Introduction to the Adjoint Method

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Outline

1. Adjoint Sensitivity Analysis of Linear Systems

Consider the Ordinary Differential Equation (ODE)

$$a(t,z)\frac{d\psi}{dt} + b(t,z)\psi = s(t)$$
(1.1)

lacktriangleright z is a design parameter that we want to change in order to minimize the objective function G

$$G = \int_0^T g(\psi, z) dt \tag{1.2}$$

- ▶ To minimize G, we need the gradient with respect to the design parameter *z*.
- ► The design parameter z can then be updated with the steepest descent

$$z = z - \alpha \frac{dG}{dz} \tag{1.3}$$

▶ Local descent involves iteratively determining a descent direction $\left(\frac{dG}{dz}\right)$ and then taking a step α in that direction and repeating that process until convergence or some termination condition is met

Lets modify the objective function G

$$G = \int_0^T g(\psi, z) dt + \int_0^T \lambda(t) R dt$$
 (1.4)

- ▶ Where the residual $R=0=a(t,z)\frac{d\psi}{dt}+b(t,z)\psi-s(t)$
- ▶ The equation is still valid and for any $\lambda(t)$, since we are multiplying $\lambda(t)$ by zero and we just added a zero to the whole equation.
- $ightharpoonup \lambda(t)$ is called the adjoint variable.

Using the chain rule to obtain the objective function gradient:

$$\frac{dG}{dz} = \int_0^T \frac{\partial g}{\partial z} + \frac{\partial g}{\partial \psi} \frac{\partial \psi}{\partial z} dt + \int_0^T \lambda \left[\frac{\partial a}{\partial z} \dot{\psi} + a \frac{\partial \dot{\psi}}{\partial z} + \frac{\partial b}{\partial z} \psi + b \frac{\partial \psi}{\partial z} \right] dt$$
(1.5)

lacksquare Integrating by parts the term containing $rac{\partial \dot{\psi}}{\partial z}$

$$\int_{0}^{T} \lambda \, a \frac{\partial \dot{\psi}}{\partial z} \, dt = \lambda a \frac{\partial \psi}{\partial z} \Big|_{0}^{T} - \int_{0}^{T} \frac{\partial \psi}{\partial z} \frac{d(\lambda a)}{dt} dt \tag{1.6}$$

 \blacktriangleright Collecting all the terms containing the integral of $\frac{\partial \psi}{\partial z}$

$$\frac{dG}{dz} = \int_{0}^{T} \frac{\partial g}{\partial z} + \lambda \frac{\partial b}{\partial z} \psi + \lambda \frac{\partial a}{\partial z} \dot{\psi} dt + \int_{0}^{T} -\frac{\partial \psi}{\partial z} \frac{d(\lambda a)}{dt} + \lambda b \frac{\partial \psi}{\partial z} + \frac{\partial g}{\partial \psi} \frac{\partial \psi}{\partial z} dt$$
(1.7)

$$\frac{dG}{dz} = \int_{0}^{T} \frac{\partial g}{\partial z} + \lambda \frac{\partial b}{\partial z} \psi + \lambda \frac{\partial a}{\partial z} \dot{\psi} dt
+ \int_{0}^{T} \frac{\partial \psi}{\partial z} \left[-\frac{d(\lambda a)}{dt} + \lambda b + \frac{\partial g}{\partial \psi} \right] dt + \lambda a \frac{\partial \psi}{\partial z} \Big|_{0}^{T}$$
(1.8)

lacktriangledown If the adjoint variable λ satisfied the following equation

$$-\frac{d(\lambda a)}{dt} + \lambda b + \frac{\partial g}{\partial \psi} = 0 \tag{1.9}$$

▶ Then the sensitivity of the objective function is

$$\frac{dG}{dz} = \int_0^T \frac{\partial g}{\partial z} + \lambda \frac{\partial b}{\partial z} \psi + \lambda \frac{\partial a}{\partial z} \dot{\psi} dt + \lambda a \frac{\partial \psi}{\partial z} \Big|_0^T \quad (1.10)$$

- $ightharpoonup rac{d\psi}{dz}=0$ at t = 0, as the initial condition does not depend on the design parameter.
- ▶ Imposing the terminal condition $\lambda(T) = 0$

$$\frac{dG}{dz} = \int_0^T \frac{\partial g}{\partial z} + \lambda \frac{\partial b}{\partial z} \psi + \lambda \frac{\partial a}{\partial z} \dot{\psi} dt$$
 (1.11)

- ▶ To solve for the sensitivity, we carry two simulations
 - 1. Solve for ψ

$$a(t,z)\frac{d\psi}{dt} + b(t,z)\psi = s(t)$$

2. Calculate the source term for the adjoint equation and solve for λ

$$\frac{d(\lambda a)}{dt} - \lambda b = \frac{\partial g}{\partial \psi}$$

3. Evaluate the sensitivity

$$\frac{dG}{dz} = \int_0^T \frac{\partial g}{\partial z} + \lambda \frac{\partial b}{\partial z} \psi + \lambda \frac{\partial a}{\partial z} \dot{\psi} dt$$