MAVProxy	Vehicle	Link Miss	ion Rally	Fence	Parameter										
STABILIZE	ARM	GPS: OK6	(10)	Vcc 5.00	Radio:	INS	MAG	AS	RNG	AHRS	EKF	LOG	FEN	RC	TE
Batt: 0%/12.5	9V 0.0A	Link 1 OK 10	00.0% (117	53 pkts, 0	lost, 0.00s de	lay)									
Hdg 353/ 0	Alt 0m	AGL 0m/0r	n AirSpe	eed 0m/s	GPSSpeed	l 0m/s	Thr 0	Roll () Pito	ch 0 \	Wind/-				
WP 0 Dista	ance 0m	Bearing 0	AltError	0m(L)	AspdError 0n	n/s(H)	FlightT	ime	ETR (D:00 I	Param 13	309/1309	Mis	sion/	
AP: EKF3 IMU	J0 MAG0 in	itial yaw alig	nment com	plete											
AP: EKF3 IML	J1 MAG0 in	itial yaw alig	nment com	plete											
pre-arm goo	d														
AP: GPS 1: de	tected as ι	ı-blox at 230	400 baud												
AP: EKF3 IMU	J1 origin se	t													
AP: EKF3 IMU	J0 origin se	t													
AP: EKF3 IMU	J0 is using (GPS													
AP: EKF3 IML	J1 is using (GPS													
Flight battery	warning														