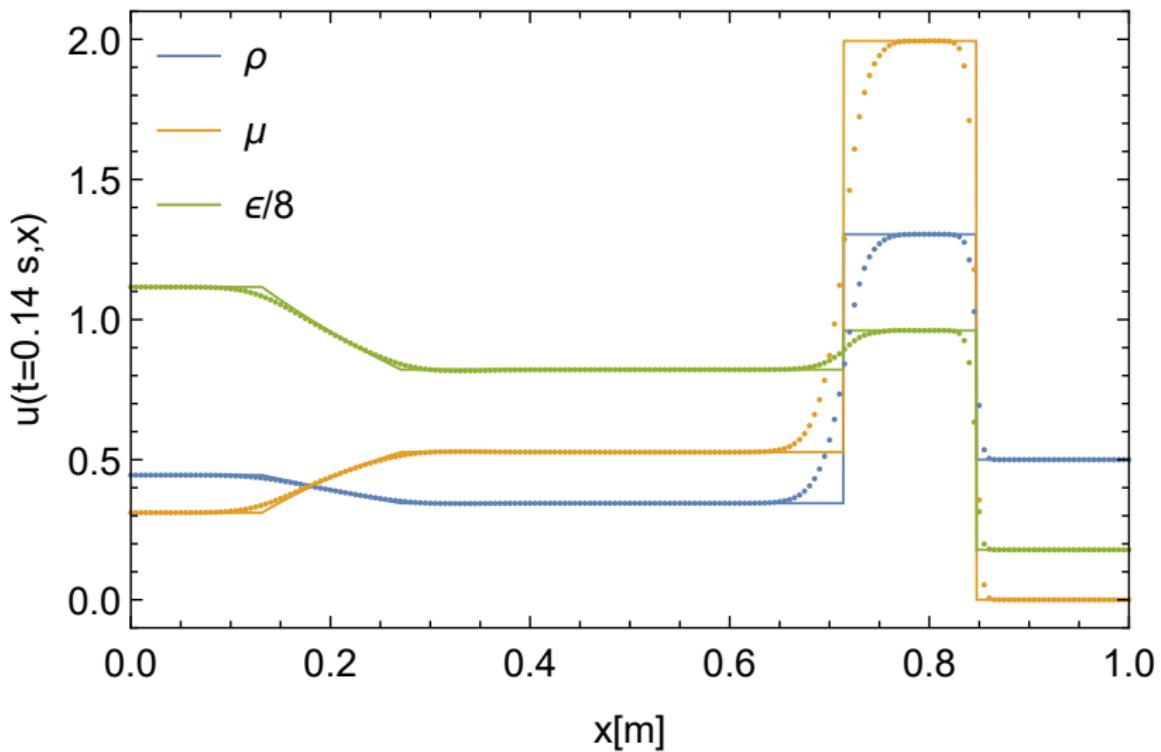


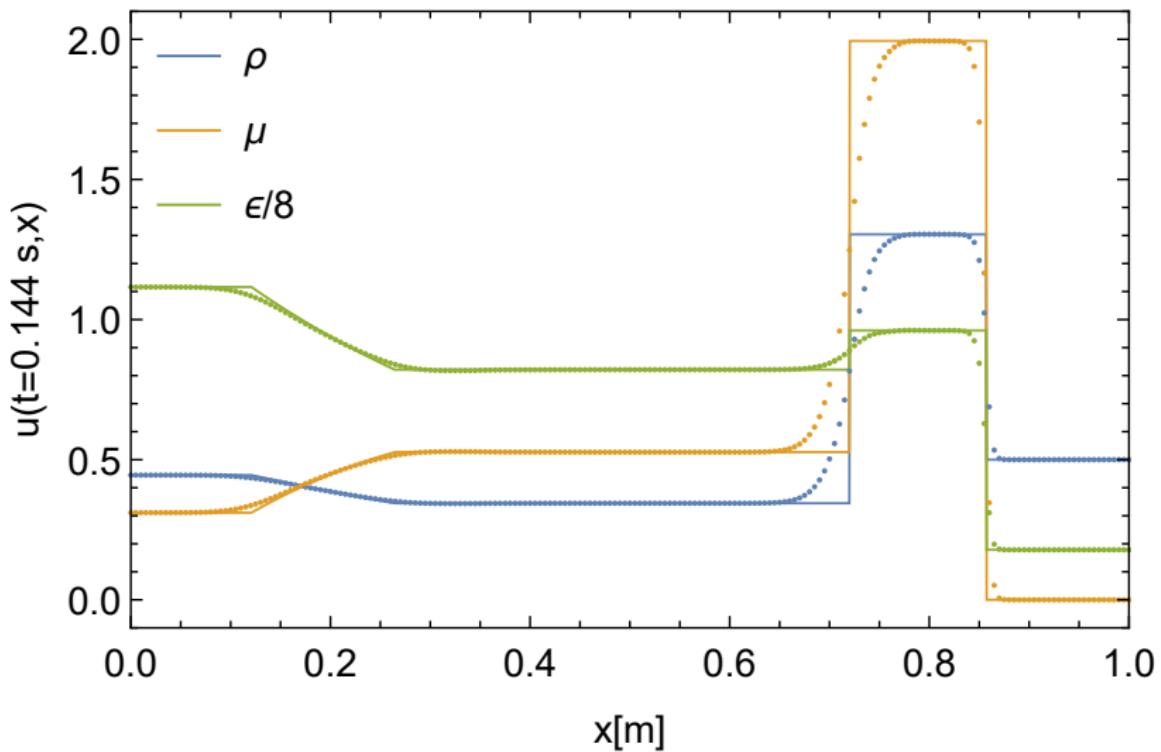


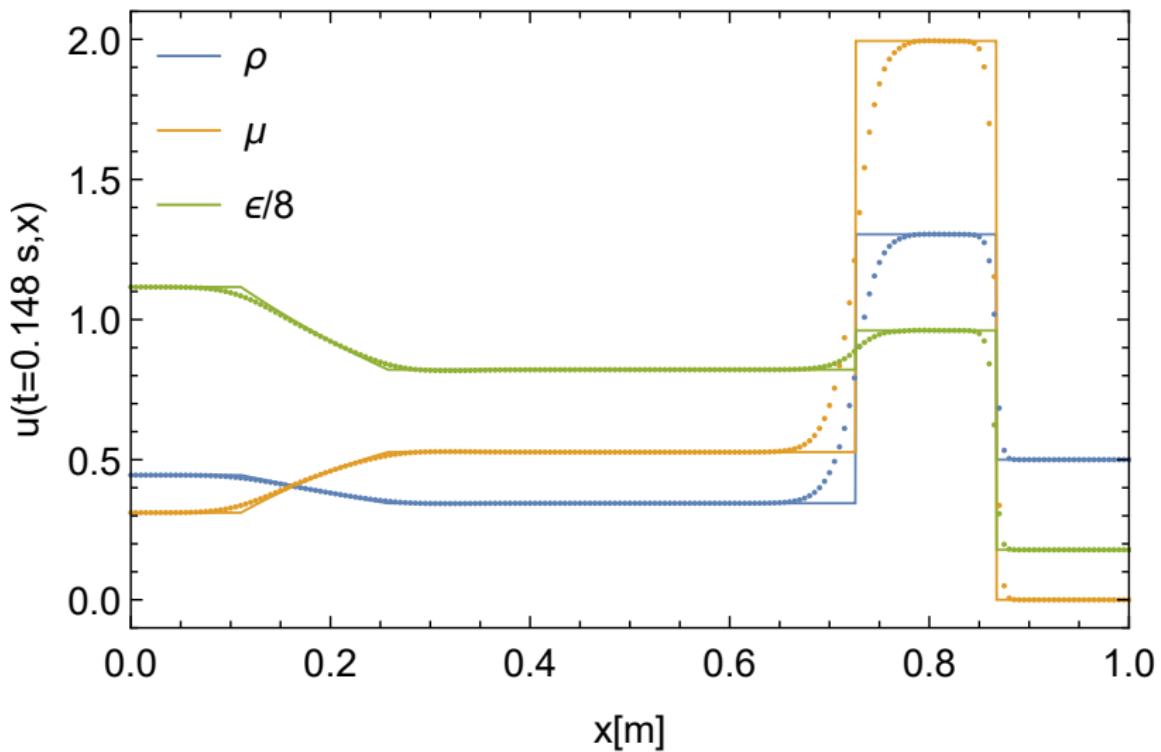


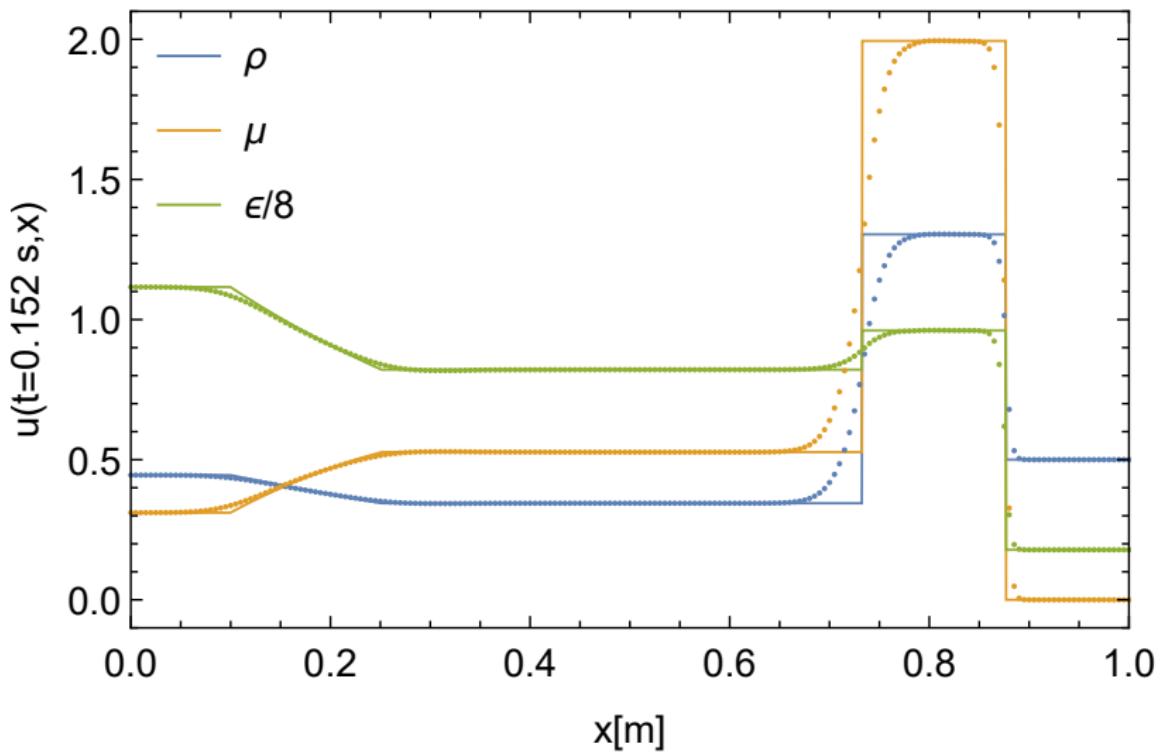


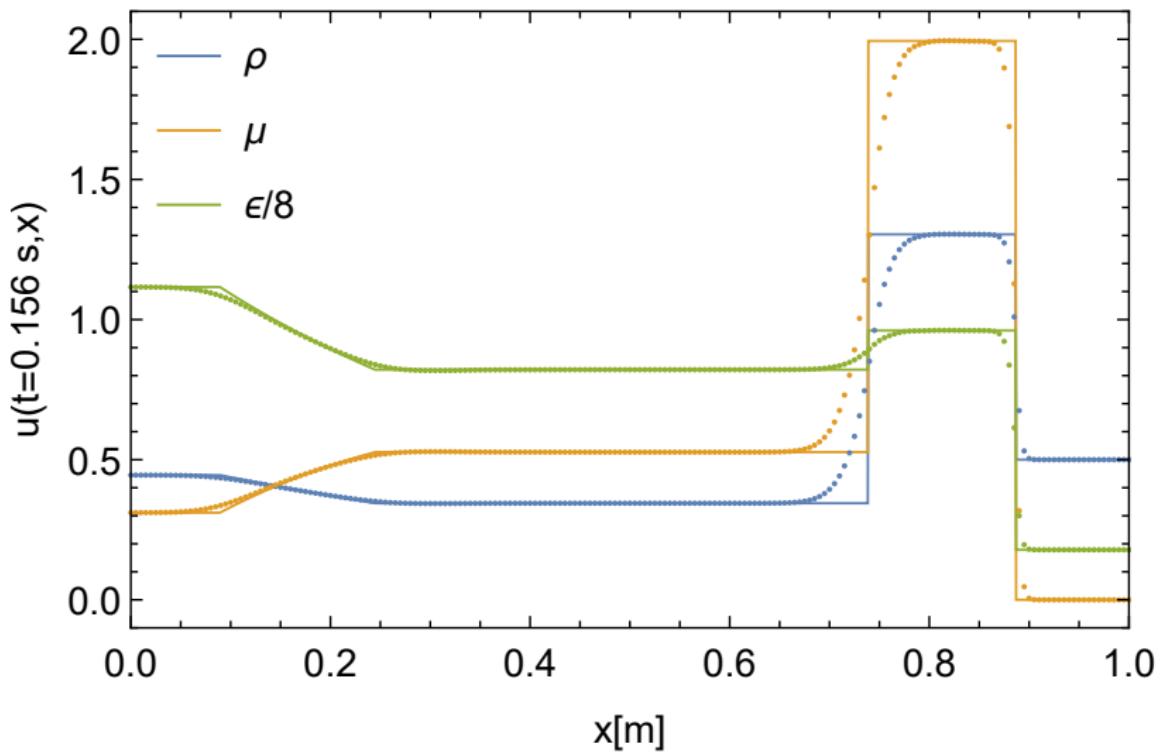


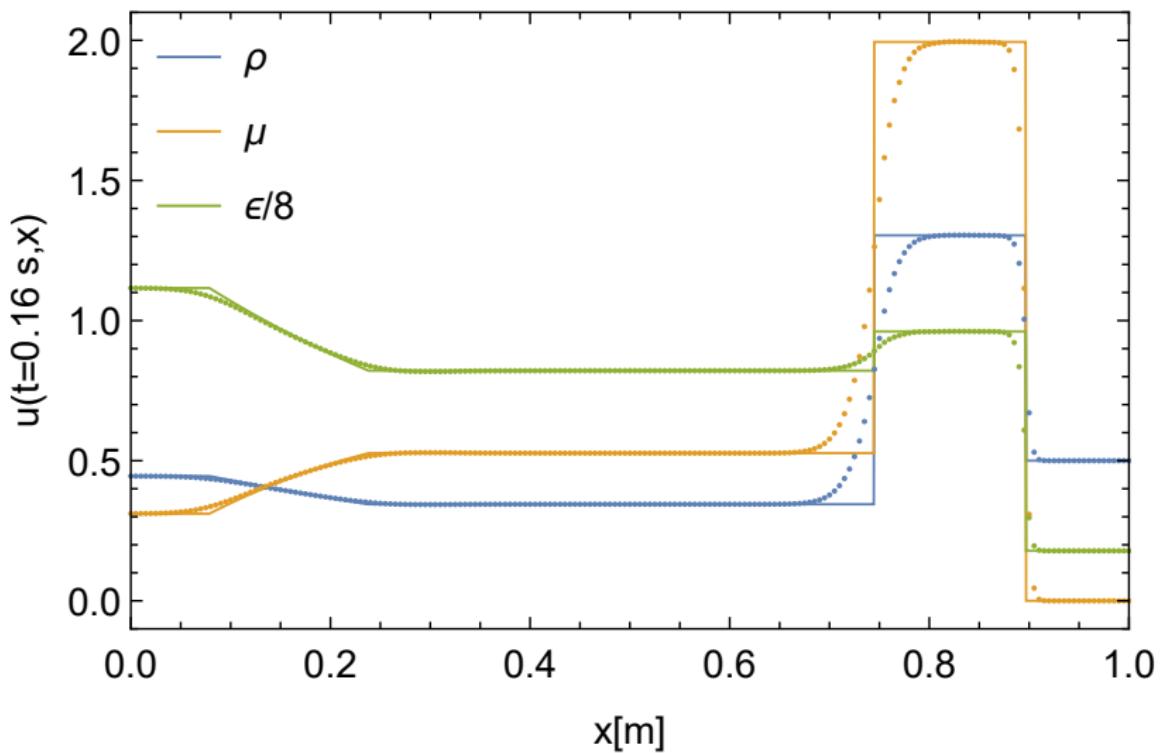


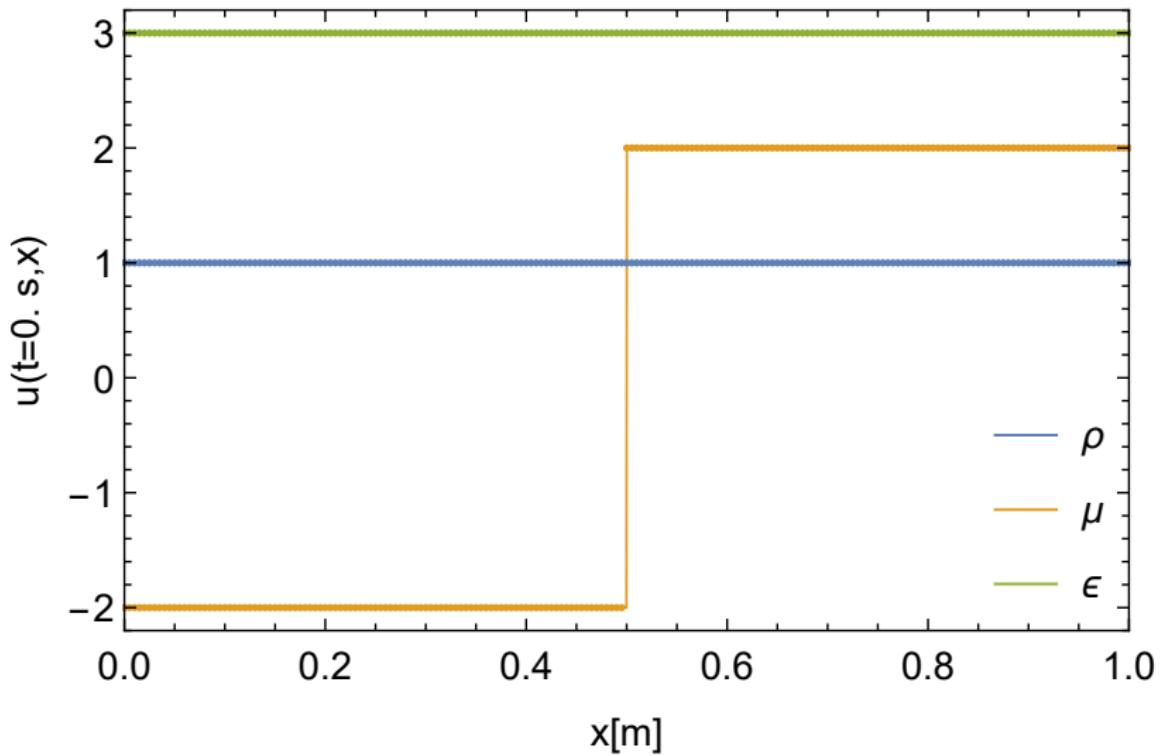


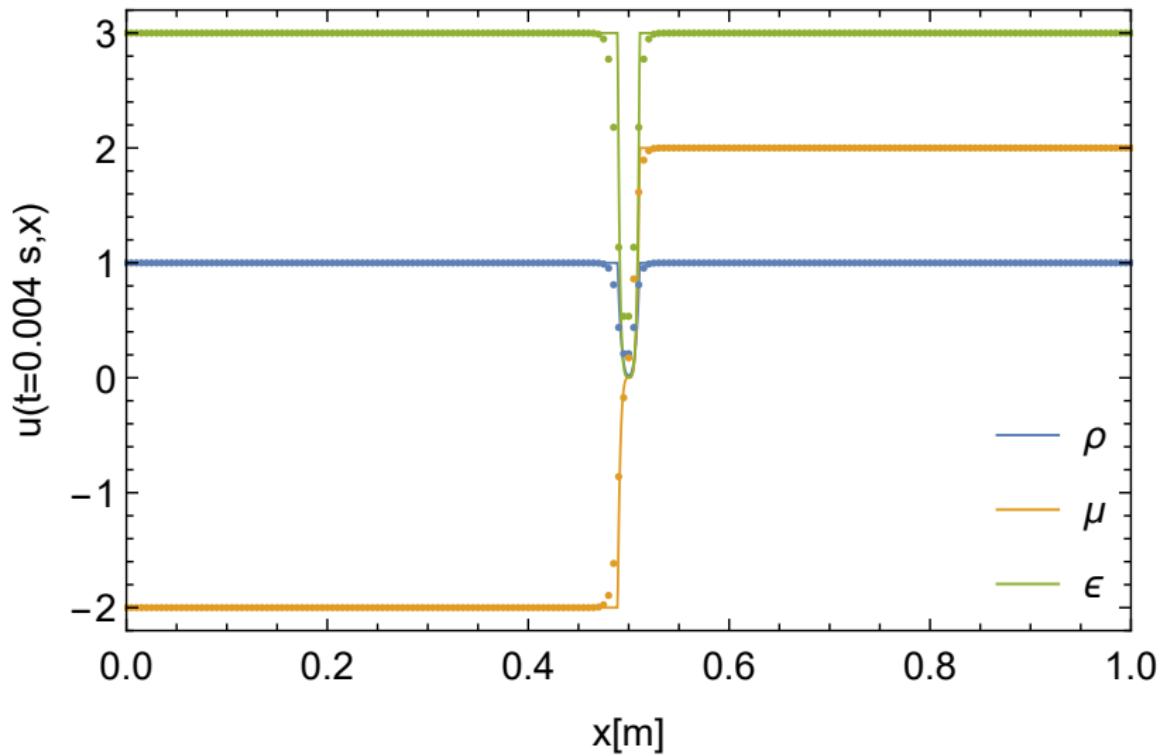


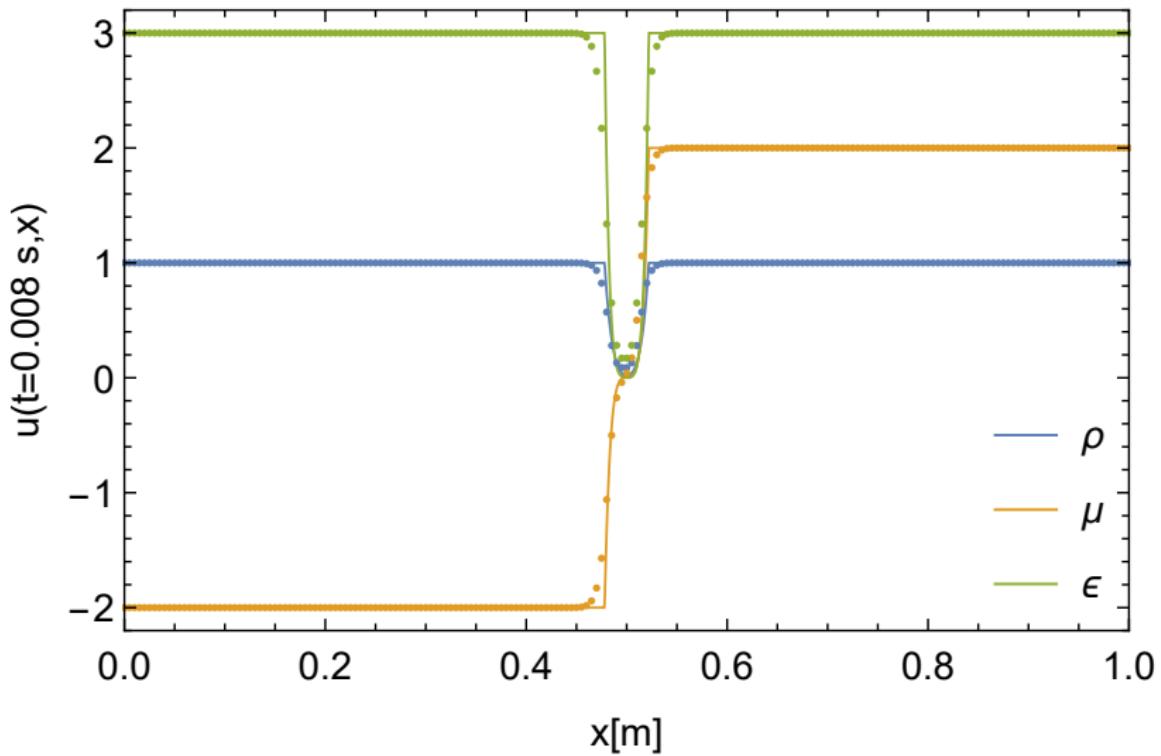


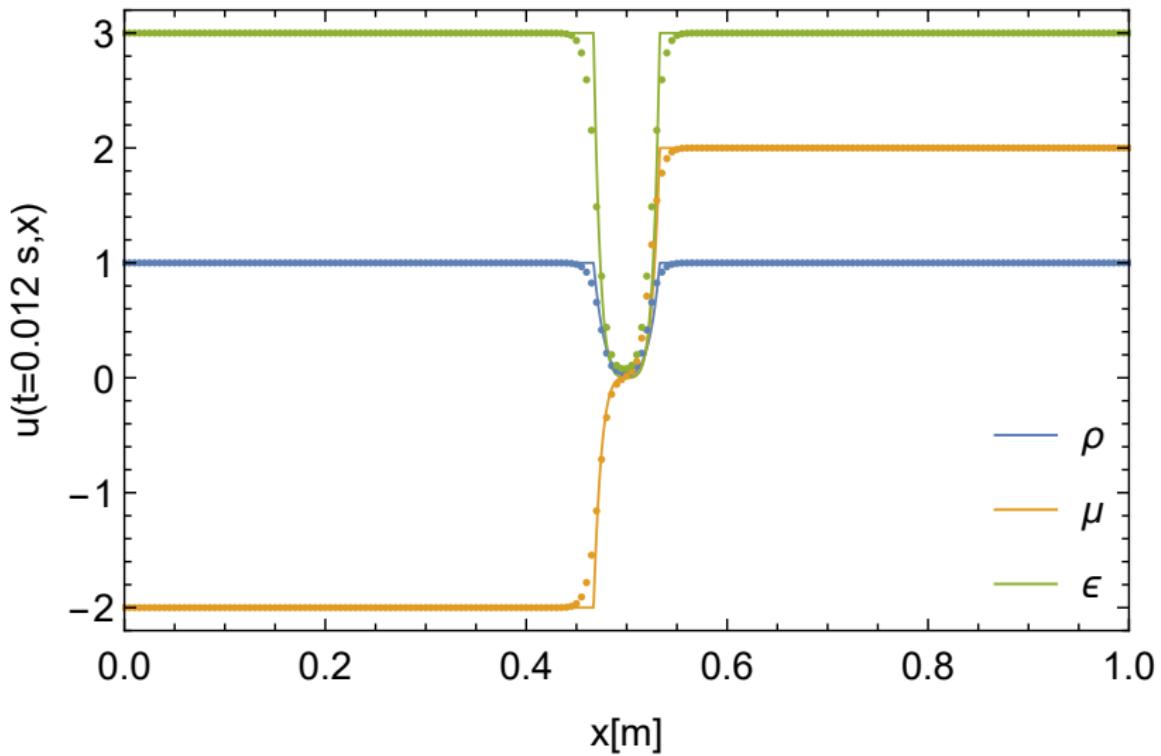


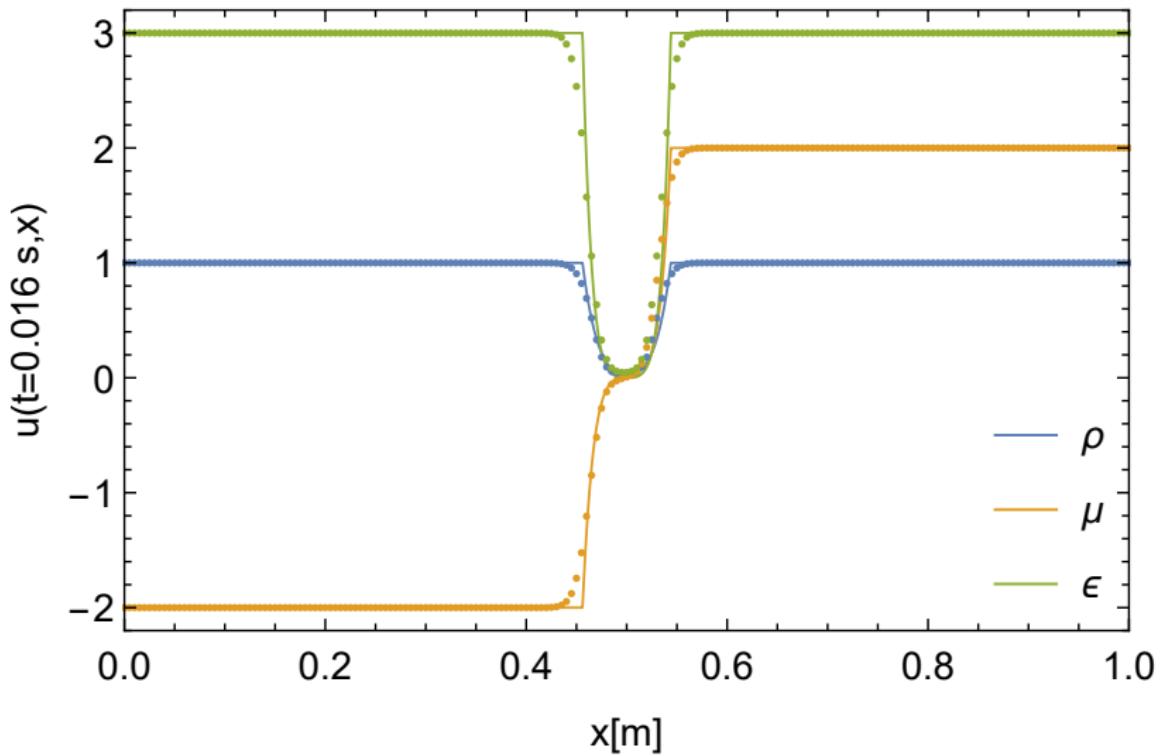


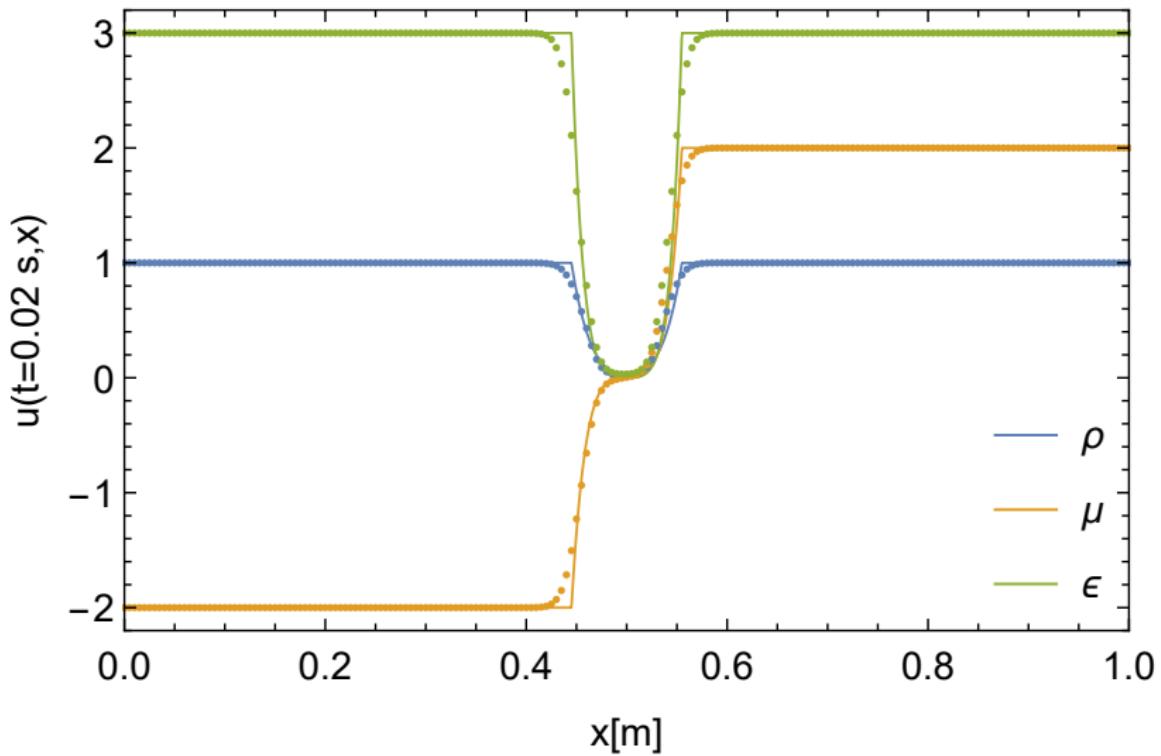


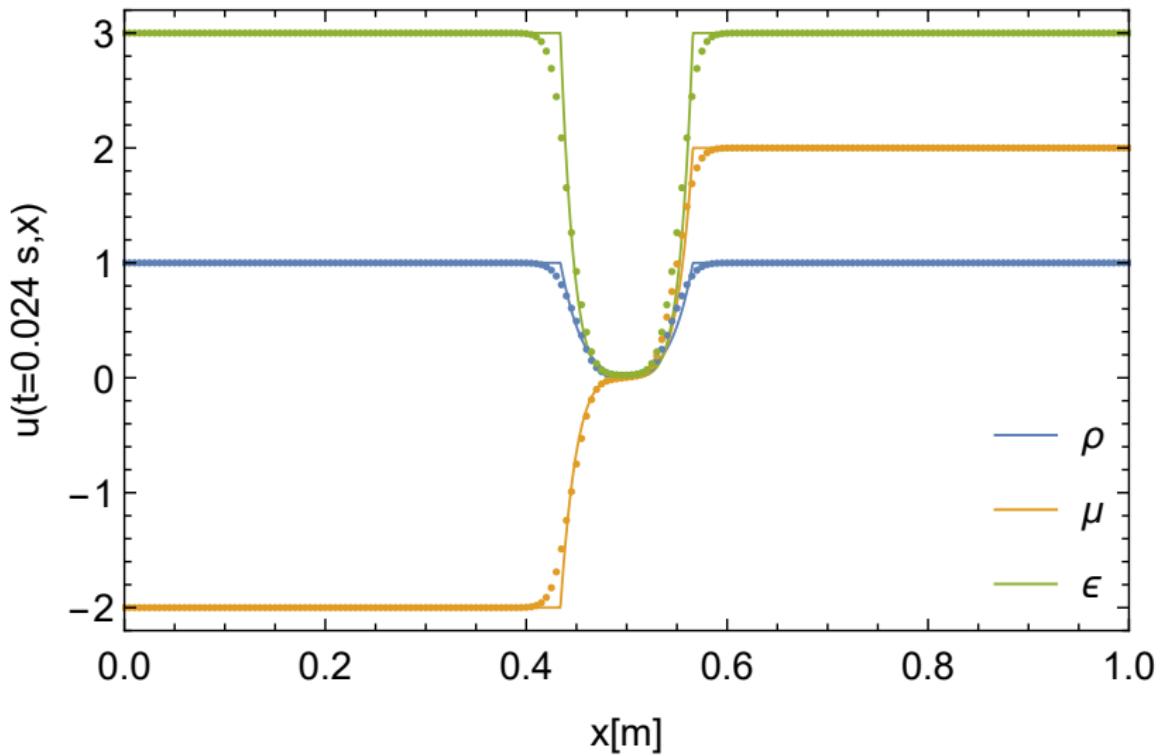


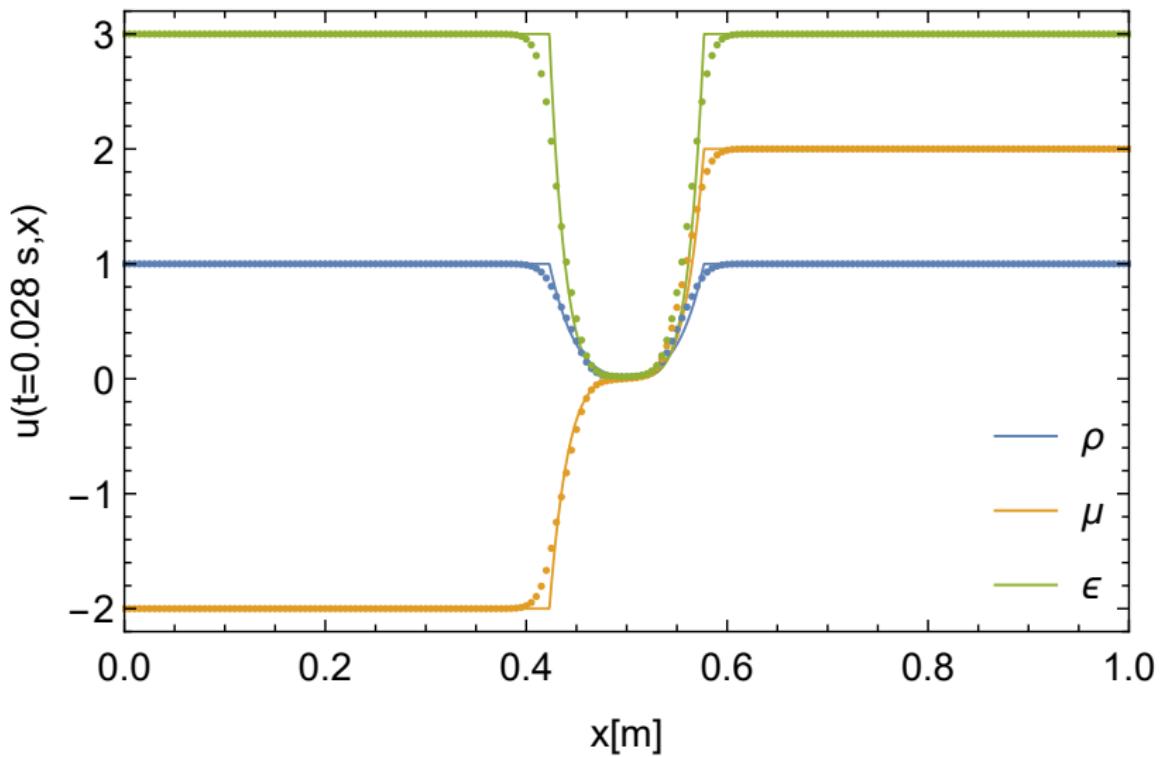


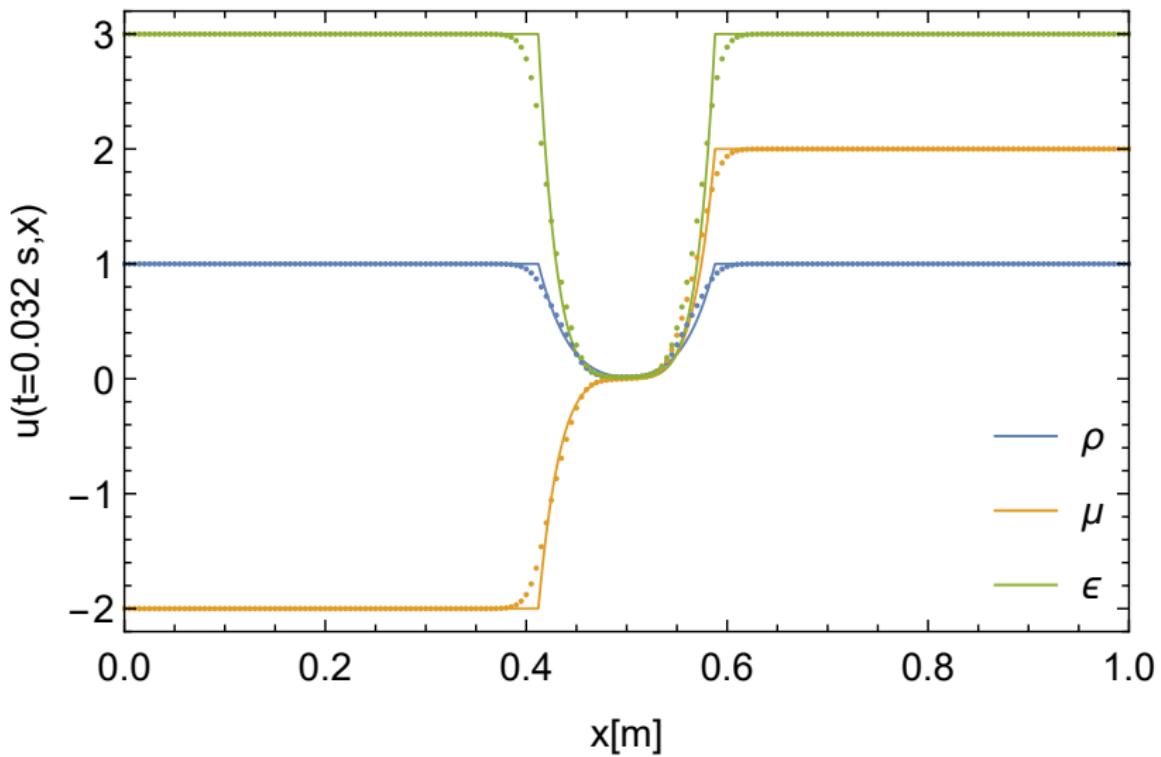


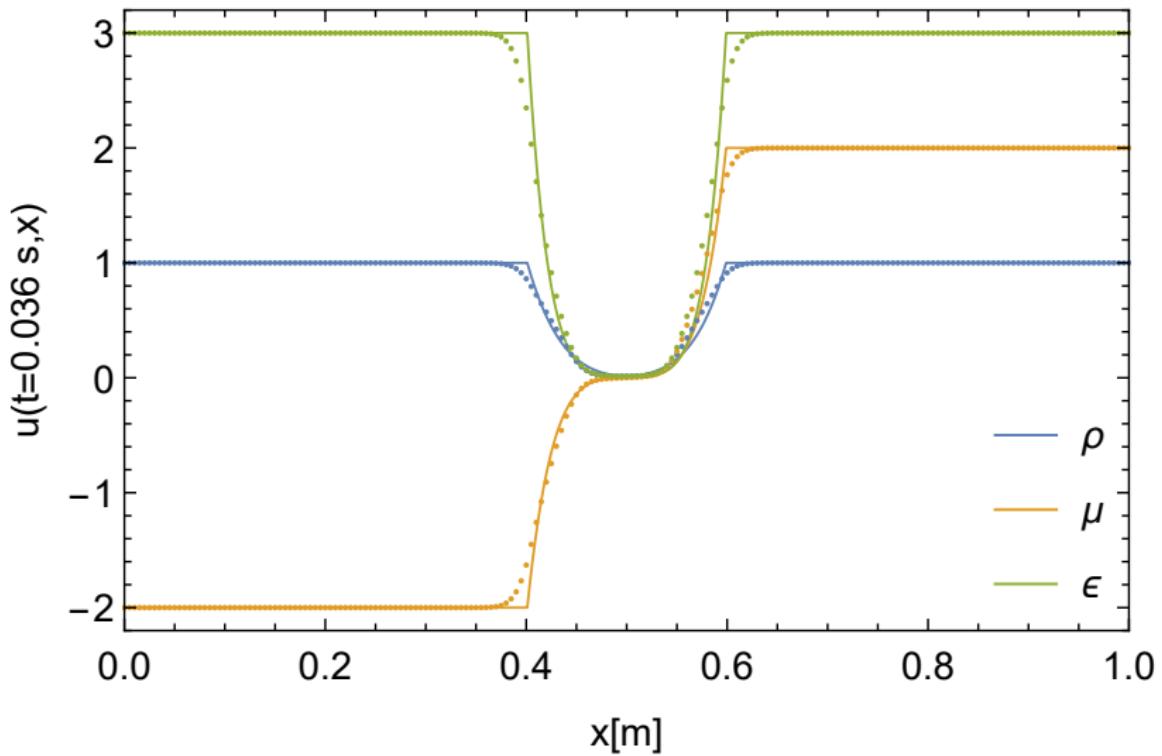


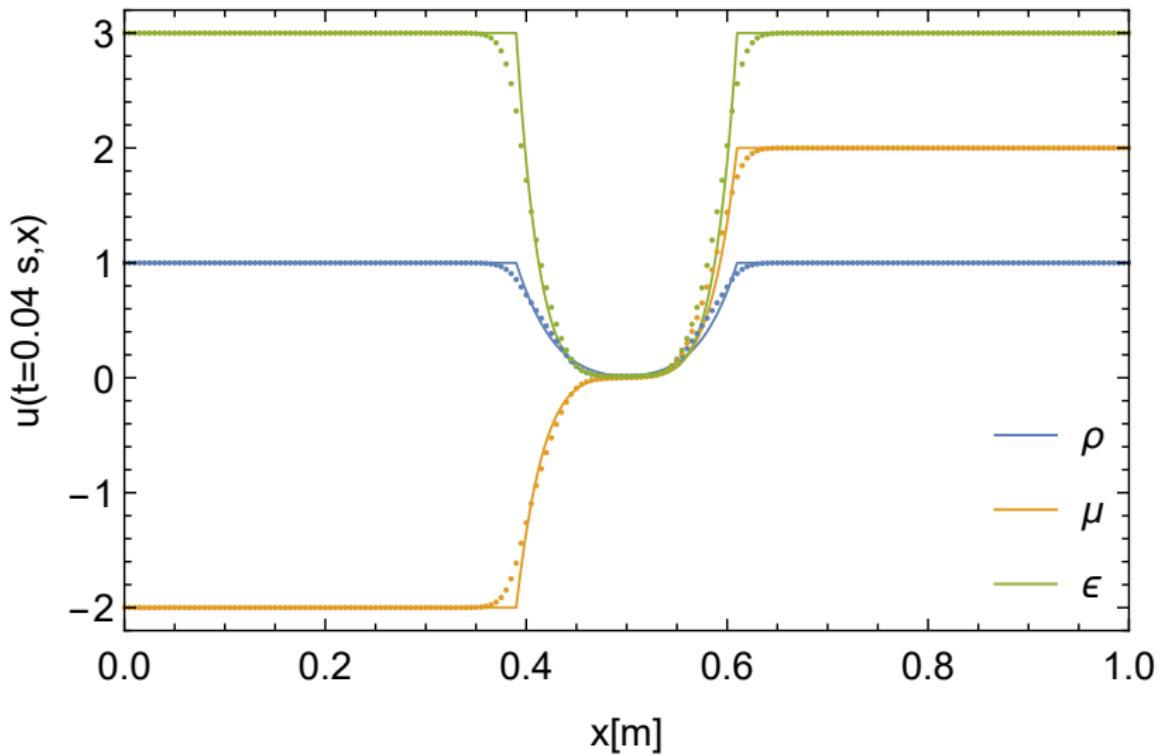


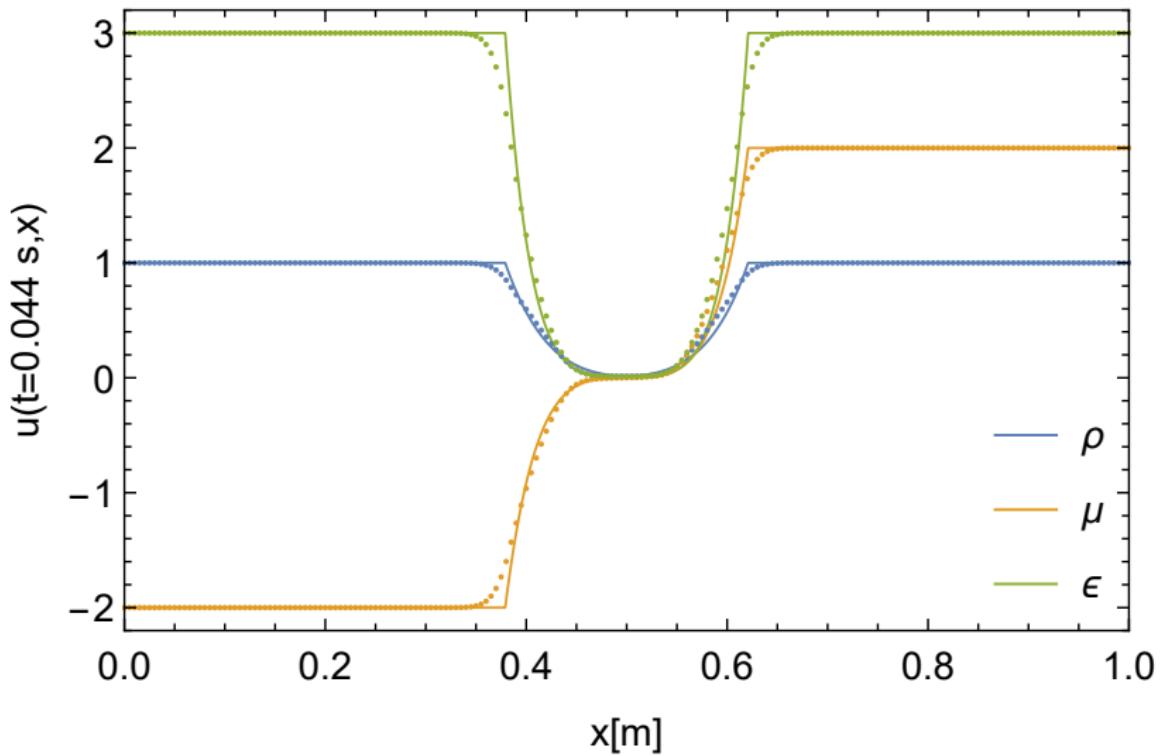


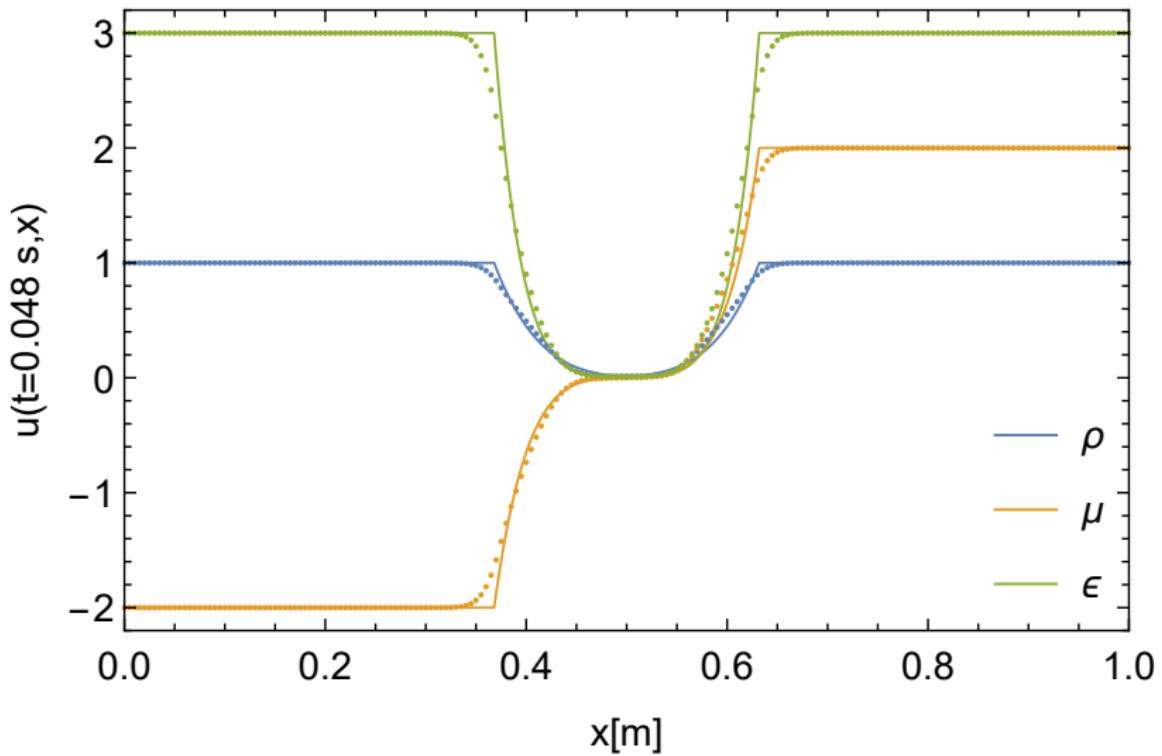


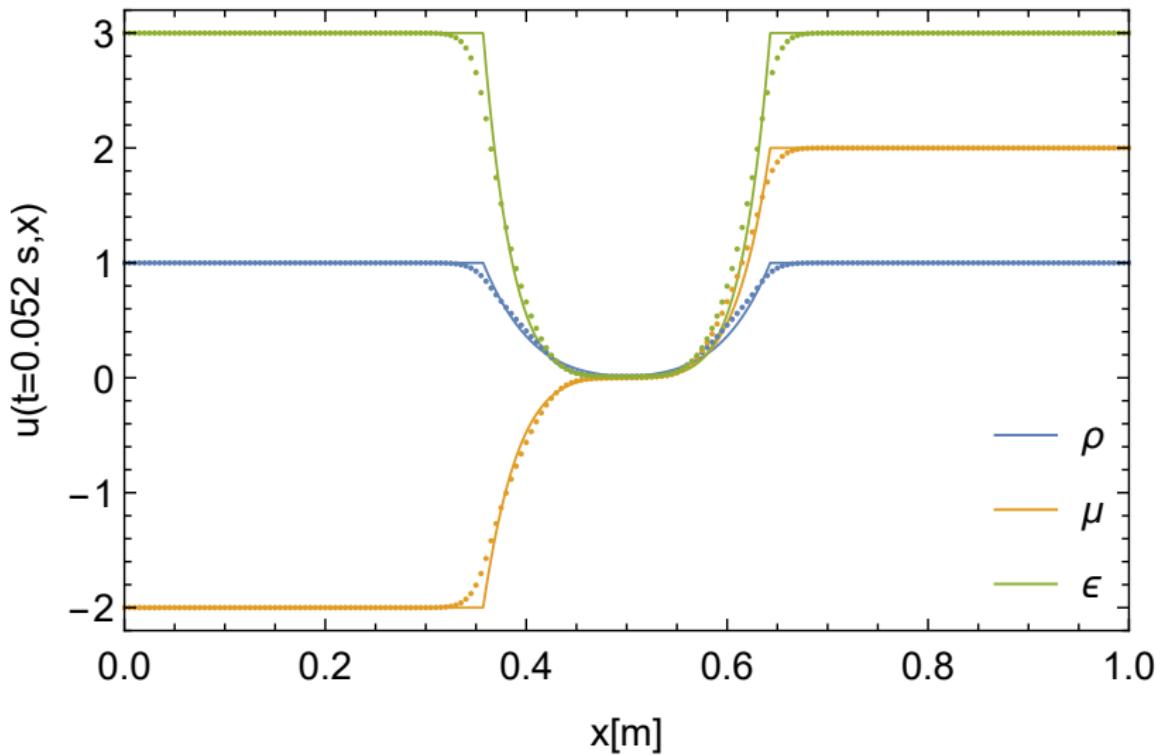


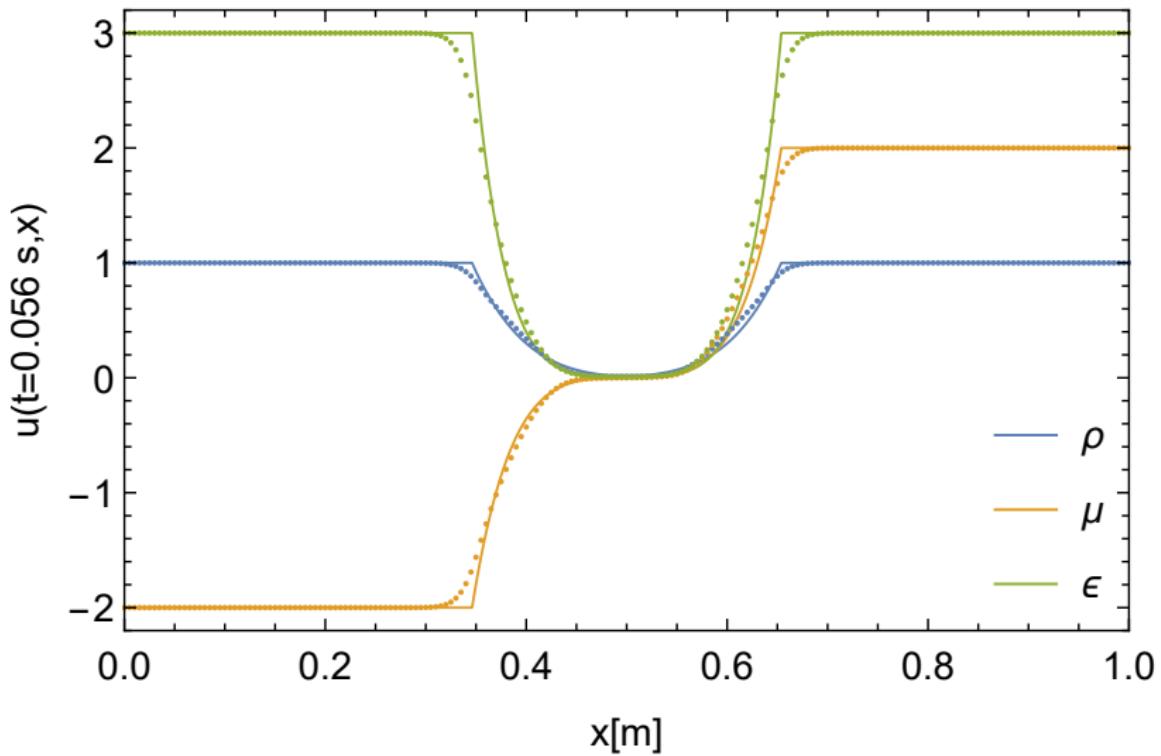


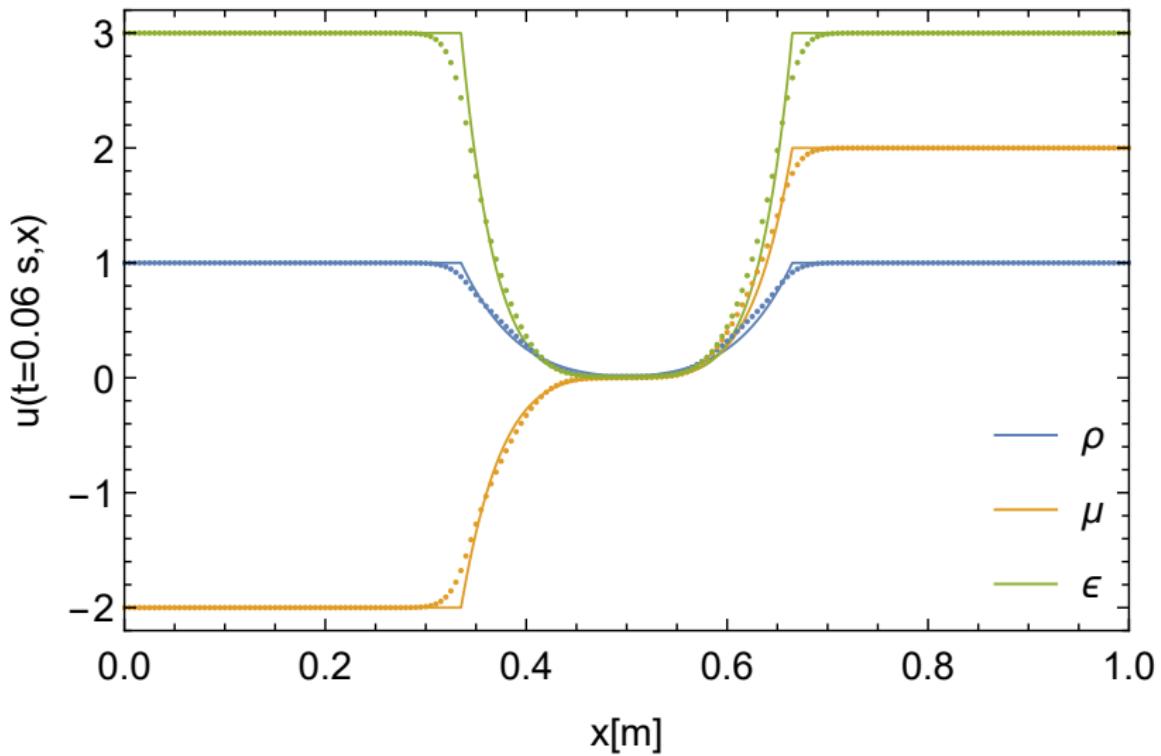


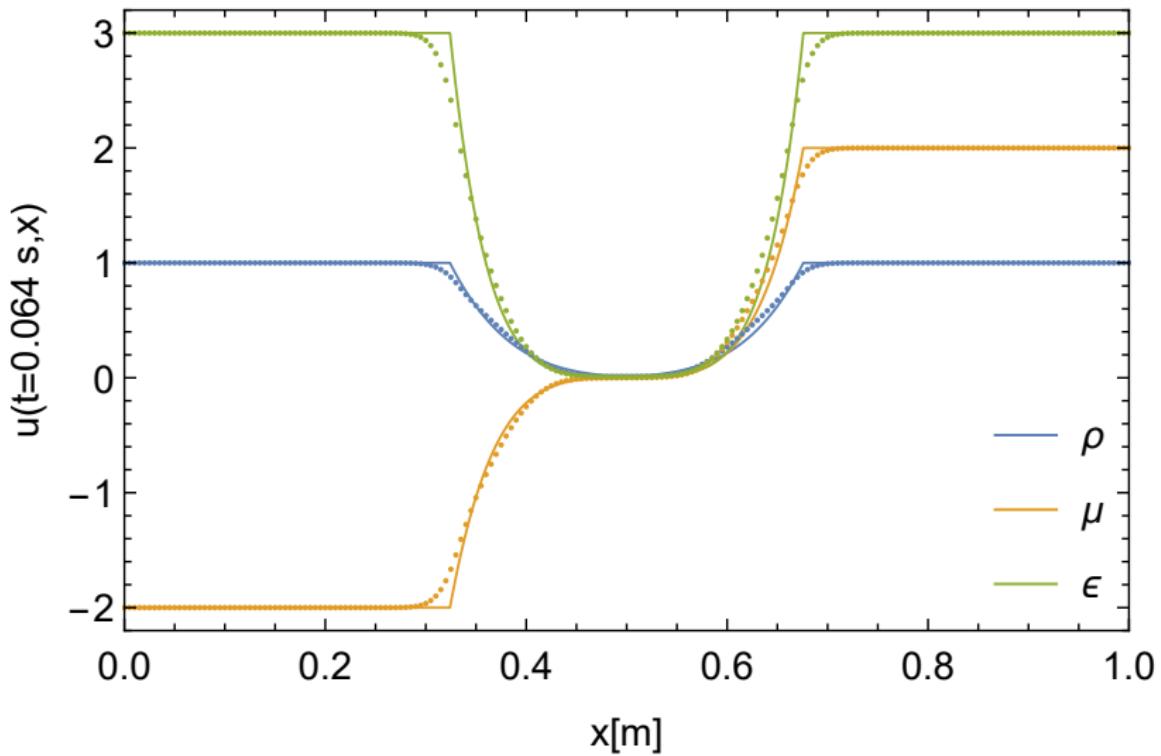


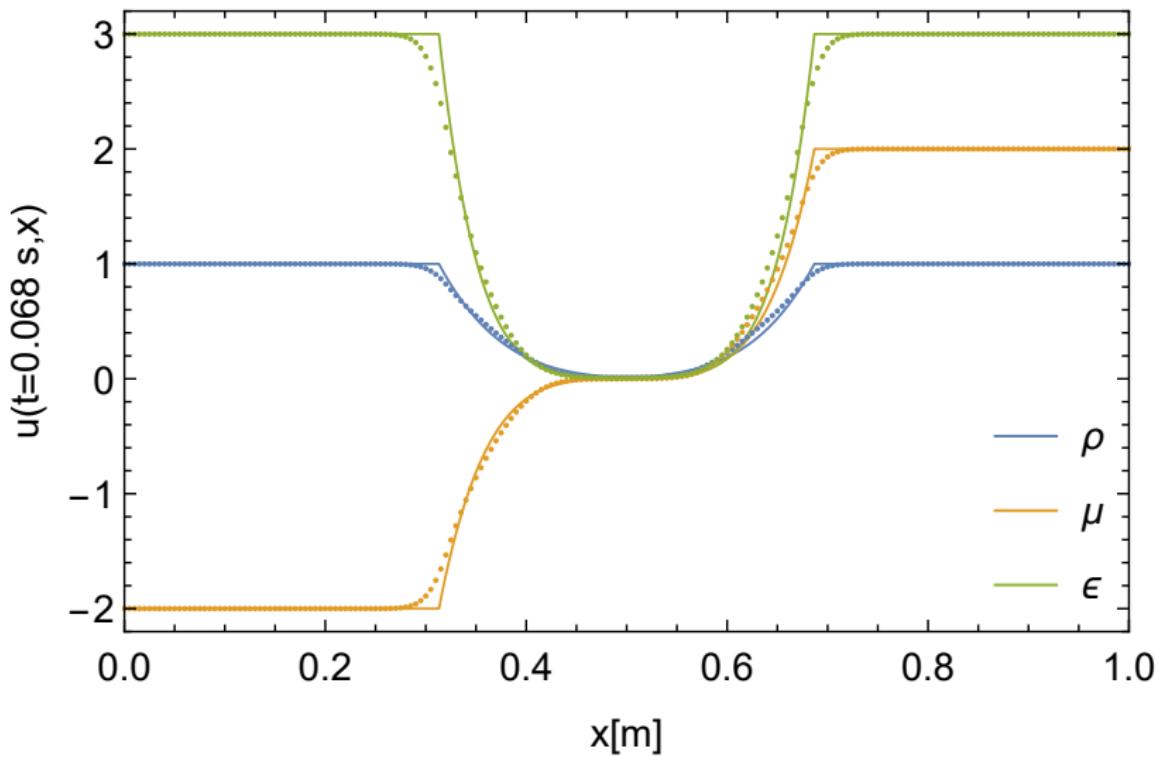


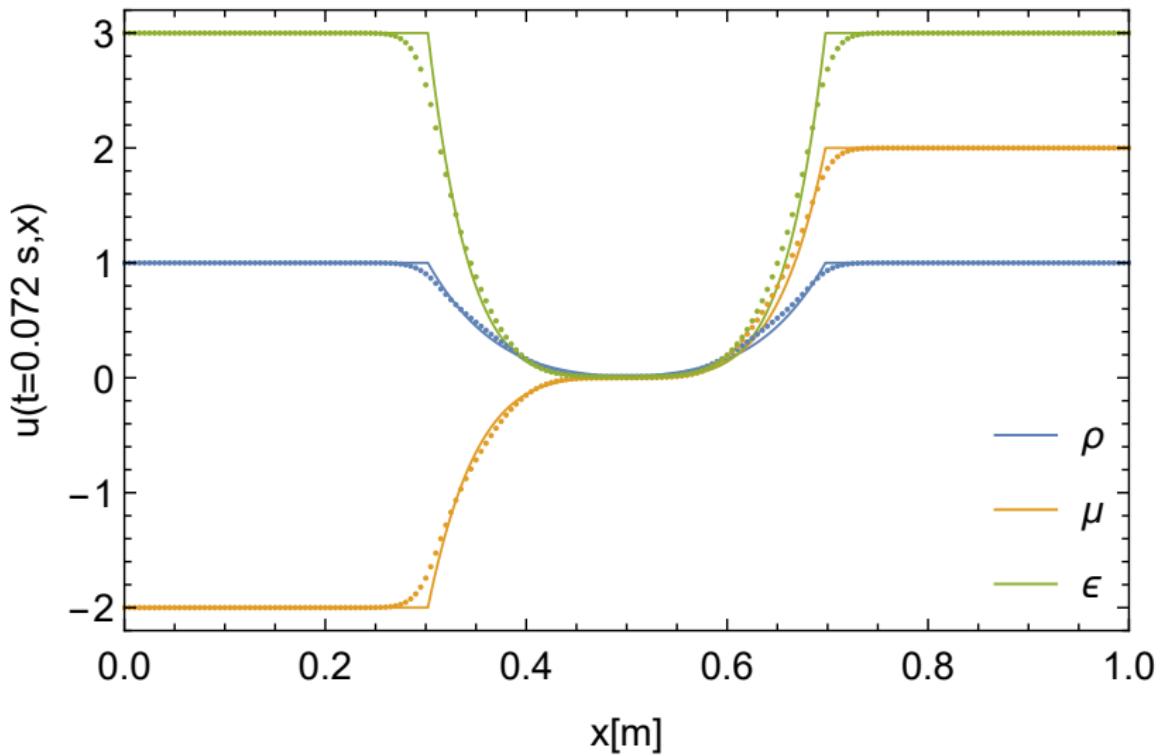


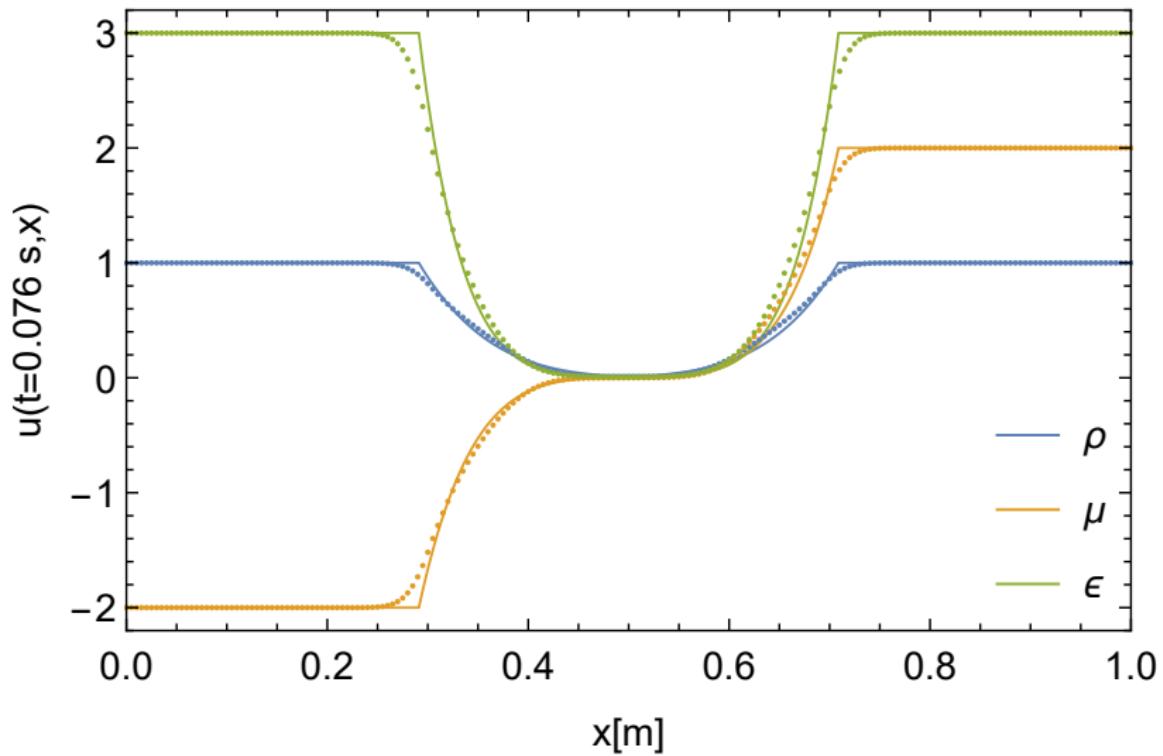


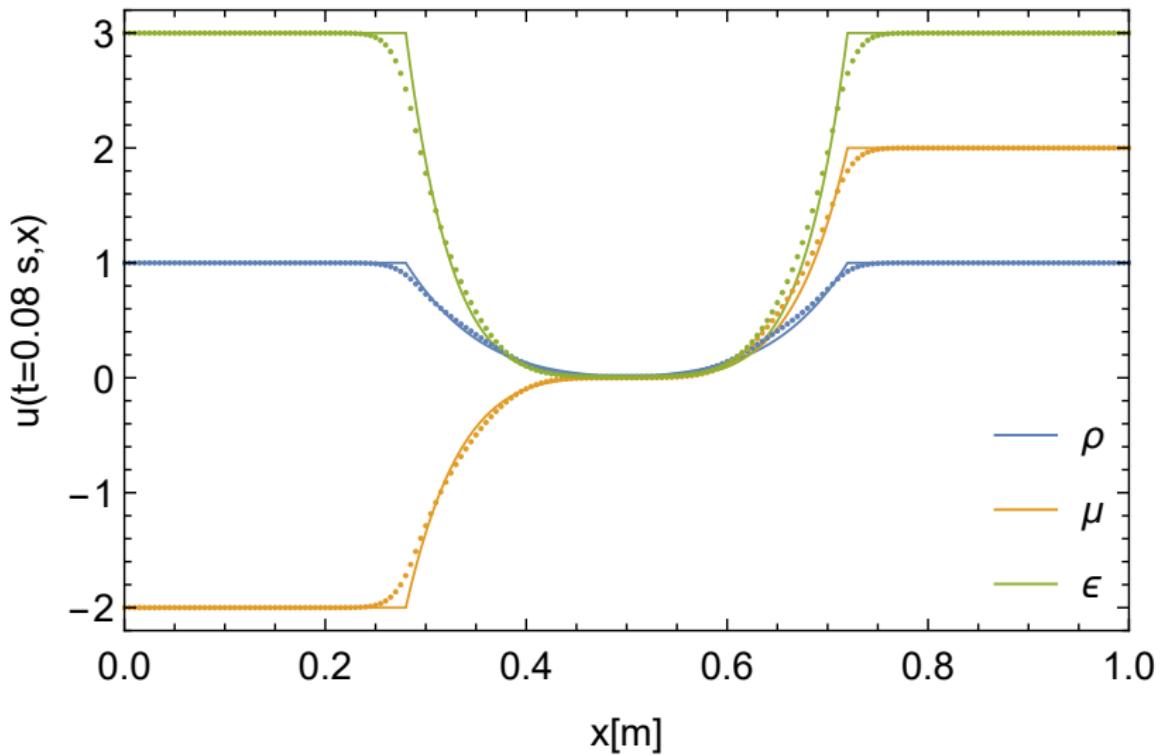


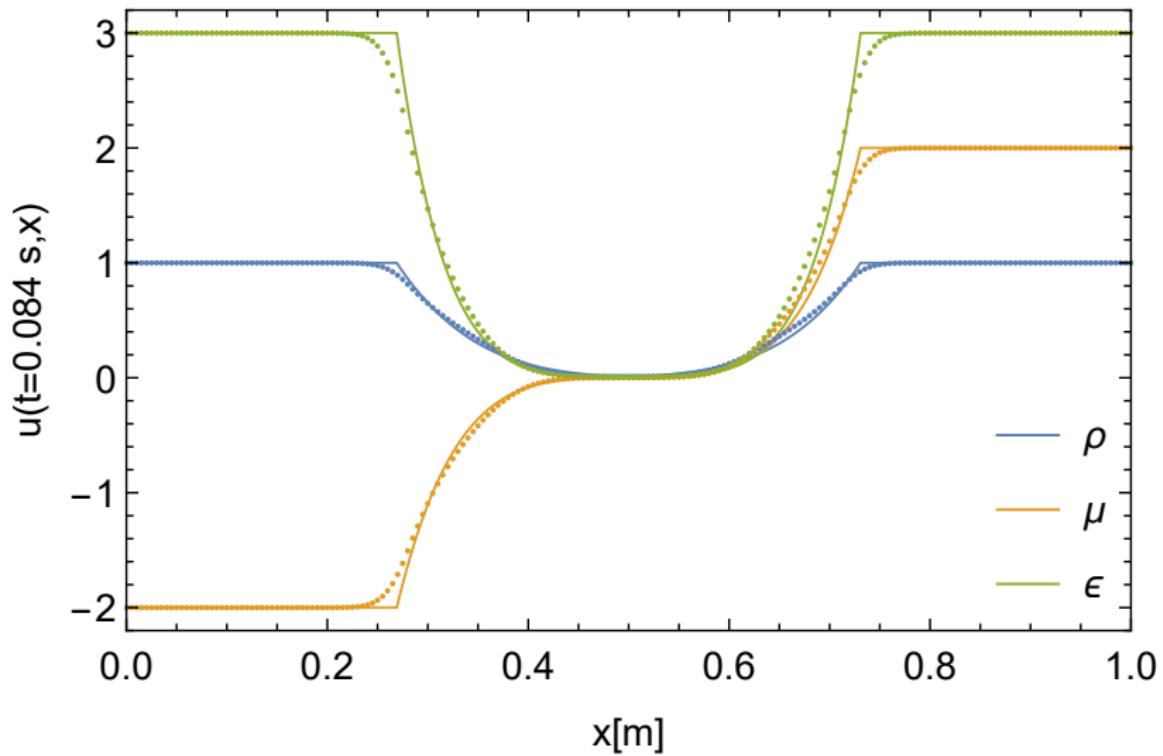


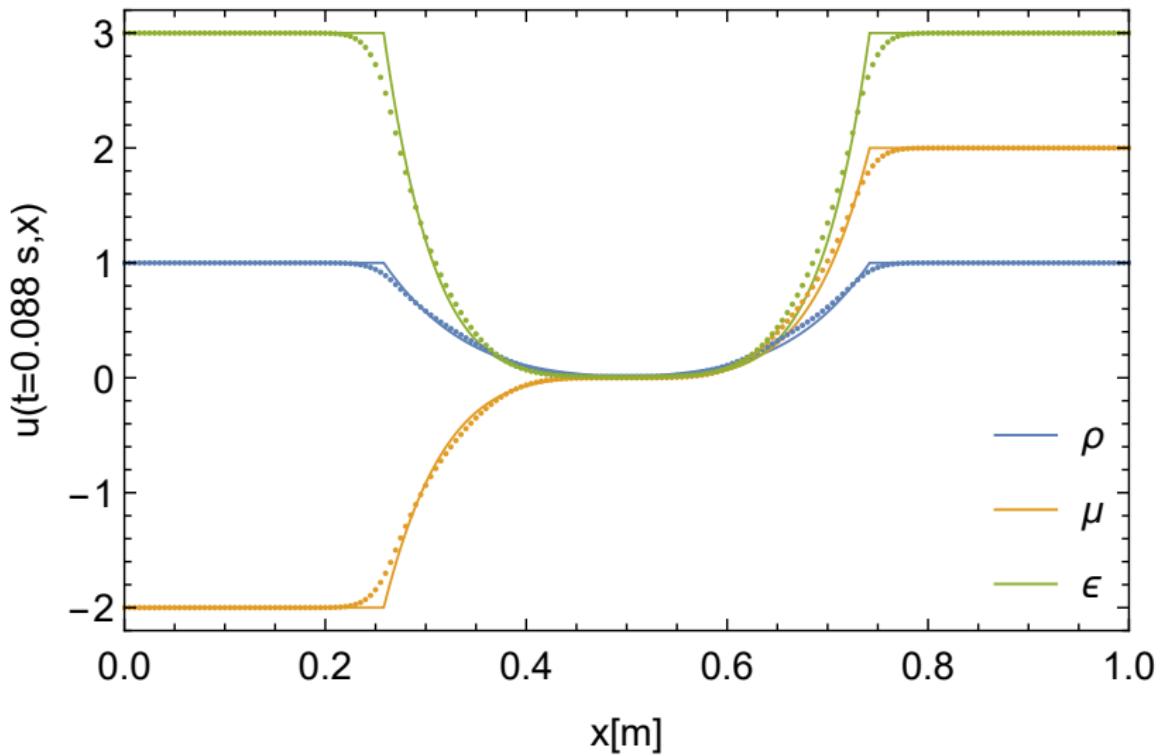


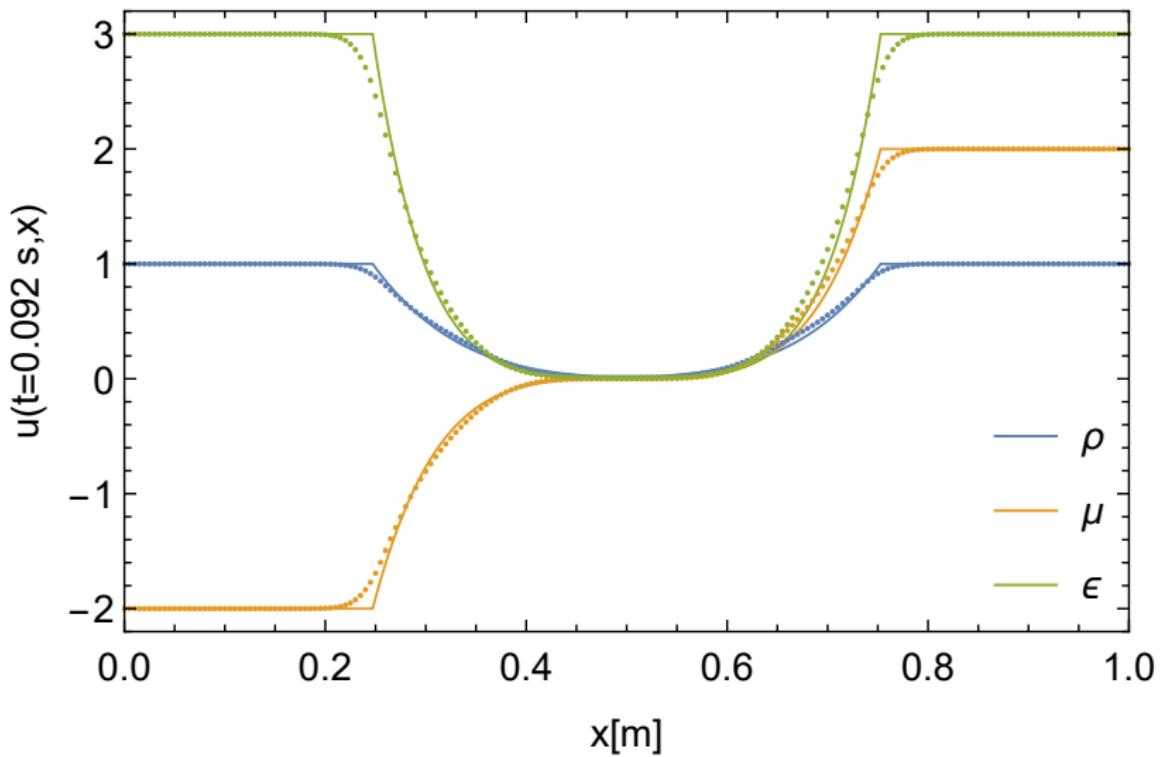


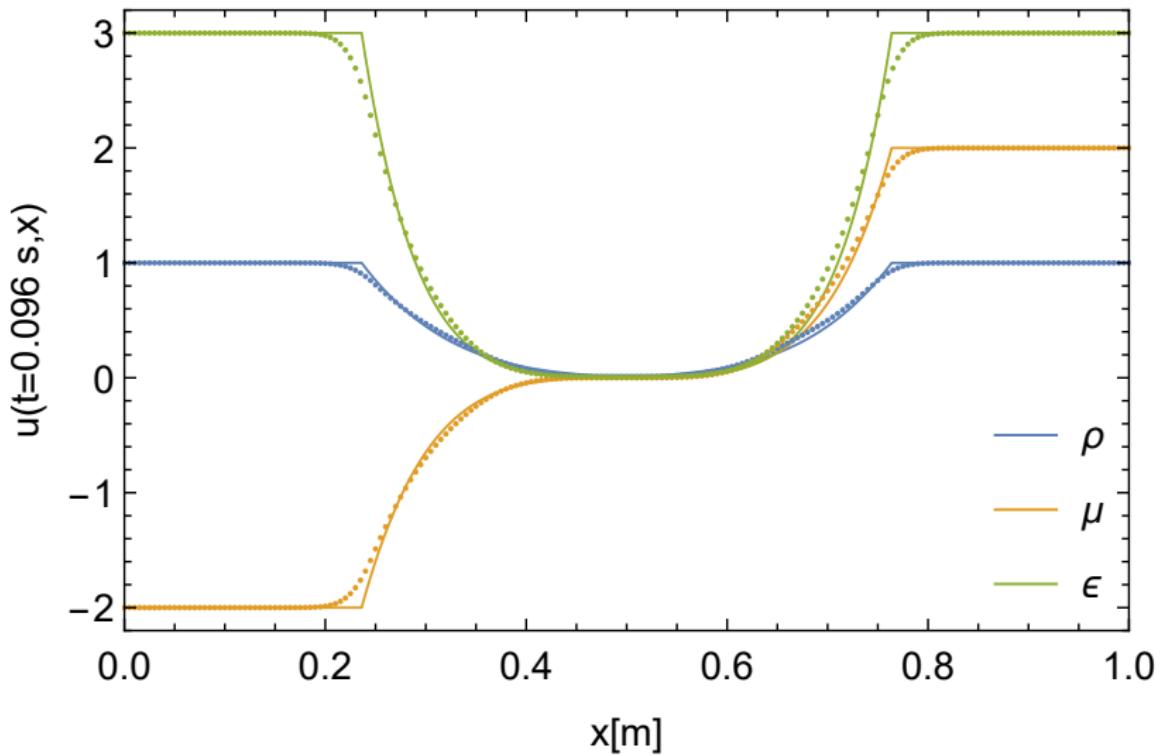


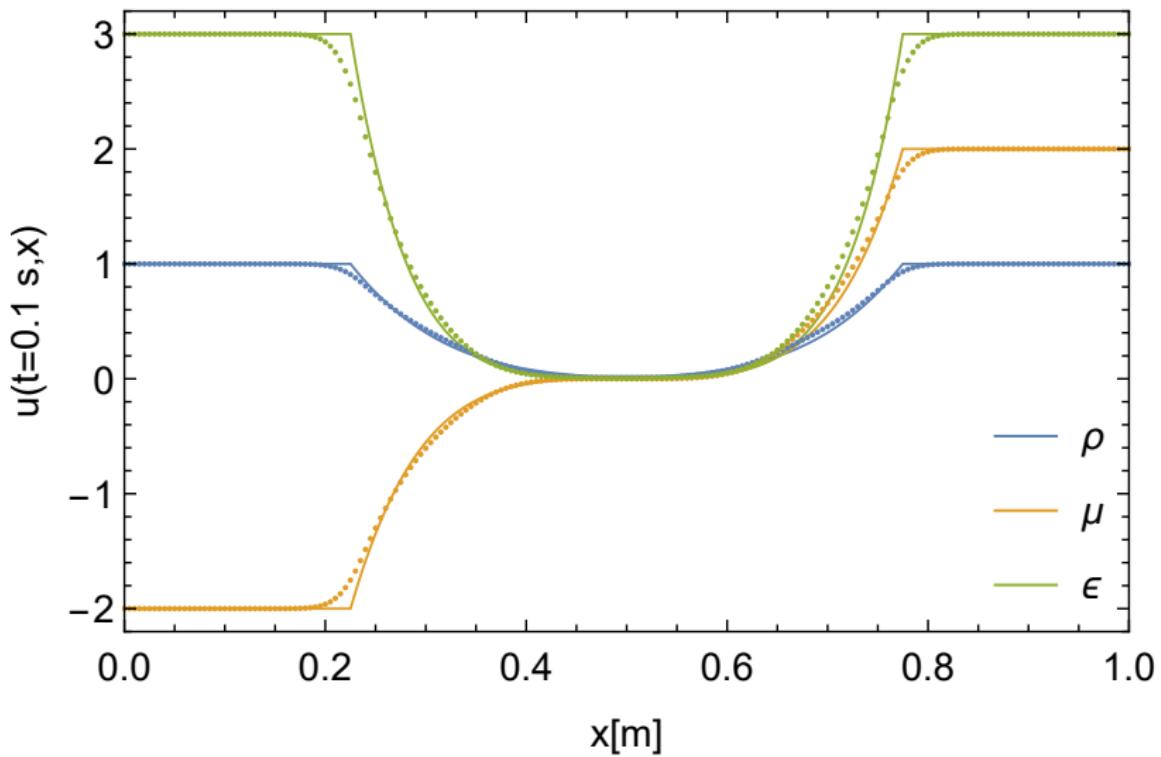


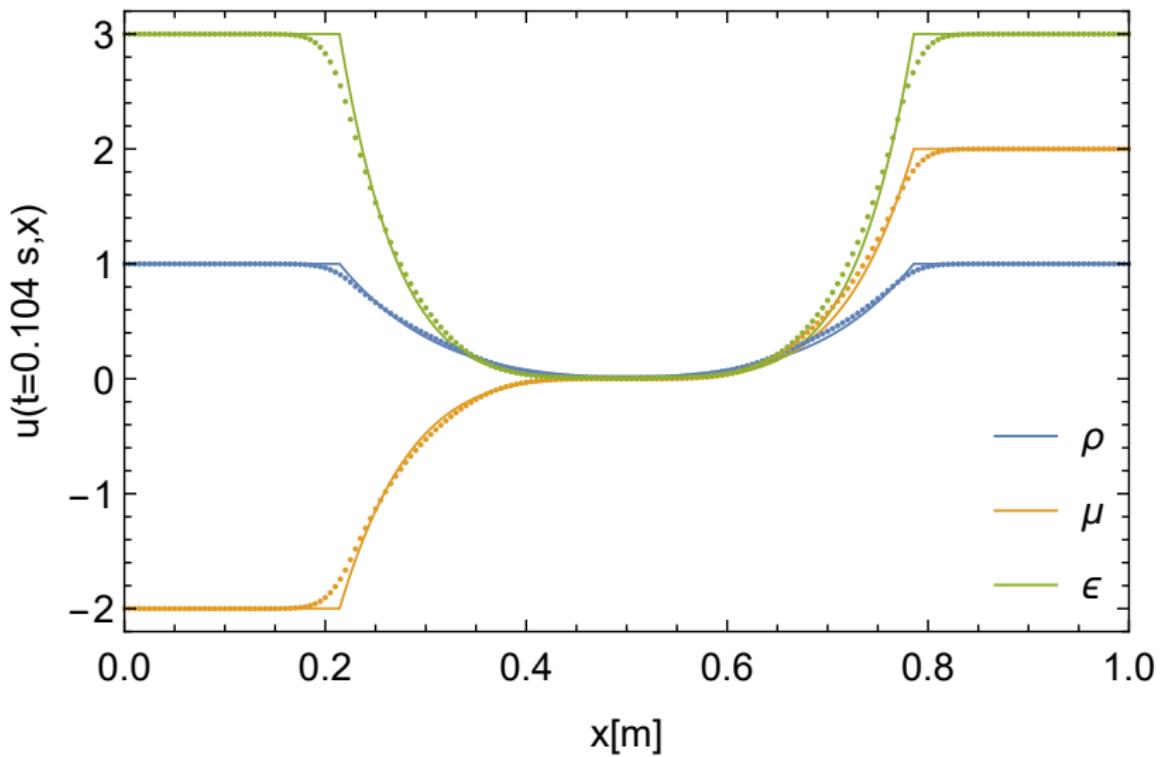


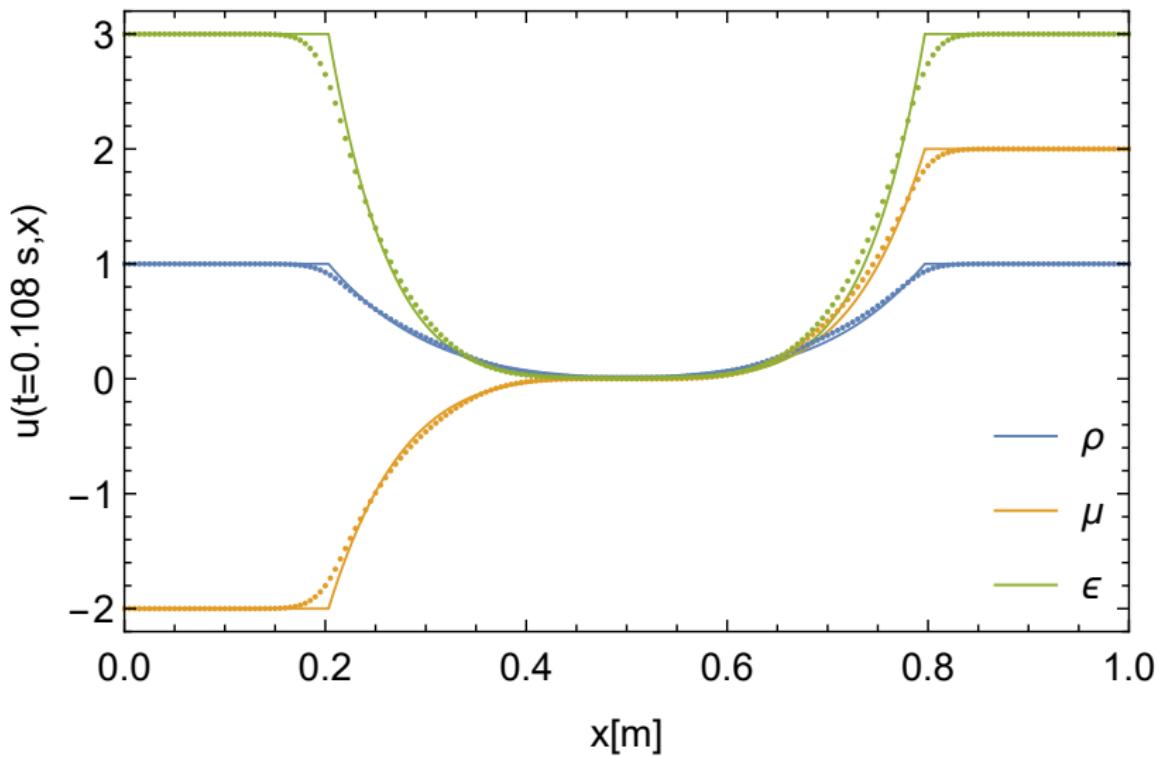


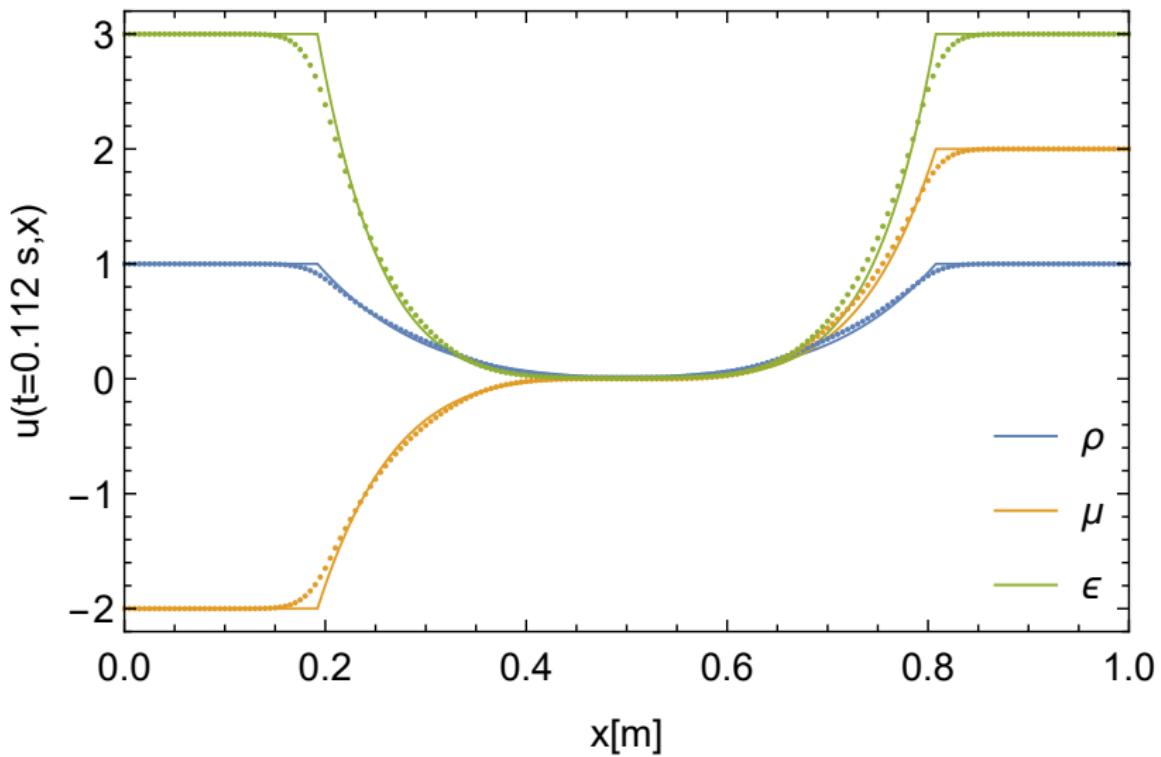


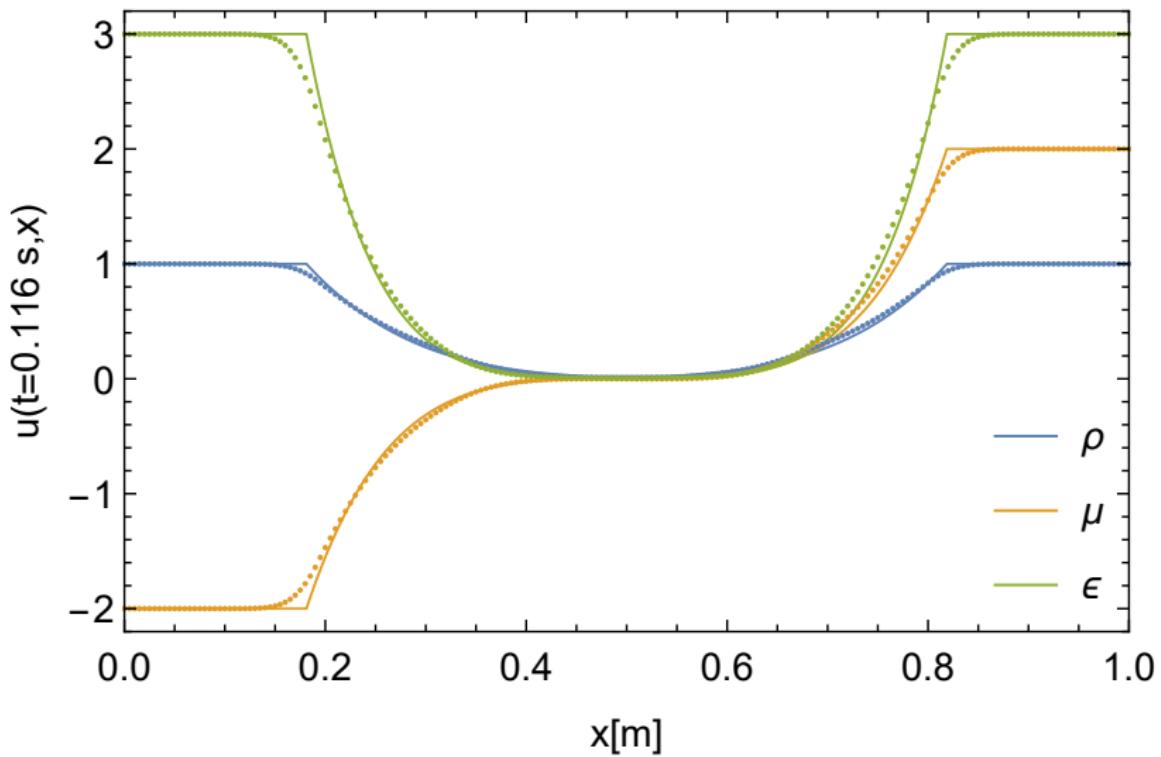


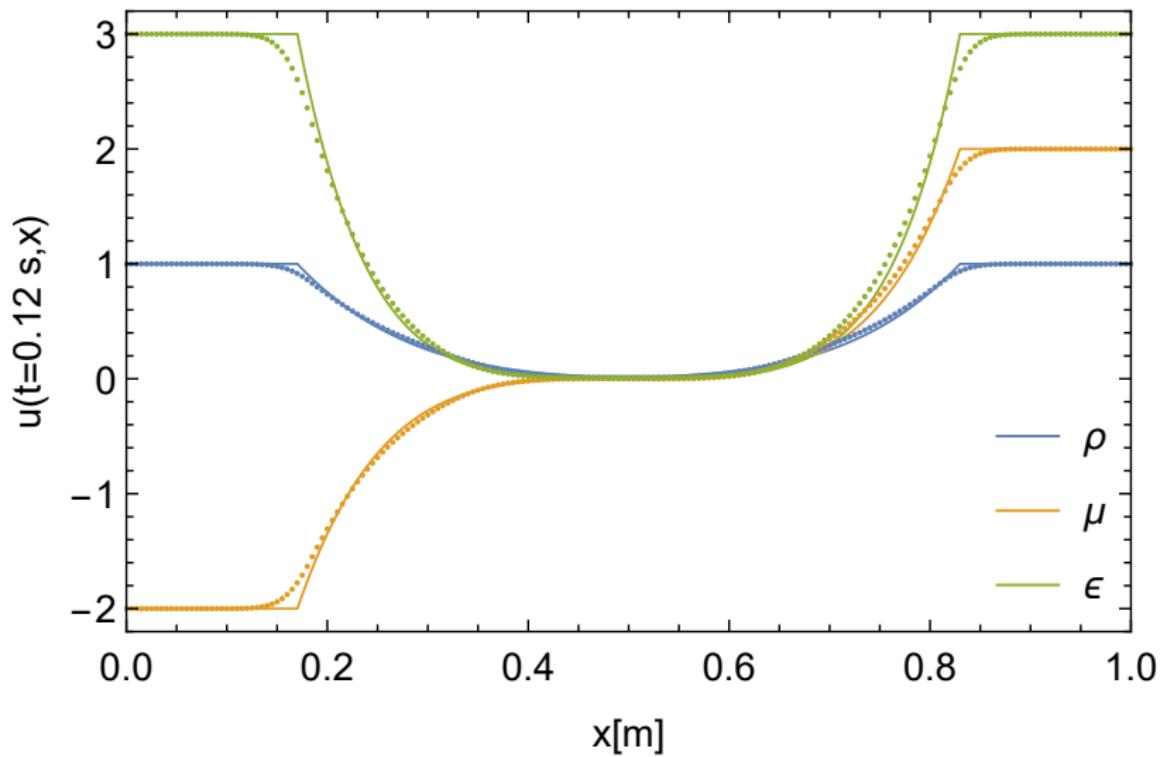


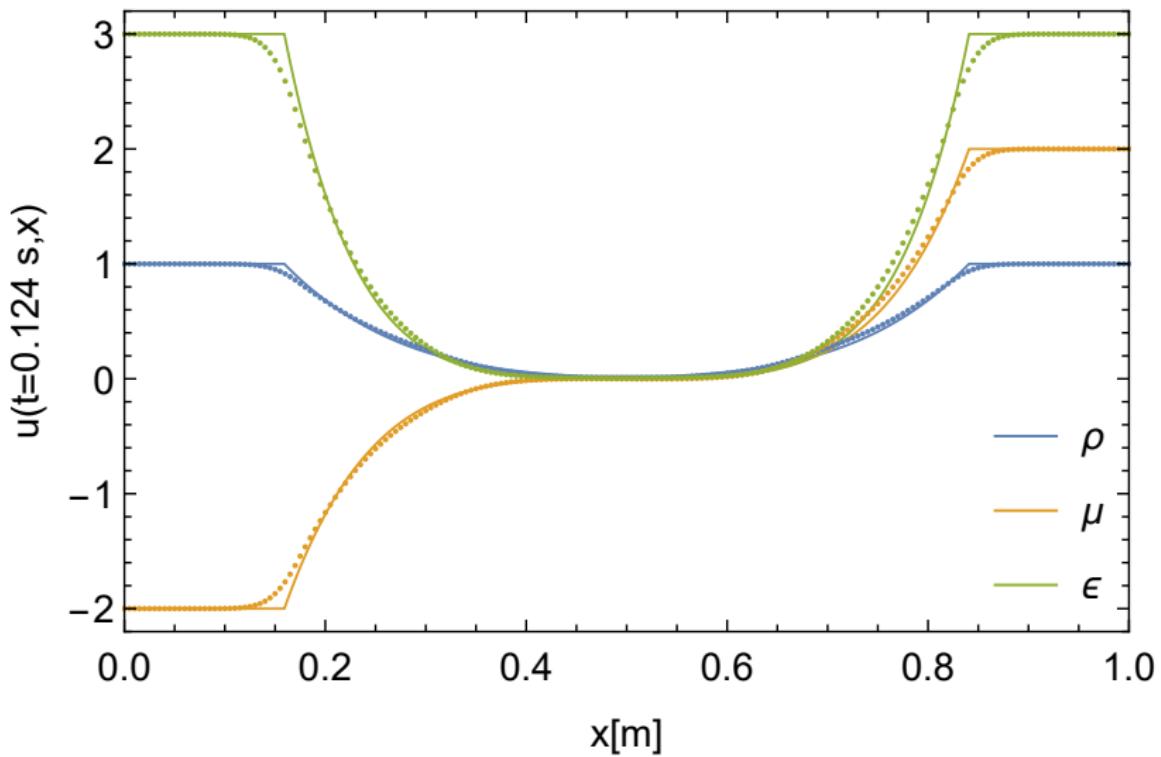


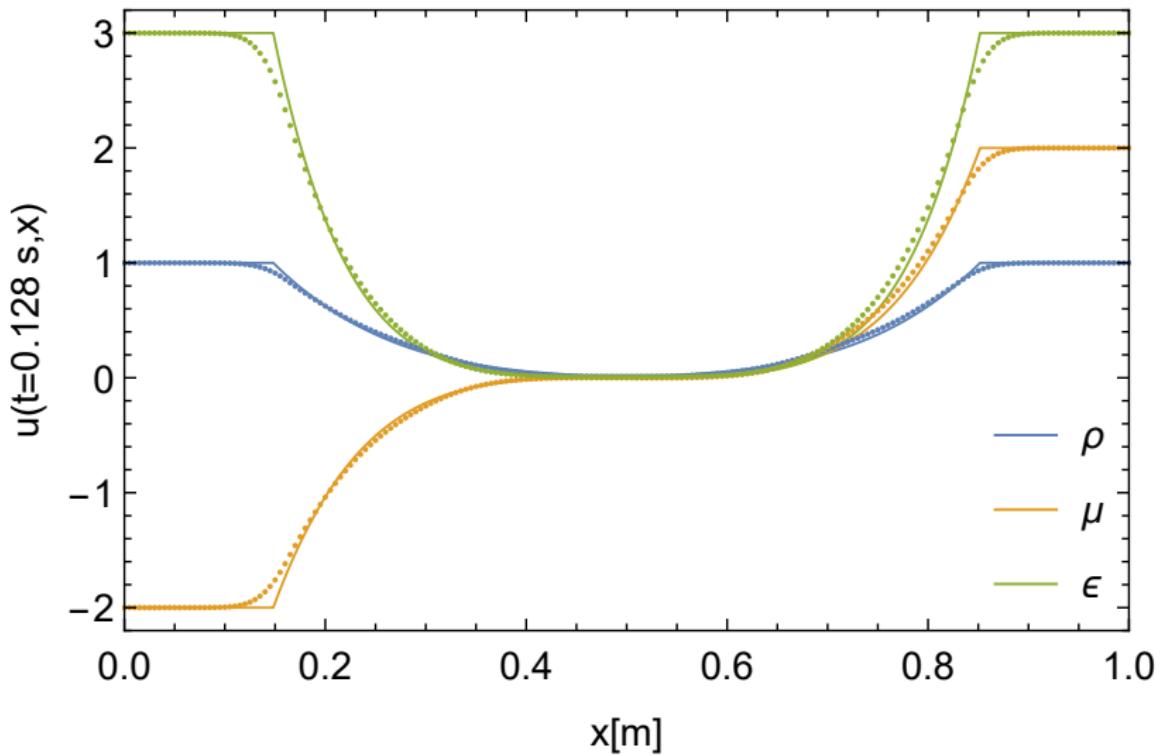


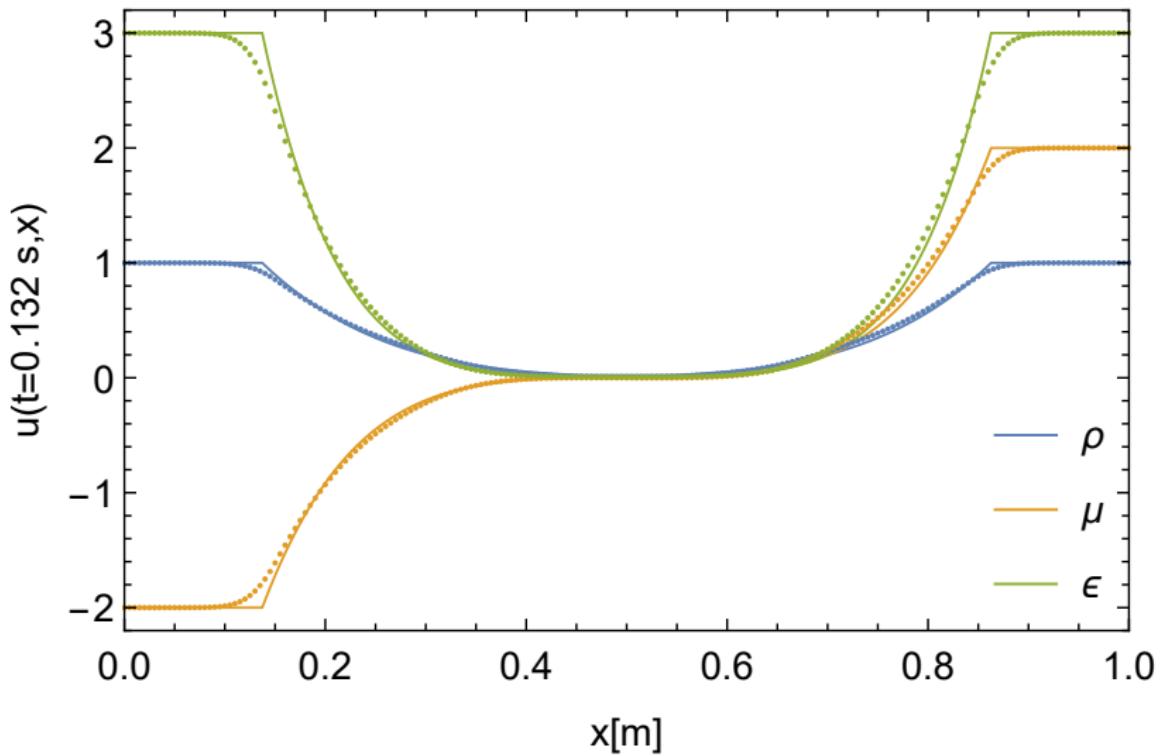


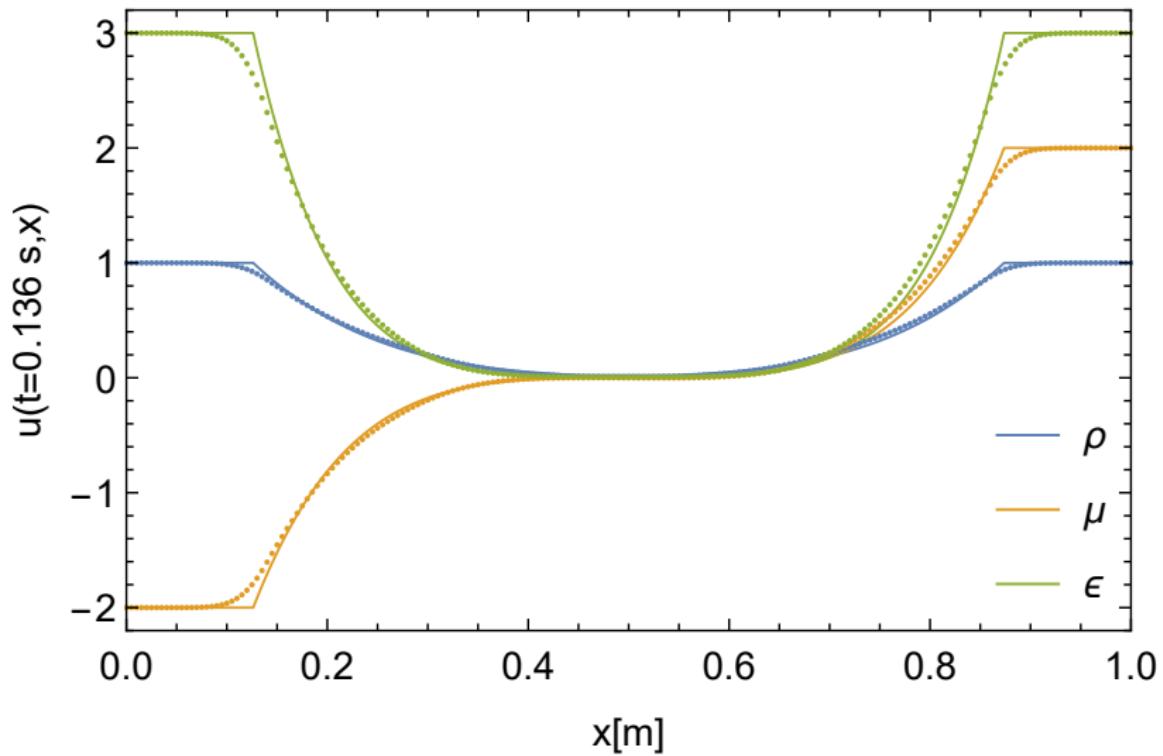


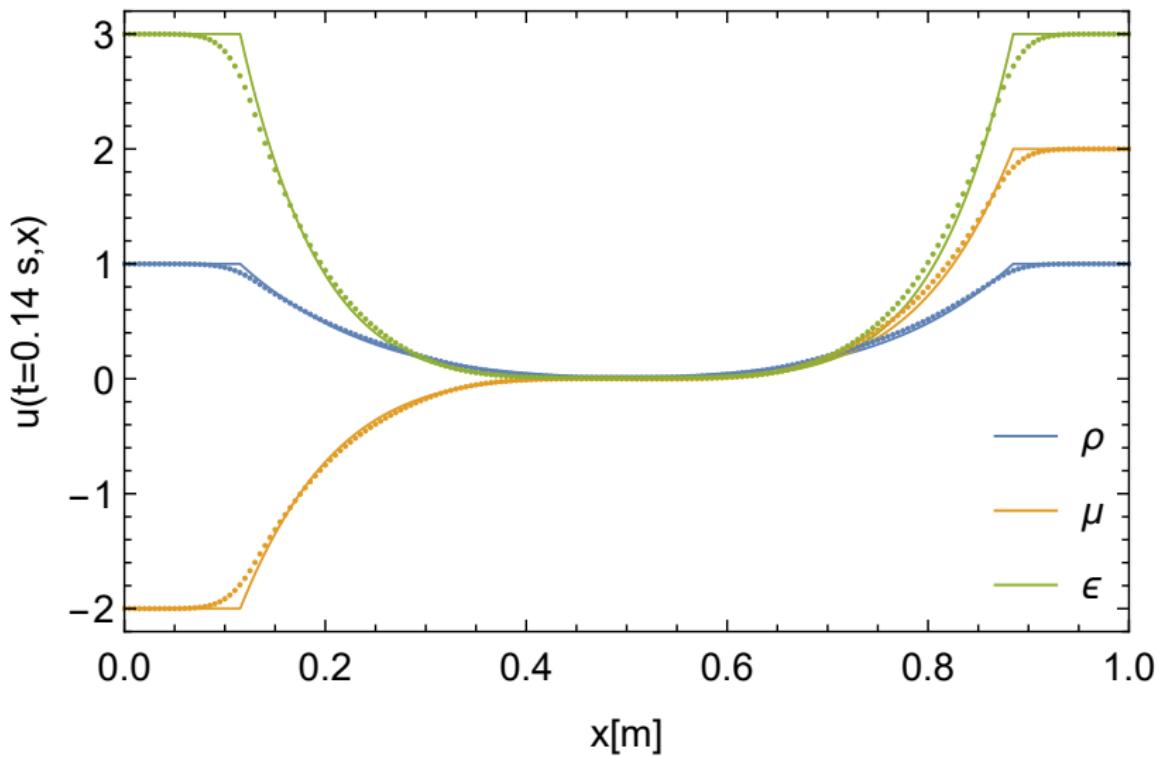


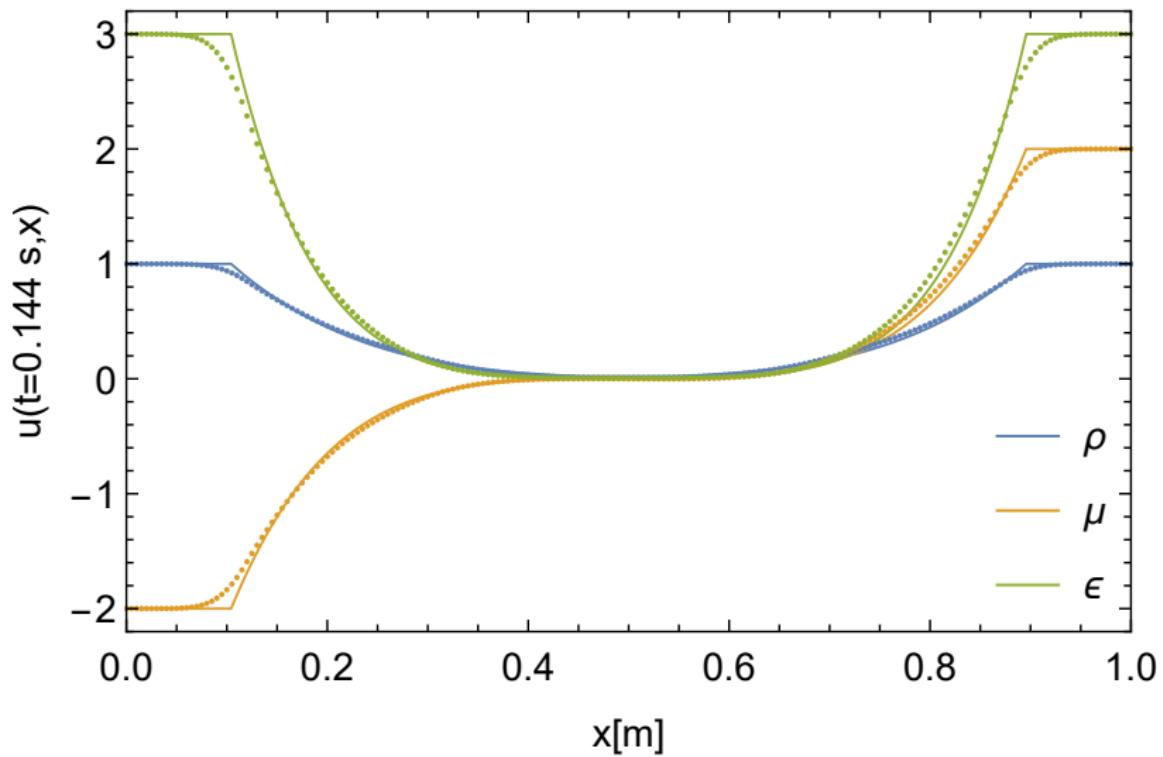


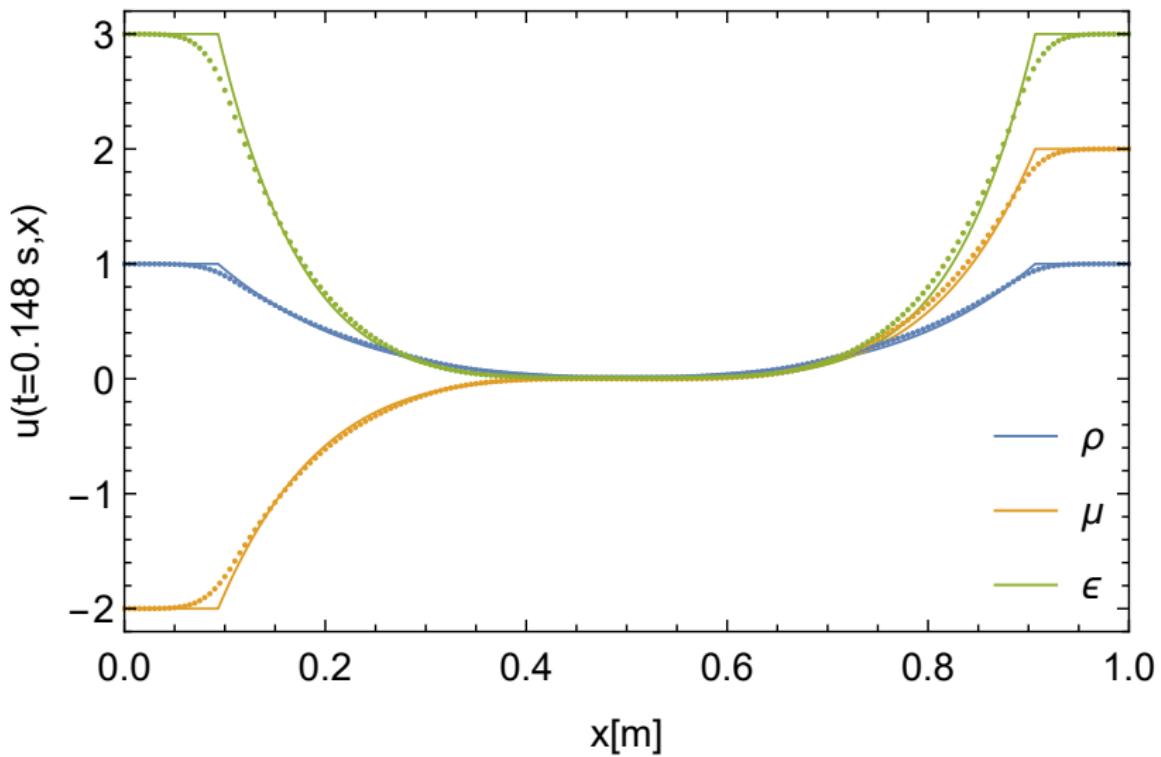


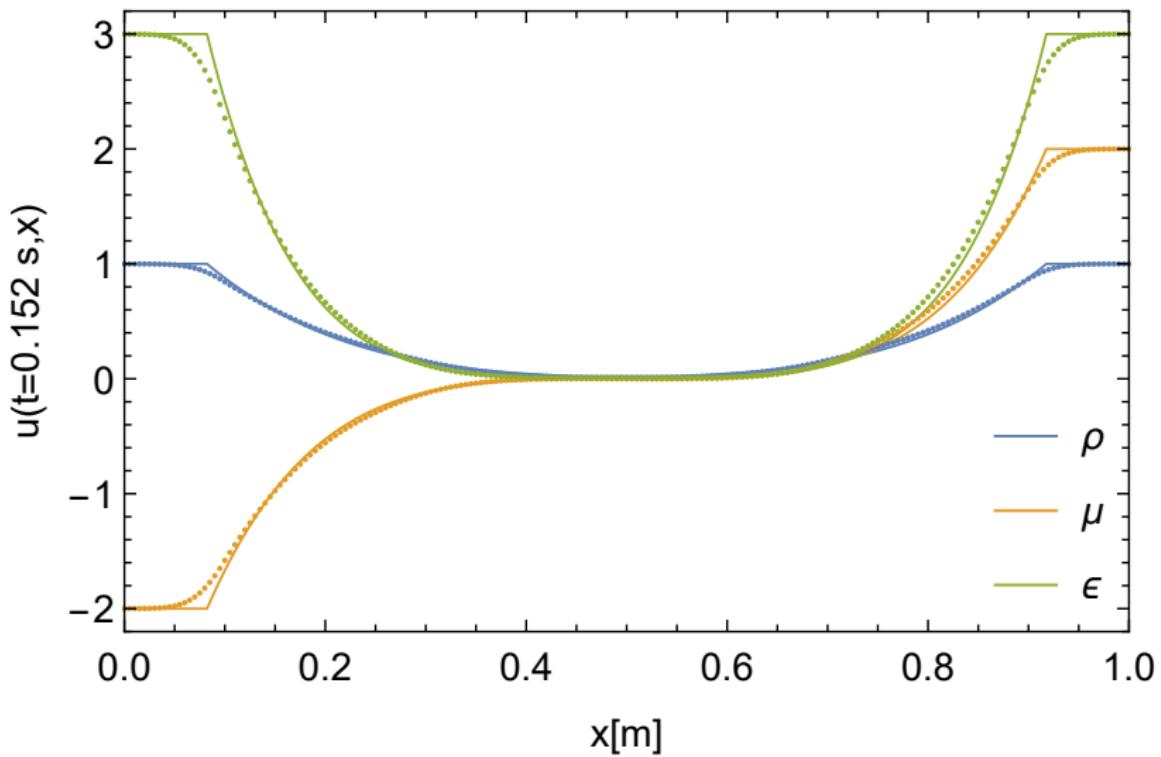


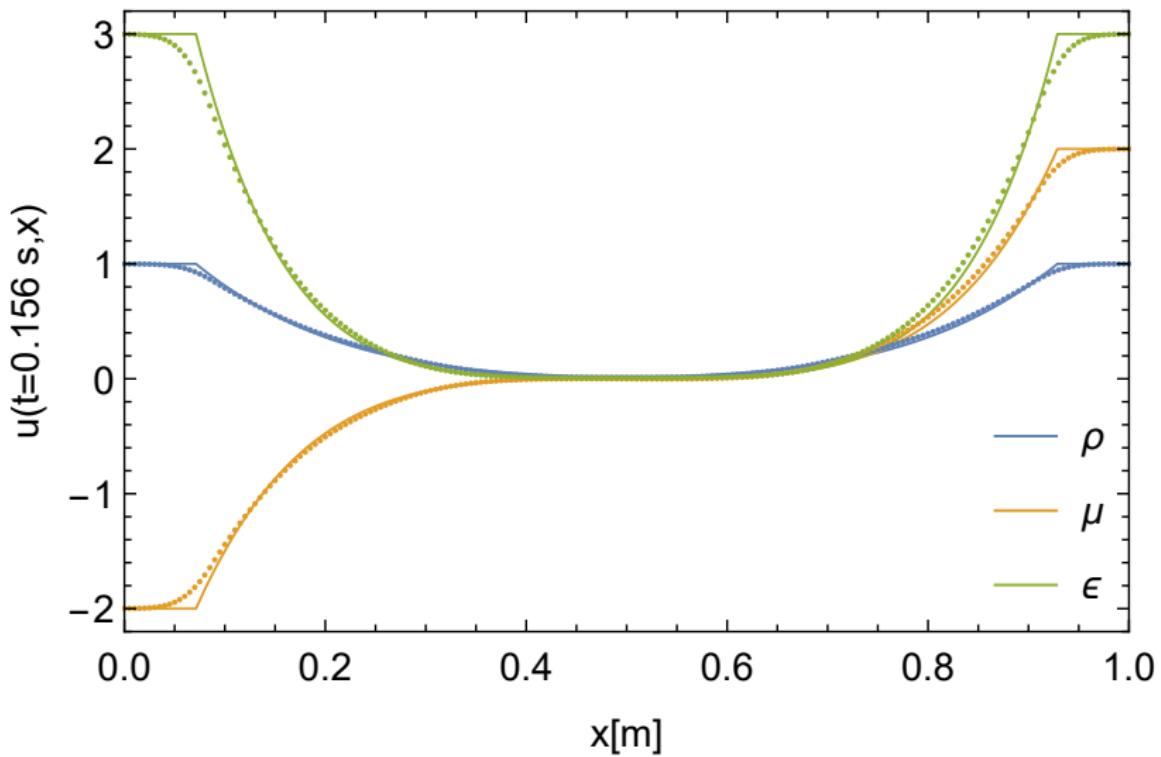


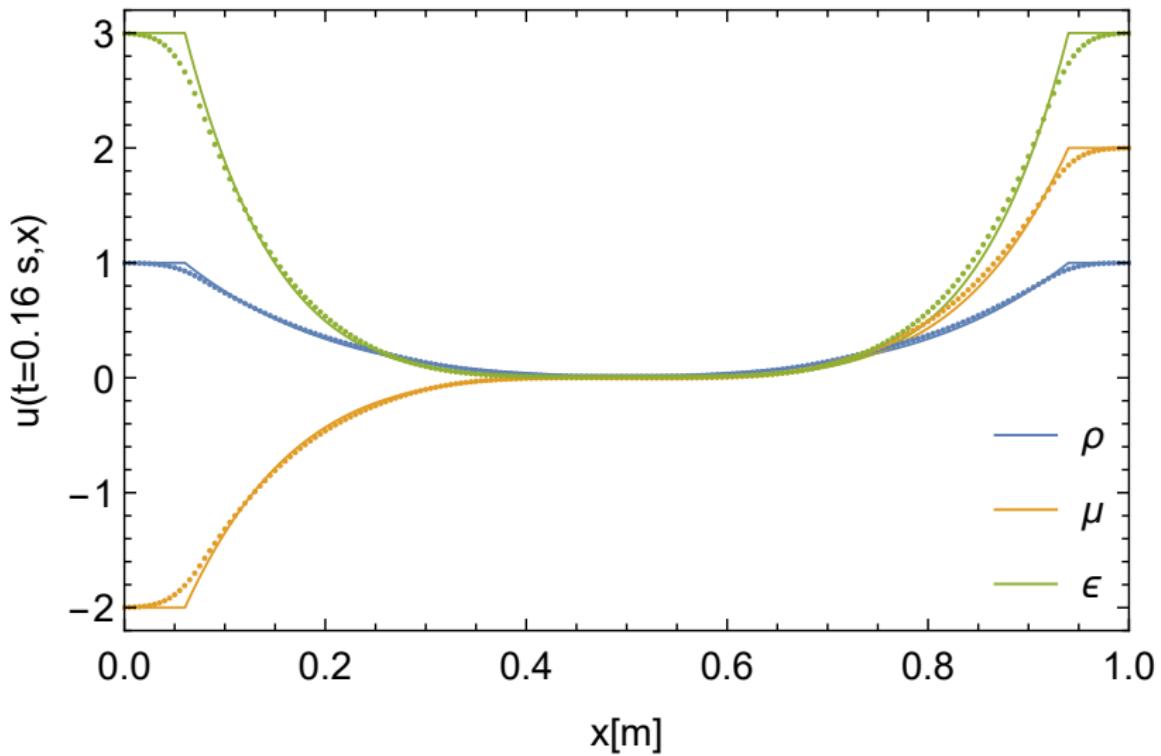












O(N) model - LPA flow equation $d > 0$

$$\partial_t u(t, x) + c_d \partial_x \frac{e^{-dt}}{1 + e^{2t} u(t, x)} = -\frac{c_d}{N-1} \partial_x \frac{e^{-dt}}{1 + e^{2t}(u(t, x) + 2x \partial_x u(t, x))} \quad (12)$$

- ▶ LPA flow equation of the O(N) model in $d > 0$ dimensions using d -dim. Litim regulator with

$$t \equiv -\log k/\Lambda \quad (13)$$

$$x \equiv \frac{\rho}{(N-1)\Lambda^{d-2}} \quad (14)$$

$$u(t, x) \equiv \frac{\partial U(t, \rho)}{\Lambda^2 \partial \rho} \quad (15)$$

$$c_d \equiv \frac{2^{-d} \pi^{-d/2}}{\Gamma(1+d/2)} \quad (16)$$

$O(\infty)$ model - $d = 3$ initial conditions

- ▶ Riemann problem (restored phase for $O(\infty)$, $d=3$)

$$u(t=0, x) = \begin{cases} 0.0 & 0.02 < x < 0.05 \\ 0.1 & \text{otherwise} \end{cases} \quad (\text{GW.2a})$$

- ▶ Quartic potential (restored phase for $O(\infty)$, $d=3$)

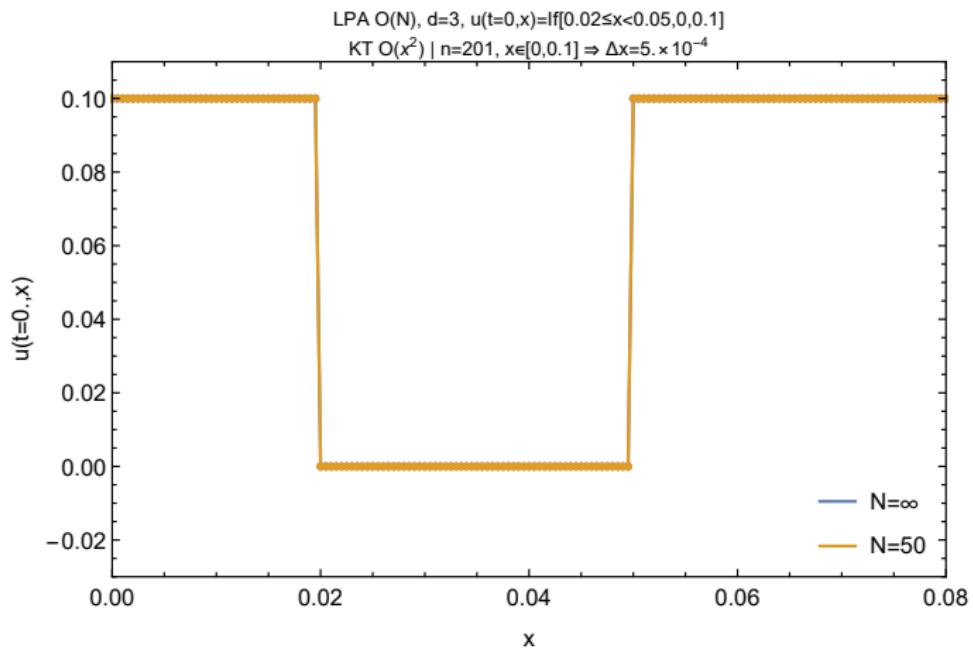
$$u(t=0, x) = 1.0x - 0.1 \quad (\text{GW.3a})$$

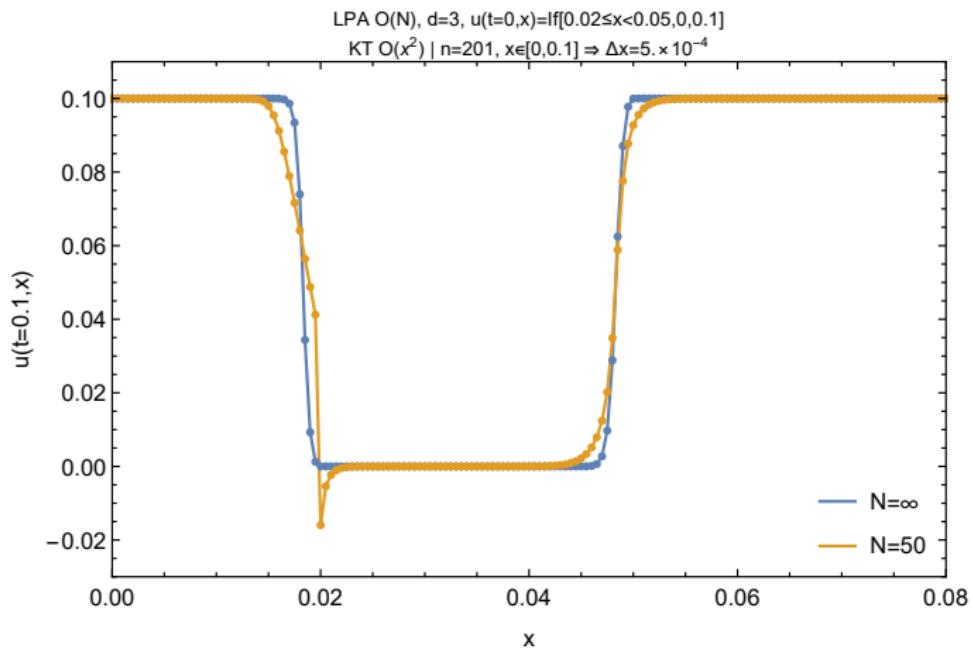
- ▶ Sextic potential (restored phase for $O(\infty)$, $d=3$)

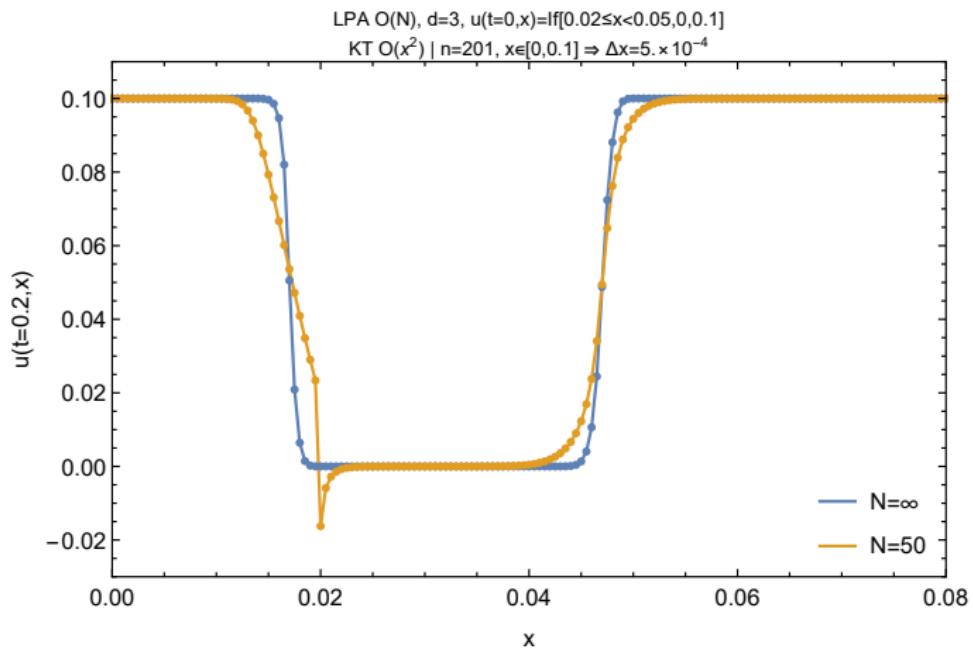
$$u(t=0, x) = 1.0x^2 - 0.103x + 0.0024 \quad (\text{GW.8c})$$

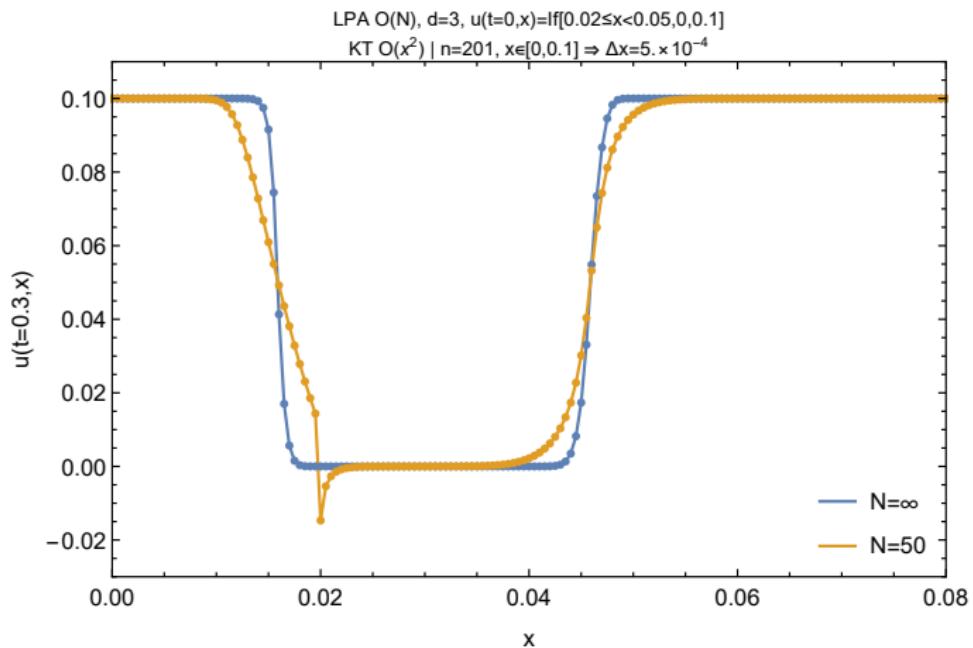
- ▶ Sextic potential (broken phase for $O(\infty)$, $d=3$)

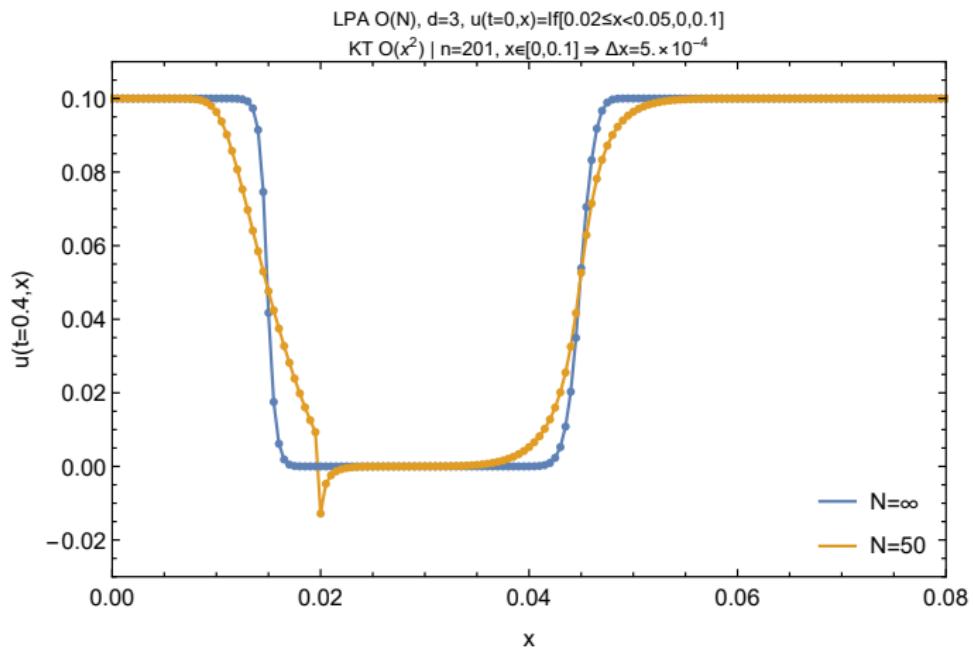
$$u(t=0, x) = 1.0x^2 - 0.105x + 0.0024 \quad (\text{GW.8d})$$

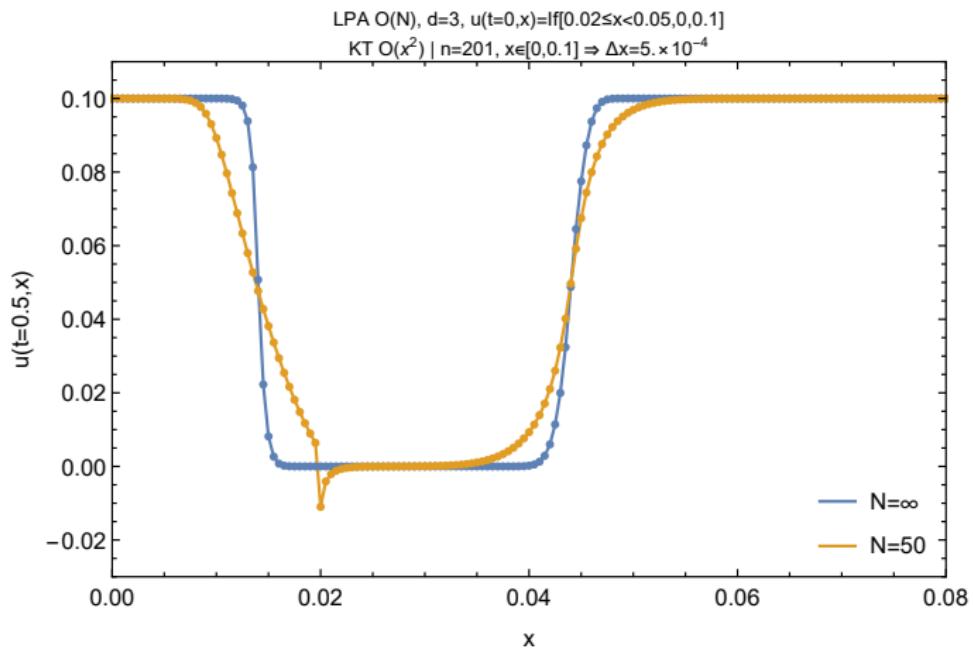




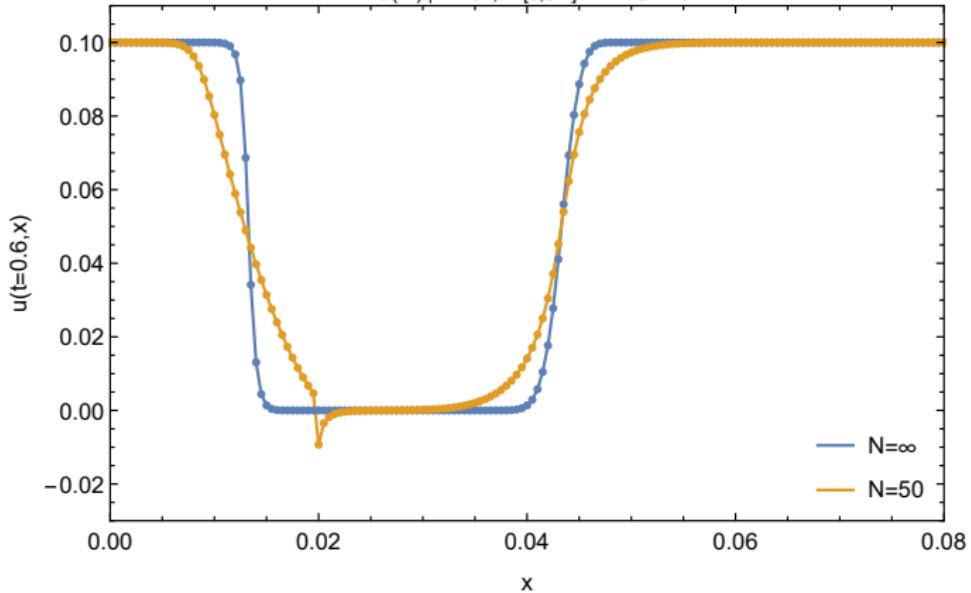


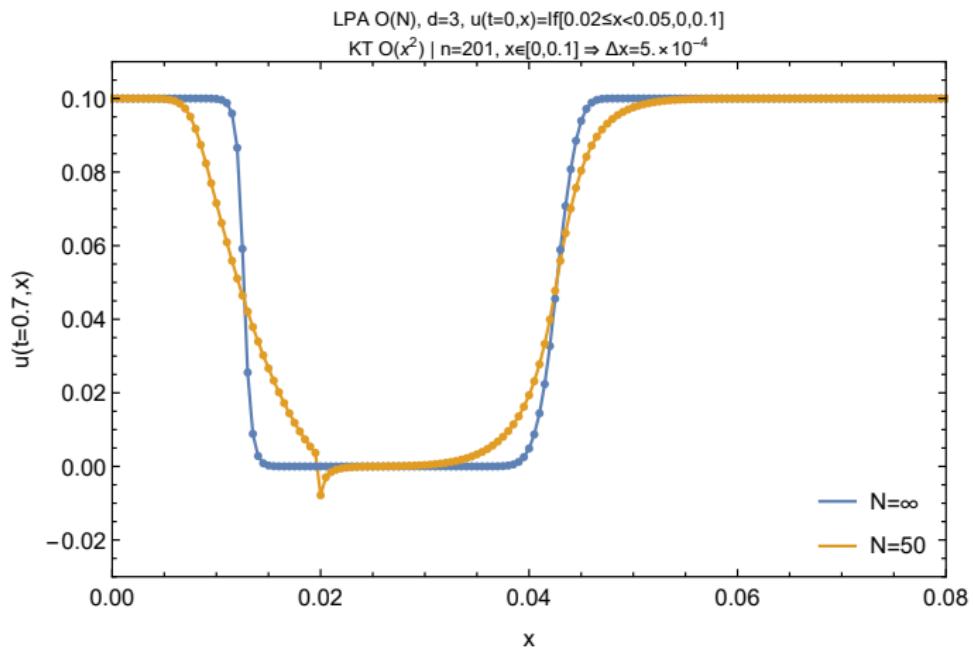


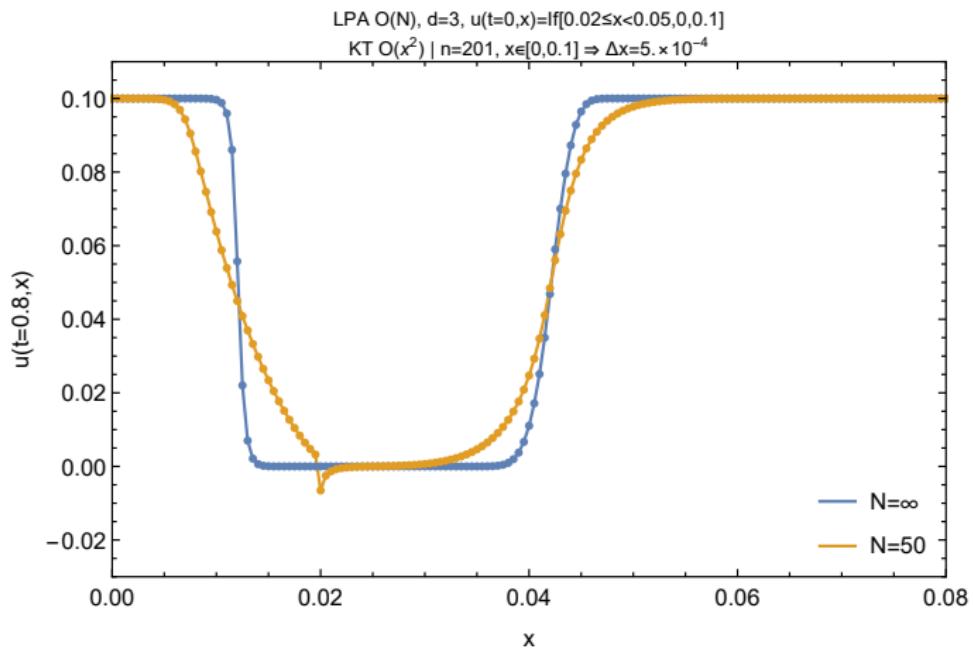




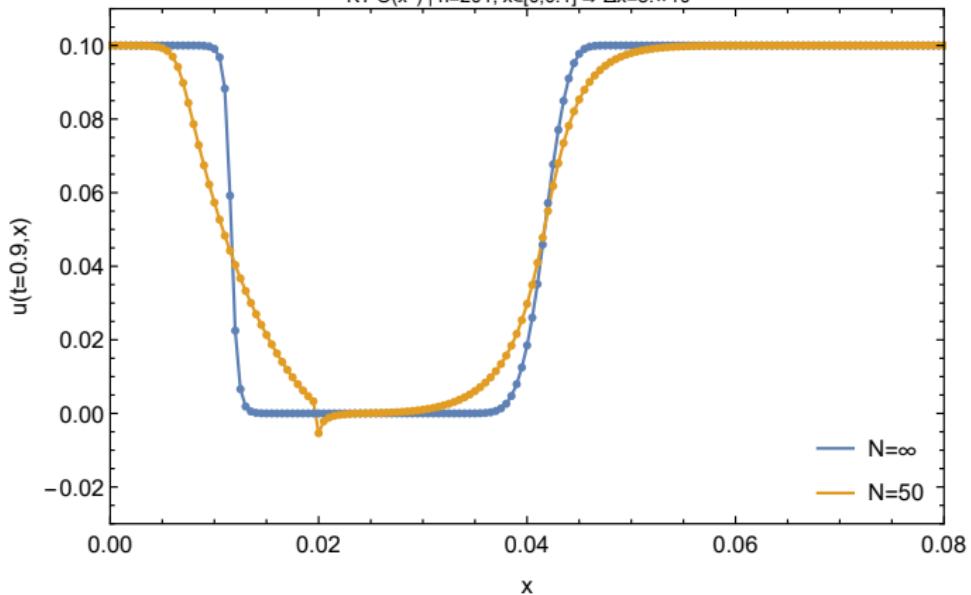
LPA $O(N)$, $d=3$, $u(t=0,x)=\text{If}[0.02 \leq x < 0.05, 0, 0.1]$
KT $O(x^2)$ | $n=201$, $x \in [0, 0.1] \Rightarrow \Delta x = 5 \cdot 10^{-4}$



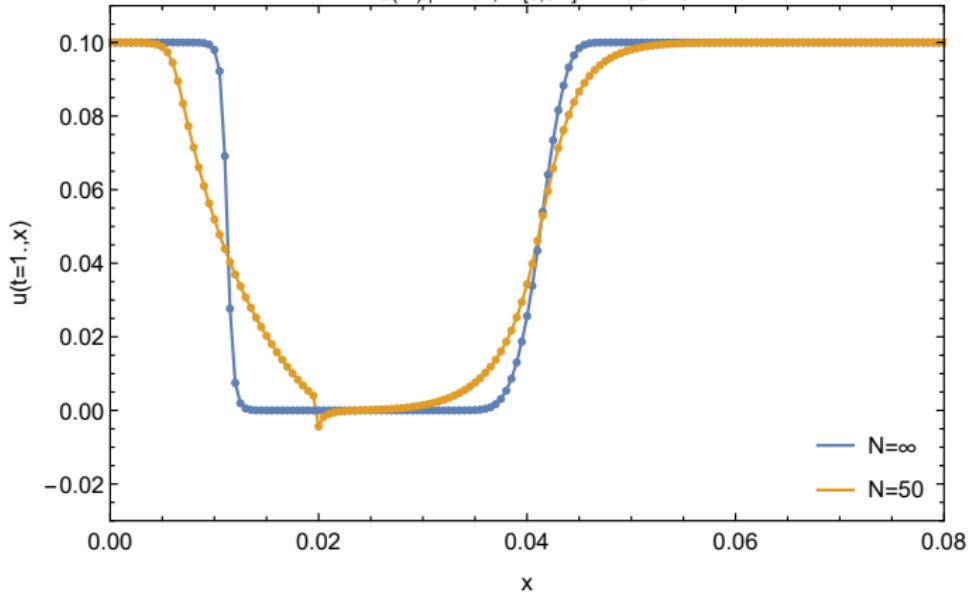




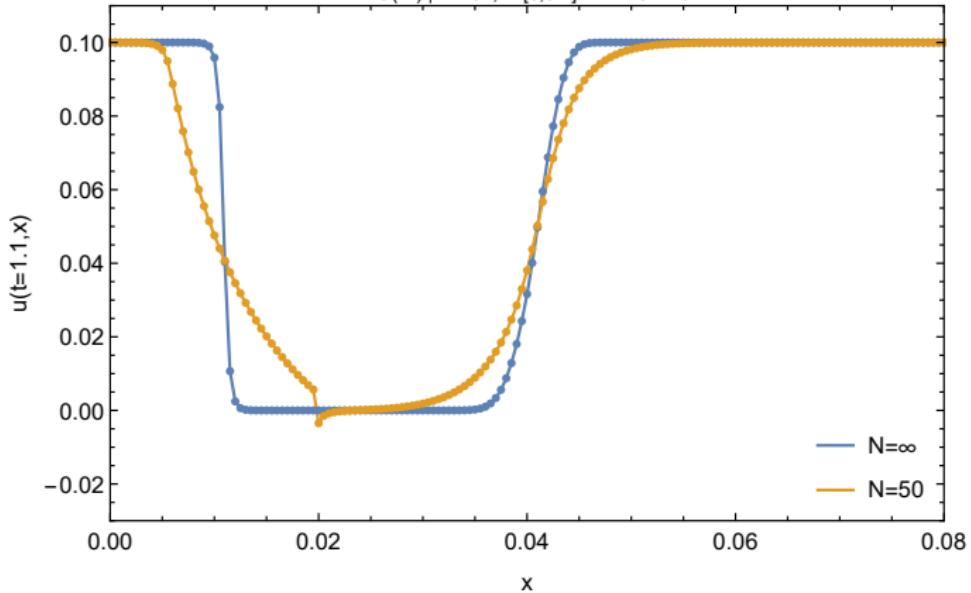
LPA $O(N)$, $d=3$, $u(t=0,x)=\text{If}[0.02 \leq x < 0.05, 0, 0.1]$
KT $O(x^2)$ | $n=201$, $x \in [0, 0.1] \Rightarrow \Delta x = 5 \times 10^{-4}$

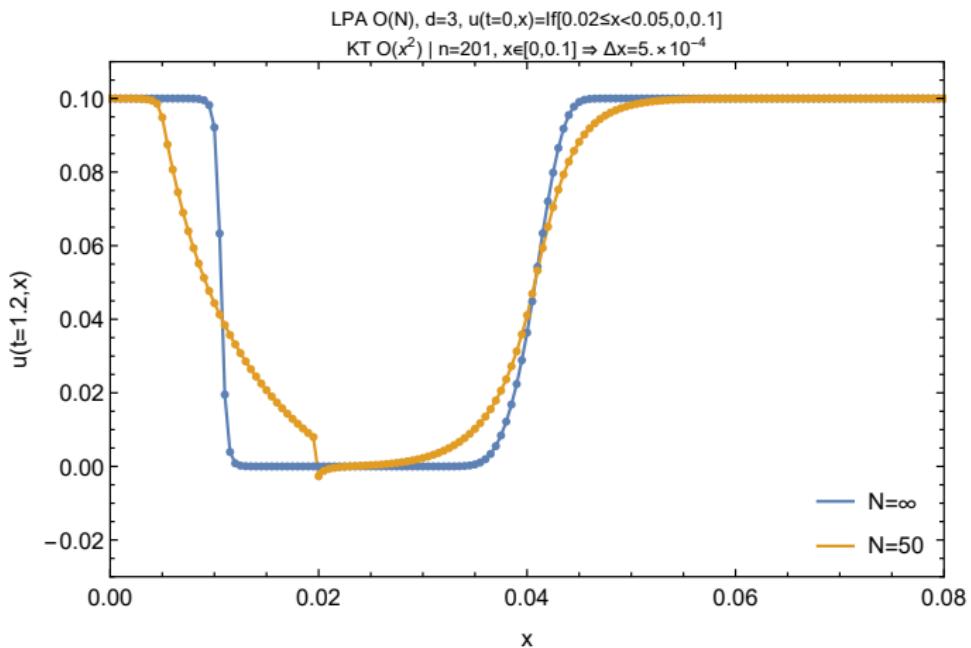


LPA $O(N)$, $d=3$, $u(t=0,x)=\text{If}[0.02 \leq x < 0.05, 0, 0.1]$
KT $O(x^2)$ | $n=201$, $x \in [0, 0.1] \Rightarrow \Delta x = 5 \times 10^{-4}$

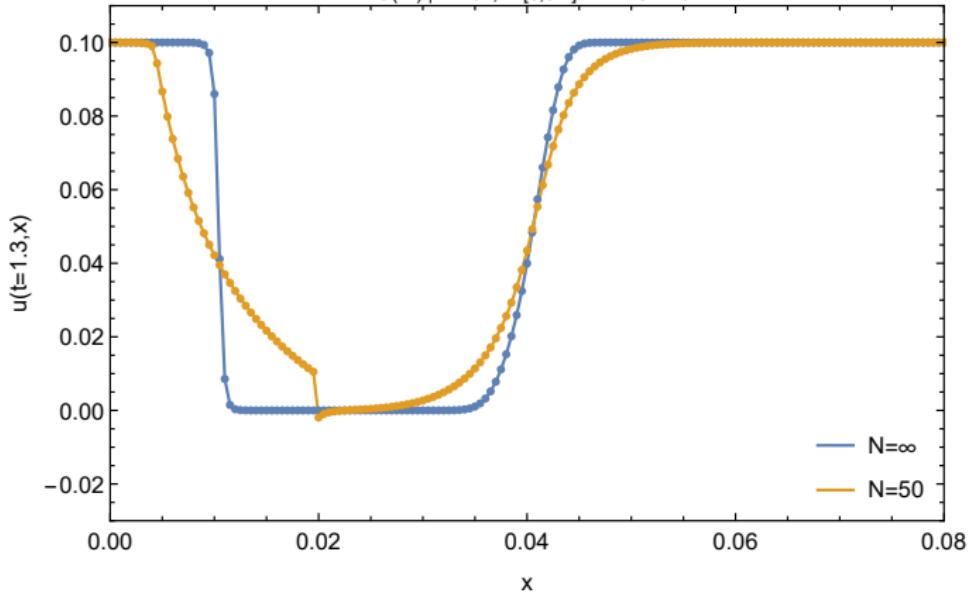


LPA $O(N)$, $d=3$, $u(t=0,x)=\text{If}[0.02 \leq x < 0.05, 0, 0.1]$
KT $O(x^2)$ | $n=201$, $x \in [0, 0.1] \Rightarrow \Delta x = 5 \times 10^{-4}$

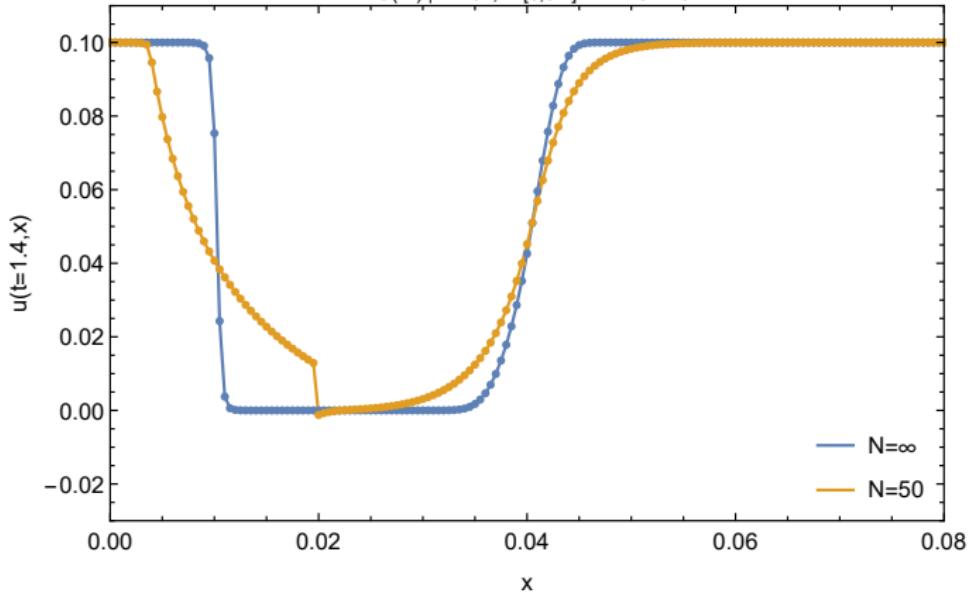




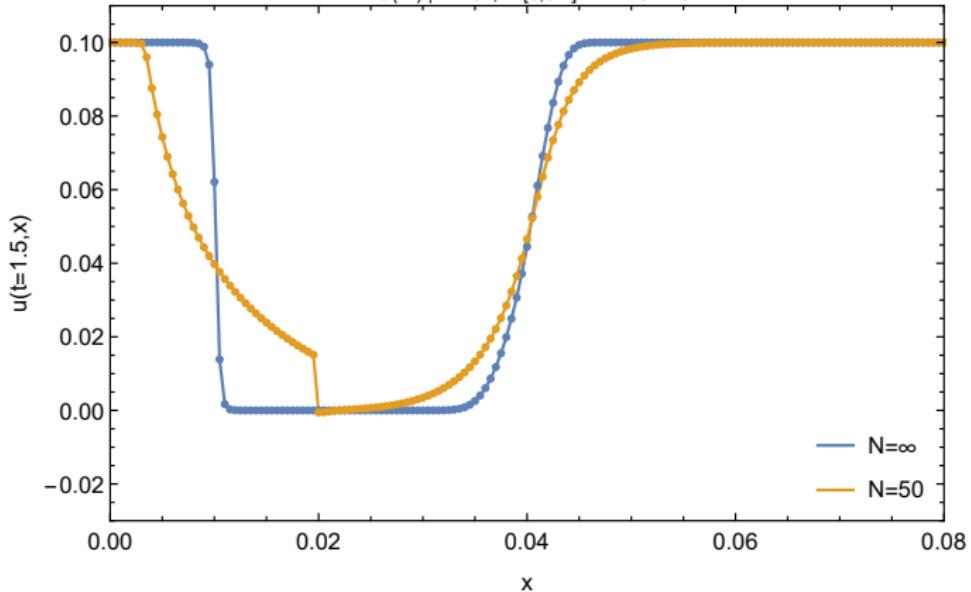
LPA $O(N)$, $d=3$, $u(t=0,x)=\text{If}[0.02 \leq x < 0.05, 0, 0.1]$
KT $O(x^2)$ | $n=201$, $x \in [0, 0.1] \Rightarrow \Delta x = 5 \times 10^{-4}$



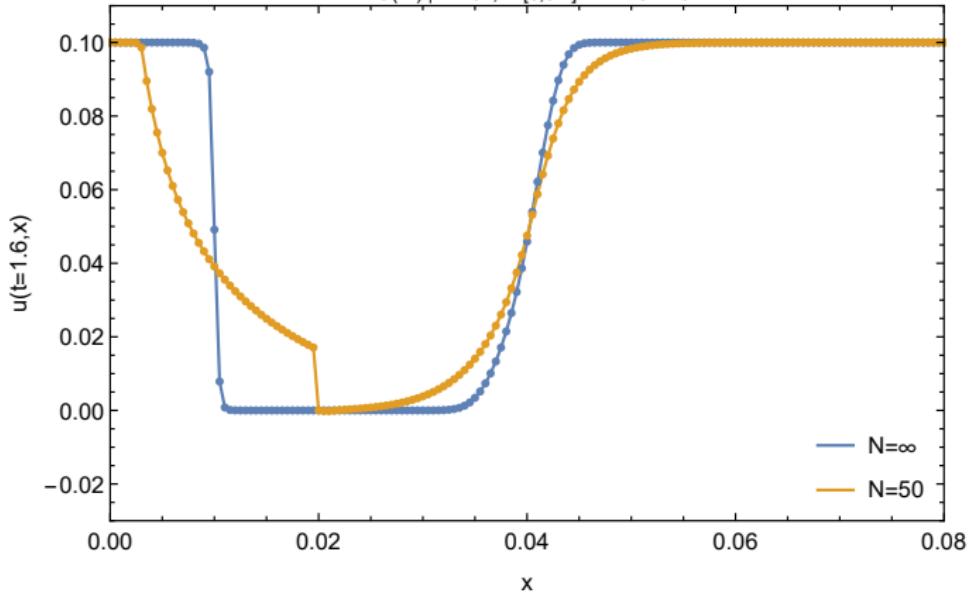
LPA $O(N)$, $d=3$, $u(t=0,x)=\text{If}[0.02 \leq x < 0.05, 0, 0.1]$
KT $O(x^2)$ | $n=201$, $x \in [0, 0.1] \Rightarrow \Delta x = 5 \times 10^{-4}$



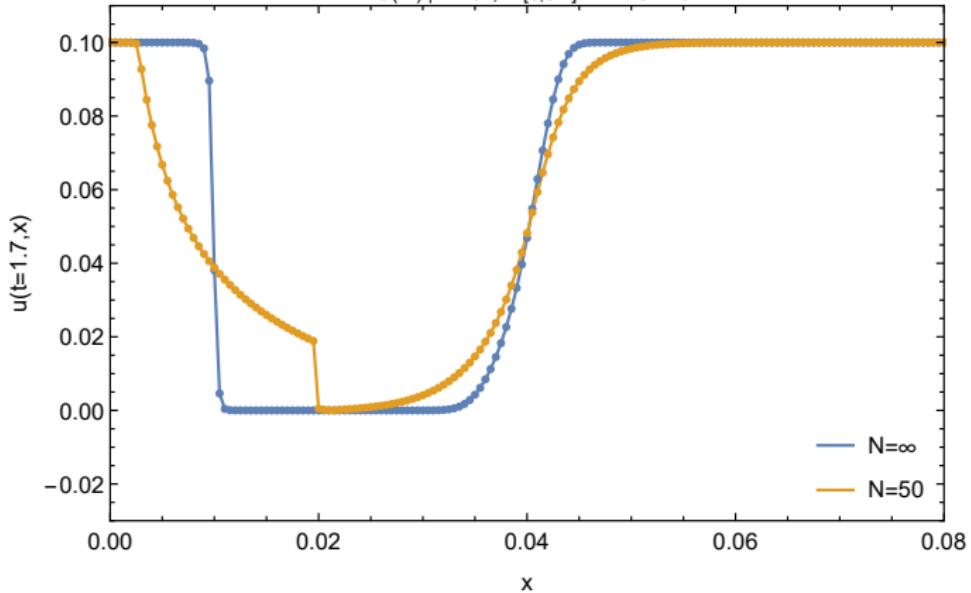
LPA $O(N)$, $d=3$, $u(t=0,x)=\text{If}[0.02 \leq x < 0.05, 0, 0.1]$
KT $O(x^2)$ | $n=201$, $x \in [0, 0.1] \Rightarrow \Delta x = 5 \times 10^{-4}$



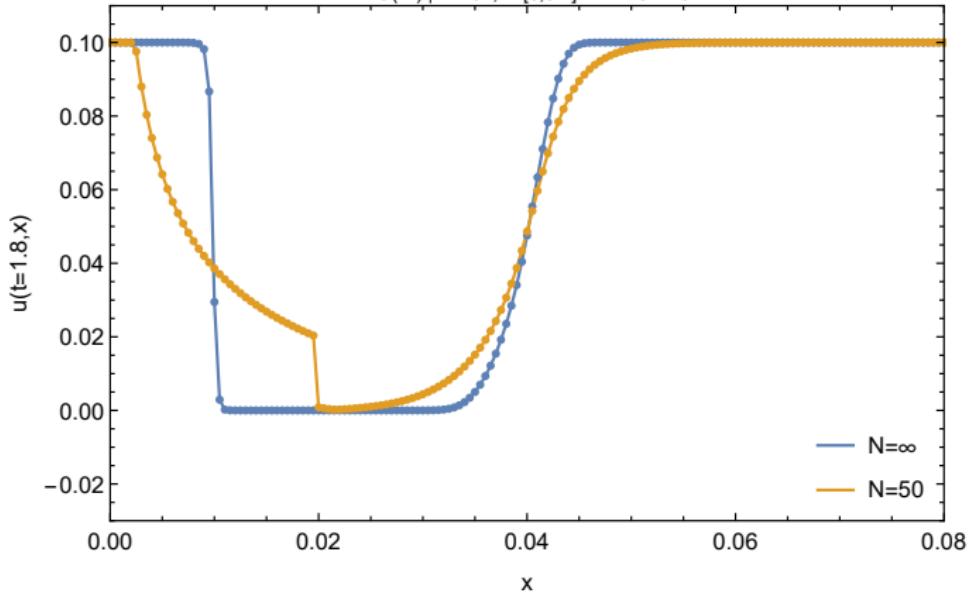
LPA $O(N)$, $d=3$, $u(t=0,x)=\text{If}[0.02 \leq x < 0.05, 0, 0.1]$
KT $O(x^2)$ | $n=201$, $x \in [0, 0.1] \Rightarrow \Delta x = 5 \times 10^{-4}$



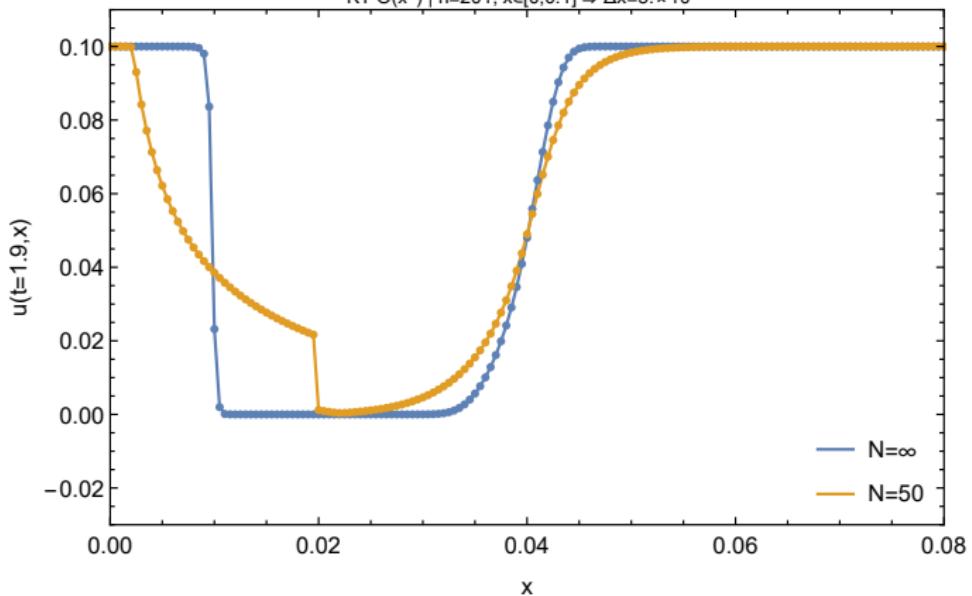
LPA $O(N)$, $d=3$, $u(t=0,x)=\text{If}[0.02 \leq x < 0.05, 0, 0.1]$
KT $O(x^2)$ | $n=201$, $x \in [0, 0.1] \Rightarrow \Delta x = 5 \times 10^{-4}$



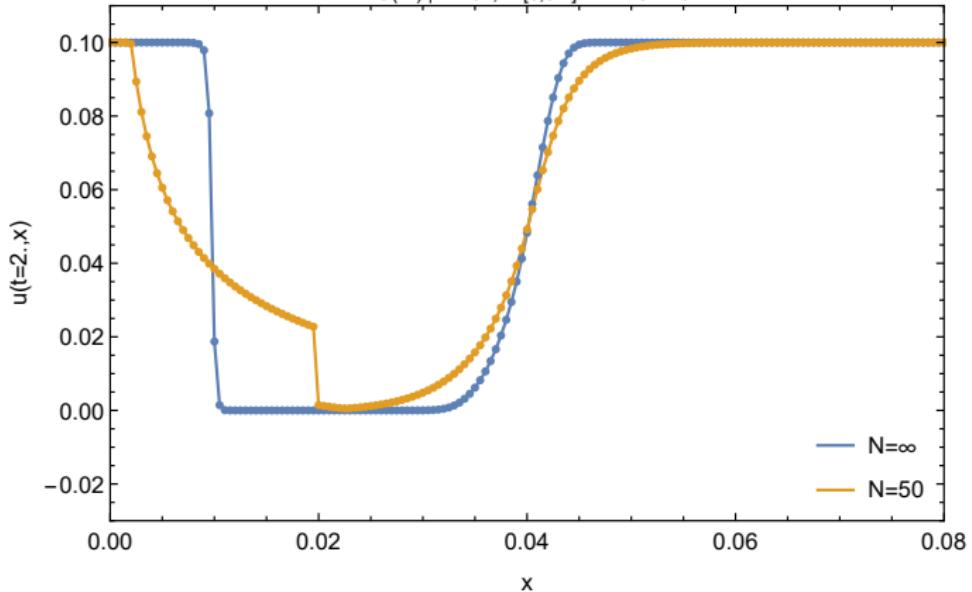
LPA $O(N)$, $d=3$, $u(t=0,x)=\text{If}[0.02 \leq x < 0.05, 0, 0.1]$
KT $O(x^2)$ | $n=201$, $x \in [0, 0.1] \Rightarrow \Delta x = 5 \times 10^{-4}$



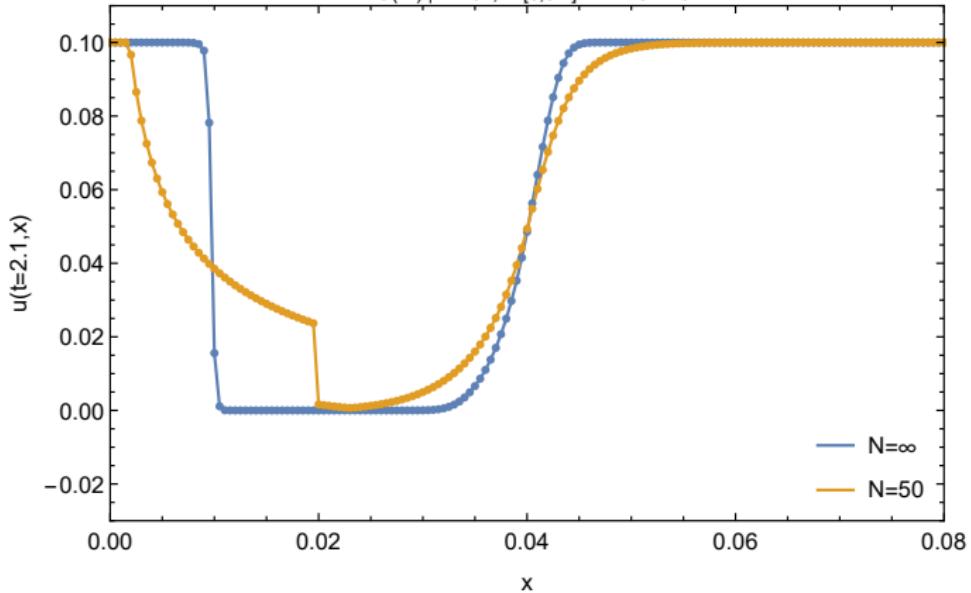
LPA $O(N)$, $d=3$, $u(t=0,x)=\text{If}[0.02 \leq x < 0.05, 0, 0.1]$
KT $O(x^2)$ | $n=201$, $x \in [0, 0.1] \Rightarrow \Delta x = 5 \times 10^{-4}$



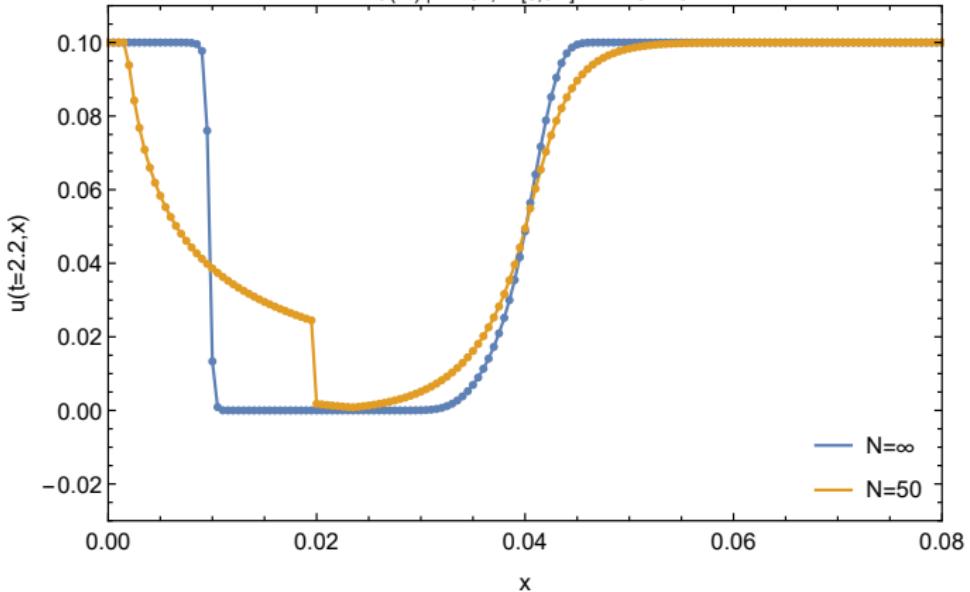
LPA $O(N)$, $d=3$, $u(t=0,x)=\text{If}[0.02 \leq x < 0.05, 0, 0.1]$
KT $O(x^2)$ | $n=201$, $x \in [0, 0.1] \Rightarrow \Delta x = 5 \times 10^{-4}$



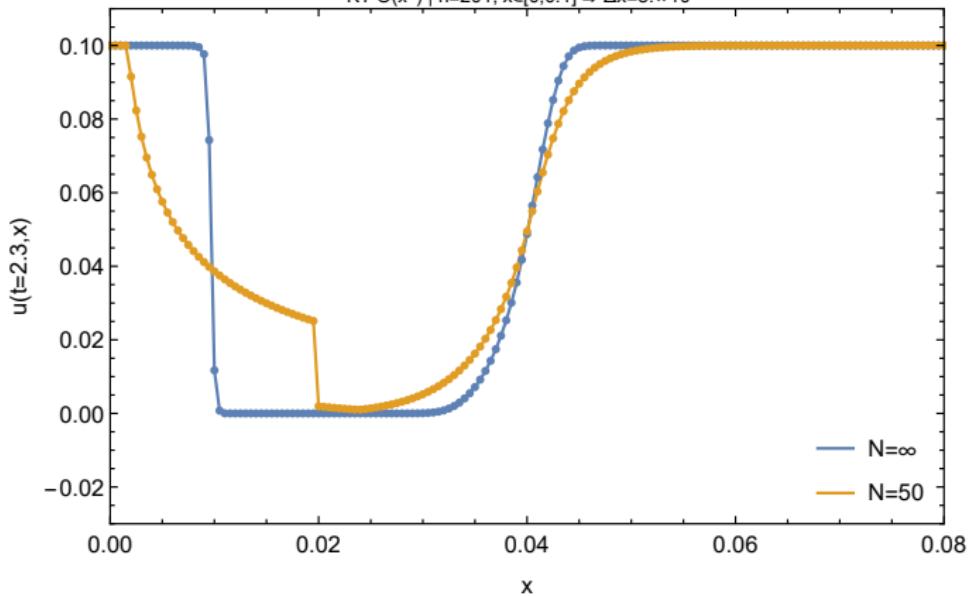
LPA $O(N)$, $d=3$, $u(t=0,x)=\text{If}[0.02 \leq x < 0.05, 0, 0.1]$
KT $O(x^2)$ | $n=201$, $x \in [0, 0.1] \Rightarrow \Delta x = 5 \times 10^{-4}$



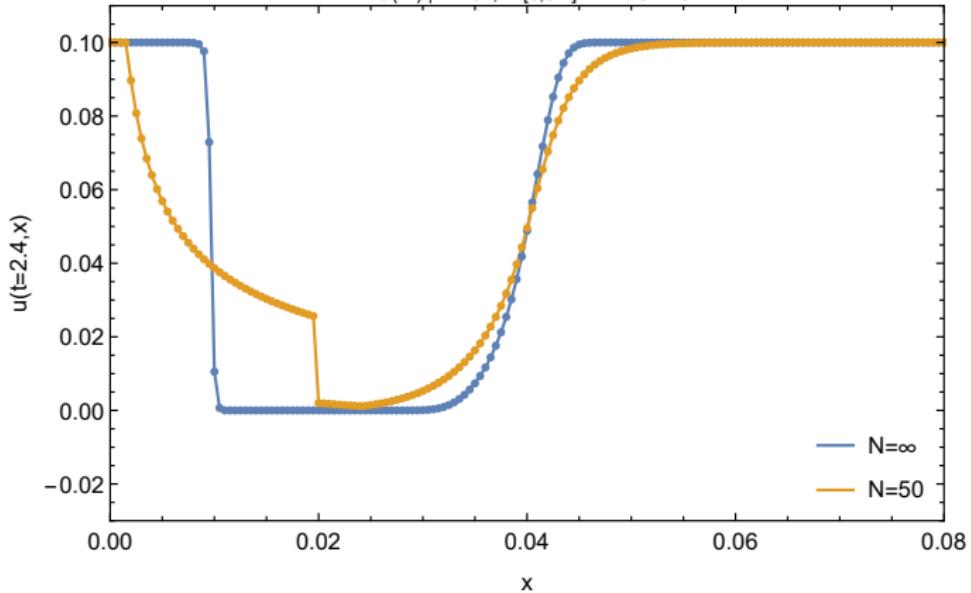
LPA $O(N)$, $d=3$, $u(t=0,x)=\text{If}[0.02 \leq x < 0.05, 0, 0.1]$
KT $O(x^2)$ | $n=201$, $x \in [0, 0.1] \Rightarrow \Delta x = 5 \times 10^{-4}$



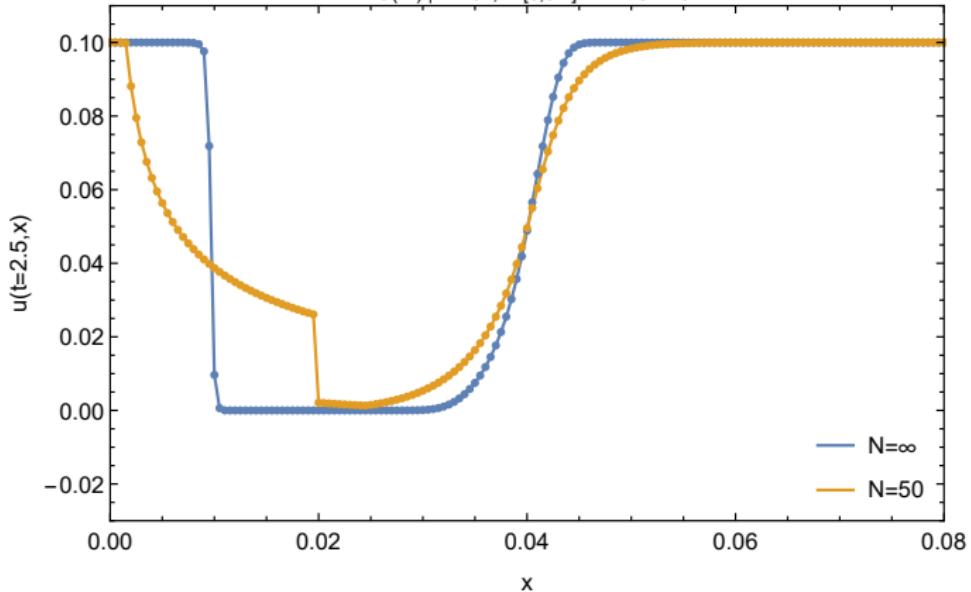
LPA $O(N)$, $d=3$, $u(t=0,x)=\text{If}[0.02 \leq x < 0.05, 0, 0.1]$
KT $O(x^2)$ | $n=201$, $x \in [0, 0.1] \Rightarrow \Delta x = 5 \times 10^{-4}$



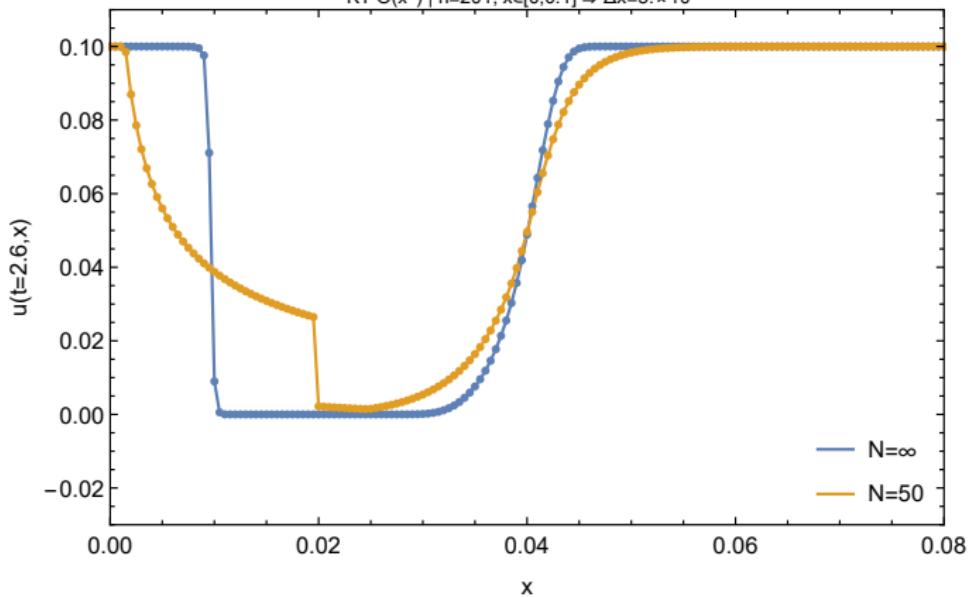
LPA $O(N)$, $d=3$, $u(t=0,x)=\text{If}[0.02 \leq x < 0.05, 0, 0.1]$
KT $O(x^2)$ | $n=201$, $x \in [0, 0.1] \Rightarrow \Delta x = 5 \times 10^{-4}$



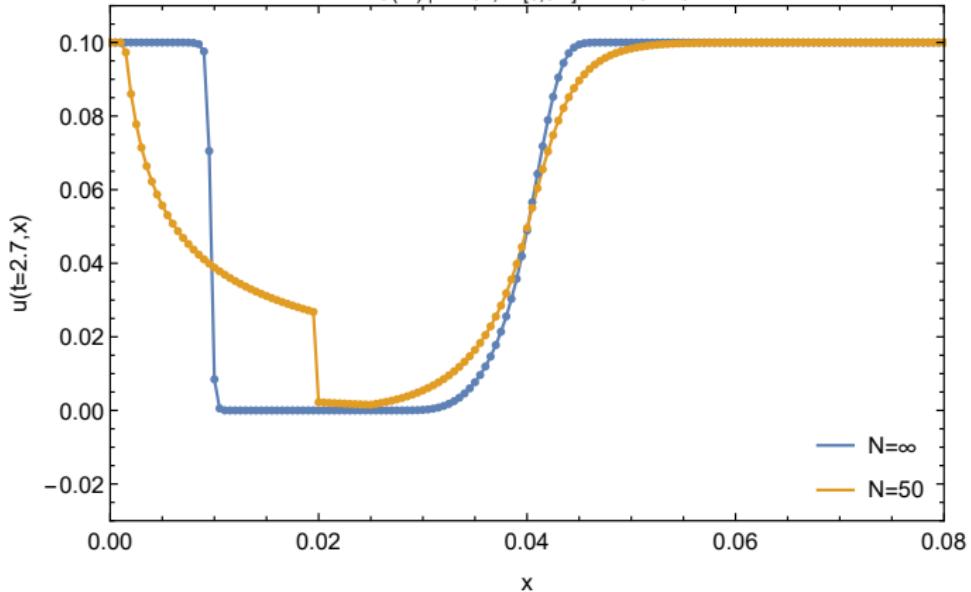
LPA $O(N)$, $d=3$, $u(t=0,x)=\text{If}[0.02 \leq x < 0.05, 0, 0.1]$
KT $O(x^2)$ | $n=201$, $x \in [0, 0.1] \Rightarrow \Delta x = 5 \cdot 10^{-4}$



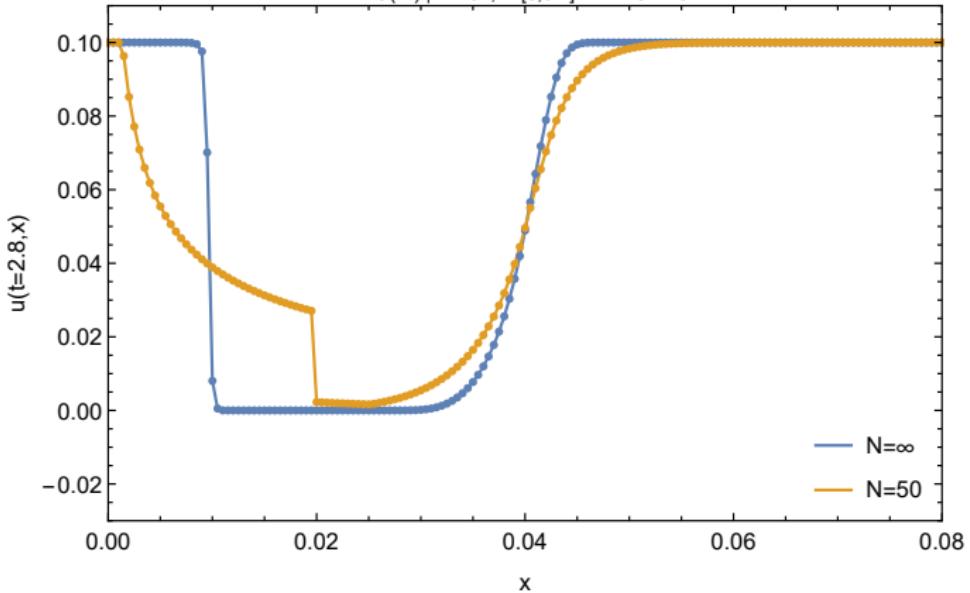
LPA $O(N)$, $d=3$, $u(t=0,x)=\text{If}[0.02 \leq x < 0.05, 0, 0.1]$
KT $O(x^2)$ | $n=201$, $x \in [0, 0.1] \Rightarrow \Delta x = 5 \cdot 10^{-4}$



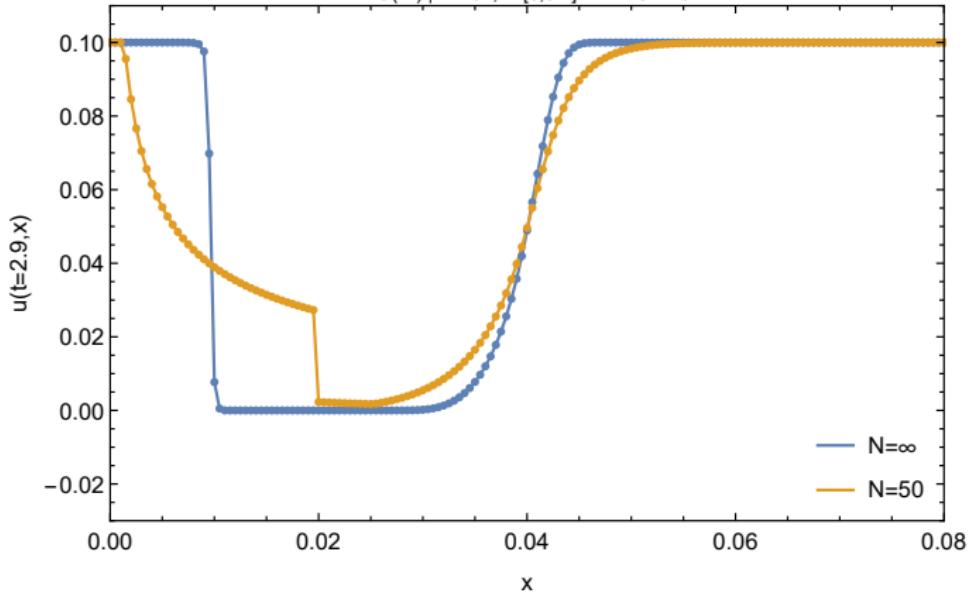
LPA $O(N)$, $d=3$, $u(t=0,x)=\text{If}[0.02 \leq x < 0.05, 0, 0.1]$
KT $O(x^2)$ | $n=201$, $x \in [0, 0.1] \Rightarrow \Delta x = 5 \cdot 10^{-4}$



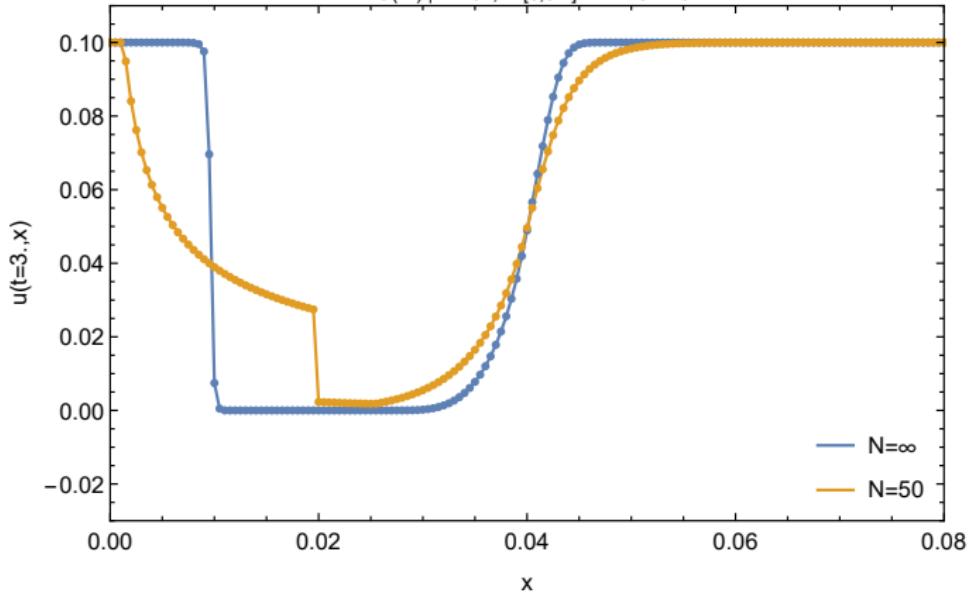
LPA $O(N)$, $d=3$, $u(t=0,x)=\text{If}[0.02 \leq x < 0.05, 0, 0.1]$
KT $O(x^2)$ | $n=201$, $x \in [0, 0.1] \Rightarrow \Delta x = 5 \times 10^{-4}$

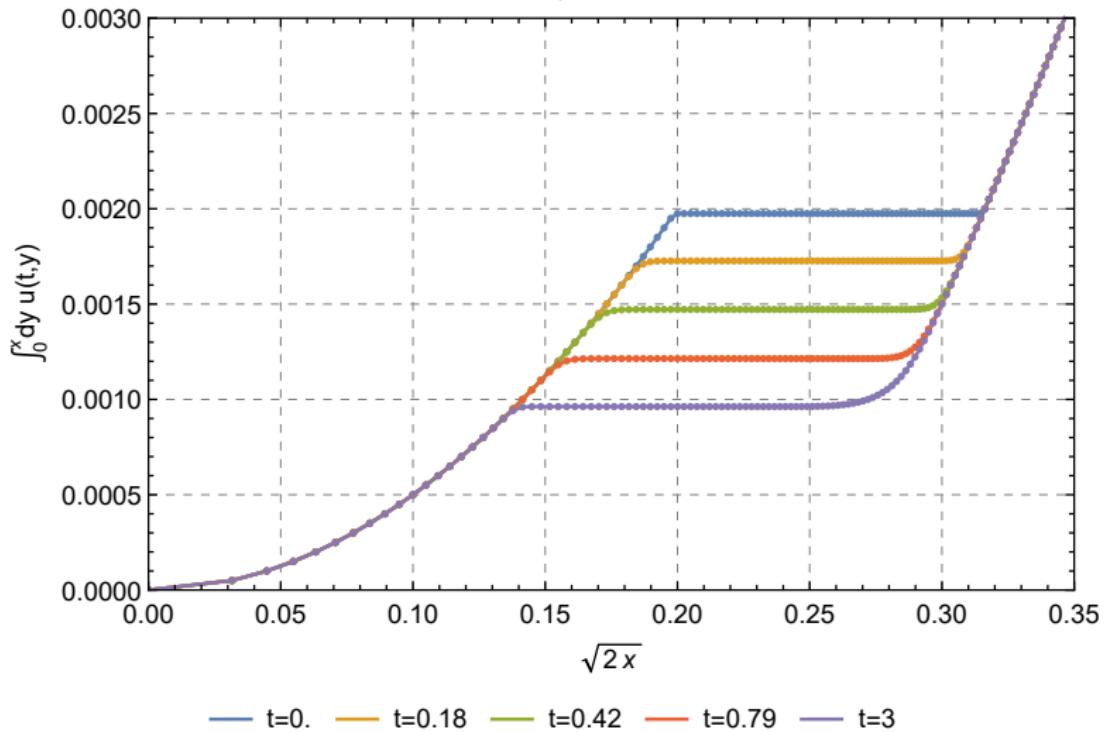


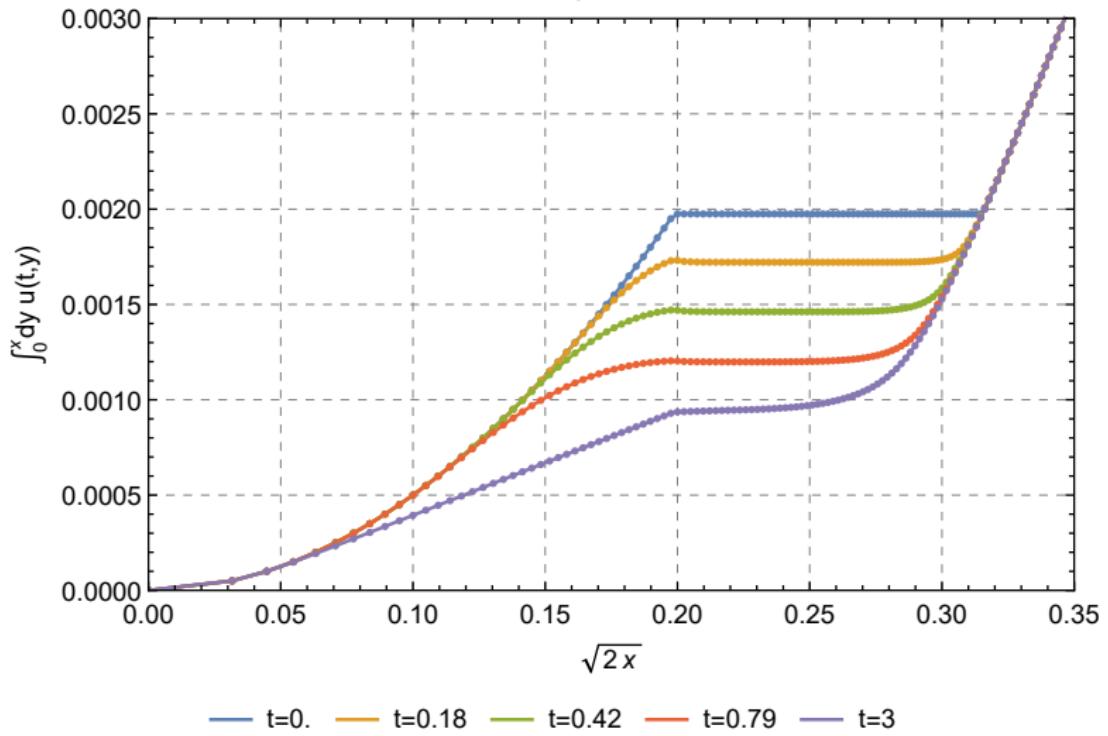
LPA $O(N)$, $d=3$, $u(t=0,x)=\text{If}[0.02 \leq x < 0.05, 0, 0.1]$
KT $O(x^2)$ | $n=201$, $x \in [0, 0.1] \Rightarrow \Delta x = 5 \cdot 10^{-4}$



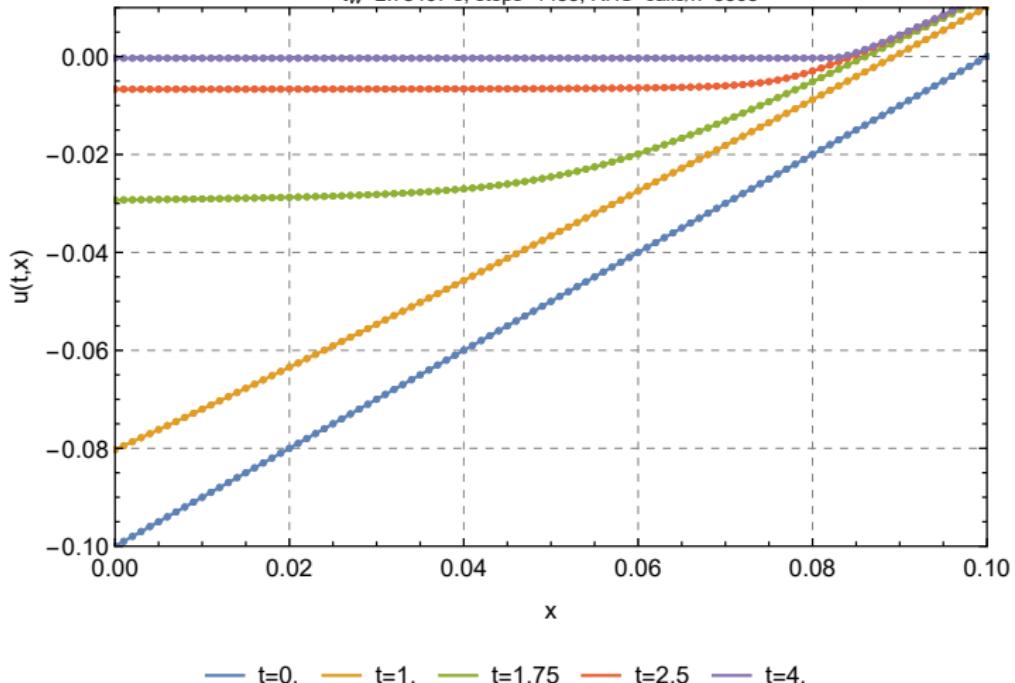
LPA $O(N)$, $d=3$, $u(t=0,x)=\text{If}[0.02 \leq x < 0.05, 0, 0.1]$
KT $O(x^2)$ | $n=201$, $x \in [0, 0.1] \Rightarrow \Delta x = 5 \times 10^{-4}$



LPA O(∞), d=3, $u(t=0,x) = \text{lf}[0.02 \leq x < 0.05, 0, 0.1]$ KT O(x^2) | n=201, $x \in [0, 0.1] \Rightarrow \Delta x = 5 \times 10^{-4}$ $t_W = 3.93594$ s, steps=1601, RHS-calls/n=3710

LPA O(50), d=3, $u(t=0,x) = \text{lf}[0.02 \leq x < 0.05, 0, 0.1]$ KT O(x^2) | n=201, $x \in [0, 0.1] \Rightarrow \Delta x = 5 \times 10^{-4}$ $t_W = 1.43539 \times 10^1$ s, steps=4959, RHS-calls/n=12492

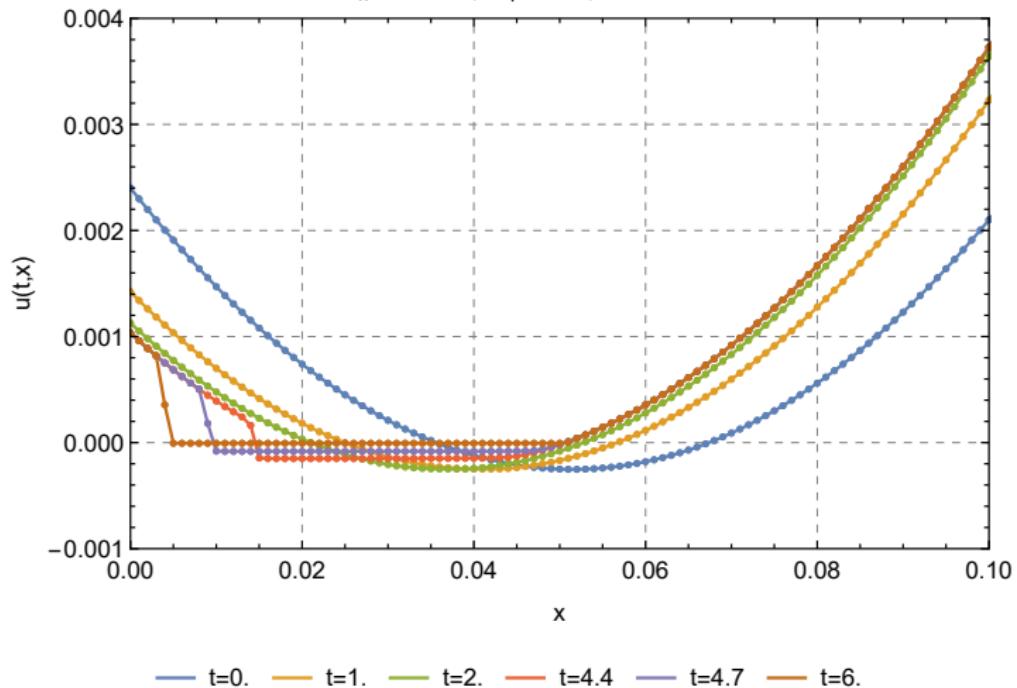
LPA $O(\infty)$, d=3, $v(t=0, x) = 1 \cdot x - 0.1$
KT $O(x^2)$ | n=151, $x \in [0, 0.15] \Rightarrow \Delta x = 1 \cdot 10^{-3}$
 $t_W = 2.78407$ s, steps=1453, RHS-calls/n=3305

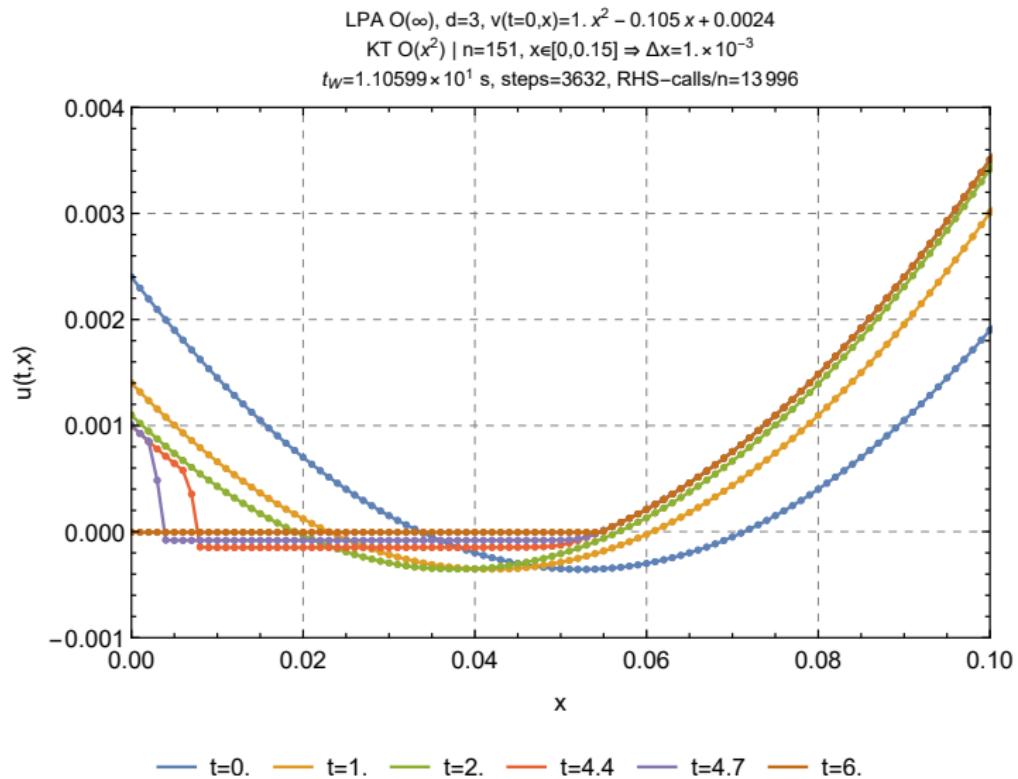


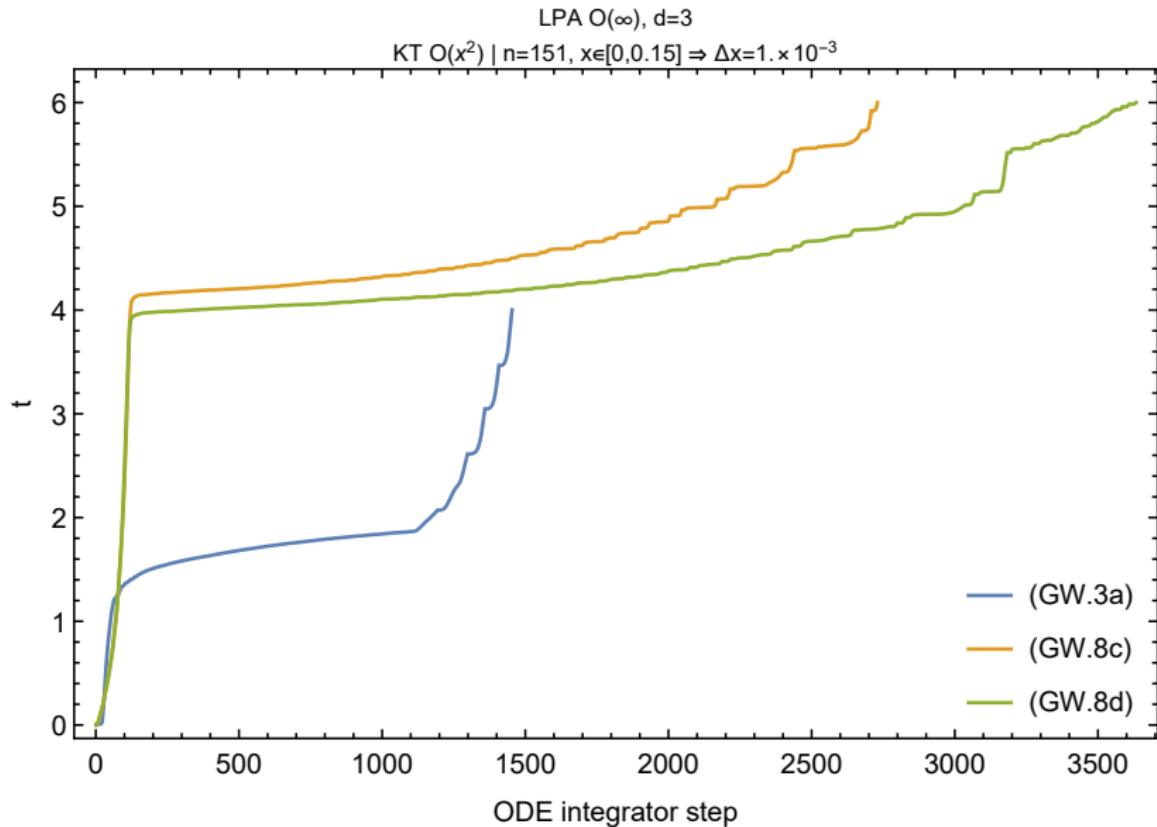
LPA $O(\infty)$, d=3, $v(t=0,x)=1 \cdot x^2 - 0.103 x + 0.0024$

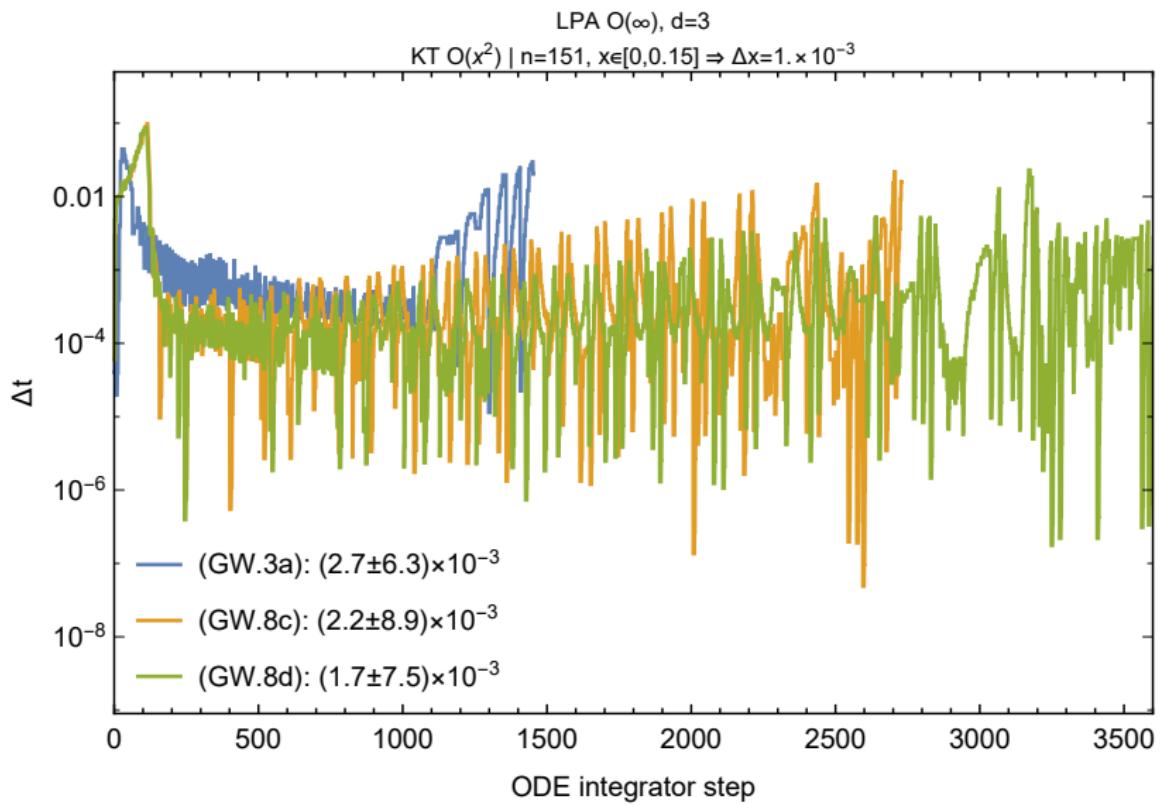
KT $O(x^2)$ | n=151, $x \in [0, 0.15] \Rightarrow \Delta x = 1 \cdot 10^{-3}$

$t_W = 8.52115$ s, steps=2729, RHS-calls/n=9978

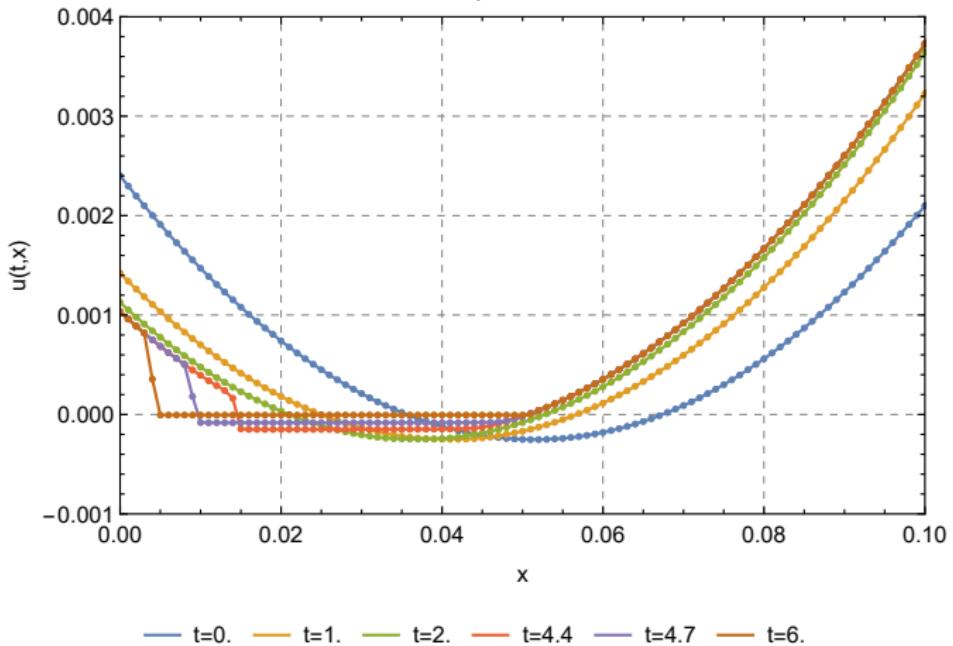




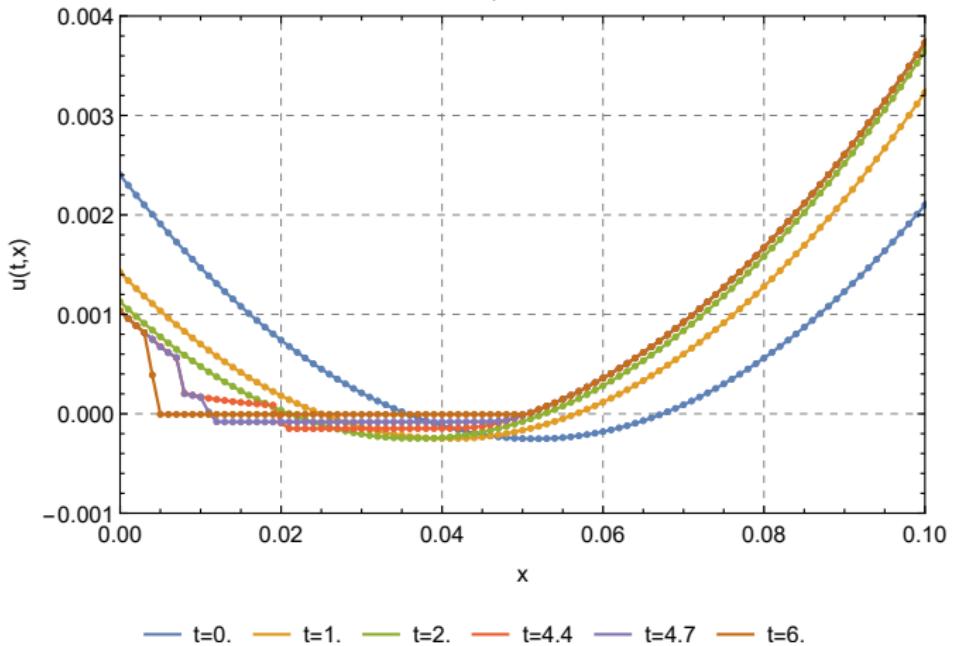




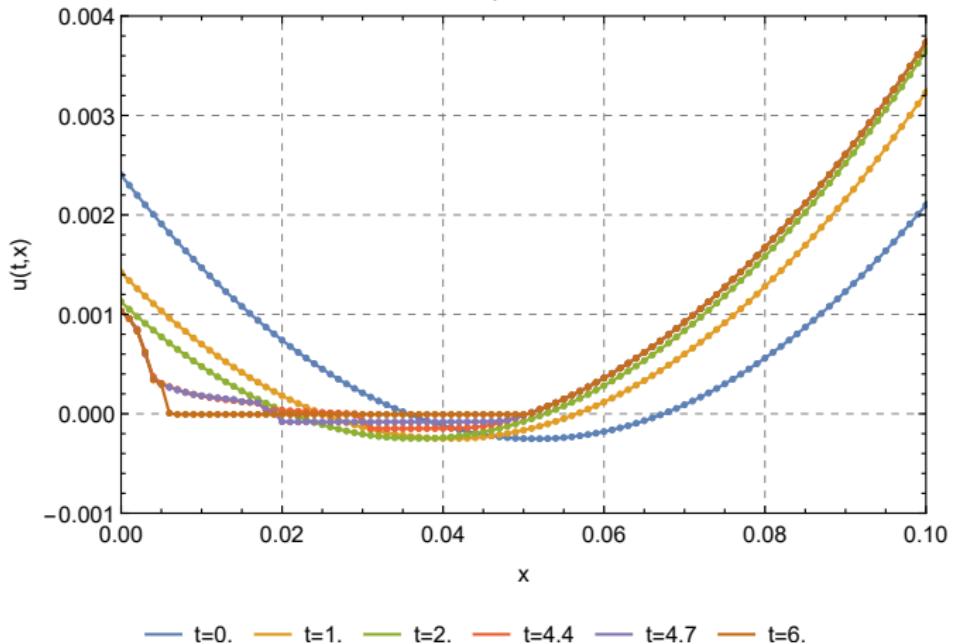
$LPA O(\infty), d=3, v(t=0,x)=1 \cdot x^2 - 0.103 x + 0.0024$
 $KT O(x^2) | n=151, x \in [0, 0.15] \Rightarrow \Delta x = 1 \cdot 10^{-3}$
 $t_W=8.16544$ s, steps=2729, RHS-calls/n=9978



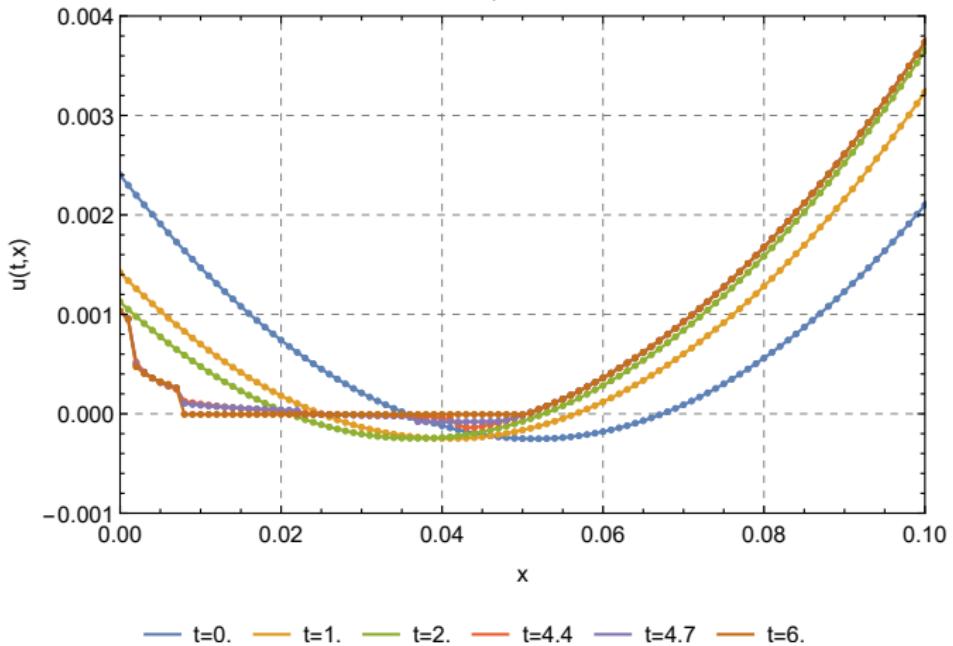
LPA O(2000), d=3, v(t=0,x)= $1 \cdot x^2 - 0.103 x + 0.0024$
 KT O(x^2) | n=151, $x \in [0, 0.15]$ $\Rightarrow \Delta x = 1 \cdot 10^{-3}$
 $t_W = 1.65594 \times 10^1$ s, steps=4431, RHS-calls/n=18721



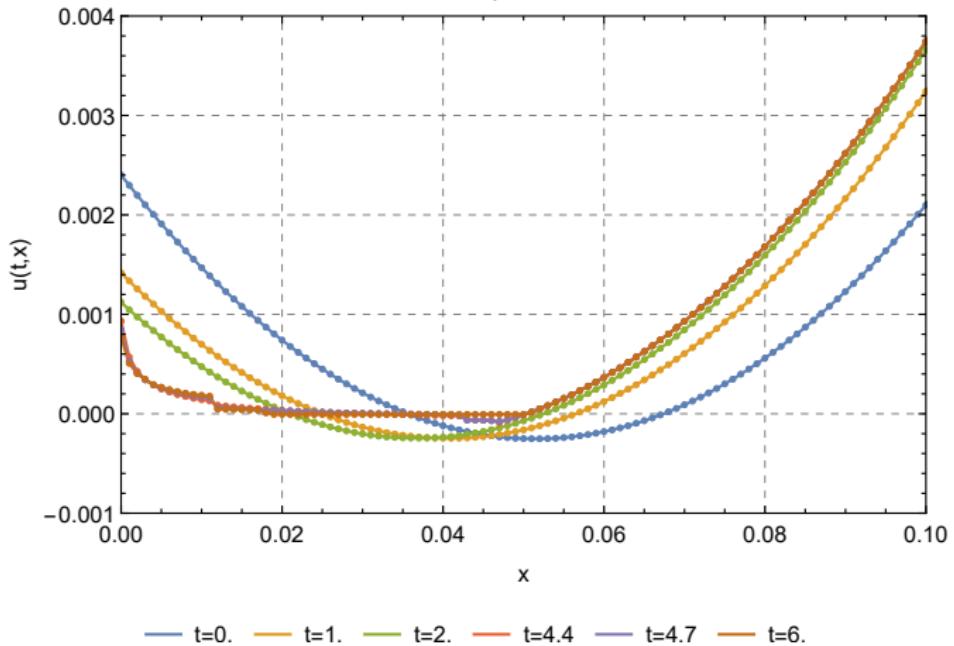
LPA $O(1500)$, $d=3$, $v(t=0,x)=1 \cdot x^2 - 0.103 x + 0.0024$
 KT $O(x^2)$ | $n=151$, $x \in [0, 0.15] \Rightarrow \Delta x = 1 \cdot 10^{-3}$
 $t_W = 1.96345 \times 10^1$ s, steps=5381, RHS-calls/n=24 766



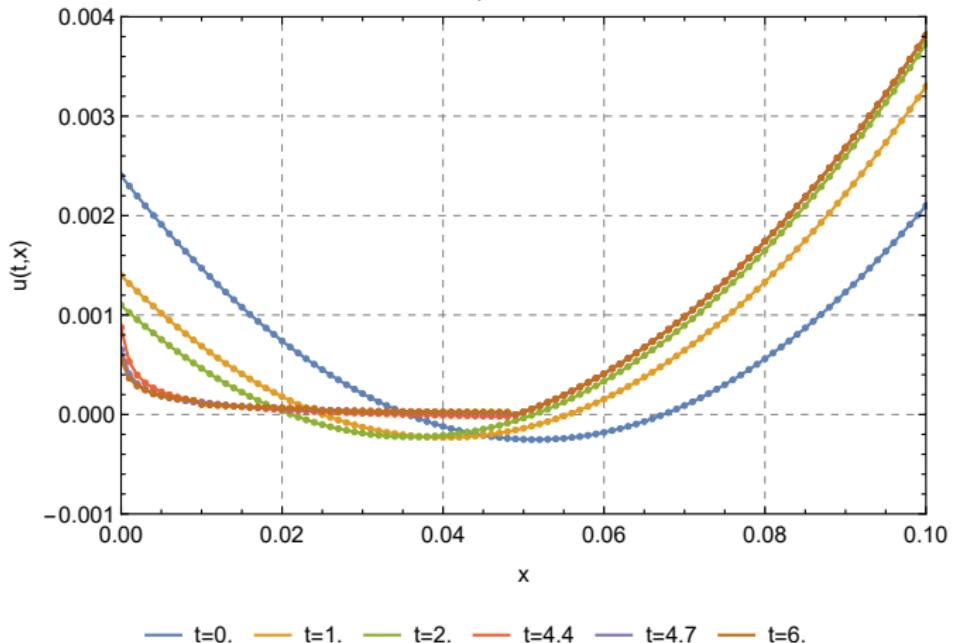
LPA O(1000), d=3, v(t=0,x)= $1 \cdot x^2 - 0.103 x + 0.0024$
 KT O(x^2) | n=151, $x \in [0, 0.15]$ $\Rightarrow \Delta x = 1 \cdot 10^{-3}$
 $t_W = 1.86091 \times 10^1$ s, steps=4990, RHS-calls/n=23 552



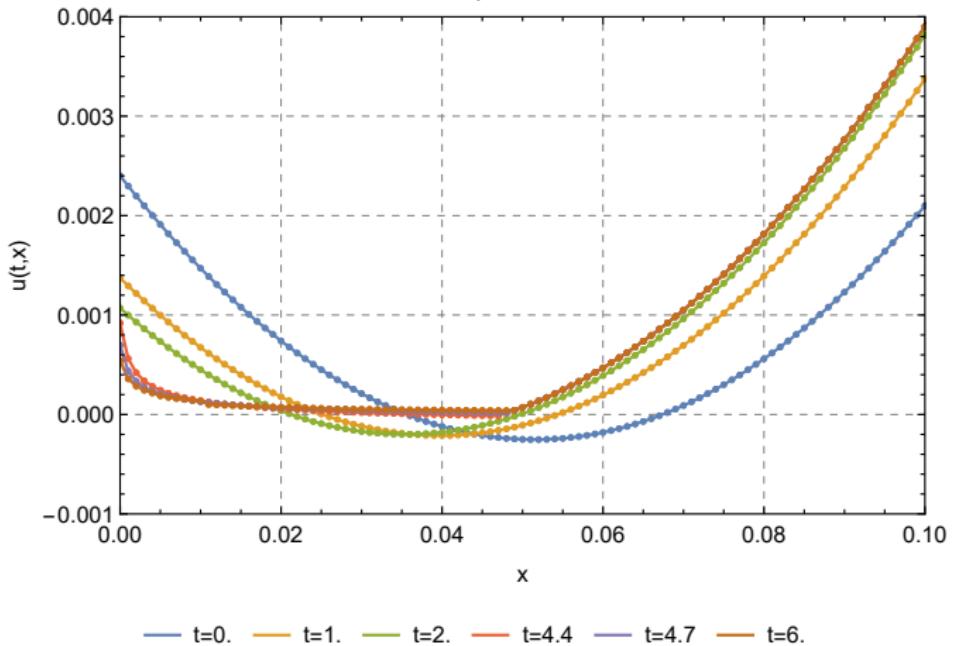
LPA $O(500)$, $d=3$, $v(t=0,x)=1 \cdot x^2 - 0.103 x + 0.0024$
 KT $O(x^2)$ | $n=151$, $x \in [0, 0.15] \Rightarrow \Delta x = 1 \cdot 10^{-3}$
 $t_W = 1.57667 \times 10^1$ s, steps=3985, RHS-calls/n=18999



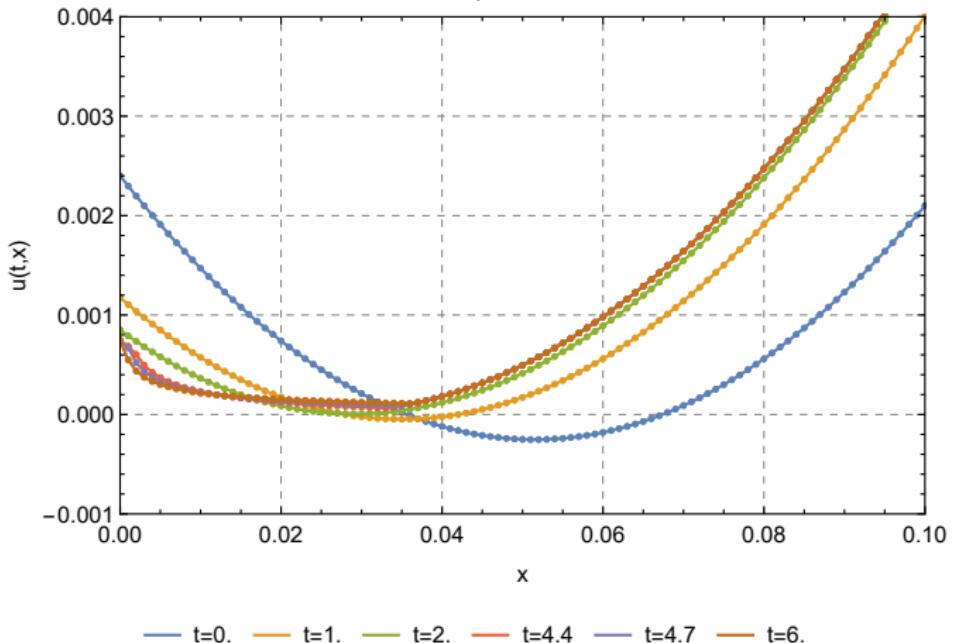
LPA O(100), d=3, v(t=0,x)= $1 \cdot x^2 - 0.103 x + 0.0024$
 KT O(x^2) | n=151, $x \in [0, 0.15]$ $\Rightarrow \Delta x = 1 \cdot 10^{-3}$
 $t_W = 6.19885$ s, steps=1843, RHS-calls/n=7732



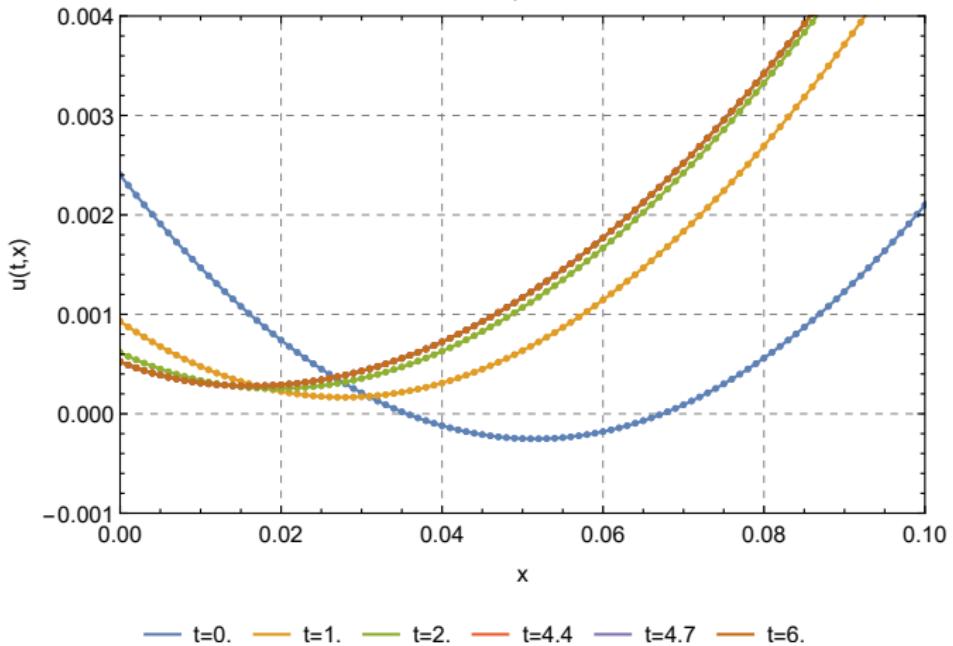
LPA O(50), d=3, v(t=0,x)= $1 \cdot x^2 - 0.103 x + 0.0024$
KT O(x^2) | n=151, $x \in [0, 0.15] \Rightarrow \Delta x = 1 \cdot 10^{-3}$
 $t_W = 5.94463$ s, steps=1735, RHS-calls/n=6806



LPA O(10), d=3, v(t=0,x)= $1 \cdot x^2 - 0.103 x + 0.0024$
 KT O(x^2) | n=151, $x \in [0, 0.15]$ $\Rightarrow \Delta x = 1 \cdot 10^{-3}$
 $t_W = 3.57829$ s, steps=1152, RHS-calls/n=4044



LPA O(5), d=3, v(t=0,x)= $1 \cdot x^2 - 0.103 x + 0.0024$
 KT O(x^2) | n=151, $x \in [0, 0.15]$ $\Rightarrow \Delta x = 1 \cdot 10^{-3}$
 $t_W = 9.31835 \times 10^{-1}$ s, steps=442, RHS-calls/n=917



O(N) model in d=0 - Exact solution

- ▶ A zero dimensional field-theory of N scalars ϕ_a :

$$S = U(\phi_a \phi^a / 2) = \frac{\lambda_1}{2} \phi_a \phi^a + \frac{\lambda_2}{8} (\phi_a \phi^a)^2 + \frac{\lambda_3}{24} (\phi_a \phi^a)^3 + \dots \quad (17)$$

$$= U(\rho), \quad \rho \equiv \phi_a \phi^a / 2 \quad (18)$$

- The physical minimum is always at $\langle \phi_a \phi^a \rangle = 0$
- All n -Point functions can be computed by solving one-dimensional integrals: e.g.:

$$\Gamma^{(2)} = \frac{NR_{N-1}}{R_{N+1}}, \quad R_N = \int_0^\infty dy y^N \exp \left[-U(y^2/2) \right] \quad (19)$$

for further details see e.g.: J. Keitel and L. Bartosch, J. Phys. **A45** (2012), arXiv: 1109.3013 [cond-mat.stat-mech]

O(N) model in d=0 - FRG approach

- ▶ The Wetterich eq. in $d = 0$ is a partial differential equation:

$$\frac{dU_t(\rho)}{dt} = \frac{N-1}{R_t + U'_t(\rho)} \frac{dR_t}{dt} + \frac{1}{R_t + U'_t(\rho) + 2\rho U''_t(\rho)} \frac{dR_t}{dt} \quad (20)$$

with $t = 0$ and $R_0 = \infty$ in the UV and $t = 1$ and $R_1 = 0$ in the IR.

- Various regulators can be constructed e.g.:

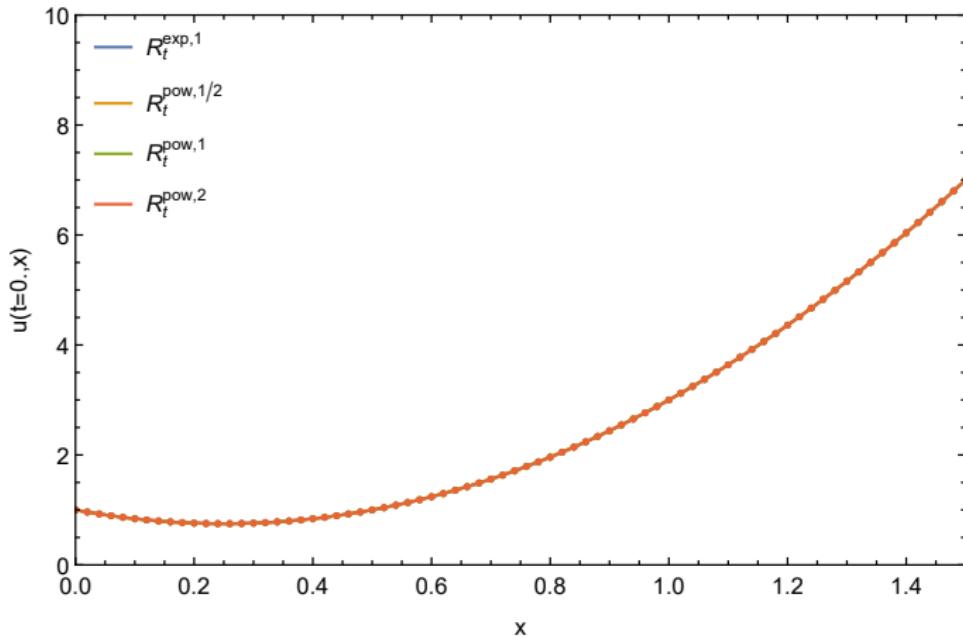
$$R_t^{\text{exp},m} = \exp[1/t^m - 1] - 1 \quad \text{with } m > 0 \quad (21)$$

$$R_t^{\text{pow},m} = 1/t^m - 1, \quad \text{with } m > 0 \quad (22)$$

- The exact flow eqs. for $\partial_\rho U_t$ can be solved numerically and results can be confronted with n -point functions from exact integration

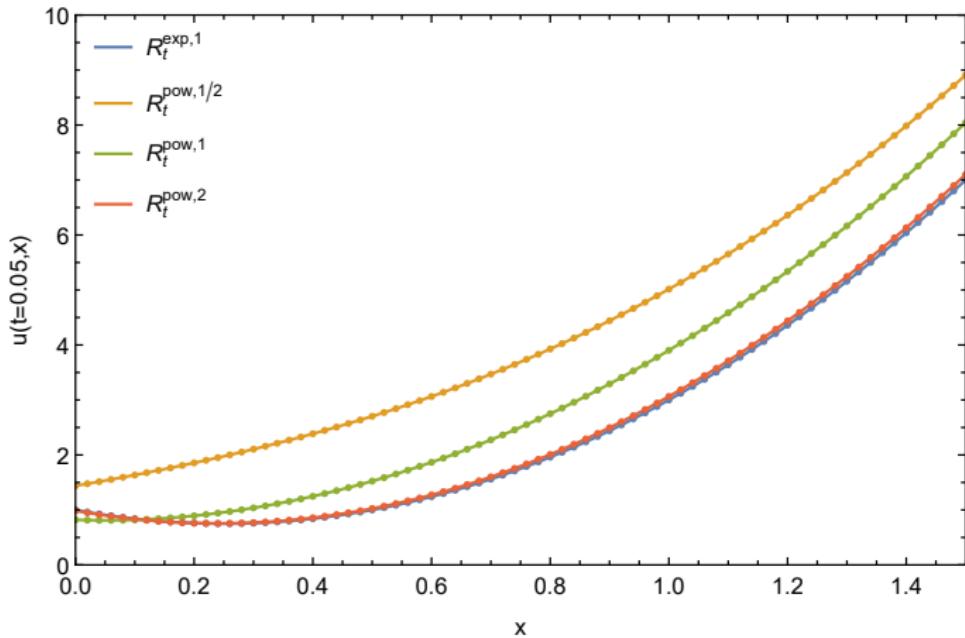
O(N) model in d=0 - Regulator trajectories

$O(4), d=0, u(t=0, x) = 1 + (-2 + 4x)x$
KT $O(x^2) \mid n=201, x \in [0, 4] \Rightarrow \Delta x = 2 \times 10^{-2}$

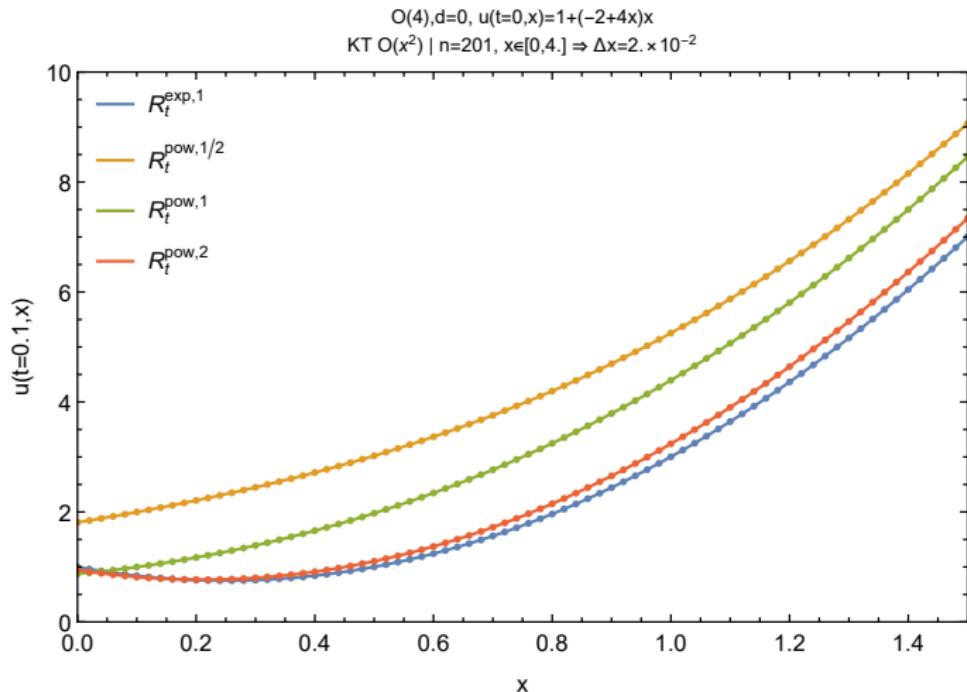


O(N) model in d=0 - Regulator trajectories

$O(4), d=0, u(t=0, x) = 1 + (-2 + 4x)x$
KT $O(x^2) \mid n=201, x \in [0, 4] \Rightarrow \Delta x = 2 \times 10^{-2}$

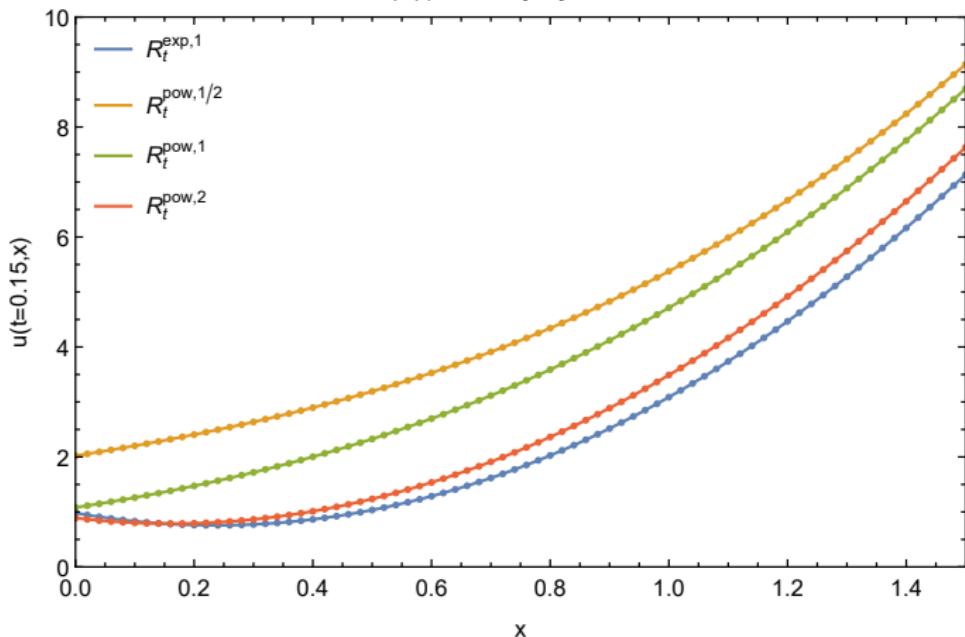


O(N) model in d=0 - Regulator trajectories



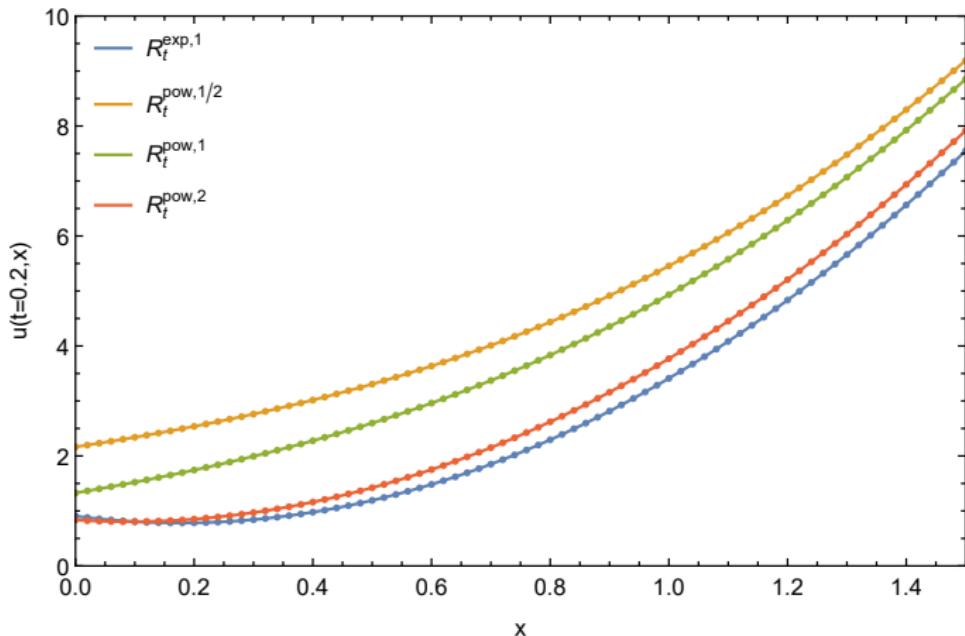
O(N) model in d=0 - Regulator trajectories

$O(4), d=0, u(t=0, x) = 1 + (-2 + 4x)x$
KT $O(x^2) \mid n=201, x \in [0, 4] \Rightarrow \Delta x = 2 \times 10^{-2}$

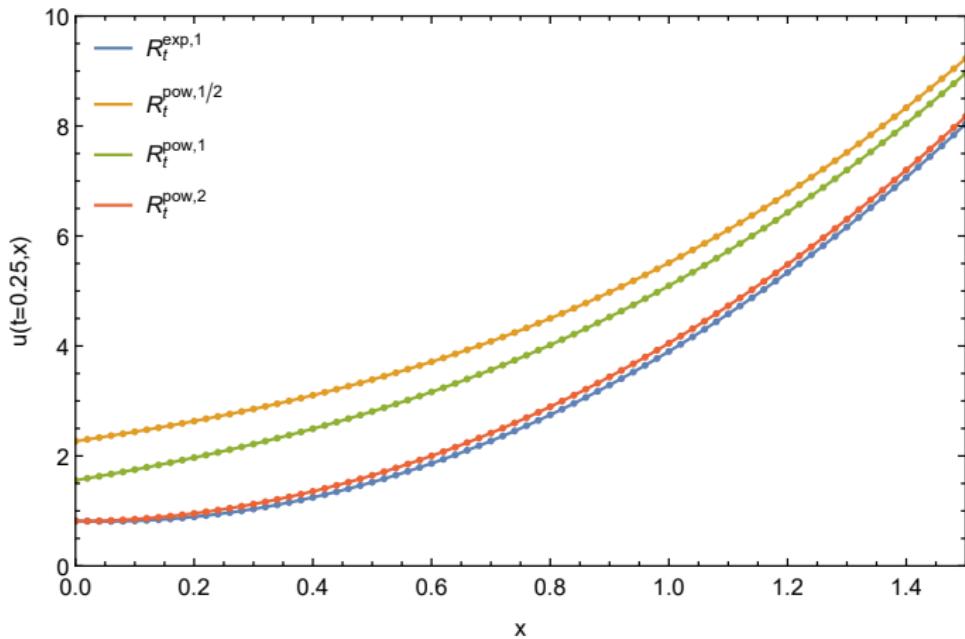


O(N) model in d=0 - Regulator trajectories

$O(4), d=0, u(t=0, x) = 1 + (-2 + 4x)x$
KT $O(x^2) \mid n=201, x \in [0, 4] \Rightarrow \Delta x = 2 \times 10^{-2}$

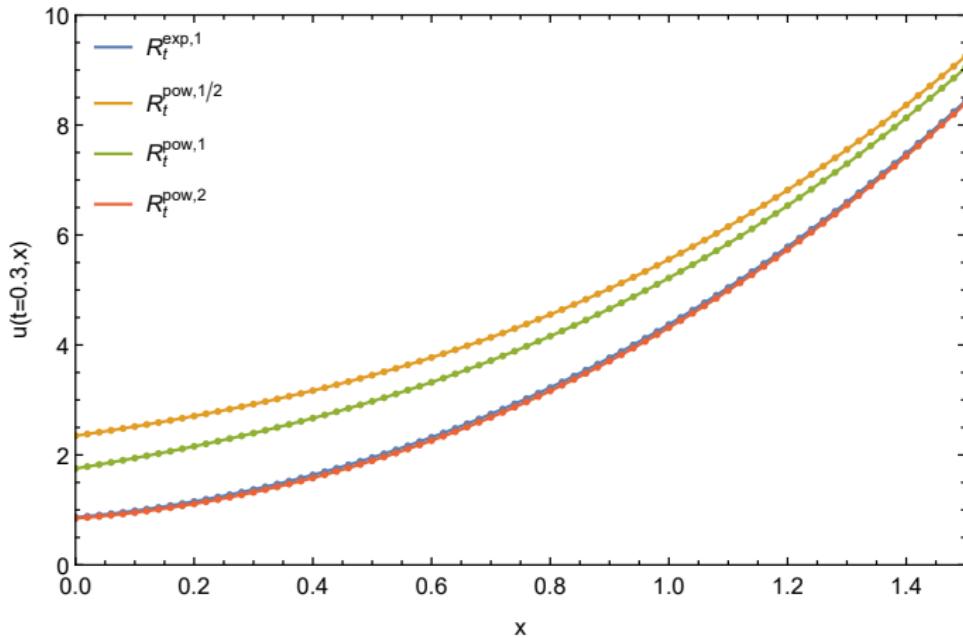


$O(4), d=0, u(t=0, x) = 1 + (-2 + 4x)x$
 KT $O(x^2) \mid n=201, x \in [0, 4] \Rightarrow \Delta x = 2 \times 10^{-2}$

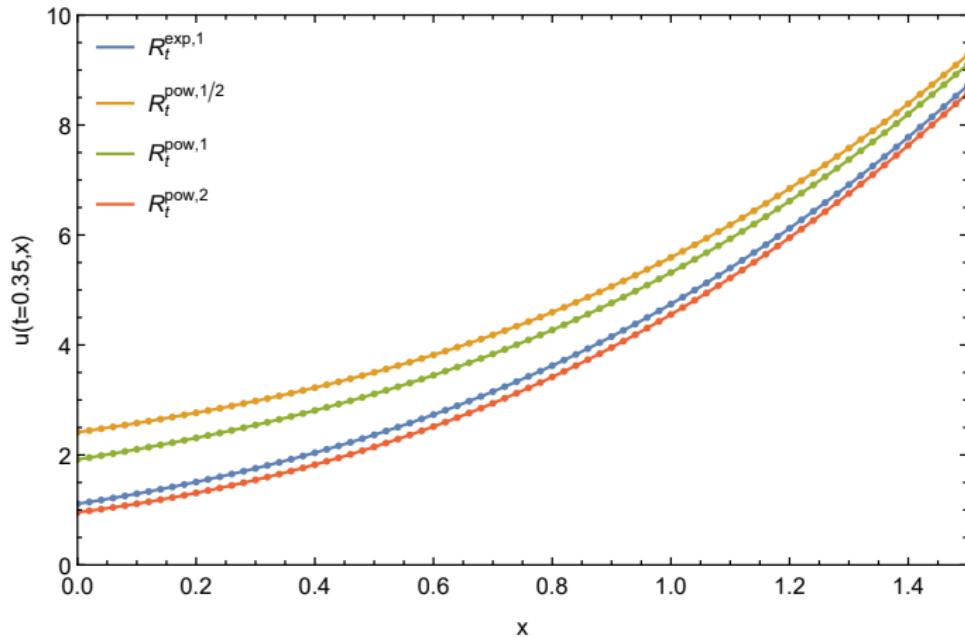


O(N) model in d=0 - Regulator trajectories

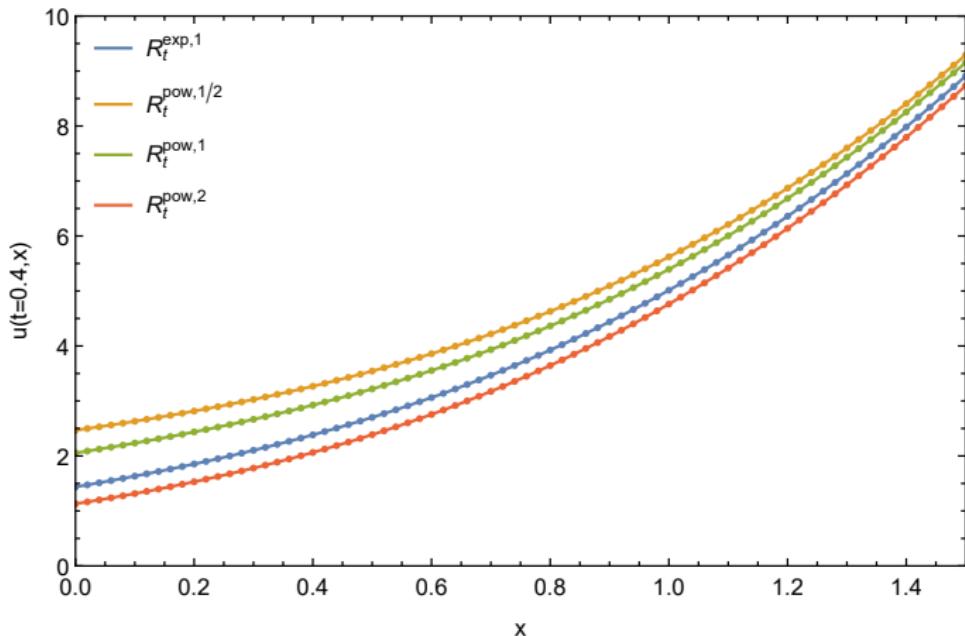
$O(4), d=0, u(t=0, x) = 1 + (-2 + 4x)x$
KT $O(x^2) \mid n=201, x \in [0, 4] \Rightarrow \Delta x = 2 \times 10^{-2}$



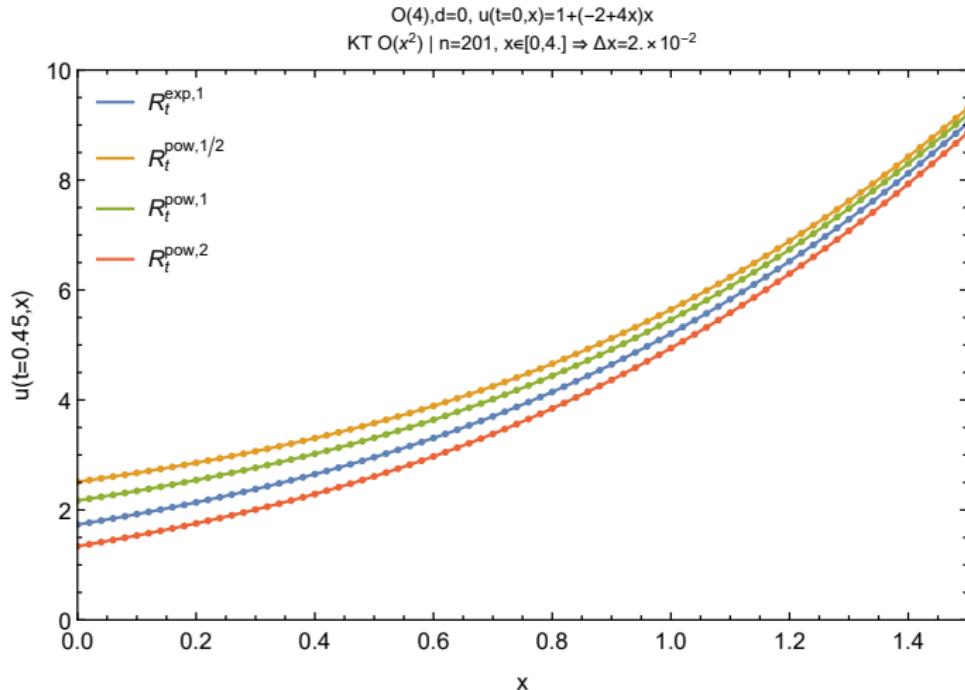
$O(4), d=0, u(t=0, x) = 1 + (-2 + 4x)x$
 KT $O(x^2) \mid n=201, x \in [0, 4] \Rightarrow \Delta x = 2 \cdot 10^{-2}$

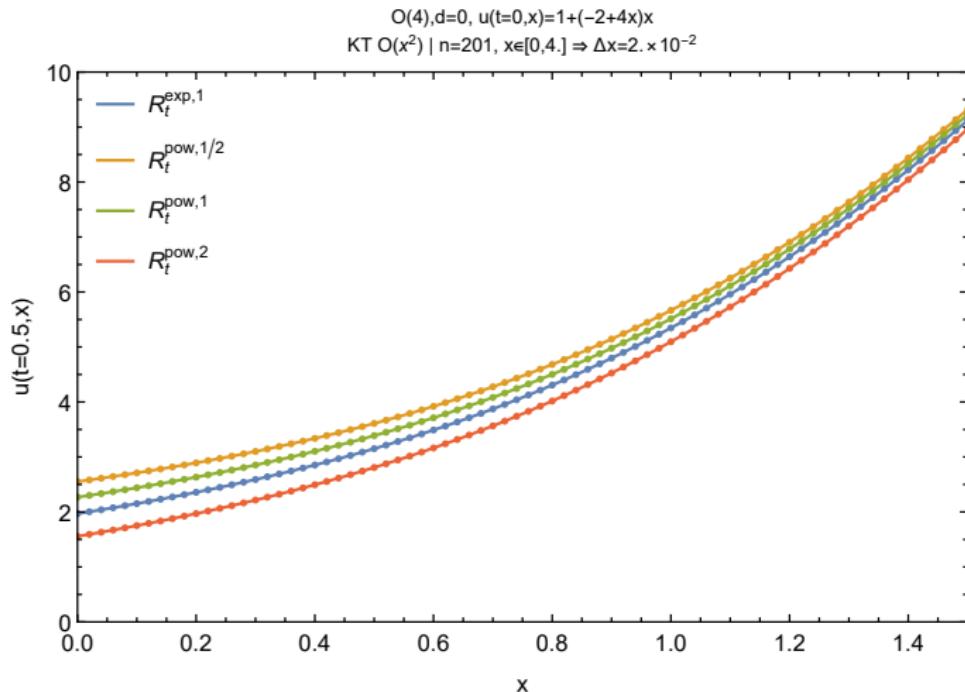


$O(4), d=0, u(t=0, x) = 1 + (-2 + 4x)x$
 KT $O(x^2) \mid n=201, x \in [0, 4] \Rightarrow \Delta x = 2 \cdot 10^{-2}$

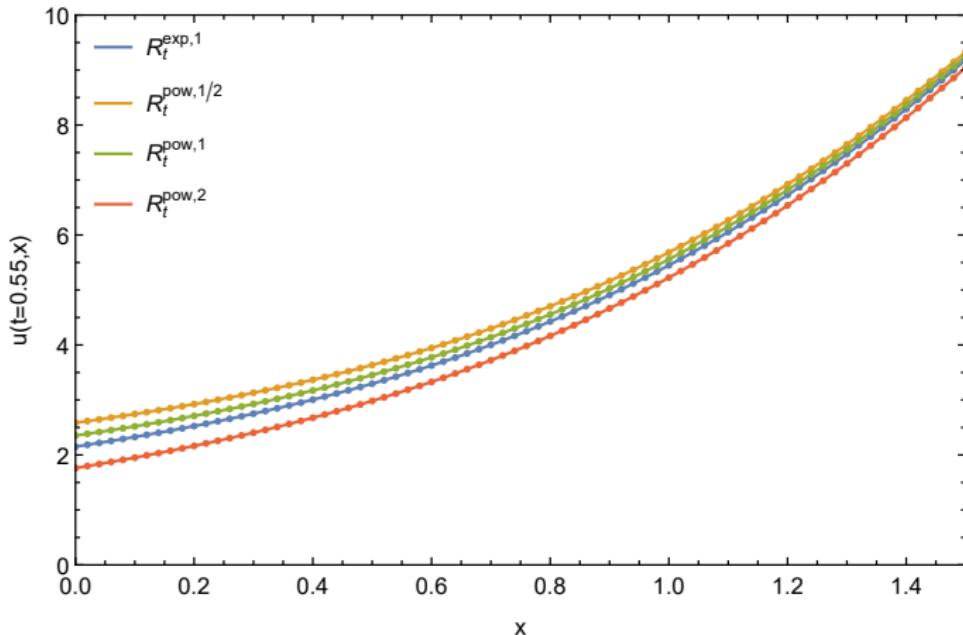


O(N) model in d=0 - Regulator trajectories



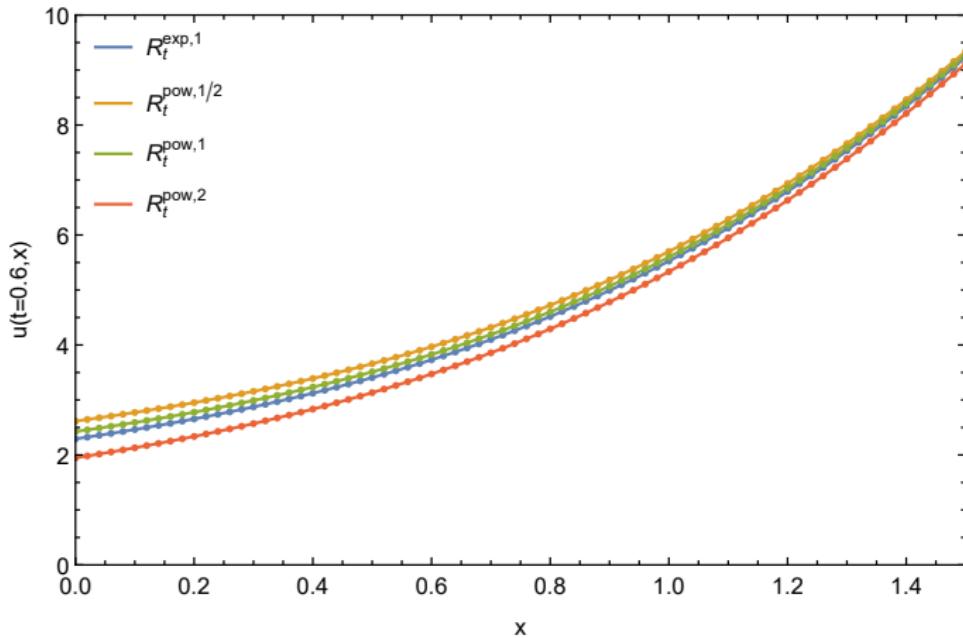


$O(4), d=0, u(t=0, x) = 1 + (-2 + 4x)x$
KT $O(x^2) \mid n=201, x \in [0, 4] \Rightarrow \Delta x = 2 \times 10^{-2}$



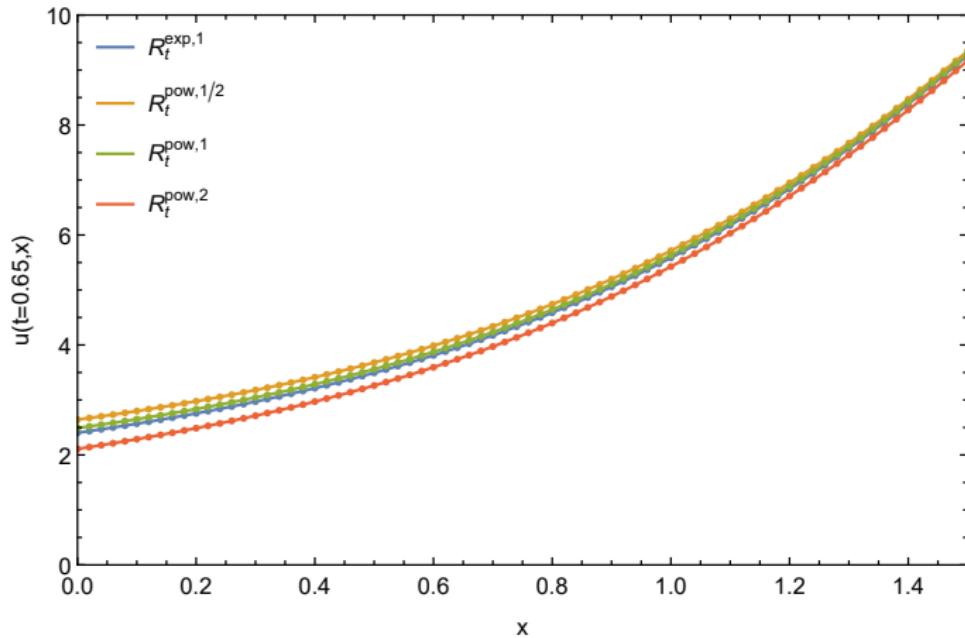
O(N) model in d=0 - Regulator trajectories

$O(4), d=0, u(t=0, x) = 1 + (-2 + 4x)x$
KT $O(x^2) \mid n=201, x \in [0, 4] \Rightarrow \Delta x = 2 \times 10^{-2}$



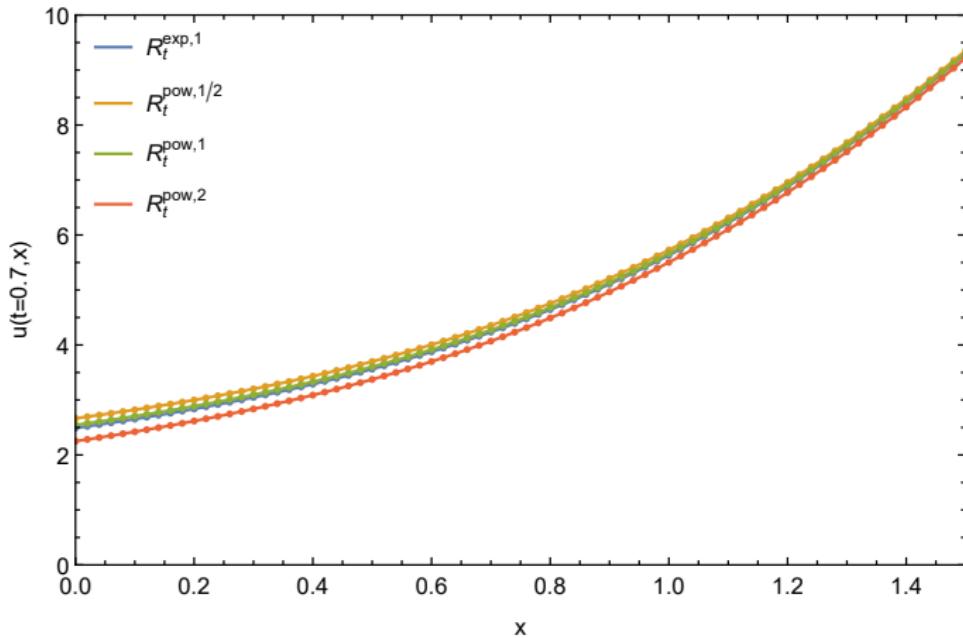
O(N) model in d=0 - Regulator trajectories

$O(4), d=0, u(t=0, x) = 1 + (-2 + 4x)x$
KT $O(x^2) \mid n=201, x \in [0, 4] \Rightarrow \Delta x = 2 \times 10^{-2}$

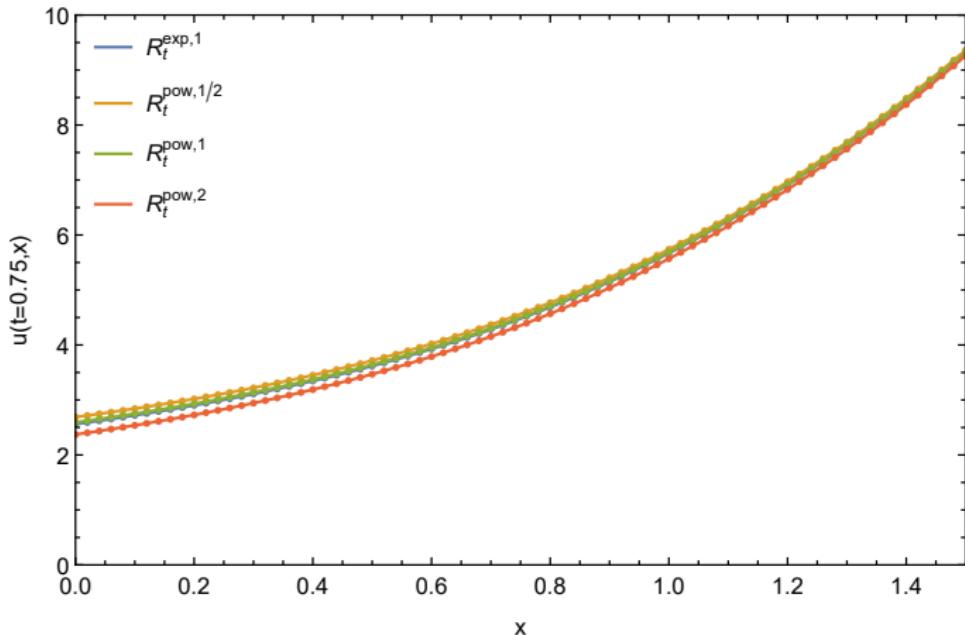


O(N) model in d=0 - Regulator trajectories

$O(4), d=0, u(t=0, x) = 1 + (-2 + 4x)x$
KT $O(x^2) \mid n=201, x \in [0, 4] \Rightarrow \Delta x = 2 \times 10^{-2}$

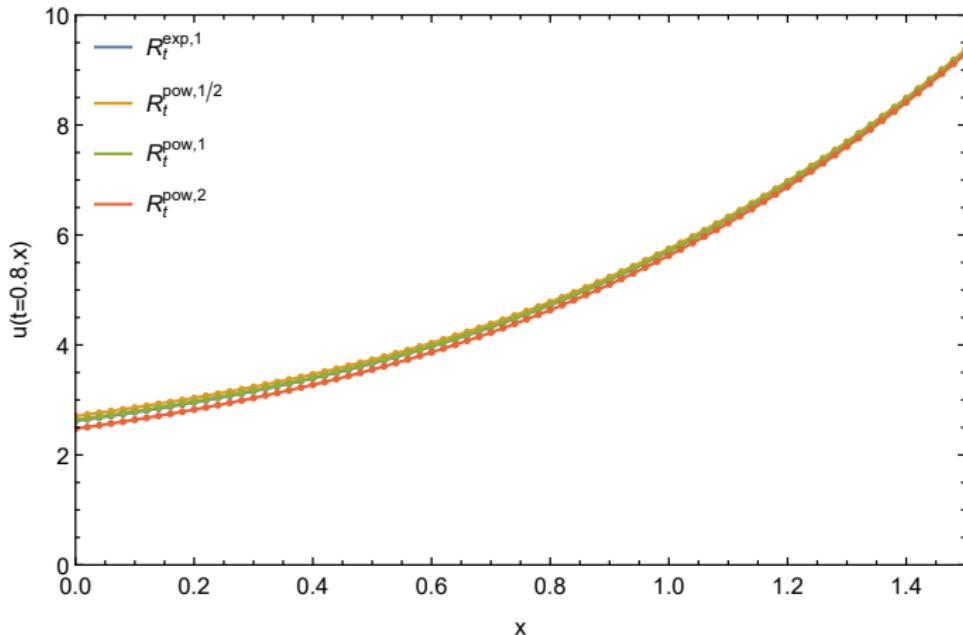


$O(4), d=0, u(t=0, x) = 1 + (-2 + 4x)x$
KT $O(x^2) \mid n=201, x \in [0, 4] \Rightarrow \Delta x = 2 \times 10^{-2}$



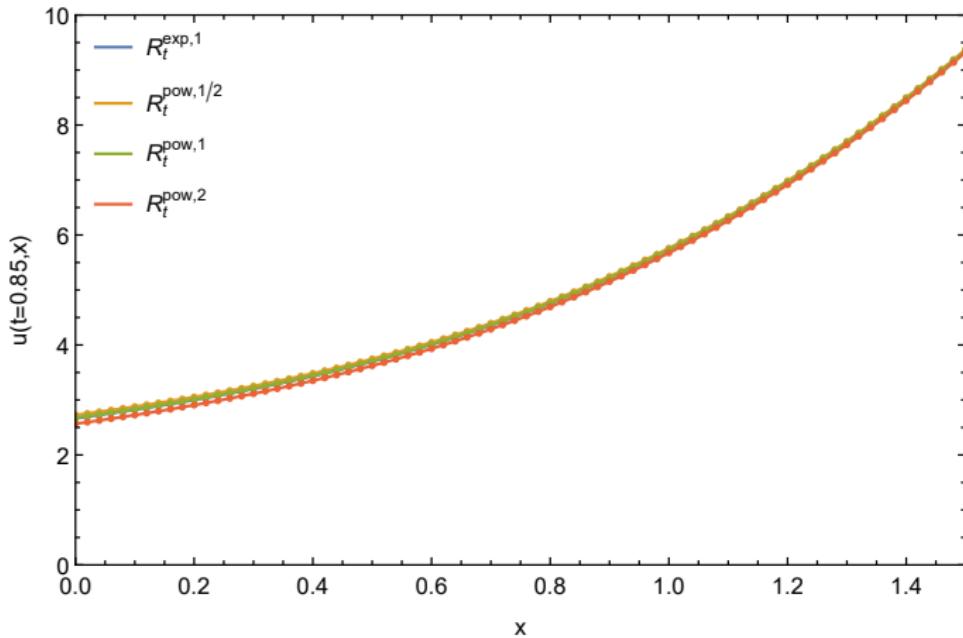
O(N) model in d=0 - Regulator trajectories

$O(4), d=0, u(t=0, x) = 1 + (-2 + 4x)x$
KT $O(x^2) \mid n=201, x \in [0, 4] \Rightarrow \Delta x = 2 \times 10^{-2}$



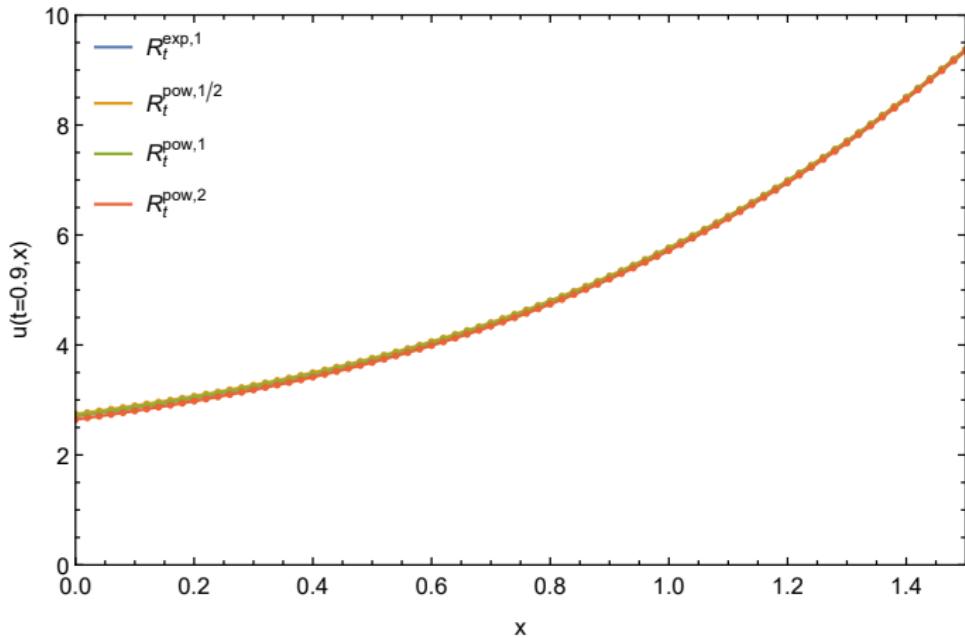
O(N) model in d=0 - Regulator trajectories

$O(4), d=0, u(t=0, x) = 1 + (-2 + 4x)x$
KT $O(x^2) \mid n=201, x \in [0, 4.] \Rightarrow \Delta x = 2 \times 10^{-2}$



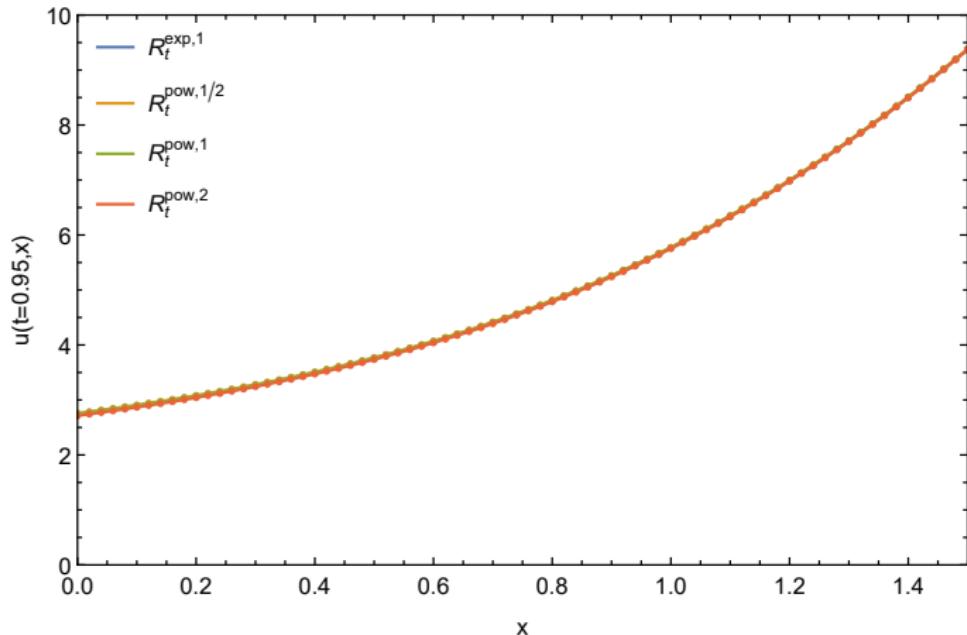
O(N) model in d=0 - Regulator trajectories

$O(4), d=0, u(t=0, x) = 1 + (-2 + 4x)x$
KT $O(x^2) \mid n=201, x \in [0, 4.] \Rightarrow \Delta x = 2 \times 10^{-2}$

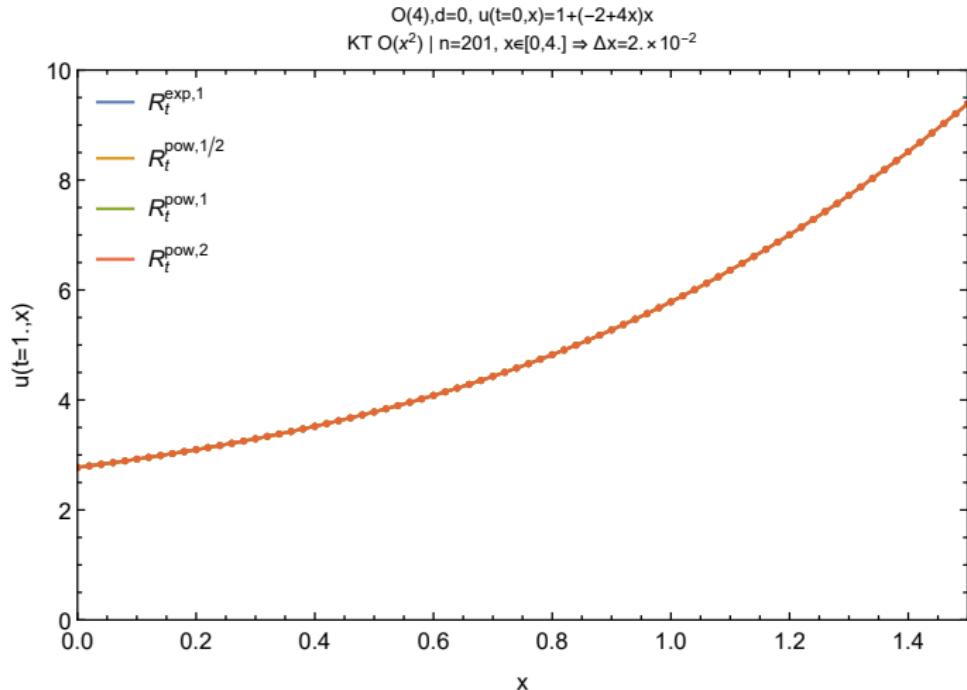


O(N) model in d=0 - Regulator trajectories

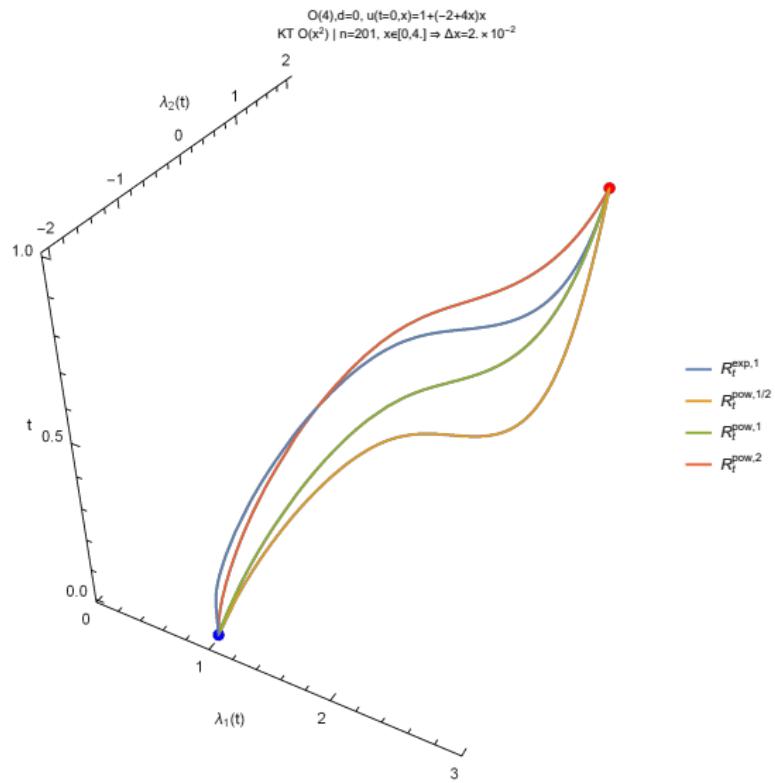
$O(4), d=0, u(t=0, x) = 1 + (-2 + 4x)x$
KT $O(x^2) \mid n=201, x \in [0, 4.] \Rightarrow \Delta x = 2 \times 10^{-2}$



O(N) model in d=0 - Regulator trajectories



O(N) model in d=0 - $\lambda_1(t)$ and $\lambda_2(t)$



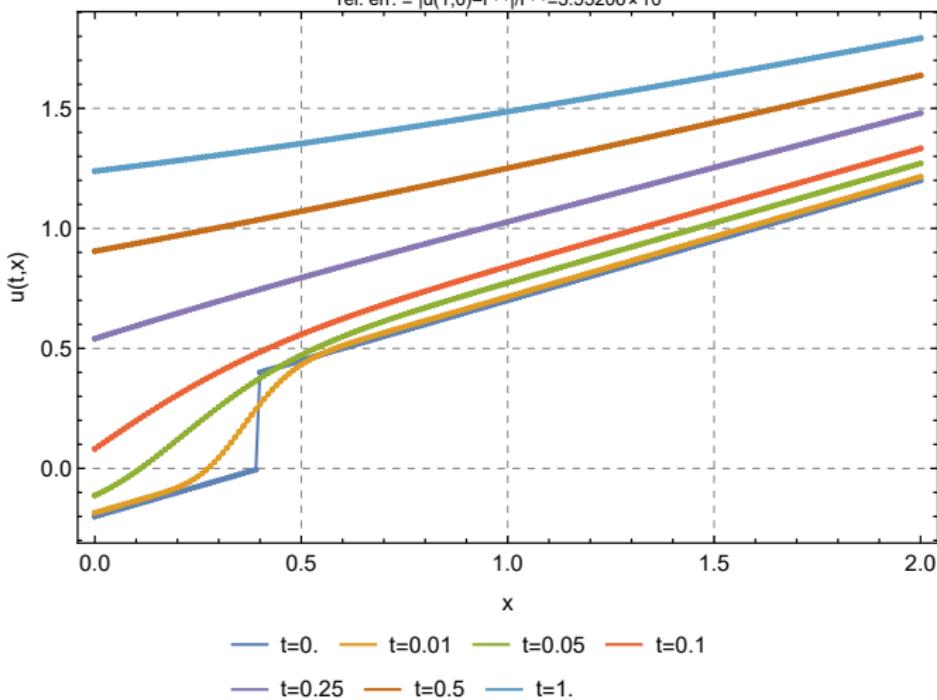
O(4) model in d=0 - Discontinuous IC

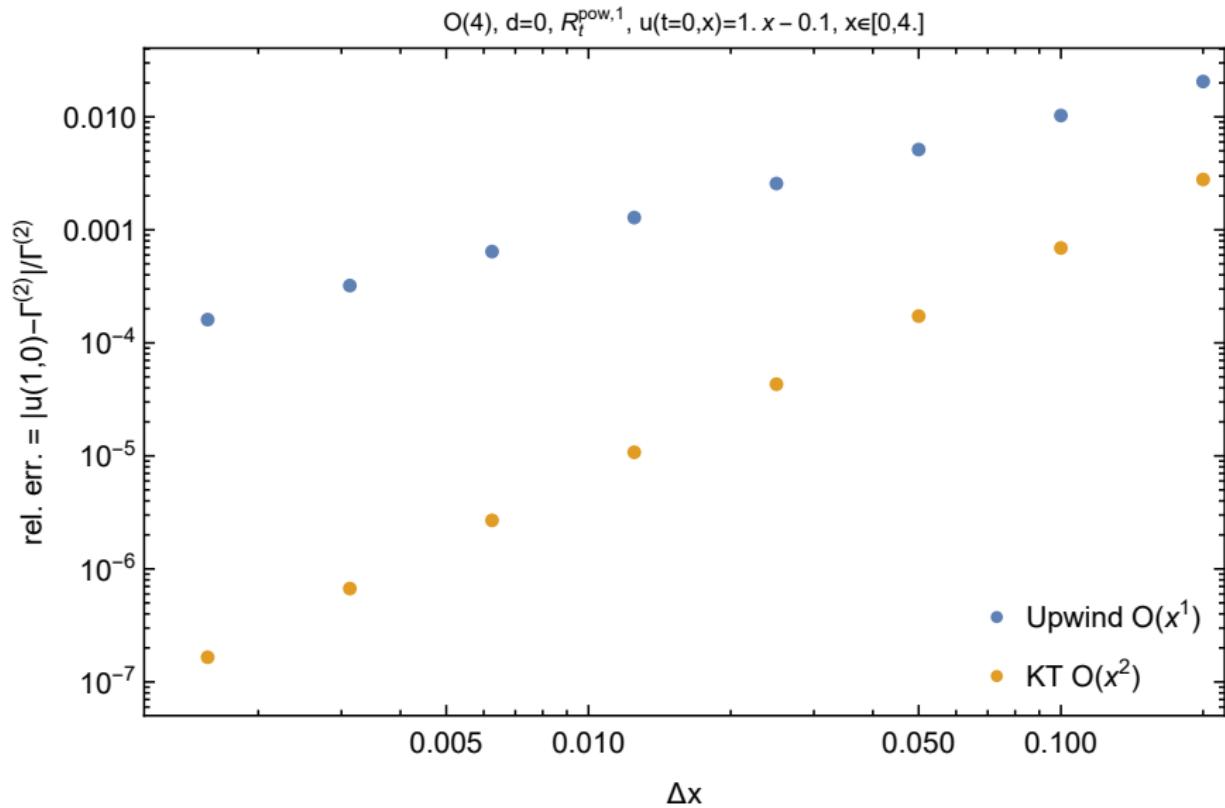
O(4), d=0, $R_t^{\text{POW},1}$ $u(t=0,x)=0.5x+\text{lf}[x<0.4,-0.2,0.2]$

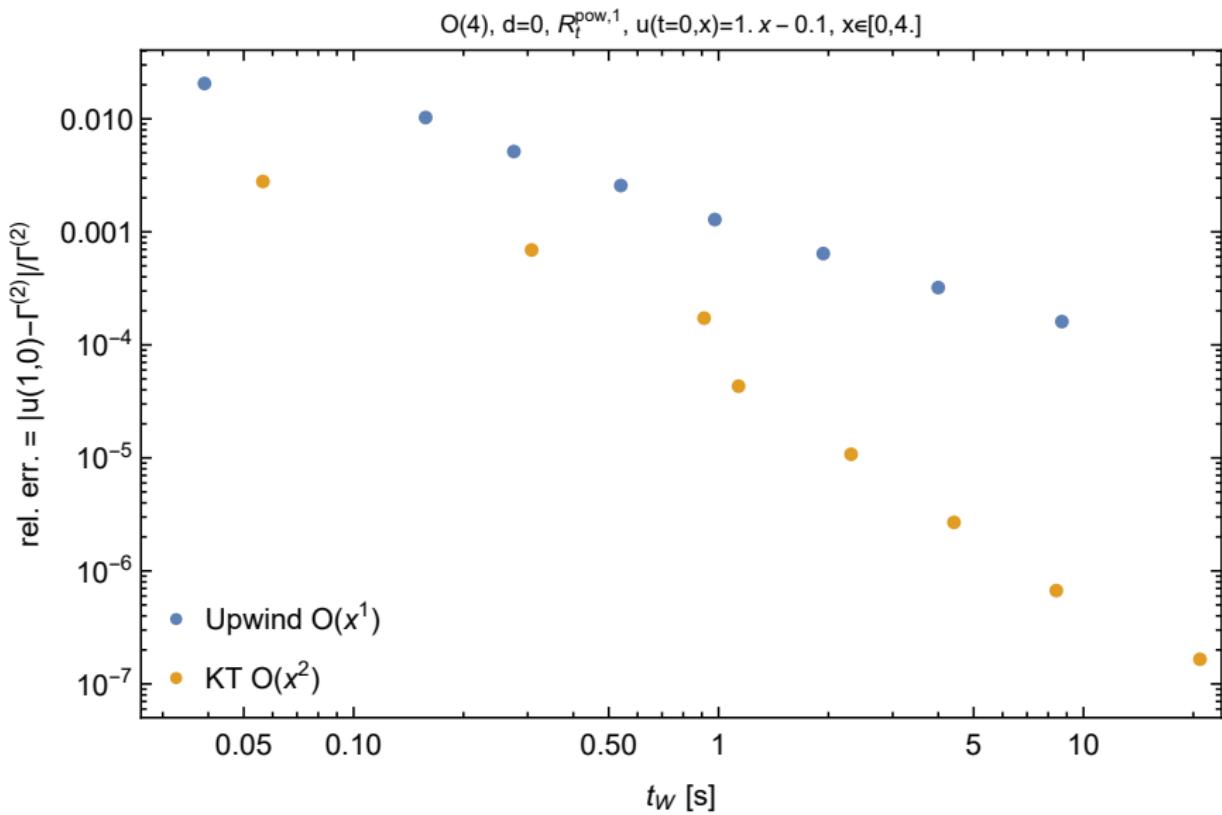
KT O(x^2) | n=201, x $\in[0,2]$ $\Rightarrow \Delta x=1 \times 10^{-2}$

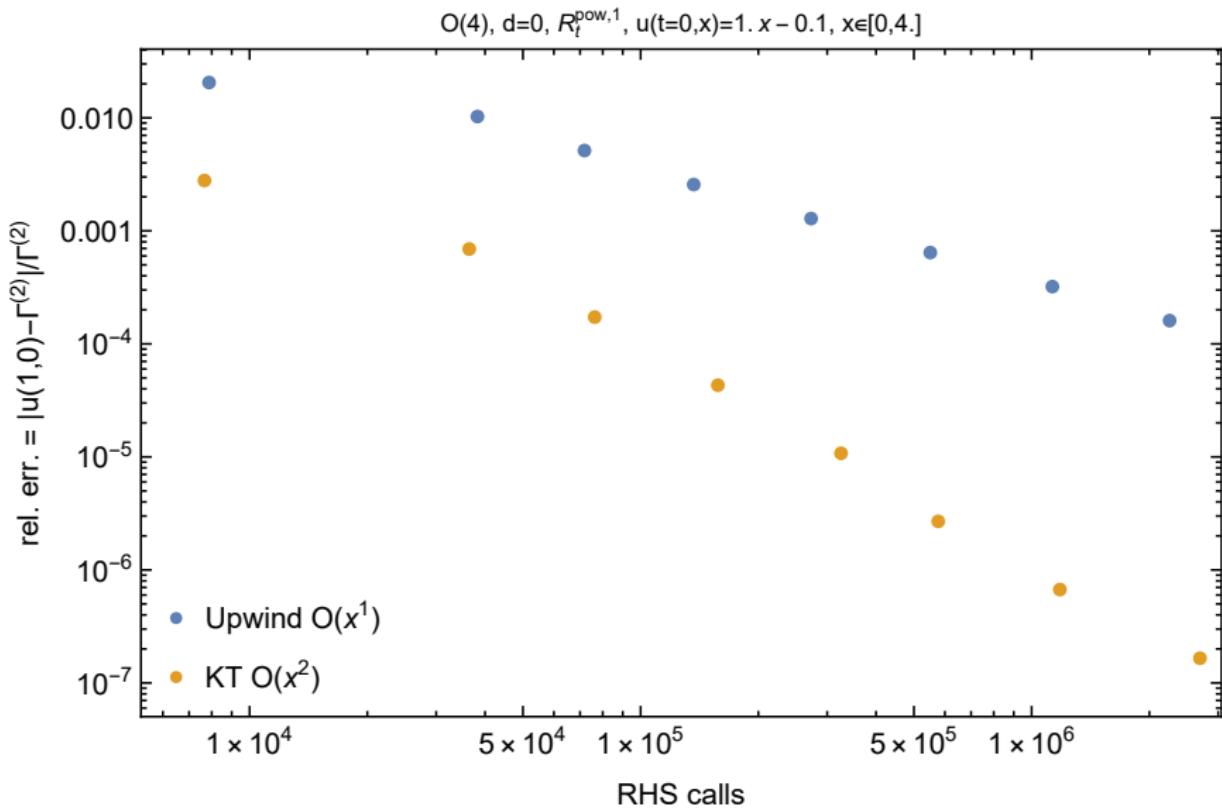
$t_W=1.25177 \times 10^1$ s, steps=3288, RHS-calls/n=9026

rel. err. = $|u(1,0)-\Gamma^{(2)}|/\Gamma^{(2)}=3.55206 \times 10^{-4}$









- ▶ The second order KT-scheme in its semi-discrete form (4)
 - Robust and competitive spatial discretisation scheme
 - Easy to implement/extend
 - First applications to FRG LPA flow eqs. look very promising
- ▶ O(N) model in zero dimensions
 - Well suited for numerical test (exact solutions, non-trivial flow eqs.)
 - Very instructive toy model for various aspects of FRG and QFTs in general
- ▶ TODO:
 - Finite volume/KT scheme beyond LPA
 - Finite volume/KT scheme at finite T and μ
 - ...