

# CSC 225 - Summer 2019

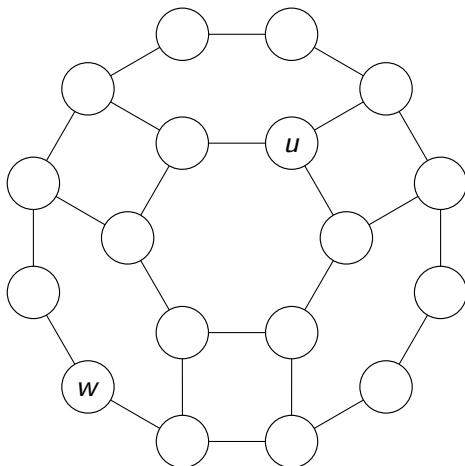
## Traversals I

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University of Victoria

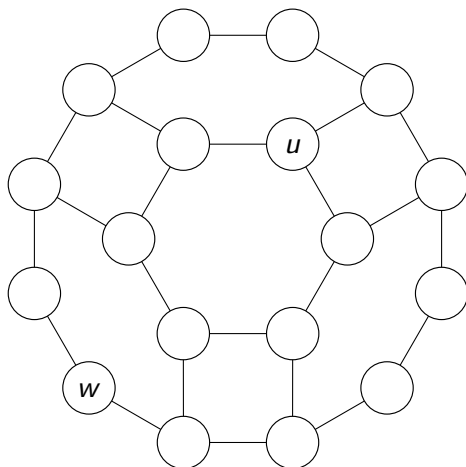
July 17, 2019

# Path Finding (1)



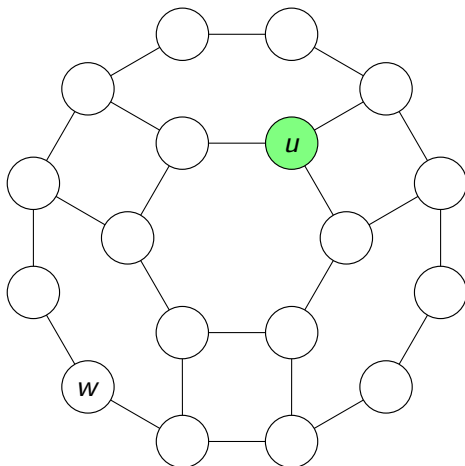
**Problem:** Design an algorithm to find a path from  $u$  to  $w$  in the graph above.

## Path Finding (2)



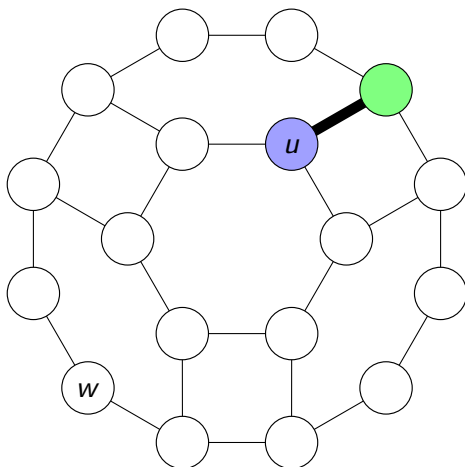
Although it is clear to a human observer how to reach  $w$  from  $u$ , there is no information in the graph itself besides the neighbours of each vertex.

## Path Finding (3)



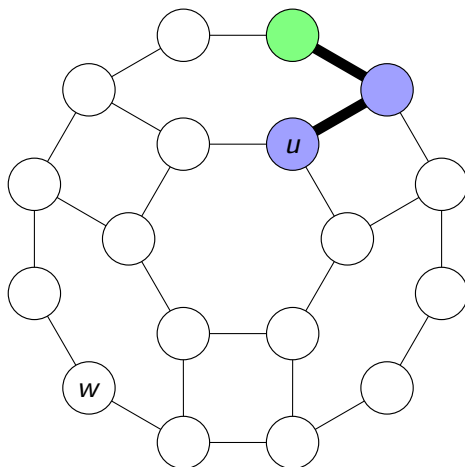
**Idea:** Start at  $u$ , pick a direction and start walking.

## Path Finding (4)



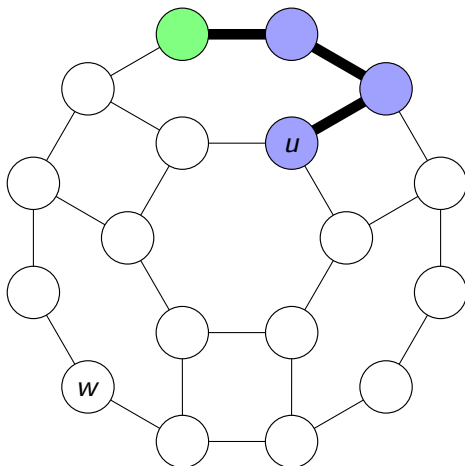
After arriving at a neighbour of  $u$ , mark  $u$  as 'visited' and keep track of the edge used.

## Path Finding (5)



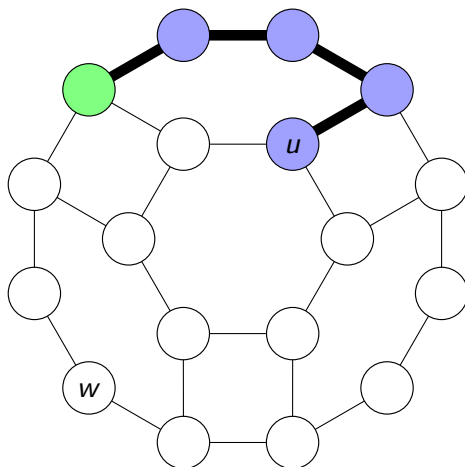
Continue walking through the graph, picking an unvisited vertex (white) at each step, and marking all visited vertices (blue).

## Path Finding (6)



Continue walking through the graph, picking an unvisited vertex (white) at each step, and marking all visited vertices (blue).

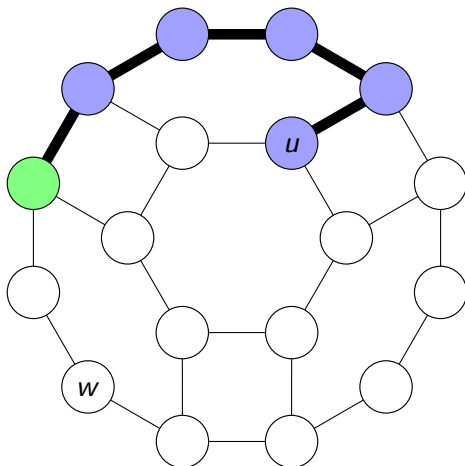
## Path Finding (7)



Continue walking through the graph, picking an unvisited vertex (white) at each step, and marking all visited vertices (blue).

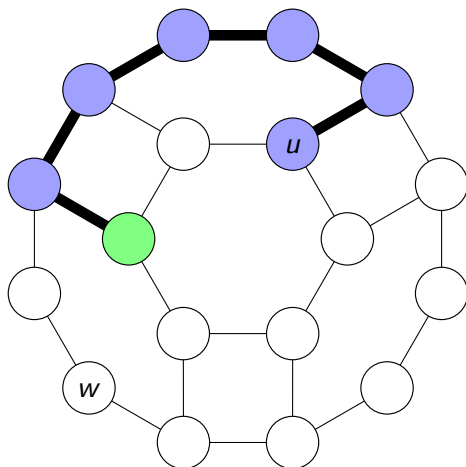


## Path Finding (8)



Continue walking through the graph, picking an unvisited vertex (white) at each step, and marking all visited vertices (blue).

## Path Finding (9)



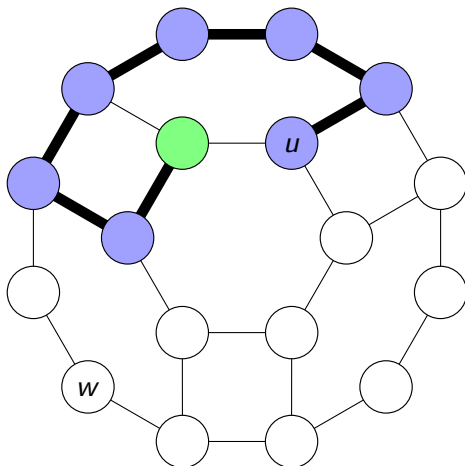
Continue walking through the graph, picking an unvisited vertex (white) at each step, and marking all visited vertices (blue).

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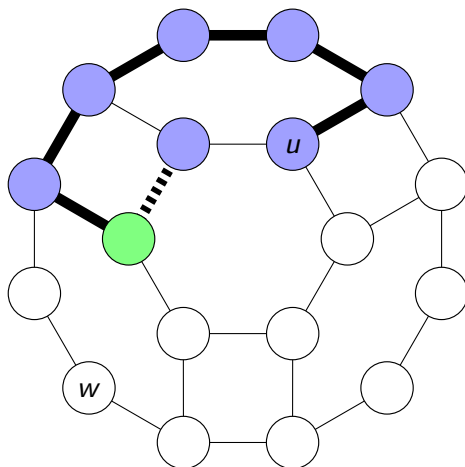
At this point, there are no unvisited vertices neighbouring the current vertex.

## Path Finding (11)



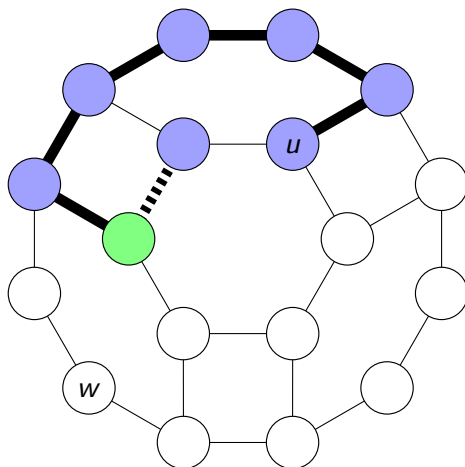
It is impossible to continue without either visiting an already-visited neighbour or doubling back.

## Path Finding (12)



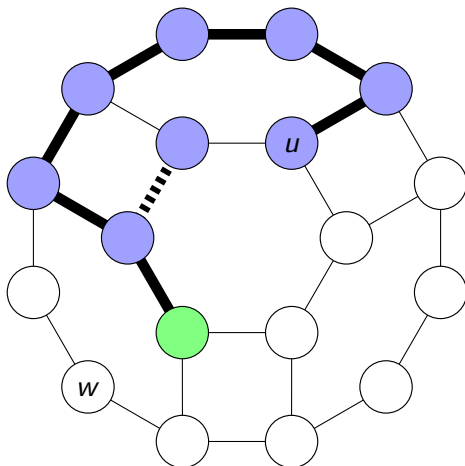
Since the path reached a dead end, double back and ignore the edge used (but leave the vertex marked as visited).

## Path Finding (13)

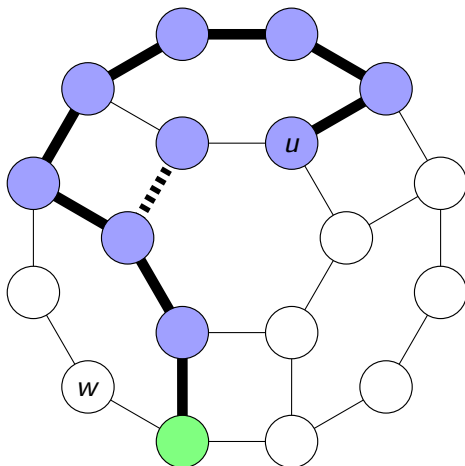


After backing up to the last vertex with an unvisited neighbour, continue walking.

## Path Finding (14)

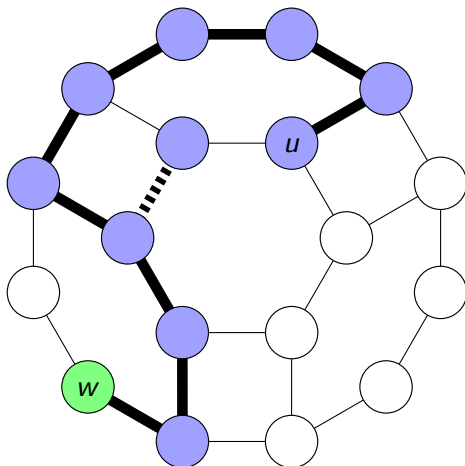


## Path Finding (15)



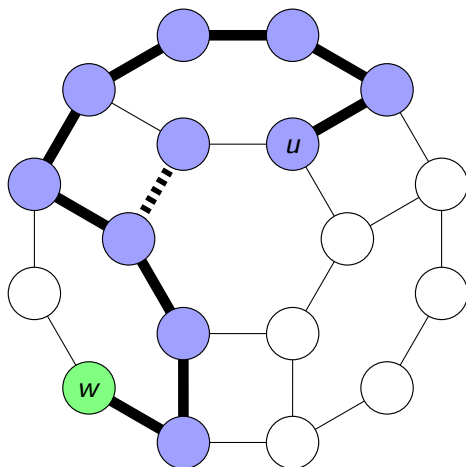


## Path Finding (16)



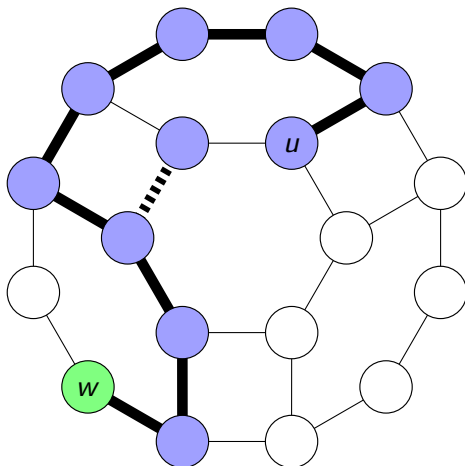
When  $w$  is reached, the set of edges followed during the walk (darkened in the diagram) is a path from  $u$  to  $w$ .

## Path Finding (17)



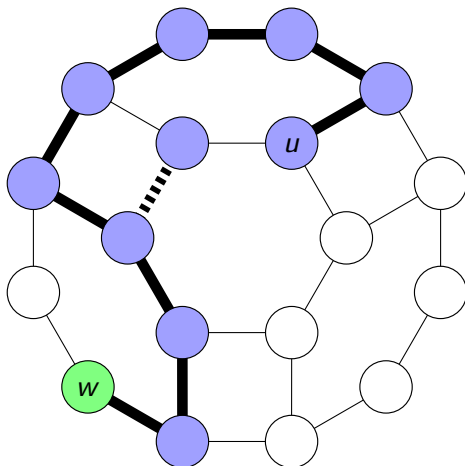
Observe that the resulting path is not the most direct route.

## Path Finding (18)



Algorithms which explore a graph by walking along edges are called **graph traversals**.

## Path Finding (19)



The 'pick a direction and start walking' approach corresponds to an algorithm called **Depth First Search** (or DFS).

## Path Finding (20)

```
1: procedure PATHDFS( $v, w, \text{PathStack}$ )
2:   if  $v$  is marked as visited then
3:     return
4:   end if
5:   Mark  $v$  as visited
6:   Push  $v$  onto PathStack
7:   if  $v = w$  then
8:     Output the contents of PathStack
9:     return
10:  end if
11:  for each neighbour  $q$  of  $v$  do
12:    PATHDFS( $q, w, \text{PathStack}$ )
13:  end for
14:  Pop PathStack
15: end procedure
```

The pseudocode above describes the algorithm in the example.

## Path Finding (21)

```
1: procedure PATHDFS( $v, w, \text{PathStack}$ )
2:   if  $v$  is marked as visited then
3:     return
4:   end if
5:   Mark  $v$  as visited
6:   Push  $v$  onto PathStack
7:   if  $v = w$  then
8:     Output the contents of PathStack
9:     return
10:  end if
11:  for each neighbour  $q$  of  $v$  do
12:    PATHDFS( $q, w, \text{PathStack}$ )
13:  end for
14:  Pop PathStack
15: end procedure
```

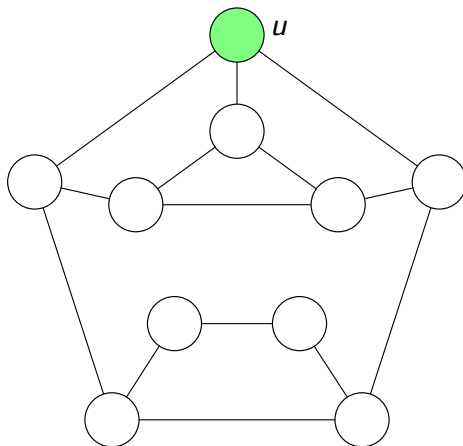
To find a  $u$ - $w$  path, the initial call is PATHDFS( $u, w, \text{PathStack}$ ), where PathStack is an empty stack.

## Path Finding (22)

```
1: procedure PATHDFS( $v, w, \text{PathStack}$ )
2:   if  $v$  is marked as visited then
3:     return
4:   end if
5:   Mark  $v$  as visited
6:   Push  $v$  onto PathStack
7:   if  $v = w$  then
8:     Output the contents of PathStack
9:     return
10:  end if
11:  for each neighbour  $q$  of  $v$  do
12:    PATHDFS( $q, w, \text{PathStack}$ )
13:  end for
14:  Pop PathStack
15: end procedure
```

When the traversal reaches vertex  $w$ , the contents of PathStack will be the set of vertices in a  $u$ - $w$  path.

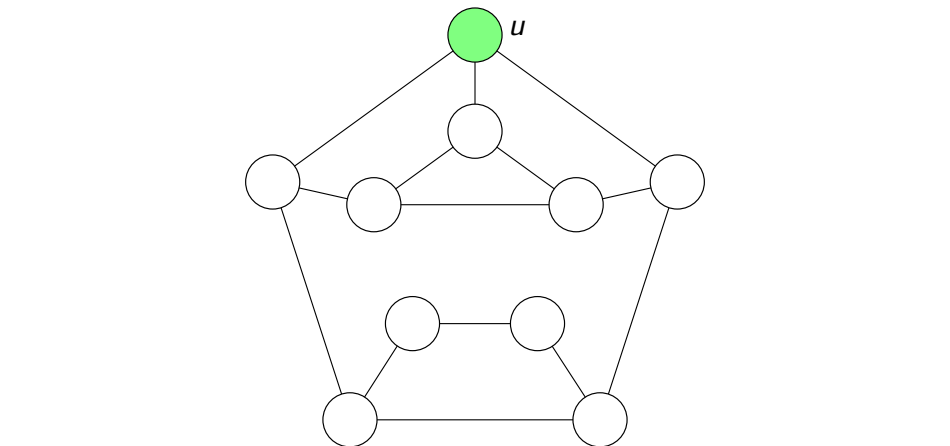
# Depth-First Search (1)



The path finding algorithm in the previous example was a special case of Depth-First Search (DFS).

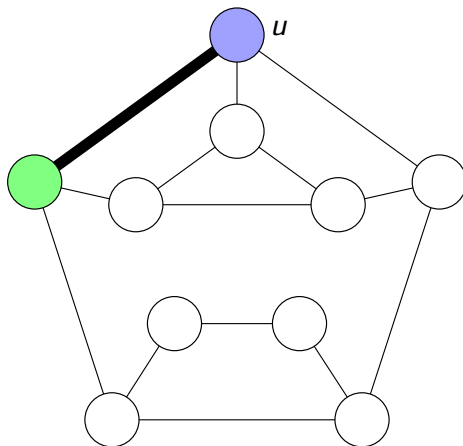


## Depth-First Search (2)



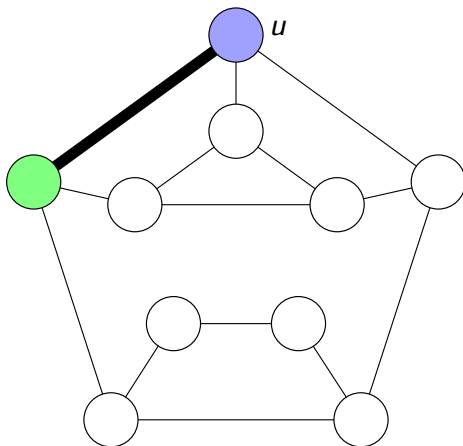
The general DFS algorithm starts at a vertex  $u$  and visits every vertex reachable from  $u$ .

## Depth-First Search (3)



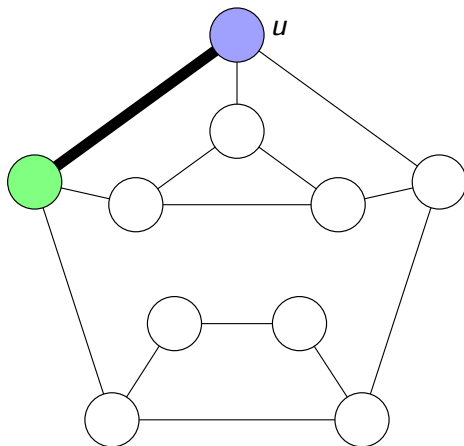
At each step, a neighbour of the current vertex is chosen to be the next vertex visited.

## Depth-First Search (4)



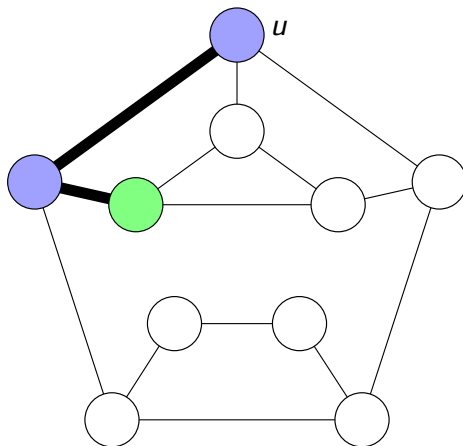
The edge (darkened) followed to reach the next vertex becomes part of the **DFS tree**.

## Depth-First Search (5)



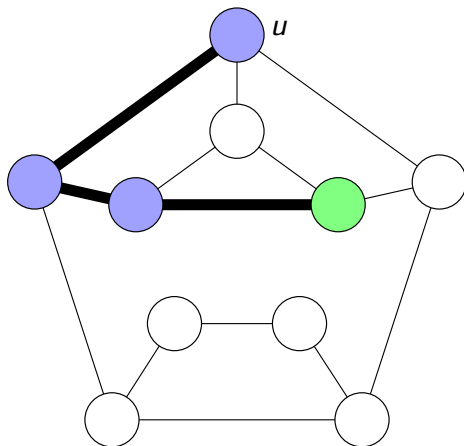
The root of a DFS tree is the initial starting vertex  $u$ .

## Depth-First Search (6)

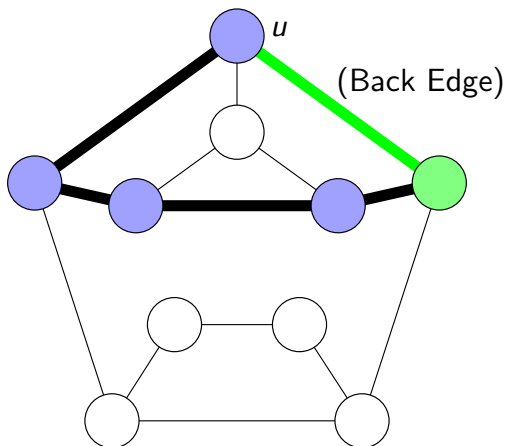


Edges in the DFS tree may be called **tree edges** or **discovery edges**.

## Depth-First Search (7)

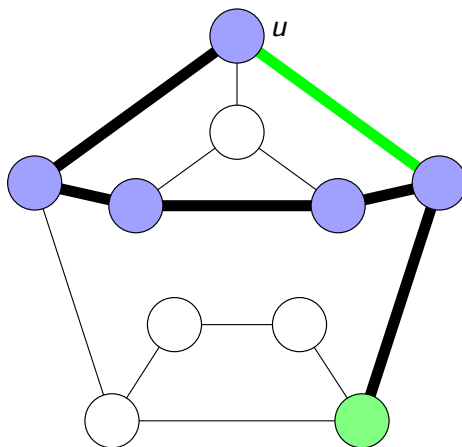


## Depth-First Search (8)



The green edge in the diagram cannot be followed by DFS, since it is connected to a previously visited vertex. Such edges are called **back edges**.

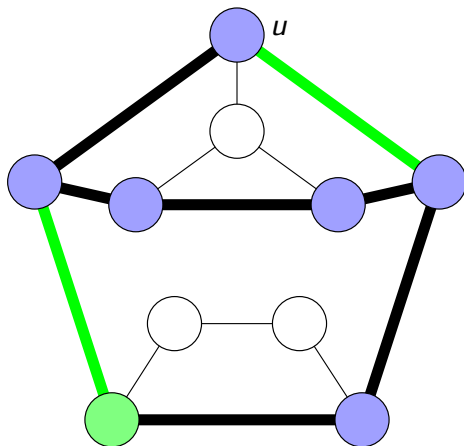
## Depth-First Search (9)



**Exercise:** Show that if a back edge exists, the graph must contain a cycle.



# Depth-First Search (10)

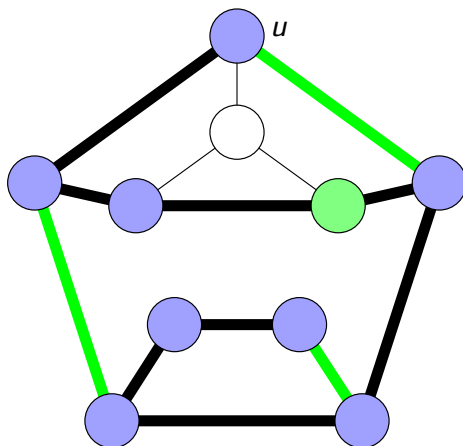


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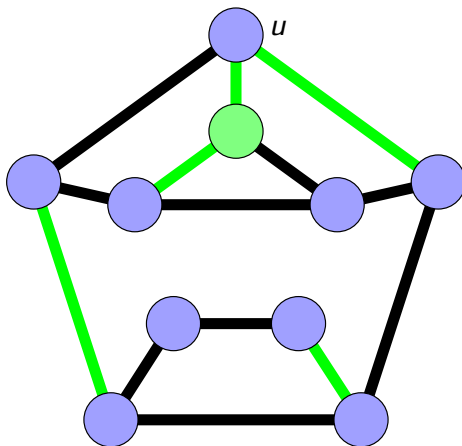


## Depth-First Search (13)



Recursion unwinds to the last vertex with unvisited neighbours and the traversal continues from there.

## Depth-First Search (14)



A DFS tree is a spanning tree of the connected component containing the starting vertex  $u$ .

## Depth-First Search (15)

```
1: procedure DFS( $v$ )
2:   Mark  $v$  as visited
3:   //Visit  $v$  (pre-order)
4:   for each neighbour  $w$  of  $v$  do
5:     if  $w$  has not already been visited then
6:       //( $v, w$ ) is a discovery edge
7:       //Recursively traverse  $w$ 
8:       DFS( $w$ )
9:     else
10:      //( $v, w$ ) is a back edge
11:    end if
12:  end for
13:  //Visit  $v$  (post-order)
14: end procedure
```

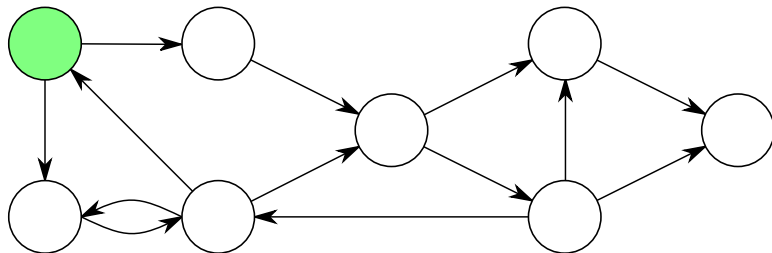
The pseudocode above gives the general structure of DFS.

## Depth-First Search (16)

```
1: procedure DFS( $v$ )
2:   Mark  $v$  as visited
3:   //Visit  $v$  (pre-order)
4:   for each neighbour  $w$  of  $v$  do
5:     if  $w$  has not already been visited then
6:       //( $v, w$ ) is a discovery edge
7:       //Recursively traverse  $w$ 
8:       DFS( $w$ )
9:     else
10:      //( $v, w$ ) is a back edge
11:    end if
12:  end for
13:  //Visit  $v$  (post-order)
14: end procedure
```

Depending on the application, some aspects (such as the status of edges) may be irrelevant.

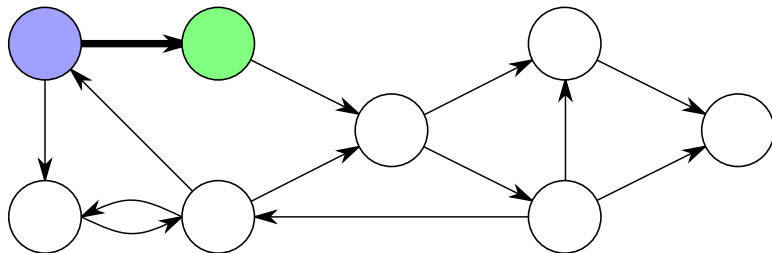
# DFS on Directed Graphs (1)



DFS has a natural generalization to directed graphs. The main difference is that the directions of edges must be respected.

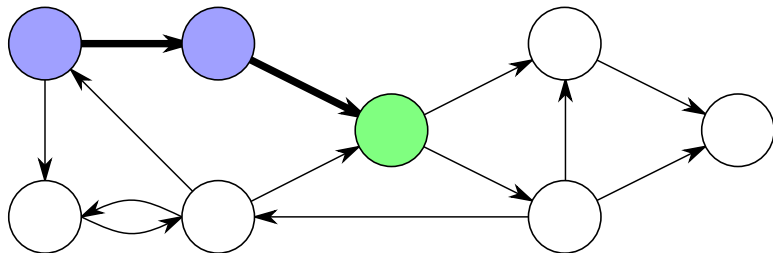


## DFS on Directed Graphs (2)



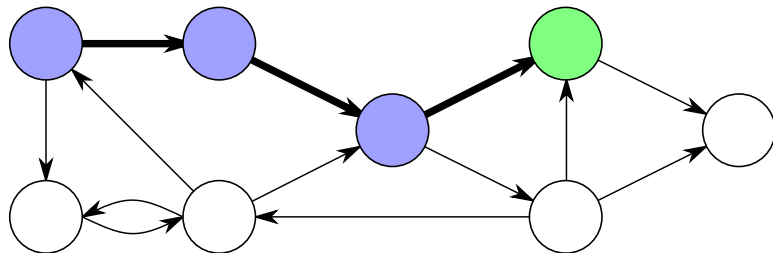
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## DFS on Directed Graphs (3)



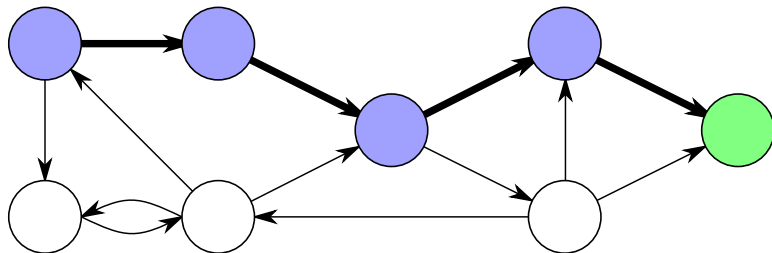
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## DFS on Directed Graphs (4)



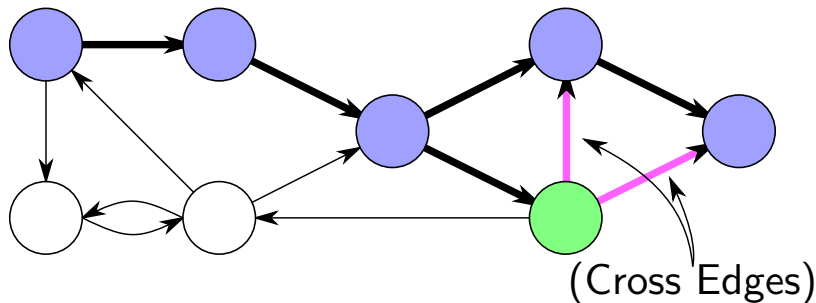
DFS has a natural generalization to directed graphs. The main difference is that the directions of edges must be respected.

## DFS on Directed Graphs (5)



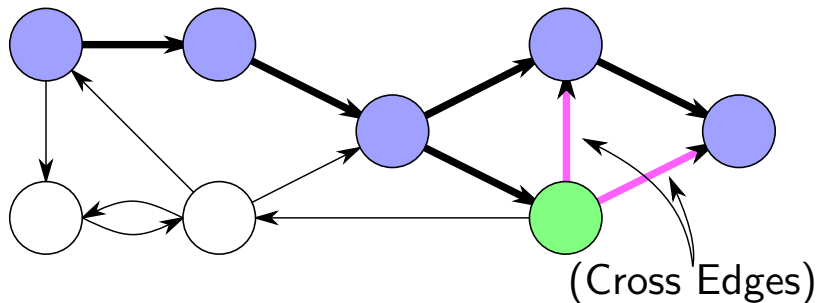
At this point, the current vertex has no unvisited neighbours, since the edges incident with the vertex are inbound edges.

## DFS on Directed Graphs (6)



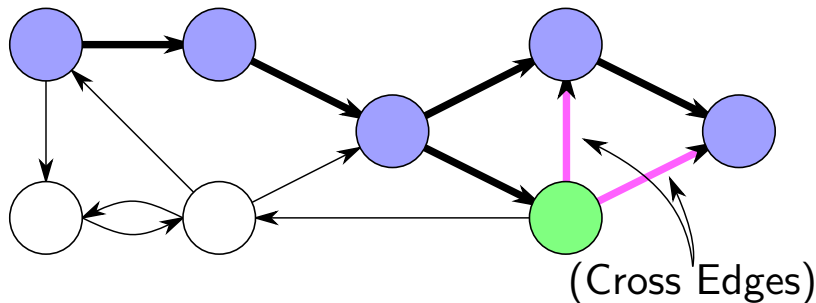
Recursion unwinds to the last vertex with unvisited neighbours.

## DFS on Directed Graphs (7)



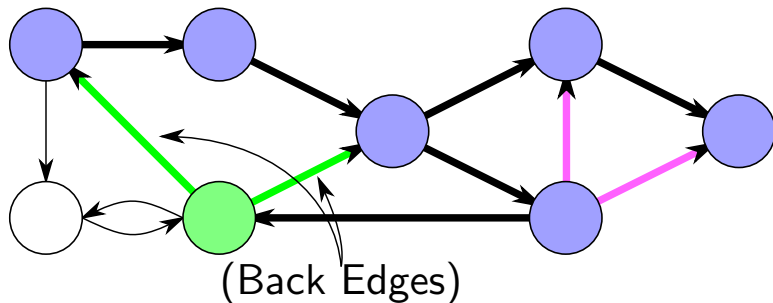
The neighbours of the current vertex are in a different branch of the DFS tree, so the edges are called **cross edges**.

## DFS on Directed Graphs (8)



**Exercise:** Show that cross edges will never appear during DFS on an undirected graph.

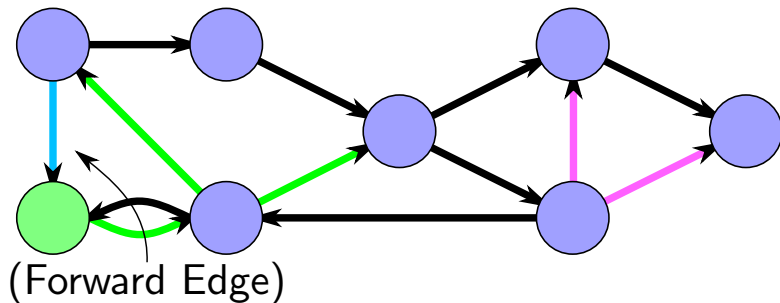
## DFS on Directed Graphs (9)



The two green edges are back edges, since the other endpoint of each edge is an ancestor of the current node in the DFS tree.

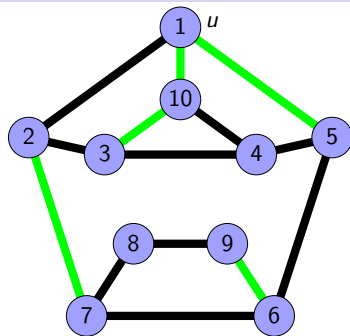


## DFS on Directed Graphs (10)

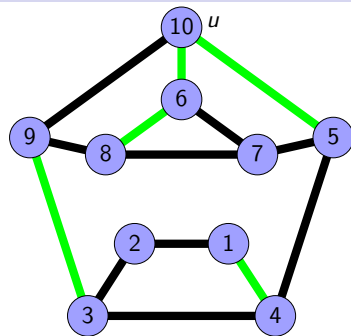


The light blue edge points from the root of the DFS tree to the current node. It is therefore a **forward edge**, since it points from a node to one of its descendants.

# DFS Vertex Numbering (1)



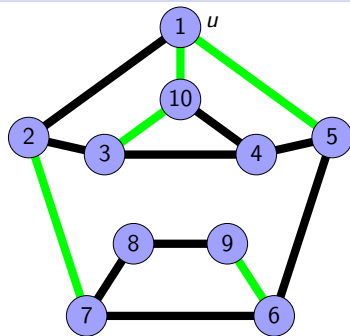
Pre-Order Numbering



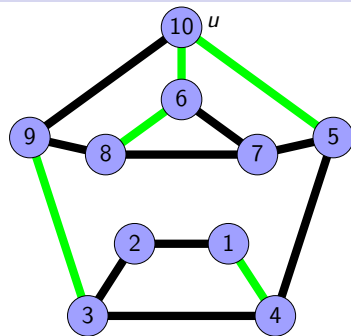
Post-Order Numbering

The order in which vertices are visited in a DFS traversal is often significant. Vertices can be assigned indices based on their order during a traversal.

## DFS Vertex Numbering (2)



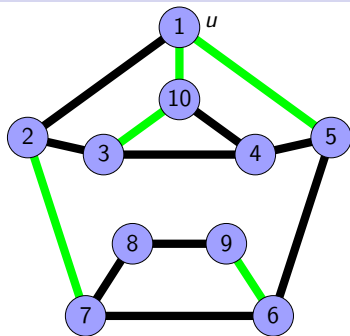
Pre-Order Numbering



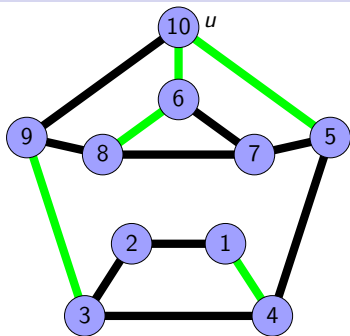
Post-Order Numbering

(In the diagrams above, the vertex  $u$  is the root of the DFS tree)

## DFS Vertex Numbering (3)



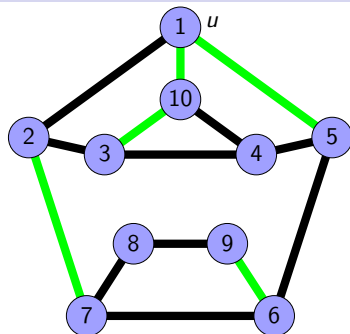
Pre-Order Numbering



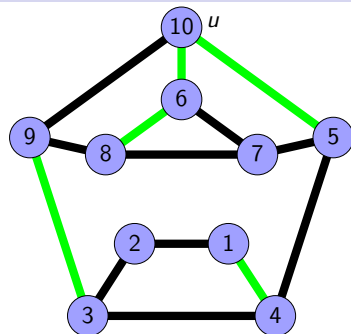
Post-Order Numbering

In a **pre-order** numbering, each vertex is assigned the next available index during the 'pre-order visit' (as DFS first arrives at the vertex).

## DFS Vertex Numbering (4)



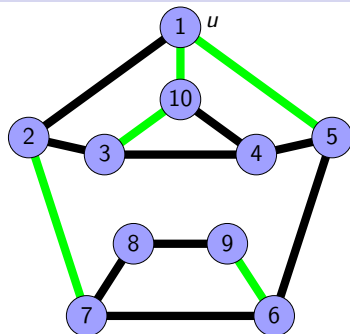
Pre-Order Numbering



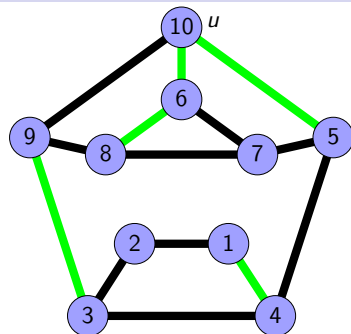
Post-Order Numbering

A pre-order numbering corresponds to the order in which vertices are visited in a pre-order traversal of the DFS tree.

## DFS Vertex Numbering (5)



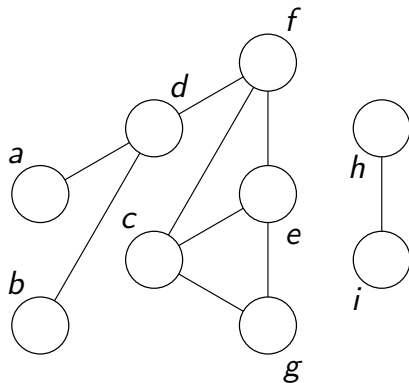
Pre-Order Numbering



Post-Order Numbering

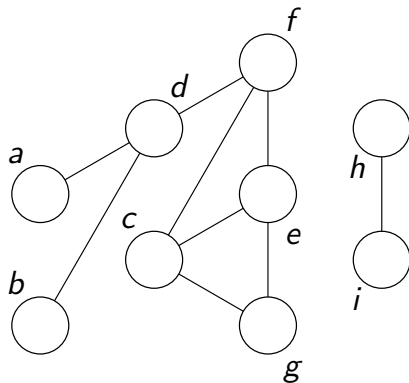
In a **post-order** numbering, each vertex is assigned the next available index during the 'post-order visit' (just before DFS leaves the vertex for the last time). A post-order numbering corresponds to a post-order traversal of the DFS tree.

# Storing Traversal Trees (1)



**Exercise:** Perform a DFS traversal starting at vertex *f* above and store the resulting DFS tree.

## Storing Traversal Trees (2)

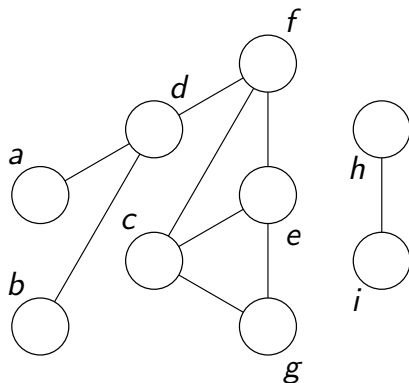


Vertex	a	b	c	d	e	f	g	h	i
Parent	×	×	×	×	×	×	×	×	×

Traversal trees (and other rooted trees) can be represented with a **parent array** structure. A parent array is an associative map which stores the parent of each vertex.



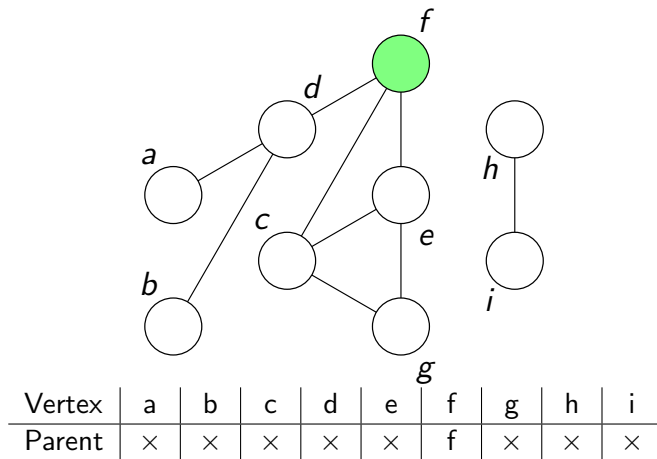
## Storing Traversal Trees (3)



Vertex	a	b	c	d	e	f	g	h	i
Parent	×	×	×	×	×	×	×	×	×

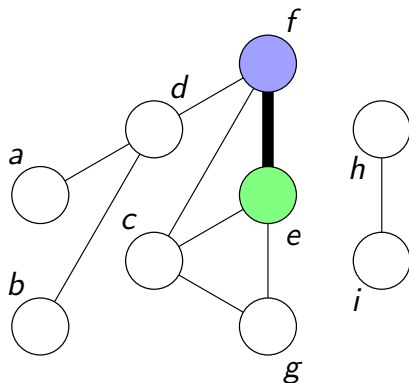
Vertices which are not part of the tree have no parent, and are marked as invalid (in this case, using the symbol  $\times$ ). Before the traversal starts, all vertices have invalid parents.

## Storing Traversal Trees (4)



At the beginning of the traversal, the starting vertex  $f$  is set to be its own parent (to indicate that  $f$  is the root).

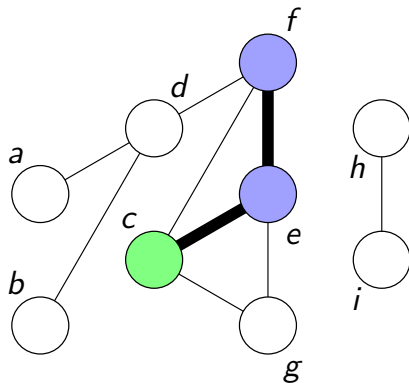
## Storing Traversal Trees (5)



Vertex	a	b	c	d	e	f	g	h	i
Parent	×	×	×	×	f	f	×	×	×

Since vertex *e* is visited for the first time from vertex *f*, the parent of *e* is set to be *f*.

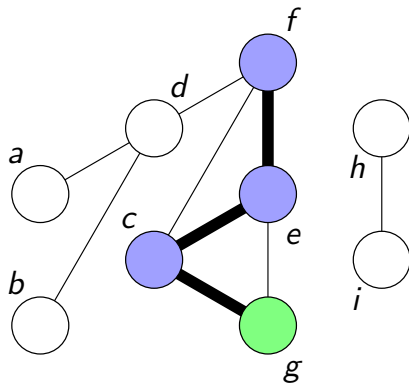
## Storing Traversal Trees (6)



Vertex	a	b	c	d	e	f	g	h	i
Parent	×	×	e	×	f	f	×	×	×

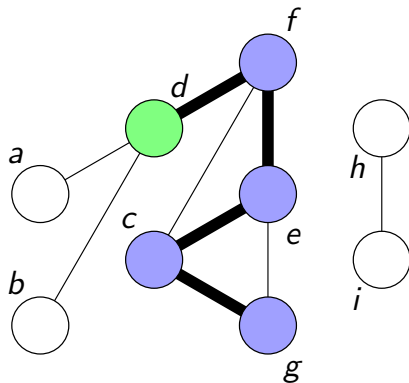
As the traversal proceeds, the parent of each newly discovered vertex  $w$  is set to be the vertex  $u$  on the other endpoint of its discovery edge.

# Storing Traversal Trees (7)



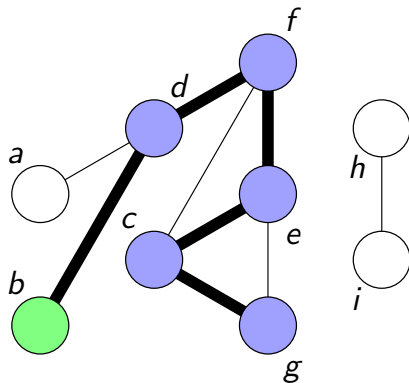
Vertex	a	b	c	d	e	f	g	h	i
Parent	×	×	e	×	f	f	c	×	×

# Storing Traversal Trees (8)



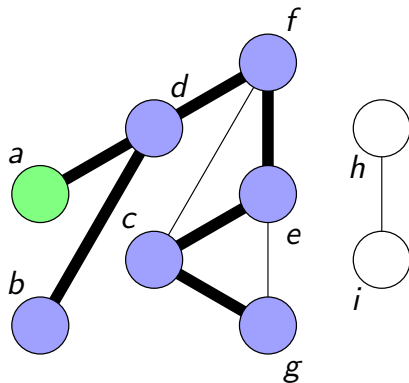
Vertex	a	b	c	d	e	f	g	h	i
Parent	×	×	e	f	f	f	c	×	×

# Storing Traversal Trees (9)



Vertex	a	b	c	d	e	f	g	h	i
Parent	×	d	e	f	f	f	c	×	×

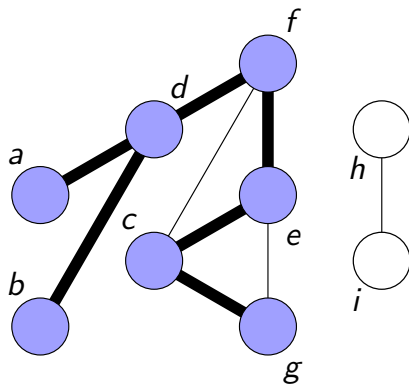
# Storing Traversal Trees (10)



Vertex	a	b	c	d	e	f	g	h	i
Parent	d	d	e	f	f	f	c	×	×



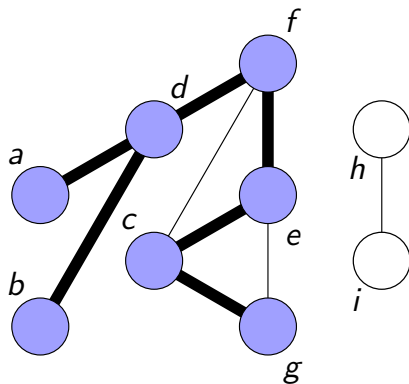
# Storing Traversal Trees (11)



Vertex	a	b	c	d	e	f	g	h	i
Parent	d	d	e	f	f	f	c	×	×

When the traversal finishes, any vertices with an invalid parent (such as *h* and *i* in the above example) are not reachable from the starting vertex *f*.

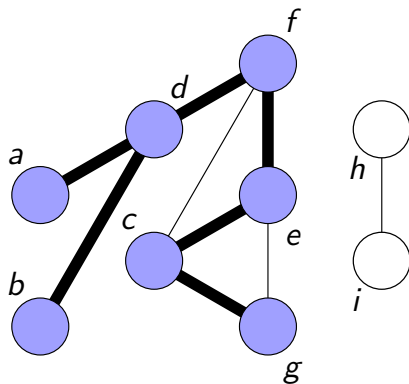
# Storing Traversal Trees (12)



Vertex	a	b	c	d	e	f	g	h	i
Parent	d	d	e	f	f	f	c	×	×

If a vertex  $v$  has a valid parent, a path from  $v$  to the starting vertex can be found by following the parent pointers to the root of the tree.

## Storing Traversal Trees (13)



Vertex	a	b	c	d	e	f	g	h	i
Parent	d	d	e	f	f	f	c	×	×

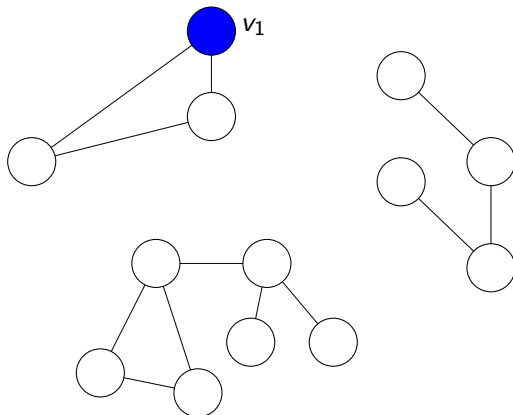
Observe that a single DFS traversal rooted at a vertex  $u$  will find a path from  $u$  to **all** vertices reachable from  $u$ .

## Storing Traversal Trees (14)

```
1: procedure GENERATEDFSTREE( $v$ )
2:   for each neighbour  $w$  of  $v$  do
3:     if Parent[ $w$ ] =  $\times$  then
4:       //(  $v, w$  ) is a discovery edge
5:       Parent[ $w$ ] =  $v$ 
6:       GENERATEDFSTREE( $w$ )
7:     end if
8:   end for
9: end procedure
```

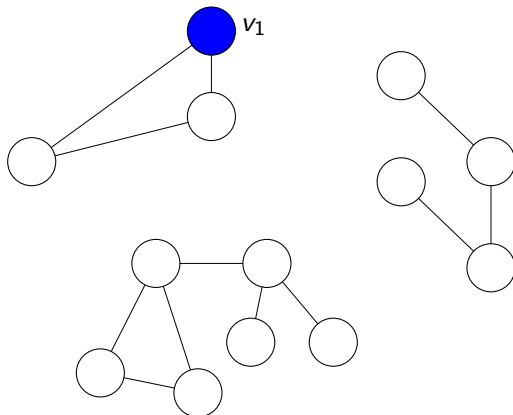
To start the recursive traversal above at a vertex  $u$ , set Parent[ $u$ ] =  $u$  and set all other elements of Parent to  $\times$ .

# Finding Connected Components (1)



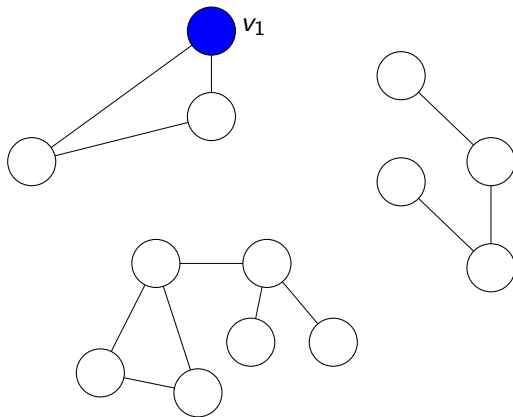
**Exercise:** Describe an algorithm to find the connected components of a graph  $G$ .

## Finding Connected Components (2)



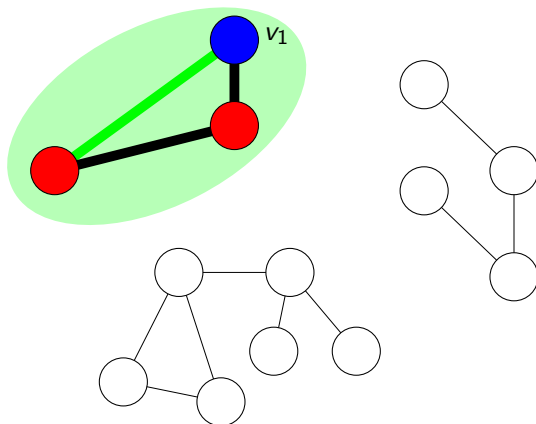
(This will be very helpful on Programming Assignment 3...)

## Finding Connected Components (3)



A DFS traversal rooted at a vertex  $v$  will visit all vertices reachable from  $v$ .

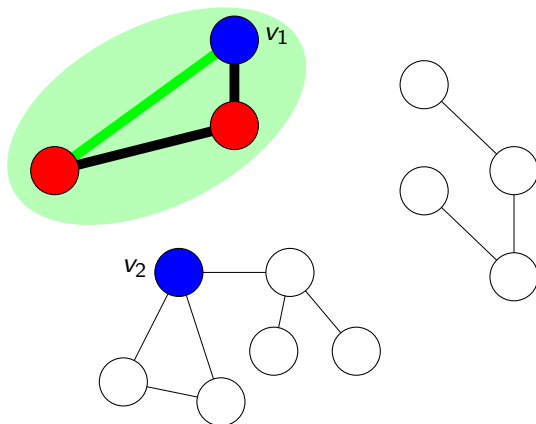
## Finding Connected Components (4)



To find the components, choose a vertex  $v_1$  and run DFS to find the component containing  $v_1$ .

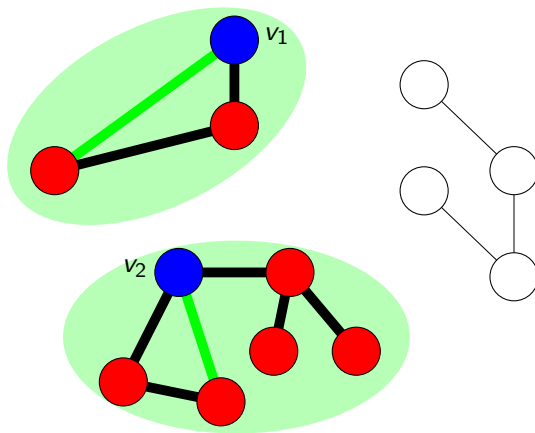


## Finding Connected Components (5)



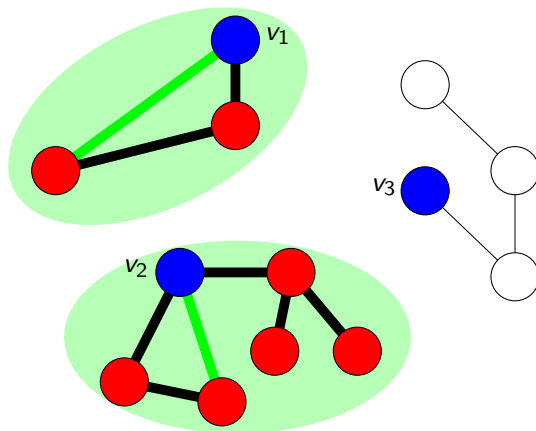
If all vertices in the graph have not been visited, choose another vertex  $v_2$  and run DFS again.

## Finding Connected Components (6)



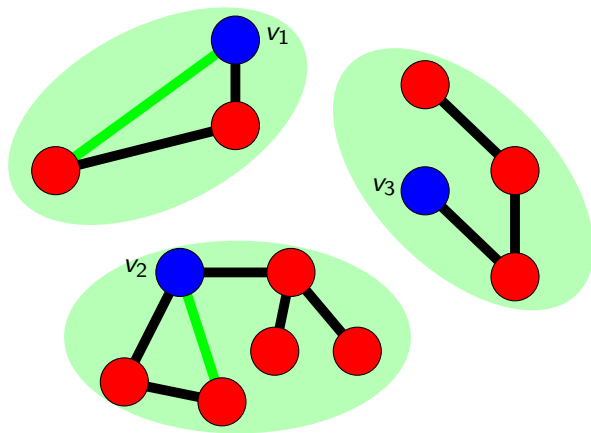
Each instance of DFS finds a spanning tree of one connected component.

# Finding Connected Components (7)



While unvisited vertices remain, continue choosing an unvisited vertex and running DFS.

## Finding Connected Components (8)



While unvisited vertices remain, continue choosing an unvisited vertex and running DFS.