

Introduction to Stationary Time Series

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- Messy
- Important

What makes time series different?

- The goal is the same: Model outcomes from an underlying data generating process. However...

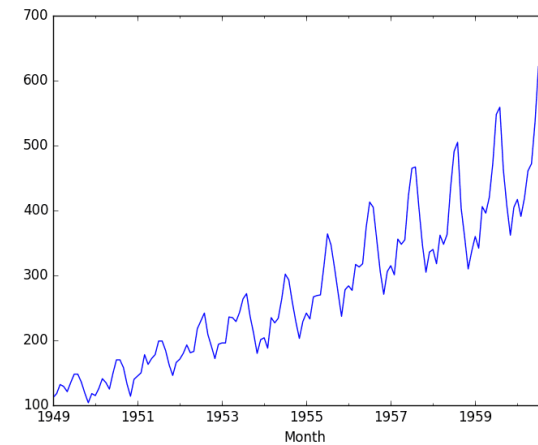
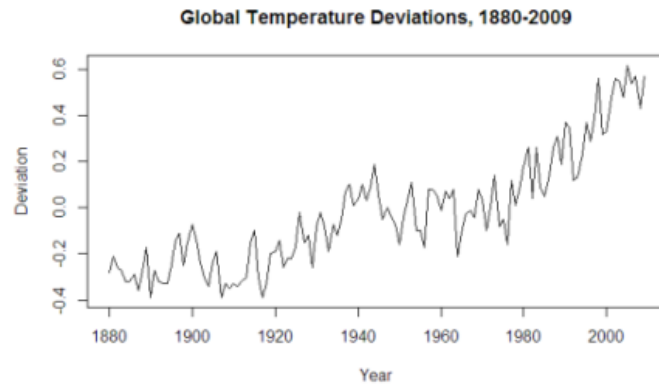
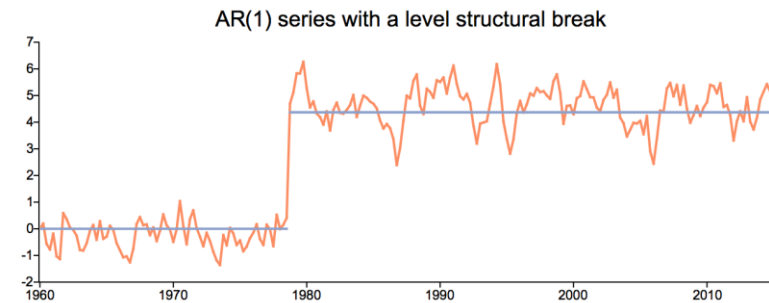
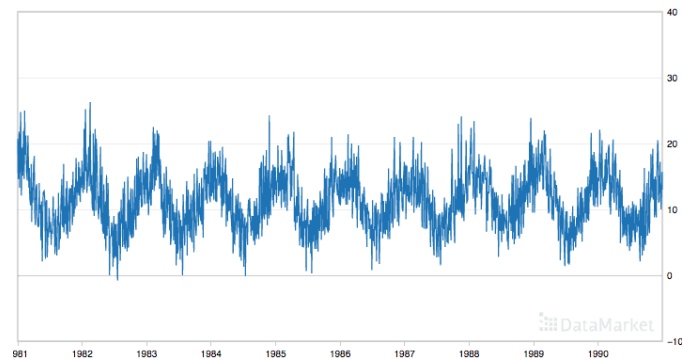
What makes time series different?

- The goal is the same: Model outcomes from an underlying data generating process. However...
- OLS assumes independent random variables
 - $E(\varepsilon | X) = 0$ (The expected value of the error term given our regressors is zero)
 - Also known as “strict exogeneity”

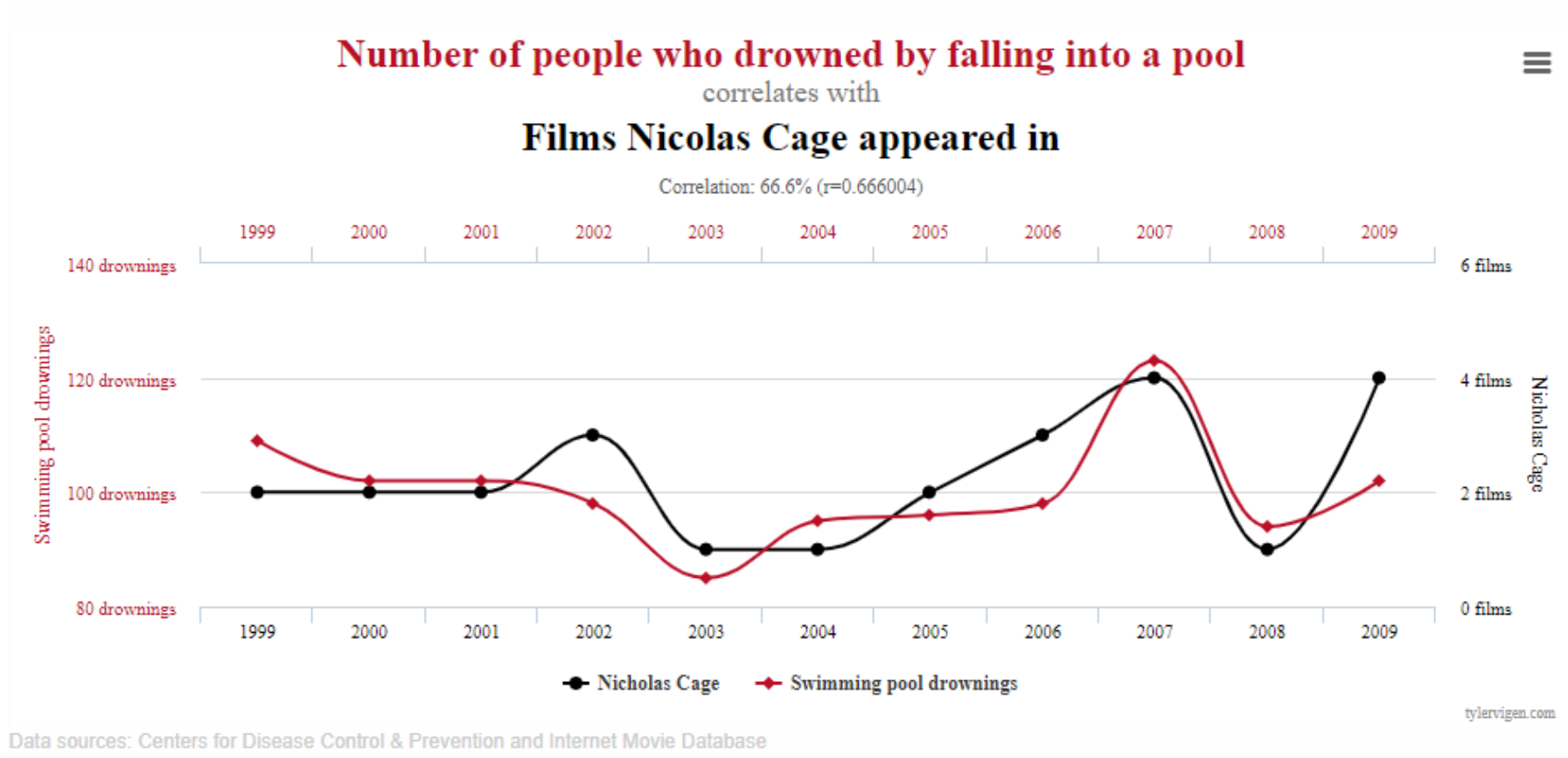
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- OLS assumes independent random variables
 - $E(\varepsilon | X) = 0$ (The expected value of the error term given our regressors is zero)
 - Also known as “strict exogeneity”
- Time series data usually violates this assumption because y_t is a function of y_{t-1} , thus OLS is no longer BLUE.
 - If y_t is a function of y_{t-1} , then the errors compound over time and the expected value of the error term is no longer zero.
 - $y_t = y_{t-1} + X_t + \varepsilon_t$
 - $y_{t-1} = y_{t-2} + X_{t-1} + \varepsilon_{t-1}$
- As a result, time series must model system dynamics

System Dynamics



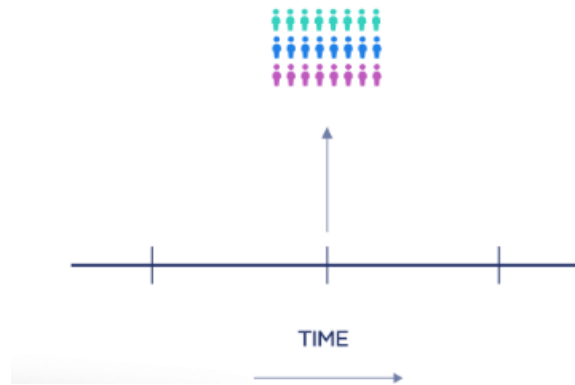
Spurious correlations



Key Concepts and Nomenclature

Types of Data

Cross Sectional

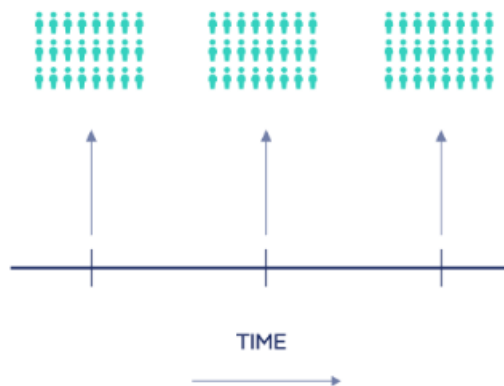


Types of Data

Cross Sectional

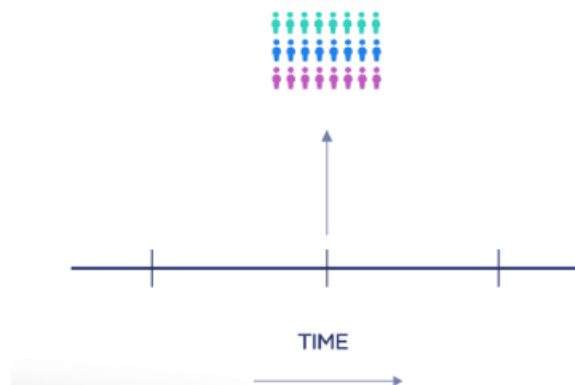


Time Series

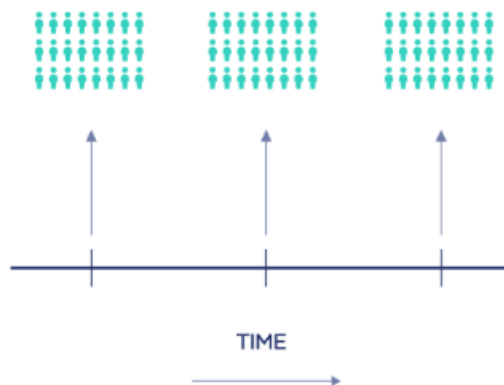


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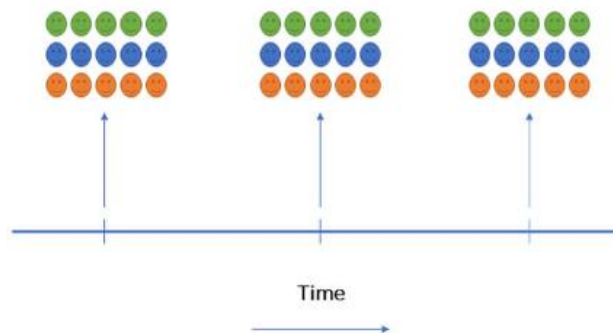
Cross Sectional



Time Series



Panel

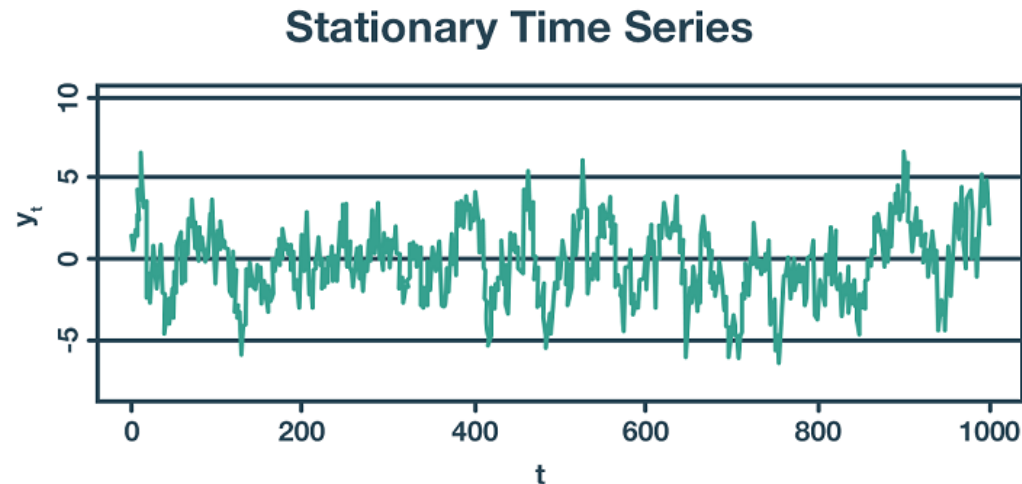


Sample window and interval

- Window: The total period of time over which your data are collected
- Interval: The discrete period of time you use to measure your data (e.g. hours, days, years)

Stationarity

- A time series is *covariance stationary* if its mean and variance are independent of time and its covariances are finite and depend only on the number of periods separating observations
 - $\mu_t = \mu_{t-s}$ or $E(y_t) = E(y_{t-s})$
 - $V(y_t) = V(y_{t-s})$
 - $\text{cov}(y_t, y_{t-s}) = \text{cov}(y_{t-j}, y_{t-j-s})$



Autocorrelation

- The dependence between observations of the same time series observed at different points in time.
- Formally, the autocorrelation coefficient is:
 - $\rho_s = \text{cov}(y_t, y_{t-s}) / V(y_t)$

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 - $\rho_s = \text{cov}(y_t, y_{t-s}) / V(y_t)$
- Autocorrelation is just a bivariate regression coefficient!
 - $\hat{\beta}_x = \text{cov}(y_i, x_i) / V(x_i)$

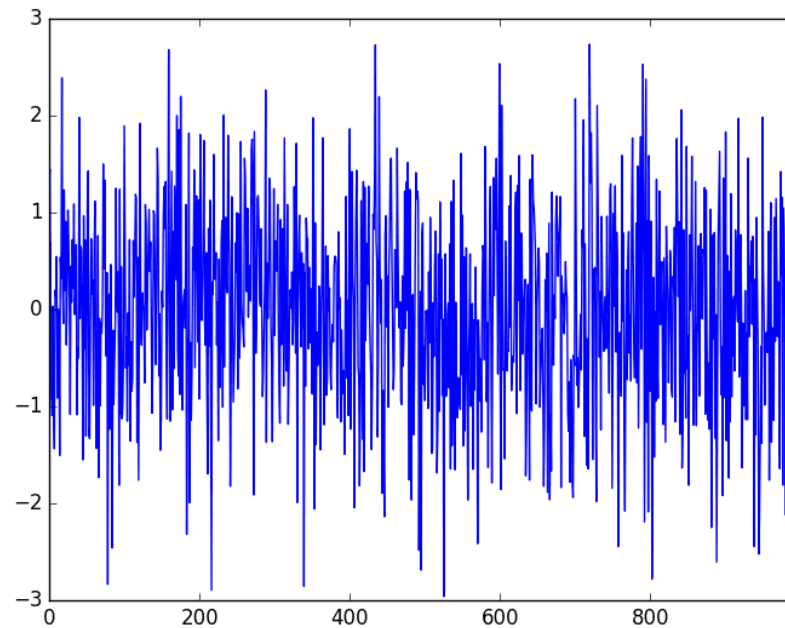


Partial autocorrelation

- The correlation between y_t and y_{t-s} after controlling for the intervening lags.
- If autocorrelation is a slope coefficient in a bivariate regression, partial autocorrelation is a slope coefficient in a multiple regression.
- Generally represented as φ (fi)

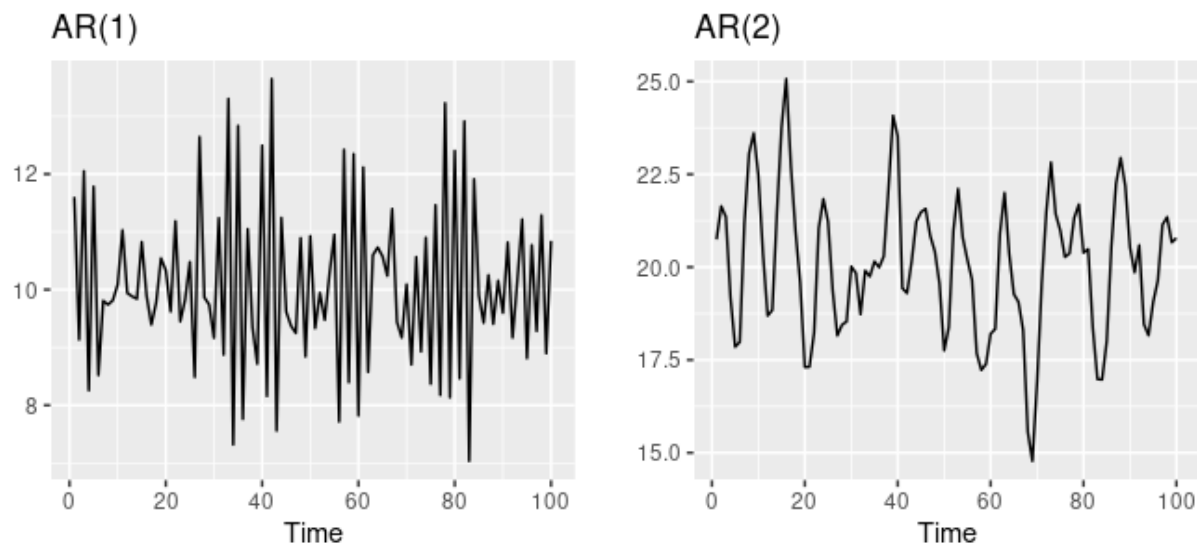
White noise process

- No predictable pattern over time
 - $E(y_t) = E(\varepsilon_t)$
 - Mean of zero
 - Constant variance
 - All covariances equal zero



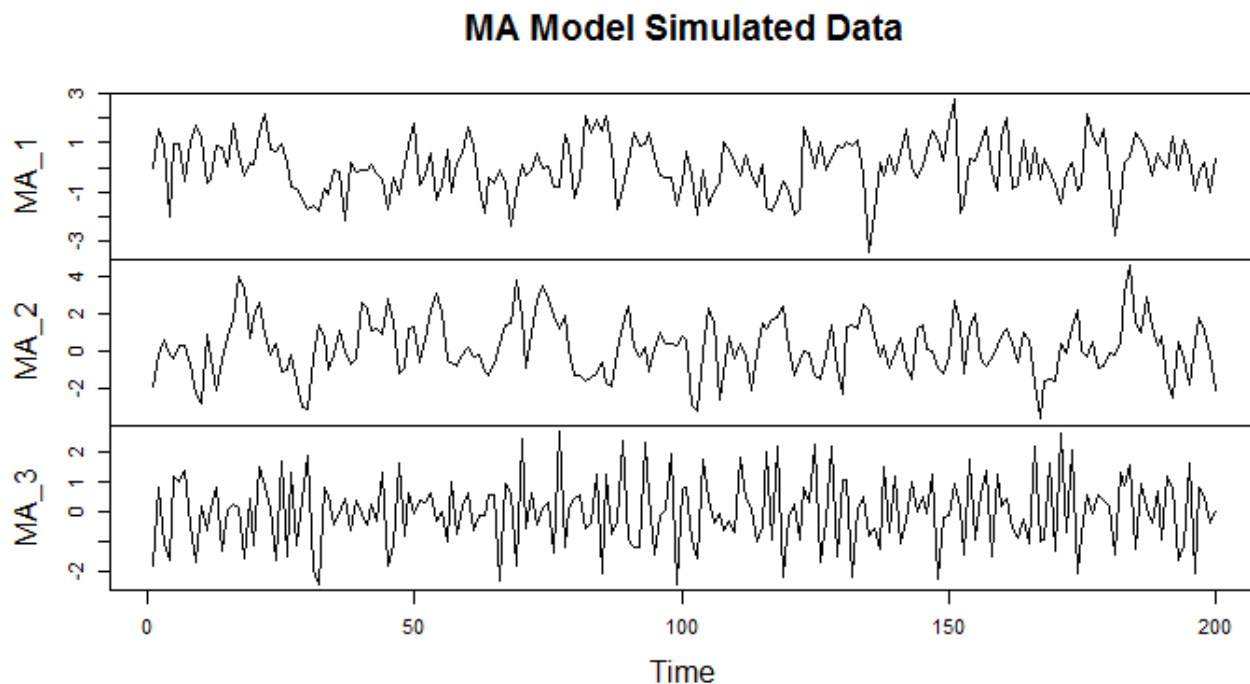
Autoregressive process (AR)

- A process in which the current value of y_t is a function of previous values of y_t
- $y_t = c + \varphi y_{t-1} + \varepsilon_t$
- $y_{t-1} = c + \varphi y_{t-2} + \varepsilon_{t-1}$
- Useful to think of AR as inertia in the process regressing back to its mean.



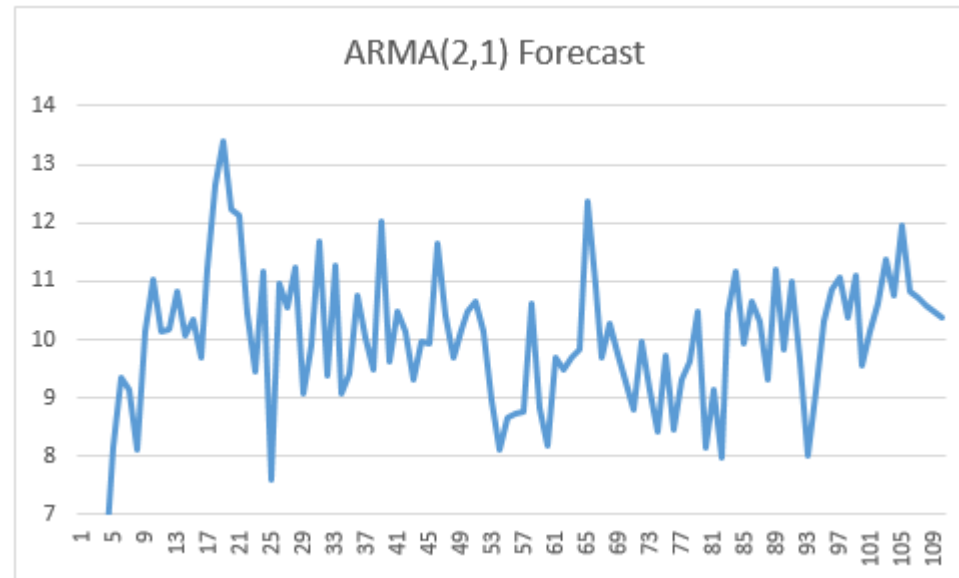
Moving average process (MA)

- The current values of y_t is a function of past values of the error term. The data generating process for y_{t+1} adjusts in response to ε_t
- Example: Polling accuracy



Autoregressive moving average process (ARMA)

- A process that has both AR and MA components.
- Example: Budgets.
 - AR: Start with previous years budget and then adjust
 - MA: Additional adjustments for unexpected windfalls and shortfalls



Seasonality

- Regular patterns that repeat over some number of time periods s .

