

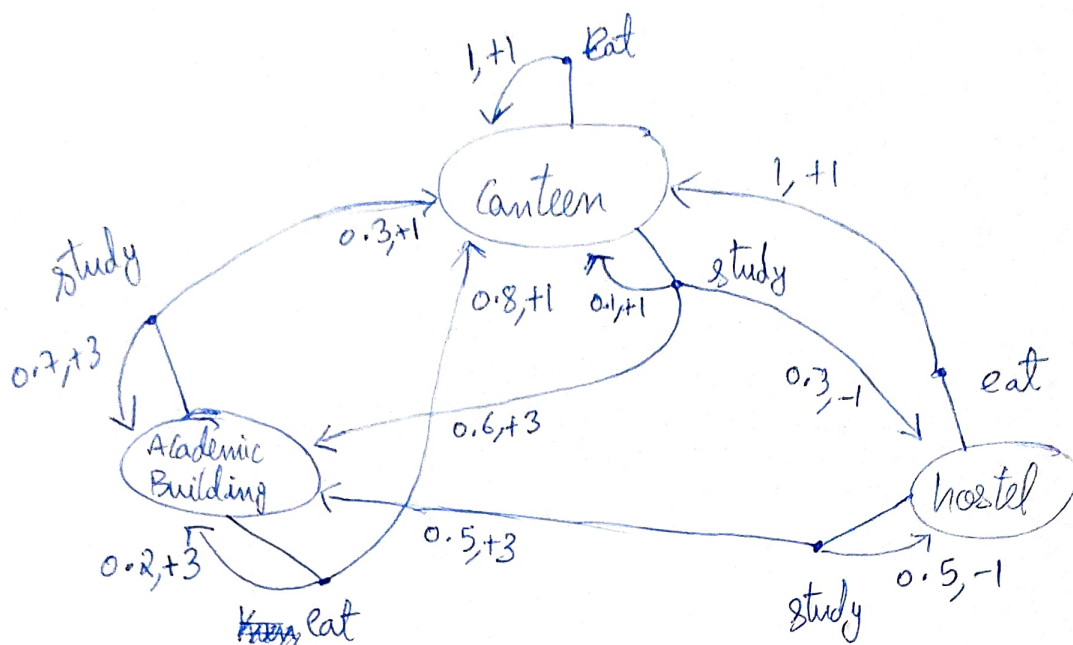
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Assignment - I

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Q1



MDP diagram

s	a	s'	$P(s', r s, a)$	$\gamma(s, a, s')$
Canteen	study	Canteen	0.1	+1
Canteen	study	hostel	0.3	-1
Canteen	study	Academic Build.	0.6	+3
Canteen	eat	Canteen	1	+1
hostel	study	hostel	0.5	-1
hostel	study	Academic Build.	0.5	+3
hostel	eat	Canteen	1	+1
Academic Build	study	Academic Build	0.7	+3
Academic Build	study	Canteen	0.3	+1
Academic Build	eat	Academic Build	0.2	+3
Academic Build	eat	Canteen	0.8	+1

other transitions have probability = 0 and hence no reward.

⇒ Both value and policy iteration show same trend in state-value function,

$$\Rightarrow V(\text{academic building}) > V(\text{canteen}) > V(\text{hostel})$$

as expected because of the rewards associated with these places show same pattern.

⇒ The optimal policy in both cases was to 'study' in any locations when possible.