
Exercici 2 - Teoria

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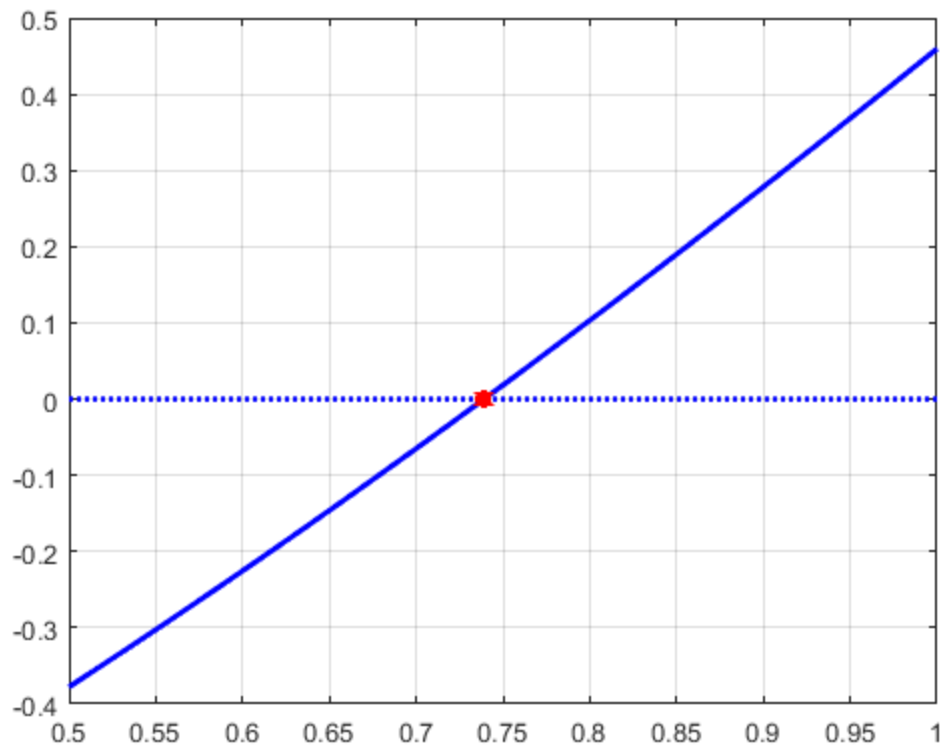
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by M. Àngela Grau Gotés

```
clc, clear all, format long
```

Gràfica

```
t=0.5:0.01:1;  
f=@(x)x-cos(x);  
figure(1)  
alpha = fzero(f,1)  
plot(t,f(t),'b',t,zeros(size(t)),'b:',alpha,0,'r*','LineWidth',2),grid  
  
alpha =  
    0.739085133215161
```



Mètode de Newton

```
f=@(x)x-cos(x);  
df=@(x)1+sin(x);  
a=0.5; tol = 0.00005;  
[ xnw ] = newton( f,df,a,tol );
```

iteration	/	xns	/	f(xns)	/	error rel
0	/	0.50000	/	-0.37758	/	0.00000
1	/	0.75522	/	0.02710	/	0.33794
2	/	0.73914	/	0.00009	/	0.02176
3	/	0.73909	/	0.00000	/	0.00008
4	/	0.73909	/	0.00000	/	0.00000

```
final solution:  
x = 0.7390851332  
time elapsed in milliseconds:  
t = 3.8297481249
```

Mètodes de la iteració simple

Mètode 1. $x=(x+\cos(x))/2$

```
a=0; b=1; tol = 0.0000000005;
```

```

g1=@(x)(x+cos(x))/2; dg1=@(x)(1-sin(x))/2;
if abs(dg1(a)) < 1
    [ xi ] = fixedpt( f, g1, a, b, tol );
else
    fprintf('\nMètode divergent\n')
end
fprintf('\n\n')

```

iteration	/	xns	/	f(xns)	/	error rel
0	/	0.00000000	/	-1.00000000	/	1.00000000
1	/	0.50000000	/	-0.37758256	/	1.00000000
2	/	0.68879128	/	-0.08322357	/	0.27409070
3	/	0.73040306	/	-0.01450249	/	0.05697099
4	/	0.73765431	/	-0.00239389	/	0.00983014
5	/	0.73885125	/	-0.00039141	/	0.00162001
6	/	0.73904696	/	-0.00006389	/	0.00026480
7	/	0.73907890	/	-0.00001043	/	0.00004323
8	/	0.73908412	/	-0.00000170	/	0.00000705
9	/	0.73908497	/	-0.00000028	/	0.00000115
10	/	0.73908511	/	-0.00000005	/	0.00000019
11	/	0.73908513	/	-0.00000001	/	0.00000003
12	/	0.73908513	/	-0.00000000	/	0.00000001
13	/	0.73908513	/	-0.00000000	/	0.00000000
14	/	0.73908513	/	-0.00000000	/	0.00000000

final solution:

x = 0.7390851332

time elapsed in milliseconds:

t = 5.2993189123

Mètode 2. $x=(2x+\cos(x))/3$

```

a=0; b=1; tol = 0.00000000005;
g2=@(x)(2*x+cos(x))/3; dg2=@(x)(2-sin(x))/3;
if abs(dg2(a)) < 1
    [ xi ] = fixedpt( f, g2, a, b, tol );
else
    fprintf('\nMètode divergent\n')
end
fprintf('\n\n')

```

iteration	/	xns	/	f(xns)	/	error rel
0	/	0.00000000	/	-1.00000000	/	1.00000000
1	/	0.33333333	/	-0.61162361	/	1.00000000
2	/	0.53720787	/	-0.32193300	/	0.37950773
3	/	0.64451887	/	-0.15487006	/	0.16649784
4	/	0.69614222	/	-0.07117951	/	0.07415633
5	/	0.71986873	/	-0.03202355	/	0.03295949
6	/	0.73054325	/	-0.01426877	/	0.01461175
7	/	0.73529950	/	-0.00633037	/	0.00646846

8		0.73740963		-0.00280311		0.00286154
9		0.73834400		-0.00124017		0.00126549
10		0.73875739		-0.00054848		0.00055958
11		0.73894021		-0.00024253		0.00024742
12		0.73902106		-0.00010724		0.00010939
13		0.73905680		-0.00004741		0.00004837
14		0.73907261		-0.00002096		0.00002138
15		0.73907960		-0.00000927		0.00000945
16		0.73908268		-0.00000410		0.00000418

final solution:

x = 0.7390826847
time elapsed in milliseconds:
t = 0.8327567795

Mètode 3. $x=x-\cos(x)$

```
a=1; b=0.6; tol = 0.0000000005;
g3=@(x)cos(x); dg3=@(x)sin(x);
if abs(dg3(a)) < 1
    [ xi ] = fixedpt( f, g3, a, b, tol );
else
    fprintf('\nMètode divergent\n')
end
fprintf('\n\n')
```

iteration		xns		f(xns)		error rel
0		1.00000000		0.45969769		0.66666667
1		0.54030231		-0.31725091		0.85081572
2		0.85755322		0.20326343		0.36994895
3		0.65428979		-0.13919057		0.31066269
4		0.79348036		0.09211159		0.17541779
5		0.70136877		-0.06259091		0.13133117
6		0.76395968		0.04185726		0.08192960
7		0.72210243		-0.02831534		0.05796582
8		0.75041776		0.01901372		0.03773276
9		0.73140404		-0.01283331		0.02599619
10		0.74423735		0.00863261		0.01724357
11		0.73560474		-0.00582035		0.01173540
12		0.74142509		0.00391820		0.00785021
13		0.73750689		-0.00264045		0.00531276
14		0.74014734		0.00177813		0.00356746
15		0.73836920		-0.00119800		0.00240819
16		0.73956720		0.00080688		0.00161986

final solution:

x = 0.7395672022
time elapsed in milliseconds:
t = 0.5645017945

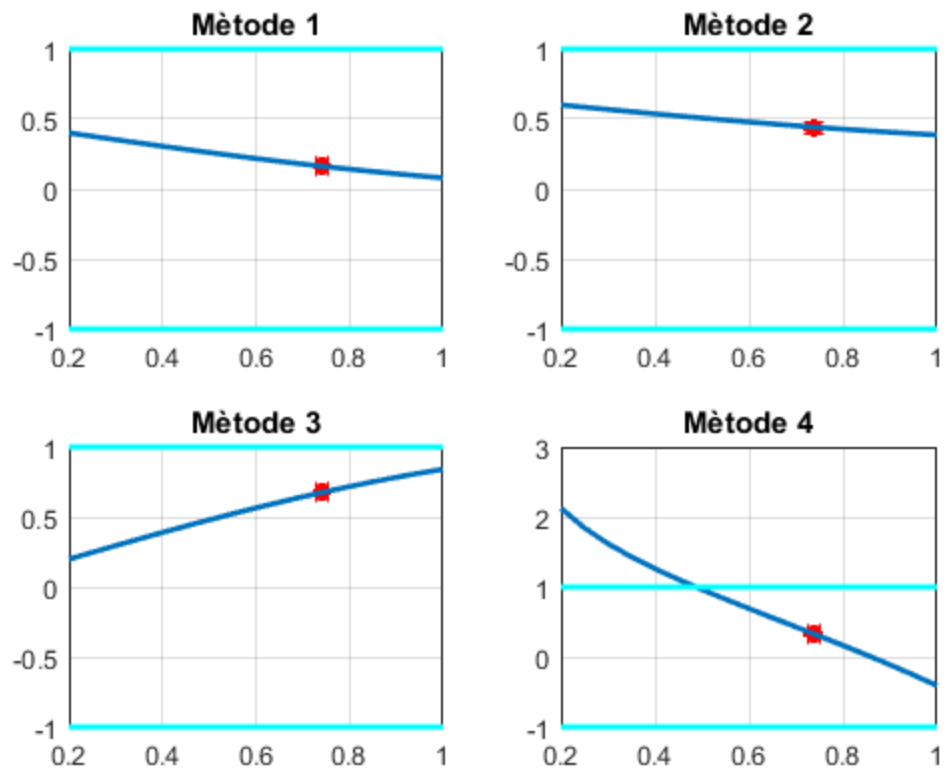
Mètode 4. $x=\sqrt{x*\cos(x)}$

```
a=0.2; b=0.4;
%a=0.6; b=0.8;
ol = 0.0000000005;
g4=@(x)sqrt(x*cos(x));
dg4=@(x)(cos(x)-x.*sin(x))./(sqrt(x.*cos(x)));
if abs(dg4(a)) < 1
    [ xi ] = fixedpt( f, g4, a, b, tol );
else
    fprintf('\nMètode divergent\n')
end
fprintf('\n\n')
```

Mètode divergent

Estudi convergència

```
t=0.2:0.05:1;
figure(2)
subplot(2,2,1),plot(alpha,dg1(alpha),'r*',t,-
ones(size(t)),'c',t,dg1(t),t,ones(size(t)),'c','LineWidth',2),grid,title('Mètode
1')
subplot(2,2,2),plot(alpha,dg2(alpha),'r*',t,-
ones(size(t)),'c',t,dg2(t),t,ones(size(t)),'c','LineWidth',2),grid,title('Mètode
2')
subplot(2,2,3),plot(alpha,dg3(alpha),'r*',t,-
ones(size(t)),'c',t,dg3(t),t,ones(size(t)),'c','LineWidth',2),grid,title('Mètode
3')
subplot(2,2,4),plot(alpha,dg4(alpha),'r*',t,-
ones(size(t)),'c',t,dg4(t),t,ones(size(t)),'c','LineWidth',2),grid,title('Mètode
4')
```



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