```
Build commands will be stored in build/sitl/compile_commands.json
'build' finished successfully (17.032s)
SIM_VEHICLE: Using defaults from (/home/movax/Documents/Git/ardupilot/Tools/auto
test/default_params/copter.parm,/home/movax/Documents/Git/ardupilot/Tools/autote
st/default_params/gazebo-iris.parm)
SIM_VEHICLE: Run ArduCopter
SIM_VEHICLE: "/home/movax/Documents/Git/ardupilot/Tools/autotest/run_in_terminal
_window.sh" "ArduCopter" "/home/movax/Documents/Git/ardupilot/build/sitl/bin/ard
ucopter" "-S" "--model" "gazebo-iris" "--speedup" "1" "--slave" "0" "--defaults"
 "/home/movax/Documents/Git/ardupilot/Tools/autotest/default_params/copter.parm,
/home/movax/Documents/Git/ardupilot/Tools/autotest/default_params/gazebo-iris.pa
rm" "-I0"
SIM_VEHICLE: Run MavProxy
SIM_VEHICLE: "mavproxy.py" "--out" "127.0.0.1:14550" "--out" "127.0.0.1:14551" "
--master" "tcp:127.0.0.1:5760" "--sitl" "127.0.0.1:5501"
RiTW: Starting ArduCopter : /home/movax/Documents/Git/ardupilot/build/sitl/bin/a
rducopter -S --model gazebo-iris --speedup 1 --slave 0 --defaults /home/movax/Do
cuments/Git/ardupilot/Tools/autotest/default_params/copter.parm,/home/movax/Docu
ments/Git/ardupilot/Tools/autotest/default_params/gazebo-iris.parm -I0
Connect tcp:127.0.0.1:5760 source_system=255
Log Directory:
Telemetry log: mav.tlog
Waiting for heartbeat from tcp:127.0.0.1:5760
```