

```
movax@Aspire-E5:/opt/ros/foxy/share/gazebo_plugins/worlds$ ls
```

```
gazebo_ros_ackermann_drive_demo.world  
gazebo_ros_bumper_demo.world  
gazebo_ros_camera_demo.world  
gazebo_ros_camera_distortion_barrel_demo.world  
gazebo_ros_camera_distortion_pincushion_demo.world  
gazebo_ros_camera_triggered_demo.world  
gazebo_ros_depth_camera_demo.world  
gazebo_ros_diff_drive_demo.world  
gazebo_ros_elevator_demo.world  
gazebo_ros_force_demo.world  
gazebo_ros_ft_sensor_demo.world  
gazebo_ros_gps_sensor_demo.world  
gazebo_ros_hand_of_god_demo.world  
gazebo_ros_harness_demo.world  
gazebo_ros_joint_pose_trajectory_demo.world  
gazebo_ros_joint_state_publisher_demo.world  
gazebo_ros_multi_camera_demo.world  
gazebo_ros_multicamera_demo.world  
gazebo_ros_p3d_demo.world  
gazebo_ros_planar_move_demo.world  
gazebo_ros_projector_demo.world  
gazebo_ros_ray_sensor_demo.world  
gazebo_ros_skid_steer_drive_demo.world
```