

http://braintumorsegmentation.org

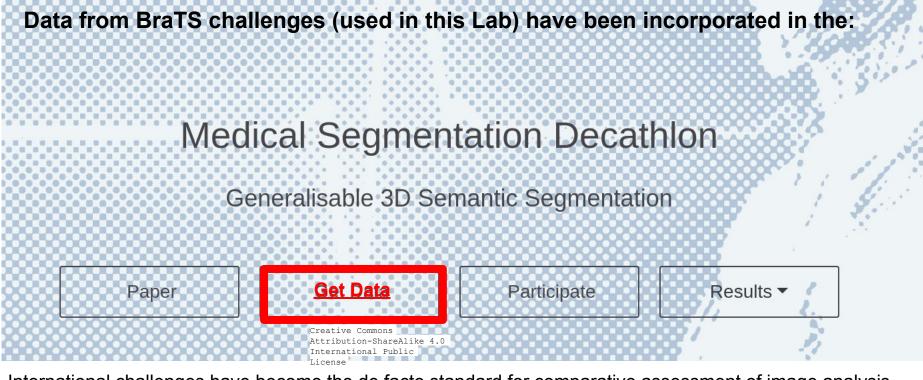
Previous BraTS Challenges

The Brain Tumor Segmentation (BraTS) challenge celebrated its 10th anniversary in 2021.

The RSNA-ASNR-MICCAI BraTS 2021 challenge utilizes multi-institutional pre-operative baseline multi-parametric magnetic resonance imaging (mpMRI) scans, and focuses on the evaluation of state-of-the-art methods for (Task 1) the segmentation of intrinsically heterogeneous brain glioblastoma sub-regions in mpMRI scans.

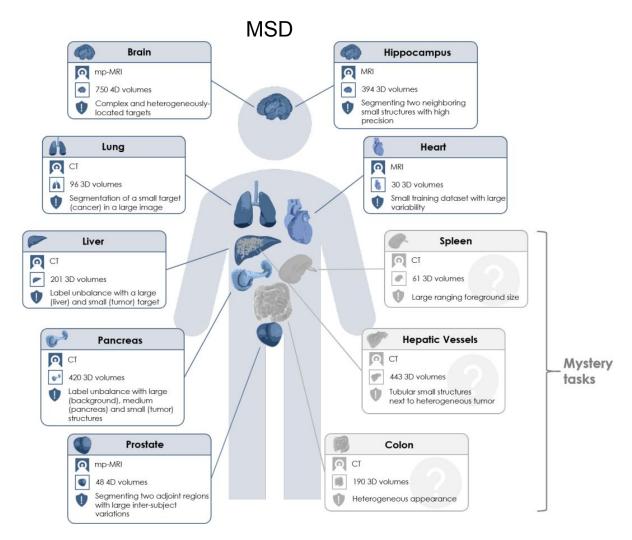
Furthemore, this BraTS 2021 challenge also focuses on the evaluation of (**Task 2**) **classification** methods to predict the MGMT promoter methylation status.

- BraTS 2012 (Nice, France) [proceedings]
- BraTS 2013 (Nagoya, Japan) [proceedings]
- BraTS 2014 (Boston, USA) [proceedings]
- BraTS 2015 (Munich, Germany) [proceedings]
- BraTS 2016 (Athens, Greece) [proceedings]
- BraTS 2017 (Quebec City, Canada) [proceedings]
- BraTS 2018 (Granada, Spain) [proceedings]
- BraTS 2019 (Shenzhen, China) [proceedings: vol.1, vol.2]
- BraTS 2020 (virtual) [proceedings: vol.1, vol.2]



International challenges have become the de facto standard for comparative assessment of image analysis algorithms given a specific task. Segmentation is so far the most widely investigated medical image processing task, but the various segmentation challenges have typically been organized in isolation, such that algorithm development was driven by the need to tackle a single specific clinical problem. We hypothesized that a method capable of performing well on multiple tasks will generalize well to a previously unseen task and potentially outperform a custom-designed solution.

http://medicaldecathlon.com



Overview of the ten different tasks of the Medical Segmentation Decathlon (MSD) http://medicaldecathlon.com

The challenge comprised different target regions, modalities and challenging characteristics and was separated into seven known tasks (blue; the development phase)

and three mystery tasks probing **generalization** to unseen segmentation tasks.

mp-MRI= multiparametric-magnetic resonance imaging

Development Phase - Brain (Brain Tumor Segmentation (BraTS) challenges)

- The data set consists of 750 multiparametric magnetic resonance images (mp-MRI) from patients diagnosed with either glioblastoma or lower-grade glioma.
- The sequences used were native T1-weighted (**T1**), post-Gadolinium (Gd) contrast T1-weighted (**T1-Gd**), native T2-weighted (**T2**), and T2 Fluid-Attenuated Inversion Recovery (**FLAIR**).
- The corresponding target ROIs were the three tumor sub-regions, namely edema, enhancing tumor, and non-enhancing tumor.
- This data set was selected due to the challenge of locating these complex and heterogeneously-located targets.
- The data was acquired from 19 different institutions and contained a subset of the data used in the 2016 and 2017 Brain Tumor Segmentation (BraTS) challenges [12, 13, 14].

Summary of the ten data sets of the Medical Segmentation Decathlon

Pha	se Task	Modality	Protocol	Target	# Cases (Train/Test)
	Brain	mp-MRI	FLAIR, T1w, T1 \setminus w Gd, T2w	Edema, enhancing and non-enhancing tumor	750 4D volumes (484/266)
e e	Heart	MRI	_	Left atrium	30 3D volumes (20/10)
ent phase	Hippocampus MRI		T1w	Anterior and posterior of hippocampus	394 3D volumes (263/131)
mer	Liver	CT	Portal venous phase Liver and liver tumor		210 3D volumes (131/70)
dole	Lung	CT	-	Lung and lung cancer	96 3D volumes $(64/32)$
Developm	Pancreas CT		Portal venous phase	Pancreas and pancreatic tumor mass	420 3D volumes (282/139)
	Prostate	$mp ext{-}MRI$	T2, ADC	Prostate PZ and TZ	48 4D volumes (32/16)
Φ					
phase	Colon CT Port		Portal venous phase	Colon cancer primaries	190 3D volumes (126/64)
Mystery	Hepatic Vessels	CT	Portal venous phase	Hepatic vessels and hepatic tumor	443 3D volumes (303/140)
$M_{\mathbf{y}}$	Spleen	CT	Portal venous phase	spleen	61 3D volumes (41/20)

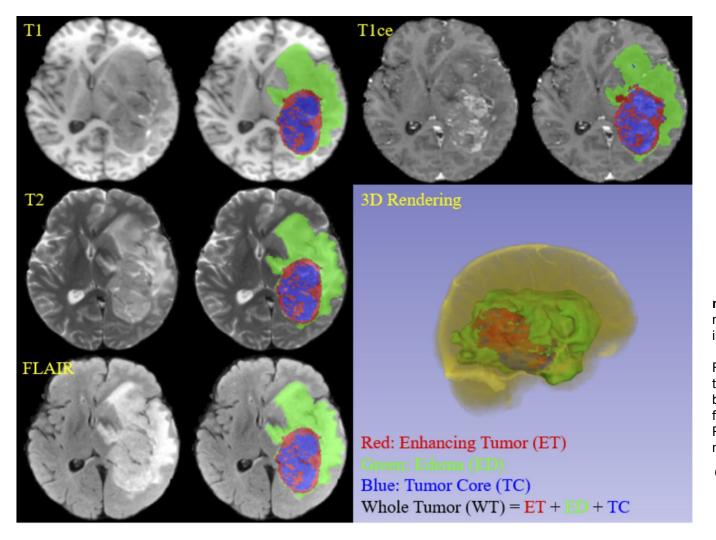
(Prostate: PZ - peripheral zone, TZ - transition zone)

http://medicaldecathlon.com

Get the data from: https://drive.google.com/drive/folders/1HqEgzS8BV2c7xYNrZdEAnrHk7osJJ--2

	Drive	Q	Search in Drive		=	<u> </u>		
+	New	Shared with me > MSD						
• 🛕	My Drive	Name	\uparrow	Owner	Last modified	File size		
	My blive		license.txt 🚢	M. Jorge Cardoso	May 15, 2018	20 KB		
· [Computers	₩	Task01_BrainTumour.tar 🚢	Michela Antonelli	Jan 14, 2020	7.09 GB		
2	Shared with me	₩	Task02_Heart.tar 🚢	Michela Antonelli	Jul 3, 2018	434.6 MB		
(J	Recent	₩	Task03_Liver.tar 🚢	Michela Antonelli	Feb 2, 2020	26.94 GB		
\Diamond	Starred	₩	Task04_Hippocampus.tar 🚢	Michela Antonelli	Jul 6, 2018	27.1 MB		
		₹	Task05_Prostate.tar 🚢	Michela Antonelli	Jul 3, 2018	228.7 MB		
	Trash	₩	Task06_Lung.tar 🚢	Michela Antonelli	Jul 3, 2018	8.53 GB		
\circ	Storage	₩	Task07_Pancreas.tar	Michela Antonelli	Feb 2, 2020	11.45 GB		
		₩	Task08_HepaticVessel.tar	M. Jorge Cardoso	Feb 2, 2020	8.71 GB		
267.82	267.82 GB of 2.02 TB used		Task09_Spleen.tar	M. Jorge Cardoso	Aug 6, 2018	1.5 GB		
Bu	ıy storage	₹	Task10_Colon.tar 🚢	M. Jorge Cardoso	Aug 6, 2018	5.81 GB		

Or, download Decathlon Dataset with Monai APIs: https://github.com/NVIDIA/clara-train-examples/blob/master/PvTorch/NoteBooks/Data/DownloadDecathlonDataSet.ipvnb



Visualized examples in BraTS Challenge

Ground truth is shown in 2D projected onto the multi-sequence MR images and in 3D together with a volume rendering of the raw data

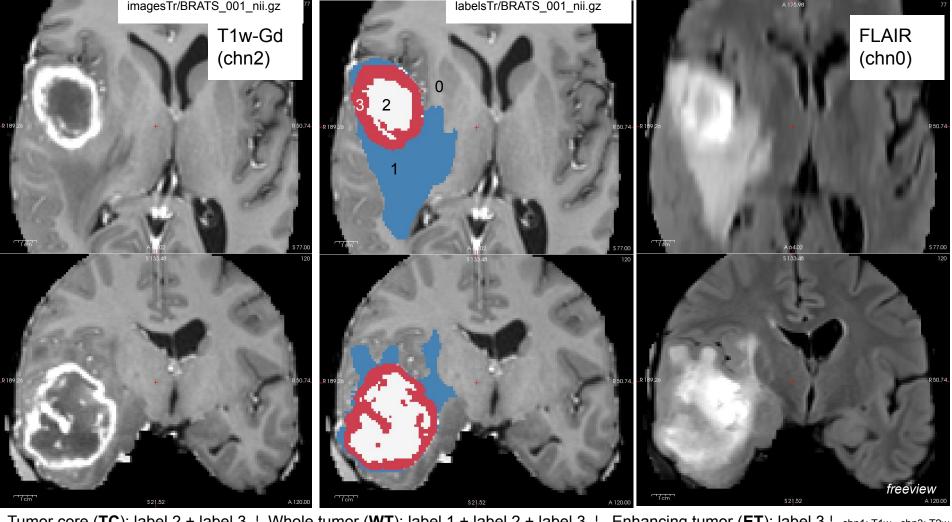
nnU-Net backbone All the top methods used UNet like architectures in the ten 3D segmentation challenges.

Remarkably, <u>nnU-Net</u> was used by the top teams in nine out of ten challenges, because it is open-sourced, powerful, flexible, and out-of-the-box.

Participants can easily integrate their new methods into nnU-Net.

Check: https://youtu.be/C6tpnJRpt90

https://arxiv.org/pdf/2101.00232.pdf



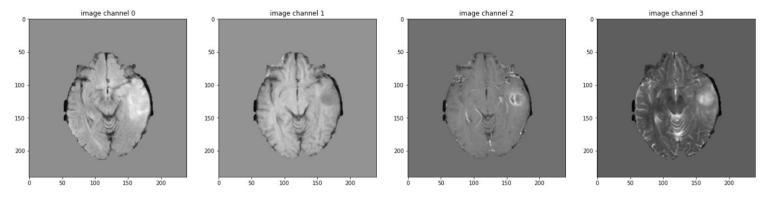
Tumor core (**TC**): label 2 + label 3 | Whole tumor (**WT**): label 1 + label 2 + label 3 | Enhancing tumor (**ET**): label 3 | chn1: T1w, chn3: T2w

Check data shape and visualize

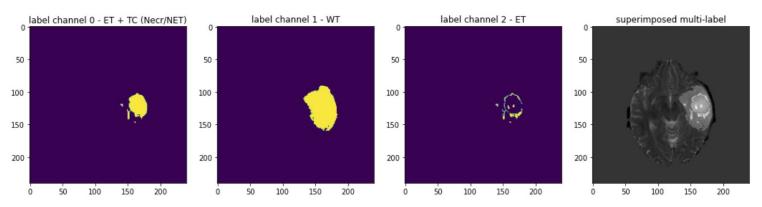
pick one image from DecathlonDataset to visualize and check the 4 channels

nshape = val ds[2]["image"][:, :, :, 60].detach().cpu().numpy().shape

image shape: torch.Size([4, 240, 240, 155])



label shape: torch.Size([3, 240, 240, 155])



https://nbviewer.org/github/MMIV-ML/ELMED219-2022/blob/main/Lab4-BRATS/ELMED219-2022-Lab4-BRATS-segmentation-3D-MONAI.ipynb

```
# standard PyTorch program style: create SegResNet, DiceLoss and Adam optimizer
device = torch.device("cuda:0")
model = SegResNet(
  blocks down=[1, 2, 2, 4],
                                                                 VAL AMP = True # Automatic Mixed Precision
  blocks up=[1, 1, 1],
                                                                  https://pytorch.org/docs/stable/notes/amp_examples.html
  init filters=16,
  in channels=4,
  out channels=3,
  dropout prob=0.2.
).to(device)
loss function = DiceLoss(smooth nr=0, smooth dr=1e-5, squared pred=True, to onehot y=False, sigmoid=True)
optimizer = torch.optim.Adam(model.parameters(), 1e-4, weight decay=1e-5)
Ir_scheduler = torch.optim.lr_scheduler.CosineAnnealingLR(optimizer, T_max=max_epochs)
dice_metric = DiceMetric(include_background=True, reduction="mean")
dice metric batch = DiceMetric(include background=True, reduction="mean batch")
post trans = Compose(
  [EnsureType(), Activations(sigmoid=True), AsDiscrete(threshold=0.5)]
```

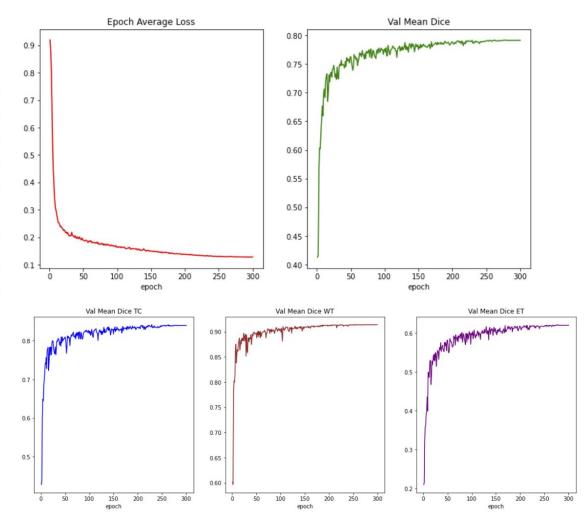
The NVIDIA RTX 6000 GPU workstation where the best_metric_model_5820_rtx6000_300epochs_20220115_1048.pth model was trained:

Fri Jan 14 13:40:10 2022

	A-SMI							CUDA Versi	on: 11.3
GPU	Name		Persis	tence-M age/Cap	Bus-Id	D	isp.A	Volatile	Uncorr. ECC Compute M. MIG M.
0 33%		Quad P8	ro R 19W	On / 260W	00000000 524M	0:65:00. iB / 241		 9% 	Off Default N/A

GPU	GI ID	ID	PID	Type	Process name	GPU Memory Usage
0	N/A	N/A	1357	G	/usr/lib/xorg/Xorg	77MiB
0	N/A	N/A	1852	G	/usr/lib/xorg/Xorg	207MiB
0	N/A	N/A	1984	G	/usr/bin/gnome-shell	81MiB
0	N/A	N/A	2914	G	AAAAAAAAAshared-files	30MiB
0	N/A	N/A	7139	G	AAAAAAAAAshared-files	54MiB
0	N/A	N/A	10037	G	/usr/lib/rstudio/bin/rstudio	57MiB
0	N/A	N/A	15250	G	gnome-control-center	3MiB

train completed, best_metric: 0.7918 at epoch: 276, total time: 80824.40817975998.



Check best model output with the input image and label

image

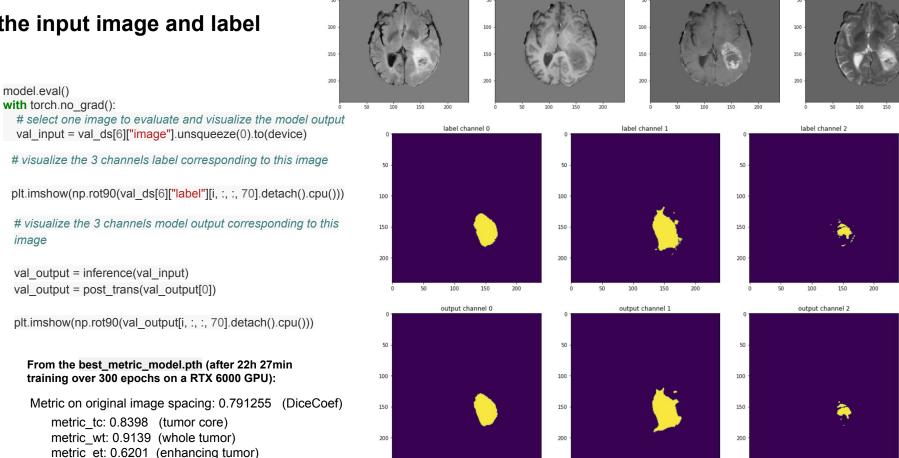


image channel 1

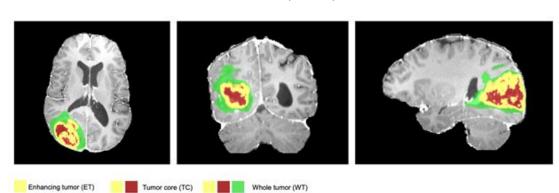
image channel 2

image channel 3

image channel 0

Note on BraTS 2021

- NVIDIA Data Scientists Take Top Spots in MICCAI 2021 <u>Brain Tumor Segmentation Challenge</u>:
- Optimized U-Net for Brain Tumor Segmentation Rank #1 (based on <u>nnU-Net</u> winner of <u>BraTS 2020</u> by <u>Isense et al.</u>)
- SegResNet: Redundancy Reduction in Semantic Segmentation of 3D Brain MRIs Rank #2
 The main model is the SegResNet architecture from MONAI, a standard encoder-decoder based convolutional neural network (CNN) similar to U-Net.



A typical segmentation example with predicted labels overlaid overT1c MRI axial, sagittal and coronal slices. The whole tumor (WT) class includes all visible labels (a union of green, yellow and red labels), the tumor core (TC) class is a union of red and yellow, and the enhancing tumor core (ET) class is shown in yellow (a hyperactive tumor part).