```
File    Edit    View    Terminal    Tabs    Help
Init Gyro**
AP: ArduPilot Ready
AP: AHRS: DCM active
fence present
AP: SaveWaypoint LOW
AP: PrecisionLoiter MIDDLE
AP: EKF3 IMU0 buffs IMU=19 OBS=7 OF=17 EN:17 dt=0.0120
AP: EKF3 IMU1 buffs IMU=19 OBS=7 OF=17 EN:17 dt=0.0120
AP: EKF3 IMU0 initialised
AP: EKF3 IMU1 initialised
AP: AHRS: EKF3 active
AP: EKF3 IMU1 tilt alignment complete
AP: EKF3 IMU0 tilt alignment complete
AP: EKF3 IMU0 MAG0 initial yaw alignment complete
AP: EKF3 IMU1 MAG0 initial yaw alignment complete
AP: GPS 1: detected as u-blox at 230400 baud
AP: EKF3 IMU0 origin set
AP: EKF3 IMU1 origin set
AP: EKF3 IMU1 is using GPS
AP: EKF3 IMU0 is using GPS
Flight battery 100 percent
Got MAVLink msg: COMMAND_ACK {command : 11, result : 0}
GUIDED> Mode GUIDED
```