

An Era-NET MarTERA project  
1.2 M€ - 01/04/2021 – 30/09/2023

Coordinated by Laurent Mortier and Yves Ponçon

- ENSTA Paris (ENSTA), France
- Sorbonne Université (SU), France
- Hydroptic (HYDROPTIC), France
- Cyprus Subsea Consulting and Services (CSCS)
- Institute of Oceanology Polish Academy of Sciences (IOPAN), Poland
- Officina Baltica Spin-off Uniwersytetu Gdanskiego sp. z o.o. (OB), Poland
- Institute of Marine Research (IMR), Norway
- Akvaplan.niva (APN), Norway
- Kongsberg Maritime AS (KM), Norway



# Follow-up of Bridges H2020

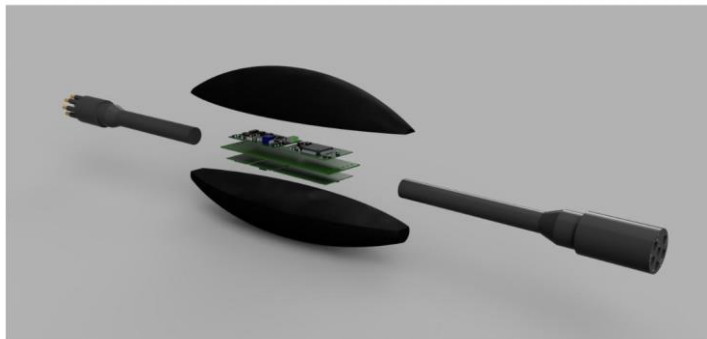
# BIOGLIDER



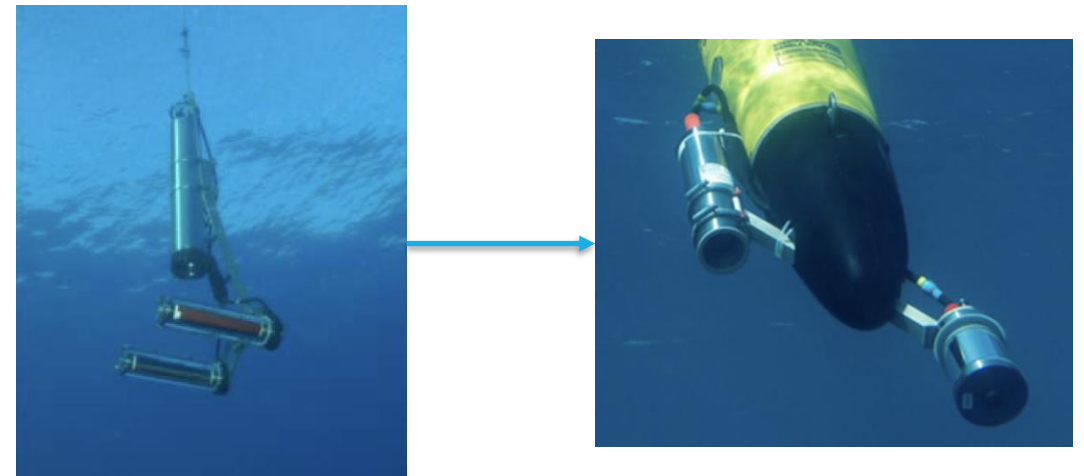
Development of deep gliders



Miniaturization of UVP-5 to UVP-6



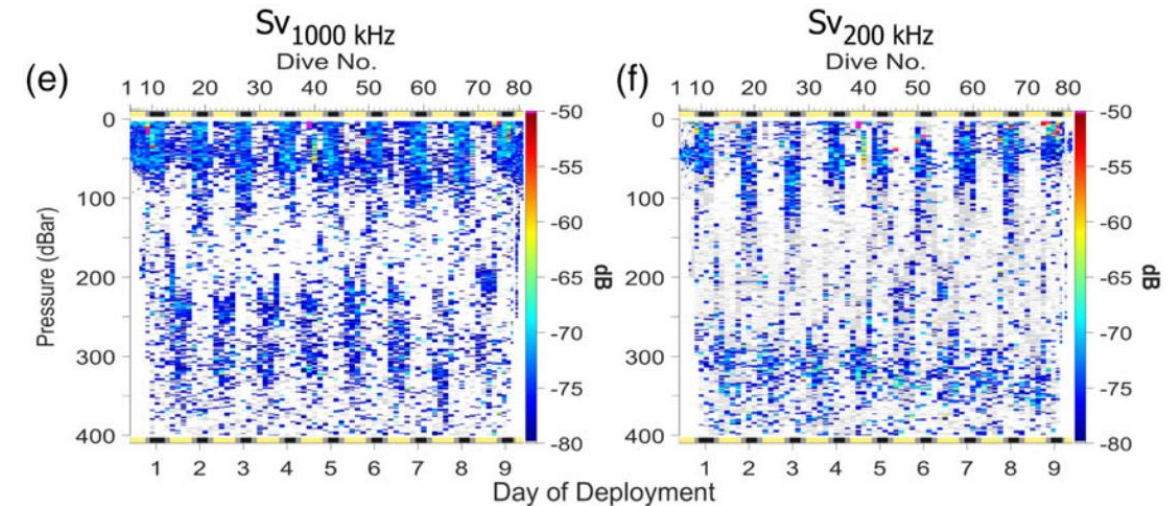
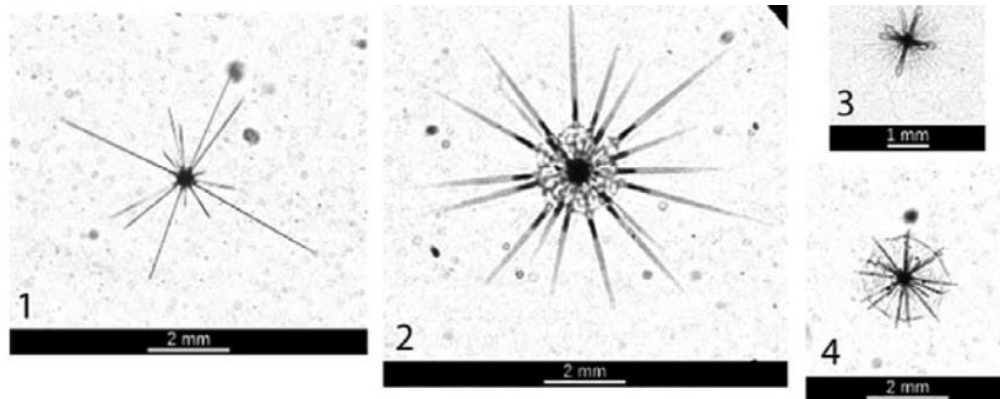
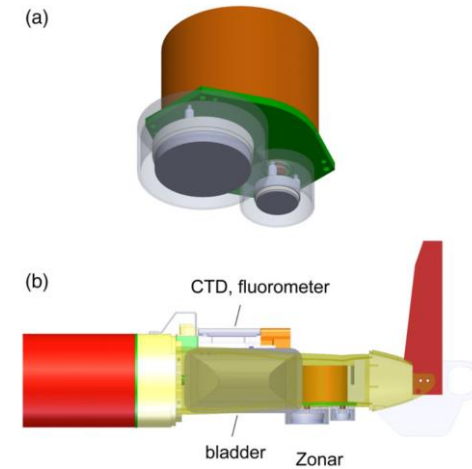
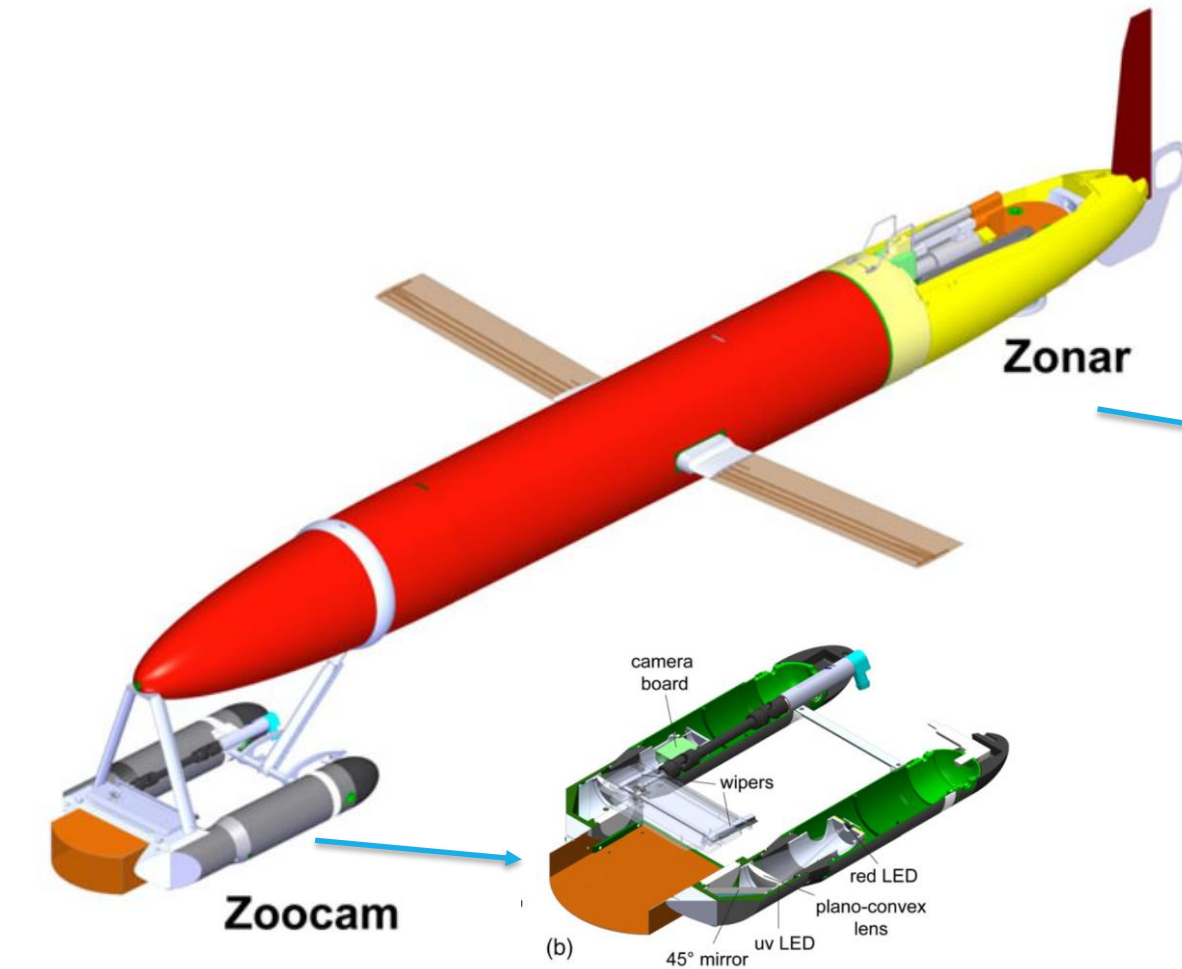
Development of  
SIRMA Smart Cable  
(by CSCS)





# BIOGLIDER

Zooglider: An autonomous vehicle for optical and acoustic sensing of zooplankton (2019)  
doi: 10.1002/lom3.10301



# The objectives of the project

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**BIOGLIDER**

- Develop a commercially available payload with UVP 6 and EK80
- That is integrated on multiple platforms (Seaglider, Slocum, Seaexplorer)
- With scientific validation of the system
- Capacity to retrieve data from moorings

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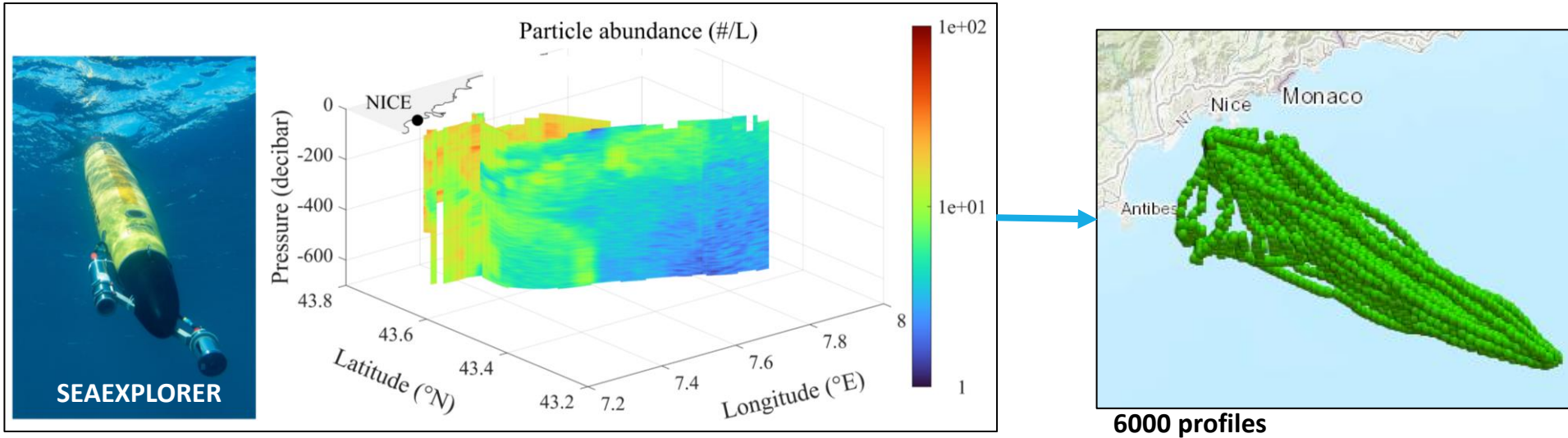
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**BIOGLIDER**

- Develop a commercially available payload with UVP 6 and EK80
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- Capacity to retrieve data from moorings
  - for OOSs and
  - for industrial applications :
    - fishery and
    - Oil and Gas (O&G) sectors.

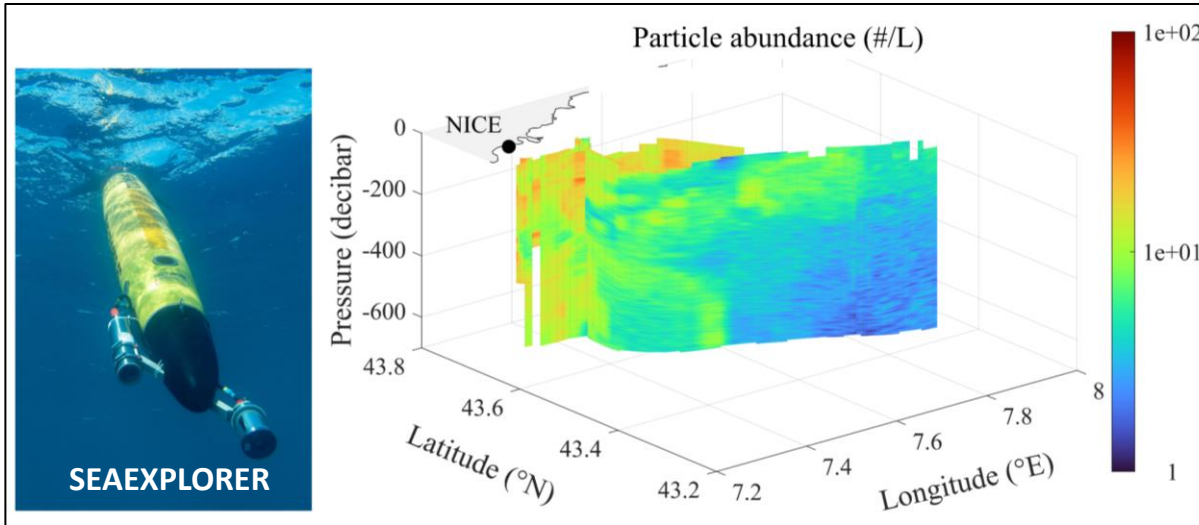
# Status of the UVP6 Integration on different gliders

**BIOGLIDER**



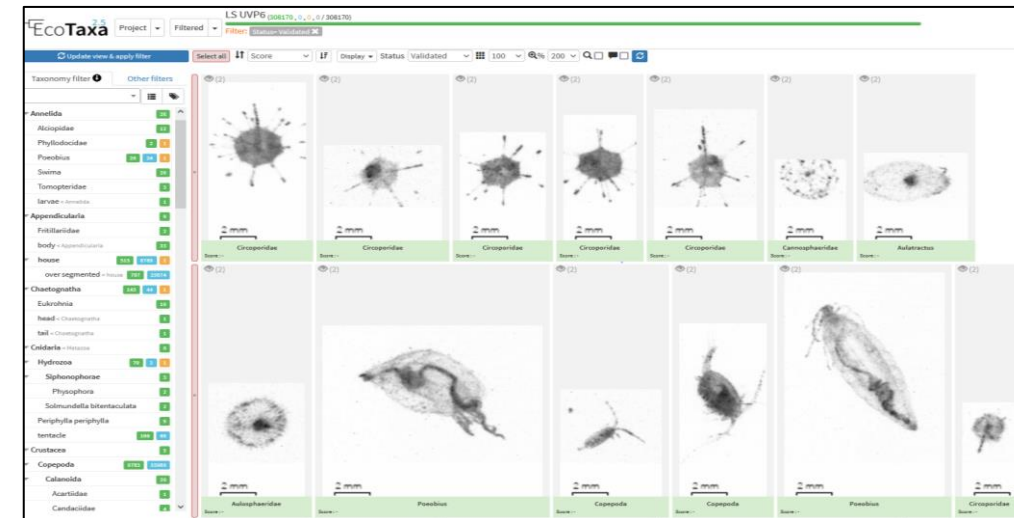
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# BIOGLIDER



6000 profiles

- UVPapp improvement (merging, metadata, piloting...)
- Matlab tool coding for data preparation for Ecotaxa and

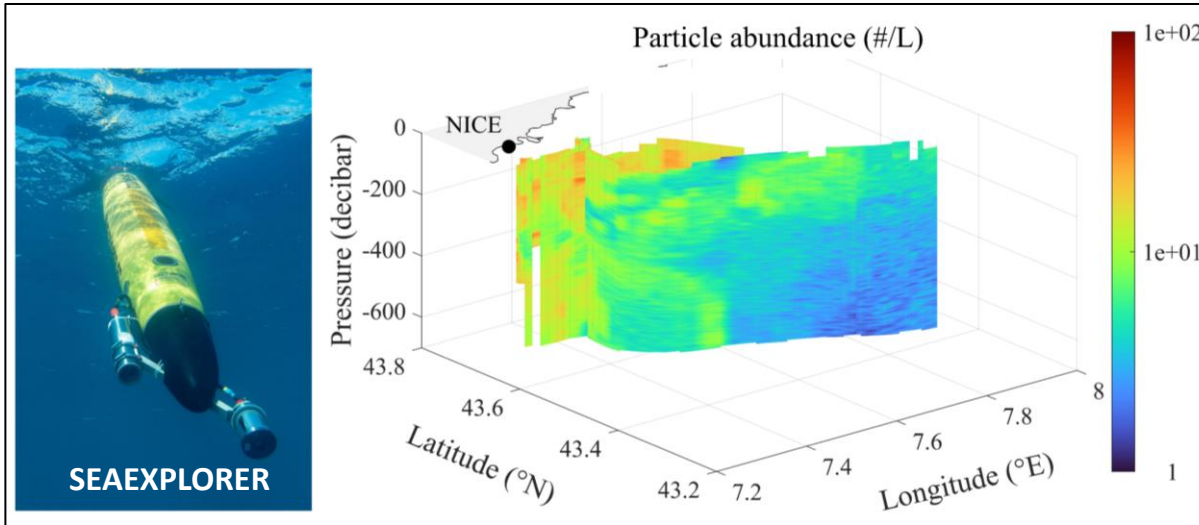


- Learning set creation for the automatic classification of UVP6 images : 650 000 images sorted



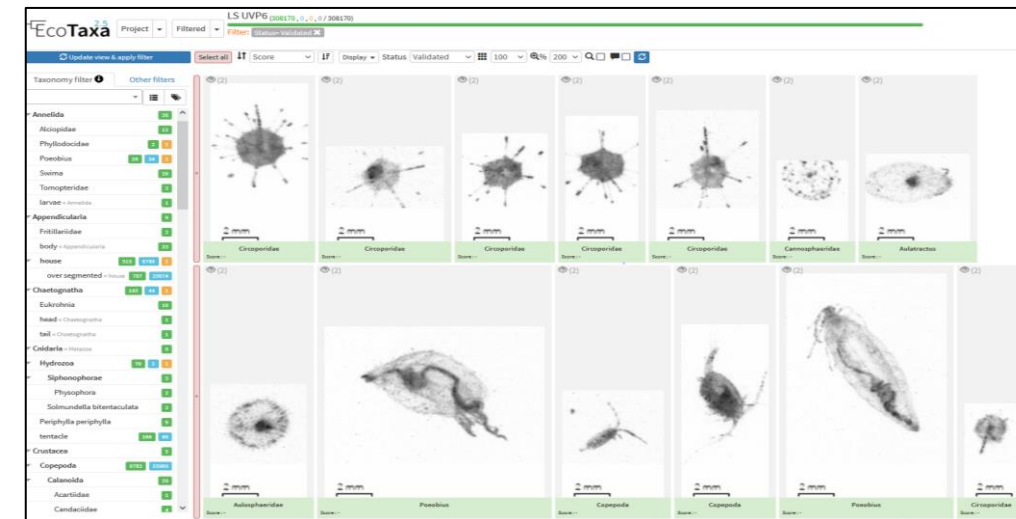
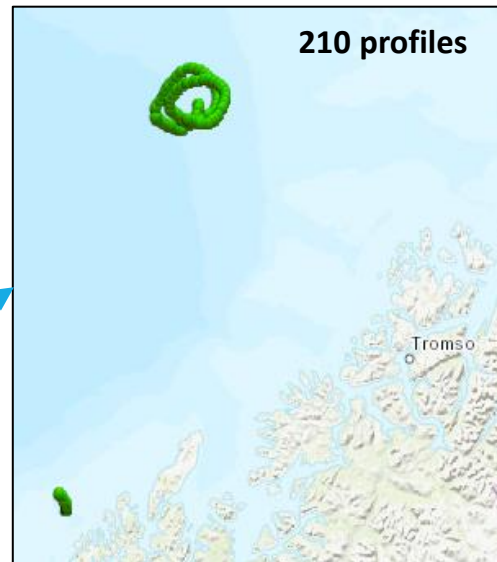
# Status of the UVP6 Integration on different gliders

# BIOGLIDER



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First tests in May 2021

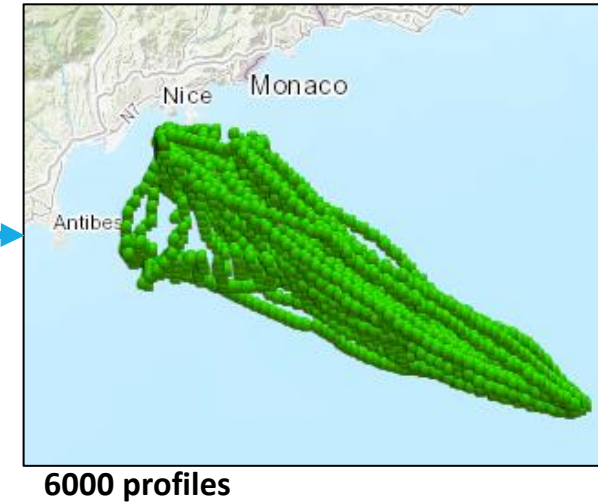
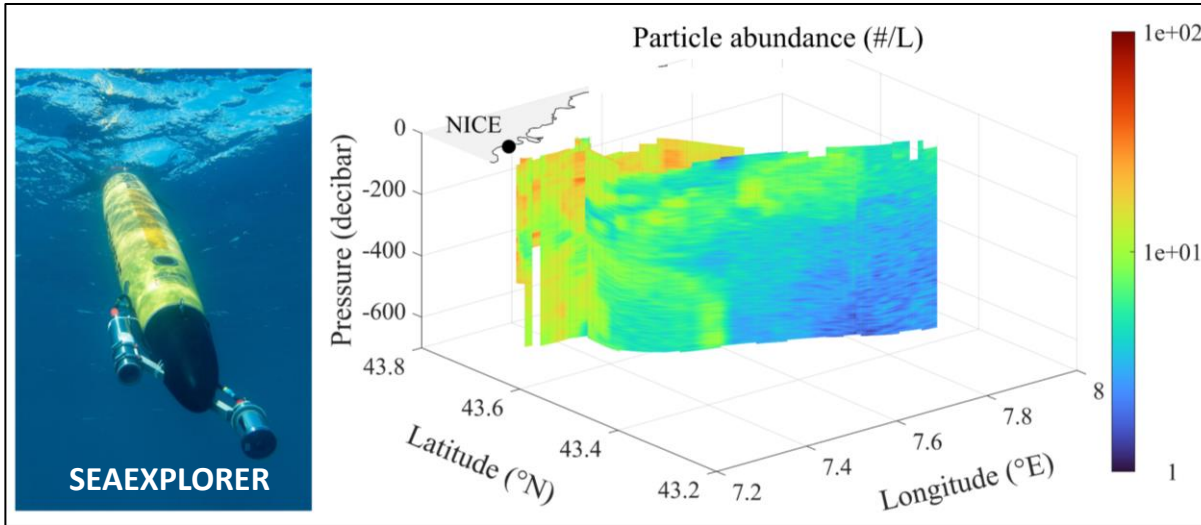


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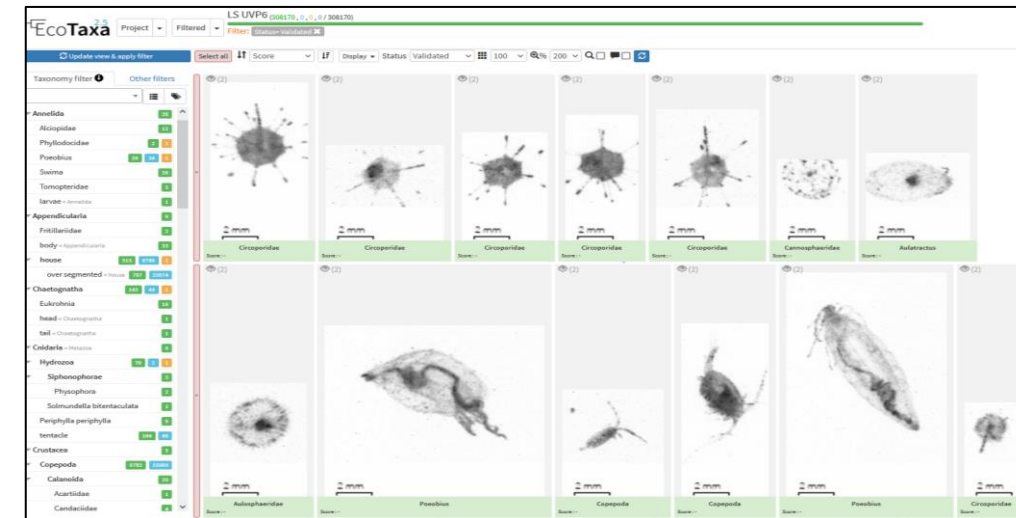
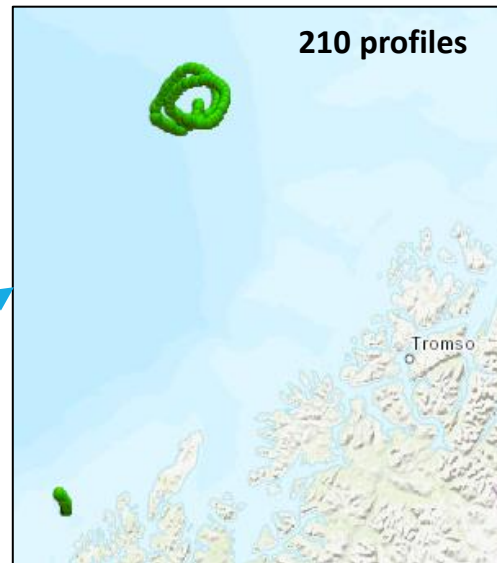
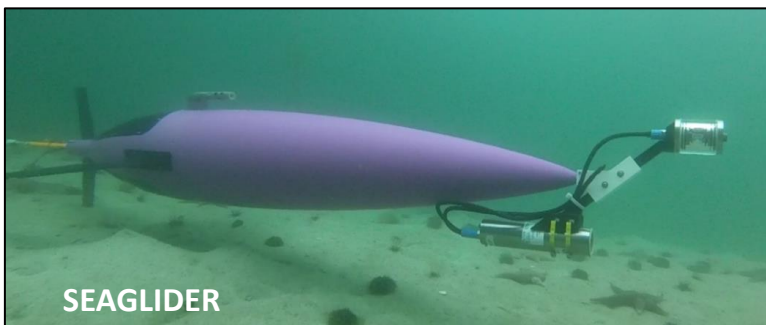
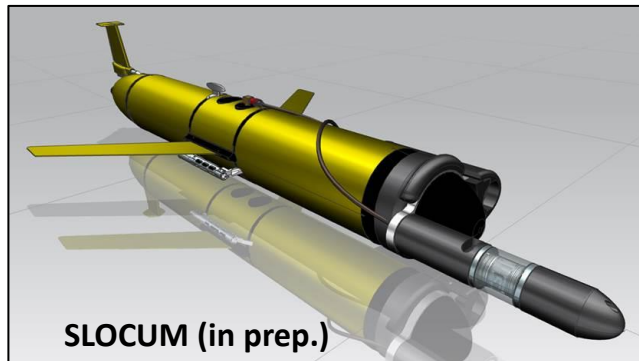


# Status of the UVP6 Integration on different gliders

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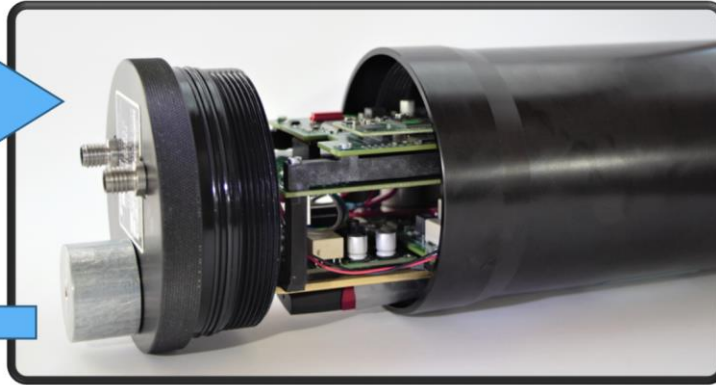
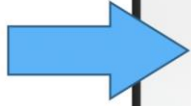
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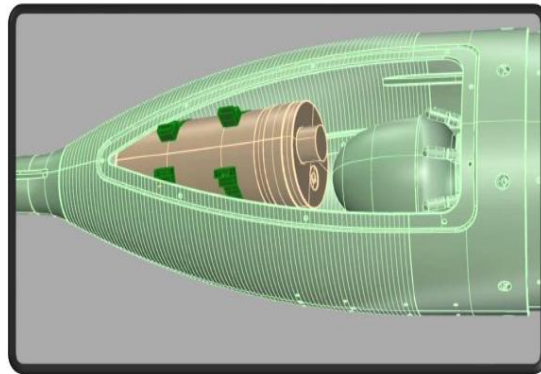
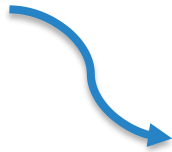
# Status of Echosounder EK80

**BIOGLIDER**

WBT mini



DeepEcho



2 PhD (IMR, AKN, Norway)  
1 Post-doc (UiT, Norway)

- **Seaglider**

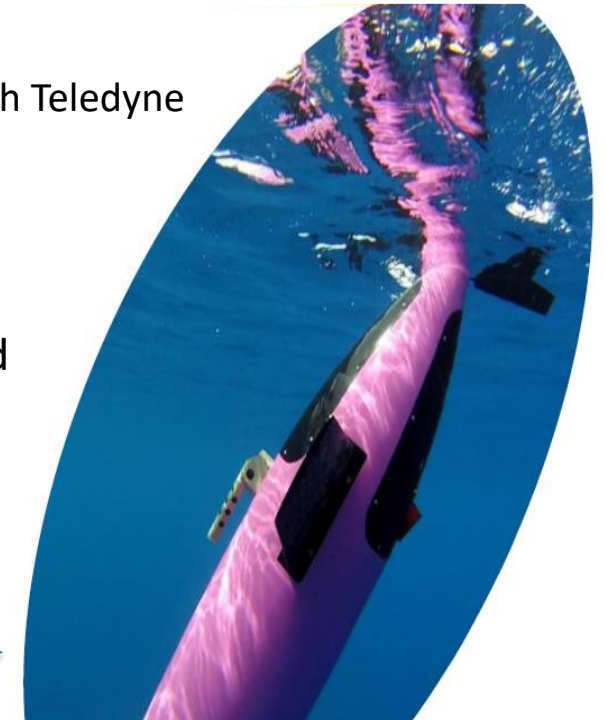
- Autonomous mode (no RT)
- Field tested Feb 2022
- Real life test in May 2022

- **Teledyne Slocum**

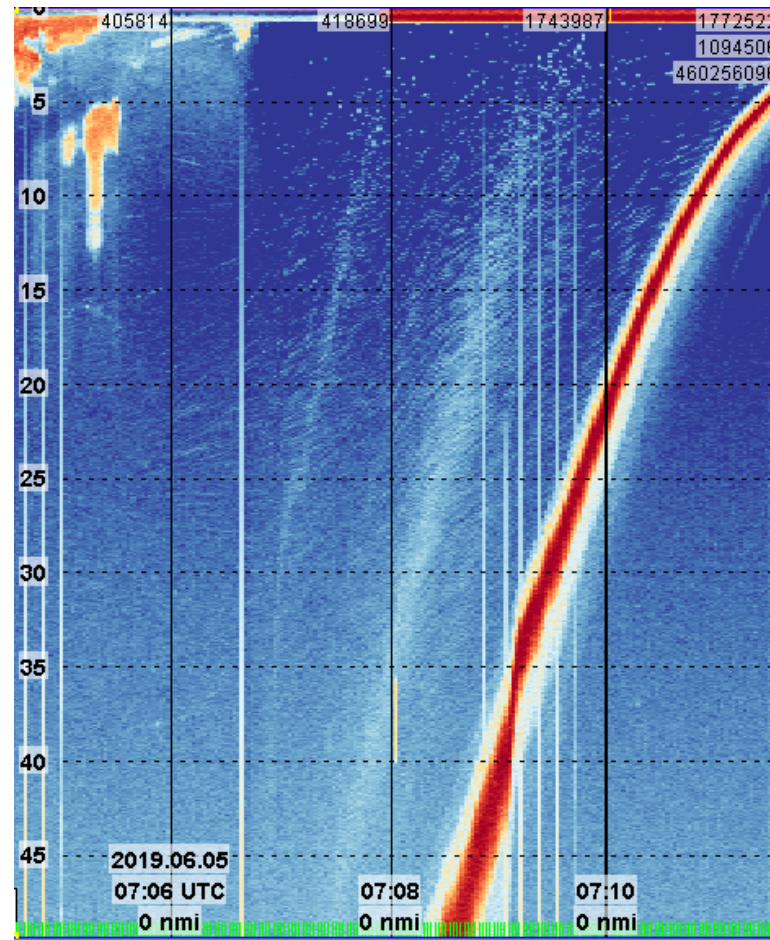
- EK80 Integration with Teledyne or at CSCS?

- **Seaexplorer**

- Discussion initiated with Alseamar



- Works with a separate battery to limit noise
- Samples on the descent and recharges on the ascent
- Two frequency tested : 200 or 333 khz.
- Software adaptation done to allow sample in non horizontal mode

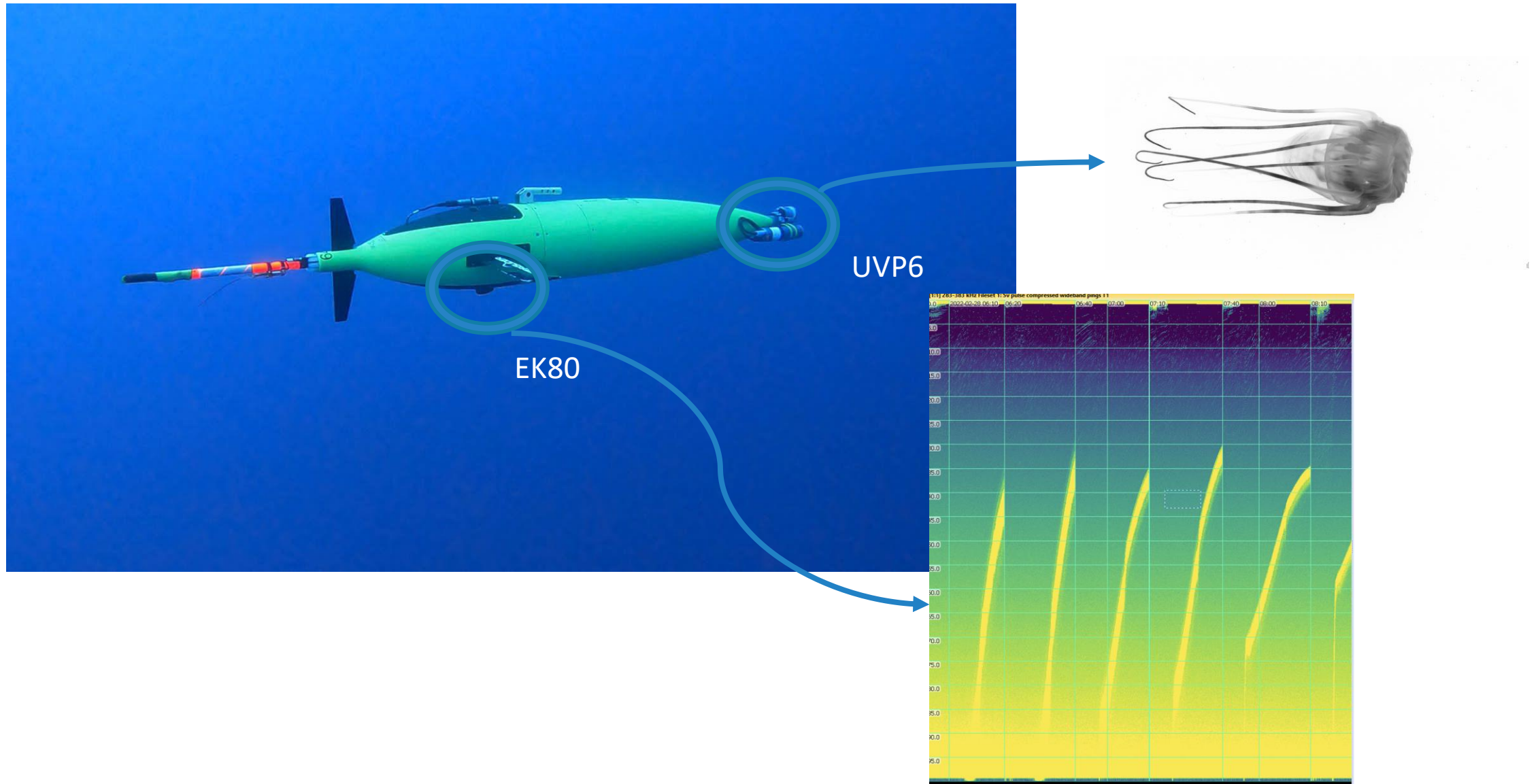


First scientific trials on glider  
in May 2022



The Seaglider Bioglider is ready

BIOGLIDER

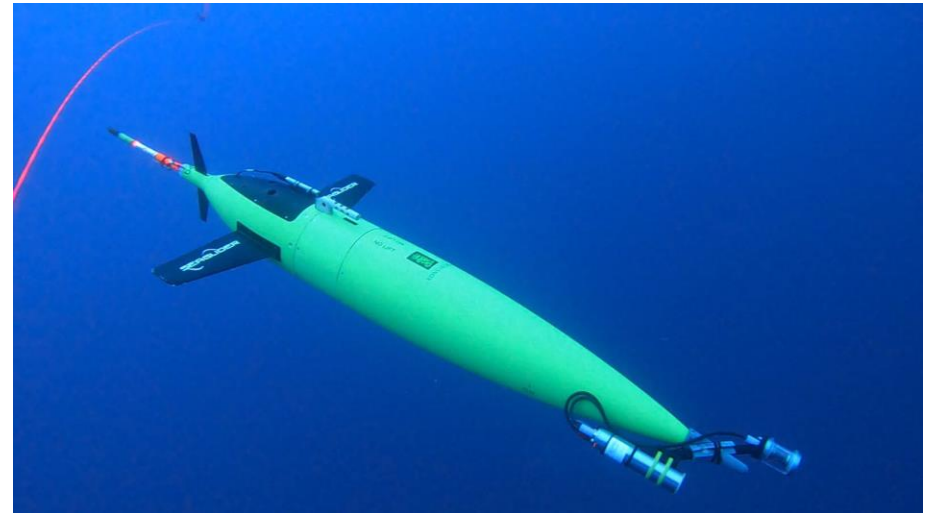




## Seaglider Bioglider in the “Polar Front” 18-27 May 2022 campaign

Around the Lofoten area to survey the phytoplankton spring bloom

- One Seaglider with UVP6 and EK80 : recorded 172 profiles for UVP6 (down and up) and 86 profiles of ek80 (down)
- A second glider carried PAR, wetlabs sea owl, and Jasco PAM
- Along with surface vehicles



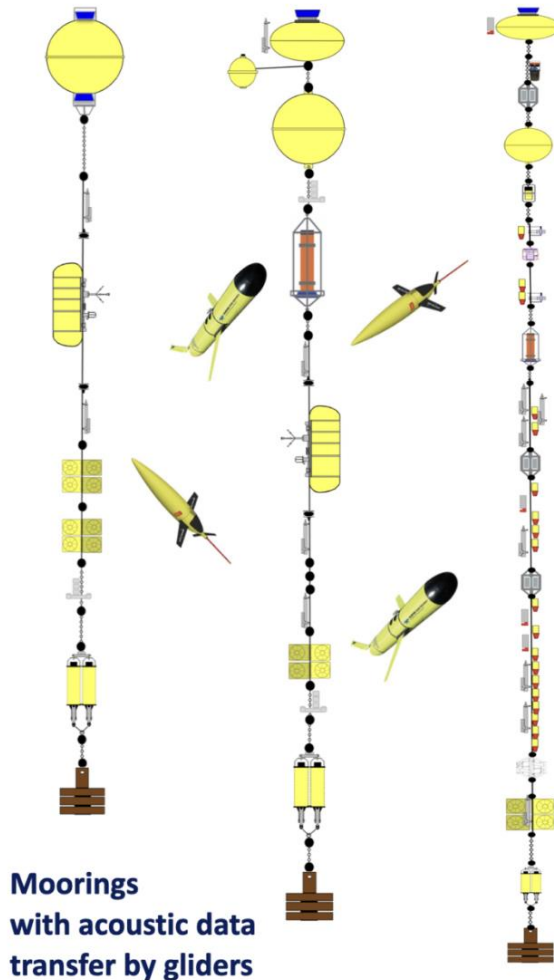
## **Complementarity and overlap:**

UVP 6 (imagery) measures small portion of water in front of the glider, recognizes particles  $> 100 \mu\text{m}$  at max 1.3 frames/seconds and configured for 0,1 fps.

EK80 (acoustics) : few meters from the sensor, resolution depends on frequency.

- UiT engaged one Post-Doc on the project for UVP-6 data interpretation and provides scientific expertise on zooplankton ecology
- IMR, and Yoann Lacroix (NIWA) provides scientific expertise on underwater acoustics

# Retrieve data from moorings with acoustic communication



Modem installed on the glider and the mooring to retrieve data from moorings with glider

Useful for moorings with no surface access and difficult to access

BIOGLIDER data transmission protocol (BGP) and Hydro-Acoustic Link Simulator (HALS) are under development for further tests.

Software for delayed packet transmission and test scenarios have also been developed.