Cheatsheet for Fisher-Rao Metric, Geometry, and Complexity of Neural Networks

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Abstract

1 Geometry of Deep Rectified Networks

1.1 Lemma 2.1

Lemma 1.1 (Structure in Gradients).

$$\sum_{t=0}^{L} \sum_{i \in [k_t], j \in [k_{t+1}]} \frac{\partial O^{L+1}}{\partial W^{t_{ij}}} W_{ij}^t = (L+1)O^{L+1}(x) = \langle \nabla_{\theta} f_{\theta}(x), \theta \rangle$$
 (1)

1.1.1 Example for Lemma 2.1

Take a simple feed forward neural network with only two inputs and one output. Remember that by definition $O^0 = x$. Illustrated:

$$O^0$$
 O^1 x_1

 x_2 y_1

The simple example can then be written with:

$$O^{0} = \begin{bmatrix} O_{1}^{0} \\ O_{2}^{0} \end{bmatrix}, W^{0} = \begin{bmatrix} W_{1}^{0} \\ W_{2}^{0} \end{bmatrix}$$
 (2)

$$O^{1} = \sigma(O^{0T}W^{0}) = \sigma(\underbrace{O_{1}^{0}W_{1}^{0} + O_{2}^{0}W_{2}^{0}}_{z}).$$
(3)

Substituting the term in brackets will simplify notation.

Now calculate the partial derivatives of (2) with respect to W_i^0 .

$$\frac{\partial O^1}{\partial W_1^0} = \sigma'(z)O_1^0$$

$$\frac{\partial O^1}{\partial W_2^0} = \sigma'(z) O_2^0$$

Summing up the $\frac{\partial O^1}{\partial W_j}W_j$ reveals,

$$\begin{split} \sum_{j=1}^2 \frac{\partial O^1}{\partial W_j^0} W_j^0 &= \sigma'(z) O_1^0 W_1^0 + \sigma'(z) O_2^0 W_2^0 = \sigma'(z) (\underbrace{O_1^0 W_1^0 + O_2^0 W_2^0}_{\mathbf{z}}) \\ &= \sigma'(z) z \end{split}$$

Note that this is equivalent to calculating $\langle \nabla_{W^0} O^1, W^0 \rangle$:

$$\nabla_{W^0} O^1 = \begin{bmatrix} \frac{\partial O^1}{\partial W_1^0} \\ \frac{\partial O^1}{\partial W_2^0} \end{bmatrix}$$
$$\langle \nabla_{W^0} O^1, W^0 \rangle = \sum_{i=1}^2 \frac{\partial O^1}{\partial W_j^0} W_j^0 = \dots = \sigma'(z) z$$

Using the relation $\sigma(z) = \sigma'(z)(z)$ reveals (2). Then reading left to right reveals (1) for L = 0, $\theta = W^0$ and $f_{\theta}(x) = O^1(x)$ which completes the example.

$$\sum_{t=0}^{L=0} \sum_{j=1}^{2} \frac{\partial O^1}{\partial W_j^t} W_j^t = \langle \nabla_{W^0} O^1, W^0 \rangle = \sigma'(z)z = \sigma(z) = O^1$$

1.2 Corollary 2.1

1.2.1 Notes

1. Proof. We want to show $\frac{\partial l(f,Y)}{\partial f} = -y \Leftrightarrow yf < 1$. So,

$$1 - y_i f_i > 0$$

$$\Leftrightarrow \qquad l = 1 - y_i f_i$$

$$\Leftrightarrow \qquad \frac{\partial l}{\partial f} = -y_i$$

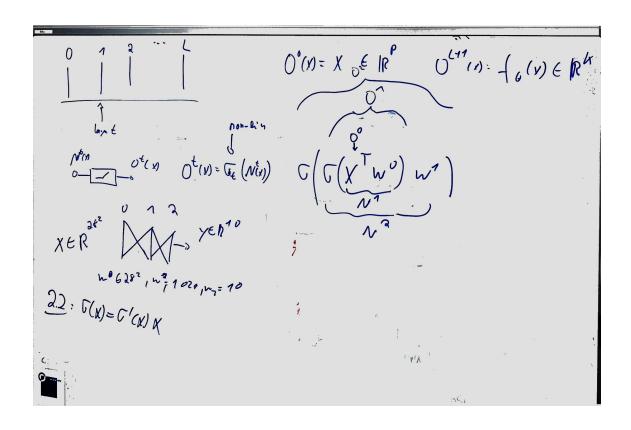
2. Proof. We want to show $\frac{\partial l(f,Y)}{\partial f} = 0 \Leftrightarrow yf > 1$. So,

$$1 - y_i f_i < 0$$

$$\Leftrightarrow \qquad l = 0$$

$$\Leftrightarrow \qquad \frac{\partial l}{\partial f} = 0$$

References



$$\frac{P.S}{P.GOL} = \frac{1}{N} \sum_{i=1}^{N} l\left(l_{G}(x_{i})_{i} Y_{i}\right)$$

$$= \frac{1}{N} \sum_{i=1}^{N} l\left(l_{G}(x_{i})_{i} Y_{i}\right)$$

$$= \frac{1}{N} \sum_{i=1}^{N} l\left(l_{G}(x_{i})_{i} Y_{i}\right) \left(l_{G}(x_{i})_{i} Y_{i}\right) \left(l_{G}(x_{i})_{i} Y_{i}\right)$$

$$= \frac{1}{N} \sum_{i=1}^{N} l\left(l_{G}(x_{i})_{i} Y_{i}\right) \left(l_{G}(x_{i})_{i} Y_{i}\right) \left(l_{G}(x_{i})_{i} Y_{i}\right)$$

$$= \frac{1}{N} \sum_{i=1}^{N} l\left(l_{G}(x_{i})_{i} Y_{i}\right) \left(l_{G}(x_{i})_{i} Y_{i}\right) \left(l_{G}(x_{i})\right)$$

$$= \frac{1}{N} \sum_{i=1}^{N} l\left(l_{G}(x_{i})_{i} Y_{i}\right) \left(l_{G}(x_{i})\right) \left(l_{G}(x_{i})\right)$$

$$= \left(l_{G}(x_{i}) \sum_{i=1}^{N} l_{G}(x_{i}) \left(l_{G}(x_{i})_{i} Y_{i}\right) l_{G}(x_{i})\right)$$

$$= \left(l_{G}(x_{i}) \sum_{i=1}^{N} l_{G}(x_{i}) l_{G}(x_{i}) l_{G}(x_{i})\right)$$

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$$(3.1) \quad ||Q||^{2} = (0, I(0)0), \quad Ton \theta: I[min min] for inth I(0) = \mathbb{E} \left[\nabla_{0} ((f_{0}(x), y), \otimes) \right]$$

$$= (0, \nabla_{0}(f_{0}(x)))^{2} = (0, \nabla_{0}(f_{0}(x))) \cdot (0, \nabla_{0}(f_{0}(x))) \cdot$$

$$| (3,1) | | (0)|^{2} = \langle (0, I(0)) \rangle, \qquad | (0, I(0))|^{2} = \langle (0, I(0)) \rangle, \qquad | (0, I(0))|^{2} = \langle (0, I(0)) \rangle, \qquad | (0, I(0))|^{2} = \langle (0, I(0)) \rangle, \qquad | (0, I(0))|^{2} = \langle (0, I(0)) \rangle, \qquad | (0, I$$

Es wor:
$$(0 | f_{\theta}(x), 0) = (1+1) | f_{\theta}(x) = (1+1) | f_{\theta}(x)$$

$$E[(\frac{\partial e}{\partial f_{\theta}(x,y)}) | (1+1) | f_{\theta}(x) |^{3}]$$

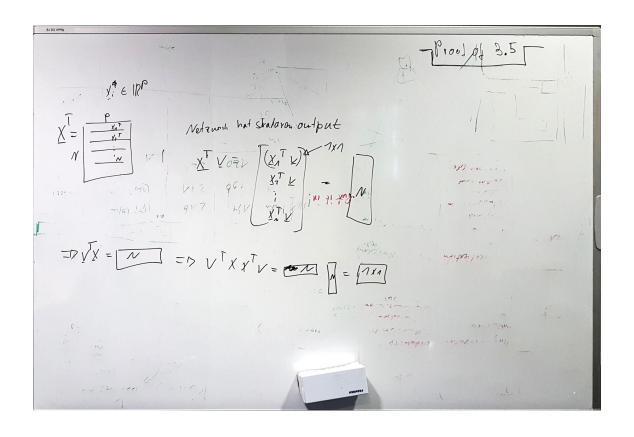
$$= (1+1)^{2} [-\frac{\partial e}{\partial f_{\theta}(x,y)} | f_{\theta}(x) |^{3}] = ||G||_{1}^{2}$$

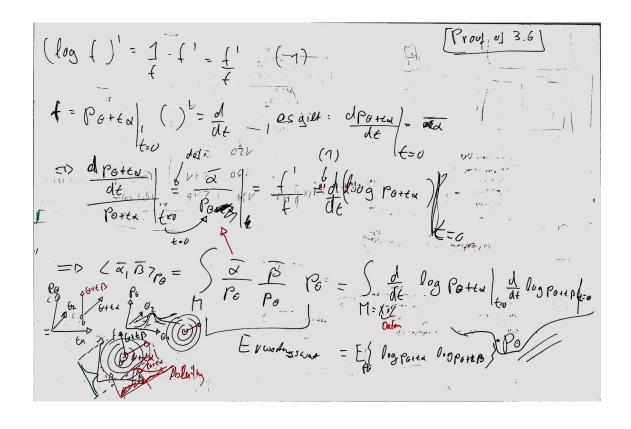
$$|f_{\theta}(x) - y|_{2}^{2} | f_{\theta}(x) |^{2}$$

$$|f_{$$

$$O(z) = O'(z) z \qquad z = [N_1]$$

$$O'(N_1) M_1 \qquad z = [O(N_1)] M_2 \qquad O'(N_1) M_2 \qquad O'(N_2) M_2 \qquad O'(N_1) M_2 \qquad O'(N_2) M_2 \qquad O'(N_2)$$





$$C(G(x^{\dagger}w^{\circ})w^{2})$$

$$([+1)^{2}E[(\frac{\partial f_{e}}{\partial f_{e}})^{2}]$$

$$= |f_{e}(x)|^{2} - |f_{e}(x)|^{2}$$

$$= |f_{e}(x)|^{2} + |f_{e}(x)|^{2}$$

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$$C(x,y) = C$$

