



# PHY 110 Engineering Physics

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Lecture 3

UNIT 1 – Electromagnetic theory

# What we learned so far!

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## 1. Scalar and Vector quantities

- It is enough to have a magnitude for **scalar** physical quantities where as it is essential to have both magnitude and direction for the **vector** physical quantities.

## 2. Scalar and vector field

- **Region of space/domain** in which a function,  $f(x,y,z)$ , signifies a physical quantity (Temperature, Velocity) is the **field**.
- **Scalar field**: Each point in space is associated with a **scalar point function** (Temperature, potential) having magnitude.
- **Vector field**: Each point space is associated with a **vector point function** (Electric field, Gravitational field) having magnitude and direction, both of which changes from point to point.

## 3. Del operator ( $\nabla$ )

- It is a differential operator
- It is not a vector by itself
- It operate on scalar and vector functions and the resulting function may be a vector or scalar function depending on the type of operation.

**Rectangular (x,y,z), cylindrical (s,φ,z) and spherical polar(r, φ,θ) coordinate systems**

- **Curvilinear coordinate system**
- **Coordinate transformation**
- **Partial differential calculus**



**Advanced Engineering Mathematics**  
**By ERWIN KREYSZIG**

# What we learned so far?

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## 4. Operation with del ( $\nabla$ ) operator

- Gradient of scalar function  $F$  – Directional derivative..maximum change of the scalar function  $F$  is along the direction of vector  $\nabla F$ , which nothing but the direction of outward surface normal vector
- Divergence of a Vector function  $\mathbf{A}$  - Gives the measure of the vector function's spread out at a point- is solenoidal or divergenceless when divergence of the vector is zero which means that flux of the such vector field entering into a region is equal to that leaving the region, a condition known as incompressibility; also gives an idea about source ( $\nabla \cdot \mathbf{A} > 0$ ) means vector diverge and sink ( $\nabla \cdot \mathbf{A} < 0$ ) means vector converge.
- Curl of a Vector function  $\mathbf{A}$  – regarding the rotation of the vector and the vector function is irrotational when curl of the vector is zero, such fields are known as conservative fields.

Which is/are correct statement(s) regarding the gradient of a scalar function ( $F$ ),  $\vec{\nabla}F$

- a) Maximum change in the scalar function ( $F$ ) is along  $\vec{\nabla}F$
- b) It is a vector quantity
- c) Both a and b
- d) None of the above

Answer: C

If the divergence of the vector is zero i.e  $\vec{\nabla} \cdot \vec{A} = 0$ . Then that vector  $\vec{A}$  is called

- a) Solenoidal vector
- b) Rotational Vector
- c) Null vector
- d) Unit vector

Answer: A

**Which is the correct statement for the ‘Curl of a vector’  $\vec{\nabla} \times \vec{A}$  ?**

- a) Curl of a vector is a vector quantity.
- b) Curl of a vector is a rotational vector
- c) Curl of a vector is normal to the area that make circulation maximum.
- d) It is not possible to have the curl of a scalar quantity.
- e) All of the above
- f) None of the above

**Answer: E**

**‘Curl of a vector’  $\vec{\nabla} \times \vec{A}$  is Zero, then the vector is**

- a) Solenoidal.
- b) Irrotational
- c) Null vector
- d) Unit vecor

## Stokes theorem relates

- a) Volume integral to surface integral
- b) Line integral to surface integral
- c) Surface integral to line integral



# Gauss's law in Electrostatic (First law)

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**Electric flux ( $\Phi_E$ )** : The area integral of the Electric field ( $\mathbf{E}$ ) over any closed surface is the  $\Phi_E$  or electric field is the flux per unit area

$$\Phi_E = \oiint \vec{E} \cdot d\vec{S} \longrightarrow \text{Eq..1}$$

**Gauss's law**: Electric flux ( $\Phi_E$ ) from a closed surface (**Gaussian surface**) is equal to  $1/\epsilon_0$  times the charge ( $q$ ) enclosed by the surface

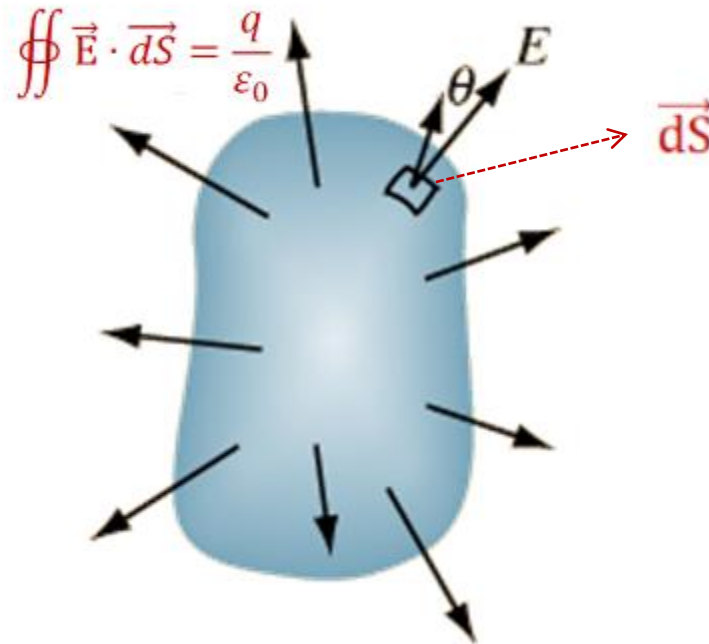
$$\Phi_E = \frac{q}{\epsilon_0} \longrightarrow \text{Eq..2}$$

$\epsilon_0$  is the permittivity of free space. We know absolute permittivity  $\epsilon = \epsilon_0 \epsilon_r$

It is the ability of a material to store electric energy under influence of an electric field in its dielectric medium.

From Eq.1 and 2

$$\oiint \vec{E} \cdot d\vec{S} = \frac{q}{\epsilon_0}$$



- Gauss's Law is a general law applying to any closed surface.
- It is an important tool since it permits the assessment of the amount of enclosed charge by mapping the **electric field normal** to the surface outside the charge distribution
- Or can be used to calculate electric field

**Poisson's Equations:** is a simple second order differential equation that come up in most of the engineering and physics fields.

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$$\nabla^2 X = -\text{constant}$$

Siméon Denis Poisson (1781-1840), French mathematician, engineer, and physicist who made many scientific advances

For example, the solution to **Poisson's equation** is the potential field caused by a given electric charge or mass density distribution; with the potential field known, one can then calculate electrostatic or gravitational (force) field

It applies to electrostatics

## Eg. In Electrostatics

Poisson's equation states that the Laplacian ( $\nabla^2$ ) of electric potential at a point is equal to the ratio of the volume charge density ( $\rho$ ) to the absolute permittivity of the medium ( $\epsilon = \epsilon_0 \epsilon_r$ ). Laplace's equation tells us that the laplacian of electric potential at a point is equal to zero.

$$\text{Eq.1} \quad \oiint \vec{E} \cdot d\vec{S} = \frac{q}{\epsilon_0} \quad \text{Gauss's first law}$$

Charge distributed over a volume with  $\rho$  is the volume charge density

$$\text{Eq.2} \quad \iiint \rho dV = q$$

$$\text{Eq.3} \quad \epsilon_0 \oiint \vec{E} \cdot d\vec{S} = q$$

Applying divergence theorem to eq.3

$$\epsilon_0 \iiint \vec{\nabla} \cdot \vec{E} dV = \iiint \rho dV \quad \longrightarrow \quad \vec{\nabla} \cdot \vec{E} = \frac{\rho}{\epsilon_0} \quad \text{Eq.4}$$

Integrands must be equal for LHS and RHS

# Poisson Equation in Electrostatics

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$$\vec{\nabla} \cdot \vec{E} = \frac{\rho}{\epsilon_0} \quad \text{Eq.4}$$

Electric field ( $\mathbf{E}$ ) and potential ( $V$ ) are related as

But  $\vec{E} = -grad V = -\vec{\nabla}V \quad \text{Eq.5}$

$V$  is the Energy required for moving a unit +ve charge from a reference point to a specific point in an electric field

$$\vec{\nabla} \cdot (-\vec{\nabla}V) = \frac{\rho}{\epsilon_0} \quad \text{Eq. 5 in Eq.4}$$

By using the vector identity for  $\vec{A} \cdot \vec{A} = A^2$

$$\nabla^2 V = -\frac{\rho}{\epsilon_0}$$

Eq.6 is the Poisson's Equation in electrostatics

**Laplace Equations:** is also simple second order differential equation that come up in most of the engineering and physics fields.  $\nabla^2 X = 0$

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Like Poisson equation, it also applies to electrostatics.

### **Eg. In Electrostatics**

$$\nabla^2 V = -\frac{\rho}{\epsilon_0} \quad \text{Poisson's Equation}$$

For a charge free region i.e  $\rho=0$ , then the Poisson's Equation changes to

$$\text{Eq.7} \quad \nabla^2 V = 0$$

This, Eq.7 is known as Laplace's equation and  $\nabla^2$  is the Laplacian operator.

# Laplace Equation

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$$\nabla^2 V = \frac{\partial^2 V}{\partial x^2} + \frac{\partial^2 V}{\partial y^2} + \frac{\partial^2 V}{\partial z^2} = 0 \quad \text{Cartesian coordinate}$$

$$\nabla^2 V = \frac{1}{s} \frac{\partial}{\partial s} \left( s \frac{\partial V}{\partial s} \right) + \frac{1}{s^2} \frac{\partial^2 V}{\partial \phi^2} + \frac{\partial^2}{\partial z^2} = 0 \quad \text{Cylindrical coordinate}$$

$$\nabla^2 V = \frac{1}{r^2} \frac{\partial}{\partial r} \left( r^2 \frac{\partial V}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left( \sin \theta \frac{\partial V}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 V}{\partial \phi^2} = 0 \quad \text{Spherical coordinate}$$

Laplace's equation is named for Pierre-Simon Laplace, a French mathematician

# Continuity Equation

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We know current,  $I$  is the rate of change of charge,  $q$  i.e.  $I = \frac{dq}{dt}$

If  $\rho$  is the charge density, then the charge,  $q$ , enclosing the volume is given by

$$q = \iiint \rho dV$$

Also if  $J$  is the current density  $I = \iint \vec{j} \cdot d\vec{S}$

$$\iint \vec{j} \cdot d\vec{S} = -\frac{d}{dt} \iiint \rho dV \quad \text{-ve sign means decreasing } \rho \text{ as current flows out of the volume}$$

By using the Gauss divergence theorem to LHS, we get



# Continuity Equation

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$$\iiint \vec{\nabla} \cdot \vec{j} dV = - \iiint \frac{d\rho}{dt} dV$$

The above equations is true for any volume. So we can put the integrands to be equal

$$\vec{\nabla} \cdot \vec{j} + \frac{d\rho}{dt} = 0 \quad \text{Continuity Equation}$$

Current density flowing out of the closed volume is equal to the rate of decrease of charge within that volume.

Gauss theorem uses which of the following operations?

- a) Gradient
- b) Curl
- c) Divergence
- d) Laplacian

Stokes theorem uses which of the following operations?

- a) Gradient
- b) Curl
- c) Divergence
- d) Laplacian