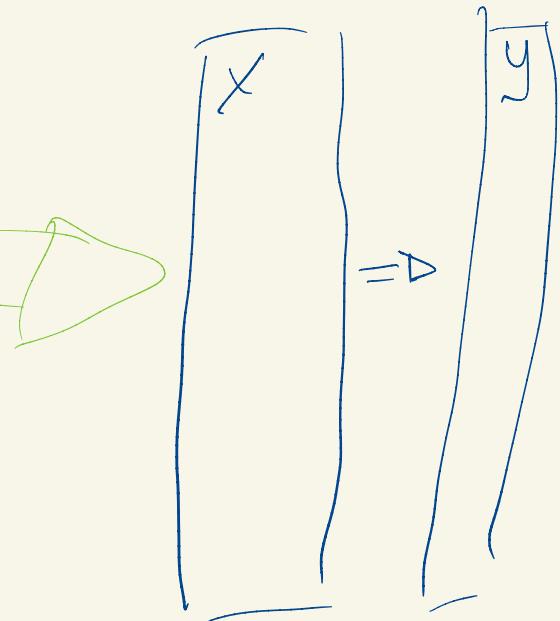
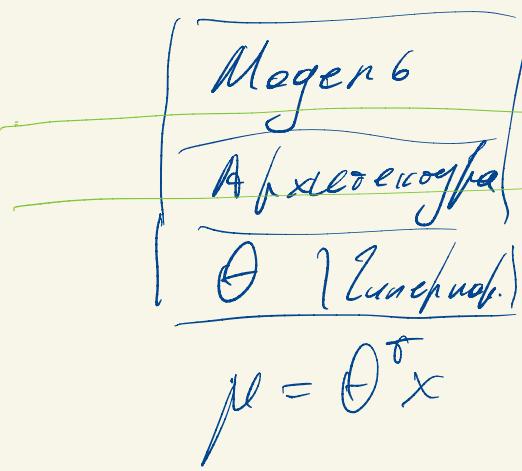


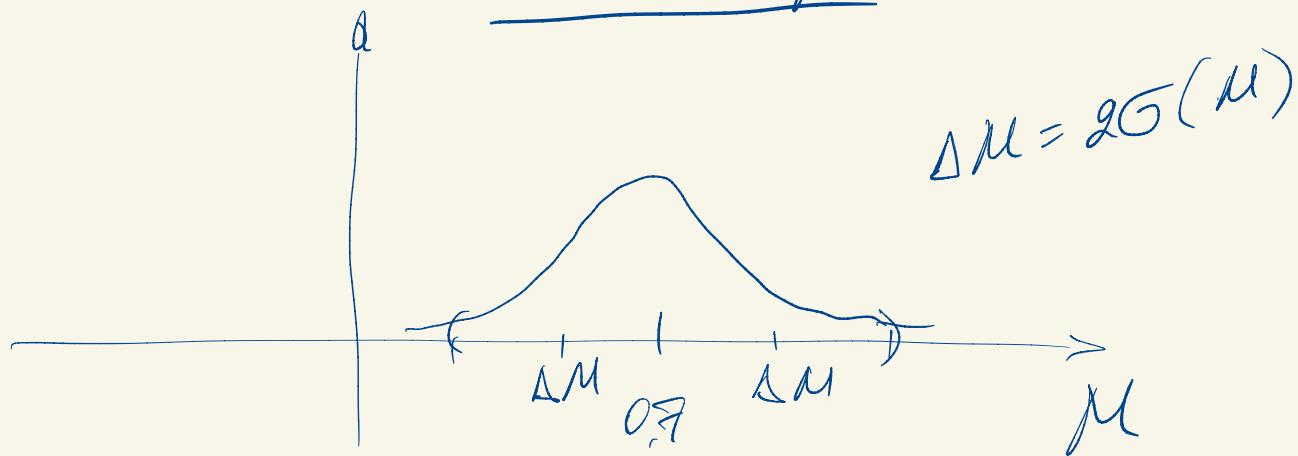
Supervised learning

X	y
Train	
Validation	
Test	



$$\bar{\mu} = \bar{\theta}_1 + \underline{\Delta \mu}$$

Bootstrap



Частичное обучение

$$\mu = \theta^T x$$

$x \not\rightarrow y$

$\theta = ?$

$$L = (y - \theta^T x)^T (y - \theta^T x)$$

$$L = \frac{1}{N} \sum_{i=1}^N (y_i - \theta^T x_i)^2$$

$$\boxed{\theta^* = \arg \min \ L(\theta, X, y)}$$

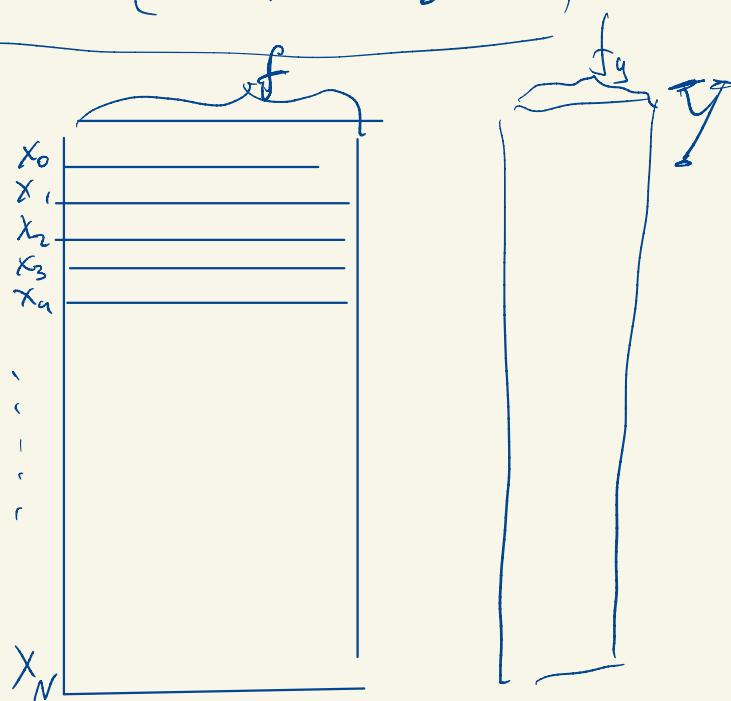
"однокаче"
КАК?

$$\nabla_{\theta} L(\theta^*) = 0 \quad \frac{\partial^2 L}{\partial \theta^2} - ?$$

$$\nabla_{\theta} L = -2 X^T y + 2 X^T X \theta = 0$$

$$\boxed{\theta^* = (X^T X)^{-1} X^T y}$$

$$\frac{\partial^2 L}{\partial \theta^2} = 2 X^T X$$



$$\boxed{\boldsymbol{\theta}^* = (\mathbf{X}^\top \mathbf{X})^{-1} \mathbf{X}^\top \mathbf{y}}$$

$$\mathbf{X}: N \times f$$

$$\mathbf{Y}: N \times f_y$$

$$\mathbf{X}^\top \mathbf{Y}: f \times N \cdot \underbrace{N \times f_y}_{f \times f_y}$$

$$\mathbf{X}^\top \mathbf{X}: f \times N \cdot \underbrace{N \times f}_{f \times f}$$

$$f \times f \cdot f \times f_y$$

$$\boldsymbol{\theta}^*: f \times f_y$$

$$\mathbf{X} \boldsymbol{\theta} \quad N \times \underbrace{(f \cdot f \times f_y)}_{N \times f_y}$$

$$\boxed{\theta^* = (X^T X)^{-1} X^T Y}$$

$$z = \theta^T x \quad p = \frac{1}{1+e^{-z}} = \sigma(z) \\ = \sigma(\theta^T x)$$

$$\theta^* = \underset{\theta}{\operatorname{arg\,min}} \mathcal{L}(\theta, \bar{X}, \bar{Y})$$

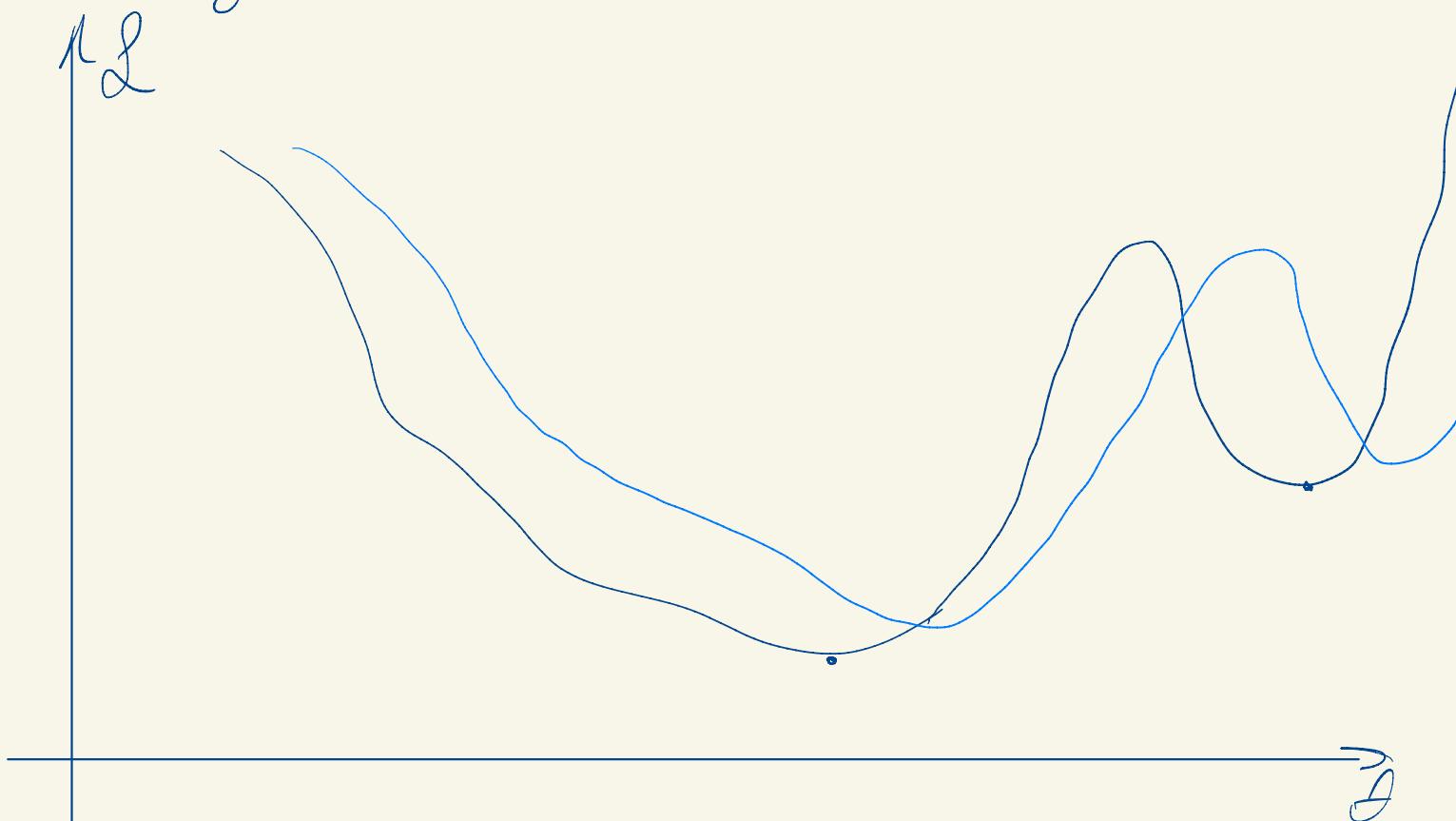
Методы оптимизации

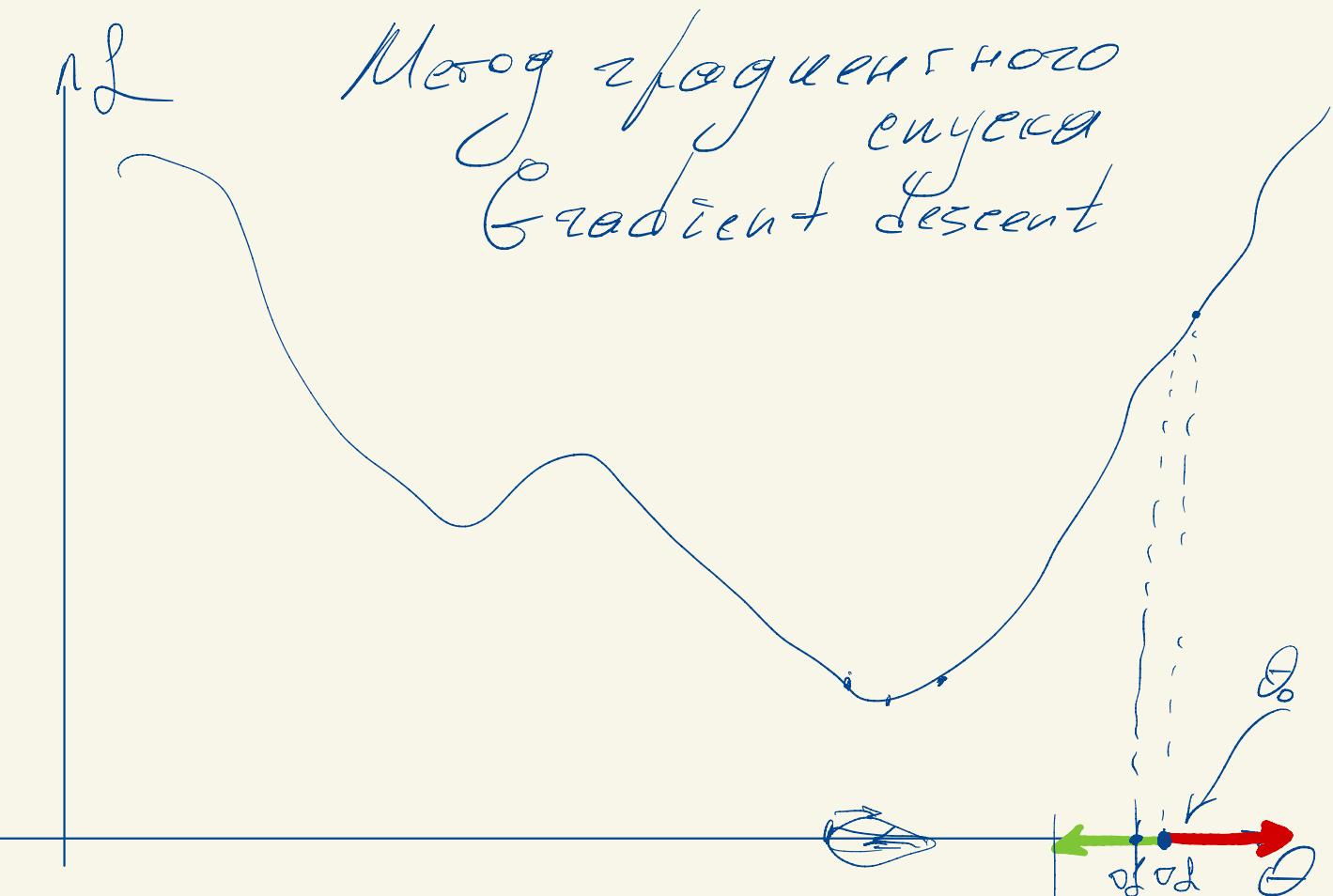
- ① Метод Калкас
- ② Геометрический
- ③ Численные

$$L(\theta, \bar{X}, \bar{Y}) \propto \bar{X}^\theta - \bar{Y} \left(\underbrace{\int x f_y(x)}_{\bar{Y}} \right)$$

$$\nabla_{\theta} \mathcal{L} = \vec{\theta}_0 \frac{\partial \mathcal{L}}{\partial \theta_0} + \vec{\theta}_1 \frac{\partial \mathcal{L}}{\partial \theta_1} + \dots + \vec{\theta}_d \frac{\partial \mathcal{L}}{\partial \theta_d}$$

$\nabla \theta$ L - указывает направление наименее затраченного
когда f на L





- 0) $\theta_0; t=0; \epsilon = 10^{-6}$ θ_0 - начальное приближение
- 1) $\nabla_{\theta} L$ $\nabla_{\theta} L$ - градиент L по θ
- 2) $\theta_{t+1} = \theta_t - \eta \nabla_{\theta} L$ η - шаг обновления
(маленькое число
 $\eta \ll 1$)
- 3) $?(|\nabla_{\theta} L| \leq \epsilon)$ Stop t - номер итерации
окончания

