Idea: Adaption of theory to networks with biases

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Abstract

1 Affine Transformations

Since our NN "somewhat" resembles linear functions following from the rule $\sigma(x) = \sigma'(x)x$ (i see this rule as separating the linear from the non-linear part), i am curious to see whether ideas of affine spaces and how to integrate them into linear-spaces translate.

I think they do.

2 Idea

Affine subspaces are usually define via $A = v + U_V$, where U_V is a subspace of V and v is a vector of V (see (german) wikipedia). But you can work in them using homogenous coordinates.

Every affine transformation can be turned into a linear transformation with a constant 1-input using the Augmented Matrix trick.

For example the intercept in linear models in statistics is often modeled this way.

We can adapt this trick with only one additional constant input using this matrix:

$$W' = \begin{bmatrix} w_{11} & w_{12} & w_{13} & \dots & w_{1n} & bias_1 \\ w_{21} & w_{22} & w_{23} & \dots & w_{2n} & bias_2 \\ \dots & \dots & \dots & \dots & \dots \\ w_{d1} & w_{d2} & w_{d3} & \dots & w_{dn} & bias_n \\ 0 & \dots & \dots & 0 & 1 \end{bmatrix} = \begin{bmatrix} W & & b \\ 0 & \dots & 0 & 1 \end{bmatrix}$$

the last line is the difference to the usual construction and should be ommitted in the last layer.

This results in:
$$f'_{\theta}(x) = f_{\theta'}(\begin{bmatrix} x \\ 1 \end{bmatrix})^1$$
,

where θ' is the parameter adpated in the above schema.

Usually proofs get a lot simple when you just have to wory about keeping one input constant. I think a lot of the proofs from the paper should still hold, for example Leamma 2.1 doesn't change. I hope the other proofs only need some tweaking here and there.

For this to work, we need to add the additional requirement that $\sigma(1) = 1$

1
 slight abuse of notation. We define $\begin{bmatrix} x \\ 1 \end{bmatrix} := \begin{bmatrix} x_1 \\ \vdots \\ x_n \\ 1 \end{bmatrix}$

3 Proof

In the following section, neural networks with biases as defined as:

$$f_{\theta}(x) = \sigma_{L+1}(\sigma_L(\dots \sigma_2(\sigma_1(xW^0 + b^0)W^1 + b^1)W^2 + b^2)\dots W^L + b^L)$$

We call b^i bias and additionally need the following constraint on the activation function σ_i :

$$\forall i \in L+1, \ldots, 1. \exists c_i.\sigma_i(c_i)=1$$

For f_{θ} with $\theta = (W^0, W^1, \dots, W^L)$ we define:

$$f_{0,\theta^0}(z) := \sigma_1(zW'^0)$$
, where $\theta^0 := (W'^0)$
 f_{L,θ^L} , so that
 $f_{\theta} = f_{L,\theta^L} \circ f_{0,\theta^0}$ and
 $\theta^L := (W^1, \dots, W^L)$

Definition 3.1. Homogenous Coordinates for Neural Networks

Let f_{θ} be a neural network with biases. Then augumented neural network $f_{\theta'}$ is a neural network as defined in Definition 1, (2.1) in [TODO: ref], where:

$$\theta' = (W'^0, \dots, W'^L)$$

and

$$W'^i = \begin{bmatrix} w^i_{11} & w^i_{12} & w^i_{13} & \dots & w^i_{1k_i} & b^i_1 \\ w^i_{21} & w^i_{22} & w^i_{23} & \dots & w^i_{2k_i} & b^i_2 \\ \dots & \dots & \dots & \dots & \dots & \dots \\ w^i_{k_{i+1}1} & w^i_{k_{i+1}2} & w^i_{k_{i+1}3} & \dots & w^i_{k_{i+1}k_i} & b^i_{k_{i+1}} \\ 0 & \dots & \dots & \dots & \dots & \dots & 0 & c_i \end{bmatrix} = : \begin{bmatrix} W^i & & b^i \\ 0 & \dots & 0 & c_i \end{bmatrix} \in \mathbb{R}^{k_i+1,k_{i+1}+1} \forall i \in \{0,\dots(L-1)\}$$

$$W'^i = \begin{bmatrix} w^i_{11} & w^i_{12} & w^i_{13} & \dots & w^i_{1k_i} & b^i_1 \\ w^i_{21} & w^i_{22} & w^i_{23} & \dots & w^i_{2k_i} & b^i_2 \\ \dots & \dots & \dots & \dots & \dots \\ w^i_{k_{i+1}1} & w^i_{k_{i+1}2} & w^i_{k_{i+1}3} & \dots & w^i_{k_{i+1}k_i} & b^i_{k_{i+1}} \end{bmatrix} =: \begin{bmatrix} W^i & b^i \end{bmatrix} \in \mathbb{R}^{k_i+1,K} \text{ with } i = L$$

Theorem 3.1. Equality of the augumented NN

For all NN with Bias f_{θ} :

$$f'_{\theta}(x) = f_{\theta'}(\begin{bmatrix} x \\ 1 \end{bmatrix})$$

Proof. via Induction over L.

1. For L = 0:

$$\Theta' = (W'^0) \tag{1}$$

$$W^{\prime 0} = \begin{bmatrix} W^0 & b^0 \end{bmatrix} \text{ because } 0 = L \tag{2}$$

$$f_{\theta'}(\begin{bmatrix} x \\ 1 \end{bmatrix}) = \sigma_1(\begin{bmatrix} x \\ 1 \end{bmatrix} W^{\prime 0}) \tag{3}$$

$$= \sigma_1 \begin{pmatrix} x \\ 1 \end{pmatrix} \begin{bmatrix} W^0 & b^0 \end{bmatrix}$$
 (4)

$$= \sigma_1(xW^0 + b^0) \tag{5}$$

$$= f_{\theta}(x) \tag{6}$$

2. For $L \to (L+1)$ holds Theorem 3.1

3. $L \to (L+1)$:

$$\theta' = (W'^0, W'^1, \dots, W'^(L+1)) \tag{7}$$

$$\theta' = (W'^{0}, W'^{1}, \dots, W'^{(L+1)})$$

$$W'^{0} = \begin{bmatrix} W^{0} & b^{0} \\ 0 & \dots & 0 & c_{0} \end{bmatrix} \text{ because } 0 \neq (L+1)$$
(8)

(9)

$$f_{0,\theta'^{0}}\left(\begin{bmatrix} x\\1 \end{bmatrix}\right) = \sigma_{1}\left(\begin{bmatrix} x\\1 \end{bmatrix}W'^{0}\right) \tag{10}$$

$$f_{0,\theta'^{0}}(\begin{bmatrix} x \\ 1 \end{bmatrix}) = \sigma_{1}(\begin{bmatrix} x \\ 1 \end{bmatrix} W'^{0})$$

$$= \begin{bmatrix} \sigma_{1}(\begin{bmatrix} x \\ 1 \end{bmatrix} \begin{bmatrix} W^{0} & b^{0} \end{bmatrix}) \end{bmatrix}$$

$$= \begin{bmatrix} f_{0,\theta^{0}}(x) \\ 1 \end{bmatrix}$$

$$(12)$$

$$= \begin{bmatrix} f_{0,\theta^0}(x) \\ 1 \end{bmatrix} \tag{12}$$

$$f_{\theta'}(\begin{bmatrix} x \\ 1 \end{bmatrix}) = (f_{L,\theta'L} \circ f_{0,\theta'^0})(\begin{bmatrix} x \\ 1 \end{bmatrix})$$
(13)

$$= f_{\theta'^L} \begin{pmatrix} f_{\theta^0}(x) \\ 1 \end{pmatrix}$$
 (14)

$$= (f_{L,\theta^L} \circ f_{0,\theta^0})(x) \tag{15}$$

$$= (f_{L,\theta^L} \circ f_{0,\theta^0})(x)$$

$$= f_{\theta}(x)$$

$$(15)$$

$$(16)$$

References