

copy-of-gwp2-group-4186

October 26, 2023

1 Worldquant University

1.1 23/09 622 Stochastic Modeling GWP2

1.2 Group 4186

2 Part 1

```
[1]: import pandas as pd
import numpy as np
import matplotlib.pyplot as plt

from scipy.stats import norm
import yfinance as yf
```

2.0.1 Collect crypto tickers

```
[2]: crypto_tickers = ['BTC-USD', 'ETH-USD']

crypto = pd.DataFrame()

for tick in crypto_tickers:
    ydata = yf.download(tick, start = '2019-01-01', end = '2022-12-31')
    crypto[tick] = ydata['Adj Close']

crypto.index = pd.to_datetime(ydata.index, format='%Y%m%d')

crypto.head()
```

```
[*****100%*****] 1 of 1 completed
[*****100%*****] 1 of 1 completed
```

```
[2]:
```

	BTC-USD	ETH-USD
Date		
2019-01-01	3843.520020	140.819412
2019-01-02	3943.409424	155.047684
2019-01-03	3836.741211	149.135010
2019-01-04	3857.717529	154.581940

2019-01-05 3845.194580 155.638596

```
[3]: crypto.describe()
```

```
[3]:
```

	BTC-USD	ETH-USD
count	1460.000000	1460.000000
mean	23532.857680	1313.156052
std	17561.500613	1281.337690
min	3399.471680	104.535301
25%	9142.184814	203.814823
50%	17129.605469	734.661774
75%	38713.802734	2162.123413
max	67566.828125	4812.087402

```
[4]: # Create a Figure and an Axes with plt.subplots
fig, ax = plt.subplots()

# Plot the data
ax.plot(crypto['BTC-USD'], label='BTC')
ax.plot(crypto['ETH-USD'], label='ETH')

# naming
ax.set_xlabel('date')
ax.set_ylabel('$')
ax.set_title("Prices")
ax.legend()

# Display the figure.
plt.show()
```



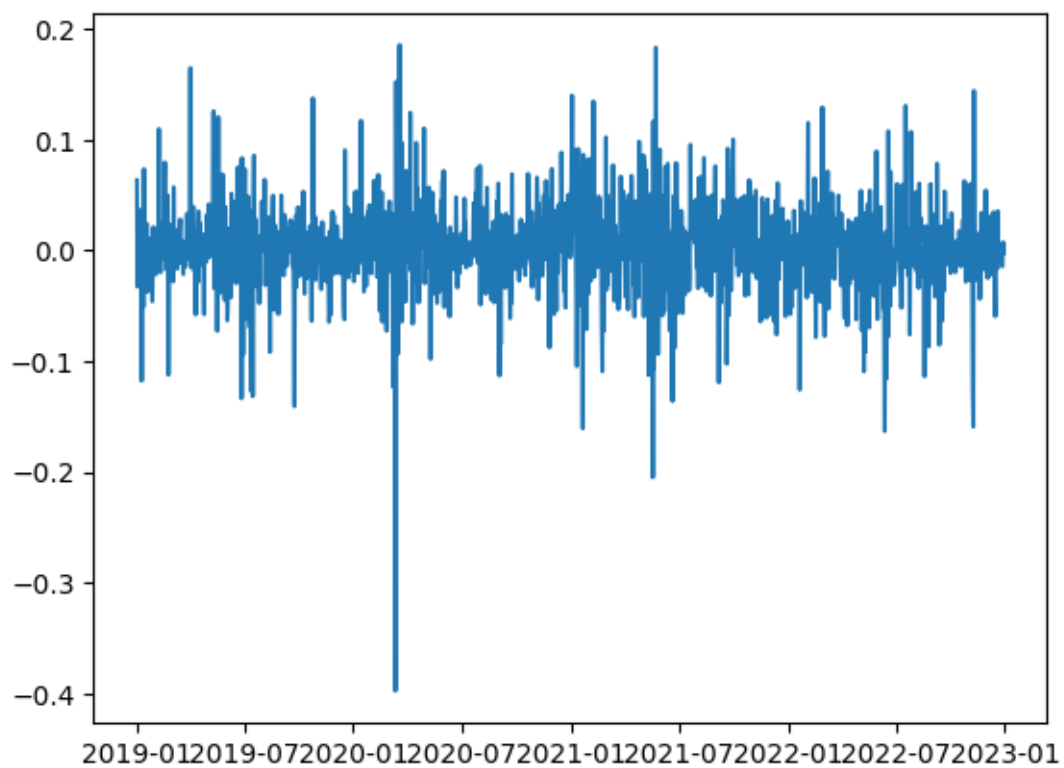
```
[5]: crypto_returns = crypto.pct_change(axis=0) # daily returns
      crypto_returns
```

```
[5]:
```

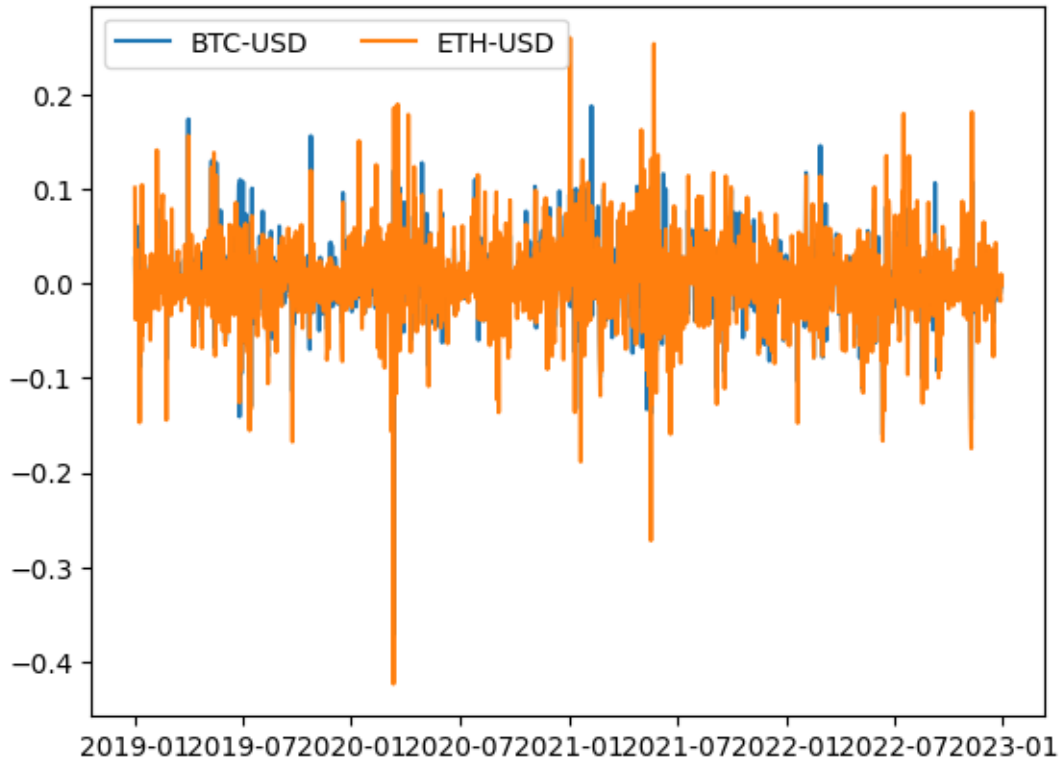
	BTC-USD	ETH-USD
Date		
2019-01-01	NaN	NaN
2019-01-02	0.025989	0.101039
2019-01-03	-0.027050	-0.038135
2019-01-04	0.005467	0.036523
2019-01-05	-0.003246	0.006836
...
2022-12-26	0.004620	0.006573
2022-12-27	-0.011976	-0.011559
2022-12-28	-0.009846	-0.018804
2022-12-29	0.005423	0.009756
2022-12-30	-0.002389	-0.001966

```
[1460 rows x 2 columns]
```

```
[6]: plt.plot(crypto_returns.index, crypto_returns.mean(axis=1))  
plt.show()
```



```
[7]: plt.plot(crypto_returns.index, crypto_returns)  
plt.legend(crypto_tickers, loc='upper left', ncol=3)  
plt.show()
```



2.0.2 Collect index tickers

```
[8]: index_tickers = ['^GSPC', '^IXIC']

indices = pd.DataFrame()

for tick in index_tickers:
    ydata = yf.download(tick, start = '2019-01-01', end = '2022-12-31')
    indices[tick] = ydata['Adj Close']

indices.index = pd.to_datetime(ydata.index, format='%Y%m%d')

indices.head()
```

```
[*****100%*****] 1 of 1 completed
[*****100%*****] 1 of 1 completed
```

```
[8]:           ^GSPC           ^IXIC
Date
2019-01-02  2510.030029  6665.939941
2019-01-03  2447.889893  6463.500000
```

```

2019-01-04    2531.939941    6738.859863
2019-01-07    2549.689941    6823.470215
2019-01-08    2574.409912    6897.000000

```

```
[9]: indices.describe()
```

```

[9]:          ^GSPC          ^IXIC
count    1008.000000    1008.000000
mean      3624.904483    11184.147952
std        634.328208    2630.880711
min       2237.399902    6463.500000
25%       3005.232483    8518.844971
50%       3678.189941    11187.955078
75%       4180.419922    13539.997559
max       4796.560059    16057.440430

```

```

[10]: indices_returns = indices.pct_change(axis=0) # daily returns
      indices_returns = indices_returns.dropna()
      indices_returns

```

```

[10]:          ^GSPC          ^IXIC
Date
2019-01-03 -0.024757 -0.030369
2019-01-04  0.034336  0.042602
2019-01-07  0.007010  0.012556
2019-01-08  0.009695  0.010776
2019-01-09  0.004098  0.008711
...
2022-12-23  0.005868  0.002075
2022-12-27 -0.004050 -0.013777
2022-12-28 -0.012021 -0.013517
2022-12-29  0.017461  0.025927
2022-12-30 -0.002541 -0.001108

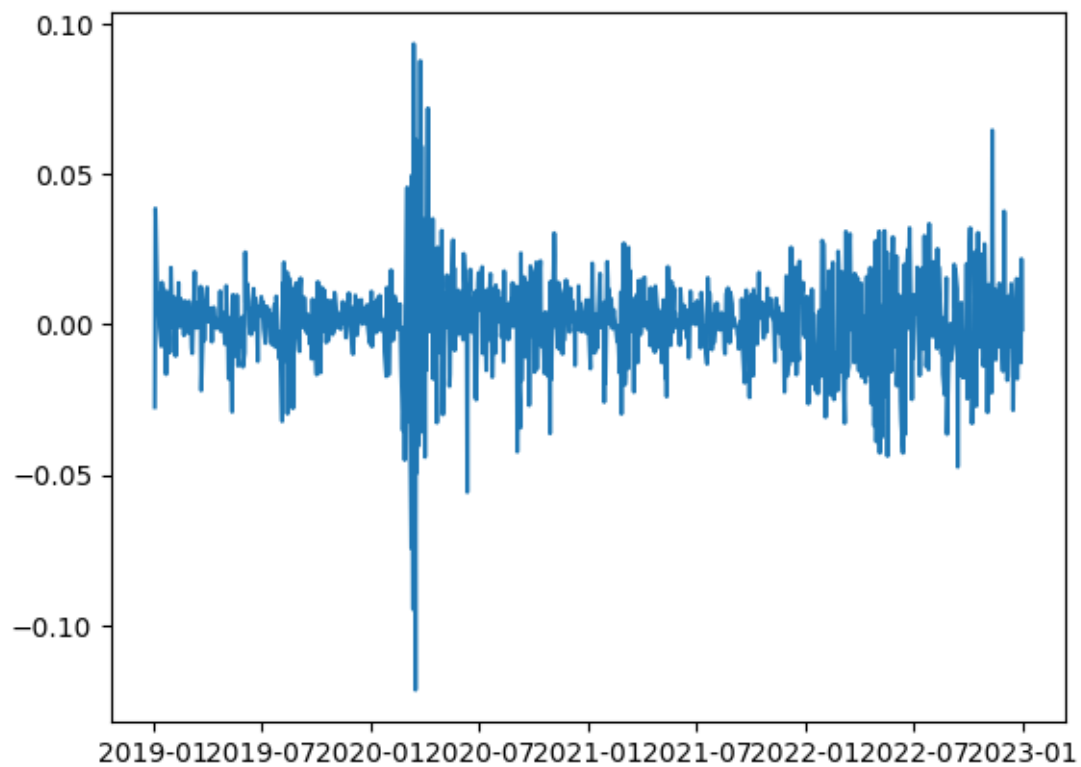
```

```
[1007 rows x 2 columns]
```

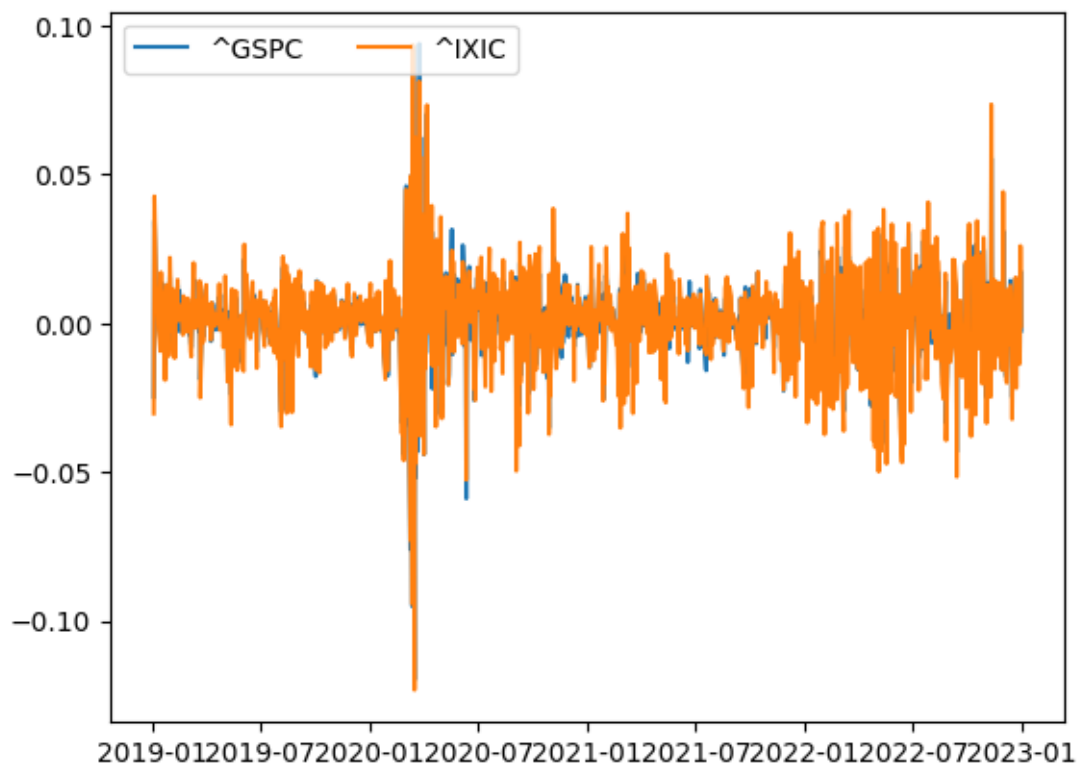
```

[11]: plt.plot(indices_returns.index, indices_returns.mean(axis=1))
      plt.show()

```



```
[12]: plt.plot(indices_returns.index, indices_returns)
plt.legend(index_tickers, loc='upper left', ncol=3)
plt.show()
```



2.0.3 Collect currency tickers

```
[13]: currency_tickers = ['EURUSD=X', 'GBPJPY=X', 'CADUSD=X']

currencies = pd.DataFrame()

for tick in currency_tickers:
    ydata = yf.download(tick, start = '2019-01-01', end = '2022-12-31')
    currencies[tick] = ydata['Adj Close']

currencies.index = pd.to_datetime(ydata.index, format='%Y%m%d')
currencies.columns = [['EURUSD', 'GBPJPY', 'CADUSD']]

currencies.head()
```

```
[*****100%*****] 1 of 1 completed
[*****100%*****] 1 of 1 completed
[*****100%*****] 1 of 1 completed
```

```
[13]:      EURUSD      GBPJPY      CADUSD
Date
```


2019-01-01	1.149306	139.600006	0.746586
2019-01-02	1.146171	139.858002	0.733923
2019-01-03	1.131811	134.483994	0.733611
2019-01-04	1.139108	136.141006	0.741906
2019-01-07	1.141044	138.182999	0.747982

```
[14]: currencies.describe()
```

```
[14]:
```

	EURUSD	GBPJPY	CADUSD
count	1043.000000	1043.000000	1043.000000
mean	1.124730	147.278955	0.766809
std	0.059639	10.907987	0.026508
min	0.959619	125.961998	0.689741
25%	1.096263	138.264000	0.749963
50%	1.125885	145.481995	0.763068
75%	1.176516	155.070000	0.787730
max	1.234111	171.376007	0.830703

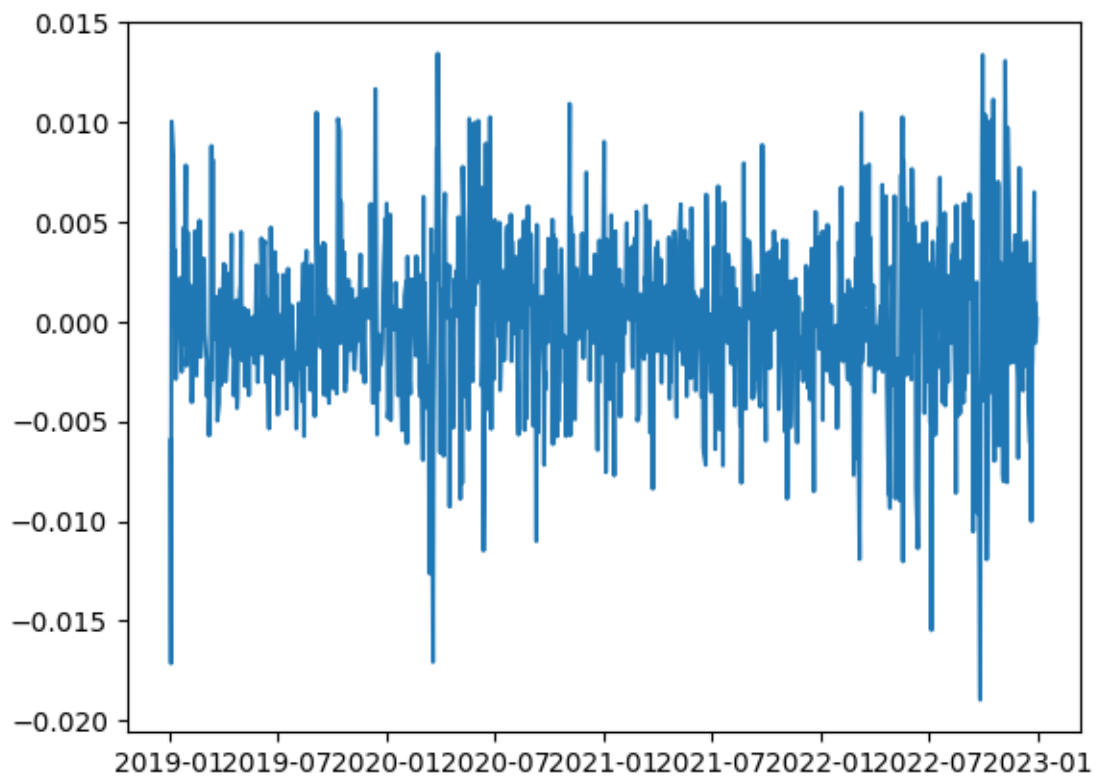
```
[15]: currencies_returns = currencies.pct_change(axis=0) # daily returns
currencies_returns
```

```
[15]:
```

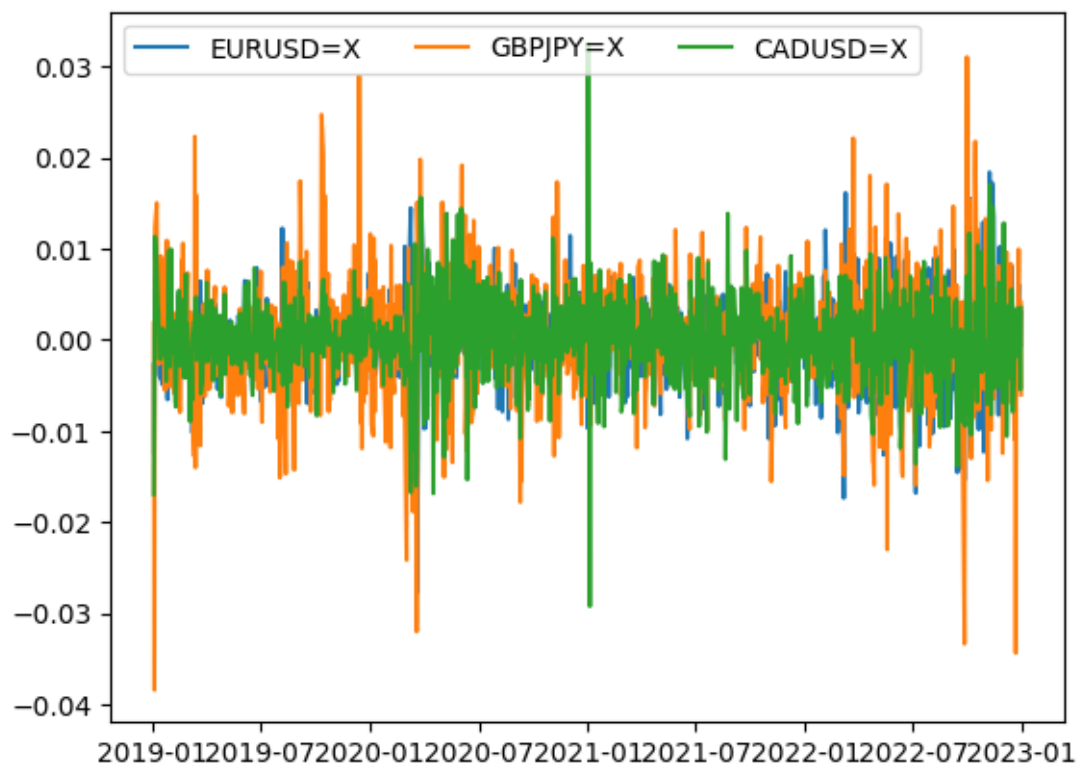
	EURUSD	GBPJPY	CADUSD
Date			
2019-01-01	NaN	NaN	NaN
2019-01-02	-0.002728	0.001848	-0.016961
2019-01-03	-0.012529	-0.038425	-0.000425
2019-01-04	0.006447	0.012321	0.011307
2019-01-07	0.001700	0.014999	0.008190
...
2022-12-26	0.006081	0.009918	0.003466
2022-12-27	-0.002586	-0.003102	0.002412
2022-12-28	-0.000287	0.000723	0.002366
2022-12-29	-0.000744	0.004243	-0.005471
2022-12-30	0.002964	-0.006030	0.003498

[1043 rows x 3 columns]

```
[16]: plt.plot(currencies_returns.index, currencies_returns.mean(axis=1))
plt.show()
```



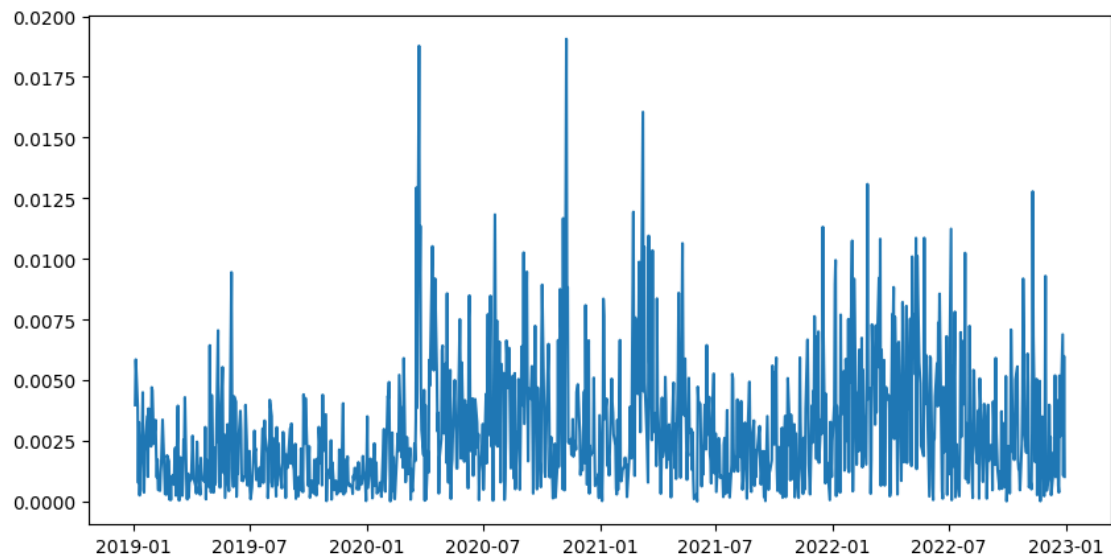
```
[17]: plt.plot(currencies_returns.index, currencies_returns)
plt.legend(currency_tickers, loc='upper left', ncol=3)
plt.show()
```



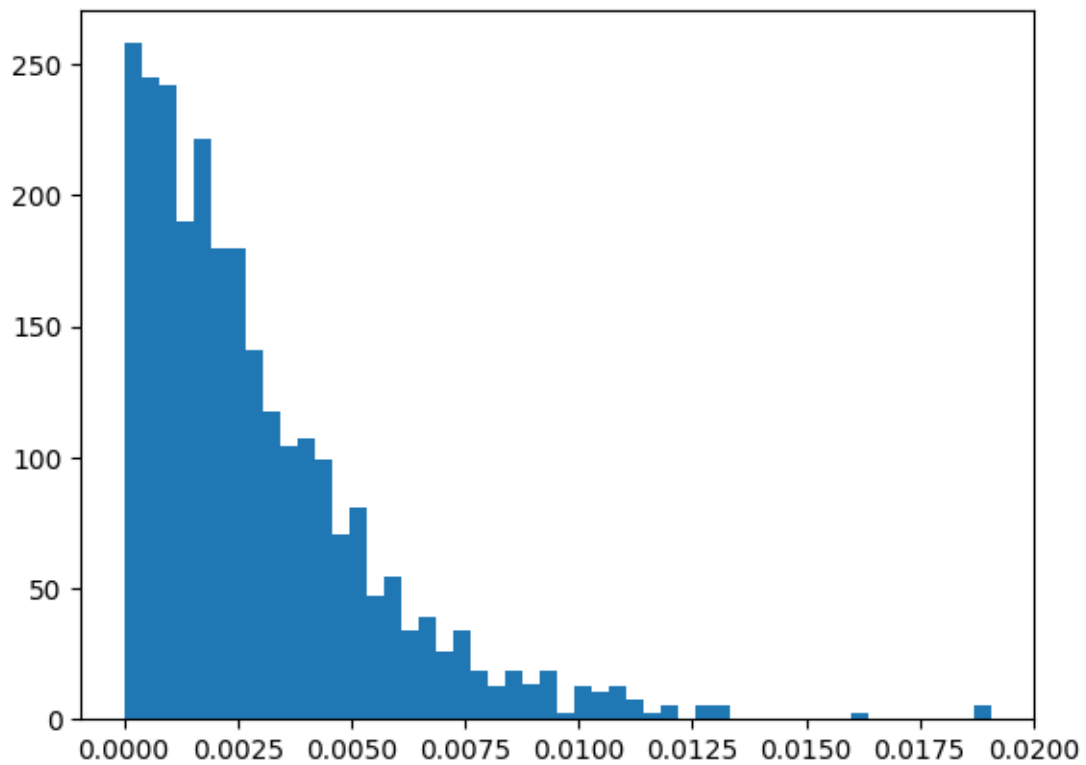
3 Part 2

3.0.1 a. Dispersion of the returns

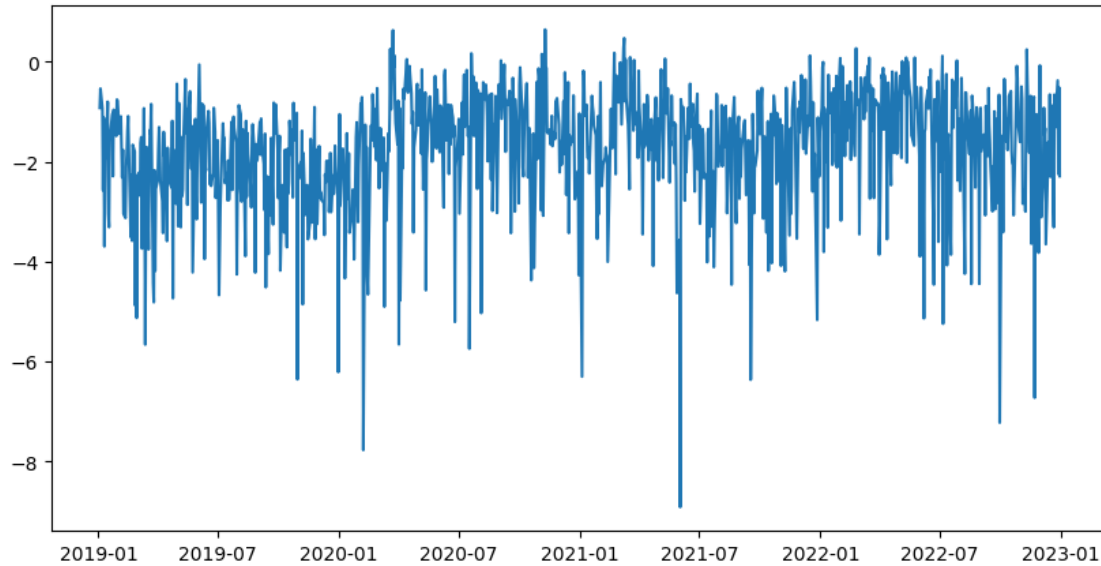
```
[18]: df = indices_returns.std(axis=1)
df = df.dropna(axis=0)
plt.figure(figsize=(10,5))
plt.plot(df.index, df)
plt.show()
```



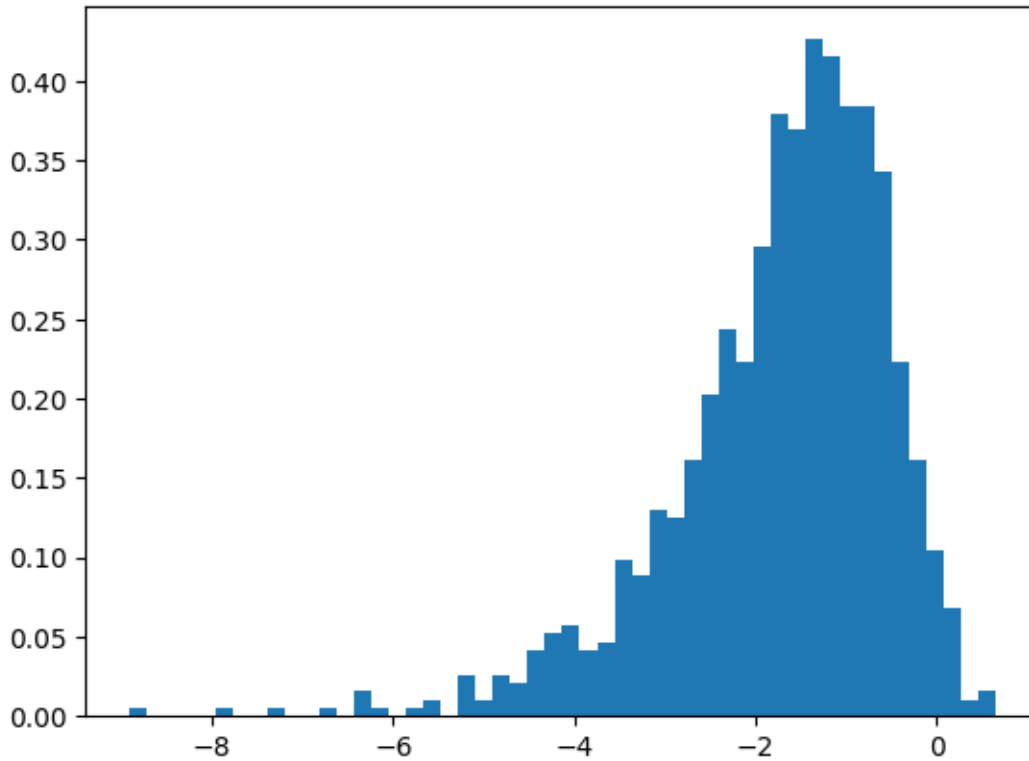
```
[19]: count, bins, ignored = plt.hist(df, 50, density=True)  
plt.show()
```



```
[20]: df= np.log(100*df)
plt.figure(figsize=(10,5))
plt.plot(df.index, df)
plt.show()
```



```
[21]: count, bins, ignored = plt.hist(df, 50, density=True)
plt.show()
```



Define the cross-sectional dispersion in crypto returns as:

$t = et$

where et follows a normal distribution with mean i and variance $2i$. The realization of the vector $\{i, i\}$ depends itself on the realization of a Hidden Markov process.

3.0.2 Define functions

```
[22]: # likelihood of an estimation
def likelihood(xi_prob, mu, sigma, y):
    phi = norm.pdf((y-mu)/sigma)/sigma
    y_like=np.dot(xi_prob, phi)
    return y_like, phi
```

```
[23]: # Hamilton filtering correction
def forward_alg(pi0, N, T, P, mu, sigma, Y):
    # pi0: initial distribution
    # N: number of states in the Markov process
    # T: Length of time series
    # mu: expected realizations of random variables
    # sigma: volatilities of realizations of random variable
    # Y: time series
```

```

xi_prob_t = np.zeros((T, N))
xi_prob_t1 = np.zeros((T, N))

# Case t=1
y_like, phi = likelihood(pi0, mu, sigma, Y[0])
# xi_1/1
xi_prob_t[0,:] = np.multiply(pi0, phi) / y_like
# xi_2/1
for ss in range(0, N):
    xi_prob_t1[0, ss] = np.dot(P[:, ss], xi_prob_t[0, :])
# Case t > 1
for tt in range(1, T):
    y_like, phi = likelihood(xi_prob_t1[tt - 1, :], mu, sigma, Y[tt])

    xi_prob_t[tt, :] = np.multiply(xi_prob_t1[tt - 1, :], phi) / y_like
    for ss in range(0, N):
        xi_prob_t1[tt, ss] = np.dot(P[:, ss], xi_prob_t[tt, :])

return xi_prob_t, xi_prob_t1

```

```

[24]: # Kim filtering
def backward_alg(xi_prob_t, xi_prob_t1, N, T, P):
    xi_prob_T = np.zeros((T, N))

    #xi_T/t <-- last element computed in Forward algorithm
    xi_prob_T[T - 1, :] = xi_prob_t[T - 1, :]

    #xi_t/T
    for tt in range(T - 2, -1, -1):
        xi_T_xi = np.divide(xi_prob_T[tt + 1, :], xi_prob_t1[tt, :])
        for ss in range(0, N):
            xi_prob_T[tt, ss] = xi_prob_t[tt, ss] * np.dot(P[ss, :], xi_T_xi)

    return xi_prob_T # , xi_prob_T1

```

3.0.3 b. Estimate a Markov-regime switching model for the selected financial time series. Estimate the model under different assumptions:

i) Different number of states N

```

[25]: # Initialize parameters
T = len(df) # length of time-series
N = 4 # Number of states

# SET INITIAL GUESSES

mu_hat0 = [-0.1, 0, 0.5, 1] * np.ones((N)) #expectation parameters of  $\mu$ 
        ↪ the distribution

```

```

sigma_hat0 = [0.1, 0.1, 0.1, 0.1] * np.ones((N))
P_hat0 = np.zeros((N, N))

P_hat0[0, 0] = 0.75
P_hat0[0, 1] = 0.15
P_hat0[0, 2] = 0.1
P_hat0[0, 3] = 0

P_hat0[1, 0] = 0.1
P_hat0[1, 1] = 0.75
P_hat0[1, 2] = 0.1
P_hat0[1, 3] = 0.05

P_hat0[2, 0] = 0.05
P_hat0[2, 1] = 0.1
P_hat0[2, 2] = 0.75
P_hat0[2, 3] = 0.1

P_hat0[3, 0] = 0
P_hat0[3, 1] = 0.1
P_hat0[3, 2] = 0.15
P_hat0[3, 3] = 0.75

```

```

[26]: # Ster as initial probability the stationary distribution
pi_hat0 = [0.5, 0.5, 0.5, 0.5] * np.ones((N))
for t in range(1, 100):
    pi_hat0 = np.dot(P_hat0.T, pi_hat0)

```

ii. Allowing the expected realization of the time series to differ across states (different “mus”), but with constant variance (same “sigma”).

```

[27]: # Initialize parameters
T = len(df) # length of time-series
N = 2 # Number of states

# SET INITIAL GUESSES

mu_hat0 = [2, 4] * np.ones((N)) #expectation parameters of the
    ↪ distribution
sigma_hat0 = 0.1

```

```

[28]: def M_step_func_v2(xi_prob, P, N, T, Y):

    # Initialize estimates
    mu_hat = np.zeros((N))
    sigma_hat = 0 #np.zeros((N))
    P_hat = np.zeros((N, N))

```



```

pi_hat = np.zeros((N))

for ss in range(0, N):
    # New estimates for "mu"
    xi_y = np.dot(xi_prob[:, ss], Y)
    mu_hat[ss] = xi_y / np.sum(xi_prob[:, ss])

    xi_y_mu2 = np.dot(xi_prob[:, ss], (Y - mu_hat[ss]) ** 2)
    # New estimates for "sigma"
    sigma_hat += xi_y_mu2

    # New estimates for transition matrix
    for ss2 in range(0, N):
        P_hat[ss, ss2] = np.sum(P[ss, ss2, 1:]) / np.sum(P[ss, :, 1:])
    pi_hat[ss] = xi_prob[0,ss]

    # New estimation for initial probabilities
    sigma_hat = np.sqrt(sigma_hat/T)

return mu_hat, sigma_hat, P_hat, pi_hat

```

iii. Allowing the variance of the time series to change across states (different “sigmas”), but with constant expectation (same “mu”).

```

[29]: # Initialize parameters
T = len(df) # length of time-series
N = 2 # Number

# SET INITIAL GUESSES

mu_hat0 = 0 #expectation parameters of the distribution
sigma_hat0 = [0.1, 0.1] * np.ones((N))

```

```

[30]: def M_step_func_v3(xi_prob, sigma_hat_prev, P, N, T, Y):
    # Initialize estimates

    sigma_hat = np.zeros((N))
    P_hat = np.zeros((N, N))
    pi_hat = np.zeros((N))

    xi_y_sigma = np.zeros((N))
    xi_sigma = np.zeros((N))

    for ss in range(0, N):
        # New estimates for "mu"
        xi_y_sigma[ss] = np.dot(xi_prob[:, ss], Y)/sigma_hat_prev[ss]
        xi_sigma[ss] = np.sum(xi_y_sigma)/np.sum(xi_sigma)

```

```

mu_hat = np.sum(xi_y_sigma) / np.sum(xi_sigma)

for ss in range(0, N):
    # New estimates for "sigma"
    xi_y_mu2 = np.dot(xi_prob[:, ss], (Y - mu_hat) ** 2)
    sigma_hat[ss] = (xi_y_mu2 / np.sum(xi_prob[:, ss])) ** 0.5

    # New estimates for transition matrix
    for ss2 in range(0, N):
        P_hat[ss, ss2] = np.sum(P[ss, ss2, 1:]) / np.sum(P[ss, :, 1:])
    pi_hat[ss] = xi_prob[0, ss] # New estimation for initial
    ↪probabilities

return mu_hat, sigma_hat, P_hat, pi_hat

```

iv. Allowing for different expectations and variances across states.

```

[31]: # Initialize parameters
T = len(df) # length of time-series
N = 2 # Number of states

# SET INITIAL GUESSES

mu_hat0 = [2, 4] * np.ones((N)) #expectation parameters of the
    ↪distribution
sigma_hat0 = [0.1, 0.1] * np.ones((N))

```

```

[32]: def M_step_func_v4(xi_prob, P, N, T, Y):
    # Initialize estimates
    mu_hat = np.zeros((N))
    sigma_hat = np.zeros((N))
    P_hat = np.zeros((N, N))
    pi_hat = np.zeros((N))

    xi_y_sigma = np.zeros((N))
    xi_sigma = np.zeros((N))

    for ss in range(0, N):
        # New estimates for "mu"
        xi_y = np.dot(xi_prob[:, ss], Y)
        mu_hat[ss] = xi_y / np.sum(xi_prob[:, ss])
        # New estimates for "sigma"
        xi_y_mu2 = np.dot(xi_prob[:, ss], (Y - mu_hat) ** 2)
        sigma_hat[ss] = (xi_y_mu2 / np.sum(xi_prob[:, ss])) ** 0.5

        # New estimates for transition matrix
        for ss2 in range(0, N):

```

```

        P_hat[ss, ss2] = np.sum(P[ss, ss2, 1:]) / np.sum(P[ss, :, 1:])
        pi_hat[ss] = xi_prob[0, ss]    # New estimation for initial
        ↪probabilities

    return mu_hat, sigma_hat, P_hat, pi_hat

```

4 STEP 3

4.0.1 Define a function that calculate the likelihood probability

```

[33]: def log_likelihood2(xi_prob, T, pi_hat0, P, mu, sigma, Y):
    y_like = np.zeros(T)
    for tt in range(0, T):
        y_like[tt], _ = likelihood(xi_prob[tt, :], mu, sigma, Y[tt])

    sum_log_like = np.sum(np.log(y_like))
    k = (np.prod(mu.shape) + np.prod(sigma.shape))
    k += (np.prod(pi_hat0.shape) + np.prod(P.shape))
    n = len(Y)
    akaike = 2 * k - 2 * sum_log_like
    schwarz = k * np.log(n) - 2 * sum_log_like
    return sum_log_like, akaike, schwarz

```

4.0.2 Estimate the model parameters for same sigma different mus

```

[34]: # Initialize parameters
T = len(df) # length of time-series
N = 2 # Number

# SET INITIAL GUESSES

mu_hat0 = [-1, -2] * np.ones((N))    #expectation parameters of the
    ↪distribution
sigma_hat0 = [0.5, 0.5] * np.ones((N))
P_hat0 = np.zeros((N, N))

P_hat0[0, 0] = 0.75
P_hat0[0, 1] = 1 - P_hat0[0, 0]
P_hat0[1, 1] = 0.7
P_hat0[1, 0] = 1 - P_hat0[1, 1]

# Ster as initial probability the stationary distribution
pi_hat0 = [0.5, 0.5] * np.ones((N))
for t in range(1, 100):
    pi_hat0 = np.dot(P_hat0.T, pi_hat0)

```

```

    # Determine maximum number of iterations until convergence and convergence
    ↪tolerance
itemax = 200      #number of steps
itetol = 1e-4    #convergence tolerance parameter
log_like0 = -1e8
for ite in range(0, itemax):
    print(mu_hat0, sigma_hat0, P_hat0, pi_hat0)

    # Expectation step
    xi_prob_t, xi_prob_t1 = forward_alg(
        pi_hat0, N, T, P_hat0, mu_hat0, sigma_hat0, df
    )
    xi_prob_T = backward_alg(
        xi_prob_t, xi_prob_t1, N, T, P_hat0
    )

    print("")
    plt.subplot(1, 2, 1)
    plt.plot(xi_prob_T[:, 0])
    plt.title("Estimated probability of state 0")
    plt.subplot(1, 2, 2)
    plt.plot(xi_prob_T[:, 1])
    plt.title("Estimated probability of state 1")
    fig = plt.gcf()
    fig.set_size_inches(16, 6)
    plt.show()
    print("")

    # Compute  $Pr(s_{t+1} = j, s_t = i)$ 
    P_hat_T = np.zeros((N, N, T))
    for tt in range(1, T):
        for ss in range(0, N):
            for ss2 in range(0, N):
                P_hat_T[ss, ss2, tt] = (
                    P_hat0[ss, ss2]
                    * xi_prob_t[tt - 1, ss]
                    * xi_prob_T[tt, ss2]
                    / xi_prob_t1[tt - 1, ss2]
                )

    # Instead of checking estimates we only check likelihood
    log_like1, akaike, schwarz = log_likelihood2(np.concatenate(([pi_hat0],
    ↪xi_prob_t1[0:T-1])),
                                                    T, pi_hat0, P_hat0, mu_hat0,
    ↪sigma_hat0, df)
    diff = (log_like1 - log_like0)/abs(log_like0 + 1e-3)
    print("Iteration: ", ite)

```

```

print("Log-Likelihood: ", np.round(log_like1, 4), "Change: ", np.
↪round(diff,4))

# Stop when the difference in likelihood between steps decreases

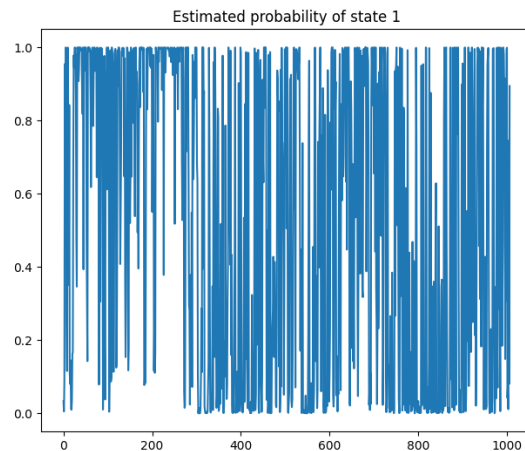
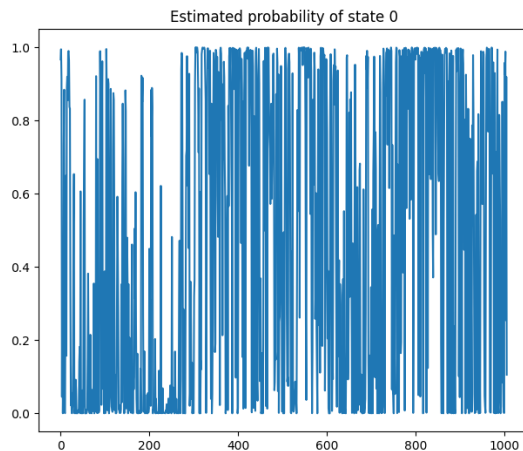
if diff > itetol :
    # M-step
    mu_hat0, sigma_hat0, P_hat0, pi_hat0 = M_step_func_v2(xi_prob_T, ↪
↪P_hat_T, N, T, df)
    log_like0 = log_like1
else:
    print("Final Estimates")
    print("Log-Likelihood: ", np.round(log_like1,4),
        "Akaike: ", np.round(akaike,4),
        "Schwarz: ", np.round(schwarz,4))
    print("Mu: ", np.round(mu_hat0,4))
    print("Sigma: ", np.round(sigma_hat0,4))
    print("Transition matrix: ")
    for ss in range(N):
        print(np.round(P_hat0[ss,:],4))
    print("Initial probabilities:", np.round(pi_hat0,4))
    break

```

```

[-1. -2.] [0.5 0.5] [[0.75 0.25]
[0.3  0.7 ]] [0.54545455 0.45454545]

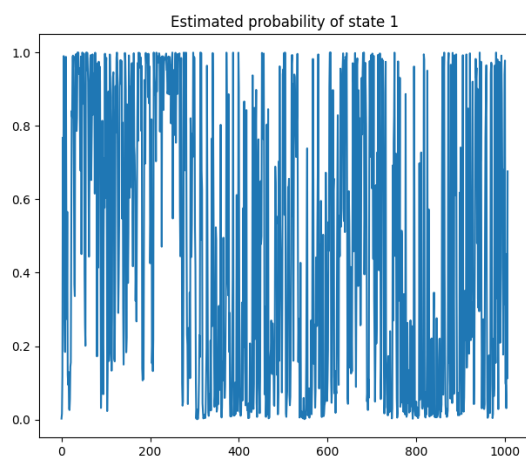
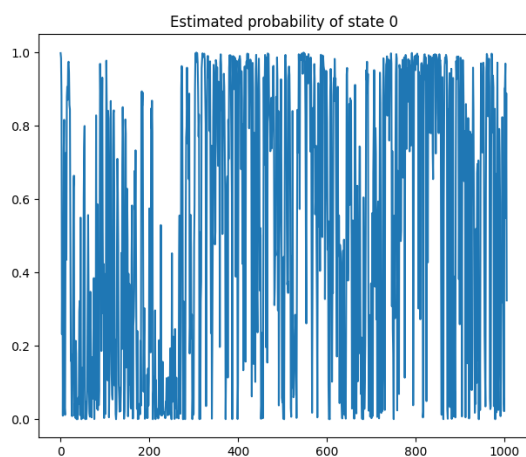
```



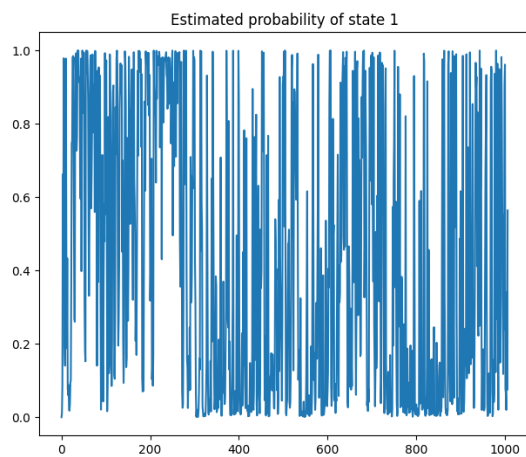
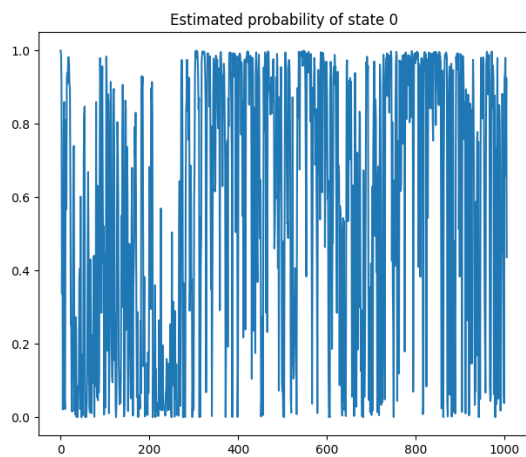
```

Iteration:  0
Log-Likelihood:  -2447.5692 Change:  1.0
[-0.89684131 -2.48894476] 0.8089707946939014 [[0.7005503  0.2994497 ]
[0.27862145 0.72137855]] [0.96696903 0.03303097]

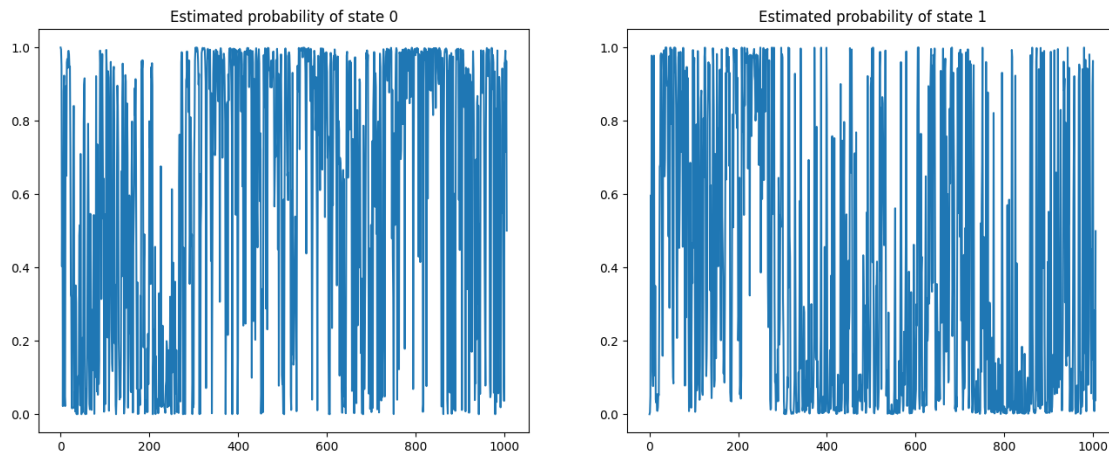
```



```
Iteration: 1
Log-Likelihood: -1651.1141 Change: 0.3254
[-1.02179855 -2.5344891 ] 0.8028927032821297 [[0.74009056 0.25990944]
[0.30215613 0.69784387]] [0.99774394 0.00225606]
```



```
Iteration: 2
Log-Likelihood: -1636.5578 Change: 0.0088
[-1.07916571 -2.62668355] 0.7695908518049503 [[0.7683363 0.2316637]
[0.3267784 0.6732216]] [9.99867752e-01 1.32247706e-04]
```



```

Iteration: 3
Log-Likelihood: -1638.8315 Change: -0.0014
Final Estimates
Log-Likelihood: -1638.8315 Akaike: 3295.663 Schwarz: 3339.8956
Mu: [-1.0792 -2.6267]
Sigma: 0.7696
Transition matrix:
[0.7683 0.2317]
[0.3268 0.6732]
Initial probabilities: [9.999e-01 1.000e-04]

```

4.0.3 Estimate the model parameters for different sigma same mus

```

[35]: # Initialize parameters
T = len(df) # length of time-series
N = 2 # Number

# SET INITIAL GUESSES

mu_hat0 = [-1, -2] * np.ones((N)) #expectation parameters of the
↪distribution
sigma_hat0 = [0.5, 0.5] * np.ones((N))
P_hat0 = np.zeros((N, N))

P_hat0[0, 0] = 0.75
P_hat0[0, 1] = 1 - P_hat0[0, 0]
P_hat0[1, 1] = 0.7
P_hat0[1, 0] = 1 - P_hat0[1, 1]

# Ster as initial probability the stationary distribution

```

```

pi_hat0 = [0.5, 0.5] * np.ones((N))
for t in range(1, 100):
    pi_hat0 = np.dot(P_hat0.T, pi_hat0)

    # Determine maximum number of iterations until convergence and convergence
    ↪tolerance
itemax = 200    #number of steps
itetol = 1e-4   #convergence tolerance parameter
log_like0 = -1e8
for ite in range(0, itemax):
    print(mu_hat0, sigma_hat0, P_hat0, pi_hat0)

    # Expectation step
    xi_prob_t, xi_prob_t1 = forward_alg(
        pi_hat0, N, T, P_hat0, mu_hat0, sigma_hat0, df
    )
    xi_prob_T = backward_alg(
        xi_prob_t, xi_prob_t1, N, T, P_hat0
    )

    print("")
    plt.subplot(1, 2, 1)
    plt.plot(xi_prob_T[:, 0])
    plt.title("Estimated probability of state 0")
    plt.subplot(1, 2, 2)
    plt.plot(xi_prob_T[:, 1])
    plt.title("Estimated probability of state 1")
    fig = plt.gcf()
    fig.set_size_inches(16, 6)
    plt.show()
    print("")

    # Compute  $Pr(s_{t+1} = j, s_t = i)$ 
    P_hat_T = np.zeros((N, N, T))
    for tt in range(1, T):
        for ss in range(0, N):
            for ss2 in range(0, N):
                P_hat_T[ss, ss2, tt] = (
                    P_hat0[ss, ss2]
                    * xi_prob_t[tt - 1, ss]
                    * xi_prob_T[tt, ss2]
                    / xi_prob_t1[tt - 1, ss2]
                )

    # Instead of checking estimates we only check likelihood
    log_like1, akaike, schwarz = log_likelihood2(np.concatenate((pi_hat0,
    ↪xi_prob_t1[0:T-1])),

```



```

T, pi_hat0, P_hat0, mu_hat0,
sigma_hat0, df)
diff = (log_like1 - log_like0)/abs(log_like0 + 1e-3)
print("Iteration: ", ite)
print("Log-Likelihood: ", np.round(log_like1, 4), "Change: ", np.
round(diff,4))

# Stop when the difference in likelihood between steps decreases

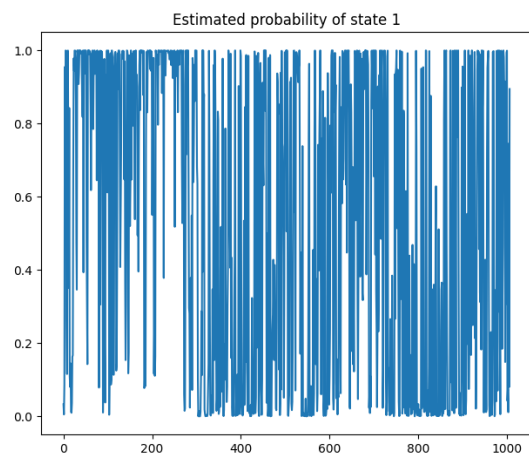
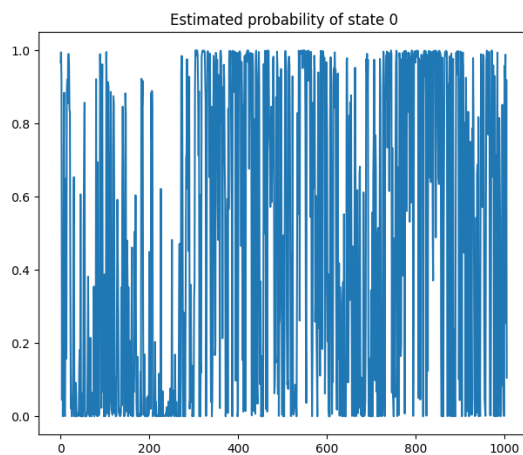
if diff > itetol :
    # M-step
    mu_hat0, sigma_hat0, P_hat0, pi_hat0 = M_step_func_v3(xi_prob_T,
sigma_hat0, P_hat_T, N, T, df)
    log_like0 = log_like1
else:
    print("Final Estimates")
    print("Log-Likelihood: ", np.round(log_like1,4),
        "Akaike: ", np.round(akaike,4),
        "Schwarz: ", np.round(schwarz,4))
    print("Mu: ", np.round(mu_hat0,4))
    print("Sigma: ", np.round(sigma_hat0,4))
    print("Transition matrix: ")
    for ss in range(N):
        print(np.round(P_hat0[ss,:],4))
    print("Initial probabilities:", np.round(pi_hat0,4))
    break

```

```

[-1. -2.] [0.5 0.5] [[0.75 0.25]
[0.3 0.7 ]] [0.54545455 0.45454545]

```

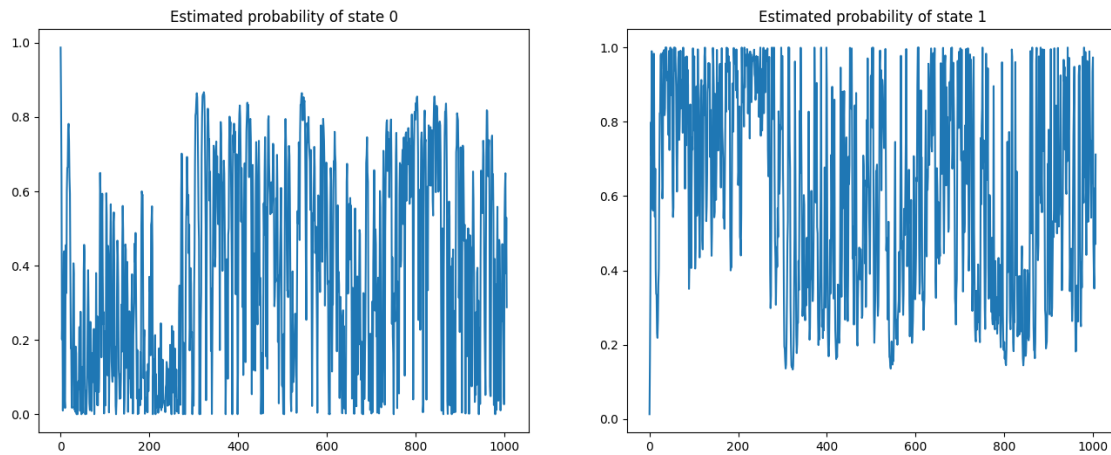


```

Iteration: 0
Log-Likelihood: -2447.5692 Change: 1.0
0.0 [1.04564117 2.73133295] [[0.7005503 0.2994497 ]
 [0.27862145 0.72137855]] [0.96696903 0.03303097]

<ipython-input-30-85de5dfb54d5>:14: RuntimeWarning: divide by zero encountered
in double_scalars
xi_sigma[ss] = np.sum(xi_y_sigma)/np.sum(xi_sigma)

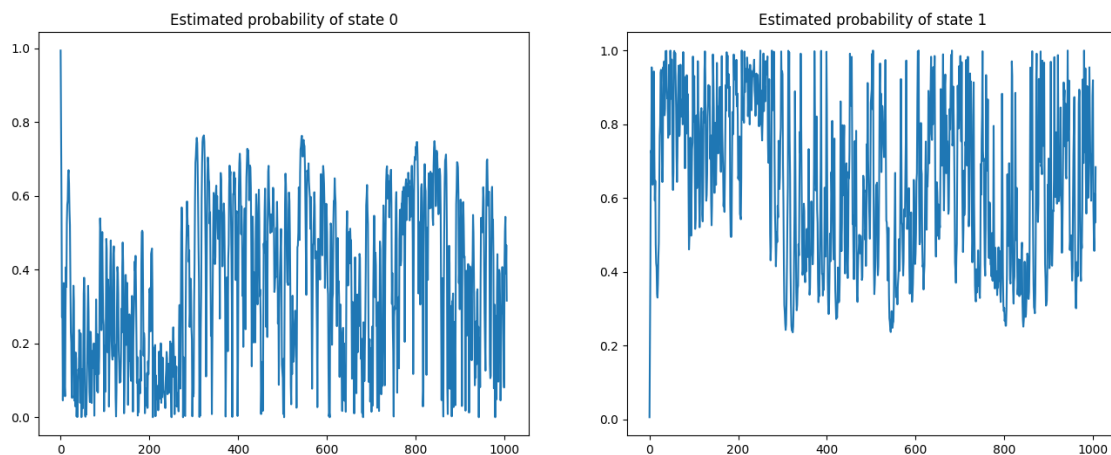
```



```

Iteration: 1
Log-Likelihood: -2221.4357 Change: 0.0924
0.0 [1.24047547 2.4958693 ] [[0.66377504 0.33622496]
 [0.21693588 0.78306412]] [0.9872404 0.0127596]

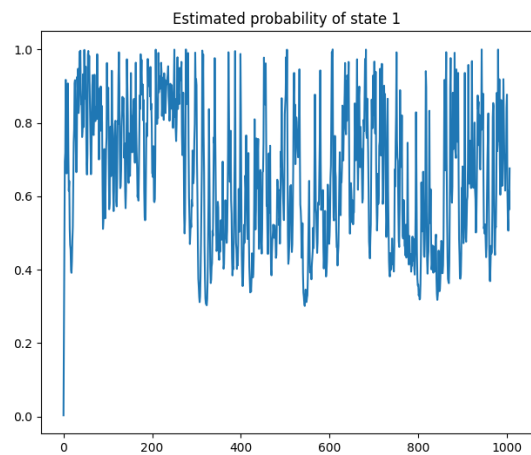
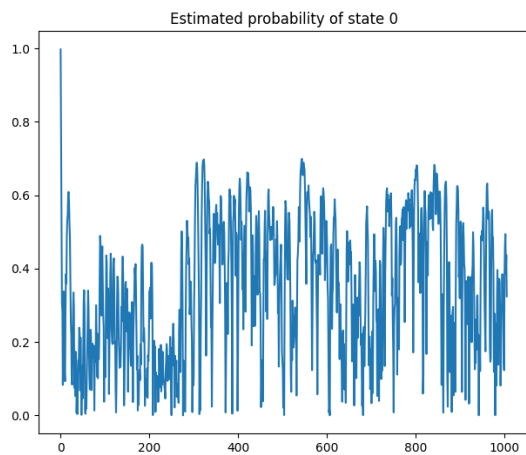
```



Iteration: 2

Log-Likelihood: -2185.49 Change: 0.0162

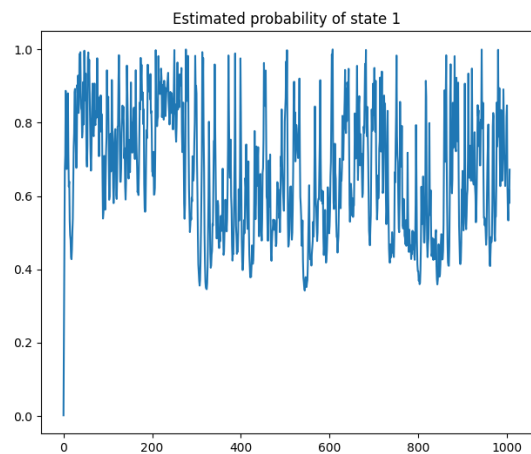
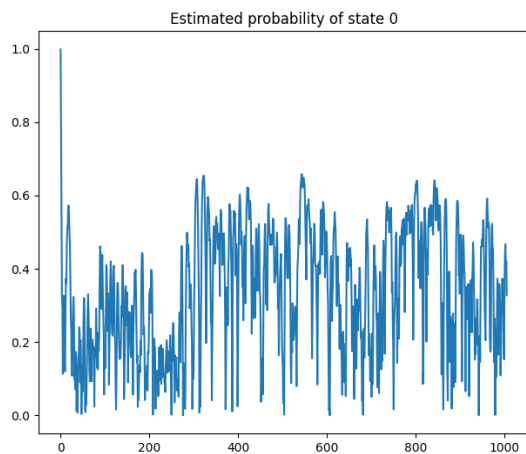
0.0 [1.35937525 2.41128623] [[0.65735869 0.34264131]
[0.19213371 0.80786629]] [0.99415341 0.00584659]



Iteration: 3

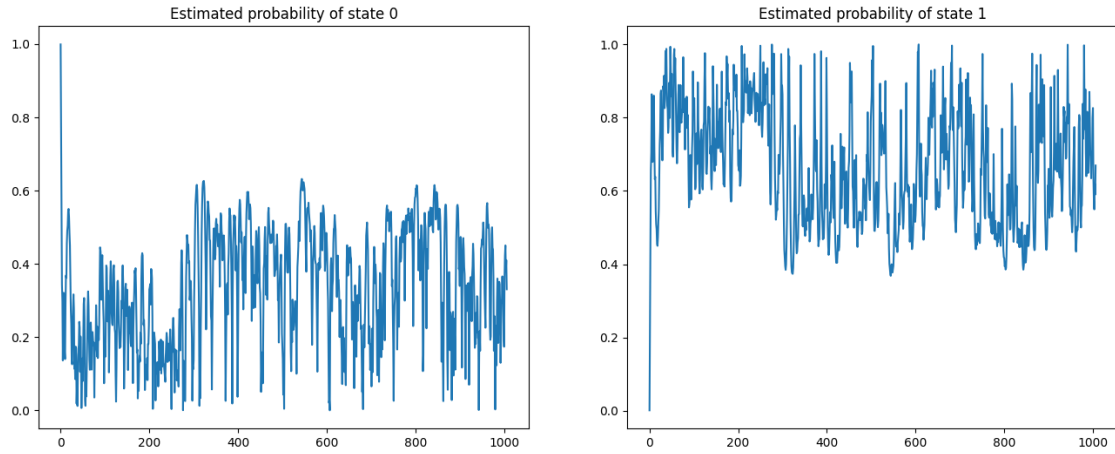
Log-Likelihood: -2177.2694 Change: 0.0038

0.0 [1.4388722 2.36759205] [[0.65933319 0.34066681]
[0.17875342 0.82124658]] [0.99702998 0.00297002]

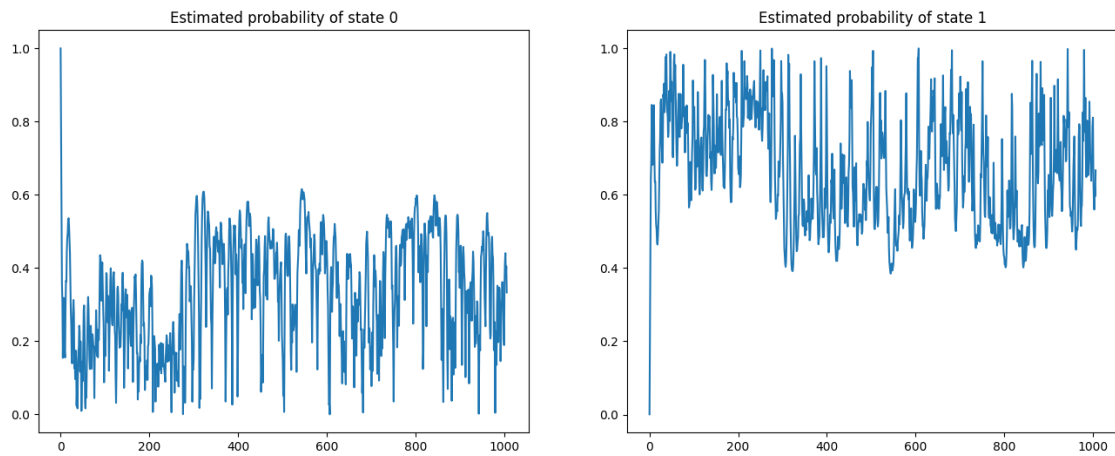


Iteration: 4

Log-Likelihood: -2174.332 Change: 0.0013
0.0 [1.49453004 2.34126581] [[0.66423843 0.33576157]
[0.1702678 0.8297322]] [0.99838479 0.00161521]

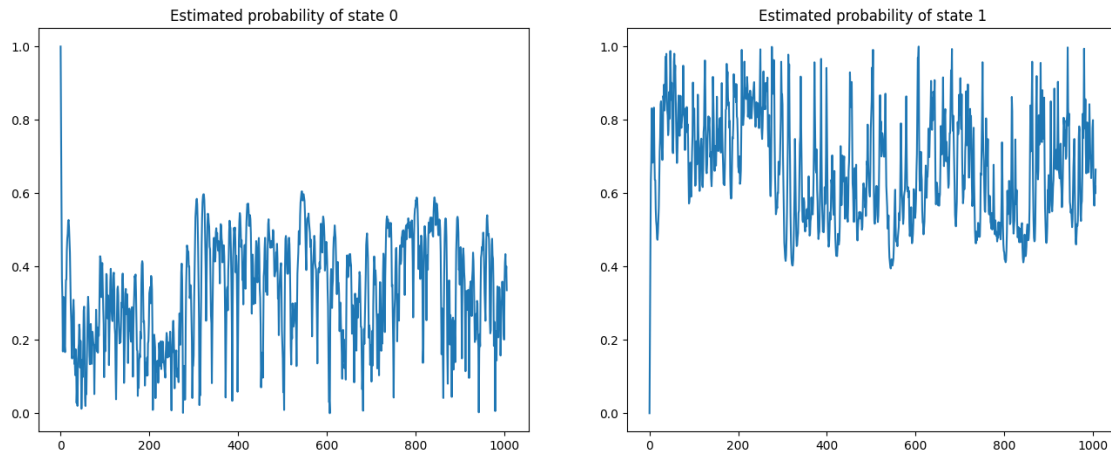


Iteration: 5
Log-Likelihood: -2173.0186 Change: 0.0006
0.0 [1.53453007 2.32417132] [[0.67028357 0.32971643]
[0.16427205 0.83572795]] [9.99079194e-01 9.20805974e-04]



Iteration: 6
Log-Likelihood: -2172.3393 Change: 0.0003
0.0 [1.56369077 2.31268673] [[0.67679479 0.32320521]

[0.15968318 0.84031682]] [9.99457264e-01 5.42736084e-04]

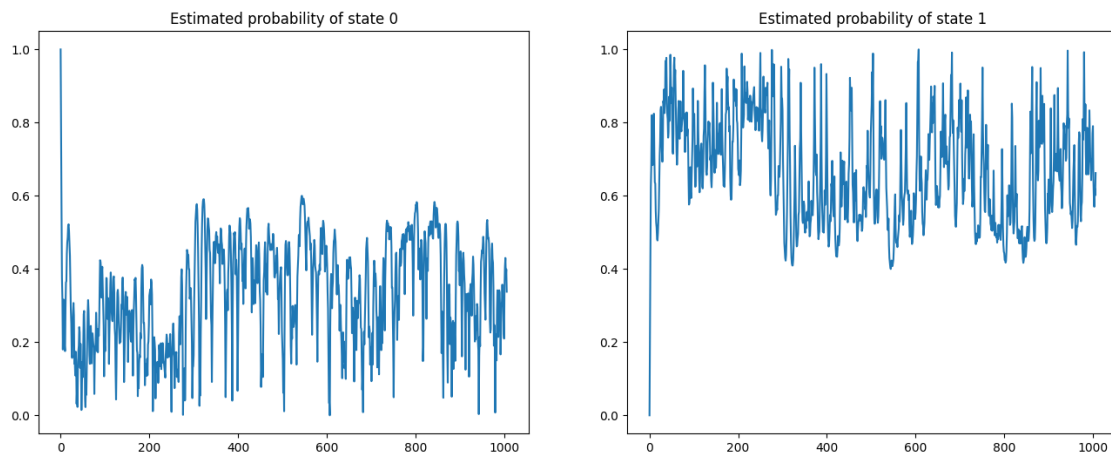


Iteration: 7

Log-Likelihood: -2171.9448 Change: 0.0002

0.0 [1.58505817 2.30492471] [[0.68350379 0.31649621]

[0.15594507 0.84405493]] [9.99672394e-01 3.27606134e-04]

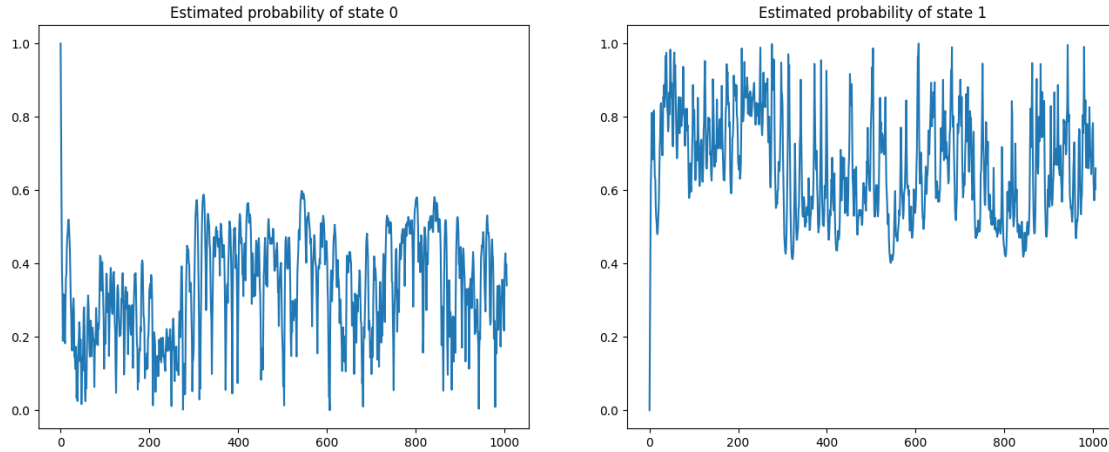


Iteration: 8

Log-Likelihood: -2171.69 Change: 0.0001

0.0 [1.60065423 2.29979122] [[0.69030594 0.30969406]

[0.15274345 0.84725655]] [9.99798868e-01 2.01132285e-04]



```

Iteration: 9
Log-Likelihood: -2171.5071 Change: 0.0001
Final Estimates
Log-Likelihood: -2171.5071 Akaike: 4361.0141 Schwarz: 4405.2467
Mu: 0.0
Sigma: [1.6007 2.2998]
Transition matrix:
[0.6903 0.3097]
[0.1527 0.8473]
Initial probabilities: [9.998e-01 2.000e-04]

```

5 Step 4

Model estimation: Hidden Markov Model with an AR(1) process

Define functions Likelihood of an observation

```

[36]: def likelihood_AR1(xi_prob, mu, sigma, rho, y, y_1):
    phi = norm.pdf((y-mu-rho*y_1)/sigma)/sigma
    y_like=np.dot(xi_prob, phi)
    return y_like, phi

```

```

[37]: # Hamilton filtering
def forward_alg_AR1(pi0, N, T, P, mu, sigma, rho, Y):

    # Y: time series
    xi_prob_t = np.zeros((T-1, N))
    xi_prob_t1 = np.zeros((T-1, N))

    # Case t=1

```

```

# Likelihood of observation y_1 and marginal densities phi_1
# xi_1/1
y_like, phi = likelihood_AR1(pi0, mu, sigma, rho, Y[1], Y[0])
#xi_2/1
xi_prob_t[0, :] = np.multiply(pi0, phi) / y_like

for ss in range(0, N):
    xi_prob_t1[0, ss] = np.dot(P[:, ss], xi_prob_t[0, :])

# case t > 1
for tt in range(1, T-1):
    # Likelihood of observation y_t and marginal densities phi_t
    y_like, phi = likelihood_AR1(xi_prob_t1[tt - 1, :], mu, sigma, rho,
    ↪ Y[tt+1], Y[tt])
    # xi_t/t
    xi_prob_t[tt, :] = np.multiply(xi_prob_t1[tt - 1, :], phi) / y_like

    for ss in range(0, N):
        xi_prob_t1[tt, ss] = np.dot(P[:, ss], xi_prob_t[tt, :])

return xi_prob_t, xi_prob_t1

```

```

[38]: def M_step_func_AR1(xi_prob, P, N, T, Y):
    # Initialize estimates
    mu_hat = np.zeros((N))
    rho_hat = np.zeros((N))
    sigma_hat = np.zeros((N))
    P_hat = np.zeros((N, N))
    pi_hat = np.zeros((N))

    for ss in range(0, N):
        # New estimates for "mu"
        xi_y = np.sqrt(xi_prob[:, ss])*Y[1:]
        z = np.stack((np.ones(T-1), Y[:-1]), axis=1)
        xi_z = np.zeros((T-1, N))
        xi_z[:, 0] = np.sqrt(xi_prob[:, ss])*z[:, 0]
        xi_z[:, 1] = np.sqrt(xi_prob[:, ss])*z[:, 1]
        z_xi_z_inv = np.linalg.inv(np.dot(xi_z.T, xi_z))
        beta_hat = np.dot(z_xi_z_inv, np.dot(xi_z.T, xi_y))

        mu_hat[ss] = beta_hat[0]
        rho_hat[ss] = beta_hat[1]

        # New estimates for "sigma"
        residuals = Y[1:] - np.dot(z, beta_hat)
        xi_y_mu2 = np.dot(xi_prob[:, ss], residuals ** 2)
        sigma_hat[ss] = (xi_y_mu2 / np.sum(xi_prob[:, ss])) ** 0.5

```

```

    # New estimates for transition matrix
    for ss2 in range(0, N):
        P_hat[ss, ss2] = np.sum(P[ss, ss2, 1:]) / np.sum(P[ss, :, 1:])
    # New estimation for initial probabilities
    pi_hat[ss] = xi_prob[0, ss]

    return mu_hat, rho_hat, sigma_hat, P_hat, pi_hat

```

logarithmic likelihood

```

[39]: def log_likelihood_AR1(xi_prob, T, pi_hat0, P, mu, sigma, rho, Y):
    y_like = np.zeros(T-1)
    for tt in range(0, T-1):
        y_like[tt], _ = likelihood_AR1(xi_prob[tt, :], mu, sigma, rho, Y[tt+1],
        ↪ Y[tt])
    sum_log_like = np.sum(np.log(y_like))
    k = (np.prod(mu.shape) + np.prod(sigma.shape) + np.prod(rho.shape))
    k += (np.prod(pi_hat0.shape) + np.prod(P.shape))
    n = len(Y)-1
    akaike = 2 * k - 2 * sum_log_like
    schwarz = k * np.log(n) - 2 * sum_log_like
    return sum_log_like, akaike, schwarz

```

Compute the model

```

[40]: # Initialize parameters
T = len(df) # length of time-series
N = 2 # Number

# SET INITIAL GUESSES

mu_hat0 = [0, 0.1] * np.ones((N)) #expectation parameters of the
    ↪ distribution
sigma_hat0 = [0.5, 0.5] * np.ones((N))
P_hat0 = np.zeros((N, N))

P_hat0[0, 0] = 0.75
P_hat0[0, 1] = 1 - P_hat0[0, 0]
P_hat0[1, 1] = 0.7
P_hat0[1, 0] = 1 - P_hat0[1, 1]

# Start as initial probability the stationary distribution
pi_hat0 = [0.5, 0.5] * np.ones((N))
for t in range(1, 100):
    pi_hat0 = np.dot(P_hat0.T, pi_hat0)

```



```

rho_hat0 = [0.1, 0.1]*np.ones((N))

# Determine maximum number of iterations until convergence and convergence
↳tolerance
itemax = 200      #number of steps
itetol = 1e-4     #convergence tolerance parameter
log_like0 = -1e8
for ite in range(0, itemax):

    # Expectation step
    xi_prob_t, xi_prob_t1 = forward_alg_AR1(pi_hat0, N, T, P_hat0, mu_hat0,
↳sigma_hat0, rho_hat0, df)
    xi_prob_T = backward_alg(xi_prob_t, xi_prob_t1, N, T-1, P_hat0)

    print("")
    plt.subplot(1, 2, 1)
    plt.plot(xi_prob_T[:, 0])
    plt.title("Estimated probability of state 0")
    plt.subplot(1, 2, 2)
    plt.plot(xi_prob_T[:, 1])
    plt.title("Estimated probability of state 1")
    fig = plt.gcf()
    fig.set_size_inches(16, 6)
    plt.show()
    print("")

    # Compute  $Pr(s_{t+1} = j, s_t = i)$ 
    P_hat_T = np.zeros((N, N, T-1))
    for tt in range(1, T-1):
        for ss in range(0, N):
            for ss2 in range(0, N):
                P_hat_T[ss, ss2, tt] = (
                    P_hat0[ss, ss2]
                    * xi_prob_t[tt - 1, ss]
                    * xi_prob_T[tt, ss2]
                    / xi_prob_t1[tt - 1, ss2]
                )

    # Instead of checking estimates we only check likelihood
    log_like1, akaike, schwarz = log_likelihood_AR1(np.concatenate(([pi_hat0],
↳xi_prob_t1[0:T-2])), T, pi_hat0, P_hat0, mu_hat0, sigma_hat0, rho_hat0, df)
    diff = (log_like1 - log_like0)/abs(log_like0 + 1e-3)
    print("Iteration: ", ite)
    print("Diff: ", diff)
    print("Log-Likelihood: ", np.round(log_like1, 4), "Change: ", np.
↳round(diff,4))

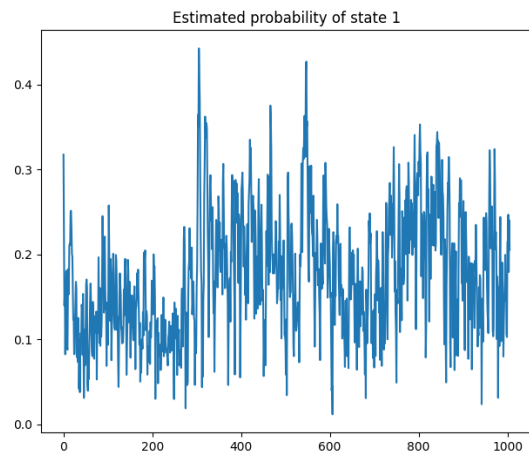
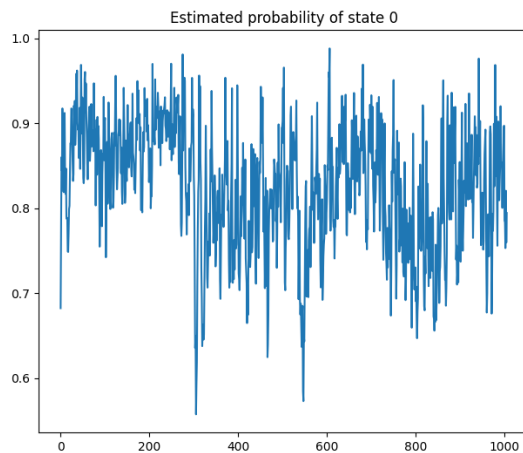
```

```

# Stop when the difference in likelihood between steps decreases

if diff > itetol :
    # M-step
    mu_hat0, rh0_hat0, sigma_hat0, P_hat0, pi_hat0 = M
    ↪ M_step_func_AR1(xi_prob_T, P_hat_T, N, T, df)
    log_like0 = log_like1
else:
    print("Final Estimates")
    print("Log-Likelihood: ", np.round(log_like1,4),
          "Akaike: ", np.round(akaike,4),
          "Schwarz: ", np.round(schwarz,4))
    print("Mu: ", np.round(mu_hat0,4))
    print("Sigma: ", np.round(sigma_hat0,4))
    print("Transition matrix: ")
    for ss in range(N):
        print(np.round(P_hat0[ss,:],4))
    print("Initial probabilities:", np.round(pi_hat0,4))
    break

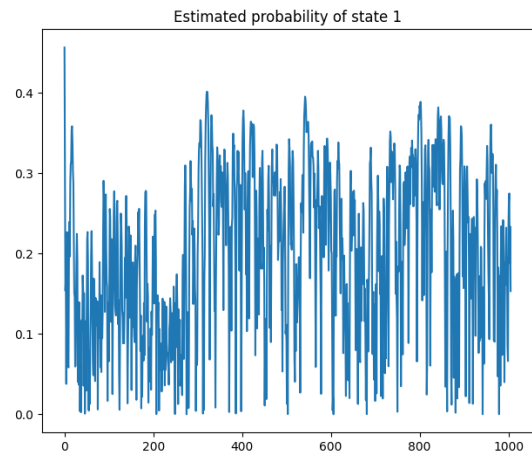
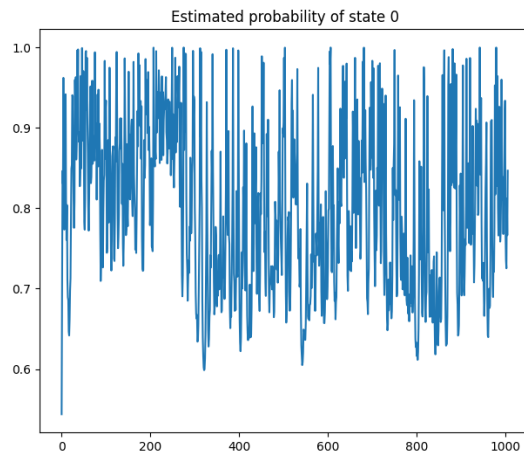
```



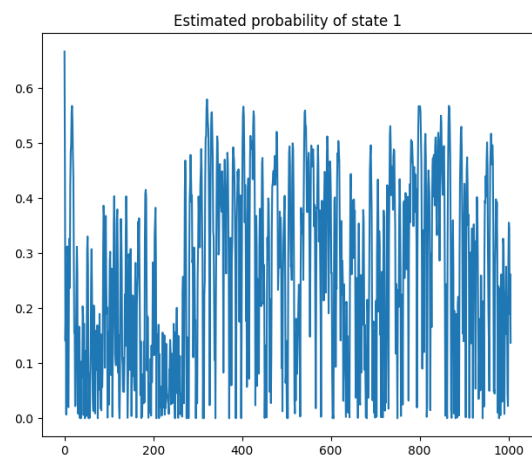
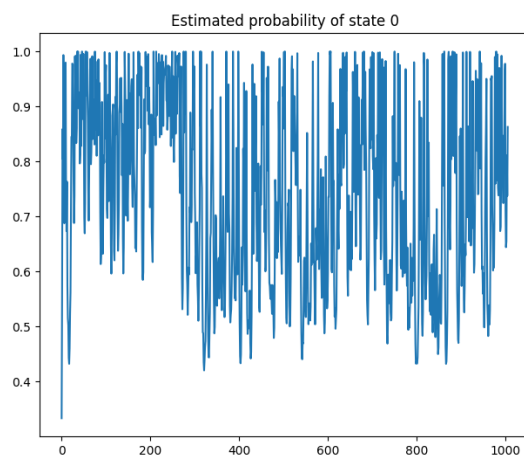
```

Iteration:  0
Diff:  0.999919441303113
Log-Likelihood:  -8055.8707 Change:  0.9999

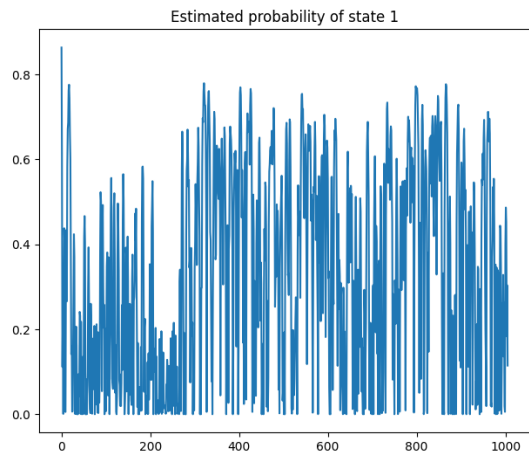
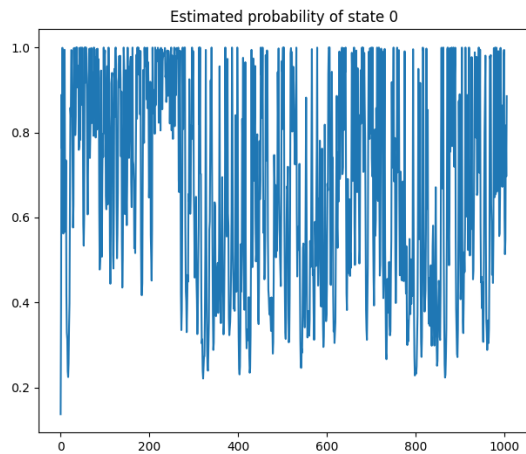
```



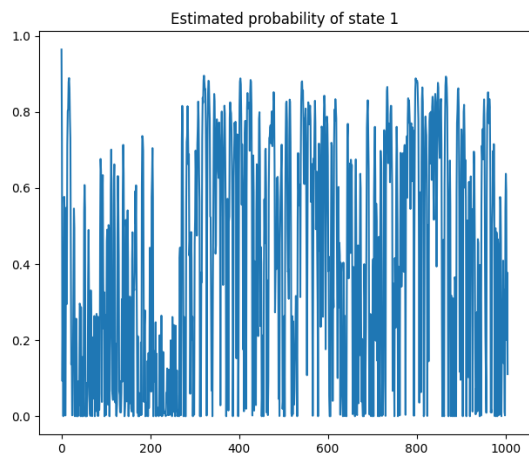
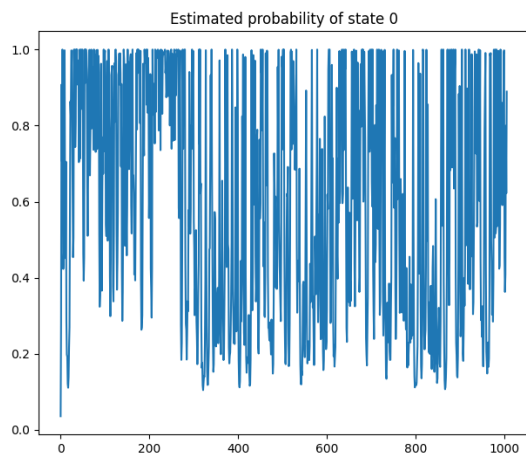
Iteration: 1
Diff: 0.8034010329519496
Log-Likelihood: -1583.7767 Change: 0.8034



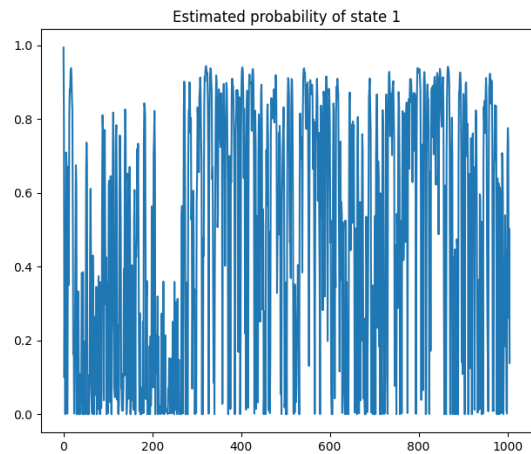
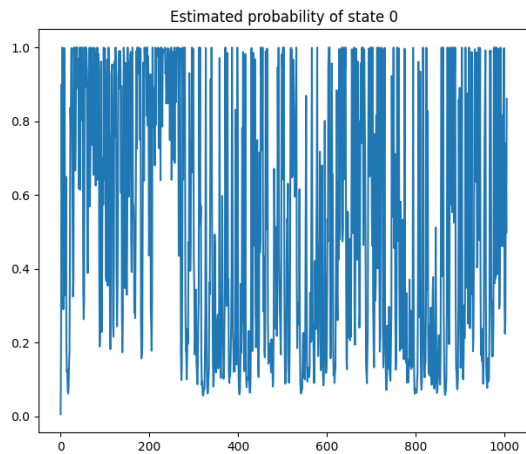
Iteration: 2
Diff: 0.014207733235905668
Log-Likelihood: -1561.2748 Change: 0.0142



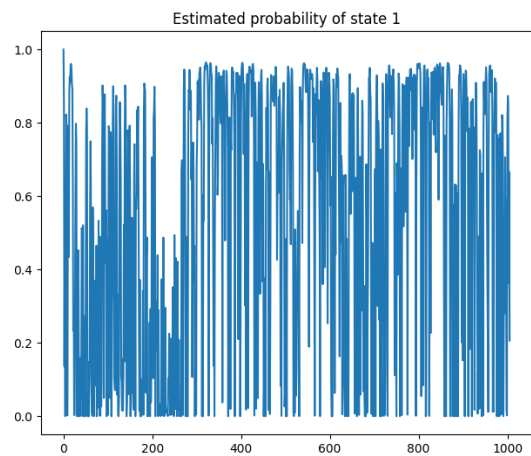
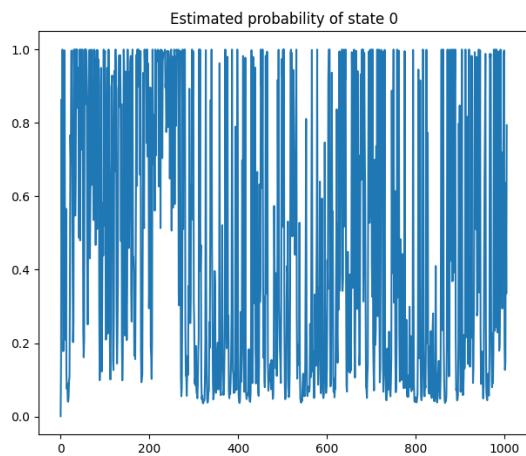
Iteration: 3
 Diff: 0.016031698448923548
 Log-Likelihood: -1536.2449 Change: 0.016



Iteration: 4
 Diff: 0.011039004857269564
 Log-Likelihood: -1519.2863 Change: 0.011



Iteration: 5
 Diff: 0.002794285790157826
 Log-Likelihood: -1515.041 Change: 0.0028



Iteration: 6
 Diff: -0.0022263672231471856
 Log-Likelihood: -1518.414 Change: -0.0022
 Final Estimates
 Log-Likelihood: -1518.414 Akaike: 3060.8281 Schwarz: 3119.7929
 Mu: [-2.5352 -0.914]
 Sigma: [1.2735 0.576]
 Transition matrix:
 [0.7227 0.2773]

[0.2932 0.7068]

Initial probabilities: [0.0061 0.9939]