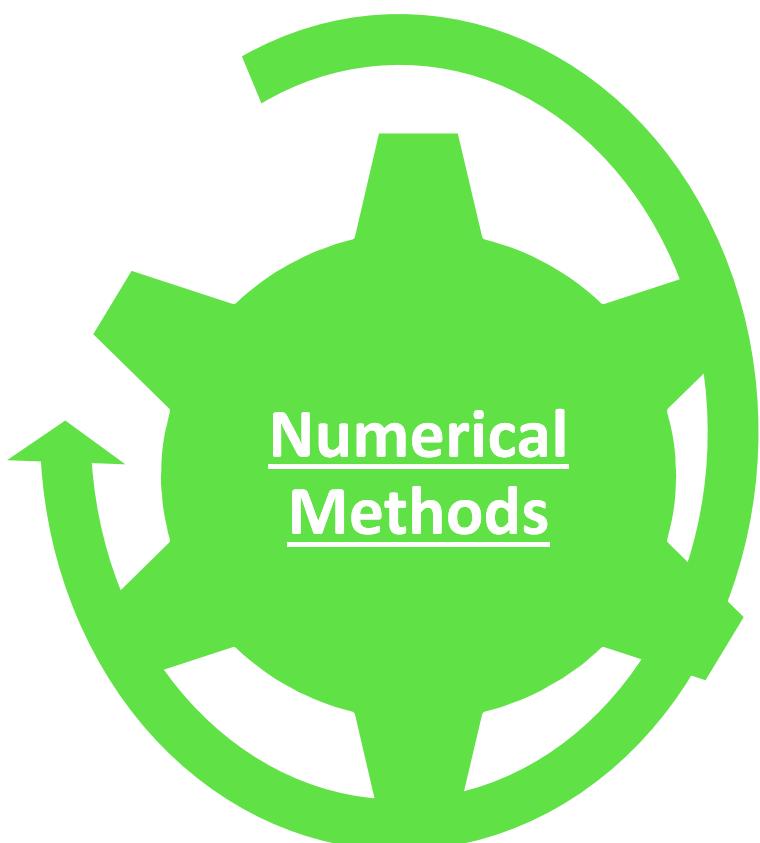


# NUMERICAL METHODS

## Lecture 0

Dr. P V Ramana

# Methods



# Methods

## Analytical Methods

$$EI \frac{d^2 u}{dx^2} = M, EI \frac{d^4 u}{dx^4} = w$$

$$D \left( \frac{\delta^4 u}{\delta x^4} + 2 \frac{\delta^4 u}{\delta x^2 \delta y^2} + \frac{\delta^4 u}{\delta y^4} \right) = w$$

$$D \left( \frac{\delta^4 u}{\delta x^4} + \frac{\delta^4 u}{\delta y^4} + \frac{\delta^4 u}{\delta z^4} + 2 \frac{\delta^4 u}{\delta x^2 \delta y^2} + 2 \frac{\delta^4 u}{\delta y^2 \delta z^2} + 2 \frac{\delta^4 u}{\delta x^2 \delta z^2} \right) = w$$

## Numerical Methods

Finite Element/Strip/Difference/Volume Methods

Boundary Element/Knot/Particle Methods

Domain Decomposition / Neumann & Neumann Methods

## Experimental Methods

Can't Simulate

Skilled persons required

# What do we need?

**Basic Needs in the Numerical Methods:**

**Practical:**

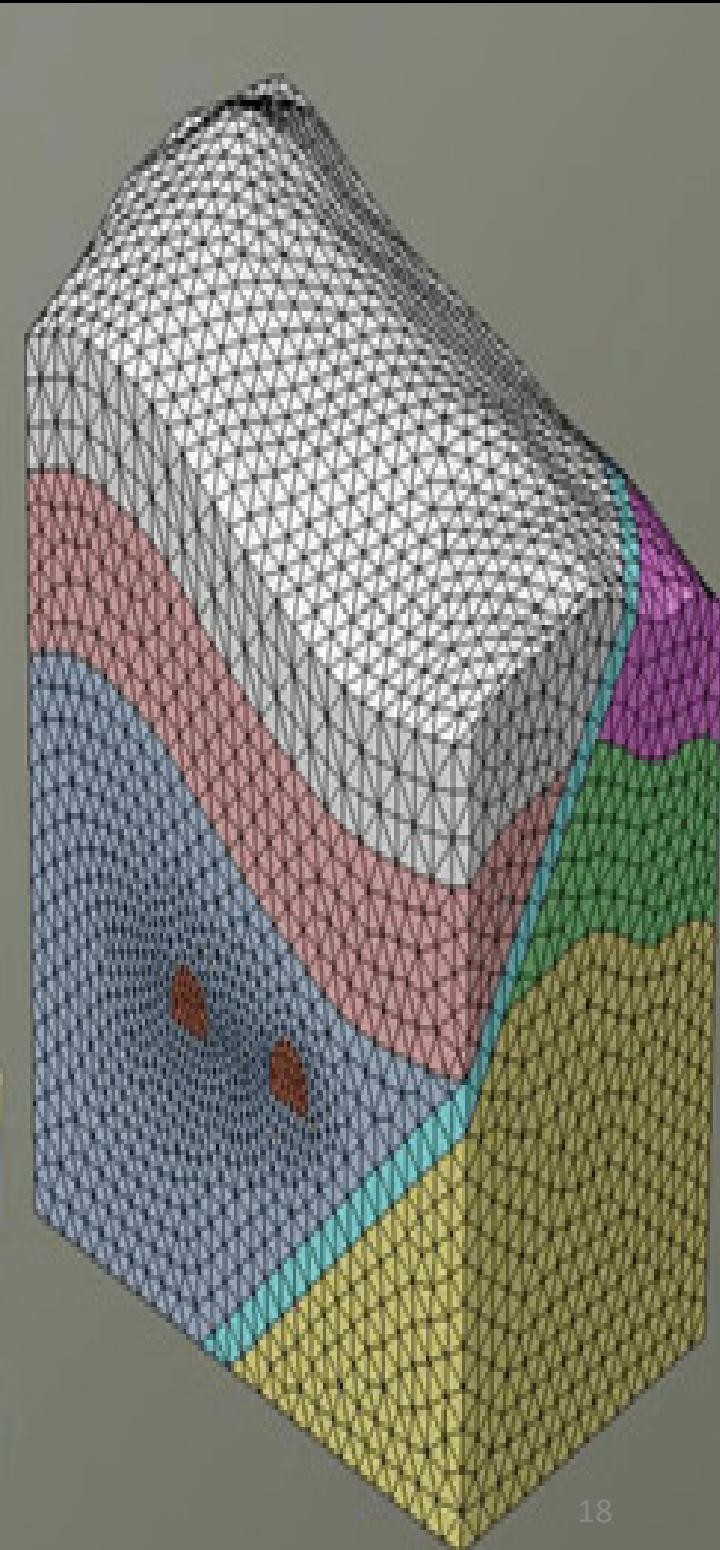
Can be computed in a reasonable amount of time.

**Accurate:**

**Good approximate to the true value,  
Information about the approximation  
error (Bounds, error order,... ).**

Solution of Linear Equation  $y = mx + c$

$$4x + 3 = 0$$



# Solution of Nonlinear Equations

- Some simple equations can be solved analytically:

$$x^2 + 4x + 3 = 0$$

Analytic solution

$$\text{roots} = \frac{-4 \pm \sqrt{4^2 - 4(1)(3)}}{2(1)}$$

$$x = -1 \text{ and } x = -3$$

- Many other equations have no analytical solution:

$$\left. \begin{array}{l} x^9 - 2x^2 + 5 = 0 \\ x = e^{-x} \end{array} \right\} \text{No analytic solution}$$

Find the minimum of the following function both analytically and numerically:

$$y = x^2 - 3x + 2$$

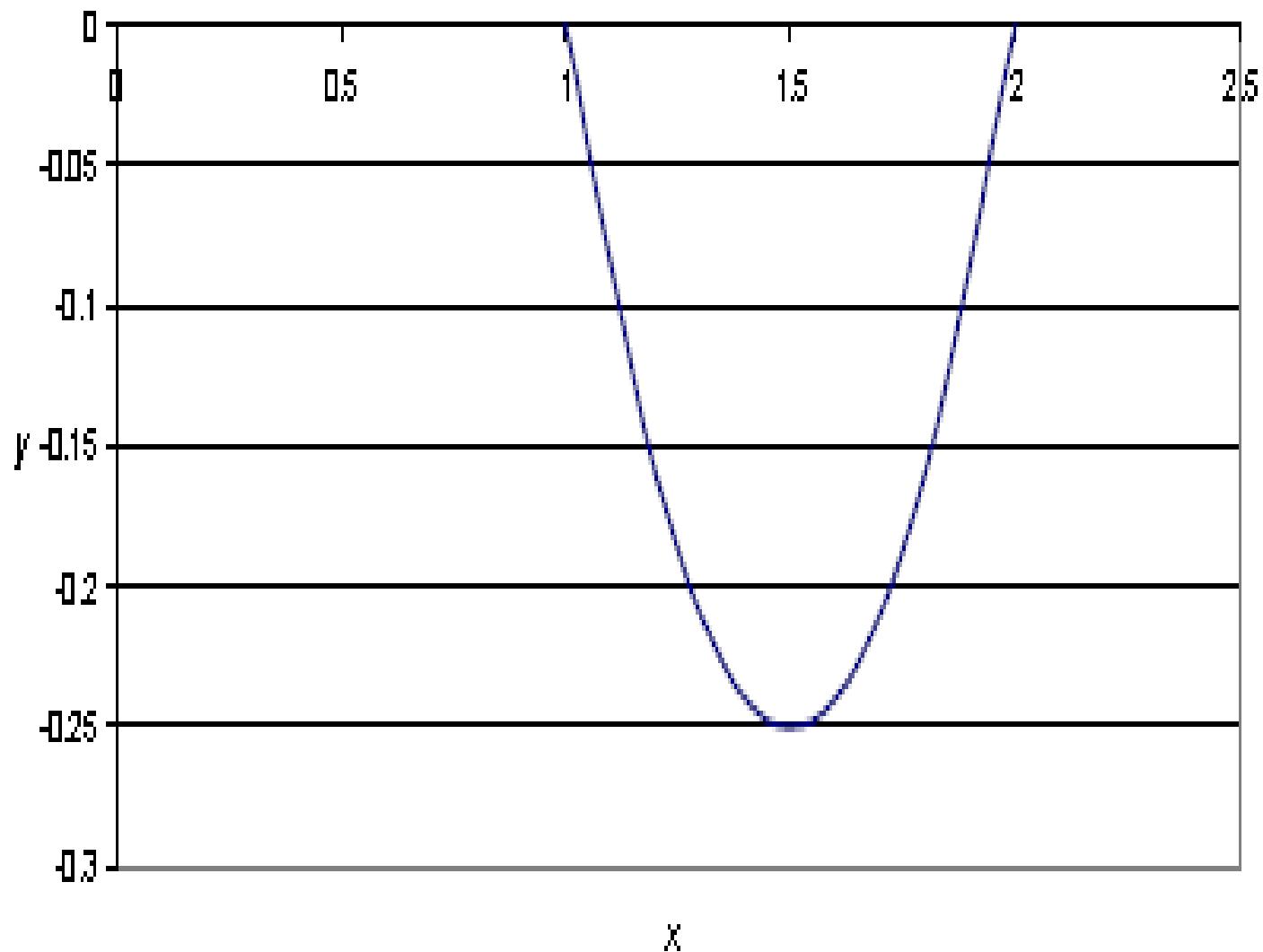
## Analytical Solution:

$$\frac{dy}{dx} = 2x - 3 = 0 \Rightarrow x = \frac{3}{2} = 1.5$$

Therefore,  $y_{\min} = (1.5)^2 - 3(1.5) + 2 = -0.25$

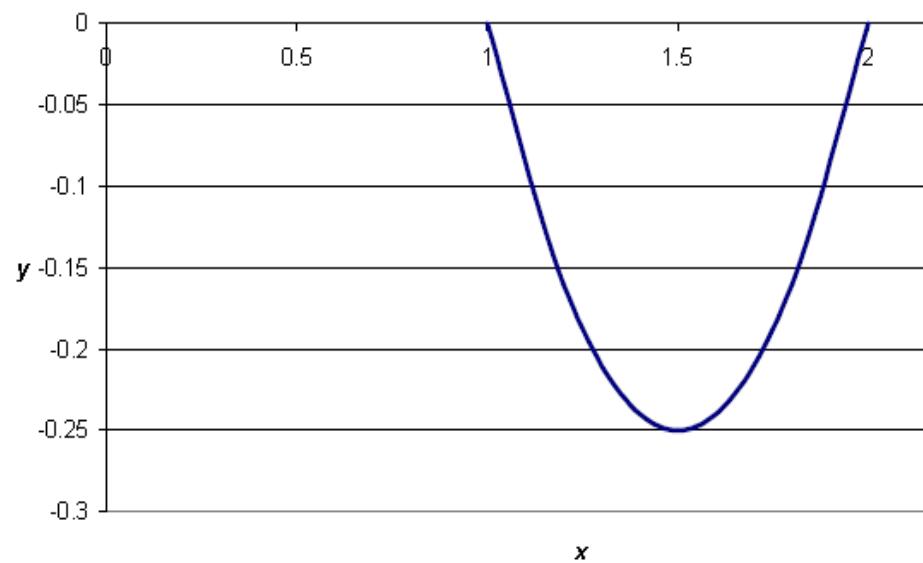
$x$	$y$
1	0
1.2	-0.16
1.4	-0.24
1.6	-0.24
1.8	-0.16
2	0

$$y = x^2 - 3x + 2$$



## ■ Example (cont'd): Analytical Vs. Numerical

$$y = x^2 - 3x + 2$$



$x$	$y$
1.4	-0.24
1.42	-0.2436
1.44	-0.2464
1.46	-0.2484
1.48	-0.2496
1.5	-0.25
1.52	-0.2496
1.54	-0.2484
1.56	-0.2464
1.58	-0.2436
1.6	-0.24

$y_{\min}$

# Methods for Solving Nonlinear Equations

Open Methods

Secant  
Method

Closed or Bracket  
Methods

Newton-Raphson  
Method

Bisection Method

# Solution of Systems of Linear Equations

$$x_1 + x_2 = 3$$

$$x_1 + 2x_2 = 5$$

$$\begin{bmatrix} 1 & 1 \\ 1 & 2 \end{bmatrix} \begin{Bmatrix} x_1 \\ x_2 \end{Bmatrix} = \begin{bmatrix} 3 \\ 5 \end{bmatrix}$$

One can solve it as :

$$x_1 = 3 - x_2, \quad 3 - x_2 + 2x_2 = 5$$

$$\Rightarrow x_2 = 2, \quad x_1 = 3 - 2 = 1$$

$$\begin{Bmatrix} x_1 \\ x_2 \end{Bmatrix} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

What to do if we have  
1000 equations in 1000 unknowns.

# Methods for Solving Systems of Linear Equations

$$\begin{array}{cccc|c} a_{11} & a_{12} & a_{13} & \cdots & a_{1n} & c_1 \\ a''_{22} & a''_{23} & \cdots & a''_{2n} & c''_2 \\ a'''_{33} & \cdots & a_{3n} & c'''_3 \\ \vdots & & \vdots & & \vdots \\ a_{nn}^{\text{n dashes}} & & & & c_n \end{array}$$

$$\begin{aligned} x_1^{(k+1)} &= \frac{1}{a_{11}}[b_1 - a_{12}x_2^{(k)} - a_{13}x_3^{(k)} - \cdots - a_{1n}x_n^{(k)}] \\ x_2^{(k+1)} &= \frac{1}{a_{22}}[b_2 - a_{21}x_1^{(k+1)} - a_{23}x_3^{(k)} - \cdots - a_{2n}x_n^{(k)}] \\ x_3^{(k+1)} &= \frac{1}{a_{33}}[b_3 - a_{31}x_1^{(k+1)} - a_{32}x_2^{(k+1)} - \cdots - a_{3n}x_n^{(k)}] \\ &\vdots \\ x_n^{(k+1)} &= \frac{1}{a_{nn}}[b_n - a_{n1}x_1^{(k+1)} - a_{n2}x_2^{(k+1)} - \cdots - a_{n,n-1}x_{n-1}^{(k+1)}] \end{aligned}$$

$$\begin{array}{ccccc} f_1 & g_1 & & & r_1 \\ e_2 & f_2 & g_2 & & r_2 \\ e_2 & f_3 & g_3 & & r_3 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ e_{n-1} & f_{n-1} & g_{n-1} & & r_{n-1} \\ e_n & f_n & & & r_n \end{array} = \left\{ \begin{array}{l} x_1 \\ x_2 \\ x_3 \\ \vdots \\ x_{n-1} \\ x_n \end{array} \right\} = \left\{ \begin{array}{l} r_1 \\ r_2 \\ r_3 \\ \vdots \\ r_{n-1} \\ r_n \end{array} \right\}$$

Naive  
Gaussian  
Elimination

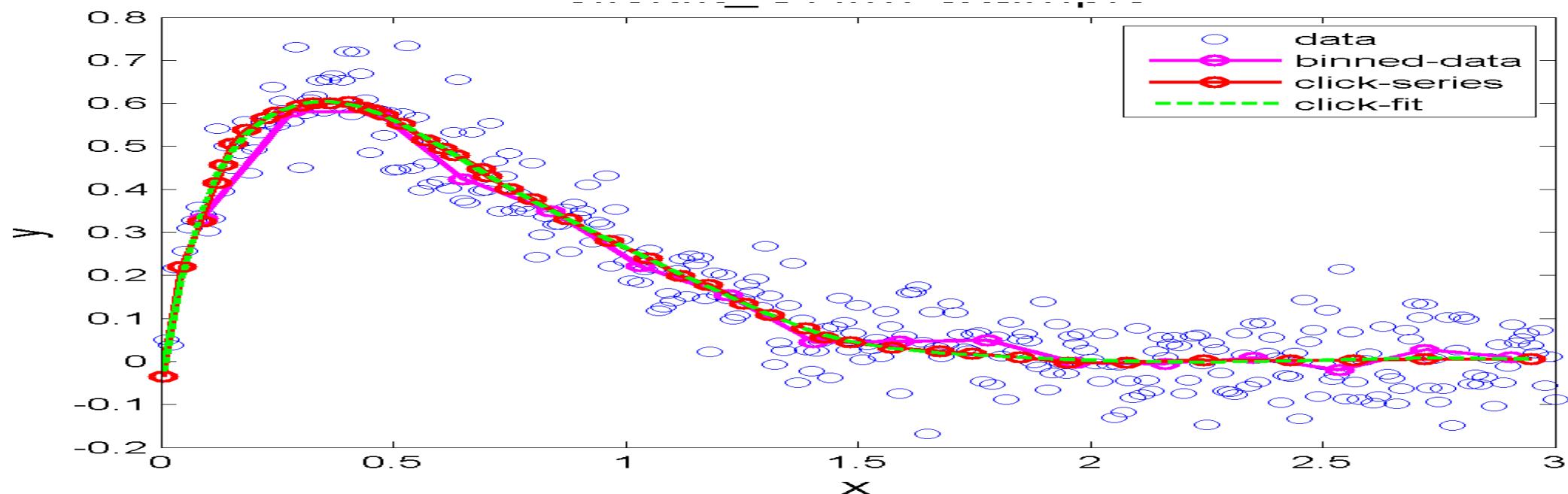
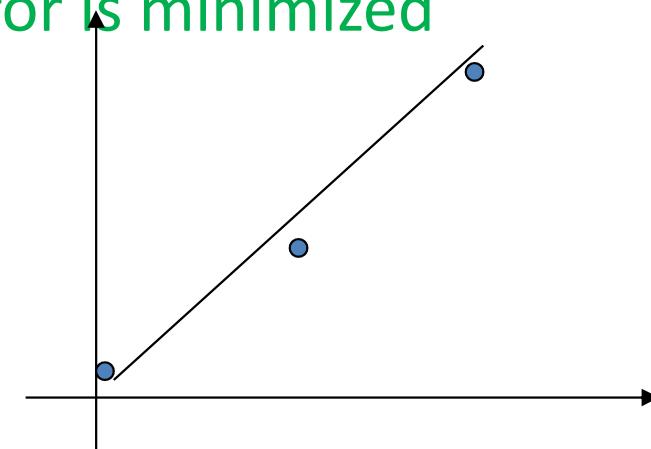
Gaussian  
Seidel

Algorithm  
for Tri-  
diagonal  
Equations

# Curve Fitting

- Given a set of data:
- Select a curve that best fits the data. One choice is to find the curve so that the sum of the square of the error is minimized

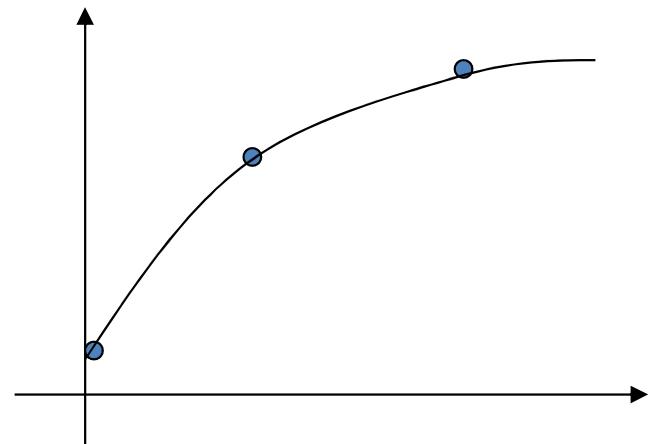
x	0	1	2
y	0.5	10.3	21.3



# Interpolation

- Given a set of data:

$x_i$	0	1	2
$y_i$	0.5	10.3	15.3



- Find a polynomial  $P(x)$  whose graph passes through all tabulated points.

$y_i = P(x_i)$  if  $x_i$  is in the table

# Methods for Curve Fitting

**Least Squares**

**Linear  
Regression**

**Nonlinear Least  
Squares Problems**

**Interpolation**

**Newton  
Polynomial  
Interpolation**

**Lagrange  
Interpolation**

# Integration

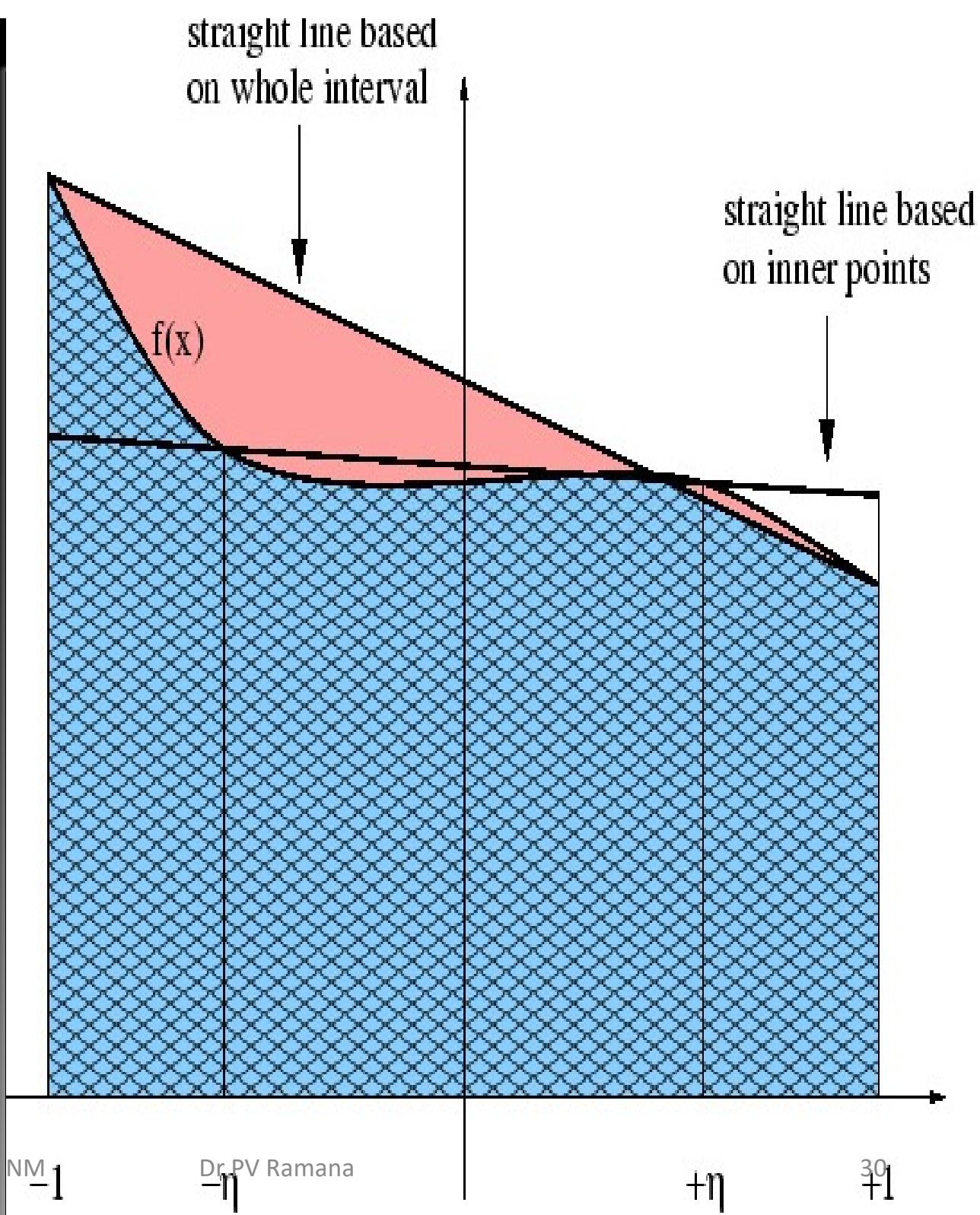
$$\int_1^3 x dx = \frac{1}{2} x^2 \Big|_1^3 = \frac{9}{2} - \frac{1}{2} = 4$$

But many functions have no analytical solutions :

$$\int_0^a e^{-x^2} dx = ?$$

# Methods for Numerical Integration

- ✓ Gauss Quadrature
- ✓ Trapezoid Method
- ✓ Romberg Method



# Differentiation

$$f(x) = x^3$$

$$(\therefore f'(x) = 3x^2 \quad f'(1) = 3)$$

$$f(x) = -0.1x^4 - 0.15x^3 - 0.5x^2 - 0.25x + 1.2$$

$$f'(x) = -0.4x^3 - 0.45x^2 - 1.0x - 0.25$$

But many functions have no analytical solutions :

$$f(x) = \frac{(\cos(100x^2))^5}{x^3}$$

# Solution of Ordinary Differential Equations

A solution to the differential equation :

$$\ddot{x}(t) + 3\dot{x}(t) + 3x(t) = 0$$

$$x(0) = 1; x'(0) = 0$$

$$\frac{2}{\sqrt{3}} e^{3t/2} \sin\left(\frac{\sqrt{3}t}{2}\right)$$

Non linear ODE :

$$\ddot{x}(t) + 3\dot{x}(t) + 3x^2(t) = 0; x(0) = 1; x'(0) = 0$$

is a function  $x(t)$  that satisfies the equations.

- \* Analytical solutions are available for special cases only.

# Solution of Partial Differential Equations

Partial Differential Equations are more difficult to solve than ordinary differential equations:

$$\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = 0;$$

$$u(0, y) = u(1, y) = 0, u(x, 0) = \sin(\pi x), u(x, 1) = -\sin(\pi x)$$

$$\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial t^2} + 2 = 0$$

$$u(0, t) = u(1, t) = 0, u(x, 0) = \sin(\pi x), u(x, 1) = -\sin(\pi x)$$

# Representing Real Numbers, Precision & Accuracy

- The decimal system as

$$312.45 = 3 \times 10^2 + 1 \times 10^1 + 2 \times 10^0 + 4 \times 10^{-1} + 5 \times 10^{-2}$$

- Decimal System: Base = 10 , Digits (0,1,...,9)
- Standard Representations:

$\pm$	3	1	2	.	4	5
sign	integral			fraction		
	part			part		

# Normalized Floating Point Representation

- Normalized Floating Point Representation:

$$\pm \frac{0. \underline{d_1 \ d_2 \ d_3 \ d_4}}{\text{sign} \qquad \text{mantissa}} \times 10^n \qquad \text{exponent}$$

$d_1 \neq 0, \quad n : \text{integer}$

- **No integral part,**
- **Advantage: Efficient in representing very small or very large numbers.**

# Calculator Example

- Suppose want to compute:

$3.578 * 2.139$

using a calculator with two-digit fractions

$$\boxed{3.57} \quad * \quad \boxed{2.13} \quad = \quad \boxed{7.60}$$

**True answer:**

**7.653342**

# Binary System

- Binary System: Base = 2, Digits {0,1}

$\pm \frac{0.1 b_2 b_3 b_4}{\text{sign}} \times 2^n$  

$$b_1 \neq 0 \Rightarrow b_1 = 1$$

$$(0.101)_2 = (1 \times 2^{-1} + 0 \times 2^{-2} + 1 \times 2^{-3})_{10} = (0.625)_{10}$$

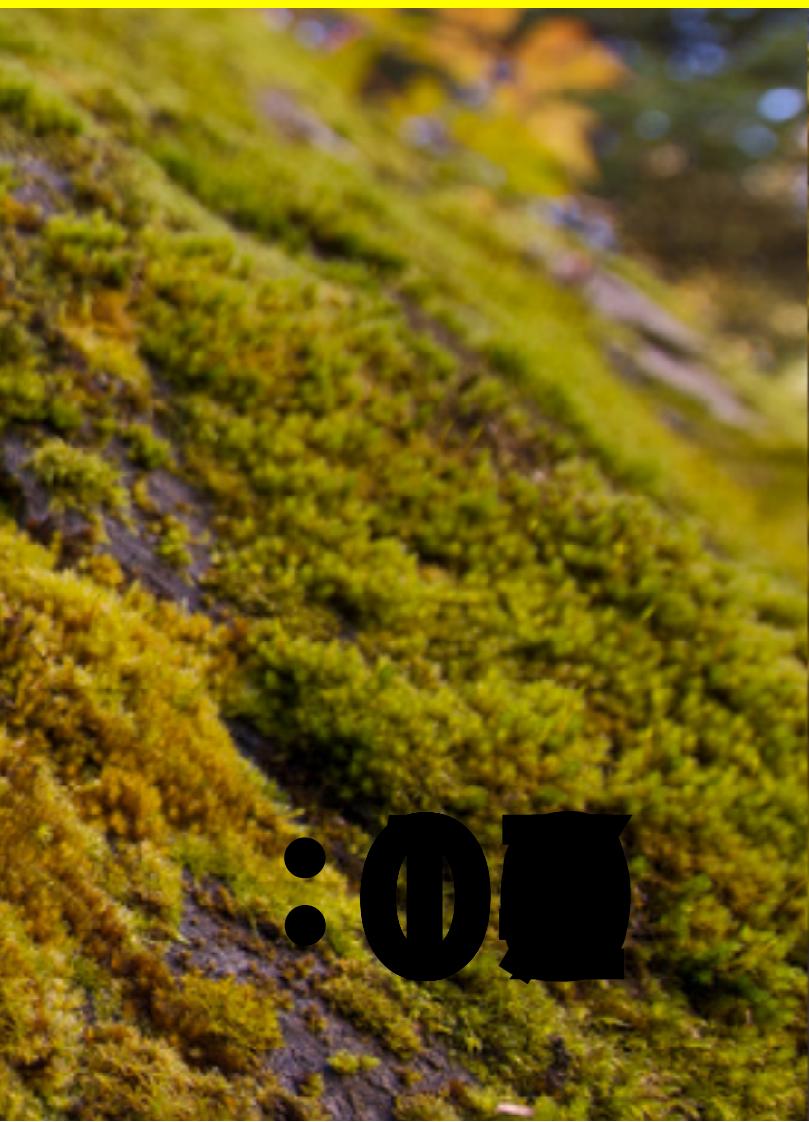
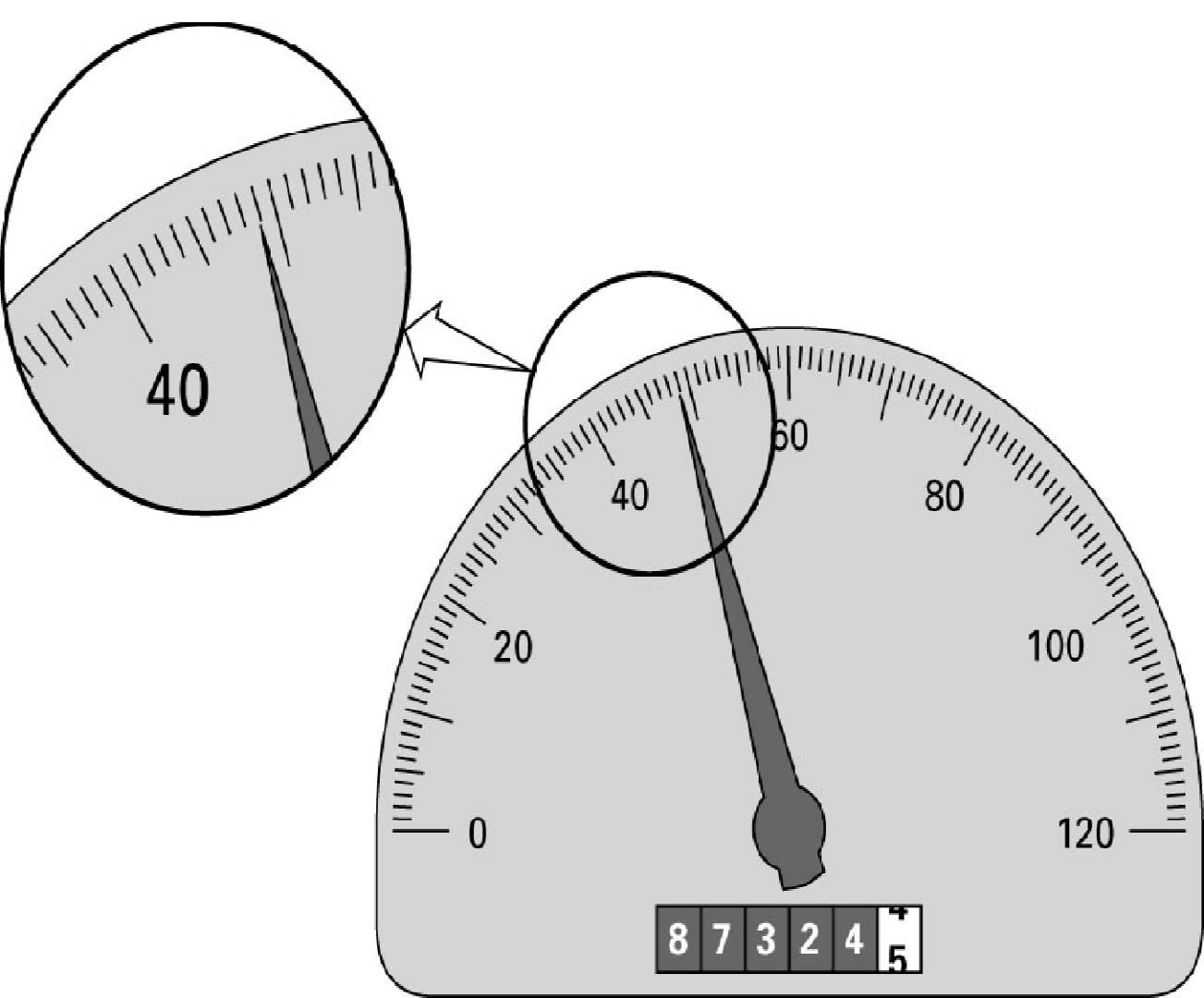
A close-up photograph of a mechanical gear assembly. Several interlocking gears of different sizes are visible, along with small metal pins and a central axis. The lighting highlights the metallic surfaces and the intricate tooth profiles of the gears.

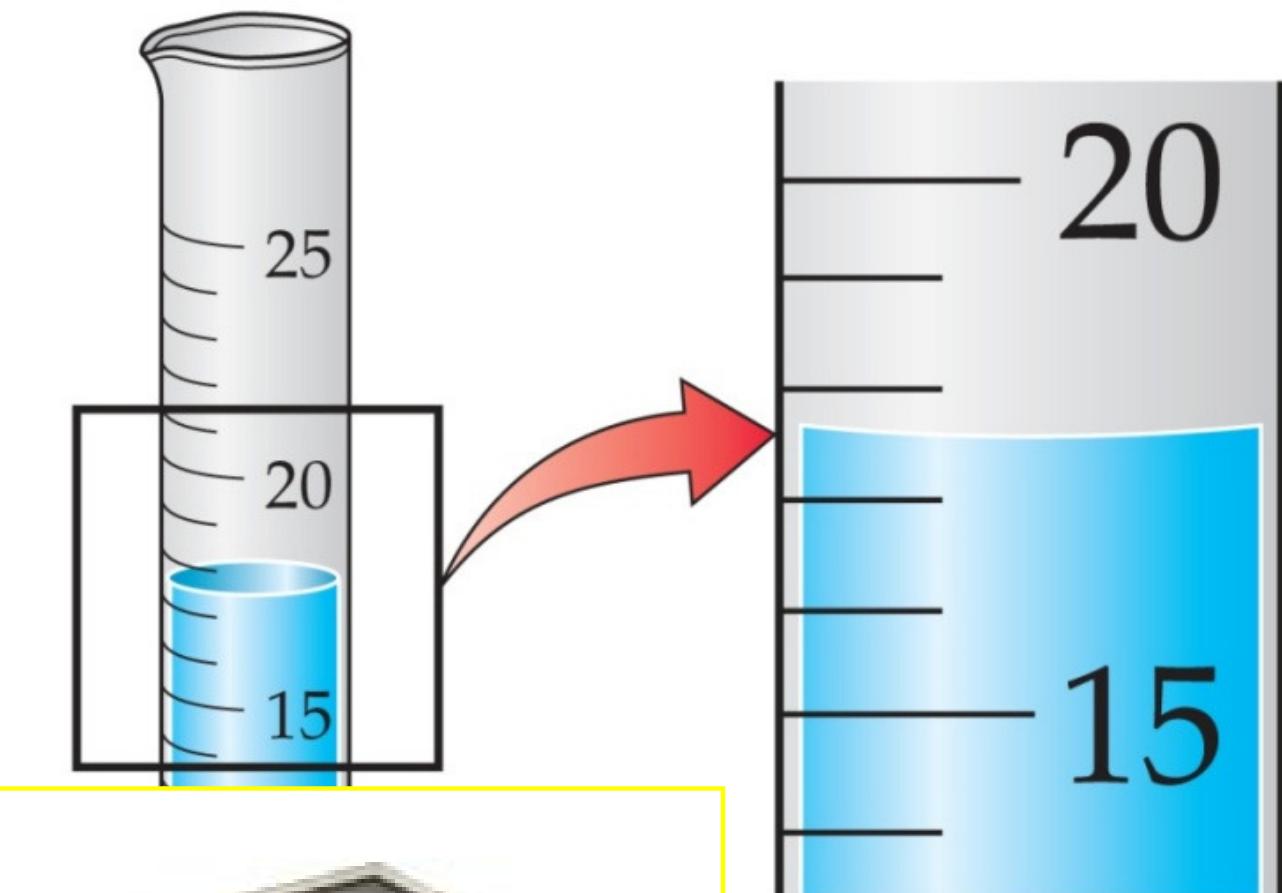
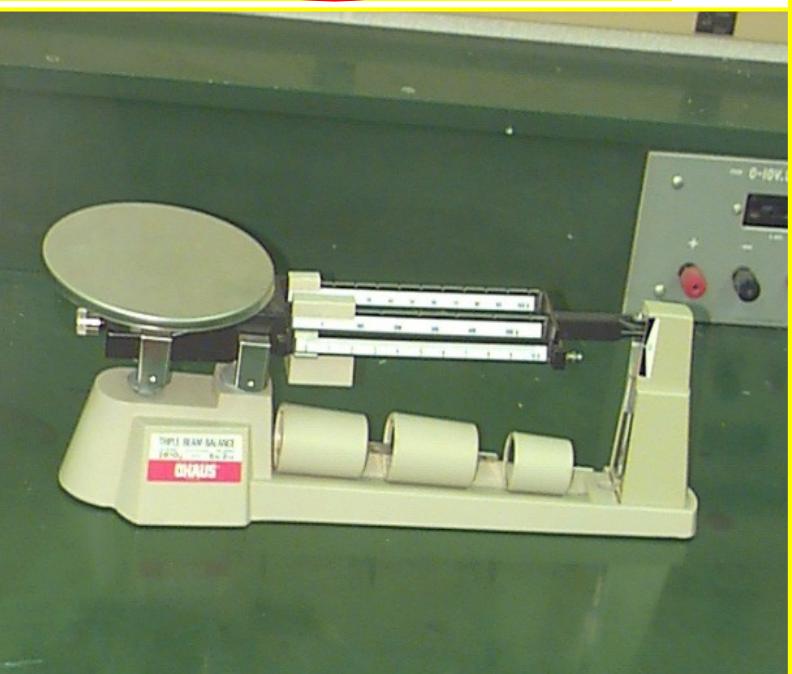
# Remarks

- ❖ Numbers that can be exactly represented are called machine numbers.
- ❖ Difference between machine numbers is not uniform
- ❖ Sum of machine numbers is not necessarily a machine number:
  - ❖  $0.25 + .3125 = 0.5625$  (not a machine number)

# Significant Digits

Significant digits are those digits that can be used with confidence.





17.  ? mL

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Dr PV Rajendra

n Prentice Hall, Inc.

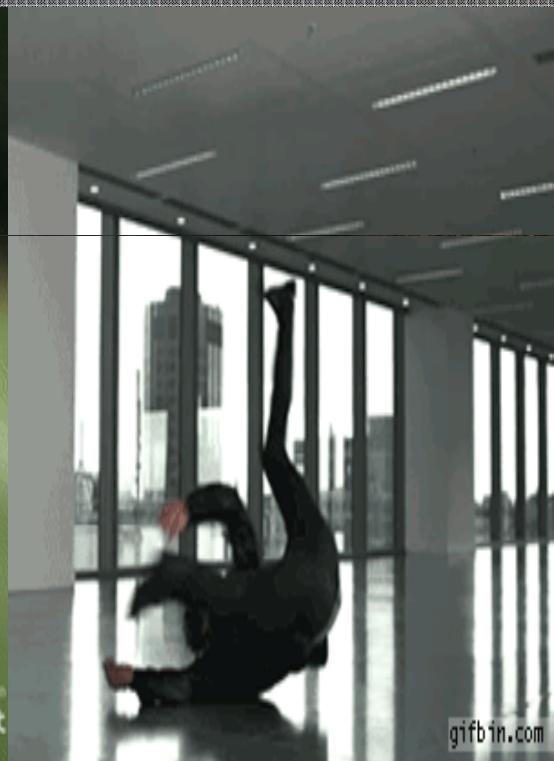
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# Accuracy and Precision

Accuracy is related to the closeness to the true value.

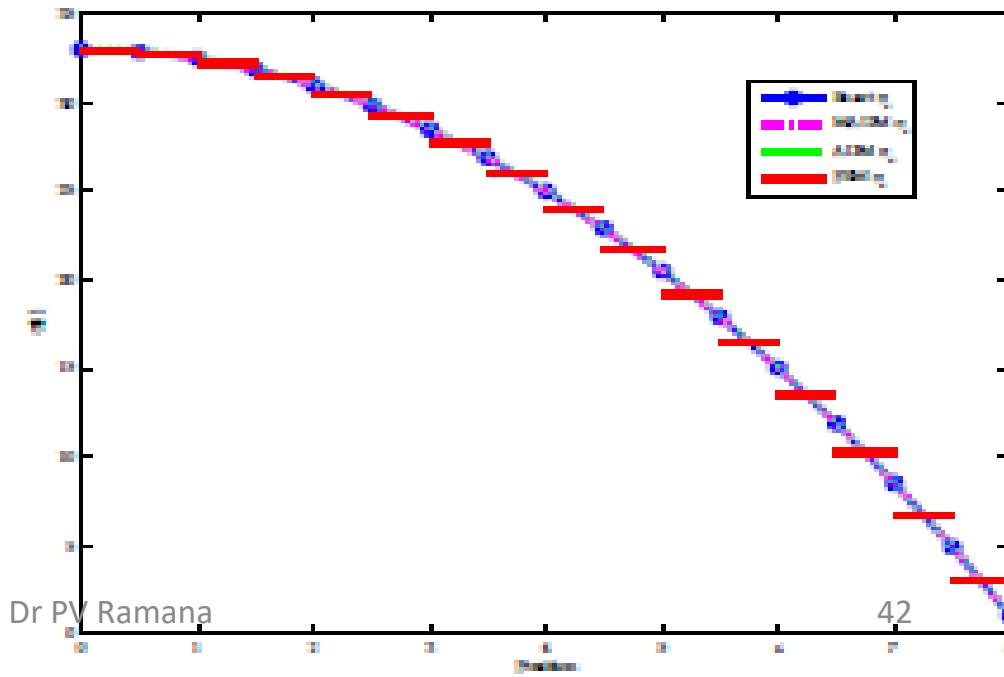
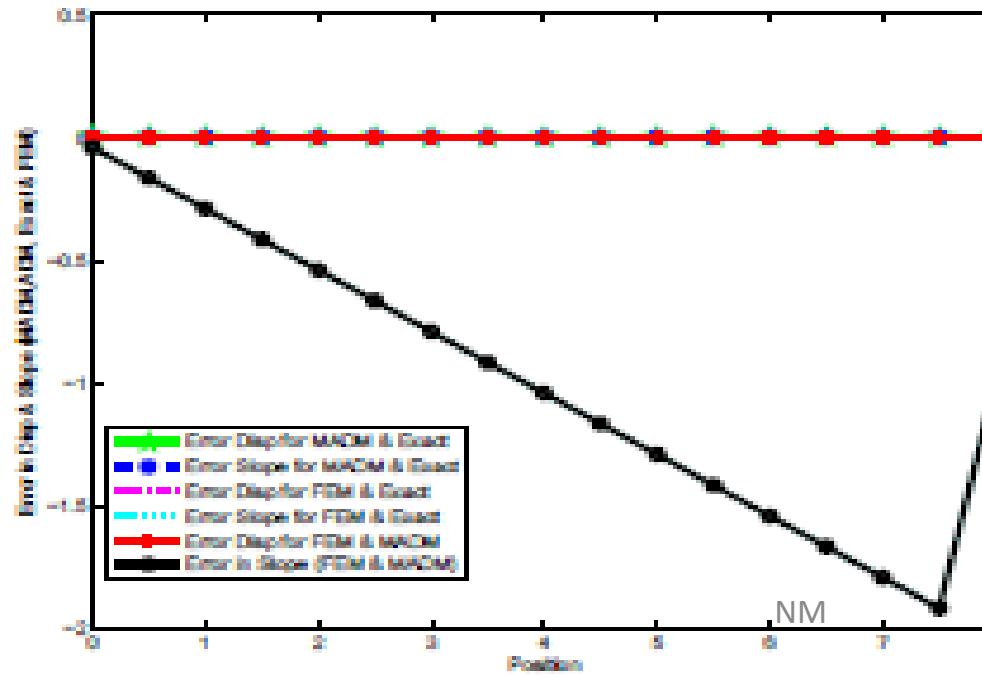
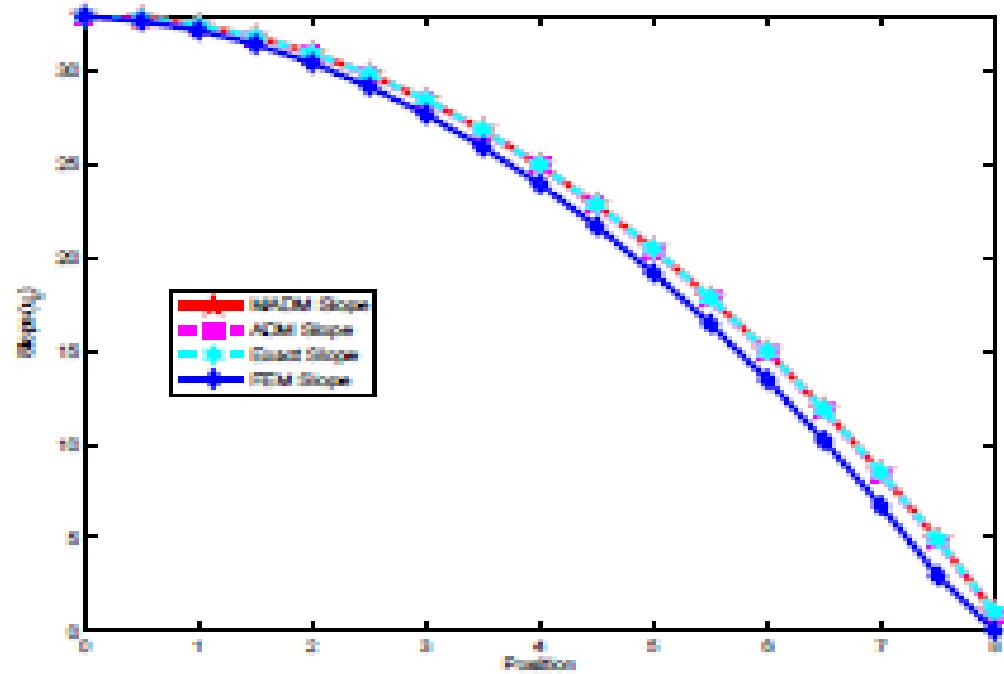
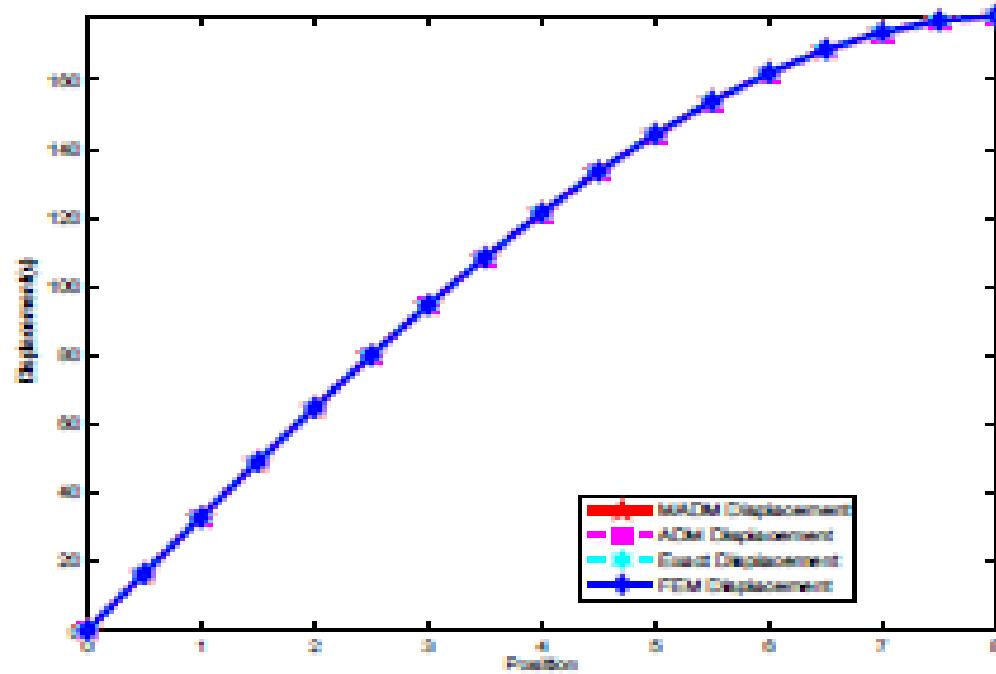
Precision is related to the closeness to other estimated values.

**Accuracy and Precision:** Accuracy refers to the closeness of a measured value to a standard or known value. For example, if in lab you obtain a weight measurement of 8.2 kg for a given substance, but the actual or known weight is 10 kg, then your measurement is not accurate.



Precision is a description of random errors, a measure of statistical variability.  
Accuracy is a description of systematic errors, a measure of statistical bias;

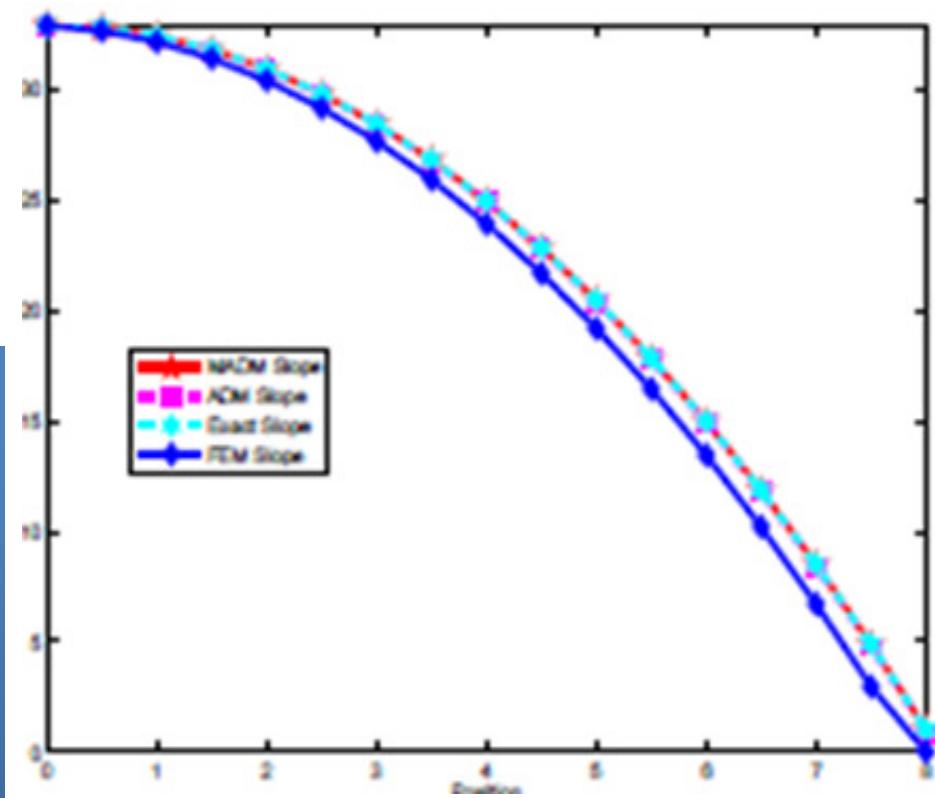
# Errors in Round off & Truncation



Absolute  
or True  
Error:

*True  
Fractional  
Relative  
Error:*

*True  
Percent  
Relative  
Error:*



$$E_t = \text{True value} - \text{Approximation value}$$

$$\epsilon_t = \frac{\text{True value} - \text{Approximate value}}{\text{True value}}$$

$$\epsilon_t = \frac{\text{True value} - \text{Approximate value} * 100\%}{\text{True value}}$$

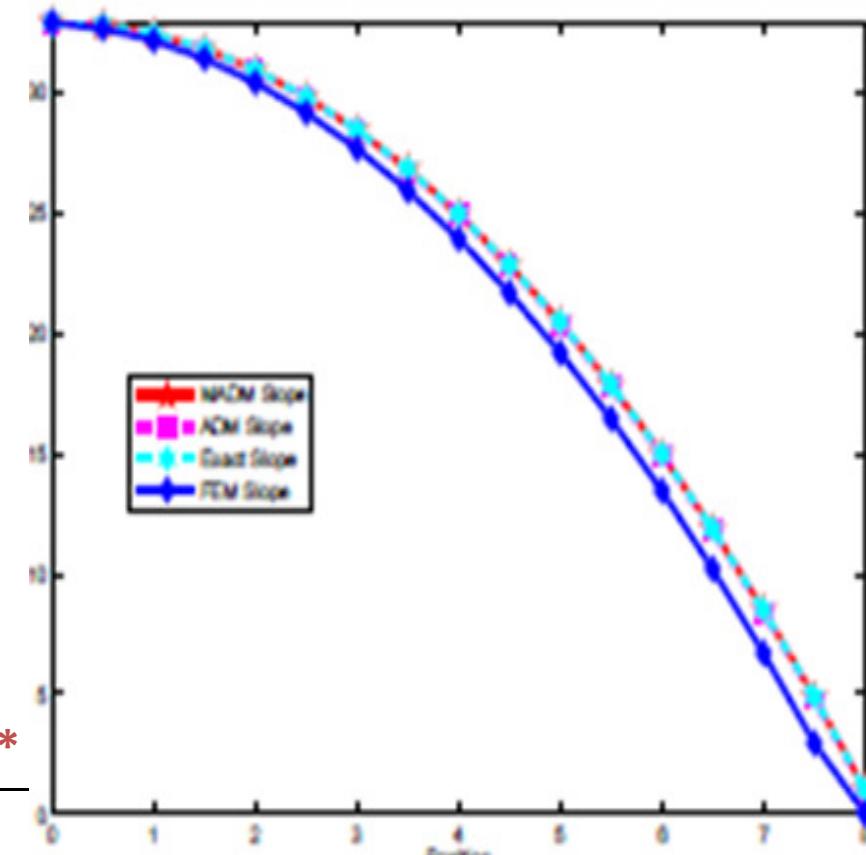
## When true value is not known

- *Approximate relative error:*

$$\epsilon_a = \frac{\text{approximate error} * 100\%}{\text{approximation}}$$

- Numerical methods using *iteration*

$$\epsilon_a = \frac{(\text{present approximate} - \text{previous approximate}) * 100\%}{\text{present approximation}}$$

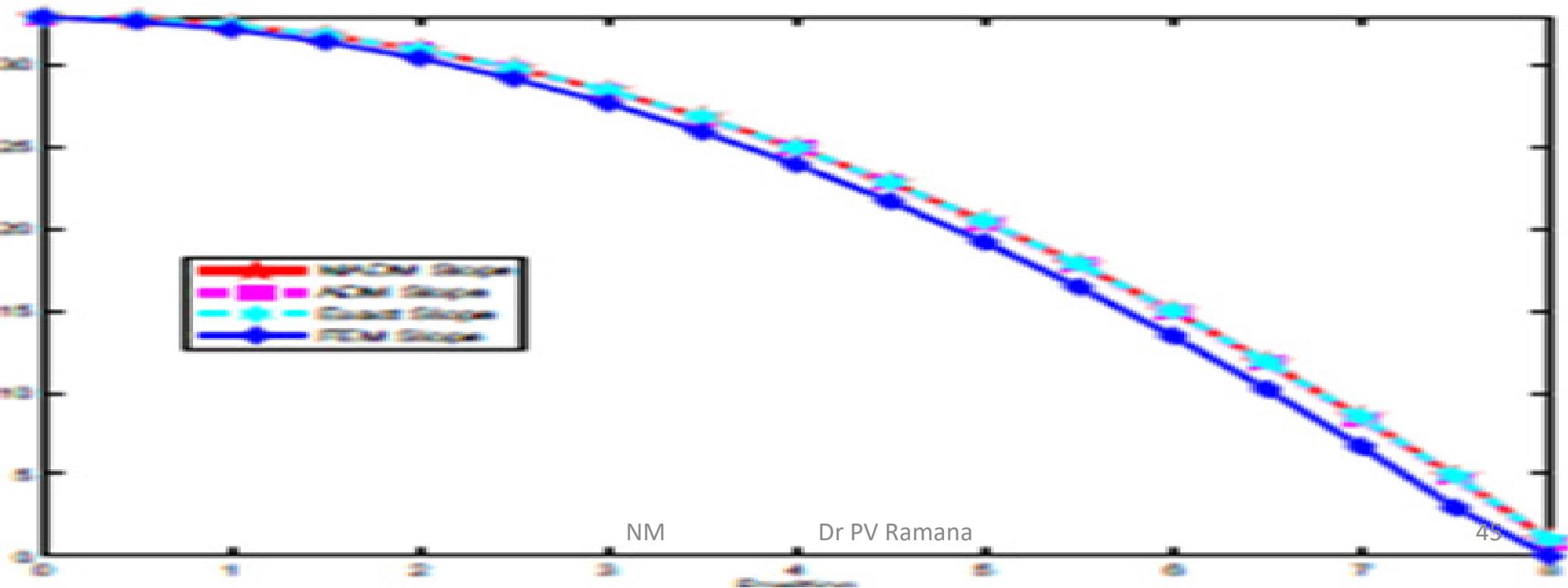


- Stopping criterion: Relative error is less than some tolerance value

- Accuracy of result up to  $n$  significant digits

$$\epsilon_s = (0.5 \times 10^{2-n}) \%$$

- When  $|\epsilon_a| < \epsilon_s$  then the result is correct up to  $n$  significant digits



# Error Estimation

01



*Errors are mainly associated with calculations and measurements*

02



*Accuracy: How closely a computed value or measured value agrees with true value*

03



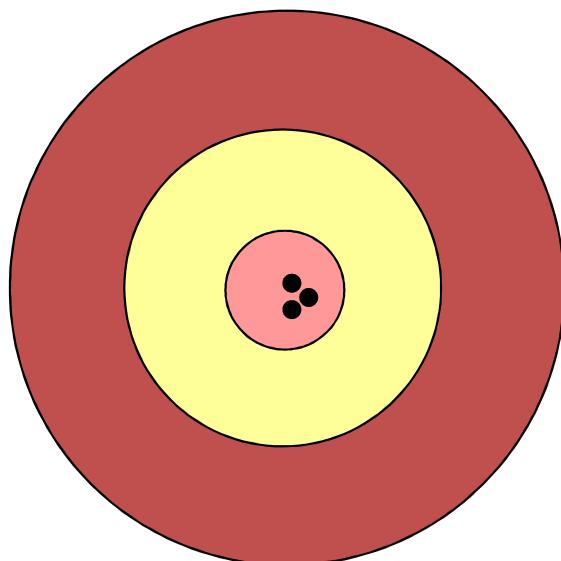
*Precision: How individual computed values or measured values agree with one another*

04

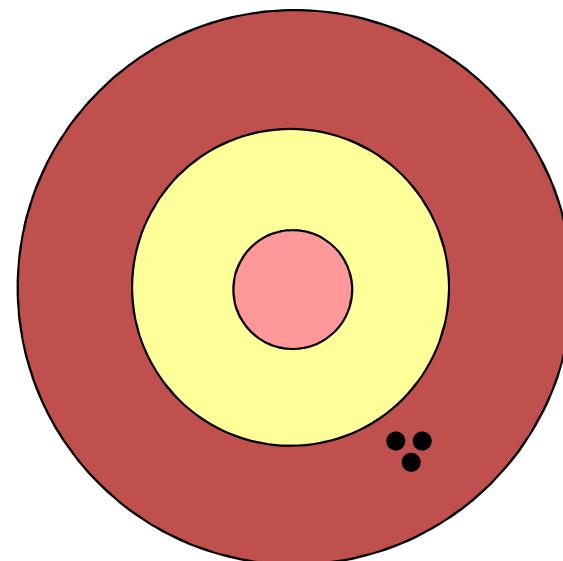
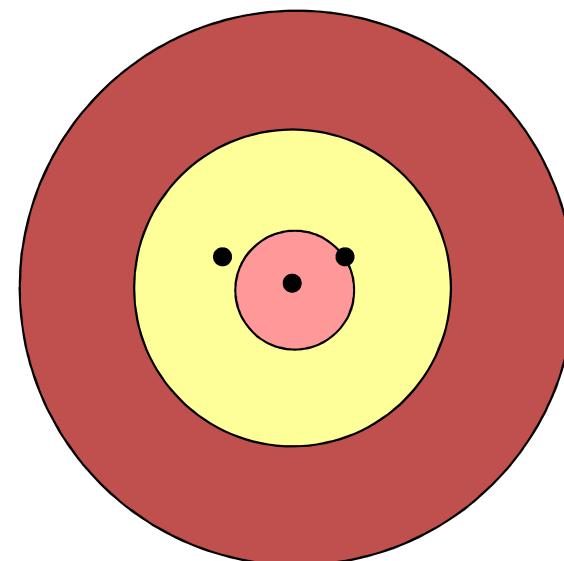


- Inaccuracy is also called *bias*
- Imprecision is also called *uncertainty*

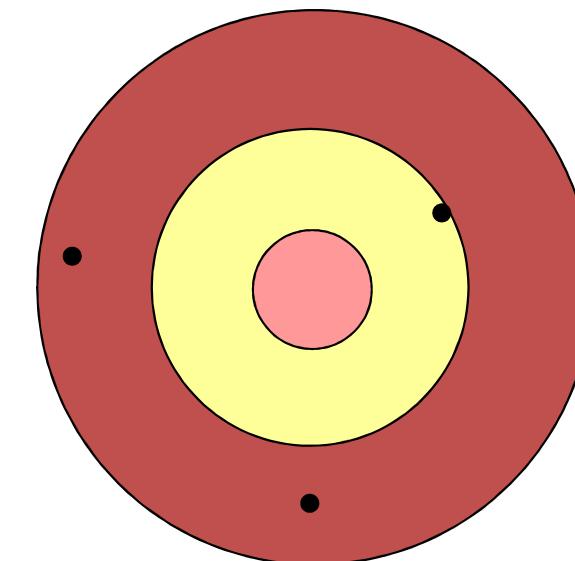
Accuracy & Precision



Accuracy without  
Precision



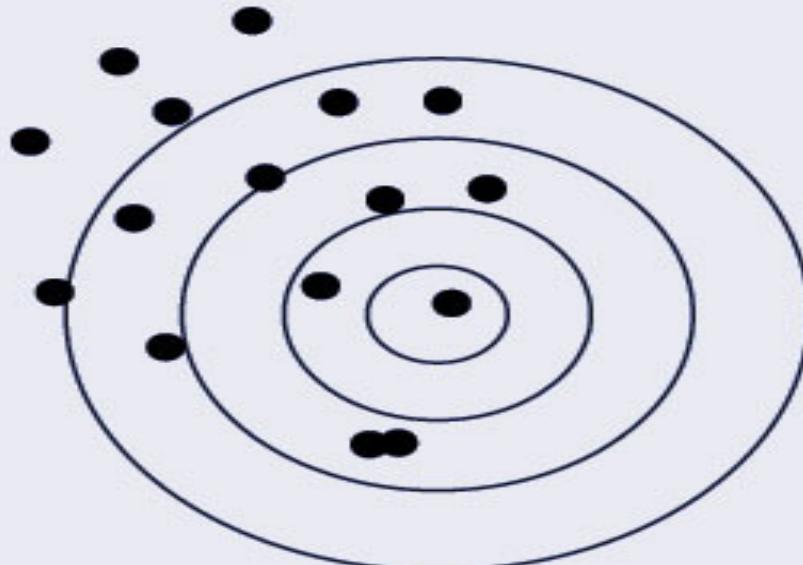
Precision without  
Accuracy



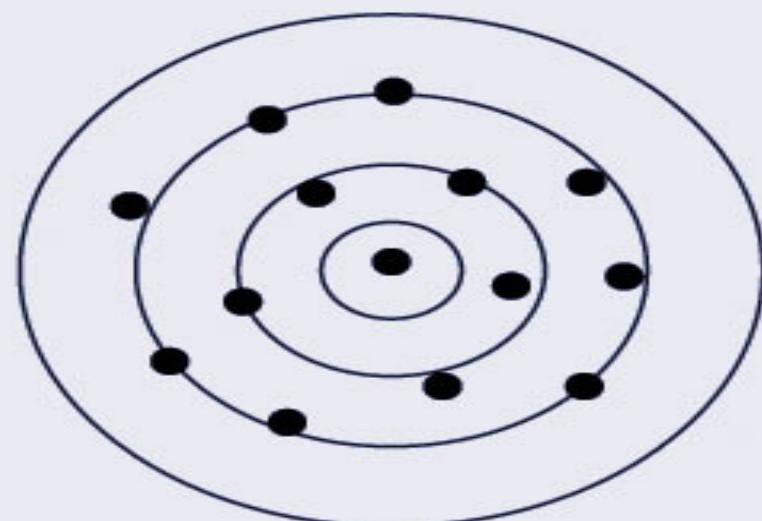
No Precision &  
No Accuracy

# Increasing accuracy

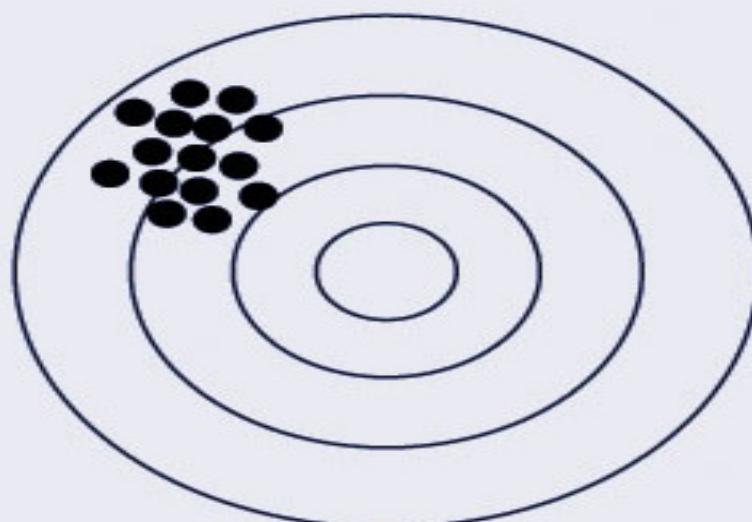
Increasing precision



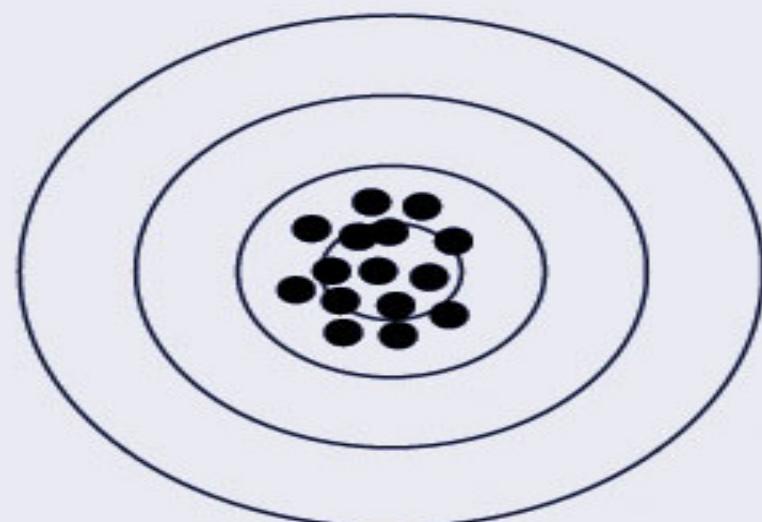
(a)



(b)



(c)



(d)

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# Types of Errors

Round-off errors:  $10/3, \pi, 7^{1/2}, e, \text{etc.}$  cannot be represented exactly

Truncation errors:

These errors are related to Taylor series

Blunders:

Due to human errors and machine imperfections

Formulation errors

Errors due to assumptions and data uncertainty

# ROUND OFF ERRORS

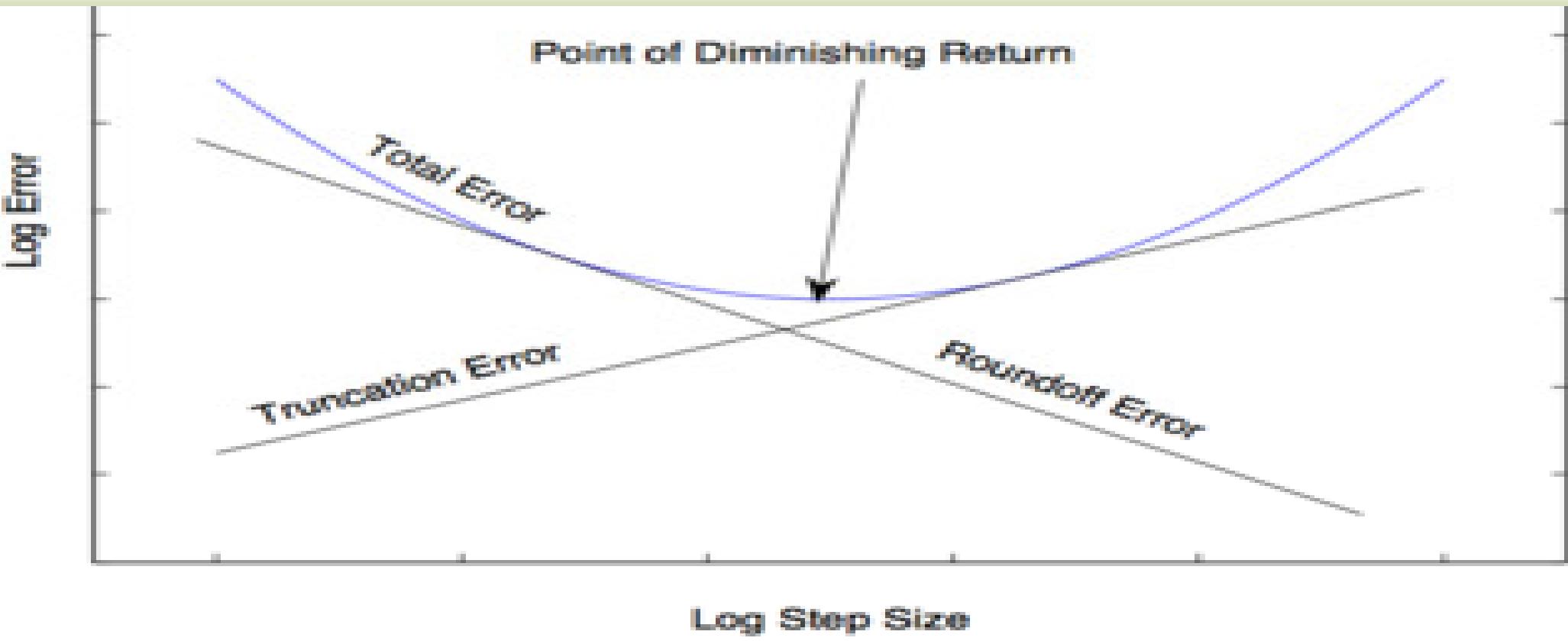
## Size and Precision limitations

- Integer representation
- Floating point representation
- Machine epsilon (machine precision)

Numerical manipulations are sensitive to round off errors

- Subtractive cancellation
- Large computations

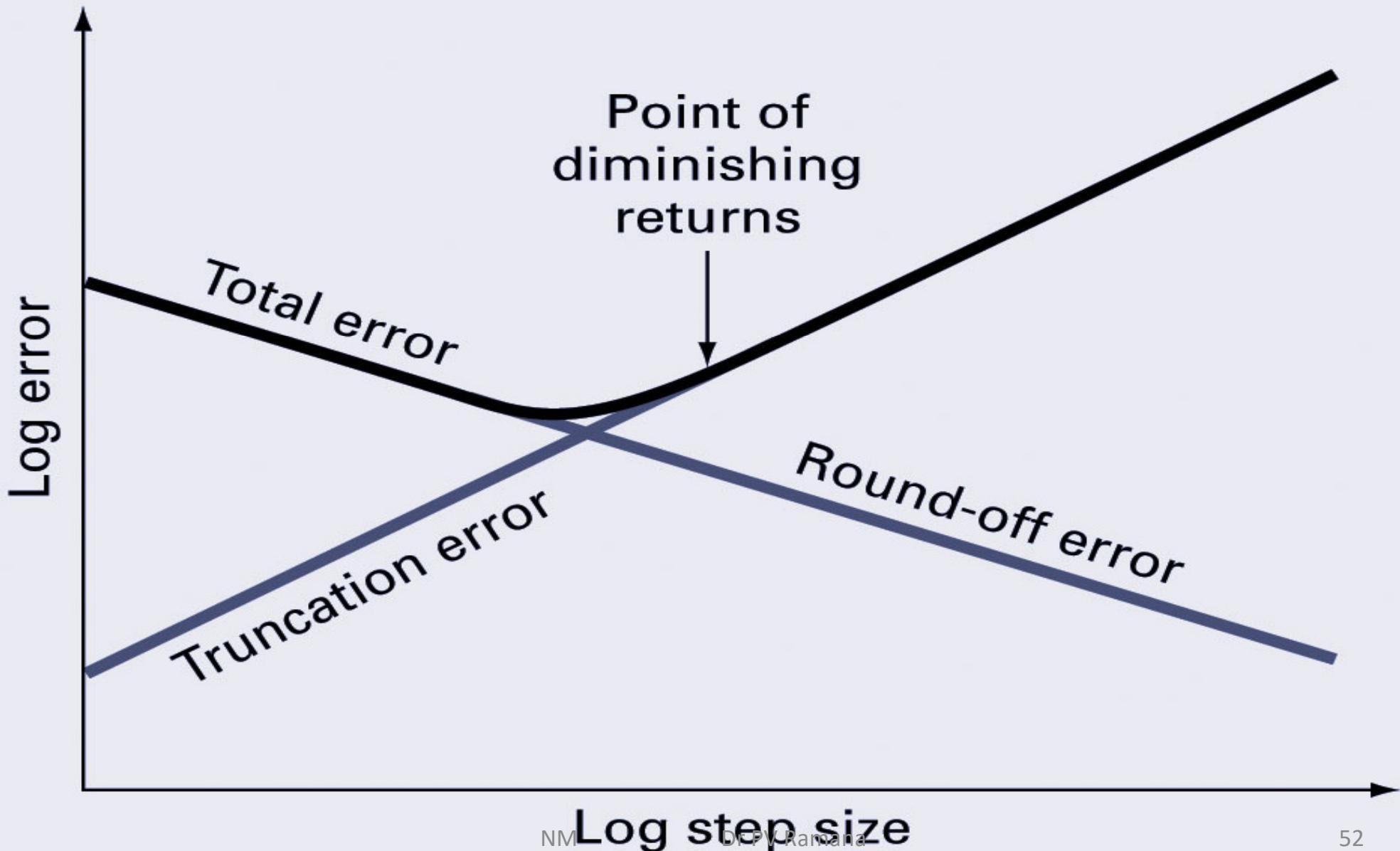
# TRUNCATION ERRORS



Result of using an approximation instead of exact mathematical procedure  
- Using Taylor series to approximate a polynomial function

# TOTAL NUMERICAL ERROR

- Summation of truncation and roundoff errors



# Rounding and Chopping

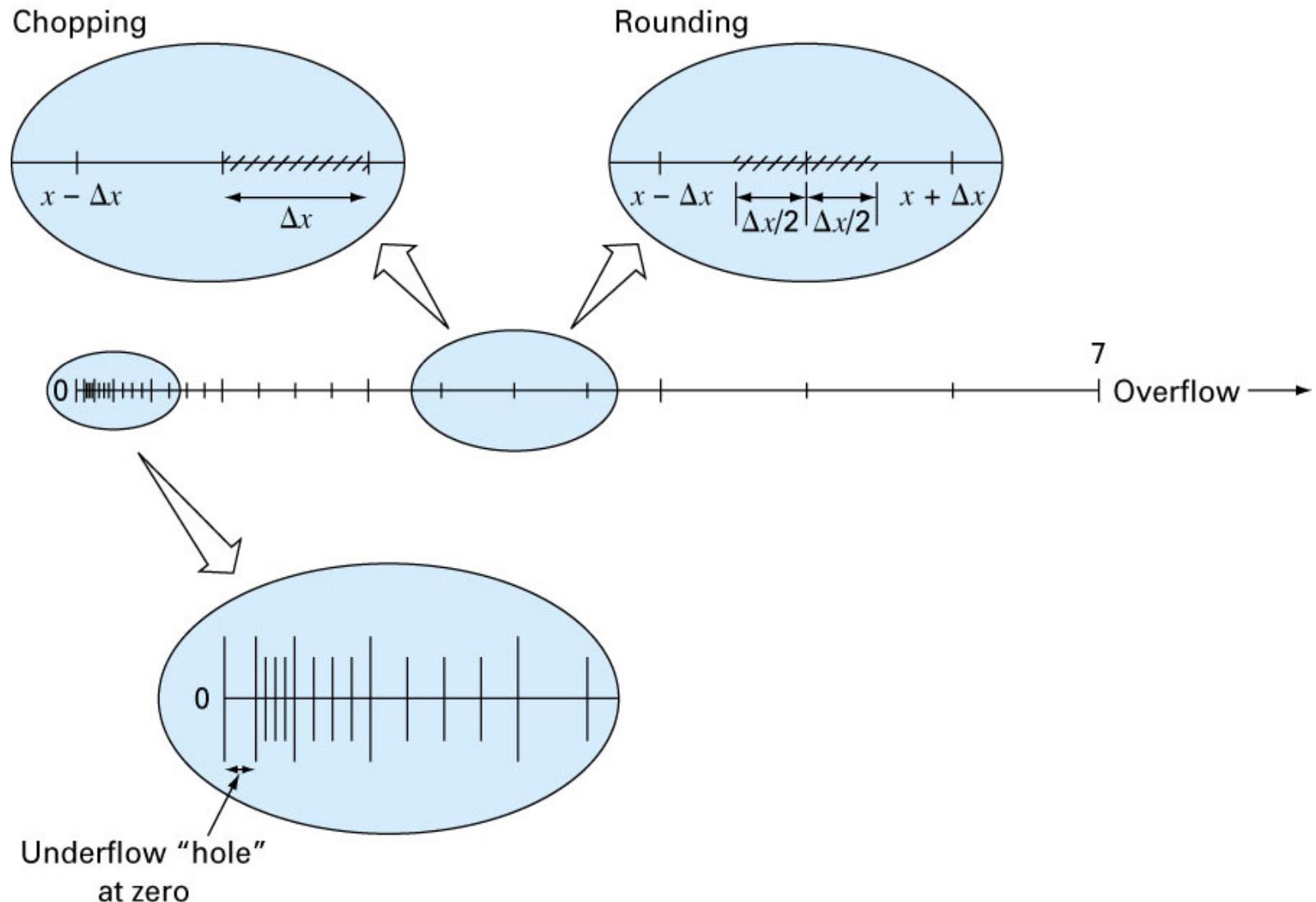
- Rounding: Replace the number by the nearest machine number.
- Chopping: Throw all extra digits.

12 → 10  
114 → 110  
57 → 60  
1,334 → 1330  
1,488 → 1490  
97 → 100

$$\begin{aligned}x &= 72.32451 = 0.7232451 \times 10^2 \\&= (0.7232 + 0.0000451) \times 10^2 \\&= (0.7232 + 0.451 \times 10^{-4}) \times 10^2\end{aligned}$$

∴ chopping error in representing  $x = 0.451 \times 10^{2-4}$ .

# Rounding and Chopping - Example



# Error Definitions – True Error

Can be computed if the true value is known:

Absolute True Error

$$E_t = | \text{true value} - \text{approximation} |$$

Absolute Percent Relative Error

$$\epsilon_t = \left| \frac{\text{true value} - \text{approximation}}{\text{true value}} \right| * 100$$

# Error Definitions – Estimated Error

When the true value is not known:

Estimated Absolute Error

$$E_a = | \text{current estimate} - \text{previous estimate} |$$

Estimated Absolute Percent Relative Error

$$\varepsilon_a = \left| \frac{\text{current estimate} - \text{previous estimate}}{\text{current estimate}} \right| * 100$$

# Notation

Say that the estimate is correct to  $n$  decimal digits if:

$$| \text{Error} | \leq 10^{-n}$$

Say that the estimate is correct to  $n$  decimal digits  
**rounded** if:

$$| \text{Error} | \leq \frac{1}{2} \times 10^{-n}$$

# Taylor Theorem

## Motivation

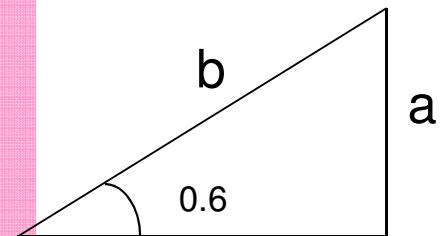
- One can easily compute expressions like:

$$\frac{3 \times 10^{-2}}{2(x+4)}$$

But, How do you compute  $\sqrt{4.1}$ ,  $\sin(0.6)$ ?

One can use the definition to compute  
 $\sin(0.6)$ ?

is this a practical way?



# Taylor Series

$$n^{\text{th}} \text{ order Taylor series: } f(x_{i+1}) \approx f(x_i) + f'(x_i)(x_{i+1} - x_i) + \frac{f''(x_i)}{2!}(x_{i+1} - x_i)^2 + \frac{f'''(x_i)}{3!}(x_{i+1} - x_i)^3$$

$$+ \dots + \frac{f^n(x_i)}{n!}(x_{i+1} - x_i)^n$$

$$f(a) + \frac{f'(a)}{1!}(x - a) + \frac{f''(a)}{2!}(x - a)^2 + \frac{f'''(a)}{3!}(x - a)^3 + \dots$$

$$\sum \sum_{n=0}^{\infty} \frac{f^{(n)}(a)}{n!} (x - a)^n$$

$$f(x+h) = f(x) + hf'(x) + \frac{h^2}{2}f''(x) + \dots + \frac{h^{(n-1)}}{(n-1)!}f^{(n-1)}(x) + \frac{h^n}{n!}f^n(x + \lambda h).$$

$$f(x_{i+1}) \approx f(x_i)$$

$$f(x_{i+1}) \approx f(x_i) + f'(x_i)(x_{i+1} - x_i)$$

Zero order Taylor series:

1<sup>st</sup> order Taylor series:

2<sup>nd</sup> order Taylor series:

$$f(x_{i+1}) \approx f(x_i) + f'(x_i)(x_{i+1} - x_i) + \frac{f''(x_i)}{2!}(x_{i+1} - x_i)^2$$

$$e^x = \sum_{n=0}^{\infty} \frac{x^n}{n!} = 1 + x + \frac{x^2}{2!} + \frac{x^3}{3!} + \dots \quad \text{for all } x$$

$$\log(1-x) = -\sum_{n=1}^{\infty} \frac{x^n}{n} \quad \text{for } -1 \leq x < 1$$

$$\log(1+x) = \sum_{n=1}^{\infty} (-1)^{n+1} \frac{x^n}{n} \quad \text{for } -1 < x \leq 1$$

$$\frac{1-x^{m+1}}{1-x} = \sum_{n=0}^m x^n \quad \text{for } x \neq 1 \text{ and } m \in \mathbb{N}_0$$

$$\frac{1}{1-x} = \sum_{n=0}^{\infty} x^n \quad \text{for } |x| < 1$$

$$\sin x = \sum_{n=0}^{\infty} \frac{(-1)^n}{(2n+1)!} x^{2n+1} = x - \frac{x^3}{3!} + \frac{x^5}{5!} - \dots \quad \text{for all } x$$

$$\cos x = \sum_{n=0}^{\infty} \frac{(-1)^n}{(2n)!} x^{2n} = 1 - \frac{x^2}{2!} + \frac{x^4}{4!} - \dots \quad \text{for all } x$$

$$\tan x = \sum_{n=1}^{\infty} \frac{B_{2n} (-4)^n (1 - 4^n)}{(2n)!} x^{2n-1} = x + \frac{x^3}{3} + \frac{2x^5}{15} + \dots \quad \text{for } |x| < \frac{\pi}{2}$$

$$\sec x = \sum_{n=0}^{\infty} \frac{(-1)^n E_{2n}}{(2n)!} x^{2n} \quad \text{for } |x| < \frac{\pi}{2}$$

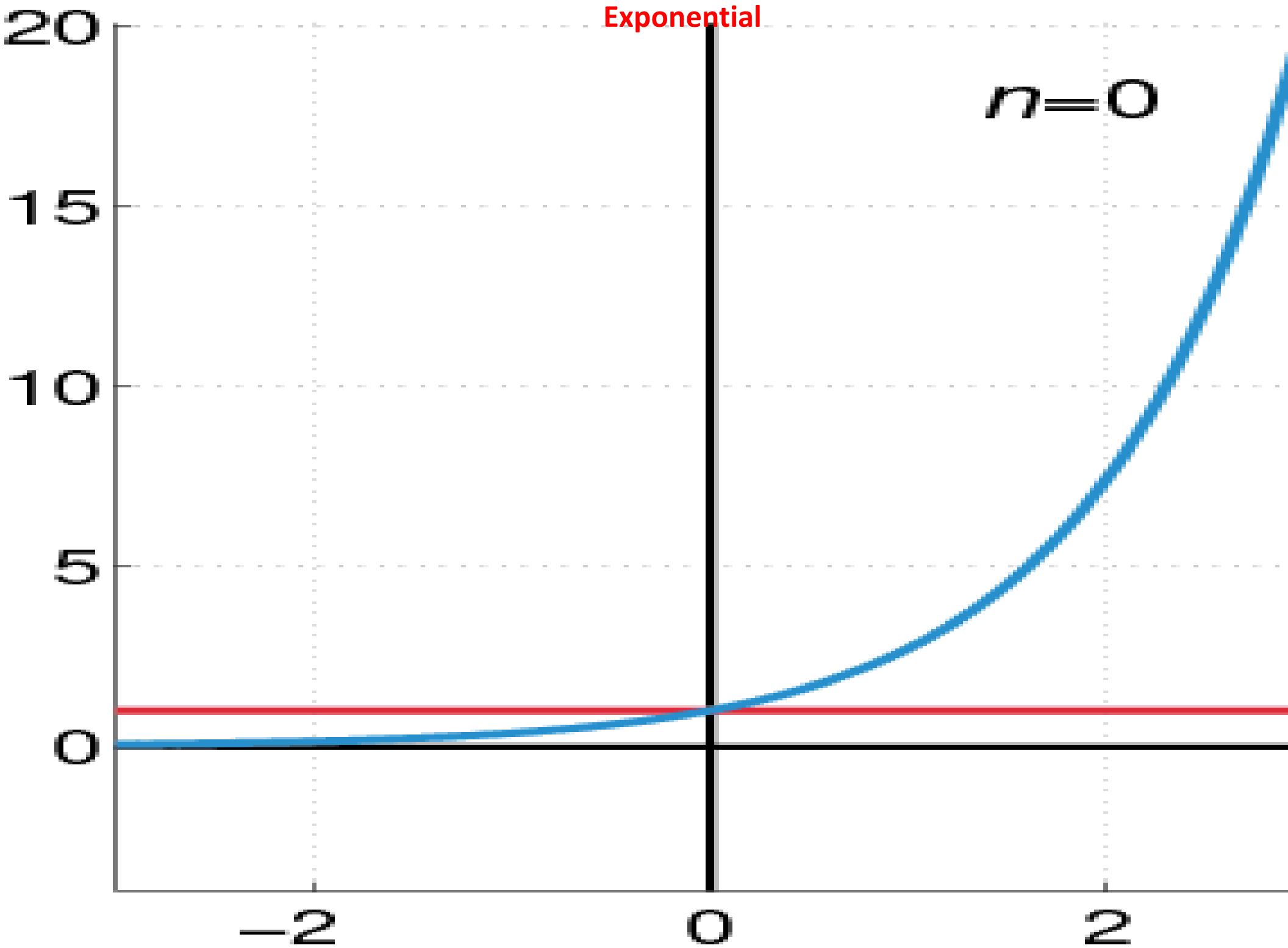
$$\arcsin x = \sum_{n=0}^{\infty} \frac{(2n)!}{4^n (n!)^2 (2n+1)} x^{2n+1} \quad \text{for } |x| \leq 1$$

$$\arccos x = \frac{\pi}{2} - \arcsin x = \frac{\pi}{2} - \sum_{n=0}^{\infty} \frac{(2n)!}{4^n (n!)^2 (2n+1)} x^{2n+1} \quad \text{for } |x| \leq 1$$

$$\arctan x = \sum_{n=0}^{\infty} \frac{(-1)^n}{2n+1} x^{2n+1} \quad \text{for } |x| < 1$$

Exponential

$n=0$



# Taylor Series

$$f(x) = c_0 + c_1x + c_2x^2 + c_3x^3 + c_4x^4 + \dots,$$

$$f(x) = 3 + 5x + 7x^2 + 9x^3 + 11x^4 + \dots,$$

$$f(0) = 3 + 0 + 0 + 0 + 0 + \dots = 3.$$

$$f'(x) = 5 + 14x + 27x^2 + 44x^3 + \dots,$$

$$f(x) = 3 + 5x + 7x^2 + 9x^3 + \dots$$

↓                    ↓                    ↓                    ...

$$f'(x) = 5 + 14x + 27x^2 + \dots$$