

Lezione 27 - Gas Turbine Engine

Final point on axial turbine analysis:

As we discussed, the last rotors on the last stage we create a twist to allow the blade to not break and it takes different form depending on the distance to the hub. It has a seal (shroud element) at the top. High pressure blades are much much smaller.

General consideration on the mechanical design.

Using impulse stages reduces the number of reaction stages. In general though, we try to maximise the number of reaction stages to maximize efficiency.

Impulse rotors \rightarrow if designed well the $\Delta P = 0$, and $F_{axial} = 0$, we can make the rotor lighter, we use BLISK (bladed-disk)

pg. 14 \rightarrow with images pg. 15

With impulse stages we use dish and diaphragm technology, meaning we keep the hub thin and increase the radius where the rotors stay. There will be some losses, so if not designed well lose impulse status.

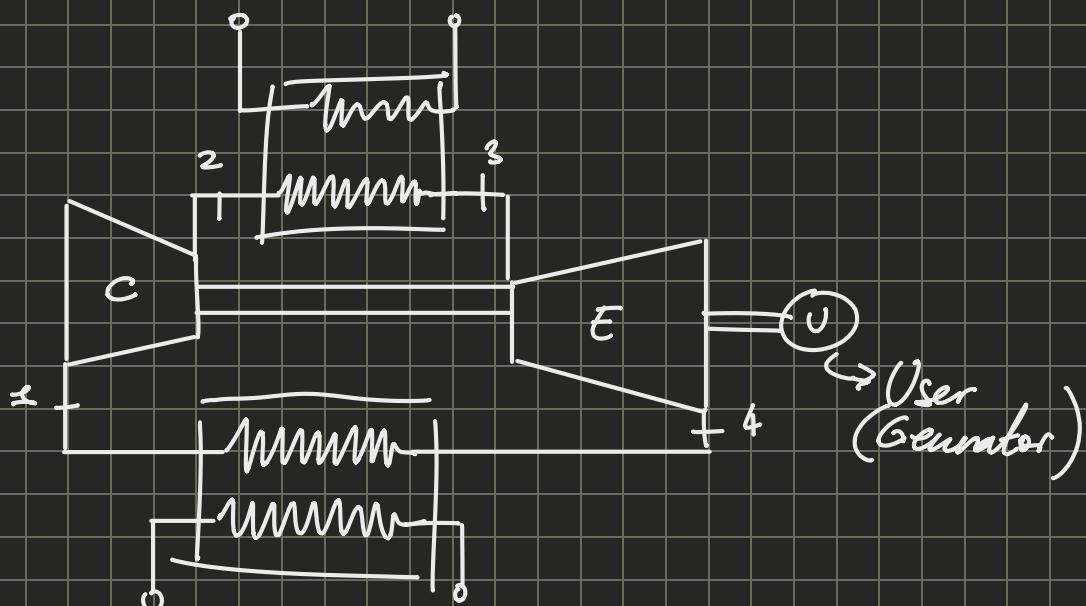
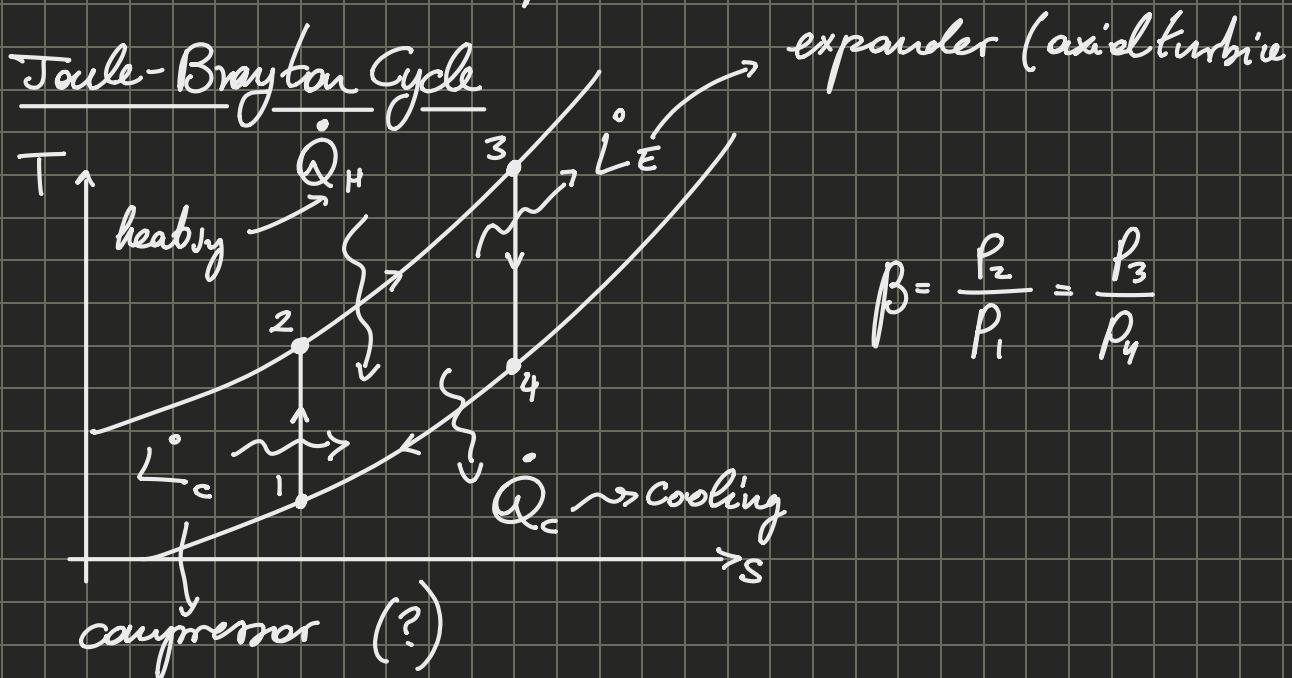
In reaction stages we use drum technology, thus has some height so seals between stages need to be strong.

Energy Systems



Gas Turbine Engines

- ↳ Gas turbine engines operate through the Joule - Brayton cycle.
- ↳ 2 isobaric + 2 isentropic transformations.



Power Balance : $\sum_i \dot{Q}_i + \sum_j \dot{L}_j = 0$
 $\Rightarrow \dot{Q}_H + \dot{Q}_c + \dot{L}_c + \dot{L}_E = 0$

$$\dot{Q}_H - |\dot{Q}_c| + \dot{L}_c - |\dot{L}_E| = 0 \rightarrow \text{considering the signs they will always have}$$

$$\Rightarrow \dot{Q}_H - |\dot{Q}_c| = |\dot{L}_E| - \dot{L}_c$$

Mechanical Balance at the shaft:

$$\dot{L}_c + \dot{L}_E + \dot{L}_v = 0 \rightarrow \text{If not } 0, \text{ the shaft accelerates and there will be an initial term.}$$

$$\dot{L}_c - |\dot{L}_E| + \dot{L}_v = 0$$

$$\Rightarrow \dot{L}_v = |\dot{L}_E| - \dot{L}_c$$

Efficiency:

$$\left[\eta_{TB} = \frac{\dot{L}_v}{\dot{Q}_H} = \frac{|\dot{L}_E| - \dot{L}_c}{\dot{Q}_H} = \frac{\dot{Q}_H - |\dot{Q}_c|}{\dot{Q}_H} = 1 - \frac{|\dot{Q}_c|}{\dot{Q}_H} \right]$$

↳ Thermodynamic

J-B cycle performance \rightarrow Effective performance

\hookrightarrow only representative of the real cycle.

$$\eta_{JB} = 1 - \frac{|\dot{Q}_c|}{\dot{Q}_H} = 1 - \frac{\dot{m}_c c_p (T_4 - T_1)}{\dot{m}_H c_p (T_3 - T_2)} = 1 - \frac{T_1}{T_2} \cdot \frac{\left(\frac{T_4}{T_1} - 1\right)}{\left(\frac{T_3}{T_2} - 1\right)} = 1 - \frac{T_1}{T_2} \cdot \frac{1 - \gamma}{1 - \frac{T_3}{T_2}}$$

$$l + q = \Delta h + \frac{\Delta V}{2} + g \Delta z = c_p \Delta T$$

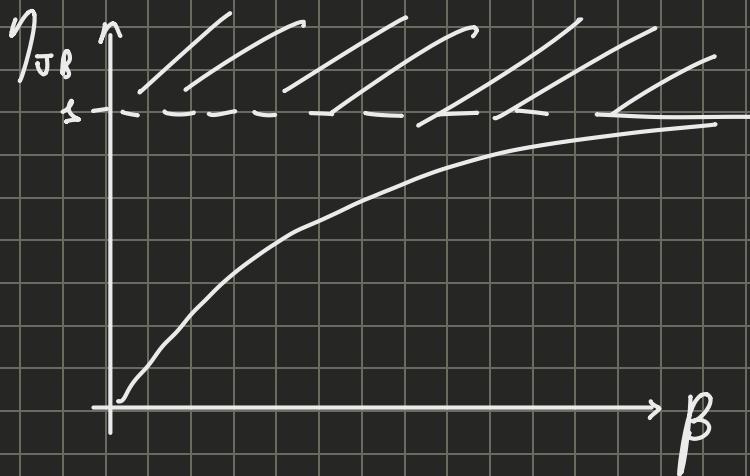
\hookrightarrow heat exchangers $\hookrightarrow \approx 0$, at our level (for us as students), in reality this is not neglected.

have $l = 0$

\hookrightarrow this is only important in aeroturbines since after turbine there is a nozzle.

\hookrightarrow jet engine + turbofan.

$$\text{since } \frac{T_2}{T_1} = \beta^{\frac{1}{f-1}}$$



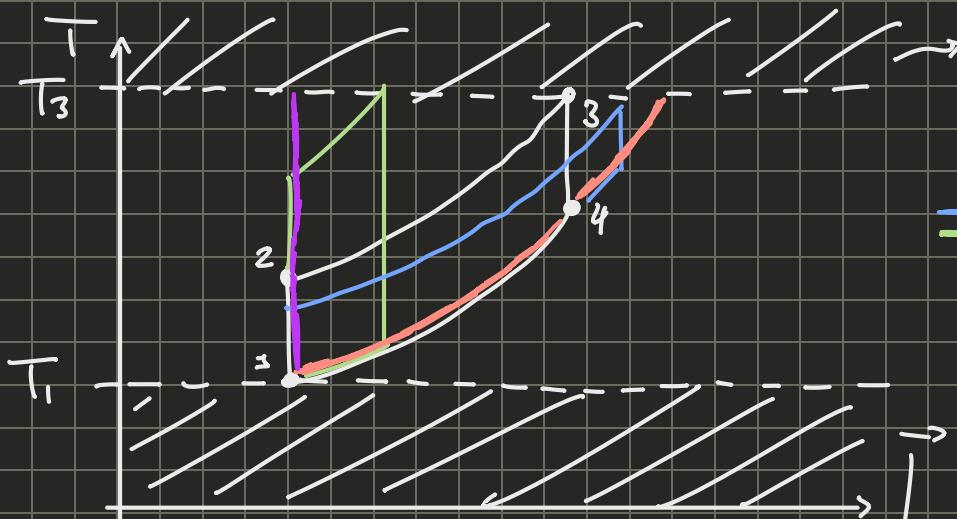
As we increase the stages, the efficiency (This is a theoretical result)

$$\dot{h}_u = \frac{\dot{L}_0}{m} = |\dot{h}_e| - \dot{h}_c = c_p (\bar{T}_3 - \bar{T}_4) - c_p (\bar{T}_2 - \bar{T}_1) =$$

since $q=0$ in expander and compressor

\bar{T}_4 and \bar{T}_2 should be T_{4S} and T_{2S} , but we have no introduced any losses that occur in reality, but we will have to do it later.

$$\begin{aligned} &= c_p (\bar{T}_2 - \bar{T}_1) \left(\frac{\bar{T}_3 - \bar{T}_4}{\bar{T}_2 - \bar{T}_1} - 1 \right) = c_p \bar{T}_1 \left(\beta^{\frac{x-1}{r}} - 1 \right) \left(\frac{\bar{T}_3}{\bar{T}_2} \frac{1 - \cancel{\bar{T}_4/\bar{T}_3}}{1 - \cancel{\bar{T}_2/\bar{T}_1}} - 1 \right) \\ &= c_p \bar{T}_1 \left(\beta^{\frac{x-1}{r}} - 1 \right) \underbrace{\left(\frac{\bar{T}_3}{\bar{T}_1} \beta^{\frac{1-x}{r}} - 1 \right)}_{\bar{T}_3/\bar{T}_2} = \dot{h}_u \end{aligned}$$



The technologies we choose set a limit on T_3 .

— = possible cycles based on technological choice
— = limit set by technology

We impose a limit on T_1 , since

The work depends on T_1 , T_3 and β .

it depends on the heat sink system
Our environmental limit sets this limit.

$$\beta = 1 \Rightarrow \gamma = 0$$

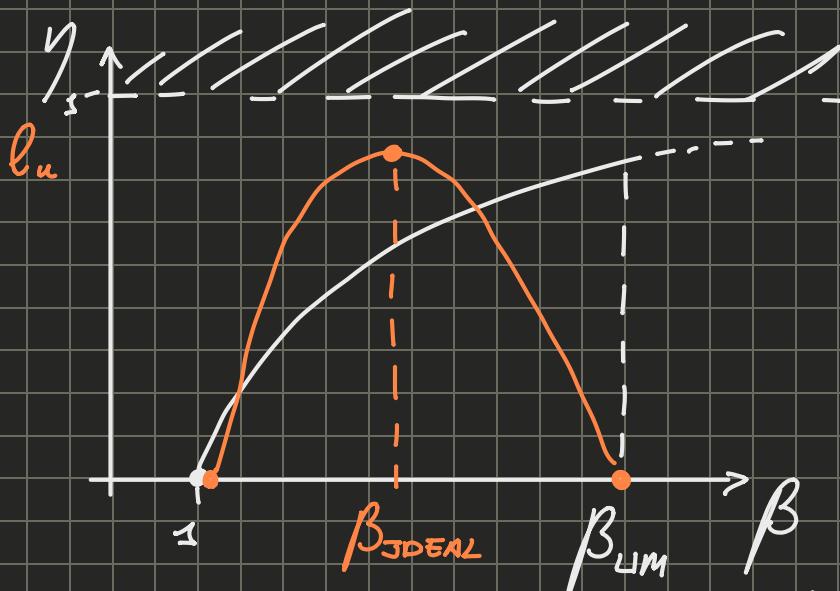
$$l_u = 0 \rightarrow \frac{T_3}{T_1} \beta^{\frac{1-\gamma}{\gamma}} = 1 \Rightarrow \underline{\beta = \left(\frac{T_3}{T_1}\right)^{\frac{\gamma}{\gamma-1}}} \triangleq \beta_{\text{lim}}$$

Since l_u is once-dependent on β .

$\Rightarrow T_2 \rightarrow T_3$ & $T_4 \rightarrow T_1$

Once we violate
an environmental limit of

T_1 and technological
limit to T_3 , we
have our β_{lim} .



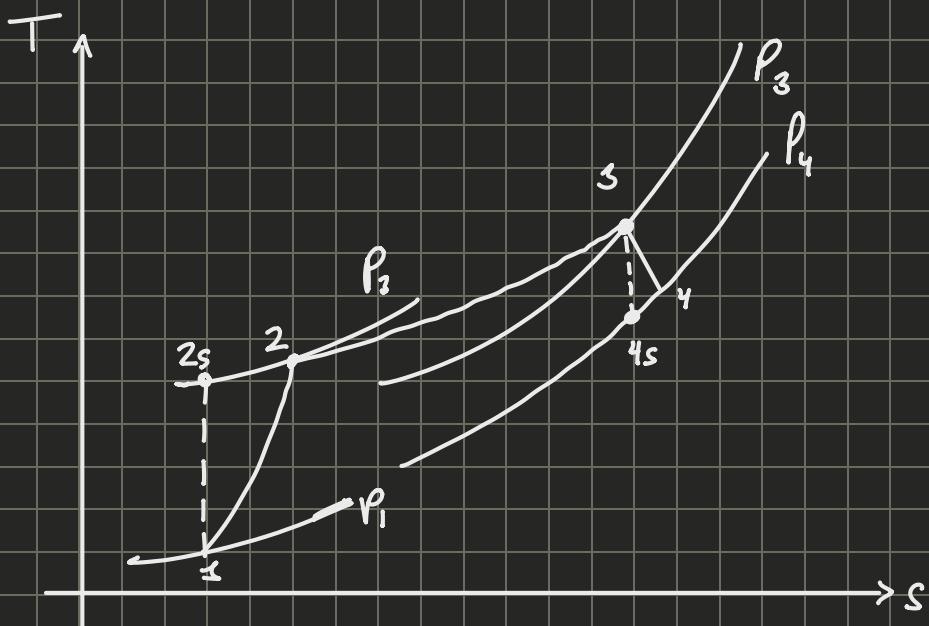
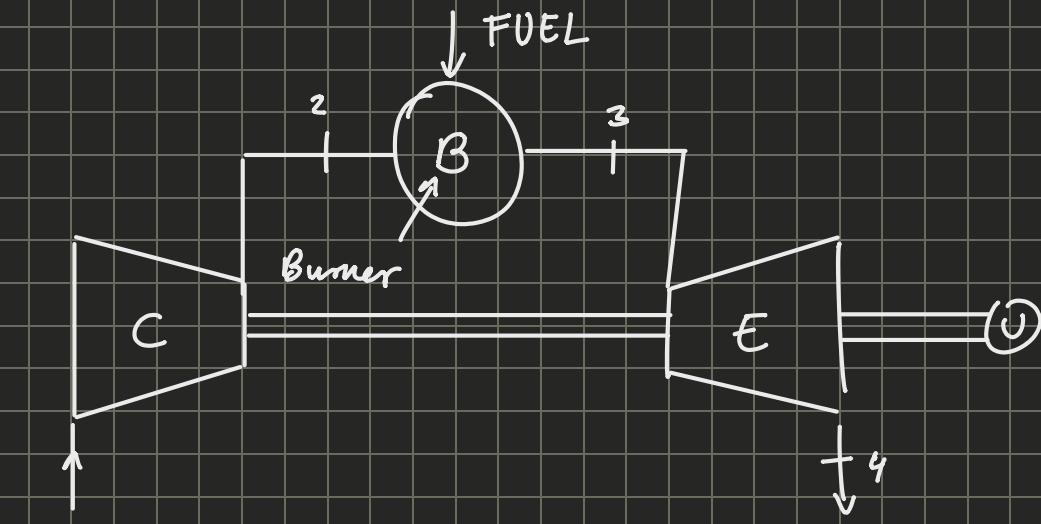
This is not true in the real case but that's fine for now.

$\beta = \beta_{\text{IDEAL}}$ when $T_2 = T_1 \rightarrow$ this will be true for the real system.

Military systems work at more l_u rather than more γ .

Real Gas Turbine Cycle

→ The high temp. heater is a waste of energy, we can replace it with a combustor-changer which mixes the fluid with the gas and send it to the turbine to leave the system. Since the fluid leaves we can also remove the heat exchanger.



- Open, not closed cycle:
- Consequences:
 - Fluid at compressor and turbine is not the same, a compressor we have air, at turbine we have air + fuel.
 - Flow-rate changes, since we add fuel flow rate.
 - Different values of C_p (we keep the same)
 - Conclusions are not significantly different.
 - $\beta_c \neq \beta_e$, but the scenario is not too different
- Compression and expansion are not isentropic, will have

big consequences.