

# Week 4: Nonparametric Regression

## MATH-517 Statistical Computation and Visualization

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One-dimensional KDE (from last week):

$$\hat{f}(x) = \frac{1}{nh_n} \sum_{i=1}^n K\left(\frac{X_i - x}{h_n}\right)$$

Multidimensional generalization (separable) when  $X_1, \dots, X_n \in \mathbb{R}^d$ :

$$\hat{f}(\mathbf{x}) = \frac{1}{nh^d} \sum_{i=1}^n K\left(\frac{X_{i,1} - x_1}{h}\right) \cdot \dots \cdot K\left(\frac{X_{i,d} - x_d}{h}\right)$$

## Section 1

# Non-parametric Regression

# Non-parametric Regression Setup

- we observe i.i.d. copies of a bivariate random vector  $(X, Y)^\top$ 
  - a random sample  $(X_1, Y_1)^\top, \dots, (X_n, Y_n)^\top$
- the response variable  $Y$  is related to the covariate  $X$  through

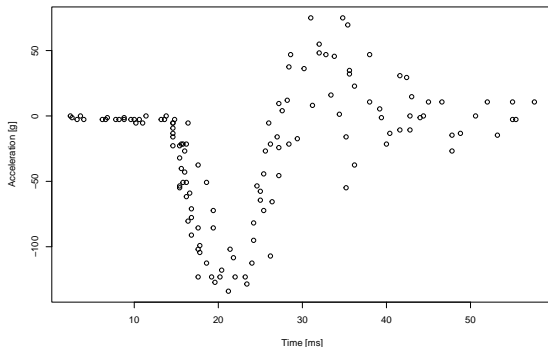
$$Y_i = m(X_i) + \epsilon_i, \quad \mathbb{E}(\epsilon_i) = 0 \quad \text{and} \quad \text{var}(\epsilon_i) = \sigma^2$$

- we are interested in the conditional expectation of  $Y$  given  $X$ , i.e., the regression function

$$m(x) = \mathbb{E}(Y|X = x)$$

- we want to avoid parametric assumptions

# Data Example



- head acceleration  $Y$  depending on time  $X$  in a simulated motorcycle accident used to test crash helmets

# Local average estimator

**Goal:** estimate  $m(x) = \mathbb{E}(Y|X = x)$  from  $(X_1, Y_1)^\top, \dots, (X_n, Y_n)^\top$  i.i.d.

Since  $m(x) = \mathbb{E}(Y|X = x)$ , one can estimate  $m(x)$  by averaging the  $Y_i$ s for which  $X_i$  is “close” to  $x$

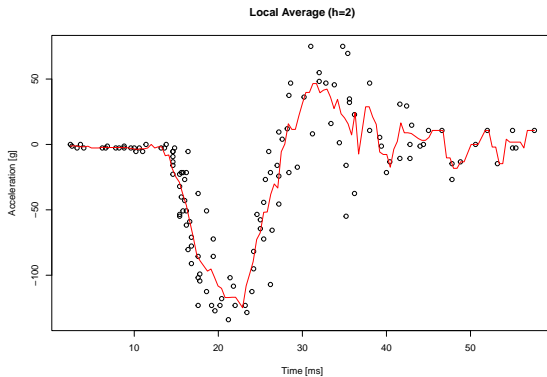
$\Rightarrow$  different averaging methods and different measures of closeness yield different estimators

The local average estimator is

$$\begin{aligned}\widehat{m}_n(x) &= \frac{\sum_{i=1}^n I(x-h < X_i \leq x+h) Y_i}{\sum_{i=1}^n I(x-h < X_i \leq x+h)} \\ &= \frac{\sum_{i=1}^n \frac{1}{2} \mathbb{1}_{[-1,1)}\left(\frac{x-X_i}{\tilde{h}}\right) Y_i}{\sum_{i=1}^n \frac{1}{2} \mathbb{1}_{[-1,1)}\left(\frac{x-X_i}{\tilde{h}}\right)},\end{aligned}$$

for  $h > 0$

# Local average estimator



# Local Constant Regression

Since  $m(x) = \int_{\mathbb{R}} y f_{Y|X}(y|x) dy = \frac{\int_{\mathbb{R}} y f_{X,Y}(x,y) dy}{f_X(x)}$  and we can now estimate densities, let's plug in those estimators

$$\hat{f}_X(x) = \frac{1}{nh} \sum_{i=1}^n K\left(\frac{x - X_i}{h}\right)$$

$$\hat{f}_{X,Y}(x,y) = \frac{1}{nh^2} \sum_{i=1}^n K\left(\frac{x - X_i}{h}\right) K\left(\frac{y - Y_i}{h}\right)$$

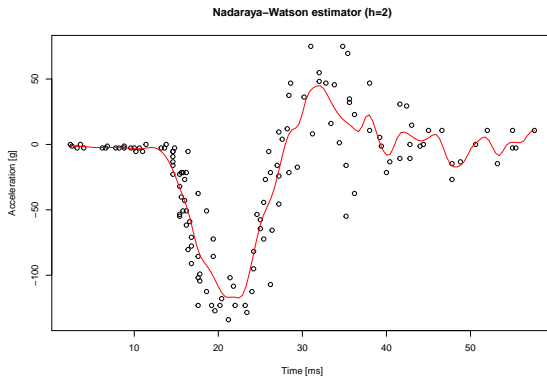
to obtain

$$\hat{m}(x) = \frac{\sum_{i=1}^n K\left(\frac{x - X_i}{h}\right) Y_i}{\sum_{i=1}^n K\left(\frac{x - X_i}{h}\right)}$$

⇒ The “box” kernel is replaced by a general kernel and yields the so-called Nadaraya–Watson kernel estimator



# Local Constant Regression



# Local Constant Regression

The Nadaraya–Watson kernel estimator

$$\widehat{m}(x) = \frac{\sum_{i=1}^n K\left(\frac{X_i - x}{h}\right) Y_i}{\sum_{i=1}^n K\left(\frac{X_i - x}{h}\right)} = \sum_{i=1}^n W_i^0(x) Y_i$$

is a weighted mean of the  $Y_i$ . Thus, it must be a solution to a weighted least squares:

$$\widehat{m}(x) = \arg \min_{\beta_0 \in \mathbb{R}} \sum_{i=1}^n K\left(\frac{x - X_i}{h}\right) (Y_i - \beta_0)^2$$

For a fixed  $x$ , this is a weighted intercept-only regression, with weights given by the kernel  $\Rightarrow$  estimate suffers from boundary bias

What if we went for better than intercept-only regression?

# Local Polynomial Regression

The aim is to find the local regression parameters  $\beta(x)$  s.t.

$$\hat{\beta}(x) = \arg \min_{\beta \in \mathbb{R}^{p+1}} \sum_{i=1}^n K\left(\frac{x - X_i}{h}\right) \{Y_i - \beta_0 - \beta_1(X_i - x) - \dots - \beta_p(X_i - x)^p\}^2$$

# Local Polyomial Regression

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$$\hat{\beta}(x) = \arg \min_{\beta \in \mathbb{R}^{p+1}} \sum_{i=1}^n K\left(\frac{x - X_i}{h}\right) \{Y_i - \beta_0 - \beta_1(X_i - x) - \dots - \beta_p(X_i - x)^p\}^2$$

Why does this make sense?

Recall that the aim is to estimate  $m(x) = \mathbb{E}(Y|X = x)$  and hence to minimize the RSS

$$\sum_{i=1}^n \{Y_i - m(X_i)\}^2$$

A Taylor expansion of  $m$  for  $x$  close to  $X_i$  is

$$m(X_i) \approx m(x) + (X_i - x)m'(x) + \frac{(X_i - x)^2}{2!}m''(x) + \dots + \frac{(X_i - x)^p}{p!}m^p(x),$$

# Local Polynomial Regression

The RSS can be rewritten as

$$\sum_{i=1}^n \left\{ Y_i - \sum_{j=0}^p \frac{m^{(j)}(x)}{j!} (X_i - x)^j \right\}^2$$

Thus,  $\hat{\beta}_j(x)$  estimates  $\frac{m^{(j)}(x)}{j!}$

- $\widehat{m}(x) = \hat{\beta}_0(x)$
- $\widehat{m}'(x) = \hat{\beta}_1(x)$

Finally, add a weighting kernel to make the contributions of  $X_i$  dependent on their distance to  $x$

$\Rightarrow \hat{\beta}$  becomes the solution to a weighted least squares problem

$$\hat{\beta} = \arg \min_{\beta \in \mathbb{R}^{p+1}} (\mathbf{Y} - \mathbf{X}\beta)^\top \mathbf{W} (\mathbf{Y} - \mathbf{X}\beta) = (\mathbf{X}^\top \mathbf{W} \mathbf{X})^{-1} \mathbf{X}^\top \mathbf{W} \mathbf{Y},$$

where  $\mathbf{W}$  is a diagonal matrix with entries depending on the kernel!

# Local Linear Regression

Choosing the order  $p = 1$  leads to the local linear estimator

$$(\hat{\beta}_0(x), \hat{\beta}_1(x)) = \arg \min_{\beta \in \mathbb{R}^2} \sum_{i=1}^n \{Y_i - \beta_0 - \beta_1(X_i - x)\}^2 K\left(\frac{x - X_i}{h}\right),$$

It can be shown that  $\hat{m}(x) = \hat{\beta}_0(x) = \sum_{i=1}^n w_{ni}(x) Y_i$ , where

$$w_{ni}(x) = \frac{1}{nh} \frac{K\left(\frac{x - X_i}{h}\right) \left\{ S_{n,2}(x) - (X_i - x) S_{n,1}(x) \right\}}{S_{n,0}(x) S_{n,2}(x) - S_{n,1}^2(x)}$$

with  $S_{n,k}(x) = \frac{1}{nh} \sum_{i=1}^n (X_i - x)^k K\left(\frac{X_i - x}{h}\right)$

- $\sum_{i=1}^n w_{ni}(x) = 1$

$\Rightarrow \hat{m}$  is a linear smoother, i.e.,  $\forall x$ , it can be defined by a weighted average:  $\hat{m}(x) = \sum_{i=1}^n l_i(x) Y_i$  (valid for Nadaraya–Watson and any  $p$ )

A shiny App can be found [here](#)

# Bias and Variance

For local linear regression, similarly to KDE and under regularity assumptions on  $m$ ,  $f$ ,  $K$ ,  $h$ , and  $nh$ ,

$$\begin{aligned}\text{bias}\{\widehat{m}(x)\} &= \frac{1}{2}m''(x)h_n^2 \int z^2 K(z)dz + o_P(h_n^2) \\ \text{var}\{\widehat{m}(x)\} &= \frac{\sigma^2(x)}{f_X(x)} \frac{\int \{K(z)\}^2 dz}{nh_n} + o_P\left(\frac{1}{nh_n}\right)\end{aligned}$$

where  $\sigma^2(x) = \text{var}(Y_1|X_1 = x)$  is the conditional/local variance

This implies that

- the bias depends on the curvature of  $m$ : negative for concave and positive for convex regions
- the variance decreases at a rate inversely proportional to the effective sample size  $nh$

For other orders, similar expressions can be obtained



# Nadaraya–Watson vs Local Linear estimator

It can be shown that, under the same smoothing conditions on  $f(x)$  and  $m(x)$ , the Nadaraya–Watson estimator  $\tilde{m}$

- has the same variance as the local linear estimator  $\hat{m}$
- has bias

$$\text{bias}\{\tilde{m}(x)\} = h_n^2 \left\{ \frac{1}{2} m''(x) + m'(x) \frac{f'(x)}{f(x)} \right\} \int z^2 K(z) dz + o_P(h_n^2)$$

⇒ At the boundary points, the NW estimator bears high value due to the large absolute value of  $f'(x)/f(x)$

⇒ Local linear estimation has no boundary bias as it does not depend on  $f(x)$  (no design bias)

# Bandwidth Selection

Similarly to what we did last week with KDEs, we consider

$$MSE\{\widehat{m}(x)\} = \text{var}\{\widehat{m}(x)\} + [\text{bias}\{\widehat{m}(x)\}]^2$$

and, dropping the little-o terms, we obtain

$$AMSE\{\widehat{m}(x)\} = \frac{\sigma^2(x) \int \{K(z)\}^2 dz}{f_X(x) n h_n} + \frac{1}{4} \{m''(x)\}^2 h_n^4 \left( \int z^2 K(z) dz \right)^2.$$

Now, a local bandwidth choice can be obtained by optimizing AMSE. Taking derivatives and setting them to zero, we obtain

$$h_{opt}(x) = n^{-1/5} \left[ \frac{\sigma^2(x) \int \{K(z)\}^2 dz}{\{m''(x) \int z^2 K(z) dz\}^2 f_X(x)} \right]^{1/5}$$

# Bandwidth Selection

$$h_{opt}(x) = n^{-1/5} \left[ \frac{\sigma^2(x) \int \{K(z)\}^2 dz}{\{m''(x) \int z^2 K(z) dz\}^2 f_X(x)} \right]^{1/5}$$

This is somewhat more complicated compared to the KDE case, because we have to estimate

- the marginal density  $f_X(x)$ ,
  - let's say that we already know how to do this, e.g., by KDE even though that requires a choice of yet another bandwidth
- the local variance function  $\sigma^2(x)$ , and
- the second derivative of the regression function  $m''(x)$

Again, like in the case of KDEs, the global bandwidth choice can be obtained by integration:

- calculate  $AMISE(\widehat{m}) = \int AMSE\{\widehat{m}(x)\}dx$ , and
- set  $h_{AMISE} = \arg \min_{h>0} AMISE(\widehat{m})$

# Rule of Thumb Plug-in Algorithm

Replace the unknown quantities in

$$h_{AMISE} = n^{-1/5} \left[ \frac{\int K^2(z) dz \int \sigma^2(x) dx}{\int z^2 K(z) dz \int \{m''(x)\}^2 f_X(x) dx} \right]^{1/5}$$

by parametric OLS estimators

- Assume homoscedasticity and a quartic kernel, then

$$h_{AMISE} = n^{-1/5} \left( \frac{35\sigma^2 |supp(X)|}{\theta_{22}} \right)^{1/5}, \quad \theta_{22} = \int \{m''(x)\}^2 f_X(x) dx$$

- Block the sample in  $N$  blocks and fit, in each block  $j$ , the model

$$y_i = \beta_{0j} + \beta_{1j}x_i + \beta_{2j}x_i^2 + \beta_{3j}x_i^3 + \beta_{4j}x_i^4 + \epsilon_i$$

to obtain estimate  $\hat{m}_j(x_i) = \hat{\beta}_{0j} + \hat{\beta}_{1j}x_i + \hat{\beta}_{2j}x_i^2 + \hat{\beta}_{3j}x_i^3 + \hat{\beta}_{4j}x_i^4$

# Rule of Thumb Plug-in Algorithm

- Estimate the unknown quantities by

$$\hat{\theta}_{22}(N) = \frac{1}{n} \sum_{i=1}^n \sum_{j=1}^N \hat{m}_j''(X_i) \hat{m}_j''(X_i) \mathbb{1}_{X_i \in \mathcal{X}_j}$$

$$\hat{\sigma}^2(N) = \frac{1}{n - 5N} \sum_{i=1}^n \sum_{j=1}^N \{Y_i - \hat{m}_j(X_i)\}^2 \mathbb{1}_{X_i \in \mathcal{X}_j}$$

**Remark** Unknown quantities can also be replaced by non-parametric estimates, using a pilot bandwidth (see [lecture notes](#) for details).

# Why Local Linear?

Bias and variance can be calculated similarly also for higher order local polynomial regression estimators. In general:

- bias decreases with an increasing order
- variance increases with increasing order, but only for  $p = 2k + 1 \rightarrow p + 1$ , i.e., when increasing an odd order to an even one

For this reason, odd orders are preferred to even ones

- $p = 1$  is easy to grasp as it corresponds to locally fitted simple regression line
- increasing  $p$  has a similar effect to decreasing the bandwidth  $h$ 
  - hence  $p = 1$  is usually fixed and only  $h$  is tuned

## Section 2

### Other Smoothers

# Smoothing Splines

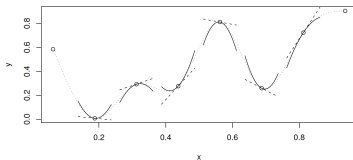
Consider the optimization problem

$$\arg \min_{g \in C^2} \sum_{i=1}^n \{Y_i - g(X_i)\}^2 + \lambda \int \{g''(x)\}^2 dx$$

- measure of closeness to the data, and
- smoothing penalty:  $\lambda > 0$  controls the trade-off between fit and smoothness

Unique solution: the **natural cubic spline**

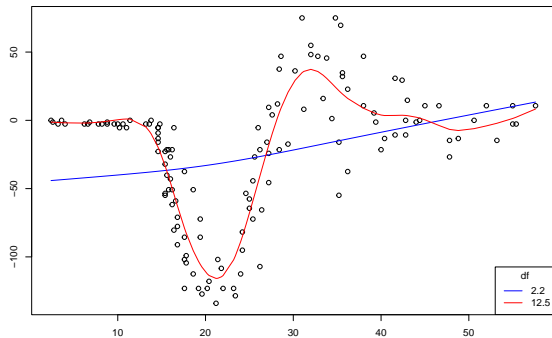
- piece-wise cubic polynomial between
  - knots at  $X_i$ ,  $i = 1, \dots, n$
  - two continuous derivatives at the knots
  - $\hat{m}''(x_1) = \hat{m}''(x_n) = 0$
- $\Rightarrow$  it has  $n$  free parameters



Source: [Wood \(2017\)](#)



# Smoothing Spline: Example



# Smoothing Splines

A natural cubic spline  $g$  with  $n$  knots can be expressed w.r.t. the natural cubic spline basis  $\{e_j\}$  (a set of basis functions) as

$$m(x) = \sum_{j=1}^n \gamma_j e_j(x)$$

Let

- $\gamma = (\gamma_1, \dots, \gamma_n)^\top \in \mathbb{R}^n$  be unknown coefficients
- $E := (e_{ij}) := \{e_j(x_i)\}_{i,j=1}^n \in \mathbb{R}^{n \times n}$  and
- $\Omega = (\omega_{ij}) \in \mathbb{R}^{n \times n}$  with  $\omega_{ij} = \int e_i''(x) e_j''(x) dx$

Then, the optimisation problem becomes

$$\sum_{i=1}^n \{Y_i - m(X_i)\}^2 + \lambda \int \{m''(x)\}^2 dx \quad \equiv \quad (Y - E\gamma)^\top (Y - E\gamma) + \lambda \gamma^\top \Omega \gamma$$

# Smoothing Splines

The solution is obtained in closed form

$$\hat{\gamma} = (E^\top E + \lambda \Omega) E^\top Y$$

The fitted values are

$$\hat{Y} = (\hat{m}_\lambda(x_1), \dots, \hat{m}_\lambda(x_n))^\top = E\hat{\gamma} = S_\lambda Y, \quad \text{with } S_\lambda = E(E^\top E + \gamma \Omega) E^\top$$

$\Rightarrow$  smoothing splines are linear smoothers

The matrix  $S_\lambda$  is the hat matrix and  $tr(S_\lambda)$  plays the role of the degrees of freedom (how many effective parameters you have in the model)

- Although there are  $n$  unknown coefficients, many are shrunk towards zero through the smoothness/roughness penalty
- $\lambda$  encodes the bias-variance trade-off ( $\lambda = 0$  : very rough,  $\lambda = \infty$  : very smooth)
- $\lambda$  is chosen by CV (next week's lecture)

# Orthogonal Series: Regression Splines

- take a pre-defined set of orthogonal functions  $\{e_j\}_{j=1}^{\infty}$ 
  - customarily some basis, e.g. Fourier basis, B-splines, etc.
- truncate it to  $\{e_j\}_{j=1}^p$
- approximate  $m(x) \approx \sum_{j=1}^p \gamma_j e_j(x)$

Then estimate  $m$  by least-squares:

$$\arg \min_{\gamma \in \mathbb{R}^p} \sum_{i=1}^n [Y_i - \gamma_1 e_1(x_i) - \dots - \gamma_p e_p(x_i)]^2$$

- just a single linear regression
- no penalty term, simplicity achieved via truncation
  - bias-variance trade-off controlled by the choice of  $p$
  - can be related to smoothness when  $e_j$ 's get more wiggly with increasing  $j$  (which is typical for most bases)
  - choice of location of knots is critical but tricky too (not needed with smoothing splines)

## Assignment 3 [5 %]

Go to [Assignment 3](#) for details.