

# Applied Programming I

Programming computers in a nutshell.

# Introduction to algorithms and data structures

Some minimal basics

# Today's objectives

- Basic understanding of
  - Algorithms and
  - Data structures.
- What are they, why are they important, what to consider?



Break:  
Midterm evaluation

# Algorithm



- An algorithm is well-defined step-by-step procedure to solve a specific (computational) problem. The algorithm typically gets input and produces output.
- A cooking recipe is a good illustration of an algorithm. It takes the ingredients as input, and by a step-by-step procedure, the dish as output is produces.

# Sorting

The **sorting problem** is quite popular to illustrate algorithms. The sorting problem is defined by:

- Input: a sequence of  $n$  numbers:  $(a_1, a_2, a_3, \dots, a_n)$
- Output: a permutation of the input:  $(a'_1, a'_2, a'_3, \dots, a'_n)$ , so that  $a'_1 \leq a'_2 \leq a'_3 \leq \dots \leq a'_n$

# Insertion sort

```
For j = 2 to A.length:  
    key = A[j]  
    i = j - 1  
    while i > 0 and A[i] > key:  
        A[i+1] = A[i]  
        i = i - 1  
    A[i+1] = key
```

Index / step	1	2	3	4	5	6
a	14	6	11	17	3	8
b	6	14	11	17	3	8
c	6	11	14	17	3	8
d	6	11	14	17	3	8
e	3	6	11	14	17	8
F	3	6	8	11	14	17

# Complexity



- Complexity of algorithms refers to the amount of required resources regarding time and memory/space.
- **Time complexity** is a measure of time (or certain kind of operations) an algorithm requires to solve a problem as a function of the input size.
- **Space complexity** is a measure of memory as a function of the algorithm's input size.
- The complexity considers worst-case scenarios and is given as an upper bound, usually in **Big O notation**.

# Big O notation: example for time complexity

The Big O notion describes how the running time of the algorithm increases as follows with the size  $n$  of its input:

- $O(n)$ : linearly
- $O(n^2)$ : quadratically
- $O(\log n)$  : logarithmically
- $O(e^n)$ : exponentially



# Insertion sort: analysis

For  $j = 2$  to  $A.length$ : (1)

key =  $A[j]$  (2)

$i = j - 1$  (3)

while  $i > 0$  and  $A[i] > key$ : (4)

$A[i+1] = A[i]$  (5)

$i = i - 1$  (6)

$A[i+1] = key$  (7)

How often? ...-times:

(1)  $n$

(2)  $n-1$

(3)  $n-1$

(4) depends on  $A[i] > key$

(5) One less than (4)

(6) One less than (4)

(7)  $n-1$

# Insertion sort: analysis

For j = 2 to A.length: (1)

key = A[j] (2)

i = j-1 (3)

while i>0 and A[i]>key:(4)

A[i+1] = A[i] (5)

i = i-1 (6)

A[i+1] = key (7)

Best case: sorted array as input:

(4) only n-1 times

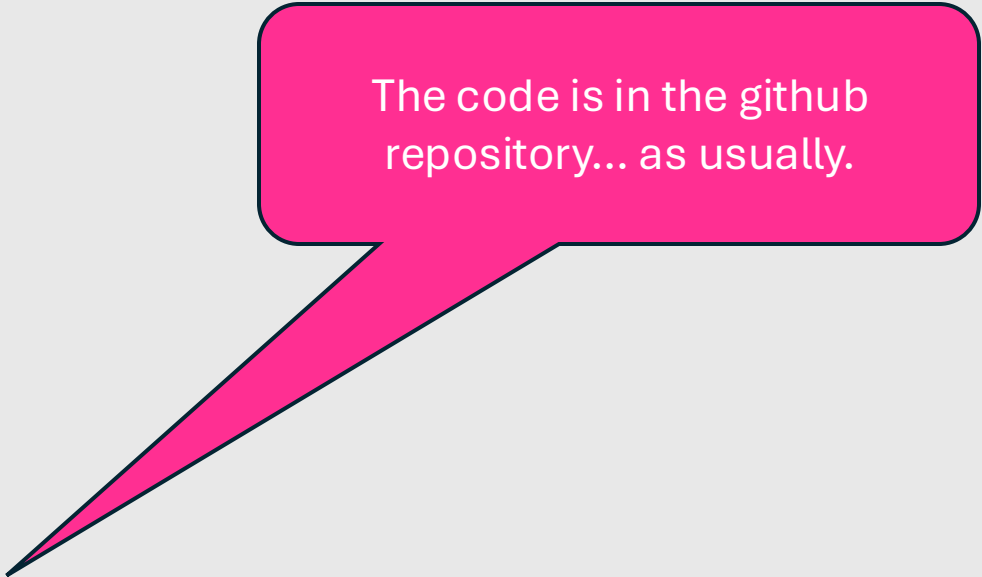
**Worst case:** reverse sorted array:

(4)  $n(n+1)/2 - 1$

(5)  $n(n-1)/2$

(6)  $n(n-1)/2$

-> Insertion sort is  $O(n^2)$



The code is in the github repository... as usually.



# Your task:

# Implement insertion sort

In (your project) groups, write a program in Python that implements insertion sort. Use the program `compare-times-sort.py` as starting point. Optional: Translate the program in another language (Javascript, C, C#) using tools such as Copilot and try to understand

Time: 20 minutes.

# Divide and conquer



- The **divide-and-conquer** approach is powerful algorithmic technic to tackle problems. The problem is broke down into smaller, but easier, problems.
- The problem is **divided** into smaller subproblems thar are similar to the original problem but easier to solve.
- The subproblems are solved (recursively) - they are **conquered**.
- Finally, the solved solutions of the subproblem are **combined** and form the solution to the original problem.

# Binary search

- Task: search an element  $x$  in a sorted array .
- Divide: Split the array into two halves with its middle element  $m$ .
- Conquer: Compare  $x$  with the middle element  $m$ ,
  - if  $x == m$ : element found, done
  - if  $x < m$ : repeat process with left/lower half of current array
  - If  $x > m$ : repeat process with right/higher half of current array
  - if half of current array is empty, element not found

# Binary search: illustration – search 9

1	2	4	7	8	9	10	13	15	17	19	23	24	27	30
1	2	4	5	6	9	10	9 <							
			9 >	6	9	10								
					==9									

# Binary search in Python, AI generated code

```
def binary_search_iterative(arr, x):  
    low = 0  
    high = len(arr) - 1  
    while low <= high:  
        mid = (low + high) // 2      # / 2 and round down  
        if arr[mid] < x:  
            low = mid + 1  
        elif arr[mid] > x:  
            high = mid - 1  
        else:  
            return mid  
    return -1      # not found
```

# Merge sort

- **Divide** the array in two halves if it has more than one element.
- Recursively sort each half with merge sort (**conquer**).
- Merge (**combine**) the two sorted halves by comparing and arranging their elements.



# Merge sort illustration

18	8	25	17	5	19	22	12
Merge		Merge		Merge		Merge	
8	18	17	25	5	19	12	22
Merge				Merge			
8	17	18	25	5	12	19	22
Merge							
5	8	12	17	18	19	22	25

# Merge sort: pseudo code 1/2

```
function mergeSort(array):  
    if length of array <= 1:  
        return array  
    mid = length of array / 2  
    leftHalf = mergeSort(array[0:mid])  
    rightHalf = mergeSort(array[mid:length of array])  
    return merge(leftHalf, rightHalf)
```

# Merge sort: pseudo code 2/2

```
function merge(left, right):
```

```
    result = []
```

```
    i = 0
```

```
    j = 0
```

```
    while (i < length of left  
           and j < length of right):
```

```
        if left[i] <= right[j]:
```

```
            append left[i] to result
```

```
            i = i + 1
```

```
        else:
```

```
            append right[j] to result
```

```
            j = j + 1
```

```
    while (i < length of left):
```

```
        append left[i] to result
```

```
        i = i + 1
```

```
    while (j < length of right):
```

```
        append right[j] to result
```

```
        j = j + 1
```

```
    return result
```

# Merge sort and complexity

- It can be shown that merge sort has a time complexity of  $O(n \log n)$  for  $n$  elements and, thus, faster as insertion sort.



# Your task:

## Implement merge sort and compare its performance with insertion sort

In (your project) groups, write a program that merge sort in Python. Optional: Translate this program into JavaScript.

Time: 30 minutes.



# Break and midterm evaluation

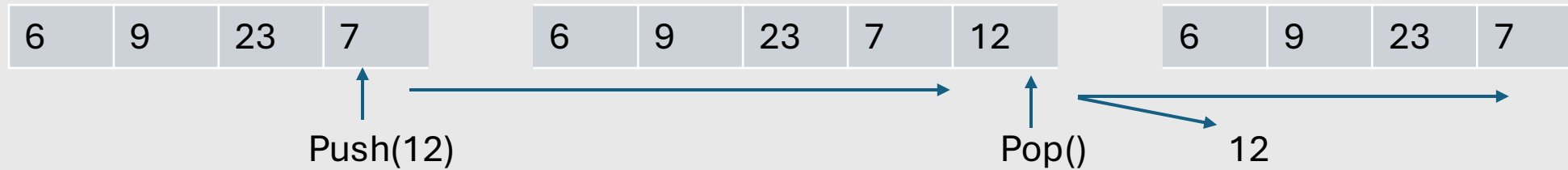
40 minutes

# Data structures



- Data structures (as the already covered arrays) are means of organizing and storing data. Using algorithms, it can be beneficial to use or develop specific data structures to solve a problem.
- Most programming languages come along with elementary data structures.

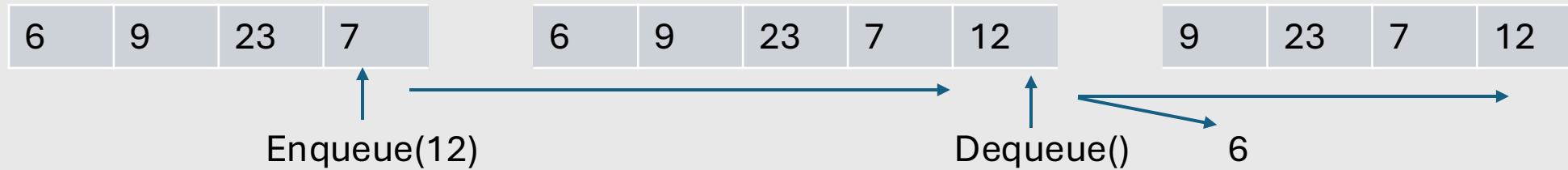
# Elementary data structure: Stack



- LIFO: Last-in-first-out data structure
- A stack provides three operations:
  - Empty: returns true if stack is empty else false
  - Push element: insert element onto the top of the stack
  - Pop element: return and delete element off the top of the stack

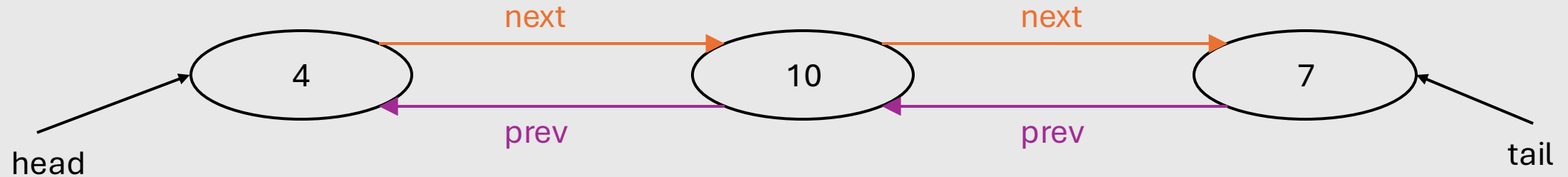


# Elementary data structure: Queue



- FIFO: First-in-first-out data structure
- A queue supports the operations
  - Length: return the size of the queue
  - Enqueue: put an element to the end of the queue
  - Dequeue: get and remove the last element of the queue

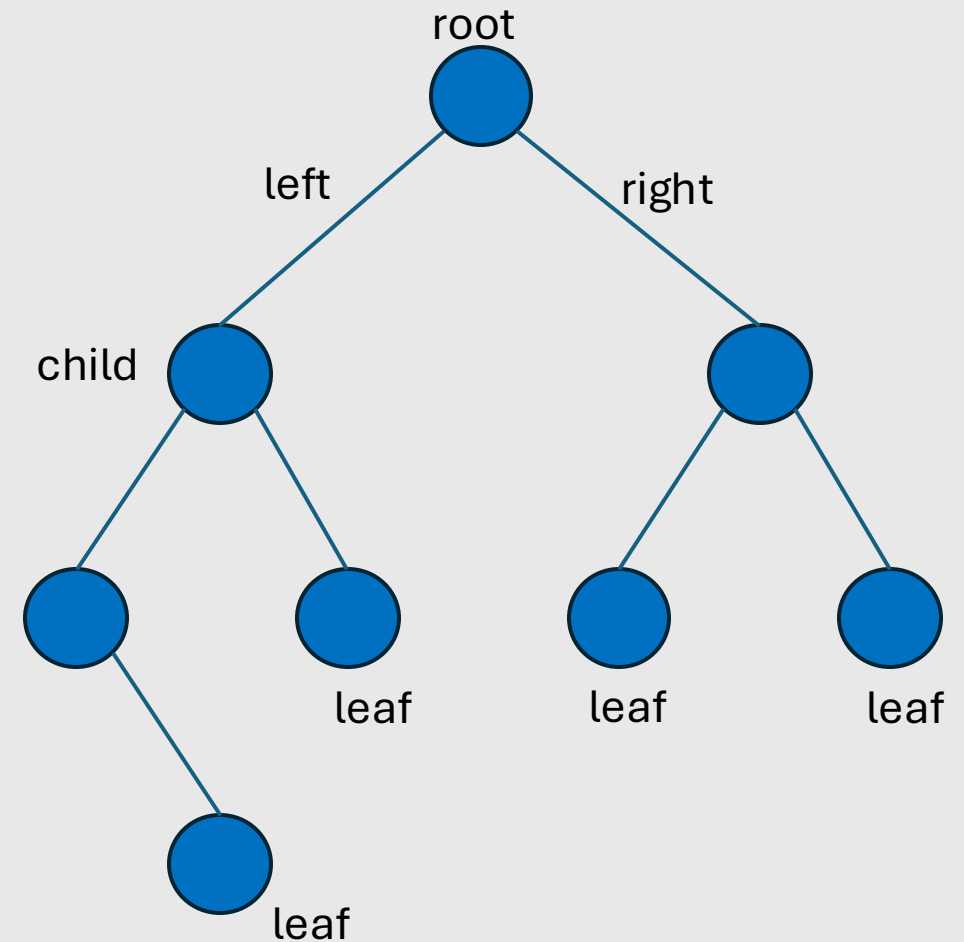
# Elementary data structure: List



- A double-linked list is a data structure with elements that contain a key (content) and pointers to the previous and next elements.
- Compared with an array, an insertion/deletion at any position does not require a lot copying of data.

# Elementary data structure: Tree

- Trees are hierarchical data structures. They extend the concept of linked elements (as in lists).
- Nodes are the elements of trees with keys (data) and information (usually pointers) to parent and children.
- Binary trees only have two nodes that can have left and right children.
- Applications are, e.g., decision trees.

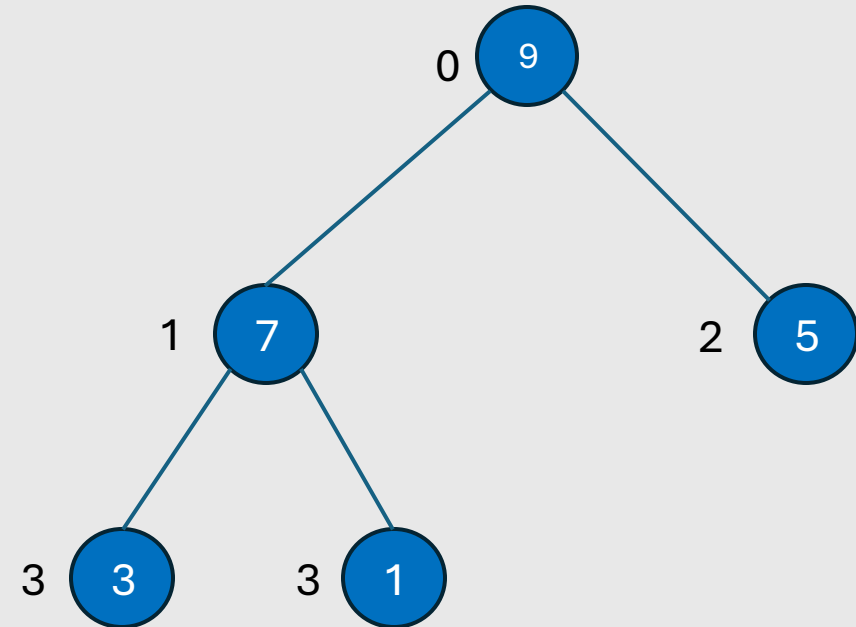


# Elementary data structure: Heap

- A binary heap is a data structure that represents a binary tree for numbers. A heap has to satisfy a heap property.
- The heap property can be max-heap or min-heap.
  - Max-heap: the value of a given node is less or equal to its parent node. The maximum value is in the root.
  - Min-heap: analogous to max-heap but with greater or equal
- A heap can be implemented using an array.

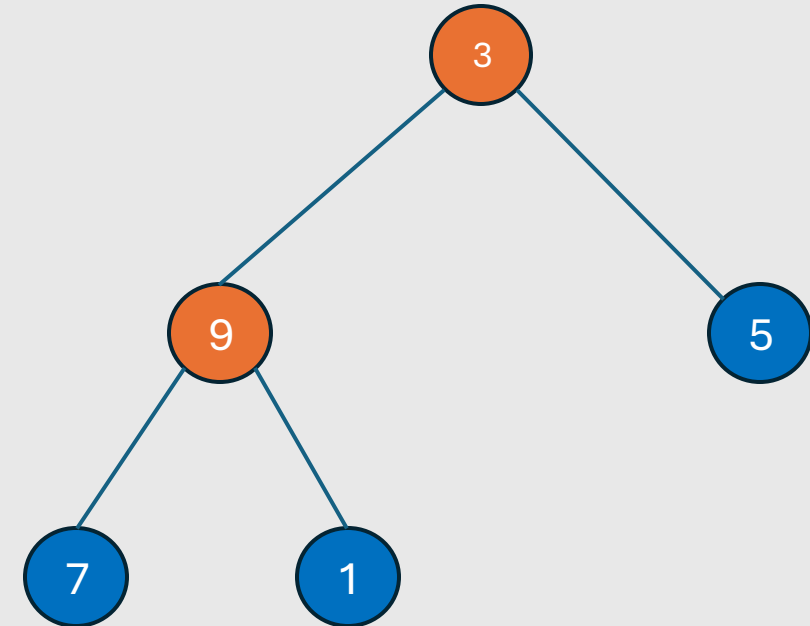
# Elementary data structure: heap as array

Indices:				
[0]	[1]	[2]	[3]	[4]
Data:				
9	5	3	7	1



# Elementary data structure: heapify an array

Array to heapify:				
3	9	5	7	1
Transform to hold max-heap property: swap				
9	3	5	7	1



# Build a max-heap in Python

```
def heapify(arr, n, i):
```

```
    max = i # largest as root
```

```
    lf = 2 * i + 1 # left = 2*i + 1
```

```
    rt = 2 * i + 2 # right = 2*i + 2
```

```
    # left child? greater than root?
```

```
    if lf < n and arr[i] < arr[lf]:
```

```
        max = lf
```

```
    # right child? greater than root?
```

```
    if rt < n and arr[max] < arr[rt]:
```

```
        max = rt
```

```
    # Change root, if needed
```

```
        if max != i:
```

```
            arr[i], arr[max] = arr[max], arr[i]
```

```
    # Heapify the root.
```

```
    heapify(arr, n, max)
```

```
def max_heap(arr):
```

```
    n = len(arr)
```

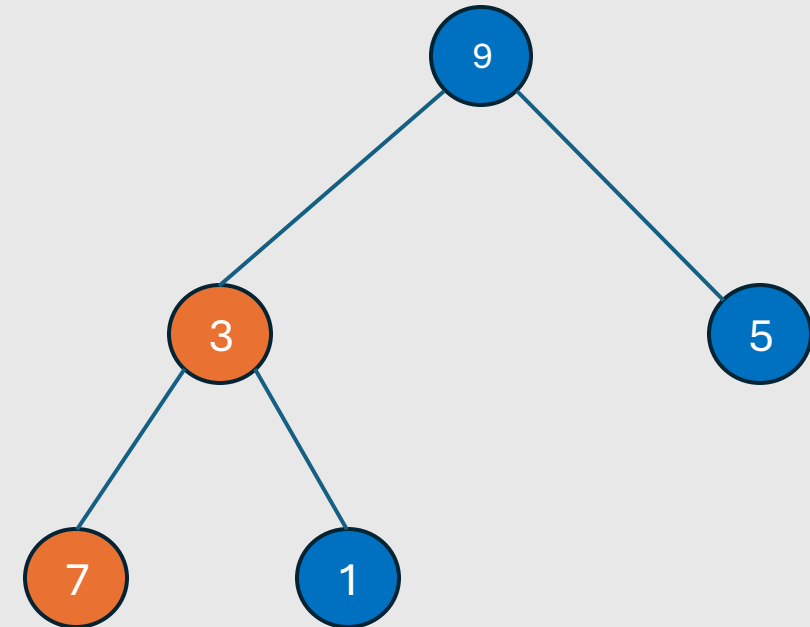
```
    # Build a maxheap.
```

```
    for i in range(n // 2 - 1, -1, -1):
```

```
        heapify(arr, n, i)
```

# Elementary data structure: heapify an array

Array to heapify:				
3	9	5	7	1
Transform to hold max-heap property: swap				
9	3	5	7	1
Transform to hold max-heap property: swap				
9	5	3	7	1



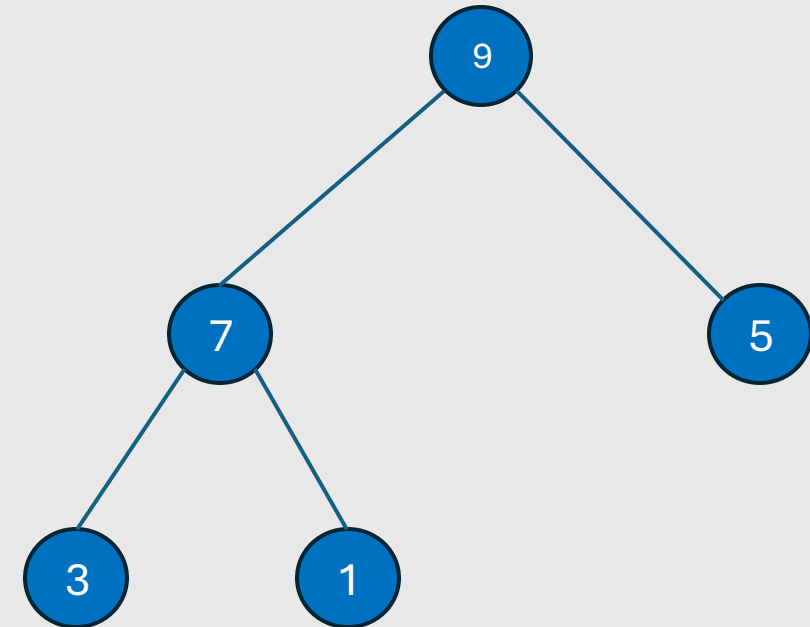


# Build a max-heap in Python

```
def heapify(arr, n, i):  
    max = i # largest as root  
    lf = 2 * i + 1 # left = 2*i + 1  
    rt = 2 * i + 2 # right = 2*i + 2  
  
    # left child? greater than root?  
    if lf < n and arr[i] < arr[lf]:  
        max = lf  
  
    # right child? greater than root?  
    if rt < n and arr[max] < arr[rt]:  
        max = rt  
  
    # Change root, if needed  
    if max != i:  
        arr[i], arr[max] = arr[max], arr[i]  
  
    # Heapify the root.  
    heapify(arr, n, max)  
  
def max_heap(arr):  
    n = len(arr)  
  
    # Build a maxheap.  
    for i in range(n // 2 - 1, -1, -1):  
        heapify(arr, n, i)
```

# Elementary data structure: heapify an array

Array to heapify:				
3	9	5	7	1
Transform to hold max-heap property: swap				
9	3	5	7	1
Transform to hold max-heap property: swap				
9	5	3	7	1



# Heap sort

1. Build a max-heap
2. Until heap is empty,
  - a) Take largest element from heap and put into result array
  - b) Heapify remaining heap

The result array can be build using the array of the heap by filling it from the back.

Advice: Research what this line does first:

```
for i in range(n // 2 - 1, -1, -1):
```



# Your task:

## Implement the remaining step of heap sort.

In (your project) groups, write a Python program that implements the remaining step of heap sort.

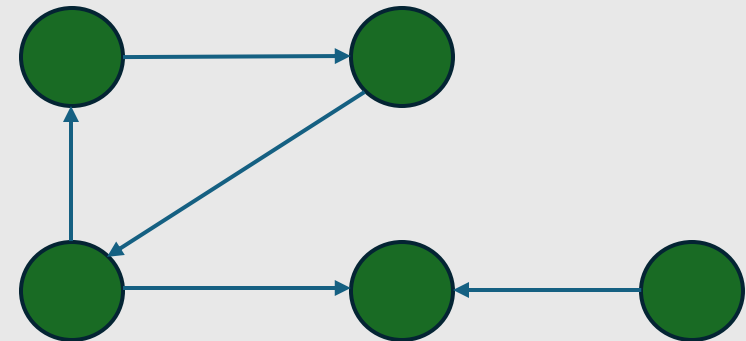
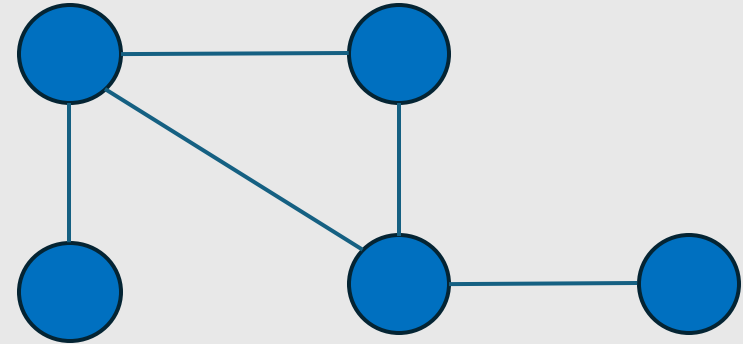
Time: 20 minutes.

# Heap sort and complexity

- Heap sort has a time complexity of ???
- What do you think?

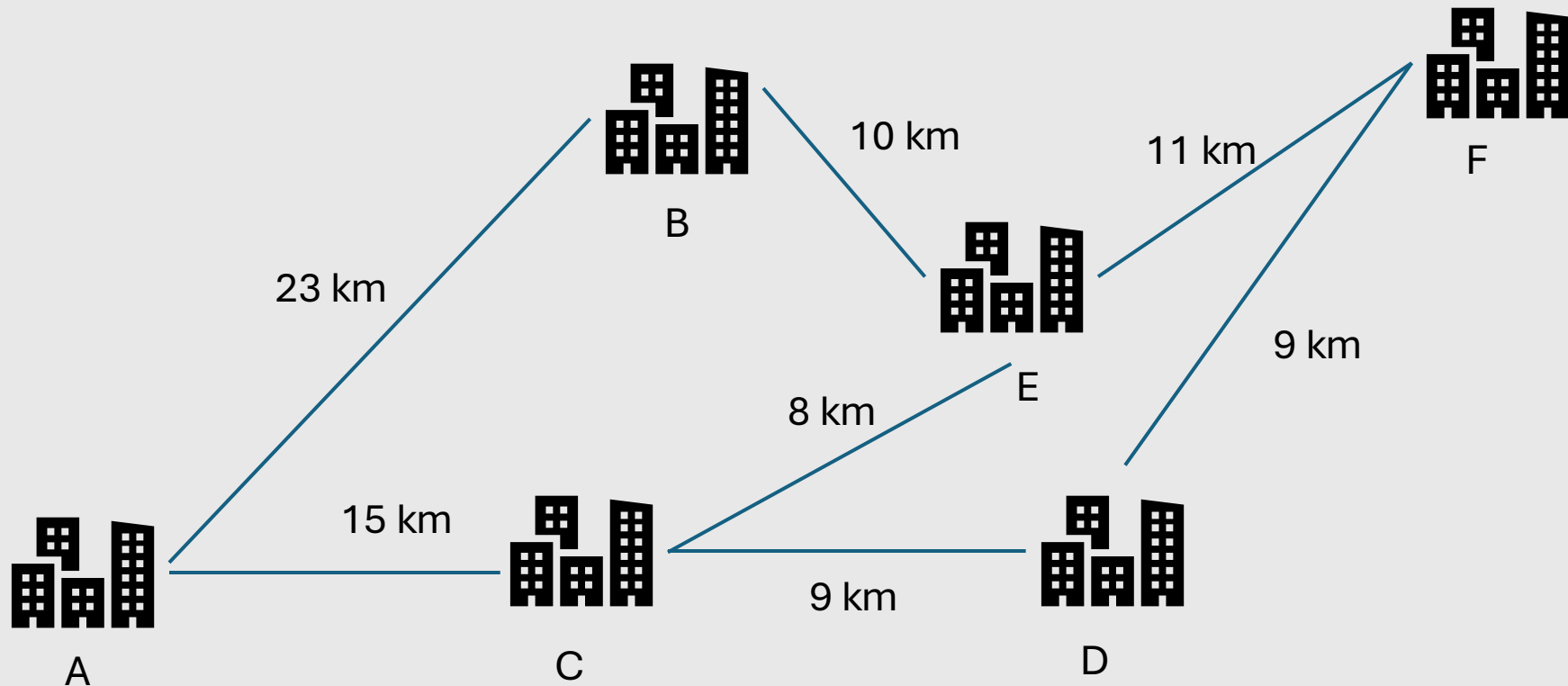
# Elementary data structure: Graph

- Graphs have vertices and edges:  $G = (V, E)$ .
- Graphs can be undirected and directed. Directed graphs have edges with directions.
- Graphs can be represented by adjacency-lists or adjacency-matrices. Edges can also be weighted.
- Graphs are used in many applications, e.g., route planning.



# Graph algorithm: shortest path

- Objective: compute the shortest path between vertices in a graph. The graph can represent, e.g., a road map between cities.



# Graph algorithm: formal setting

$G = (V, E)$ , with  $w : E \rightarrow \mathcal{R}$

The path  $p = (v_0, v_1, \dots, v_k)$  has the weight  $w(p) :$

$$w(p) = \sum_{i=1}^k w(v_{i-1}, v_i)$$

The shortest-path weight between  $u$  and  $v$  is

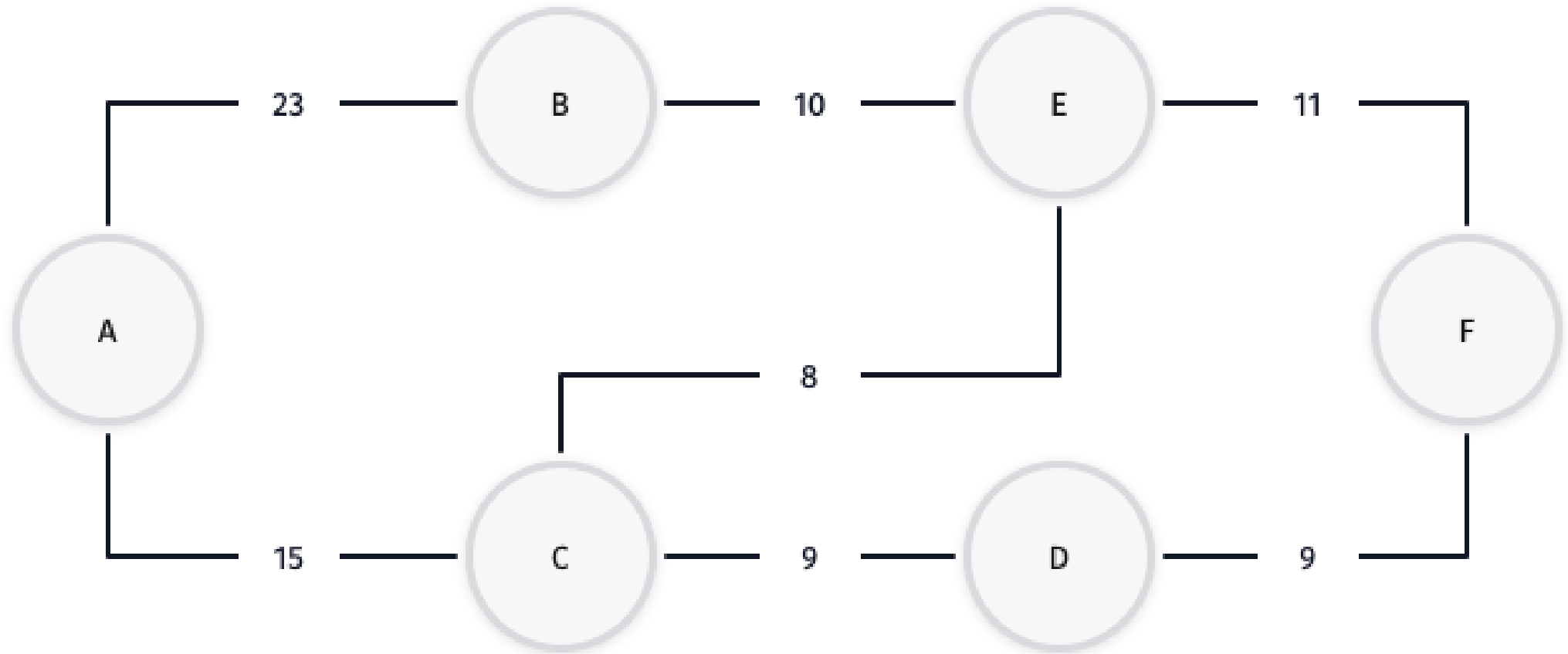
$$d(u, v) = \begin{cases} \min\{w(p) : u \rightarrow_p v\} & \text{if a path from } u \text{ to } v \\ \infty & \text{otherwise} \end{cases}$$

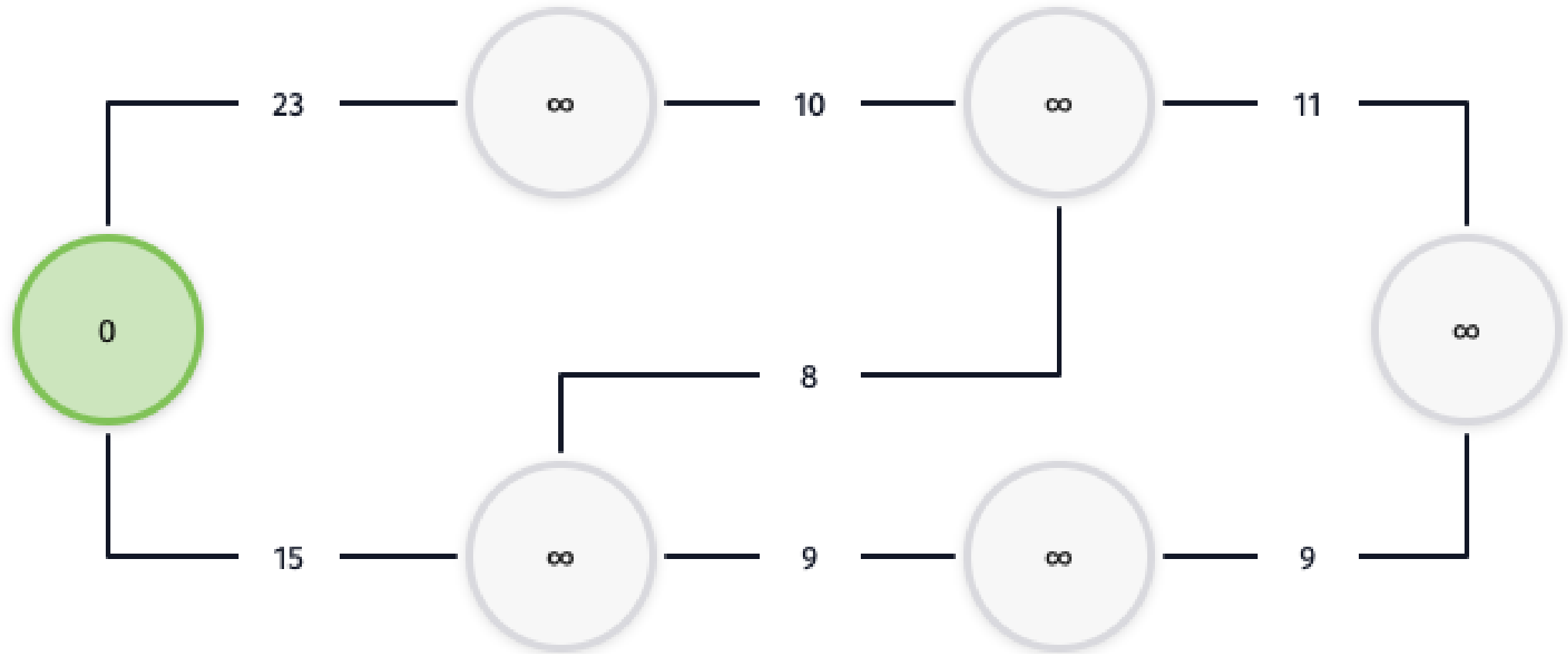


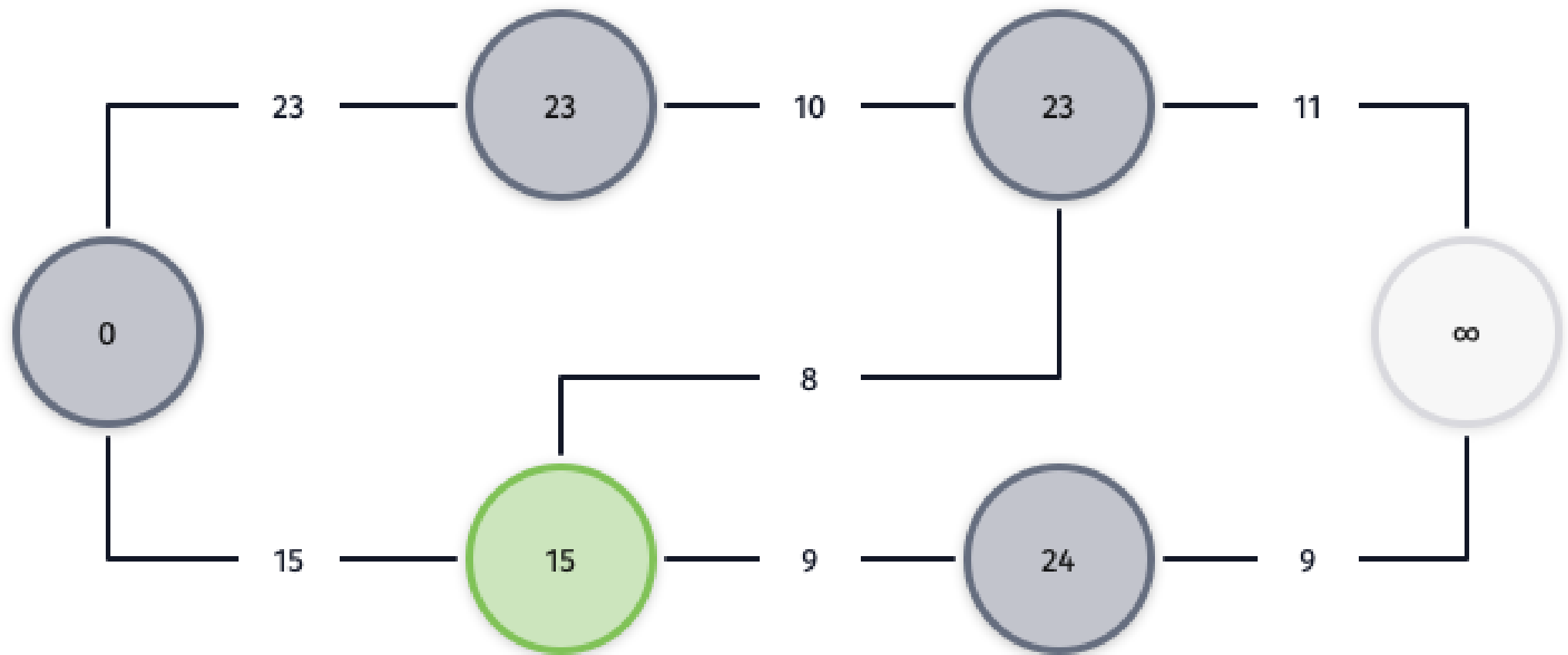
# Graph algorithm: Dijkstra shortest path

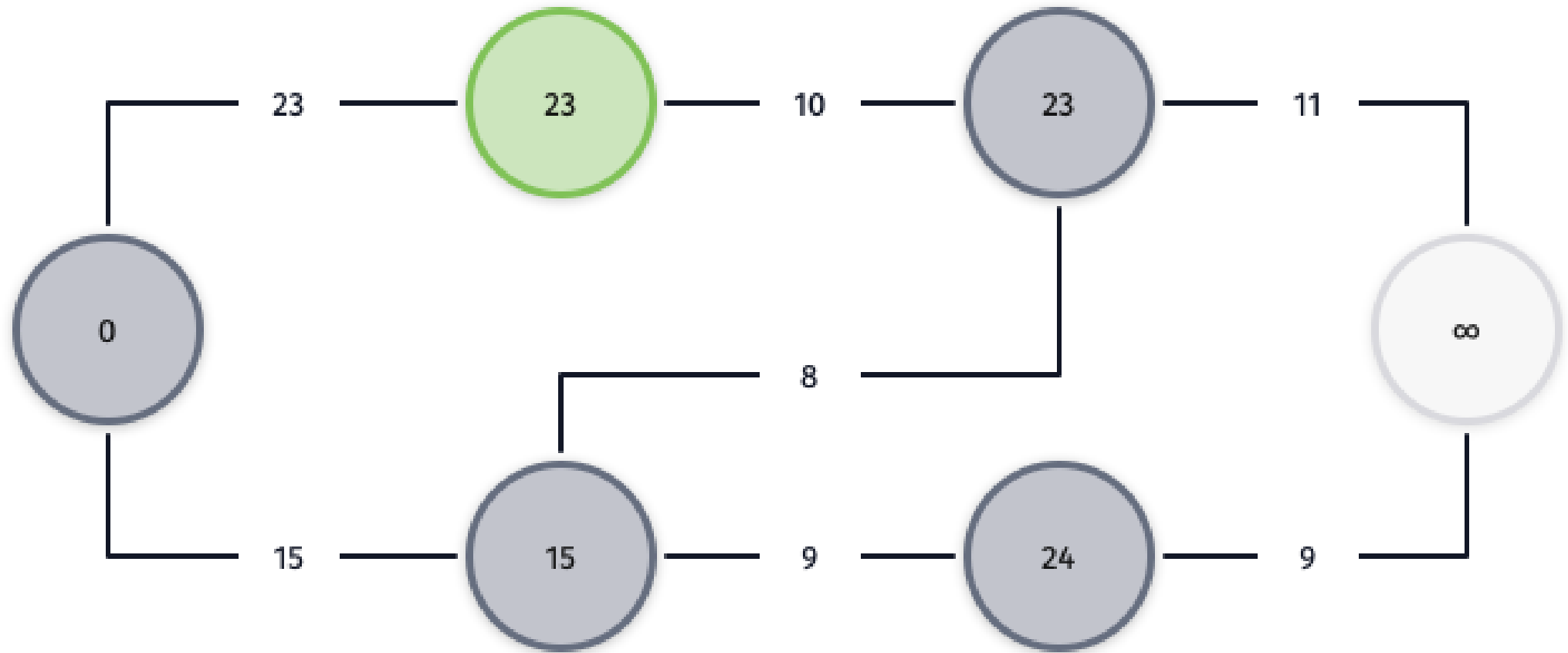
1. Initialize: Start with source node and set distance to infinity to all other nodes. Put the source node on a min-heap.
2. While the heap is not empty
  - a) Take the node from the heap (it is the node with the smallest distance)
  - b) Update its distance if a shorter path is found through the current node.

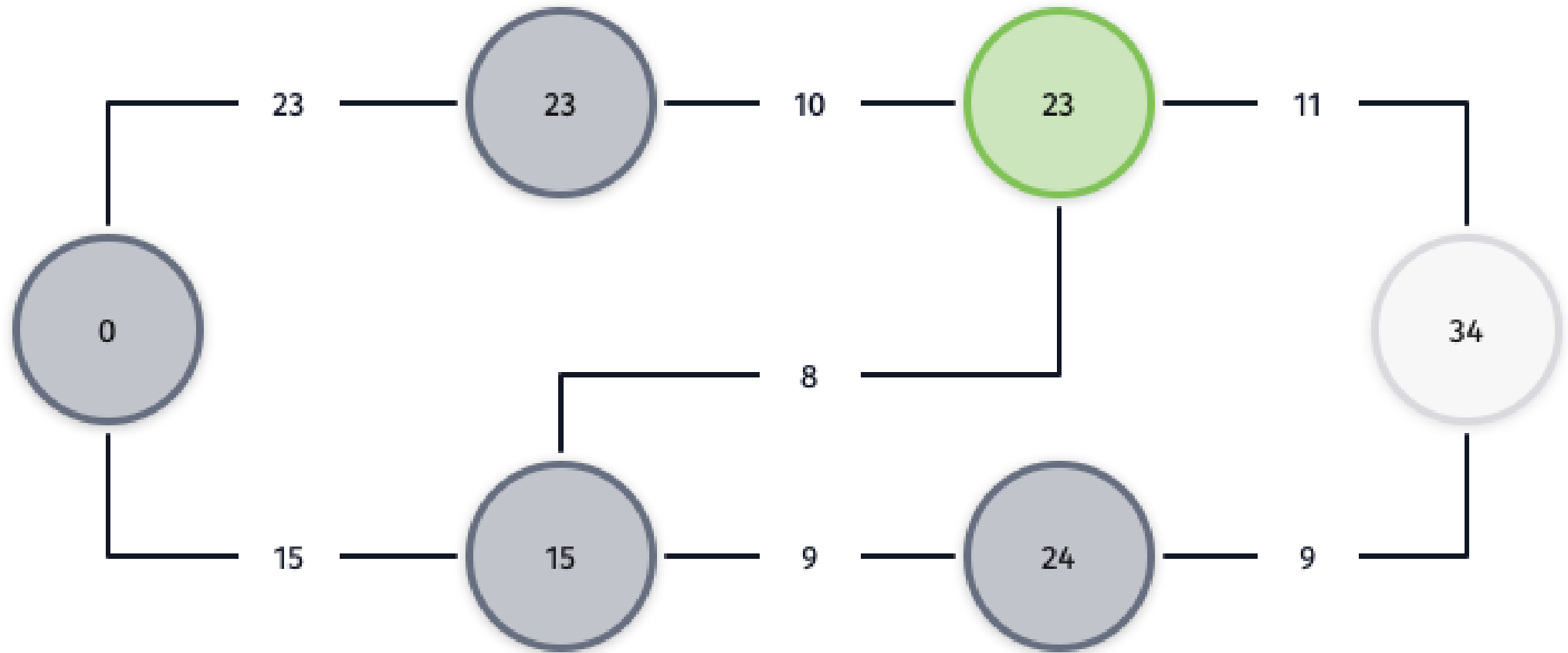
Note: To get the path, store and update the previous node to each node in 2. b). Then in a separate block, go back from the target node until source is reached.

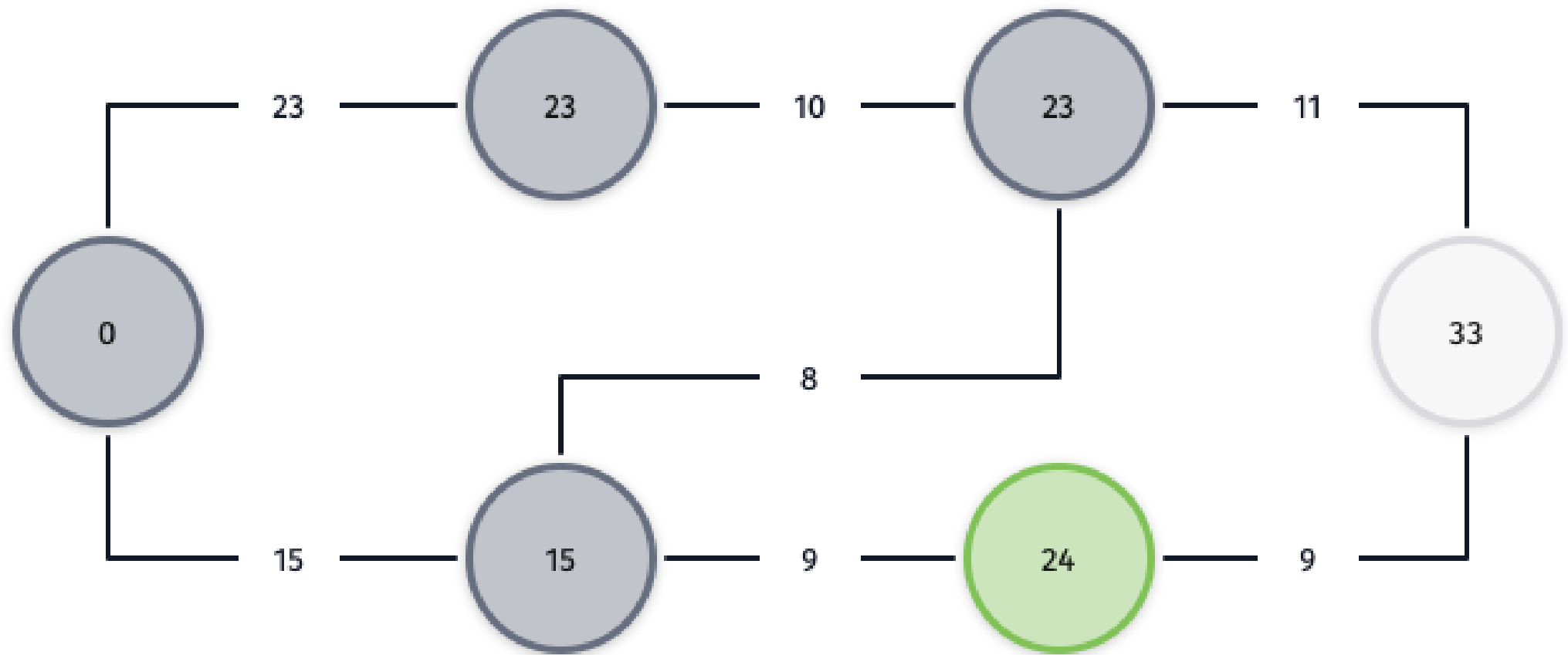












# Dijkstra in pseudo code

Dijkstra(Graph, source):

1. Initialize distances: all to infinity, zero for source
2. Enqueue source with distance zero onto min-heap
3. While min-heap is not empty
  - a) Node  $u$  = dequeue from min-heap
  - b) For each neighbor  $v$  of  $u$ :  
If distance from source through  $u$  to  $v$   $<$  current shortest path:  
Update distance of current shortest path



```
def dijkstra(graph, start):  
    # Initialize distances and priority queue  
    distances = {node: float('infinity') for node in graph}  
    distances[start] = 0  
    priority_queue = [(0, start)]  
    while priority_queue:  
        current_distance, current_node = heapq.heappop(priority_queue)  
        if current_distance > distances[current_node]:  
            continue  
        for neighbor, weight in graph[current_node].items():  
            distance = current_distance + weight  
            if distance < distances[neighbor]:  
                distances[neighbor] = distance  
                heapq.heappush(priority_queue, (distance, neighbor))  
    return distances
```

# Today's summary

- Algorithms explained using different sorting algorithms:
  - Insertion sort
  - Merge sort
  - Heap sort
- Concept of divide-and-conquer
- Elementary data structures
  - Stack, queue, list, tree, graph, heap
- Dijkstra as example of graph algorithms
- Basic idea of complexity of algorithms

Questions?

