Cheatsheet for Fisher-Rao Metric, Geometry, and Complexity of Neural Networks

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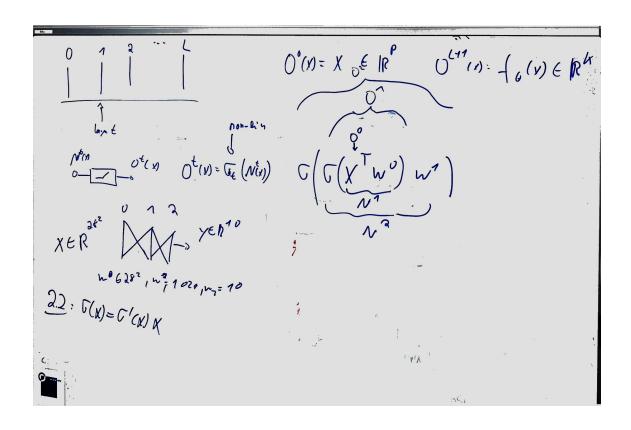
Abstract

1 Geometry of Deep Rectified Networks

Lemma 2.1 (Structure in Gradient)

$$\sum_{t=0}^{L} \sum_{i \in [k_t], j \in [k_{t+1}]} \frac{\partial O^{L+1}}{\partial W^{t_{ij}}} W_{ij}^t = (L+1)O^{L+1}(x) = \langle \nabla_{\theta} f_{\theta}(x), \theta \rangle$$
 (1)

References



$$\frac{P.S}{P.GOL} = \frac{1}{N} \sum_{i=1}^{N} l\left(l_{G}(x_{i})_{i} Y_{i}\right)$$

$$= \frac{1}{N} \sum_{i=1}^{N} l\left(l_{G}(x_{i})_{i} Y_{i}\right) \left(l_{G}(x_{i})_{i} Y_{i}\right) \left(l_{G}(x_{i})_{i} Y_{i}\right) \left(l_{G}(x_{i})_{i} Y_{i}\right) \left(l_{G}(x_{i})_{i} Y_{i}\right)$$

$$= \frac{1}{N} \sum_{i=1}^{N} l\left(l_{G}(x_{i})_{i} Y_{i}\right) \left(l_{G}(x_{i})_{i} Y_{i}\right) \left(l_{G}(x_{i})_{i} Y_{i}\right) \left(l_{G}(x_{i})_{i} Y_{i}\right)$$

$$= \frac{1}{N} \sum_{i=1}^{N} l\left(l_{G}(x_{i})_{i} Y_{i}\right) \left(l_{G}(x_{i})_{i} Y_{i}\right) \left(l_{G}(x_{i})_{i} Y_{i}\right)$$

$$= \left(l_{G}(x_{i}) \sum_{i=1}^{N} l_{G}(x_{i})_{i} Y_{i}\right) \left(l_{G}(x_{i}) \sum_{i=1}^{N} l_{G}(x_{i})_{i} Y_{i}\right)$$

$$= \left(l_{G}(x_{i}) \sum_{i=1}^{N} l_{G}(x_{i})_{i} Y_{i}\right) \left(l_{G}(x_{i})_{i} Y_{i}\right) \left(l_{G}(x_{i})_{i} Y_{i}\right)$$

$$= \left(l_{G}(x_{i}) \sum_{i=1}^{N} l_{G}(x_{i})_{i} Y_{i}\right) \left(l_{G}(x_{i})_{i} Y_{i}\right) \left(l_{G}(x_{i})_{i} Y_{i}\right) \left(l_{G}(x_{i})_{i} Y_{i}\right) \left(l_{G}(x_{i})_{i} Y_{i}\right)$$

$$= \left(l_{G}(x_{i}) \sum_{i=1}^{N} l_{G}(x_{i})_{i} Y_{i}\right) \left(l_{G}(x_{i})_{i} Y_{i}\right) \left(l_{G}(x$$

$$P.S \Rightarrow P(0) = 1 \times \frac{N}{N} \left(\left(\frac{1}{N} \left(\frac{1}{N} \right) \right) \right)$$

$$= \frac{1}{N} \sum_{i=1}^{N} \left(\left(\frac{1}{N} \left(\frac{1}{N} \right) \right) \right) \left(\frac{1}{N} \left(\frac{1}{N} \left(\frac{1}{N} \right) \right) \left(\frac{1}{N} \left(\frac{1}{N} \left(\frac{1}{N} \right) \right) \left(\frac{1}{N} \left(\frac{1}{N} \right) \right) \left(\frac{1}{N} \left(\frac{1}{N} \right) \right) \left(\frac{1}{N} \left(\frac{1}{N} \left(\frac{1}{N} \left(\frac{1}{N} \right) \right) \left(\frac{1}{N} \left(\frac{1}{N} \left(\frac{1}{N} \right) \right) \left(\frac{1}{N} \left(\frac{1}{N} \left(\frac{1}{N} \left(\frac{1}{N} \right) \right) \left(\frac{1}{N} \left(\frac{1}{N}$$

$$| (3,1) | | (0)|^{2} = \langle (0, I(0)) \rangle, \qquad | (0, I(0))|^{2} = \langle (0, I(0)) \rangle, \qquad | (0, I(0))|^{2} = \langle (0, I(0)) \rangle, \qquad | (0, I(0))|^{2} = \langle (0, I(0)) \rangle, \qquad | (0, I(0))|^{2} = \langle (0, I(0)) \rangle, \qquad | (0, I$$

Es wor:
$$(0 | f_{\theta}(x), 0) = (1+1) | f_{\theta}(x) = (1+1) | f_{\theta}(x)$$

$$E[(\frac{\partial e}{\partial f_{\theta}(x,y)}) | (1+1) | f_{\theta}(x) |^{3}]$$

$$= (1+1)^{2} [-\frac{\partial e}{\partial f_{\theta}(x,y)} | f_{\theta}(x) |^{3}] = ||G||_{1}^{2}$$

$$|f_{\theta}(x) - y|_{2}^{2} | f_{\theta}(x) |^{2}$$

$$|f_{$$

$$O(z) = O'(z) z \qquad z = [N_1]$$

$$O(\sqrt{N_1}) M_1$$

$$O(\sqrt{N_2}) M_2$$

$$O(\sqrt{N_2}) M_2$$

$$O(\sqrt{N_2}) M_3$$

$$O(\sqrt{N_2}) M_4$$

$$O(\sqrt{N_2}) M_2$$

$$O(\sqrt{N_2}) M_3$$

$$O(\sqrt{N_2}) M_4$$

