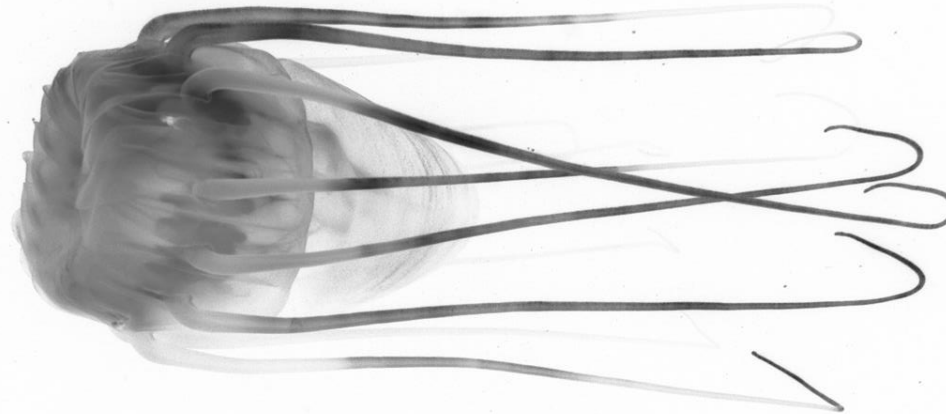






BioGlider: EK80



SIMRAD

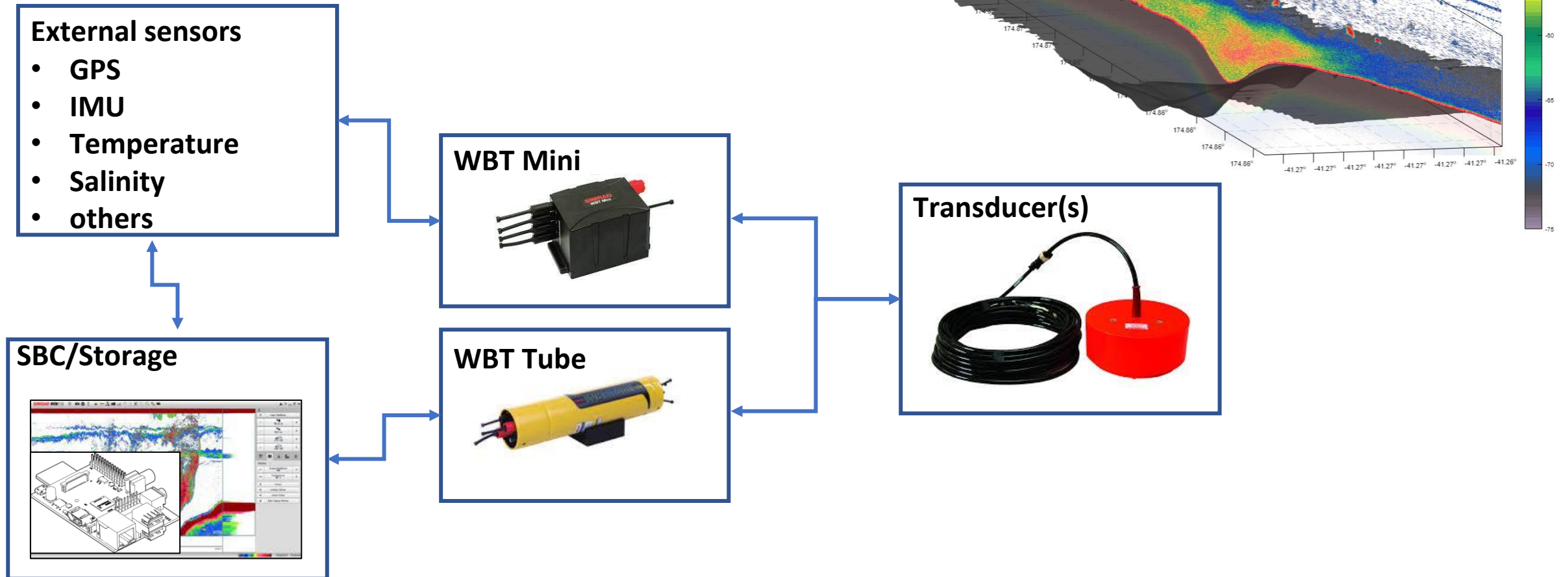
EK80

Transceiver		Depth rating	# of Channels(*)	Frequency range(**)	Multiplexing	Autonomous mode (internal storage)/glider use	Restrictions
WBT		No	4	10-500 kHz	No	No/No	--
WBT Mini		IP65	4	30-500 kHz	Yes	Yes/Yes	Lower power/ping rate
WBT Tube		4000m	8	30-500 kHz	Yes	No/Yes	Lower power/ping rate
WBAT		4000m	8	30-500 kHz	Yes	Yes/No	Lower power/ping rate/internal battery powered (not rechargeable)

*Split-beam requires 4 channels, single-beam requires 2 channels

**Depending on transducer used

Acquisition chain



Data format from EK80

- Raw data format: *.raw files
 - Binary data format
 - **Raw acoustic data** for all channels (either power/angles or complex samples)
 - All metadata (Transceiver serial number, transducer serial number, pulse length, nominal frequency etc...)
 - External sensors data
 - GPS (if available)
 - IMU
 - ...
 - Can include any external NMEA sentences send by other instruments via serial or UDP
- Other available data format available: *.nc
 - Netcdf format following [The SONAR-netCDF4 convention for sonar data](#)
 - Recent implementation, needs testing.
- Volume produced:
 - WBT Mini on Saildrone deployment
 - ES38-18/200 transducer (1 single-beam, 1 split-beam)
 - 45 days
 - recording range to 1000m
 - 0.5 Hz ping rate
 - 1ms CW pulse
 - RT trasmission of subsampled dataset after some RT processing on board
 - <https://www.saildrone.com/technology/mission-portal>



2 terabytes of *.raw files

Data example: Deep Towed body



Post-processing:

- Volumic-backscattering computed using
 - Environmental parameters (temp./sal.profiles)
 - Instrument calibration values
 - Other corrections (noise removal, motion correction...)
- Geo-referencing of all data
 - corrected from depth of Towed Body
 - offset position from vessel
- Echo-integration at appropriate scale for further analysis/modeling etc...

