

File Edit View Terminal Tabs Help

```
_window.sh" "ArduCopter" "/home/movax/Documents/Git/ardupilot/build/sitl/bin/arducopter" "-S" "--model" "+" "--speedup" "1" "--slave" "0" "--defaults" "/home/movax/Documents/Git/ardupilot/Tools/autotest/default_params/copter.parm" "-I0"
SIM_VEHICLE: Run MavProxy
SIM_VEHICLE: "mavproxy.py" "--map" "--console" "--out" "127.0.0.1:14550" "--out" "127.0.0.1:14551" "--master" "tcp:127.0.0.1:5760" "--sitl" "127.0.0.1:5501"
RiTW: Starting ArduCopter : /home/movax/Documents/Git/ardupilot/build/sitl/bin/arducopter -S --model + --speedup 1 --slave 0 --defaults /home/movax/Documents/Git/ardupilot/Tools/autotest/default_params/copter.parm -I0
Connect tcp:127.0.0.1:5760 source_system=255
Loaded module console
Loaded module map
Log Directory:
Telemetry log: mav.tlog
Waiting for heartbeat from tcp:127.0.0.1:5760
MAV> STABILIZE> Received 1309 parameters (ftp)
Saved 1309 parameters to mav.parm
mode guided
STABILIZE> arm throttle
GUIDED> GUIDED> takeoff 10
GUIDED> Take Off started
position 20 0 0
GUIDED> x:20.000000, y:0.000000, z:0.000000
```