# Safety Evaluation Report of MOBATSim -AEB

according to ISO 26262, ISO 21448, EuroNcap



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## **Chapter 1. Introduction**

This is a safety evaluation report for MOBATSim which according to three standards and generate a case study.

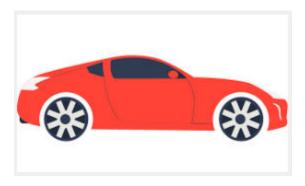


Figure 1.1. Style of the test vehicle.

## Chapter 2. HARA

### 2.1. Scenario definition -laneMerge

The test scenario shows below which contains two traffic paticipants drive on a merged road, the trajectories of two vehicles are distinguished with different color .

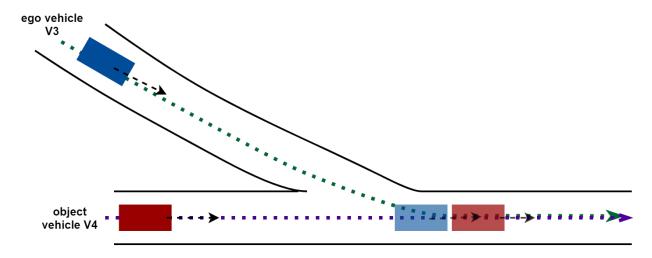


Figure 2.1. Test Scenario in MOBATSim

The road features of the test scenario are listed below:

- 1. Single lane
- 2. Road length
- 3. lane width 3.7m
- 4. No traffic signal and traffic signal controller

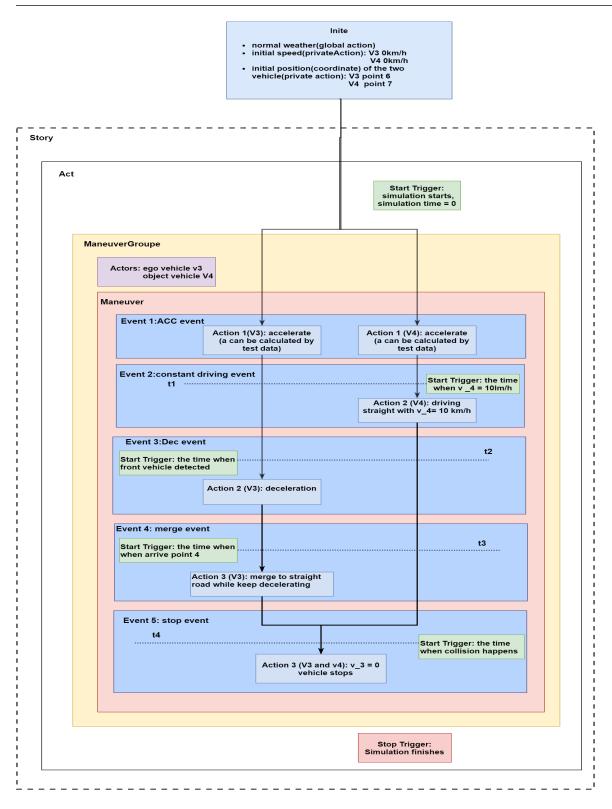
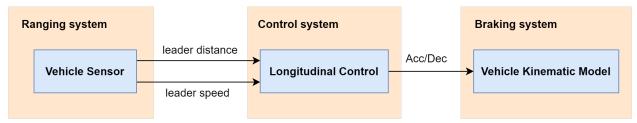


Figure 2.2. Scenario Definition under OpenScenario

#### 2.2. Item Definition -AEB



- Functionality: AEB detect leading vehicle with ranging system, with the caltulation of the control system, gives the braking command to the braking system.
- 2. Operational design domain: This AEB function is only appropriate for the MOBATSim platform, in which most of the roads are single lanes and no other vehicles drive alongside the leading vehicle.

#### 2.3. Situation analysis and Hazard identification

- 1. Operational mode: normal driving.
- 2. Operational scenario: Normal city road with single lane.
- 3. Environmental details: Normal weather (default)
- 4. Situational details: low speed (10km/h~30km/h)
- 5. Item usage: correctly used (default)

#### 2.4. Hazardous event classification

The ASIL level is ASIL B.

#### 2.5. Safety goal and functional safety requirement

# **Chapter 3. SOTIF**

### **Chapter 4. Case study**

The next table is and exanmlpe of test data from the simulation. For the sake of simplicity, only the data from vehicle\_3 and vehicle\_4 is presented here, which is used to get score for AEB system when the collision happens .

The next figure shows the variation of the speed during the simulation time (30s)in which presents the time point that the collision happens.

Chapter 5. Chapter 5: Summary					