

University of Toronto Scarborough  
Department of Computer & Mathematical Sciences

**STAD57 Time Series Analysis**

**December 2016 Final Examination**

Instructor: Sotirios Damouras  
Duration: 3hours

**Examination aids allowed:** Non-programmable scientific calculator, open book/notes

Last Name: Sol Key  
First Name: \_\_\_\_\_  
Student #: \_\_\_\_\_

**Instructions:**

- Read the questions carefully and answer only what is being asked.
- Answer all questions directly on the examination paper; use the last pages if you need more space, and provide clear pointers to your work.
- Show your intermediate work, and write clearly and legibly.

Question:	1	2	3	4	5	6	7	Total
Points:	20	15	20	20	15	10	10	110
Score:								

1. Consider the time series  $X_t = 5 + W_t + .5W_{t-1} - .25W_{t-2}$ , where  $W_t \sim WN(0, 1)$ .

(a) (4 points) The series follows an ARMA( $p, q$ ) model. Find the order of the model (i.e.  $p, q$ ) and determine whether it is stationary and/or invertible.

(b) (4 points) Find the ACF of the series.

(c) (4 points) Find the PACF of the series for lags  $h = 1, 2, 3$ .

Let  $X_{n+m}^n$  be the  $m$ -step-ahead Best Linear Predictor (BLP) based on  $n$  series values, and let  $P_{n+m}^n$  be its associated Mean Square Prediction Error (MSPE).

(d) (4 points) Find  $X_{n+m}^n$  and  $P_{n+m}^n$  for any  $m \geq 3$ .

(e) (4 points) Find  $X_{2+1}^2$  (as a function of  $X_1, X_2$ ) and  $P_{2+1}^2$ .

(a)  $ARMA(0, 2) = MA(2) \Rightarrow$  causal/stationary

roots of MA poly:  $\frac{1}{8} + \frac{1}{2}z - \frac{1}{4}z^2 = 0 \Rightarrow \Delta = b^2 - 4ac = \frac{1}{4} - 4(\frac{1}{8})(-\frac{1}{4}) = \frac{1}{4} + 1 = \frac{5}{4}$

(2)  $z = \frac{-b \pm \sqrt{\Delta}}{2a} = \frac{-1/2 \pm \sqrt{5/4}}{2 \cdot 1/8} = \frac{(1 \pm 2\sqrt{5/4})}{-2/4} = 1 \pm \frac{1}{2} = \frac{3}{2}$  which is  $> 1$  in abs. val.

(b) (1)  $\gamma(0) = (1 + \theta_1^2 + \theta_2^2) \sigma^2 = 1 + \frac{1}{4} + \frac{1}{16} = \frac{16 + 4 + 1}{16} = \frac{21}{16}$

(1)  $\gamma(1) = (\theta_1 + \theta_2 \theta_1) \sigma^2 = \frac{1}{2} \cdot (1 - \frac{1}{4}) = \frac{3}{8} = \frac{6}{16} \Rightarrow \rho(1) = \frac{6}{21}$  (1)

(1)  $\gamma(2) = \theta_2 \sigma^2 = -\frac{1}{4} = -\frac{4}{16} \Rightarrow \rho(2) = -\frac{4}{21}$

$\gamma(h) = 0, h \geq 3$

(c)  $\phi_{11} = \rho(1) = \frac{6}{21} = .2857143$  (1)

$\phi_{2,2} = \frac{\gamma(2) - \sum \phi_{11} \gamma(1)}{\gamma(0) - \sum \phi_{11} \gamma(1)} = \frac{-4/16 - \frac{6}{21} \cdot \frac{6}{16}}{\frac{21}{16} - \frac{6}{21} \cdot \frac{6}{16}} = \frac{-4 \cdot 21 - 6^2}{21^2 - 6^2} = -0.29629$  (1)

$$\varphi_{2,1} = \varphi_{1,1} - \varphi_{22} \cdot \varphi_{11} = \varphi_{11} \cdot (1 - \varphi_{22})$$

$$= \frac{6}{21} \cdot (1 - \dots) = .3703704 \text{ (1)}$$

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$$\varphi_{33} = \frac{0 - \varphi_{21} \delta(2) - \varphi_{22} \delta(1)}{\delta(0) - \varphi_{21} \delta(1) - \varphi_{22} \delta(2)} = \dots = .1852632 \text{ (1)}$$

d)  $X_{n+m}^n = 5 \text{ (2)}, \quad P_{n+m}^n = \delta(0) = \frac{21}{16} \text{ (2)}$

e)  $X_{2+1}^2 = 5 + \varphi_{21} (X_2 - 5) + \varphi_{22} (X_1 - 5) \text{ (2)}$

$$P_{2+1}^2 = \delta(0) \cdot (-\varphi_{11})^2 \cdot (1 - \varphi_{12})^2 \text{ (2)}$$

2. Consider the zero-mean, stationary *bivariate* series  $\begin{bmatrix} X_t \\ Y_t \end{bmatrix}$  with individual auto-covariance functions  $\gamma_X(h), \gamma_Y(h), \forall h \geq 0$ , and cross-covariance function  $\gamma_{X,Y}(h), \forall h \in \mathbb{Z}$ .

(a) (7 points) Find the auto-covariance function of  $V_t = X_t - Y_{t-\ell}$ , for some  $\ell \in \mathbb{Z}$ , expressed in terms of  $\gamma_X(h), \gamma_Y(h), \gamma_{X,Y}(h)$ .

(b) (8 points) Find the cross-covariance function  $\gamma_{Z,W}(h)$  of the bivariate linear transformation  $\begin{bmatrix} Z_t \\ W_t \end{bmatrix} = \begin{bmatrix} a & b \\ c & 0 \end{bmatrix} \begin{bmatrix} X_t \\ Y_t \end{bmatrix}$ , expressed in terms of  $\gamma_X(h), \gamma_Y(h), \gamma_{X,Y}(h)$  and the constants  $a, b, c$ .

$$\begin{aligned}
 (a) \quad \gamma_V(h) &= \text{Cov}(V_{t+h}, V_t) = \text{Cov}(X_{t+h} - Y_{t+h-\ell}, X_t - Y_{t-\ell}) = \\
 &= \text{Cov}(X_{t+h}, X_t) - \text{Cov}(X_{t+h}, Y_{t-\ell}) - \\
 &\quad - \text{Cov}(X_t, Y_{t+h-\ell}) + \text{Cov}(Y_{t+h-\ell}, Y_{t-\ell}) = \\
 &= \gamma_X(h) - \gamma_{XY}(h+\ell) - \gamma_{XY}(\ell-h) + \gamma_Y(h), \quad \forall h \in \mathbb{Z}
 \end{aligned}$$

$$\begin{aligned}
 (b) \quad \gamma_{ZW}(h) &= \text{Cov}(Z_{t+h}, W_t) = \begin{cases} Z_t = aX_t + bY_t \\ W_t = cX_t \end{cases} \\
 &= \text{Cov}(aX_{t+h} + bY_{t+h}, cX_t) = \\
 &= ac \text{Cov}(X_{t+h}, X_t) + bc \text{Cov}(X_t, Y_{t+h}) = \\
 &= c(a \cdot \gamma_X(h) + b \cdot \gamma_{XY}(-h))
 \end{aligned}$$

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3. The time series  $\{X_t\}$  follows a zero-mean SARIMA(0, 1, 0)  $\times$  (1, 0, 0)<sub>[3]</sub> model with a single parameter  $\Phi$  and an i.i.d. Normal(0,  $\sigma^2$ ) white noise sequence  $\{W_t\}$ .

- (a) (4 points) Write down the linear equation describing the evolution of  $X_t$  based on its past ( $X_{t-1}, X_{t-2}, \dots$ ) and the white noise ( $W_t, W_{t-1}, \dots$ ).
- (b) (4 points) Can you find a *causal* representation for  $X_t$ ? (If yes, provide the representation; if no, explain why not.)
- (c) (4 points) Find the ACF of  $\nabla X_t = X_t - X_{t-1}$ .
- (d) (8 points) Write the conditional likelihood, given  $X_0 = 0$ , of the first 4 observations of the series ( $x_1, \dots, x_4$ ), expressed as a function of the parameters  $\Phi, \sigma^2$  and the values  $x_1, \dots, x_4$ .

$$\begin{aligned}
 (a) \quad (1 - \Phi B^3) \cdot \nabla X_t &= \overset{(2)}{W_t} \Rightarrow \\
 \Rightarrow (1 - \Phi B^3)(1 - B)X_t &= (1 - B - \Phi B^3 + \Phi B^4)X_t = W_t \\
 \Rightarrow X_t - X_{t-1} - \Phi X_{t-3} + \Phi X_{t-4} &= W_t \\
 \Rightarrow X_t &= X_{t-1} + \Phi X_{t-3} - \Phi X_{t-4} + W_t
 \end{aligned}$$

(b) No, not stationary.

$$(c) \quad \rho(h) = \begin{cases} \Phi^{h/3} / (1 - \Phi^2), & h = n \cdot 3, \quad n \in \mathbb{N} \\ 0, & \text{o/w} \end{cases}$$

(d) The marginal distribution of  $\nabla X_t$  is  $N(0, \frac{\sigma^2}{1 - \Phi^2})$

The conditional distr. of  $\nabla X_1 | X_0$  is  $N(0, \frac{\sigma^2}{1 - \Phi^2})$

— 11 —

$X_2 | X_1$  is  $N(X_1, \frac{\sigma^2}{1 - \Phi^2})$

— 11 —

$X_3 | X_2$  is  $N(X_2, \frac{\sigma^2}{1 - \Phi^2})$

— 11 —

$X_4 | X_3, X_1$  is  $N(X_3 + \Phi X_1, \sigma^2)$

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$$f(x_1, x_2, x_3, x_4 | x_0 = 0) = \left( \frac{1}{\sqrt{2\pi} \sigma^2 / (1-\phi^2)} \right)^3 \cdot \left( \frac{1}{\sqrt{2\pi} \sigma^2} \right).$$

$$\cdot \exp \left\{ -\frac{1}{2} \cdot \left( \frac{x_1^2}{\sigma^2 / (1-\phi^2)} + \frac{(x_2 - x_1)^2}{\sigma^2 / (1-\phi^2)} + \frac{(x_3 - x_2)^2}{\sigma^2 / (1-\phi^2)} + \frac{(x_4 - x_3 - \Phi x_1)^2}{\sigma^2} \right) \right\}.$$

4. Consider two jointly stationary time series  $\{X_t, Y_t\}$ , with individual auto-covariance functions  $\gamma_X(h), \gamma_Y(h), \forall h \geq 0$  and cross-covariance function  $\gamma_{X,Y}(h), \forall h \in \mathbb{Z}$ .

(a) (7 points) Find the Best Linear Predictor (BLP) of  $Y_t$  given  $X_t$ , and its Mean Square Prediction Error (MSPE), expressed in terms of  $\gamma_X(h), \gamma_Y(h), \gamma_{X,Y}(h)$ .

(b) (13 points) Find the BLP of  $Y_t$  given  $X_t, X_{t-1}, Y_{t-1}$ , and its MSPE, expressed in terms of  $\gamma_X(h), \gamma_Y(h), \gamma_{X,Y}(h)$ .

(Note: you don't need to solve the system of equations defining the BLP coefficients.)

$$\text{Let } \hat{Y}_t = aX_t$$

$$(a) \text{ Want } E[(Y_t - \hat{Y}_t)X_t] = 0 \Rightarrow$$

$$\Rightarrow E[(Y_t - aX_t)X_t] = 0 \Rightarrow \text{Cov}(Y_t, X_t) - a \cdot \text{Cov}(X_t, X_t) = 0$$

$$\Rightarrow \hat{a} = \frac{\gamma_{XY}(0)}{\gamma_X(0)}$$

$$\text{MSPE } E[(\hat{Y}_t - Y_t)^2] = E[(aX_t - Y_t)^2] =$$

$$= E[a^2 X_t^2 + Y_t^2 - 2aX_t Y_t] =$$

$$= \gamma_Y(0) + a^2 \gamma_X(0) - 2a \gamma_{XY}(0) = \gamma_Y(0) - a \gamma_{XY}(0) -$$

$$= \gamma_Y(0) - \frac{(\gamma_{XY}(0))^2}{\gamma_X(0)}$$



(b). similarly, we have

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$$\hat{Y}_t = \alpha_1 X_t + \alpha_2 X_{t-1} + \alpha_3 Y_{t-1}$$

$$E[(Y_t - \hat{Y}_t) \begin{pmatrix} X_t \\ X_{t-1} \\ Y_{t-1} \end{pmatrix}] = 0 \Rightarrow$$

$$\Rightarrow \underbrace{\begin{bmatrix} \sigma_{XX}(0) & \sigma_{XX}(1) & \sigma_{XY}(1) \\ \sigma_{XX}(1) & \sigma_{XX}(0) & \sigma_{XY}(0) \\ \sigma_{XY}(1) & \sigma_{XY}(0) & \sigma_{YY}(0) \end{bmatrix}}_{\underline{\Gamma}} \underbrace{\begin{pmatrix} \alpha_1 \\ \alpha_2 \\ \alpha_3 \end{pmatrix}}_{\underline{a}} = \underbrace{\begin{bmatrix} \sigma_{XY}(0) \\ \sigma_{XY}(-1) \\ \sigma_{YY}(1) \end{bmatrix}}_{\underline{\gamma}}$$

$$\Rightarrow \underline{a} = \underline{\Gamma}^{-1} \underline{\gamma}$$

$$P = \sigma_{YY}(0) - \underline{\gamma} \underline{\Gamma}^{-1} \underline{\gamma}$$

5. Consider a zero-mean (i.e. no drift) random walk  $X_t = X_{t-1} + W_t$ ,  $t \geq 1$ , where  $X_0 = 0$  and  $W_t \sim \text{WN}(0, \sigma^2)$ .

- (a) (5 points) Assume you try to estimate the auto-covariance at lag 0 (i.e. the variance) based on  $n$  observations, *as if* the process was stationary. More specifically, you use

$$\hat{\gamma}(0) = \frac{1}{n} \sum_{t=1}^n X_t^2$$

Find the expected value of  $\hat{\gamma}(0)$ , as a function of  $n, \sigma$ .

- (b) (5 points) Assume you try to estimate the auto-covariance at lag 1 based on  $n$  observations, *as if* the process was stationary. More specifically, you use

$$\hat{\gamma}(1) = \frac{1}{n} \sum_{t=2}^n X_t X_{t-1}$$

Find the expected value of  $\hat{\gamma}(1)$ , as a function of  $n, \sigma$ .

- (c) (5 points) Assume you are fitting an AR(1) model to  $n$  observations of  $X_t$  using Yule-Walker estimation. Furthermore, assume you replace all sample moment estimators with their expected values. Find the resulting estimate  $\hat{\phi}_1$  of the AR(1) coefficient, as a function of  $n, \sigma$ .

$$(a) \quad X_t = \sum_{s=1}^t W_s \Rightarrow E[X_t^2] = E\left[\left(\sum_{s=1}^t W_s\right)^2\right] = \text{by uncorrelated } W_t \\ = \sum_{s=1}^t E[W_s^2] = t \cdot \sigma_w^2$$

$$\Rightarrow E[\hat{\gamma}(0)] = E\left[\frac{1}{n} \sum_{t=1}^n X_t^2\right] = \frac{1}{n} \cdot \sum_{t=1}^n E[X_t^2] = \\ = \frac{1}{n} \cdot \sum_{t=1}^n t \sigma_w^2 = \frac{1}{n} \cdot n \cdot \frac{(n-1)}{2} \cdot \sigma_w^2 = \frac{n-1}{2} \sigma_w^2$$

$$(b) \quad E[X_t X_{t-1}] = E\left[\left(\sum_{s=1}^t W_s\right) \left(\sum_{r=1}^{t-1} W_r\right)\right] = \text{by uncorrelated } W_t \\ = \sum_{r=1}^{t-1} E[W_r^2] = (t-1) \sigma_w^2$$

$$\Rightarrow E[\hat{\gamma}(1)] = E\left[\frac{1}{n} \sum_{t=2}^n X_t X_{t-1}\right] = \frac{1}{n} \sum_{t=2}^n E[X_t X_{t-1}] = \\ = \frac{1}{n} \cdot \sum_{t=2}^n (t-1) \sigma_w^2 = \frac{\sigma_w^2}{n} \sum_{t=2}^n t = \frac{(n-1)(n-2)}{2n} \sigma_w^2$$

$$(c) \quad \hat{\phi}_1 = \frac{\hat{f}(1)}{\hat{f}(0)} \stackrel{\text{replace}}{\approx} \frac{\frac{n-1}{2} \sigma_u^2}{\frac{(n-1)(n-2)}{2n} \sigma_u^2} = \frac{n}{n-2}$$

6. Consider the ARCH(1) process  $X_t = \sigma_t \cdot \varepsilon_t$ , where  $\sigma_t^2 = \alpha_0 + \alpha_1 X_{t-1}^2$  and  $\varepsilon_t \sim^{iid} N(0, 1)$ .

(a) (5 points) Find  $Cov(X_t, X_{t-1}^2)$ .

(b) (5 points) Find  $E(X_t^2 | X_{t-2})$  as a function of  $X_{t-2}$ .

$$\begin{aligned}
 (a) \quad Cov(X_t, X_{t-1}^2) &= Cov(\sigma_t \cdot \varepsilon_t, \overset{\text{uncorrelated}}{\sigma_{t-1}^2 \cdot \varepsilon_{t-1}^2}) = \\
 &= E(\sigma_t \varepsilon_t \sigma_{t-1}^2 \varepsilon_{t-1}^2) = \\
 &= E(\varepsilon_t) \cdot E(\sigma_t \sigma_{t-1}^2) E(\varepsilon_{t-1}^2) = 0
 \end{aligned}$$

(b) For ARCH(1), we have  $X_t^2 = \alpha_0 + \alpha_1 X_{t-1}^2 + v_t$  WN.

$$\Rightarrow X_t^2 = \alpha_0 + \alpha_1 (\alpha_0 + \alpha_1 X_{t-2}^2 + \underbrace{v_{t-1}}_{\text{WN}}) + \underbrace{v_t}_{\text{WN}}$$

$$\begin{aligned}
 \Rightarrow E(X_t^2 | X_{t-2}) &= \alpha_0 + \alpha_1 (\alpha_0 + \alpha_1 X_{t-2}^2) + \\
 &\quad + E(\alpha_1 v_{t-1} | X_{t-2}) + E(v_t | X_{t-1})
 \end{aligned}$$

$$= \alpha_0 + \alpha_1 \alpha_0 + \alpha_1^2 X_{t-2}^2$$

7. (10 points) Consider the two time series  $\begin{cases} X_t = .5X_{t-1} + W_t \\ Y_t = W_t + .5W_{t-1} \end{cases}$ , defined based on the common white noise sequence  $W_t \sim \text{WN}(0, 1)$ . Find the cross-covariance function  $\gamma_{XY}(h), \forall h \in \mathbb{Z}$ , and show that the series are jointly stationary.

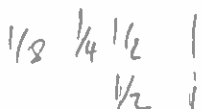
3  $\left( X_t \sim \text{AR}(1) \Rightarrow X_t = \sum_{j=0}^{\infty} \left(\frac{1}{2}\right)^j W_{t-j} \right.$   
 $\Rightarrow$  stationary with  $\gamma_X(h) = \frac{(\frac{1}{2})^h}{1 - (\frac{1}{2})^2} = \frac{4}{3} \left(\frac{1}{2}\right)^h, h \geq 0$

3  $\left( Y_t \sim \text{MA}(1) \Rightarrow \right.$  stationary with  $\gamma_Y(h) = \begin{cases} 1 + \frac{1}{4} = \frac{5}{4}, & h=0 \\ \frac{1}{2}, & h=1 \\ 0, & h \geq 2 \end{cases}$

$\gamma_{XY}(h) = \text{Cov}(X_{t+h}, Y_t) = \text{Cov}\left(\sum_{j=0}^{\infty} \left(\frac{1}{2}\right)^j W_{t+h-j}, W_t + \frac{1}{2}W_{t-1}\right) =$

$= \sum_{j=0}^{\infty} \left(\frac{1}{2}\right)^j \left[ \text{Cov}(W_{t+h-j}, W_t) + \frac{1}{2} \text{Cov}(W_{t+h-j}, W_{t-1}) \right] =$

4  $= \begin{cases} \left(\frac{1}{2}\right)^h \left(1 + \left(\frac{1}{2}\right)^2\right) & , h \geq 0 \\ \left(\frac{1}{2}\right)^2 & , h = -1 \\ 0 & , h \leq -2 \end{cases}$



**Extra Space** (use if needed and clearly indicate which questions you are answering)

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