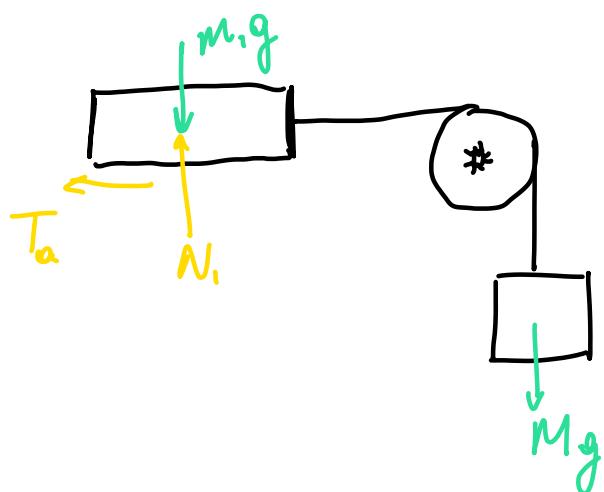
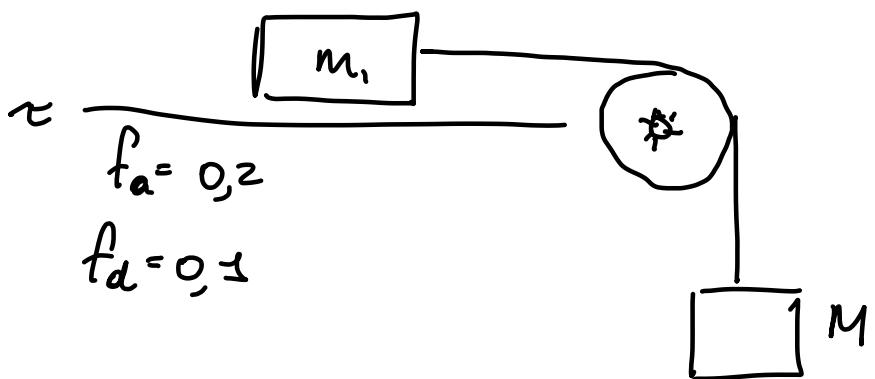


Esercitazione 15 -

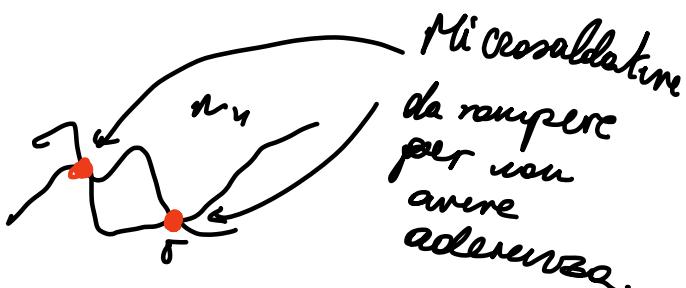
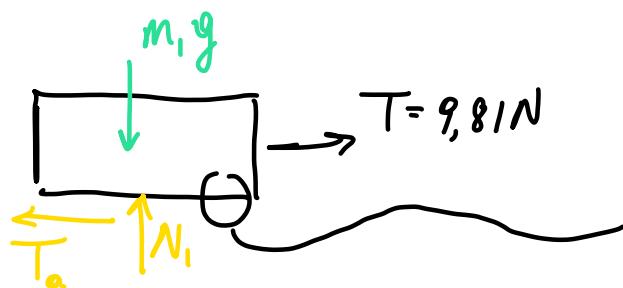
Iniziamo con l'attacco statico e dinamico

$$m_1 = 10 \text{ kg} \quad M = ? \text{ tale che}$$



$$T_{\text{att}} = f_a \cdot N_1$$

$$M = 1 \text{ kg} \rightarrow M g = 9,81 \text{ N}$$



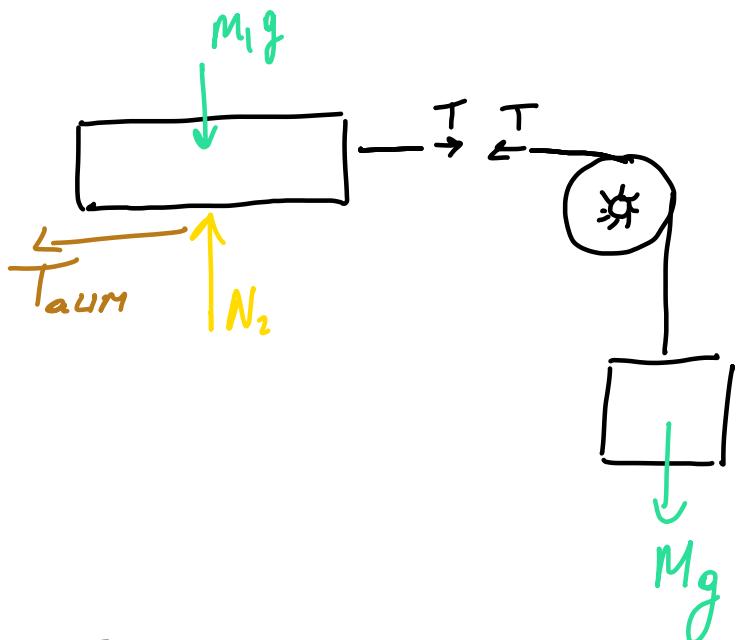
$$\sum F_r = 0 \Rightarrow N_1 = m_1 g$$

$$\sum F_o = 0 \Rightarrow T_a = T = 9,81 \text{ N}$$

$$T_{\text{adim}} = f_a N_1 = 0,2 \cdot m_1 \cdot 9,81 = 19,62 \text{ N}$$

$T = 9,81$ non è abbastanza per superare l'aderenza.

Ma? Tale per romper aderenza \rightarrow ci mettiamo alle condizioni limite di aderenza



$$\sum F_v = 0 \rightarrow N_2 = m_1 g$$

$$T_{\text{adim}} = f_a N_1 = 0,2 m_1 g = 19,62 \text{ N}$$

$$\sum F_o = 0 \rightarrow T = T_{\text{adim}} = 19,62$$

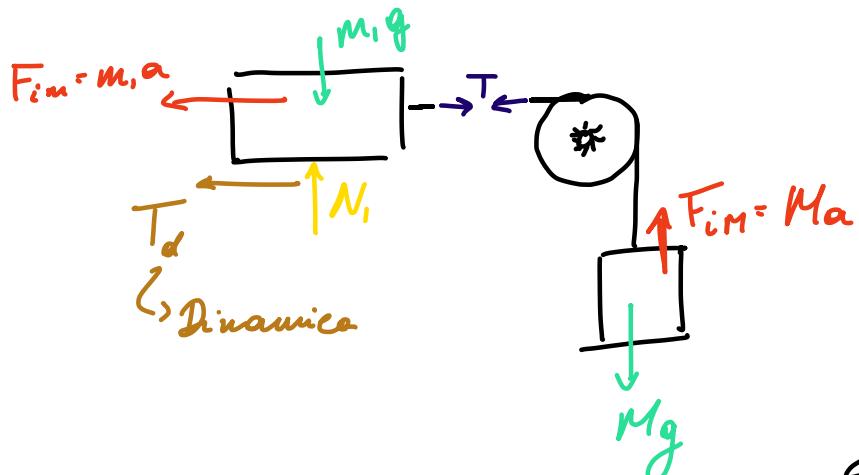
$$\sum M_o^{\text{DUEG}} = 0 \rightarrow TR = MgR \rightarrow T = Mg$$

$$M = \frac{T}{g} = \frac{19,62}{9,81} = 2 \text{ kg}$$

Supponiamo che il sistema inizia muoversi sempre a $M \cdot g$

CONDIZIONE LIMITE DINAMICA a $M = 2\text{kg}$

Scheme Dinamico

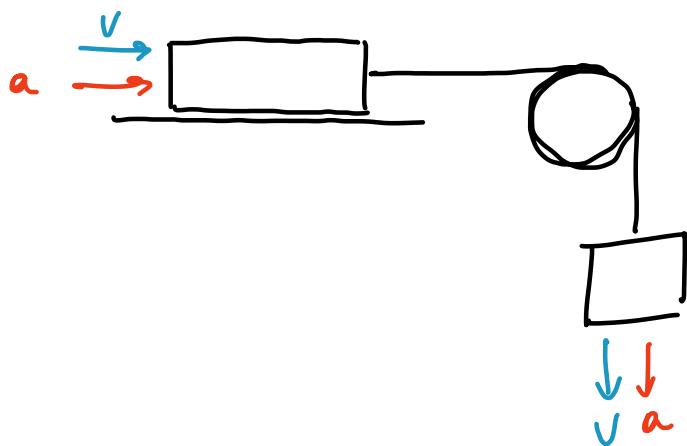


$$|T_d| = f_d \cdot |N_1|$$

$$\sum F_v^{m_1} = 0 \rightarrow N_1 = m_1 g$$

$$\begin{aligned} \sum F_o^{m_1} &= 0 \rightarrow T = m_1 a + T_d \\ &= m_1 a + f_d m_1 g \end{aligned}$$

Scheme Cinematico



$$\sum M_o^{\text{ext}} = 0$$

$$\hookrightarrow TR = MgR - F_{im}R$$

$$Mg - Ma = m_1 a + f_d m_1 g$$

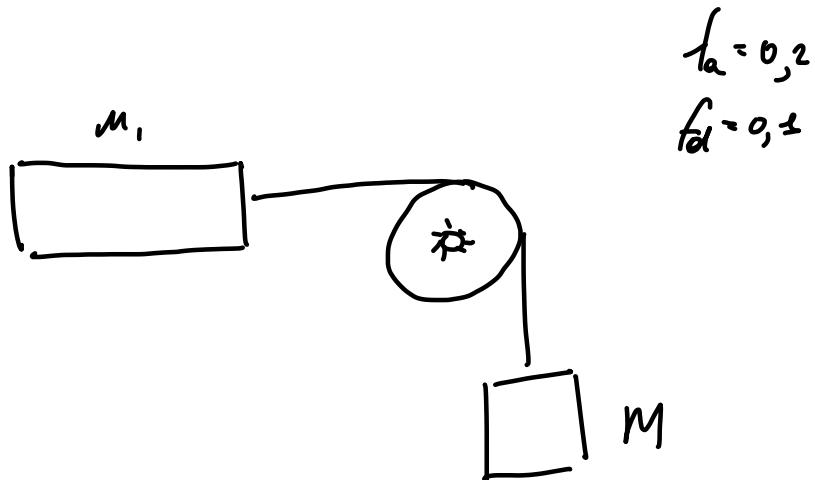
$$\hookrightarrow a(M+m) = Mg - f_d m_1 g$$

$$\hookrightarrow a = \frac{Mg - f_d m_1 g}{M + m_1}$$

$$- \frac{2 \cdot 9,81 - 0,2 \cdot 10 \cdot 9,81}{12}$$

$$= 0,82 \frac{\text{m}}{\text{s}^2}$$

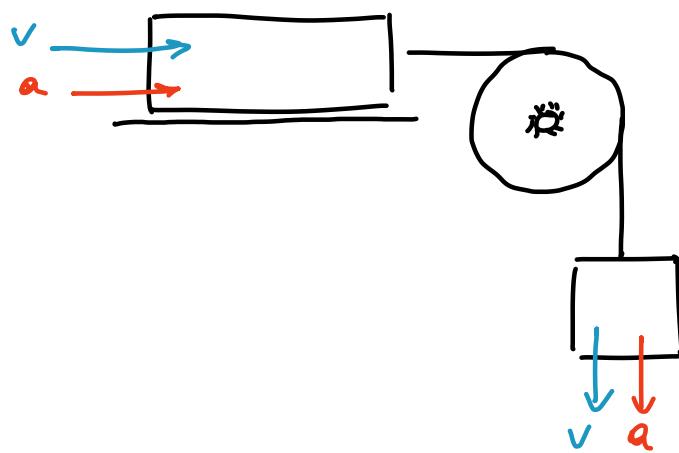
Stern esercizio ma $M = 20\text{kg}$



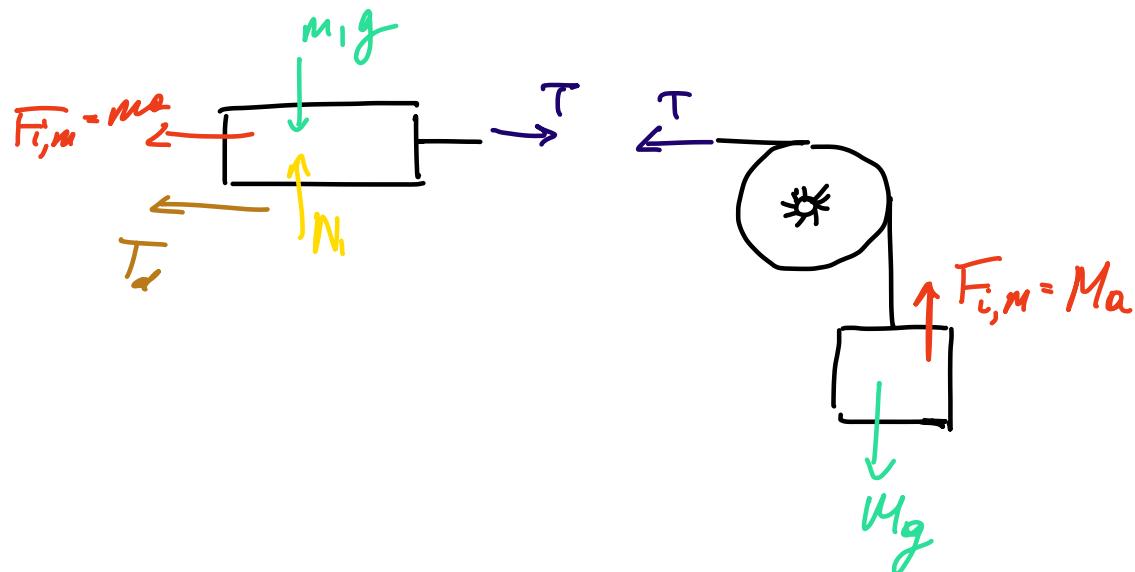
$$f_a = 0,2$$

$$f_d = 0,1$$

Schema Cinematico



Schema Dinamico



1) $|T_d| = f_d N_1$ Relazione attuale dinamico

2) $\sum F_r^{m_1} = 0 \rightarrow N_1 = m_1 g$

$$\overline{T_d} = f_d m_1 g$$

3) $\sum F_o^{m_1} = 0 \rightarrow T = m_1 a + f_d m_1 g$

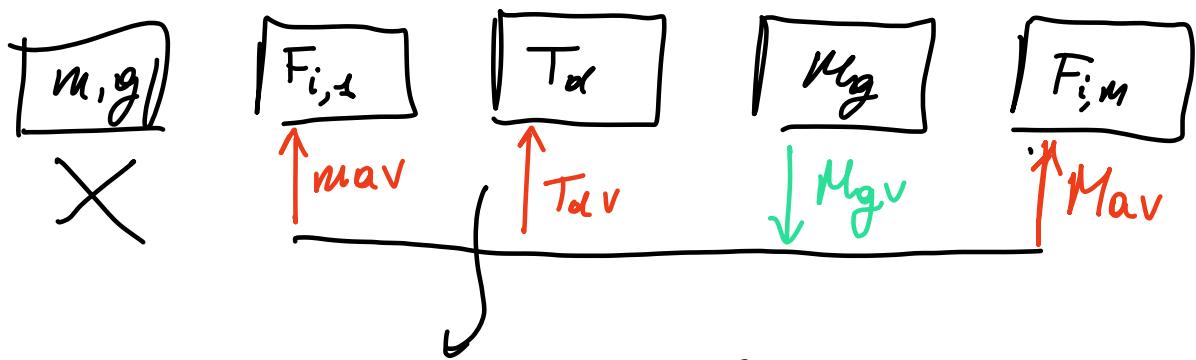
4) $\sum M_o^{m_2} = 0 \rightarrow TR = MgR - MaR$

$$Mg - Ma = m_1 a + f_d m_1 g$$

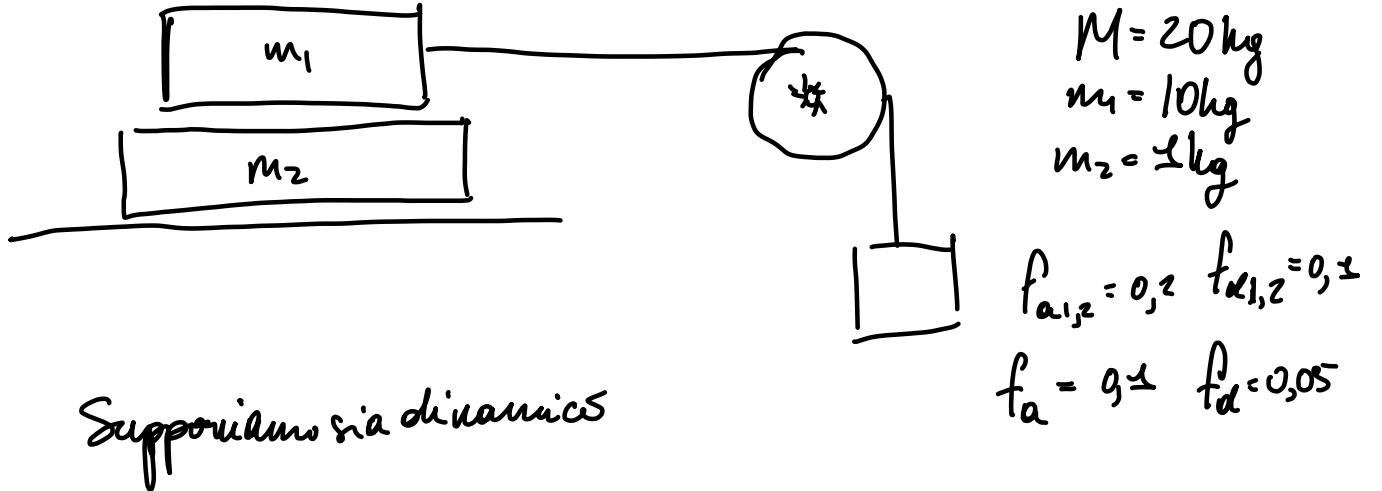
$$M_a + m_1 a = Mg - f_d m_1 g$$

$$a = \frac{Mg - f_d m_1 g}{M + m} =$$

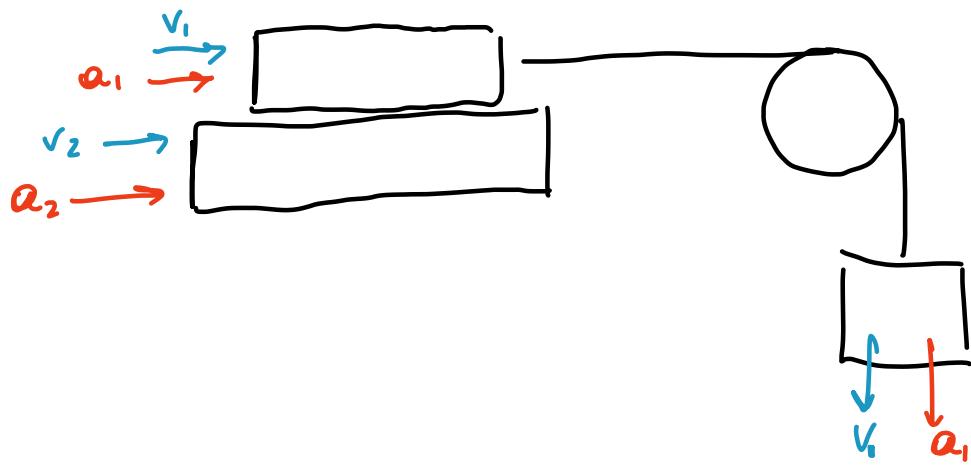
Diagramma rappresentativo



Prende in energia e la dissipata in calore

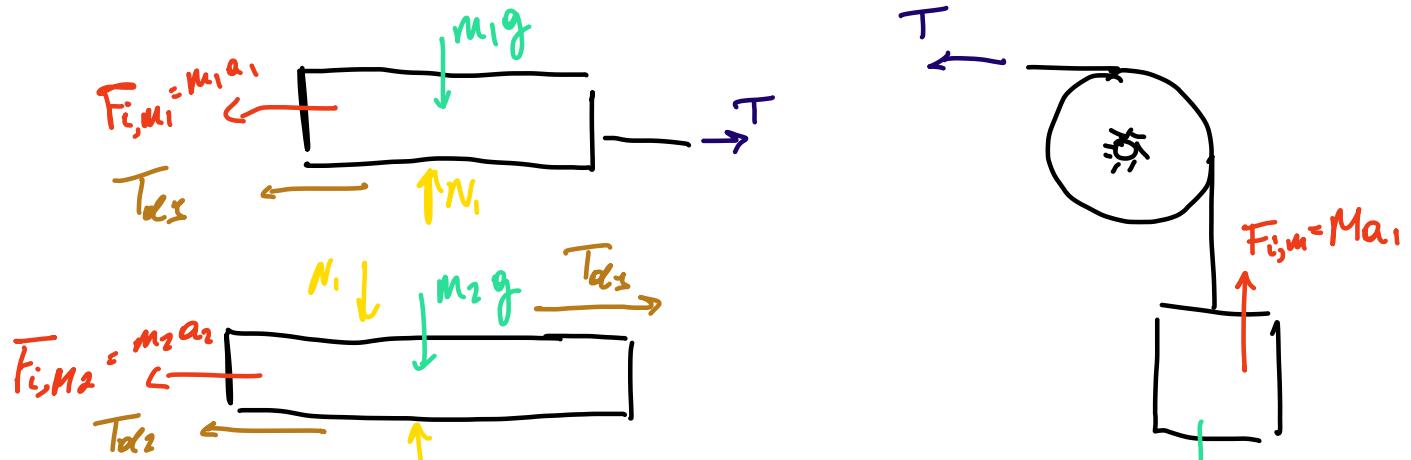


Schemi Cinematici



Ci possiamo aspettare che $v_1 > v_2$ e $a_1 > a_2$

Schemi Dinamici





Potenza al filo ha già posso M_a_1

T_{d2} è utile per il corpo m_2 e inutile nel corpo m_1

T_{d2} assorbe energia, in parte la trasforma in calore, in parte va a battere l'inerzia e l'altro in calore nel corpo m_2 che lo converte in calore

$$\sum F_0^{m_1} = 0 \quad T_{d2} - N_1 - M_{a_1} A$$

$$\sum F_r^{m_1} = 0 \quad N_1 = m_1 g$$

$$\sum F_r^{m_2} = 0 \quad N_2 = N_1 + m_2 g = (m_1 + m_2)g$$

$$T_{d2} = f_{d1,2} A_1 = f_{d2} m_1 g$$

$$T_{d2} = f_{d2} N_2 = f_{d2} m_2 g$$

$$\sum F_0^{m_1} = 0 \quad T = m_1 a_1 + T_{d2} = m_1 a_1 + f_{d2} m_1 g$$

$$\sum F_r^{m_2} = 0 \quad T_{d2} = m_2 a_2 - T_{d2}$$

Incoquite a_1 e a_2

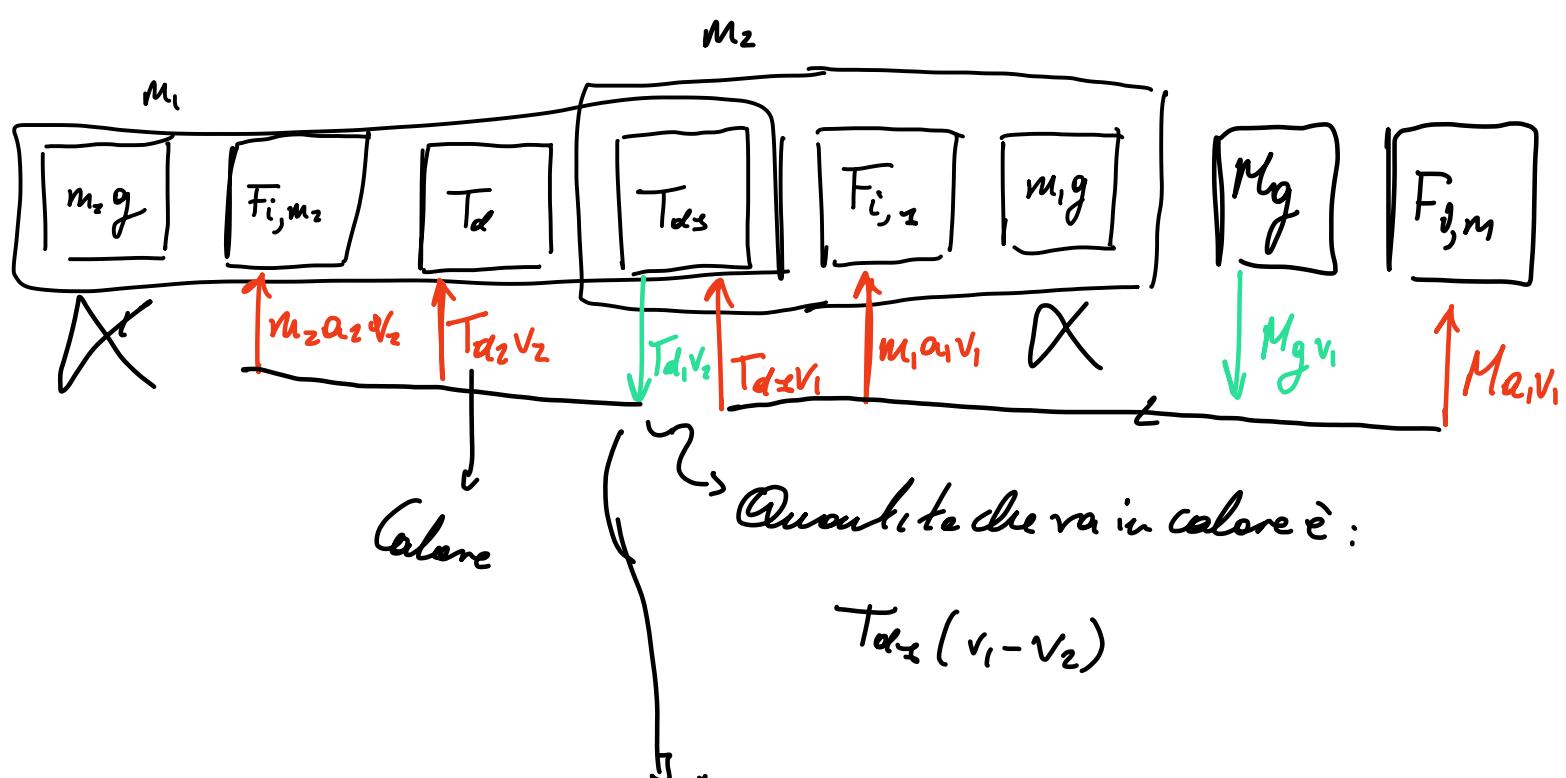
$$Mg - M_{a_1} = m_1 a_1 + f_{d2} m_1 g$$

$$a_1 (M+m) = Mg - f_{\text{diss}} m_1 g$$

$$a_1 = \frac{Mg - f_{\text{diss}} m_1 g}{M+m} = \frac{19}{30} g = 6,21 \frac{m}{s^2}$$

$$\rightarrow m_1 g f_{\text{diss}} = m_2 a_2 + f_d (m_1 + m_2) g$$

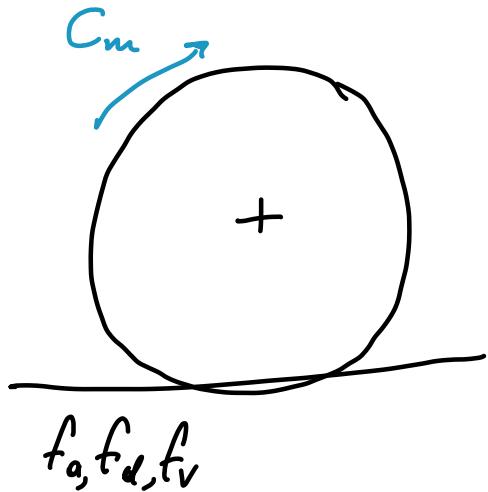
$$a_2 = \frac{m_1 g f_{\text{diss}} - f_d (m_1 + m_2) g}{m_2} = \frac{9,81 - 5,39}{m_2} = 4,42$$



Quantità che va in calore è :

$$T_{d2} (v_1 - v_2)$$

Absorbe potenza e una parte la restituisce, il resto è assorbito

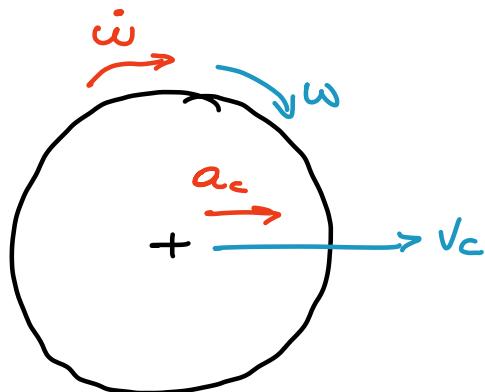


$$m = 20 \text{ kg} \quad v = 0,3 \text{ m} \\ J = 0,8 \text{ kgm}^2 \quad C_m = 10 \text{ Nm} \\ f_a = 0,2 \quad f_d = 0,05 \quad f_v = 0,05$$

Determinare a?

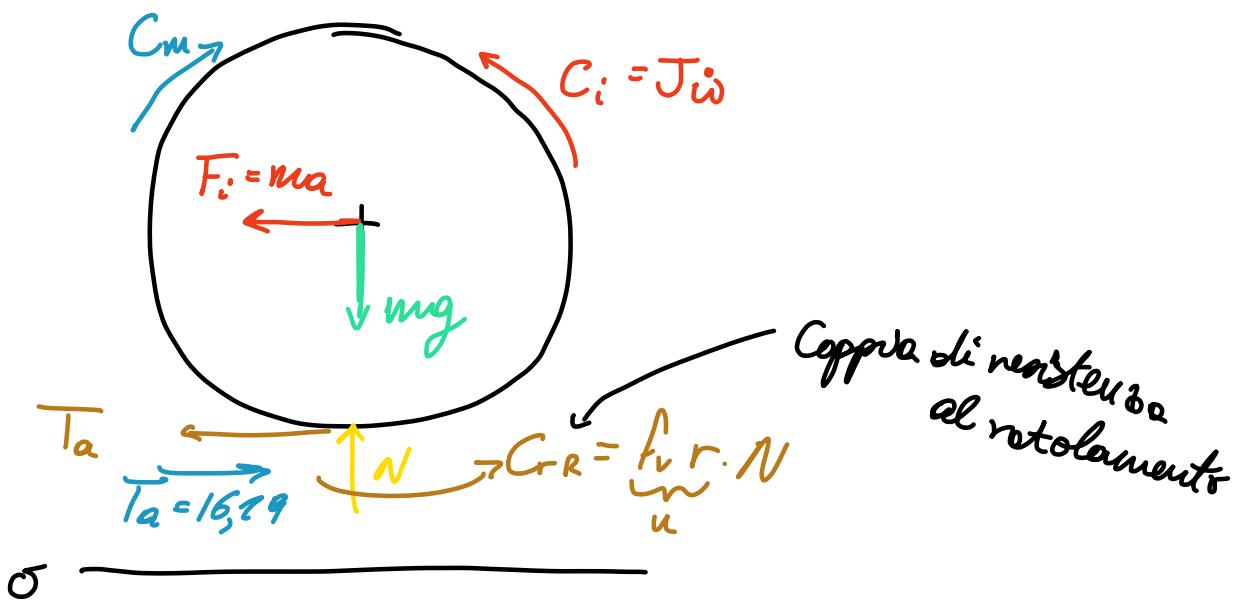
$$3g\ell - 2gdv = 1g\ell$$

Schemă Cinematică



$$v_c = \omega r \quad \left. \begin{array}{l} v_c = \omega r \\ a_c = \omega r \end{array} \right\} \begin{array}{l} \text{Per le leggi} \\ \text{pero} \\ \text{rotolamento} \end{array}$$

Schemă Dinamico



$$\sum F_v^{\text{TUTTO}} \rightarrow N = Mg$$

$$\sum F_o^{\text{TUTTO}} = 0 \rightarrow ma + Ta = 0$$

$$\sum M_E = 0 \quad C_m - F_i r - C_i - Cr_R = 0$$

$$mar + J\dot{\omega} = C_m - F_{vrmg}$$

$$m\ddot{r}^2 + J\dot{\omega} = C_m - F_{vrmg}$$

$$\dot{\omega} = \frac{C_m - F_{vrmg}}{mr^2 + J} = \frac{10 - 6,05 \cdot 0,3 \cdot 20 \cdot 9,81}{20(0,3)^2 + 0,8} = \frac{10 - 2,194}{1,8 + 0,8} = 2,71 \frac{\text{rad}}{\text{s}}$$

$$\alpha_c = \dot{\omega}r = 0,81 \frac{\text{m}}{\text{s}^2}$$

$$F_i \cdot m \alpha_c = 16,29 \text{ N}$$

$$16,29 \text{ N} \leq 0,2 \cdot 20 \cdot 9,81 ?$$

$$16,29 \leq 39,24$$

$$\begin{array}{c} 16,29 \leq 39,24 \\ \uparrow \qquad \uparrow \\ T_{MAX} \end{array}$$

Tclavista

Il vincolo crea abbastanza attrito per battere l'aderenza.