OPENGL BASICS: PIPELINE, TEXTURING

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Contents

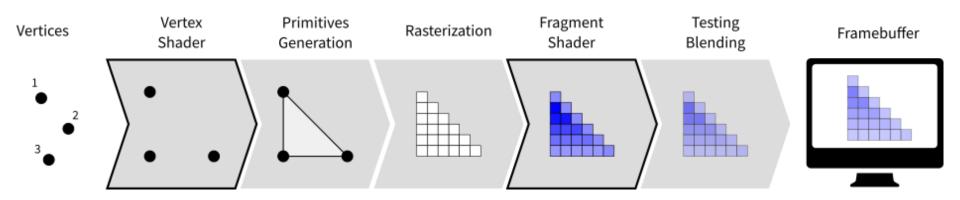
- Basics
- OpenGL pipeline
- Simple texturing
- Advanced texturing
- Environment mapping

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Basics

Pipeline overview



Basics

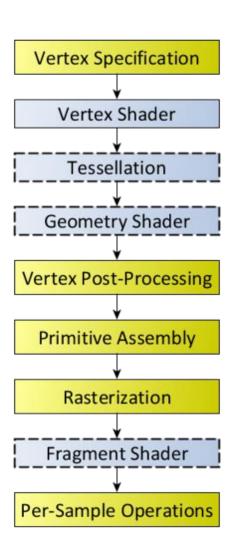
 Vertex shader must output (at least) the vertex transformed position

```
void main()
{
    gl_Position = vec4(0.0,0.0,0.0,1.0);
}
```

Fragment shader must output (at least) the fragment color

```
void main()
{
    gl_FragColor = vec4(0.0,0.0,0.0,1.0);
}
```

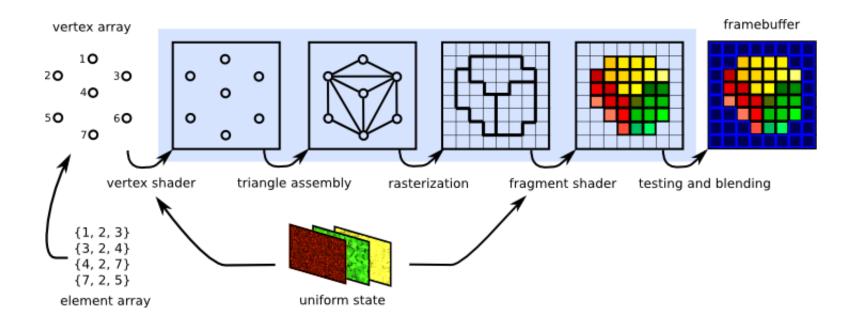
Basics



Contents

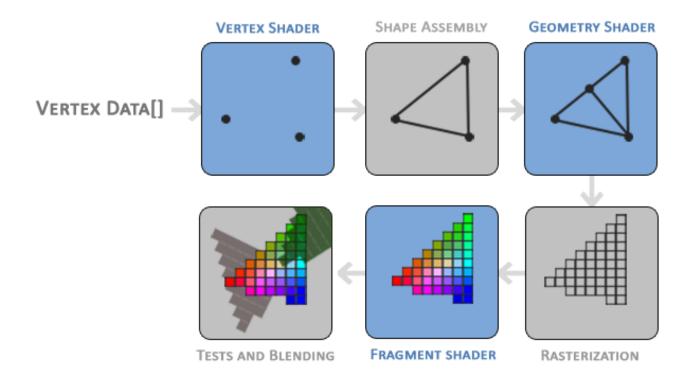
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OpenGL rendering pipeline

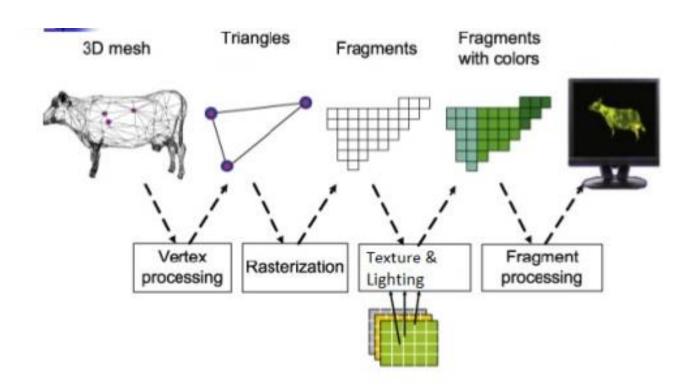


OpenGL pipeline – overview

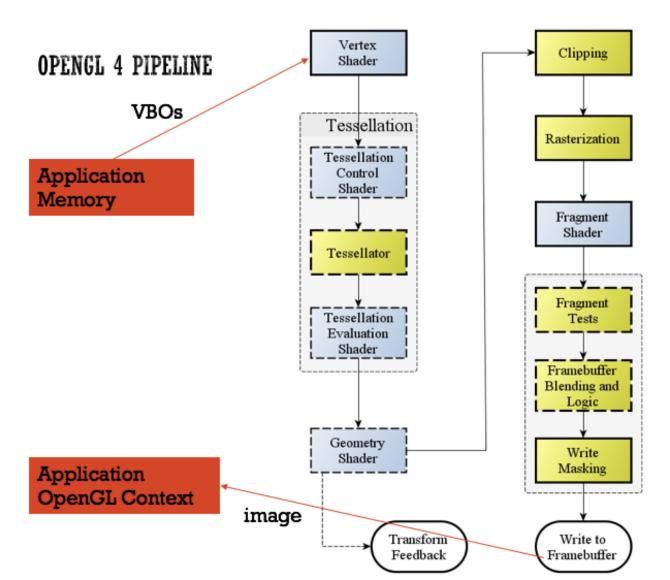
OpenGL rendering pipeline



OpenGL pipeline – overview

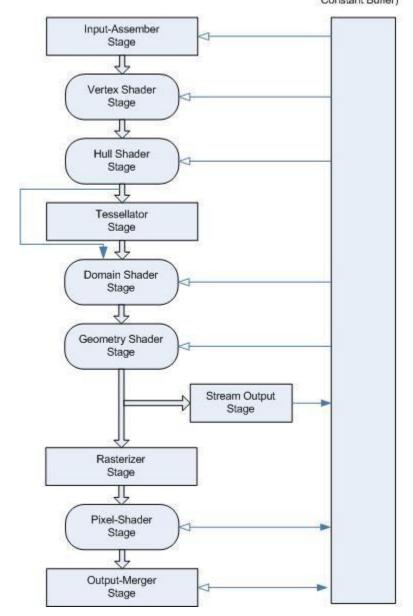


OpenGL pipeline – stages

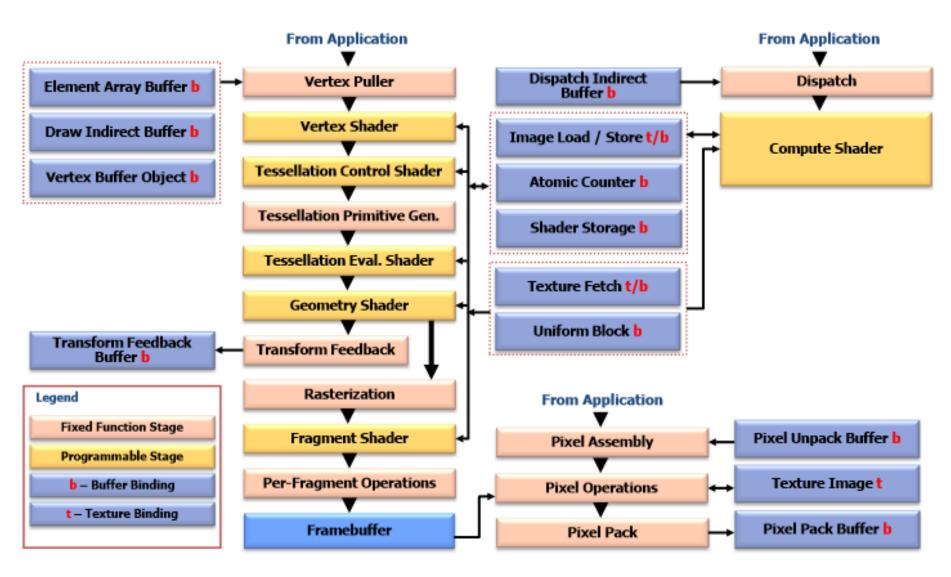


Inputs

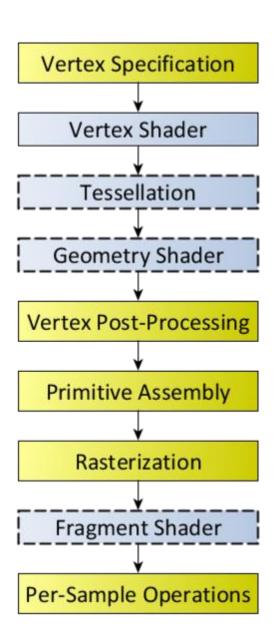
Memory Resources (Buffer, Texture, Constant Buffer)



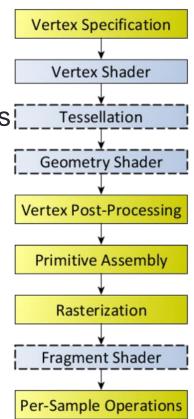
OpenGL pipeline – complete 4.6



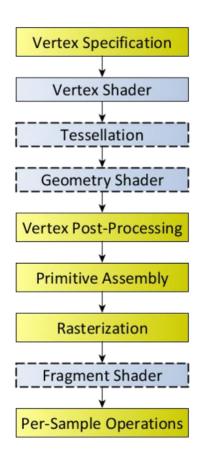
Simplified version



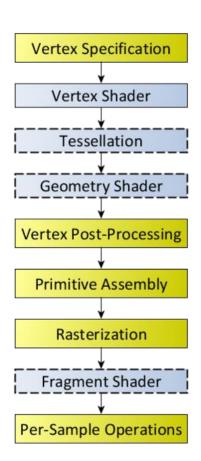
- Prepare vertex array data and render
- Vertex Processing
- Vertex Post-Processing
 - outputs last stage adjusted/shipped to different locations
- Primitive Assembly
- Scan conversion and primitive parameter interpolation
- A Fragment Shader processes each fragment
 - One or more outputs
- Per-Sample_Processing



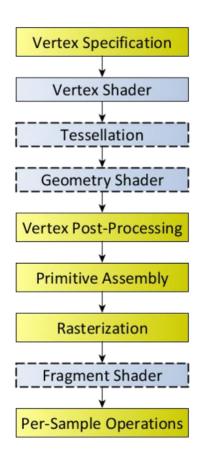
- Prepare vertex array data and render
 - Generate vertex buffers
 - Geometric data: positions, normals, etc.
 - Optical data: material properties
 - Other stuff (lighting, textures...)
- Render vertex data
 - Send vertex data to the GPU
 - May render multiple instances of same geometry
 - Use indexed primitives
 - Facilitates T&L caching



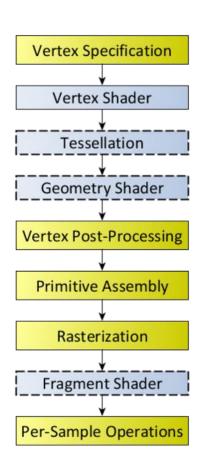
- Vertex Processing
 - Each vertex is acted upon by a vertex shader
 - Main work: transform vertices
 - Optional work: pass other stuff (texture data, lighting...)
 - Optional tessellation
 - May further subdivide original triangle mesh
 - Optional geometry shader
 - Acts upon full triangles
 - Transforms, culls...
 - Might subdivide and/or generate extra information



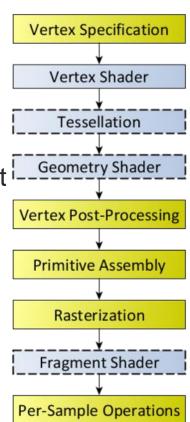
- Vertex Post-Processing
 - Adapts output for further operations (e.g. primitive assembly and rasterization)
 - May use transform feedback (more on this later)
 - Clipping is performed here
 - Depth clampling, perspective divide, viewport transform...



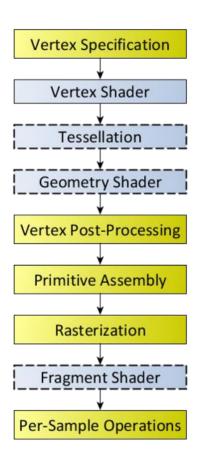
- Primitive Assembly
 - Transforms a vertex stream into a sequence of primitives (e.g. triangles)
 - Order depends on the vertex rendering sorting
- Scan conversion:
 - Generates the corresponding fragments
 - With depth and other properties
 - Parameters requiring it are interpolated



- Fragment Shader
 - Executed for all rasterized fragments
 - Can only write in its own position
 - Must write color (gl_FragColor -> out data defined in layout)
 - Can generate more than one output (gl_FragData -> out data defined in layout)
 - Can discard data
 - May generate depth



- Per-Sample Processing
 - Scissor test
 - Stencil test
 - Depth test
 - Blending
 - Logical operation
 - Write Mask



OpenGL pipeline. Fragment shaders

- Fragment shader output
 - Depth value
 - Possible stencil value (unmodified by the fragment shader),
 - Zero or more color values to be potentially written to the buffers in the current framebuffers
 - Opens the possibility of multiple pass rendering
- Fragment shaders take a single fragment as input and produce a single fragment as output

Contents

- Basics
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- Simple texturing
- Advanced texturing
- Environment mapping

- Complex domain
 - It has infinite possibilities
 - Specially when using shaders
- Basic texturing
 - Get a color and apply it to a surface
- Other uses of textures
 - Store environment information
 - Store functions
 - Store geometric information
 - . . .

- Main stages:
 - Set up texture from the application
 - Access to texture in a shader
 - Do whatever you want with it:
 - The results of one texture access define the parameters of another texture access
 - Textures store intermediate rendering results
 - Textures serve as lookup tables for complex functions
 - Textures store normals, normal perturbation factors, gloss values, visibility information...

- Basic method to map a texture onto an object
- One texture unit is required in the pixel shader
- The access to the texture's texels is done using the texture() function
 - Takes as parameters the texture we wish to access (a sampler2D) and the texture coordinates

```
#version 300 es
#define FRAG_COLOR_LOCATION 0
precision highp float;
precision highp int;
struct Material
    sampler2D diffuse[2];
};
uniform Material material;
in vec2 v st;
layout(location = FRAG COLOR LOCATION) out vec4 color;
```

```
void main()
{
     color = texture(material.diffuse[1], v_st) * 0.77;
}
```

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```
varying vec2 vUv;

uniform sampler2D image1;
uniform sampler2D image2;

uniform float time;
```

```
void main() {
    float percent = 0.5 + 0.5 * sin(time);
     gl FragColor = mix(
         texture2D( image1, vUv ),
         texture2D( image2, vUv ),
         percent
     );
```

```
4 varying vec2 vUv;

uniform sampler2D image1;
uniform sampler2D image2;
```

```
uniform float time;
void main() {
    float percent = 0.5 + 0.5 * sin(time);
     gl FragColor = mix(
         texture2D( image1, vUv ),
         texture2D( image2, vUv ),
         percent
     );
```

```
varying vec2 vUv;
uniform sampler2D image1;
uniform sampler2D image2;
uniform float time;
void main() {
    float percent = 0.5 + 0.5 * sin(time);
     gl FragColor = mix(
         texture2D( image1, vUv ),
         texture2D( image2, vUv ),
         percent
     );
```

```
varying vec2 vUv;
uniform sampler2D image1;
uniform sampler2D image2;
uniform float time;
void main() {
    float percent = 0.5 + 0.5 * sin(time);
     gl FragColor = mix(
         texture2D( image1, vUv ),
         texture2D( image2, vUv ),
         percent
    );
```

```
4 varying vec2 vUv;
7 uniform sampler2D image1;
8 uniform sampler2D image2;
```

```
uniform float time;
void main() {
    float percent = 0.5 + 0.5 * sin(time);
     gl_FragColor = mix(
         texture2D( image1, vUv ),
         texture2D( image2, vUv ),
         percent
```

Multiple textures. Result:





Modifying texture coordinates over time (ripples + blending)

```
precision highp float;
precision highp int;

varying vec2 vUv;

uniform vec2 uvScale;
uniform sampler2D image1;
uniform sampler2D image2;
uniform float speed;
uniform float frequency;
uniform float amplitude;
uniform float time;
```

Modifying texture coordinates over time (ripples + blending)

```
void main() {

vec2 ripple = vec2(
    // - 0.5 to center the ripple in the middle of image
    sin( (length( vUv - 0.5 ) * frequency ) + ( time * speed ) ),
    cos( ( length( vUv - 0.5 ) * frequency ) + ( time * speed ) )

// Scale amplitude to make input more convenient for users
) * ( amplitude / 1000.0 );
```

Modifying texture coordinates over time (ripples + blending)

```
float percent = 0.5 + 0.5 * sin( time );
gl_FragColor = mix(
    texture2D( image1, vUv + ripple * percent ),
    texture2D( image2, vUv + ripple * ( 1.0 - percent ) ),
    percent
);
```

• Ripples + blending. Result



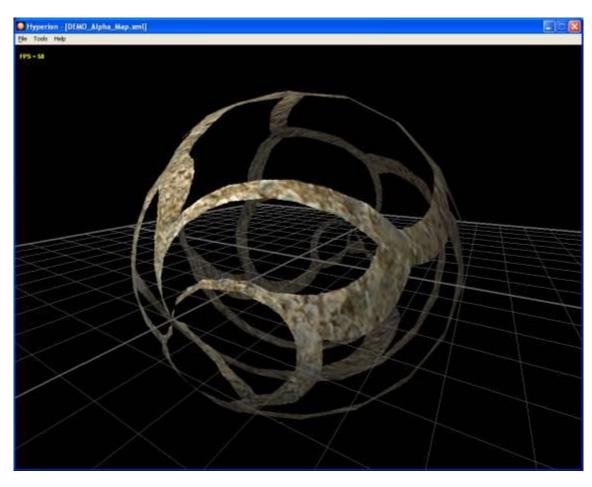
Alpha Maps

- An alpha map is a binary texture in the meaning it contains information that allows all or nothing based choices
- Alpha maps are usually used for tests at the pixel level (alphatesting) in order to know if a pixel is either fully opaque or fully transparent
 - In this last case, the pixel is not sent to the framebuffer

- Alpha Maps
 - discard is a keyword in GLSL to prevent a fragment to update the framebuffer
 - According to the OpenGL implementations, the instructions that follow the discard keyword can or can not be executed but in all cases the framebuffer will not be updated
 - discard is available in the pixel shader only

Alpha Maps

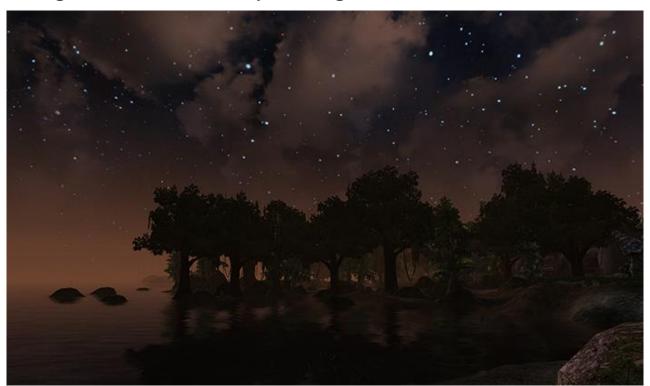




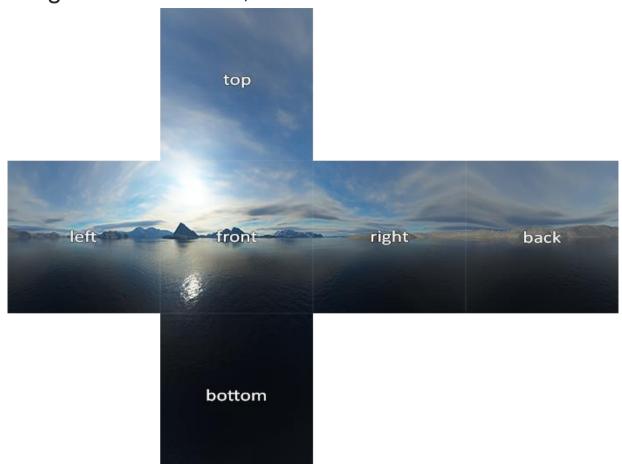
Alpha Maps. Fragment shader:

```
varying vec2 vUv;
uniform sampler2D colorMap;
uniform sampler2D alphaMap;
void main (void)
 vec4 alpha_color = texture2D(alphaMap, vUv);
  if(alpha_color.r<0.1)
    discard;
 gl_FragColor = texture2D(colorMap, vUv);
```

- Skybox: Large cube that encompasses the entire scene and contains 6 images of a surrounding environment
 - Giving the player the illusion that the environment he's in is actually much larger than it actually is, e.g.:



- Skybox
 - Built using a cubic texture, such as:



```
unsigned int loadCubemap(vector<std::string> faces)
   unsigned int textureID;
   glGenTextures(1, &textureID);
   glBindTexture(GL TEXTURE CUBE MAP, textureID);
   int width, height, nrChannels;
   for (unsigned int i = 0; i < faces.size(); i++)
       unsigned char *data = stbi load(faces[i].c str(), &width, &height, &nrChannels, 0);
       if (data)
            glTexImage2D(GL TEXTURE CUBE MAP POSITIVE X + i,
                         0, GL RGB, width, height, 0, GL RGB, GL UNSIGNED BYTE, data
            stbi image free (data);
       else
            std::cout << "Cubemap texture failed to load at path: " << faces[i] << std::endl
            stbi image free(data);
```

```
unsigned int loadCubemap(vector<std::string> faces)
   unsigned int textureID;
   qlGenTextures(1, &textureID);
   glBindTexture(GL TEXTURE CUBE MAP, textureID);
   int width, height, nrChannels;
   for (unsigned int i = 0; i < faces.size(); i++)
       unsigned char *data = stbi load(faces[i].c str(), &width, &height, &nrChannels, 0);
       if (data)
            glTexImage2D(GL TEXTURE CUBE MAP POSITIVE X + i,
                         0, GL RGB, width, height, 0, GL RGB, GL UNSIGNED BYTE, data
            stbi image free (data);
       else
            std::cout << "Cubemap texture failed to load at path: " << faces[i] << std::endl
            stbi image free(data);
```

```
unsigned int loadCubemap(vector<std::string> faces)
   unsigned int textureID;
    qlGenTextures(1, &textureID);
    glBindTexture(GL TEXTURE CUBE MAP, textureID);
    int width, height, nrChannels;
    for (unsigned int i = 0; i < faces.size(); i++)
        unsigned char *data = stbi load(faces[i].c str(), &width, &height, &nrChannels, 0);
        if (data)
            glTexImage2D(GL TEXTURE CUBE MAP POSITIVE X + i,
                         0, GL RGB, width, height, 0, GL RGB, GL UNSIGNED BYTE, data
            stbi image free (data);
        else
            std::cout << "Cubemap texture failed to load at path: " << faces[i] << std::endl
            stbi image free (data);
```

```
else
{
      std::cout << "Cubemap texture failed to load at path: " << faces[i] << std::endl
      stbi_image_free(data);
}

glTexParameteri(GL_TEXTURE_CUBE_MAP, GL_TEXTURE_MIN_FILTER, GL_LINEAR);
glTexParameteri(GL_TEXTURE_CUBE_MAP, GL_TEXTURE_MAG_FILTER, GL_LINEAR);
glTexParameteri(GL_TEXTURE_CUBE_MAP, GL_TEXTURE_WRAP_S, GL_CLAMP_TO_EDGE);
glTexParameteri(GL_TEXTURE_CUBE_MAP, GL_TEXTURE_WRAP_T, GL_CLAMP_TO_EDGE);
glTexParameteri(GL_TEXTURE_CUBE_MAP, GL_TEXTURE_WRAP_R, GL_CLAMP_TO_EDGE);
return textureID;
}</pre>
```

- Skybox. Drawing the box
 - Disable depth writing!

```
glDepthMask(GL_FALSE);
skyboxShader.use();
// ... set view and projection matrix
glBindVertexArray(skyboxVAO);
glBindTexture(GL_TEXTURE_CUBE_MAP, cubemapTexture);
glDrawArrays(GL_TRIANGLES, 0, 36);
glDepthMask(GL_TRUE);
// ... draw rest of the scene
```

Skybox. Vertex shader

```
#version 330 core
layout (location = 0) in vec3 aPos;
out vec3 TexCoords;

uniform mat4 projection;
uniform mat4 view;

void main()
{
    TexCoords = aPos;
    gl_Position = projection * view * vec4(aPos, 1.0);
}
```

Skybox. Vertex shader

```
#version 330 core
layout (location = 0) in vec3 aPos;

out vec3 TexCoords;

uniform mat4 projection;
uniform mat4 view;

void main()
{
    TexCoords = aPos;
    gl_Position = projection * view * vec4(aPos, 1.0);
}
```

Skybox. Fragment shader

```
#version 330 core
out vec4 FragColor;
in vec3 TexCoords;
uniform samplerCube skybox;

void main()
{
    FragColor = texture(skybox, TexCoords);
}
```

Skybox. Fragment shader

```
#version 330 core
out vec4 FragColor;
in vec3 TexCoords;

uniform samplerCube skybox;

void main()
{
    FragColor = texture(skybox, TexCoords);
}
```

Skybox. Fragment shader

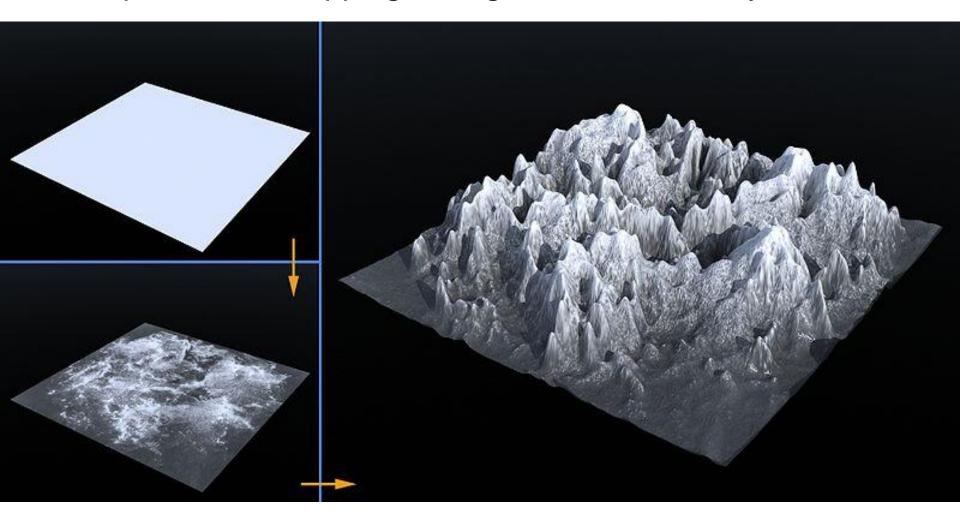
```
#version 330 core
out vec4 FragColor;
in vec3 TexCoords;
uniform samplerCube skybox;

void main()
{
    FragColor = texture(skybox, TexCoords);
}
```

Skybox. Result



Displacement mapping: Using textures to modify vertices



Displacement mapping. Vertex shader

```
#version 300 es
#define POSITION LOCATION 0
#define NORMAL LOCATION 1
#define TEXCOORD LOCATION 4
precision highp float;
precision highp int;
uniform mat4 mvMatrix;
uniform mat4 pMatrix;
uniform sampler2D displacementMap;
layout(location = POSITION LOCATION) in vec3 position;
layout(location = NORMAL LOCATION) in vec3 normal;
layout(location = TEXCOORD LOCATION) in vec2 texcoord;
out vec2 v st;
out vec3 v position;
```

Displacement mapping. Vertex shader

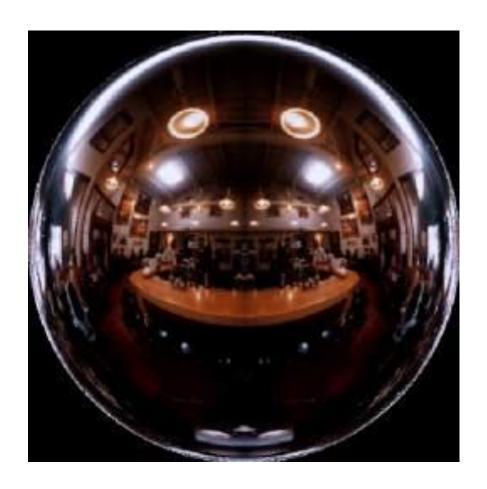
```
void main()
{
    v_st = texcoord;
    float height = texture(displacementMap, texcoord).b;
    vec4 displacedPosition = vec4(position, 1.0) + vec4(normal * height, 0.0);
    v_position = vec3(mvMatrix * displacedPosition);
    gl_Position = pMatrix * mvMatrix * displacedPosition;
}
```

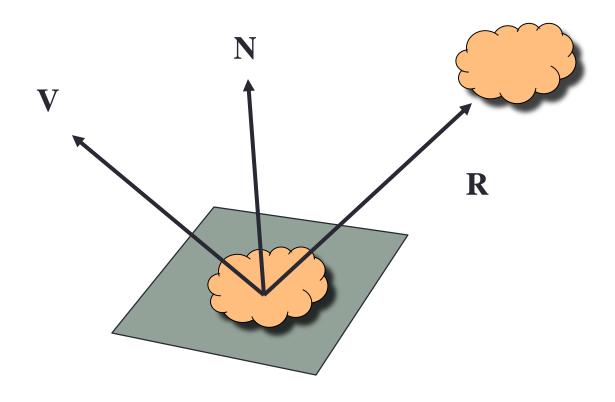
Contents

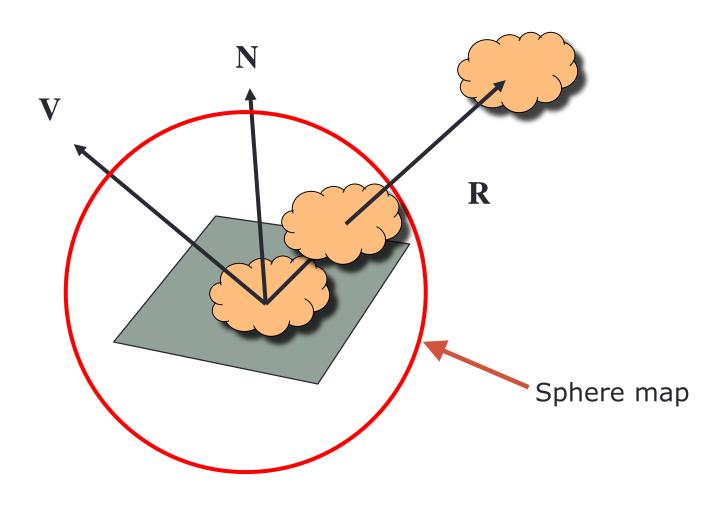
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- Spherical Environment Mapping
 - The first and simplest of the techniques allowing to simulate the reflection of the environment on an object's surface
 - SEM uses only one texture for the reflection
 - The texture can be whatever you want but usually we use SEM-ready textures

Spherical Environment Mapping







- In order to compute s and t coordinates:
 - u: unit vector that goes from the camera to the current vertex:
 - the position of the vertex in eye space and also the view vector
 - n: vertex normal in eye space.
 - r: is the reflected vision vector against n:

```
r = reflect(u, n)

r = 2 * ( n dot u) * n - u
```

m is an intermediate value:

$$m = sqrt(r.x^2 + r.y^2 + (r.z + 1.0)^2)$$

s and t are the final texture coordinates:

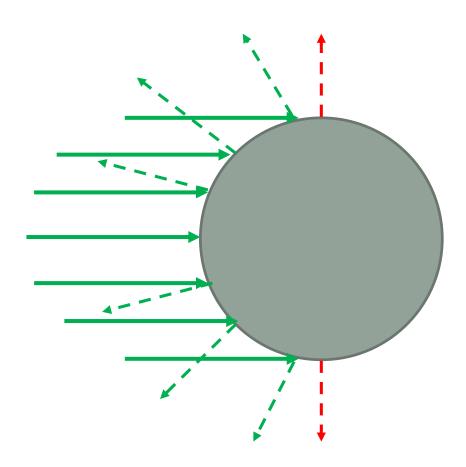
$$s = r.x / m + 0.5$$

 $t = r.y / m + 0.5$

- Construction:
 - Can use a ray tracer
 - Or can use projection-based rendering
 - By modifying the projected coordinates in the vertex shader
 - Typically two spheres can be created

- Sampling problems:
 - Highly varying resolution
 - Texels do not represent the same information
 - Subtended solid angle is not the same
 - Minimum accuracy in poles
 - Actually, there is a singularity (no samples for the north & south poles)

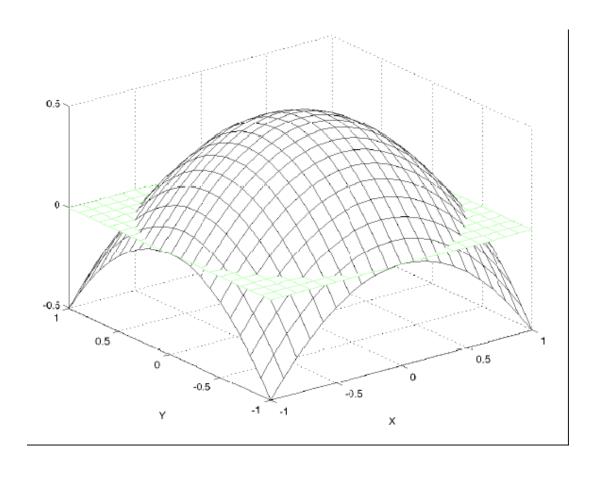
Sampling problems



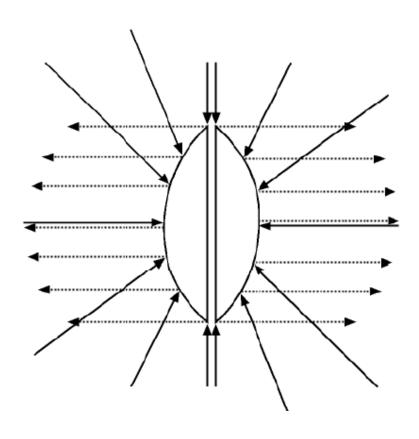
- Sampling problems:
 - Can be alleviated using dual-paraboloids mapping
 - No singularity
 - Better sampling ratio (≈ 4 to 1)
 - Dual paraboloid mathematical definition:

$$f(x,y) = \frac{1}{2} - \frac{1}{2}(x^2 + y^2)$$
 for $x^2 + y^2 \le 1$

Paraboloid:



Dual Paraboloid:



Dual paraboloid. Texture coordinates. Vertex shader:

```
void main()
{
    ...

// find world space position.
    vec4 WorldPos = ModelWorld4x4 * gl_Vertex;
    // find world space normal.
    vec3 N = normalize( ModelWorld3x3 * gl_Normal );
    // find world space eye vector.
    vec3 E = normalize( WorldPos.xyz - CameraPos.xyz );
    // calculate the reflection vector in world space.
    R = reflect( E, N );
}
```

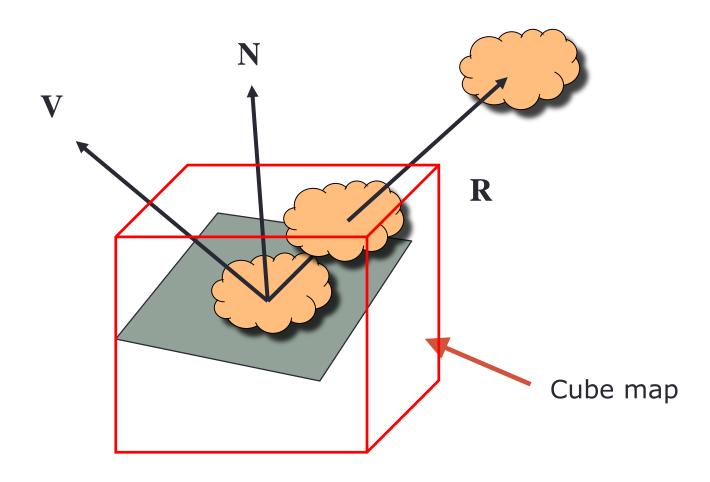
Dual paraboloid. Texture coordinates. Fragment shader:

```
uniform sampler2D frontMap;
uniform sampler2D backMap;
varying vec3 R;
void main (void)
   vec4 output_color; vec3 vR = normalize(R);
   if(vR.z>0.0)
      vec2 frontUV = (vR.xy / (2.0*(1.0 + vR.z))) + 0.5;
      output color = texture2D( frontMap, frontUV );
```

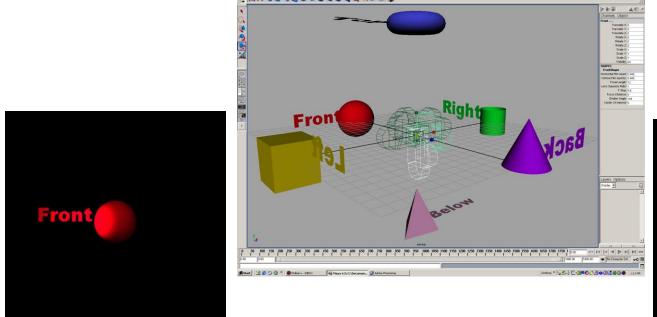
Dual paraboloid. Texture coordinates. Fragment shader:

```
else
{
    // calculate the backward paraboloid map
    // texture coordinates
    vec2 backUV;
    backUV = (vR.xy / (2.0*(1.0 - vR.z))) + 0.5;
    output_color = texture2D(backMap, backUV);
}
gl_FragColor = output_color;
}
```

- OpenGL supports spherical and cube maps
 - Cube maps share the same idea
 - But a better sampling rate



- Construction:
 - Use six cameras, each with a 90 degree angle of view





- OpenGL supports spherical and cube maps
- First must form map
 - Use images from a real camera
 - Form images with OpenGL
- Texture map it to object

```
precision highp float;
precision highp int;
uniform mat4 modelMatrix;
uniform mat4 modelViewMatrix;
uniform mat4 projectionMatrix;
uniform mat4 viewMatrix;
uniform mat3 normalMatrix;
uniform vec3 cameraPosition;
attribute vec3 position;
attribute vec3 normal;
attribute vec2 uv:
attribute vec2 uv2;
varying vec3 vReflect;
```

```
void main() {

vec3 worldPosition = ( modelMatrix * vec4( position, 1.0 )).xyz;

vec3 cameraToVertex = normalize( worldPosition - cameraPosition );

vec3 worldNormal = normalize(

mat3( modelMatrix[ 0 ].xyz, modelMatrix[ 1 ].xyz, modelMatrix[ 2 ].xyz ) * normal

);

vReflect = reflect( cameraToVertex, worldNormal );

gl_Position = projectionMatrix * modelViewMatrix * vec4(position, 1.0);

}
```

```
void main() {

vec3 worldPosition = ( modelMatrix * vec4( position, 1.0 )).xvz;

vec3 cameraToVertex = normalize( worldPosition - cameraPosition );

vec3 worldNormal = normalize(

mat3( modelMatrix[ 0 ].xyz, modelMatrix[ 1 ].xyz, modelMatrix[ 2 ].xyz ) * normal

vReflect = reflect( cameraToVertex, worldNormal );

gl_Position = projectionMatrix * modelViewMatrix * vec4(position, 1.0);

gl_Position = projectionMatrix * modelViewMatrix * vec4(position, 1.0);

year and the projection of the p
```

```
void main() {
    vec3 worldPosition = ( modelMatrix * vec4( position, 1.0 )).xyz;
    vec3 cameraToVertex = normalize( worldPosition - cameraPosition );

vec3 worldNormal = normalize(
    mat3( modelMatrix[ 0 ].xyz, modelMatrix[ 1 ].xyz, modelMatrix[ 2 ].xyz ) * normal );
    vReflect = reflect( cameraToVertex, worldNormal );
    gl_Position = projectionMatrix * modelViewMatrix * vec4(position, 1.0);
}
```

```
void main() {
    vec3 worldPosition = ( modelMatrix * vec4( position, 1.0 )).xyz;
    vec3 cameraToVertex = normalize( worldPosition - cameraPosition );
    vec3 worldNormal = normalize(
        mat3( modelMatrix[ 0 ].xyz, modelMatrix[ 1 ].xyz, modelMatrix[ 2 ].xyz ) * normal
    );
    vReflect = reflect( cameraToVertex, worldNormal );
    gl_Position = projectionMatrix * modelViewMatrix * vec4(position, 1.0);
}
```

```
void main() {
    vec3 worldPosition = ( modelMatrix * vec4( position, 1.0 )).xyz;
    vec3 cameraToVertex = normalize( worldPosition - cameraPosition );
    vec3 worldNormal = normalize(
        mat3( modelMatrix[ 0 ].xyz, modelMatrix[ 1 ].xyz, modelMatrix[ 2 ].xyz ) * normal
    );
    vReflect = reflect( cameraToVertex. worldNormal ):
        gl_Position = projectionMatrix * modelViewMatrix * vec4(position, 1.0);
}
```

GLSL implementation. Fragment Shader:

```
precision highp float;
precision highp int;

varying vec3 vReflect;

uniform float mirrorReflection;
uniform samplerCube reflectionSampler;

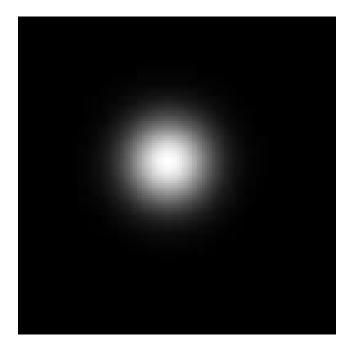
void main() {
    vec4 cubeColor = textureCube( reflectionSampler, vec3( mirrorReflection * vReflect.x, vReflect.yz ) );
    cubeColor.w = 1.0;
    gl_FragColor = cubeColor;
}
```

Result

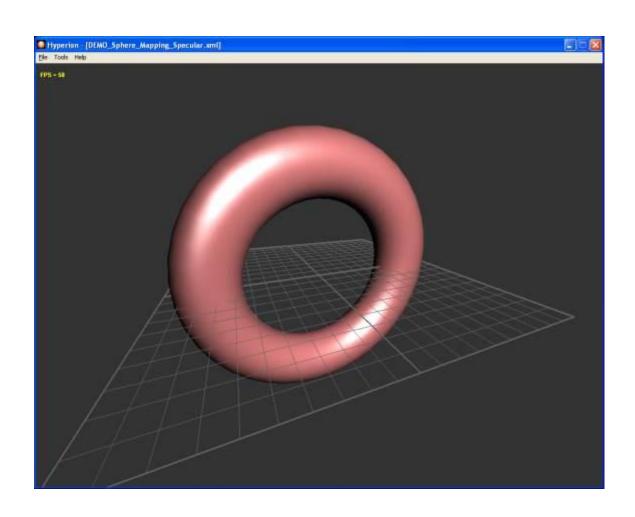


- Spherical mapping. Discussion:
 - Advantage:
 - Simple to use
 - Disadvantages:
 - Must assume environment is very far from object
 - It is view-dependent: the reflection slides on the object and follows the view
 - Need a new map if viewer moves
 - If we map all objects to hemisphere, we cannot tell if they are on the sphere or anywhere else along the reflector
 - Object cannot be concave
 - No reflections between objects
 - Need a reflection map for each object

- Spherical mapping: Other uses:
 - We can take advantage of the fact that spherical mapping is viewdependent in order to generate of specular highlights
 - Use for instance the following texture:



Result:



OPENGL BASICS: PIPELINE, TEXTURING

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