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Q.3  
Eigen Value

$$A = \begin{bmatrix} 0 & -1 \\ 2 & 3 \end{bmatrix}$$

Calculating eigen values.

$$|A - \lambda I| = 0$$

$$\begin{bmatrix} 0 & -1 \\ 2 & 3 \end{bmatrix} - \begin{bmatrix} \lambda & 0 \\ 0 & \lambda \end{bmatrix} = 0$$

$$\begin{vmatrix} -\lambda & -1 \\ 2 & 3-\lambda \end{vmatrix} = 0 \Rightarrow (-\lambda)(3-\lambda) + 2 = 0$$

$$\Rightarrow -3\lambda + \lambda^2 + 2 = 0$$

$$\lambda^2 - 3\lambda + 2 = 0$$

$$\cancel{\lambda^2} \lambda^2 - 2\lambda - \lambda + 2 = 0$$

$$\lambda(\lambda-2) - 1(\lambda-2) = 0$$

$$\boxed{\lambda = 1, \lambda = 2}$$

Calculating eigen vector

$$AX = \lambda X$$

$$\lambda = 1$$

$$\begin{bmatrix} 0 & -1 \\ 2 & 3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$



Question  
3

$$\boxed{-x_2 = x_1}$$

or

$$\boxed{x_2 = -x_1}$$

Putting  $x_2 = 1$   
we get

$$\lambda = 1$$

~~or~~

Eigen Vector

$$\begin{bmatrix} -1 \\ +1 \end{bmatrix}$$

$$\lambda = 2$$

$$AX = \lambda X$$

$$\begin{bmatrix} 0 & -1 \\ 2 & 3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 2x_1 \\ 2x_2 \end{bmatrix}$$

$$\boxed{-x_2 = 2x_1}$$

or

$$\boxed{x_2 = -2x_1}$$

~~if  $x_1 = 0$~~

~~$x_2 = 0$~~

~~$x_1 = 0$~~

$$x_2 = -2x_1 \Rightarrow \boxed{-2x_1 = x_2}$$

$$\text{Put } x_2 = 1 \quad x_1 = -1/2$$

For  $\lambda = 2$

$$\begin{bmatrix} -1/2 \\ 1 \end{bmatrix}$$

For  $\lambda = 1$

$$\begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

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Ques # 2.

Question 2. Let  $\{v_1, v_2, \dots, v_n\}$  be  
an orthogonal basis for  
a subspace  $W$  of  $\mathbb{R}^n$ .

Then for each

$$Z = c_1 v_1 + c_2 v_2 + \dots + c_n v_n$$

We can generalize to

$$\text{Ques } c_n = \frac{Z \cdot v_n}{v_n \cdot v_n} \quad (n=1, \dots, n)$$



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Calculating eigen vector

$$AX = \lambda X$$

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Question 3

$$\boxed{-x_2 = x_1}$$

or

$$\boxed{x_2 = -x_1}$$

$$\lambda = 1$$

~~or~~

Eigen Vector

$$\begin{bmatrix} -1 \\ +1 \end{bmatrix}$$

Putting  $x_2 = 1$   
we get

$$\lambda = 2$$

$$AX = \lambda X$$

$$\begin{bmatrix} 0 & -1 \\ 2 & 3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 2x_1 \\ 2x_2 \end{bmatrix}$$

$$\boxed{-x_2 = 2x_1}$$

or

$$\boxed{x_2 = -2x_1}$$

~~if  $x_1 = 1$~~

$$x_2 = -2$$

~~$x_1 = -1/2$~~

$$x_2 = -2x_1 \Rightarrow \boxed{-2x_1 = x_2}$$

$$\text{Put } x_2 = 1 \quad x_1 = -1/2$$

For  $\lambda = 2$

$$\begin{bmatrix} -1/2 \\ 1 \end{bmatrix}$$

For  $\lambda = 1$

$$\begin{bmatrix} -1 \\ 1 \end{bmatrix}$$



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Then for each

$$Z = c_1 v_1 + c_2 v_2 + \dots + c_n v_n$$

We can generalize to

~~$$c_n = \frac{Z \cdot v_n}{v_n \cdot v_n} \quad (n=1, \dots, n)$$~~

$$c_j = \frac{Z \cdot v_j}{v_j \cdot v_j} \quad (j=1, 2, \dots, n)$$

Proof:

Orthogonality of  $\{v_1, \dots, v_n\}$  shows

$$\begin{aligned} \text{that } Z \cdot v_1 &= (c_1 v_1 + c_2 v_2 + \dots + c_n v_n) \cdot v_1 \\ &= c_1 (v_1 \cdot v_1) \end{aligned}$$

Since  $v_1 \cdot v_1$  is not zero equation above can be solved for  $c_1$ . To find  $c_j$  for  $j=2, 3, 4, \dots, n$  compute  $Z \cdot v_j$  and solve for  $c_j$ .