KATER: Automating Weak Memory Model Metatheory and Consistency Checking

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1 Introduction

KATER is a tool that can automatically prove metatheoretic queries about (weak) memory consistency models (e.g., compilation correctness, program transformations), and also produce consistency checking routines for stateless model checkers (currently only GenMC [1] is supported). The underlying theory of KATER is described in a POPL 2023 paper [2].

2 Usage

An invocation of Kater resembles the following:

```
|| kater [OPTIONS] file
```

where OPTIONS include options that can be passed to KATER (use --help for a full list), and file is a file in the KAT language (see 2.1 for more details).

KATER can operate in two modes: *proof mode*, where it will try to prove all metatheoretic queries of the input, and *export mode* (invoked with -e), which will export consistency checking code.

2.1 Syntax

A KAT file is a series of declare, declare-loc, let, assert and assume statements (see 2.2 for examples). KATER also provides syntax relevant to code exporting, but this code is unstable and subject to change, so we do not provide more details here (see 2.3 for a glimpse).

declare r declares a new relation r, declare-loc r declares a new relation r and its per-location counterpart r-loc, let is used to define a derived relation, assert to declare a metatheoretic constraint to be checked by KATER, and assume to declare an assumption to be taken into account when proving the file's asserts.

To facilitate proofs, KATER has a builtin theory with relations and predicates commonly used in weak memory literature: po, po-loc, mo, rf, fr, detour, ctrl, addr, data (as well as their -imm counterparts, where applicable), and R, W, F, UR, UW, NA, RLX, ACQ, REL, SC, True, False. Users are encouraged to use the builtin theory if possible, and not re-declare such primitive relations.

KATER also knows the following properties:

- Disjoint tests: e.g., R & W = \emptyset
- Domains and ranges: e.g., rf = rfe | rfi
- Transitivity: e.g., po ; po <= po
- From-read properties: rf ; $fr \le mo$ and fr ; $mo+ \le fr$

Users can define additional properties using assume statements.

2.2 Proof Mode

2.2.1 Complete Fragment

We begin with some examples that fall within KATER's complete fragment to demonstrate matching endpoints and rotations.

The code below proves equivalence between two versions of the Release-Acquire (RA) model.

```
| let hb = ([R|W];po;[R|W] | rf)+
let ra = hb;(mo|fr)?
| let hb2 = ([R|W];po;[W] | [R];po;[W|R] | rfe)+
let ra2 = hb2;(mo|fr)? | po;fr
| assert ra & id <= [R|W];ra2;[R|W] & id
```

The construct id & r is used to enforce that the endpoints are the same in the examined paths of r. ra2 is restricted to [R|W] because KATER cannot otherwise know that there are no other types of events (in which case the stated equivalence does not hold if we do not appropriately change the definitions of hb, hb2).

Similarly, the code below proves equivalence between two other versions of RA.

```
| let hb = (po | rf)+
let ra1 = (hb;fr | hb;mo | hb)
let ra3 = (mo | fr)?;hb
| assert [R|W];ra1;[R|W] & id <= rot ra3
| assert ra3 & id <= rot ra1
```

rot is used to consider the rotations of the RHS.

In both examples above, no assumption was necessary to prove the desired result, as KATER has all the necessary information in its builtin theory.

2.2.2 Incomplete Fragment

KATER treats generic non-emptiness assumptions like a <= b in a heuristic fashion¹. Such assumptions are particularly useful in compilation schemes, like the one below from RC11 to TSO.

```
// file: tso.kat
let ppo = ([R]; po | po ; [F] | [UW|F] ; po | po ; [W])+
let tso = (ppo | rfe | mo | fr)
// file: rc11.kat
let eco = (rf \mid mo \mid fr)+
let sw = [REL] ; ([F] ; po)? ; (rf ; rmw)* ; rf ; (po ; [F])? ; [ACQ]
let hb = (po \mid sw) +
let SC' = ([F] | [R] | [W]) ; SC
let FSC = [F]; [SC]
let fhb = [F]; hb
let hbf = hb ; [F]
let scb = po | rf | mo | fr
let psc = [SC']; po; hb; po; [SC']
| [SC']; fhb?; scb; hbf?; [SC']
          | FSC ; hb ; FSC
          | FSC ; hb ; eco ; hb ; FSC
          | SC'; po; SC'
let psc_strong = ([SC'] | [F];[SC]; hb?); (hb | eco); ([SC'] | hb?; [F];[SC])
           hb;eco |
          (po | rf)+
// file: compilation.kat
include "./tso.kat"
include "./rc11.kat"
assume [W];po;[R] <= [W];po;[F];po;[R]
assert rc11::psc+ <= tso::tso+
```

The compilation scheme is provided as an assumption, and KATER produces a counterexample if it is omitted.

2.2.3 Custom Relations

Users can declare additional relations using the declare r and declare-loc r commands. (The latter also defines r-loc and equips KATER with the knowledge that r-loc $\leq r$.)

An example where rf is re-defined as a user-declared relation can be seen below.

```
declare rf
declare rf-1
declare co

let nfr = rf-1; co

let eco1 = (rf | co | nfr)+
let eco2 = rf | (co|nfr);rf?

assume co;co <= co
assume co;rf-1 = 0
assume rf;rf = 0
assume rf;rf = 0
assume rf;rf-1 <= id

assert eco1 <= eco2</pre>
```

KATER required quite a few assumptions in order to prove the desired result. Using the builtin theory in this example eliminates the need for such assumptions.

2.3 Export Mode

The code below produces GenMC consistency checking code for RC11 [3].

```
// Extended coherence order
let eco = (rf | mo | fr)+

// Export mode needs to define a PPO relation
let ppo = po
```

 $^{^{1}}$ Excluding assumptions of the form r;r <= r or r <= id which maintain completeness.

```
// Extend SW with thread creation
let relseq = [REL] ; ([F|TC|TE] ; po)? ; (rf ; rmw)*
let sw_to_r = relseq ; rf ; [ACQ]
let sw_to_f = relseq ; rf ; po ; [F|TJ|TB] ; [ACQ]
let sw = sw_to_r | sw_to_f
let asw = tc | tj
assert sw = [REL] ; ([F|TC|TE] ; po)? ; (rf ; rmw)* ; rf ; (po ; [F|TJ|TB])? ; [ACQ]
// An hb_stable view needs to be provided \underline{\text{for}} coherence
view hb_stable = (po-imm | (sw_to_r | asw) ; po-imm | sw_to_f)+
let hb = (hb_stable | hb_stable? ; (sw_to_r | asw))
// Coherence : Optimize the checking of irreflexive (hb ; eco)
coherence (hb_stable)
// No OOTA + RMW atomicity are taken care of by GenMC
// acyclic (po | rf)
// Sequential consistency order
let FSC = [F]; [SC]
let fhb = [F] ; hb
let hbf = hb ; [F]
let scb = po \mid rf \mid mo \mid fr
let psc = [SC]; po; hb; po; [SC]
        | [SC] ; fhb? ; scb ; hbf? ; [SC]
        | FSC ; hb ; FSC
        | FSC ; hb ; eco ; hb ; FSC
        | SC ; po ; SC
acyclic psc
// RC11 error detection example
let ww_conflict = [W] ; loc-overlap ; [W]
let wr_conflict = [W] ; loc-overlap ; [R] | [R] ; loc-overlap ; [W]
let conflicting = ww_conflict | wr_conflict
let na_conflict = [NA] ; conflicting | conflicting ; [NA]
error VE_AccessNonMalloc unless alloc <= hb_stable
                      unless [Free]; loc-overlap; [Free] = 0
error VE_DoubleFree
error VE_AccessFreed
                         unless loc-overlap ; [Free] <= hb_stable
error VE_AccessFreed
                       unless [Free] ; loc-overlap = 0
error VE_RaceNotAtomic
                          unless na_conflict <= hb_stable
```

3 Contact

For feedback, questions and bug reports please send an e-mail to michalis@mpi-sws.org.

References

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- [3] Ori Lahav, Viktor Vafeiadis, Jeehoon Kang, Chung-Kil Hur, and Derek Dreyer. Repairing sequential consistency in C/C++11. In *PLDI 2017*, pages 618–632, New York, NY, USA, 2017. ACM.