Modulo red neuronal y función de entrenamiento • Entrenar y validar el modelo Preparación import os In [5]: os.environ['KMP DUPLICATE LIB OK']='True' # Import the libraries we need for this lab In [4]: import matplotlib.pyplot as plt import numpy as np import torch import torch.nn as nn import torch.nn.functional as F from matplotlib.colors import ListedColormap from torch.utils.data import Dataset, DataLoader torch.manual seed(1) Out[4]: <torch.\_C.Generator at 0x2727a5677f0> Función para graficar: # Define the function to plot the diagram def plot decision regions 3class (model, data set): cmap\_light = ListedColormap(['#FFAAAA', '#AAFFAA', '#00AAFF'])
cmap\_bold = ListedColormap(['#FF0000', '#00FF00', '#00AAFF']) X = data\_set.x.numpy() y = data\_set.y.numpy() h = .02 $x_{min}$ ,  $x_{max} = X[:, 0].min() - 0.1, <math>X[:, 0].max() + 0.1$  $y_{min}$ ,  $y_{max} = X[:, 1].min() - 0.1, X[:, 1].max() + 0.1$ xx, yy = np.meshgrid(np.arange(x\_min, x\_max, h), np.arange(y\_min, y\_max, h)) XX = torch.Tensor(np.c\_[xx.ravel(), yy.ravel()])  $_{\text{,}}$  yhat = torch.max(model(XX), 1) yhat = yhat.numpy().reshape(xx.shape) plt.pcolormesh(xx, yy, yhat, cmap=cmap\_light) plt.plot(X[y[:] == 0, 0], X[y[:] == 0, 1], 'ro', label = 'y=0') plt.plot(X[y[:] == 1, 0], X[y[:] == 1, 1], 'go', label = 'y=1') plt.plot(X[y[:] == 2, 0], X[y[:] == 2, 1], 'o', label = 'y=2')plt.title("decision region") plt.legend() Creamos la clase Data: # Create Data Class In [6]: class Data(Dataset): # modified from: http://cs231n.github.io/neural-networks-case-study/ # Constructor def \_\_init\_\_(self, K=3, N=500): X = np.zeros((N \* K, D)) # data matrix (each row = single example)y = np.zeros(N \* K, dtype='uint8') # class labels for j in range(K): ix = range(N \* j, N \* (j + 1))r = np.linspace(0.0, 1, N) # radius t = np.linspace(j \* 4, (j + 1) \* 4, N) + np.random.randn(N) \* 0.2 # theta $X[ix] = np.c_[r * np.sin(t), r*np.cos(t)]$ y[ix] = jself.y = torch.from\_numpy(y).type(torch.LongTensor) self.x = torch.from\_numpy(X).type(torch.FloatTensor) self.len = y.shape[0] # Getter def \_\_getitem\_\_(self, index): return self.x[index], self.y[index] # Get Length def len (self): return self.len # Plot the diagram def plot stuff(self): plt.plot(self.x[self.y[:] == 0, 0].numpy(), self.x[self.y[:] == 0, 1].numpy(),plt.plot(self.x[self.y[:] == 1, 0].numpy(), self.x[self.y[:] == 1, 1].numpy(),plt.plot(self.x[self.y[:] == 2, 0].numpy(), self.x[self.y[:] == 2, 1].numpy(),plt.legend() Módlulo red neuronal y función de entrenamiento Módulo red neuronal usando ModuleList() In [7]: # Create Net model class class Net(nn.Module): # Constructor def init (self, Layers): super(Net, self).\_\_init\_\_() self.hidden = nn.ModuleList() for input size, output\_size in zip(Layers, Layers[1:]): self.hidden.append(nn.Linear(input\_size, output\_size)) # Prediction def forward(self, activation): L = len(self.hidden) for (1, linear\_transform) in zip(range(L), self.hidden): **if** 1 < L - 1: activation = F.relu(linear transform(activation)) activation = linear transform(activation) return activation Función utilizada para entrenar: # Define the function for training the model In [8]: def train(data set, model, criterion, train loader, optimizer, epochs=100): LOSS = []ACC = []for epoch in range(epochs): for x, y in train loader: optimizer.zero\_grad() yhat = model(x)loss = criterion(yhat, y) optimizer.zero\_grad() loss.backward() optimizer.step() LOSS.append(loss.item()) ACC.append(accuracy(model, data set)) fig, ax1 = plt.subplots() color = 'tab:red' ax1.plot(LOSS, color = color) ax1.set\_xlabel('Iteration', color = color) ax1.set\_ylabel('total loss', color = color) ax1.tick params(axis = 'y', color = color) ax2 = ax1.twinx()color = 'tab:blue' ax2.set ylabel('accuracy', color = color) # we already handled the x-label with ax2.plot(ACC, color = color)ax2.tick\_params(axis = 'y', color = color) fig.tight layout() # otherwise the right y-label is slightly clipped plt.show() return LOSS Función para calcular la precisión: In [9]: # The function to calculate the accuracy def accuracy(model, data set): , yhat = torch.max(model(data set.x), 1) return (yhat == data set.y).numpy().mean() Entrenar y validar el modelo Crear un objeto dataset: In [10]: # Create a Dataset object data set = Data() data set.plot stuff() data set.y = data set.y.view(-1) 1.00 0.75 0.50 0.25 0.00 -0.25-0.50-0.75-1.00 -0.75 -0.50 -0.25 0.00 0.25 0.50 0.75 1.00 Creamos una red para clasificar 3 clases con 1 capa oculta con 50 neuronas: # Train the model with 1 hidden layer with 50 neurons In [11]: Layers = [2, 50, 3]model = Net(Layers) learning rate = 0.10optimizer = torch.optim.SGD(model.parameters(), lr=learning\_rate) train\_loader = DataLoader(dataset=data\_set, batch\_size=20) criterion = nn.CrossEntropyLoss() LOSS = train(data set, model, criterion, train loader, optimizer, epochs=100) plot decision regions 3class(model, data set) 0.75 0.70 0.65 0.60 total loss 0.55 2 0.50 🖁 0.45 1 0.40 0.35 0 1000 2000 3000 4000 5000 6000 7000 0 Iteration <ipython-input-2-9ec70c85e4d3>:15: MatplotlibDeprecationWarning: shading='flat' when X and Y have the same dimensions as C is deprecated since 3.3. Either specify the corne rs of the quadrilaterals with X and Y, or pass shading='auto', 'nearest' or 'gouraud', or set rcParams['pcolor.shading']. This will become an error two minor releases late plt.pcolormesh(xx, yy, yhat, cmap=cmap\_light) decision region 1.00 0.75 0.50 0.25 0.00 -0.25-0.50-0.75-1.00-0.75 -0.50 -0.25 0.00 0.25 0.50 0.75 1.00 Crear una red para clasificar 3 clases con 2 capas ocultas co 20 neuronas en total: Net([3,3,4,3]).parameters In [12]: <bound method Module.parameters of Net(</pre> Out[12]: (hidden): ModuleList( (0): Linear(in\_features=3, out\_features=3, bias=True) (1): Linear(in\_features=3, out\_features=4, bias=True) (2): Linear(in features=4, out features=3, bias=True) ) > # Train the model with 2 hidden layers with 20 neurons In [13]: Layers = [2, 10, 10, 3]model = Net(Layers) learning rate = 0.01 optimizer = torch.optim.SGD(model.parameters(), lr=learning rate) train loader = DataLoader(dataset=data set, batch size=20) criterion = nn.CrossEntropyLoss() LOSS = train(data set, model, criterion, train loader, optimizer, epochs=1000) plot decision regions 3class(model, data set) 1.0 2.5 0.9 2.0 0.8 1.5 0.7 0.6 ∺ 1.0 0.5 0.5 0.4 0.0 10000 20000 30000 40000 50000 60000 70000 Iteration <ipython-input-2-9ec70c85e4d3>:15: MatplotlibDeprecationWarning: shading='flat' when X and Y have the same dimensions as C is deprecated since 3.3. Either specify the corne rs of the quadrilaterals with X and Y, or pass shading='auto', 'nearest' or 'gouraud', This will become an rcParams['pcolor.shading']. plt.pcolormesh(xx, yy, yhat, cmap=cmap\_light) decision region 0.75 0.50 0.25 0.00 -0.25-0.50y=1 -0.75-1.00-0.250.00 1.00 Práctica Crear una red con 3 capas ocultas cada una con 10 neuronas y entrenar la red: In [14]: # Practice: Create a network with three hidden layers each with ten neurons. Layers = [2, 10, 10, 10, 3]model = Net(Layers) learning rate = 0.01optimizer = torch.optim.SGD(model.parameters(), lr = learning rate) train loader = DataLoader(dataset = data set, batch size = 20) criterion = nn.CrossEntropyLoss() LOSS = train(data set, model, criterion, train loader, optimizer, epochs = 1000) plot decision regions 3class(model, data set) 1.0 0.9 6 0.8 5 0.7 4 OSS 0.6 3 0.5 2 0.4 1 0.3 0 30000 40000 10000 20000 50000 60000 Iteration <ipython-input-2-9ec70c85e4d3>:15: MatplotlibDeprecationWarning: shading='flat' when X and Y have the same dimensions as C is deprecated since 3.3. Either specify the corne rs of the quadrilaterals with X and Y, or pass shading='auto', 'nearest' or 'gouraud', or set rcParams['pcolor.shading']. This will become an error two minor releases late plt.pcolormesh(xx, yy, yhat, cmap=cmap light) decision region 1.00 0.75 0.50 0.25 0.00 -0.25-0.50y=1 -0.75y=2 -1.00-1.00 -0.75 -0.50 -0.25 0.00 0.25 0.50 0.75 1.00

Redes neuronales profundas con nn.ModuleList()

**Objetivos** 

2. Entrenar y validar el modelo

Tabla de contenido

1. Crear una red neuronal profunda con nn.ModuleList()